## High-performance EEPROM Complex Programmable Logic Device

## DATASHEET

## Features

- High-density, High-performance, Electrically-erasable Complex Programmable Logic Device
- 32 Macrocells
- 5 Product Terms per Macrocell, Expandable up to 40 per Macrocell
- 44 Pins
- 7.5ns Maximum Pin-to-pin Delay
- Registered Operation up to 125 MHz
- Enhanced Routing Resources
- In-System Programmability (ISP) via JTAG
- Flexible Logic Macrocell
- D/T Latch Configurable Flip-flops
- Global and Individual Register Control Signals
- Global and Individual Output Enable
- Programmable Output Slew Rate
- Programmable Output Open Collector Option
- Maximum Logic Utilization by Burying a Register with a COM Output
- Advanced Power Management Features
- Automatic 10 10 A Standby for "L" Version
- Pin-controlled 1mA Standby Mode
- Programmable Pin-keeper Inputs and I/Os
- Reduced-power Feature per Macrocell
- Available in Commercial and Industrial Temperature Ranges
- Available in 44-lead PLCC and 44-lead TQFP
- Advanced EEPROM Technology
- 100\% Tested
- Completely Reprogrammable
- 10,000 Program/Erase Cycles
- 20 Year Data Retention
- 2000V ESD Protection
- 200mA Latch-up Immunity
- JTAG Boundary-scan Testing to IEEE Std. 1149.1-1990 and 1149.1a-1993 Supported
- PCI-compliant
- Security Fuse Feature
- Green (Pb/Halide-fee/RoHS Compliant) Package Options


## Enhanced Features

- Improved Connectivity (Additional Feedback Routing, Alternate Input Routing)
- Output Enable Product Terms
- D Latch Mode
- Combinatorial Output with Registered Feedback within Any Macrocell
- Three Global Clock Pins
- ITD (Input Transition Detection) Circuits on Global Clocks, Inputs and I/O ("L" Versions)
- Fast Registered Input from Product Term
- Programmable "Pin-keeper" Option
- $\mathrm{V}_{\mathrm{CC}}$ Power-up Reset Option
- Pull-up Option on JTAG Pins TMS and TDI
- Advanced Power Management Features
- Input Transition Detection
- Power-down ("L" Versions)
- Individual Macrocell Power Option
- Disable ITD on Global Clocks, Inputs, and I/O


## Description

The Atmel ${ }^{\circledR}$ ATF1502AS(L) is a high-performance, high-density Complex Programmable Logic Device (CPLD) which utilizes the Atmel proven electrically-erasable technology. With 32 logic macrocells and up to 36 inputs, it easily integrates logic from several TTL, SSI, MSI, LSI, and classic PLDs. The ATF1502AS(L)'s enhanced routing switch matrices increase usable gate count and the odds of successful pin-locked design modifications.
The ATF1502AS(L) has up to 32 bi-directional I/O pins and four dedicated input pins, depending on the type of device package selected. Each dedicated pin can serve as a global control signal, register clock, register reset, or output enable. Each of these control signals can be selected for use individually within each macrocell.
Each of the 32 macrocells generates a buried feedback which goes to the global bus. Each input and I/O pin also feeds into the global bus. The switch matrix in each logic block then selects 40 individual signals from the global bus. Each macrocell also generates a foldback logic term that goes to a regional bus. Cascade logic between macrocells in the ATF1502AS(L) allows fast, efficient generation of complex logic functions. The ATF1502AS(L) contains four such logic chains, each capable of creating sum term logic with a fan-in of up to 40 product terms.
The ATF1502AS(L) macrocell, shown in Figure 1, is flexible enough to support highly complex logic functions operating at high speed. The macrocell consists of five sections:

- Product Terms and Product Term Select Multiplexer
- OR/XOR/CASCADE Logic
- Flip-flop
- Output Select and Enable
- Logic Array Inputs

Figure 1. ATF1502AS(L) Macrocell


## 1. Pin Configurations and Pinouts

## Figure 1-1. Pinouts




## 2. Block Diagram

Figure 2-1. Block Diagram


Unused product terms are automatically disabled by the compiler to decrease power consumption. A security fuse, when programmed, protects the contents of the ATF1502AS(L). Two bytes (16 bits) of User Signature are accessible to the user for purposes such as storing project name, part number, revision, or date. The User Signature is accessible regardless of the state of the security fuse.

