## LC898201

CMOS LSI
Iris/Zoom/Focus/
Day-Night switching
Drive Controller

ON Semiconductor ${ }^{\text {® }}$
http:/lonsemi.com

## Overview

LC898201 is the appropriate motor control LSI for the surveillance camera usage, and it can drive iris, focus, zoom and Day/Night switching simultaneously.
It incorporates two feedback circuits for iris and focus control, and two stepper motor control circuits for zoom and Day/Night switching (cf. P4 Application-1).
Moreover, the feedback control applies iris control, and stepper motor controls apply focus, zoom and Day/Night switching at the mode selection (cf. Application-2 to 4 of P5 to P7).
Stepper motor control circuits can drive the stepping motor efficiently(It is called "ECO(GREEN)-driver") (For a limited numerical usable channel, refer to Application-1 to 4 of P 4 to P 7 ).

## Features

- Built-in equalizer circuit by digital operation
- Iris control equalizer circuit
- Focus control equalizer circuit (MR sensor can be connected.)
- Coefficients can be set arbitrarily through the SPI interface.
- Computed values in the equalizer can be monitored.
- Built-in 3ch stepping motor control circuits
(2ch are equipped with "ECO(GREEN)-driver" circuits)
(Usable channel is shown in Application-1 to 4 of P4 to P7)
■ SPI bus interface
■ PI control circuit
- 30 mA Sink output terminal
- Built-in PI detecting function (A/D method)
- A/D converter
- 12bit (6ch)
: Iris, Focus, ECO, PI detection
- D/A converter
- 8bit (5ch)
: Hall offset, Constant current bias, MR Sensor offset, ECO offset
- Operation Amplifier
$-4 \mathrm{ch}(\mathrm{ECO} \times 1$, Iris control $\times 1$, Focus control $\times 2$ )

To the next page.

## ORDERING INFORMATION

See detailed ordering and shipping information on page 16 of this data sheet.

- PWM pulse generator
- PWM Pulse generator for feedback control (Up to 12bit accuracy)
- PWM pulse generator for stepper motor control (Up to 1024 micro steps)
- PWM pulse generator for general-purpose H-Bridge (128 voltage levels)
- Motor Driver
- ch1 to ch6 : Io $\max =200 \mathrm{~mA}$
- ch7 : Io max=300mA
- Built-in thermal protection circuit
- Built-in low-voltage malfunction prevention circuit

■ OSC (Type. 48MHz)

- Package
- LC898201TA-NH : TQFP64(7×7) 0.4 mm pitch
- LC898201RA-NH : FBGA64(6.0×6.0) 0.5 mm pitch
- Lead-free, Halogen-free

■ Power supply voltage

- Logic unit : 2.7 V to 3.6 V (IO, Internal core)
- Driver unit : 2.7 V to 5.5 V (Motor drive)


## Package Dimensions

unit: mm
[ LC898201TA-NH]
TQFP64 7x7 I TQFP64
CASE 932BC
ISSUE O


## Package Dimensions

unit: mm
[ LC898201RA-NH ]

## FBGA64 6x6

CASE 113BL
ISSUE O


NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME

Y14.5M, 1994.
Y14.5M, 1994 . CONTROLLING DIMENSION: MILLIMETERS
2. CONTROLLING DIMENSION: MILLIMETERS.
. DIMENSION b IS MEASURED AT THE MAXIMUM
SOLDER BALL DIAMETER PARALLEL TO DATUM C.
4. COPLANARITY APPLIES TO SPHERICAL CROWNS OF SOLDER BALLS
5. DIMENSION C, THE SEATING PLANE, IS DEFINED BY THE SPHERICAL CROWNS OF THE SOLDER BALLS.

|  | MILLIMETERS |  |
| :---: | :---: | :---: |
| DIM | MIN | MAX |
| A | --- | 1.05 |
| A1 | 0.05 | 0.15 |
| b | 0.24 | 0.34 |
| D | 6.00 BSC |  |
| E | 6.00 BSC |  |
| e | 0.50 BSC |  |

RECOMMENDED SOLDERING FOOTPRINT*


DIMENSIONS: MILLIMETERS
*For additional information on our $\mathrm{Pb}-$ Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

## Block Diagram

Application-1
MR-VCM


## Application-2

Stepper Motor 3ch \& Crystal oscillator(or Ceramic oscillator)