The ATF1502AS(L) device is an In-System Programmable (ISP) device. It uses the industry standard 4-pin JTAG interface (IEEE Std. 1149.1), and is fully compliant with JTAG's Boundary-scan Description Language (BSDL). ISP allows the device to be programmed without removing it from the printed circuit board. In addition to simplifying the manufacturing flow, ISP also allows design modifications to be made in the field via software.

## 3. Macrocell Sections

## Table 3-1. Macrocell Sections

| Section | Description |
| :--- | :--- |
|  | Each ATF1502AS(L) macrocell has five product terms. Each product term receives as its inputs <br> all signals from both the global bus and regional bus. <br> Select Mux |
| The Product Term Select Multiplexer (PTMUX) allocates the five product terms as needed to the <br> macrocell logic gates and control signals. The PTMUX programming is determined by the design <br> compiler, which selects the optimum macrocell configuration. |  |
|  | The ATF1502AS(L) logic structure is designed to efficiently support all types of logic. Within a <br> single macrocell, all the product terms can be routed to the OR gate, creating a 5-input AND/OR <br> sum term. With the addition of the CASIN from neighboring macrocells, this can be expanded to |
| as many as 40 product terms with little additional delay. |  |
| Logic |  |

## 4. Programmable Pin-keeper Option for Inputs and I/Os

The ATF1502AS(L) offers the option of programming all input and I/O pins so the pin-keeper circuits can be utilized. When any pin is driven high or low and then subsequently left floating, it will stay at that previous high or low level. This circuitry prevents unused input and I/O lines from floating to intermediate voltage levels, which causes unnecessary power consumption and system noise. The keeper circuits eliminate the need for external pull-up resistors and eliminate their DC power consumption.

Figure 4-1. Input Diagram


Figure 4-2. I/O Diagram


## 5. Speed/Power Management

The ATF1502AS(L) has several built-in speed and power management features. The ATF1502AS(L) contains circuitry which automatically puts the device into a low-power standby mode when no logic transitions are occurring. This not only reduces power consumption during inactive periods, but also provides proportional power savings for most applications running at system speeds below 50 MHz . This feature may be selected as a design option.
To further reduce power, each ATF1502AS(L) macrocell has a reduced-power bit feature. This feature allows individual macrocells to be configured for maximum power savings. This feature may be selected as a design option.
The ATF1502AS(L) also has an optional power-down mode. In this mode, current drops to below 10 mA . When the power-down option is selected, either PD1 or PD2 pins (or both) can be used to power down the part. The power-down option is selected in the design source file. When enabled, the device goes into power-down when either PD1 or PD2 is high. In the power-down mode, all internal logic signals are latched and held, as are any enabled outputs.

All pin transitions are ignored until the PD pin is brought low. When the power-down feature is enabled, the PD1 or PD2 pin cannot be used as a logic input or output; however, the pin's macrocell may still be used to generate buried foldback and cascade logic signals.
All power-down AC characteristic parameters are computed from external input or I/O pins, with reduced-power bit turned on. For macrocells in reduced-power mode (reduced-power bit turned on), the reduced-power adder, $t_{\text {RPA }}$, must be added to the AC parameters, which include the data paths $t_{\text {LAD }}, t_{\text {LAC }}, t_{1 C}, t_{\text {ACL }}, t_{\text {ACH }}$, and $t_{\text {SEXP }}$.
The ATF1502AS(L) macrocell also has an option whereby the power can be reduced on a per-macrocell basis. By enabling this power-down option, macrocells that are not used in an application can be turned down, thereby reducing the overall power consumption of the device.
Each output also has individual slew rate control. This may be used to reduce system noise by slowing down outputs that do not need to operate at maximum speed. Outputs default to slow switching, and may be specified as fast switching in the design file.

## 6. Design Software Support

ATF1502AS(L) designs are supported by several third-party tools. Automated fitters allow logic synthesis using a variety of high-level description languages and formats.