## Application-3

## Stepper Motor 3ch \& Oscillator



## Application-4

Stepper Motor 3ch \& ECO external connection


## Pin Description

| TYPE |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| I | INPUT | P | Power, GND | NC | NOT CONNECT |
| 0 | OUTPUT |  |  |  |  |
| B(I) | BIDIRECTION : INPUT at reset |  |  |  |  |
| $\mathrm{B}(\mathrm{O})$ | BIDIRECTION : OUTPUT at reset |  |  |  |  |


| ■ SPI interface (Slave) |  |  |
| :---: | :---: | :---: |
| SSB | I | Chip select |
| SCLK | I | Clock |
| MOSI | I | Received data |
| MISO | $\mathrm{B}(\mathrm{O})$ | Transmit data |
| BUSY/MON | $\mathrm{B}(\mathrm{O})$ | Transfer busy / Monitor output |
| - PI sensor drive signal output |  |  |
| PIS1/MON | $\mathrm{B}(\mathrm{O})$ | PI sensor drive signal output 1 / Monitor output |
| PIS2/MON | $\mathrm{B}(\mathrm{O})$ | PI sensor drive signal output 2 / Monitor output |
| - Video synchronizing signal input |  |  |
| VSYNC1/MON | B(I) | Video synchronizing signal input / Monitor output (with pull-down resistance) |
| VSYNC2/MON /SHUTTER | B(I) | Video synchronizing signal input / Monitor output / Shutter input (with pull-down resistance) |
| - Monitor output |  |  |
| MON | B(O) | Monitor output |
| ■ Clock output |  |  |
| XTALCK | I | Oscillation amplifier input : 27 MHz |
| XTAL | O | Oscillation amplifier output |
| CLKO1/MON | $\mathrm{B}(\mathrm{O})$ | Clock output 1 / Monitor output |
| CLKO2/MON | $\mathrm{B}(\mathrm{O})$ | Clock output 2 / Monitor output |
| - Reset |  |  |
| ZRESET | I | Reset signal input(Low active) |
| - Bias current pin |  |  |
| BIASO6 | O | CH6 Bias current output |
| - OP Amp pin |  |  |
| OPINM1 | I | CH1 OP Amp input(-) with ATT |
| OPINM3 | I | CH3 OP Amp input(-) with ATT |
| OPINP6 | I | CH6 OP Amp input (+) |
| OPINM6 | I | CH6 OP Amp input (-) |
| OPINP7A | I | CH7-A OP Amp input (+) |
| OPINM7A | I | CH7-A OP Amp input (-) |
| OPINP7B | I | CH7-B OP Amp input (+) |
| OPINM7B | I | CH7-B OP Amp input (-) |
| - A/D input pin |  |  |
| ADIN1 | B | CH1 A/D input (CH1 OP Amp output) |
| ADIN6 | B | CH6 A/D input (CH6 OP Amp output) |
| ADIN7A | B | CH7-A A/D input (CH7 OP Amp output) |
| ADIN7B | B | CH7-B A/D input (CH7 OP Amp output) |
| ADPIIN1 | I | CH1/2 PI sensor signal A/D input |
| ADPIIN2 | I | CH3/4 PI sensor signal A/D input |
| ADVRH | I | A/D conversion range standard voltage |
| ADVRL | I | A/D conversion range standard voltage |


| H-Bridge |  |  |
| :--- | :--- | :--- |
| OUT1A | O | CH1 H-Bridge output |
| OUT1B | O | CH1 H-Bridge output |
| OUT2A | O | CH2 H-Bridge output |
| OUT2B | O | CH2 H-Bridge output |
| OUT3A | O | CH3 H-Bridge output |
| OUT3B | O | CH3 H-Bridge output |
| OUT4A | O | CH4 H-Bridge output |
| OUT4B | O | CH4 H-Bridge output |
| OUT5A | O | CH5 H-Bridge output |
| OUT5B | O | CH5 H-Bridge output |
| OUT6A | O | CH6 H-Bridge output |
| OUT6B | O | CH6 H-Bridge output |
| OUT7A | O | CH7 H-Bridge output |
| OUT7B | O | CH7 H-Bridge output |
|  |  |  |
| Power pin | P | Digital VDD |
| DVDD | P | Digital GND |
| DVSS | P | D/A, OP Amp VDD |
| DAOPVDD | P | D/A, OP Amp GND |
| DAOPVSS | P | A/D VDD |
| ADVDD | P | A/D GND |
| ADVSS | P | H-Bridge VDD |
| VM | P | H-Bridge GND |
| PGND |  |  |

## * Process when pins are not used

PIN TYPE "O" $\cdots$. The pin must be left open.
PIN TYPE "I" $\cdots \cdots$.... The pin must not be left open. Please make sure to connect the pin to Vdd or Vss even when it is not used. (Please check with us whether to connect to Vdd or Vss.)
PIN TYPE "B" $\cdots$ Please contact us if you are uncertain about a processing method in the pin description in the PIN layout table.

A problem may occur if the processing method is used wrongly for any unused pin.
Please make sure to contact us.

## Pin Assignment



| 10 | DVDD | VSYNC2 | PIS2 | DVSS | ADVSS | ADVDD | $\begin{aligned} & \text { ADPI } \\ & \text { IN1 } \end{aligned}$ | $\begin{aligned} & \text { ADPI } \\ & \text { IN2 } \end{aligned}$ | ADIN7A | ADIN7B |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 9 | DVSS |  |  |  | ADVRL | ADVRH |  |  |  | ADIN6 |
| 8 | CLKO1 |  | XTALCK | VSYNC1 | PIS1 | DVDD | ADIN1 | $\begin{array}{\|c} \text { OPINM } \\ 7 B \end{array}$ |  | $\begin{array}{\|c} \text { OPINP } \\ 7 \mathrm{~B} \end{array}$ |
| 7 | CLKO2 |  | XTAL |  |  |  |  | OPINM6 |  | OPINP6 |
| 6 | SSB |  | ZRESET | SCLK |  |  | BIASO6 | $\begin{aligned} & \text { DAOP } \\ & \text { VSS } \end{aligned}$ |  | $\begin{aligned} & \text { DAOP } \\ & \text { VDD } \end{aligned}$ |
| 5 | MISO |  | BUSY | MOSI |  |  | OPINM1 | $\begin{gathered} \text { OPINP } \\ 7 \mathrm{~A} \end{gathered}$ |  | $\begin{gathered} \text { OPINM } \\ 7 \mathrm{~A} \end{gathered}$ |
| 4 | DVDD |  | DVSS |  |  |  |  | OPINM3 |  | OUT7A |
| 3 | MON |  | OUT6A | OUT5A | OUT4A | OUT3A | OUT1A | OUT2A |  | OUT7B |
| 2 | VM | VM |  |  |  |  |  |  | VM | VM |
| 1 | PGND | PGND | OUT6B | OUT5B | OUT4B | OUT3B | OUT1B | OUT2B | PGND | PGND |
|  | A | B | C | D | E | F | G | H | J | K |

<TOP VIEW> FBGA64(6.0X6.0)

## PIN number

| Pin No. |  | Type | Pin name |
| :---: | :---: | :---: | :---: |
| TQFP64 | FBGA64 |  |  |
| 1 | A10 | P | DVDD |
| 2 | A9 | P | DVSS |
| 3 | A8 | B(O) | CLKO1 |
| 4 | A7 | B(O) | CLKO2 |
| 5 | C6 | I | ZRESET |
| 6 | A6 | I | SSB |
| 7 | D6 | I | SCLK |
| 8 | D5 | I | MOSI |
| 9 | A5 | B(O) | MISO |
| 10 | C5 | B(O) | BUSY |
| 11 | A4 | P | DVDD |
| 12 | C4 | P | DVSS |
| 13 | A3 | B(O) | MON |
| 14 | B2 | P | VM |
| 15 | A2 | P | VM |
| 16 | B1 | P | PGND |


| Pin No. |  | Type | Pin name |
| :---: | :---: | :---: | :---: |
| TQFP64 | FBGA64 |  |  |
| 33 | J1 | P | PGND |
| 34 | J2 | P | VM |
| 35 | K2 | P | VM |
| 36 | H4 | I | OPINM3 |
| 37 | G5 | I | OPINM1 |
| 38 | K5 | I | OPINM7A |
| 39 | H5 | I | OPINP7A |
| 40 | G6 | O | BIASO6 |
| 41 | K6 | P | DAOPVDD |
| 42 | H6 | P | DAOPVSS |
| 43 | H7 | I | OPINM6 |
| 44 | K7 | I | OPINP6 |
| 45 | H8 | I | OPINM7B |
| 46 | K8 | I | OPINP7B |
| 47 | K9 | B | ADIN6 |
| 48 | K10 | B | ADIN7B |


| Pin No. |  | Type | Pin name |
| :---: | :---: | :---: | :---: |
| TQFP64 | FBGA64 |  |  |
| 17 | A1 | P | PGND |
| 18 | C3 | O | OUT6A |
| 19 | C1 | O | OUT6B |
| 20 | D3 | O | OUT5A |
| 21 | D1 | O | OUT5B |
| 22 | E3 | O | OUT4A |
| 23 | E1 | O | OUT4B |
| 24 | F3 | O | OUT3A |
| 25 | F1 | O | OUT3B |
| 26 | G3 | O | OUT1A |
| 27 | G1 | O | OUT1B |
| 28 | H3 | O | OUT2A |
| 29 | H1 | O | OUT2B |
| 30 | K4 | O | OUT7A |
| 31 | K3 | O | OUT7B |
| 32 | K1 | P | PGND |


| Pin No. |  | Type | Pin name |
| :---: | :---: | :---: | :---: |
| TQFP64 | FBGA64 |  |  |
| 49 | J10 | B | ADIN7A |
| 50 | G8 | B | ADIN1 |
| 51 | H10 | I | ADPIIN2 |
| 52 | G10 | I | ADPIIN1 |
| 53 | E9 | I | ADVRL |
| 54 | F9 | I | ADVRH |
| 55 | F10 | P | ADVDD |
| 56 | E10 | P | ADVSS |
| 57 | F8 | P | DVDD |
| 58 | D10 | P | DVSS |
| 59 | E8 | B(O) | PIS1 |
| 60 | C10 | B(O) | PIS2 |
| 61 | D8 | B(I) | VSYNC1 |
| 62 | B10 | B(I) | VSYNC2 |
| 63 | C8 | I | XTALCK |
| 64 | C7 | O | XTAL |

## Electrical Characteristics

## 1. Logic, Analog

Logic, Analog power : DVDD/DVSS, OPDAVDD/OPDAVSS, ADVDD/ADVSS, these should be connected at the same voltage. They are shown DVDD/DVSS as follows.

1) Absolute Maximum Ratings at DVSS $=0 \mathrm{~V}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :--- | :---: | :---: | :---: | :---: |
| Supply Voltage | DVDD max | $\mathrm{Ta} \leq 25^{\circ} \mathrm{C}$ | -0.3 to 4.6 | V |
| Input/Ouput Voltage | Vin,Vout | $\mathrm{Ta} \leq 25^{\circ} \mathrm{C}$ | -0.3 to DVDD +0.3 | V |
| Storage Temperature | Tstg |  | -55 to 125 | ${ }^{\circ} \mathrm{C}$ |
| Operating Temperature | Topr |  | -20 to 85 | ${ }^{\circ} \mathrm{C}$ |

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.
2) Allowable Operating Range at $\mathrm{Ta}=-20$ to $85^{\circ} \mathrm{C}$, DVSS $=0 \mathrm{~V}$

| Parameter | Symbol | Min. | Typ. | Max. | Unit | Applicable pins |
| :--- | :---: | :---: | :---: | :---: | :---: | :--- |
| Power Supply Voltage | DVDD | 2.7 | 3.3 | 3.6 | V |  |
| Input Voltage Range | $\mathrm{V}_{\text {IN }}$ | 0 | - | DVDD | V | Except for OPINM1, <br> OPINM3 |
| Input Voltage Range | $\mathrm{V}_{\text {IN }}$ | 0 | - | VM | V | OPINM1, OPINM3 |

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.
3) D.C Characteristics : Input/Ouput level at $\mathrm{Ta}=-20$ to $85^{\circ} \mathrm{C}, \mathrm{DVSS}=0 \mathrm{~V}, \mathrm{DVDD}=2.7$ to 3.6 V

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit | Applicable pins |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| High-level input voltage | VIH | CMOS | 0.7DVDD |  |  | V | (2)(3) |
| Low-level input voltage | VIL |  |  |  | 0.2DVDD | V |  |
| High-level input voltage | VIH | CMOS <br> Schmidt | 0.75DVDD |  |  | V | (1) |
| Low-level input voltage | VIL |  |  |  | 0.15DVDD | V |  |
| High-level output voltage | VOH | $\mathrm{IOH}=-4 \mathrm{~mA}$ | DVDD-0.4 |  |  | V | (2)(3)(4) |
| Low-level output voltage | VOL | $\mathrm{IOL}=4 \mathrm{~mA}$ |  |  | 0.4 | V | (2)(3) |
| Low-level output voltage | VOL | $\mathrm{IOL}=30 \mathrm{~mA}$ |  |  | 0.4 | V | (4) |
| PullDown resistance | Rdn |  | 40 | 80 | 200 | K $\Omega$ | (3) |
| Analog input voltage | VAI |  | DVSS |  | DVDD | V | (5) |
| Analog input voltage | VAI |  | PGND |  | VM | V | (6) |
| VGA output resistance | Rout |  |  | 1 |  | K $\Omega$ | (7) |
| Analog output current | IAO | $\begin{aligned} & \text { CMSDAC } \\ & =001 \mathrm{~b} \& \\ & \text { WH_DAV4 } \\ & =00 \overline{\mathrm{~h}} \end{aligned}$ |  | 1 |  | mA | (8) |

* Applicable pins
(1) ZRESET, SSB, SCLK, MOSI
(2) MISO, BUSY, MON, CLKO1, CLKO2
(3) VSYNC1, VSYNC2
(4) PIS1, PIS2
(5) OPINP6, OPINM6, OPINP7A, OPINM7A, OPINP7B, OPINM7B, ADPIIN1, ADPIIN2
(6) OPINM1, OPINM3
(7) ADIN1, ADIN6, ADIN7A, ADIN7B
(8) BIASO6


## 2. VM

1) Absolute Maximum Ratings at $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{PGND}=0 \mathrm{~V}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Supply Voltage | VMmax |  | -0.3 to 7.0 | V |
| Ouput peak current | Iopeak1 | OUT1A/B to OUT6A/B <br> $\mathrm{t} \leq 10 \mathrm{~ms}$, On-duty $\leq 20 \%$ | 300 | mA |
| Ouput peak current | Iopeak2 | $\begin{aligned} & \text { OUT7A/B } \\ & \mathrm{t} \leq 10 \mathrm{~ms} \text {, On-duty } \leq 20 \% \end{aligned}$ | 450 | mA |
| Output continuous current | Iomax1 | OUT1A/B to OUT6A/B | 200 | mA |
| Output continuous current | Iomax2 | OUT7A/B | 300 | mA |
| Storage Temperature | Tstg |  | -55 to 125 | ${ }^{\circ} \mathrm{C}$ |
| Operating Temperature | Topr |  | -20 to 85 | ${ }^{\circ} \mathrm{C}$ |

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.
2) Allowable Operating Range at $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{PGND}=0 \mathrm{~V}$

| Item | Symbol | Conditions | Ratings | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Power Supply Voltage | VM |  | 2.7 to 5.5 | V |

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.
3) Electrical Characteristics at $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{PGND}=0 \mathrm{~V}, \mathrm{VM}=5 \mathrm{~V}$

| Parameter | Symbol | Conditions | Min. | Typ. | Max. | Unit | Applicable pins |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output ON resistance | Ronu | $\mathrm{Io}=200 \mathrm{~mA} \mathrm{Pch}$ |  | 0.85 |  | $\Omega$ | (9) |
|  | Rond | $\mathrm{Io}=200 \mathrm{~mA} \mathrm{Nch}$ |  | 0.45 |  | $\Omega$ |  |
| Output ON resistance | Ronu | $\mathrm{Io}=300 \mathrm{~mA} \mathrm{Pch}$ |  | 0.85 |  | $\Omega$ | (10) |
|  | Rond | $\mathrm{I}=300 \mathrm{~mA} \mathrm{Nch}$ |  | 0.45 |  | $\Omega$ |  |
| Diode forward voltage | VD | ID $=-200 \mathrm{~mA}$ |  | 0.9 |  | V | (9) |
| Diode forward voltage | VD | ID $=-300 \mathrm{~mA}$ |  | 0.9 |  | V | (10) |

* Applicable pins
(9) OUT1A, OUT1B, OUT2A, OUT2B, OUT3A, OUT3B, OUT4A, OUT4B, OUT5A, OUT5B, OUT6A, OUT6B (10) OUT7A, OUT7B

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

## Example of External Circuit

Connection example of oscillation circuit


* In the case of X'tal, it takes about 50 ms for oscillation to stabilize (please check with the manufacturer for a precise time period).


## AC Characteristics

## Power supply, Reset pin



## Specification

| DVDD | : DVDD, OPDAVDD, ADVDD |
| :--- | :--- |
| VH_V | $: 2.7 \mathrm{~V}$ |
| VIL | $: 0.15 \times$ DVDD |


| Parameter | Symbol | Min. | Typ. | Max. | Unit |
| :--- | :--- | :--- | :---: | :---: | :---: |
| The time from the rise of DVDD to the rise of ZRESET | tVtoZR | 1 |  |  |  |
| The time from the fall of DVDD to the fall of ZRESET | tZRtoV | 500 |  |  |  |
| Low period of ZRESET | tRP | 100 |  |  |  |

VM can be turn on/off regardless above power supply AC timing.

ORDERING INFORMATION

| Device | Package | Shipping (Qty / Packing) |
| :---: | :---: | :---: |
| LC898201TA-NH | TQFP64 7x7 <br> (Pb-Free / Halogen Free) | $1000 /$ Tape \& Reel |
| LC898201RA-NH | FBGA64 6x6 <br> (Pb-Free / Halogen Free) | $1000 /$ Tape \& Reel |

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