## 7. Power-up Reset

The ATF1502AS(L) is designed with a power-up reset, a feature critical for state machine initialization. At a point delayed slightly from $\mathrm{V}_{\mathrm{CC}}$ crossing $\mathrm{V}_{\mathrm{RST}}$, all registers will be initialized, and the state of each output will depend on the polarity of its buffer. However, due to the asynchronous nature of reset and uncertainty of how $\mathrm{V}_{\mathrm{CC}}$ actually rises in the system, the following conditions are required:

- The $\mathrm{V}_{\mathrm{CC}}$ rise must be monotonic,
- After reset occurs, all input and feedback setup times must be met before driving the clock pin high, and,
- The clock must remain stable during $T_{D}$.

The ATF1502AS(L) has two options for the hysteresis about the reset level, $\mathrm{V}_{\text {RST }}$, Small and Large. During the fitting process, users may configure the device with the Power-up Reset hysteresis set to Large or Small. Atmel POF2JED users may select the Large option by including the flag "-power_reset" on the command line after "filename.POF". To allow the registers to be properly reinitialized with the Large hysteresis option selected, the following condition is added:

- If $\mathrm{V}_{\mathrm{CC}}$ falls below 2.0 V , it must shut off completely before the device is turned on again.

When the Large hysteresis option is active, $\mathrm{I}_{\mathrm{CC}}$ is reduced by several hundred micro amps as well.

## 8. Security Fuse Usage

A single fuse is provided to prevent unauthorized copying of the ATF1502AS(L) fuse patterns. Once programmed, fuse verify is inhibited; however, the 16-bit User Signature remains accessible.

## 9. Programming

ATF1502AS(L) devices are In-System Programmable (ISP) devices utilizing the 4-pin JTAG protocol. This capability eliminates package handling normally required for programming and facilitates rapid design iterations and field changes.
Atmel provides ISP hardware and software to allow programming of the ATF1502AS(L) via the PC. ISP is performed by using either a download cable, a comparable board tester, or a simple microprocessor interface.
When using the ISP hardware or software to program the ATF1502AS(L) devices, four I/O pins must be reserved for the JTAG interface. However, the logic features that the macrocells have associated with these I/O pins are still available to the design for burned logic functions.
To facilitate ISP programming by the Automated Test Equipment (ATE) vendors, Serial Vector Format (SVF) files can be created by Atmel-provided software utilities.

ATF1502AS(L) devices can also be programmed using standard third-party programmers. With a third-party programmer, the JTAG ISP port can be disabled, thereby allowing four additional I/O pins to be used for logic.

Contact your local Atmel representatives or Atmel PLD applications for details.

## 10. ISP Programming Protection

The ATF1502AS(L) has a special feature which locks the device and prevents the inputs and I/O from driving if the programming process is interrupted for any reason. The inputs and I/O default to high-Z state during such a condition. In addition, the pin-keeper option preserves the previous state of the input and I/O PMS during programming.

All ATF1502AS(L) devices are initially shipped in the erased state, thereby making them ready to use for ISP.
Note: For more information refer to the "Designing for In-System Programmability with Atmel CPLDs" application note.

## 11. Electrical Characteristics

### 11.1 Absolute Maximum Ratings*

Temperature Under Bias . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Storage Temperature . . . . . . . . . . . . . . . . . $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Voltage on Any Pin with
Respect to Ground . . . . . . . . . . . . . . . . . . . -2.0 V to $+7.0 \mathrm{~V}^{(1)}$
Voltage on Input Pins with Respect
to Ground During Programming . . . . . . . . . -2.0 V to $+14.0 \mathrm{~V}^{(1)}$
Programming Voltage with
Respect to Ground . . . . . . . . . . . . . . . . . . . -2.0 V to $+14.0 \mathrm{~V}^{(1)}$
*Notice: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note: 1. Minimum voltage is -0.6 VDC , which may undershoot to -2.0 V for pulses of less than 20 ns. Maximum output pin voltage is $\mathrm{V}_{\mathrm{CC}}+0.75 \mathrm{VDC}$, which may overshoot to 7.0 V for pulses of less than 20 ns .

### 11.2 Pin Capacitance

Table 11-1. $\quad$ Pin Capacitance ${ }^{(1)}$

|  | Typ | Max | Units | Conditions |
| :--- | :---: | :---: | :---: | :---: |
| $\mathrm{C}_{\mathrm{IN}}$ | 8 | 10 | pF | $\mathrm{V}_{\text {IN }}=0 \mathrm{~V} ; \mathrm{f}=1 \mathrm{MHz}$ |
| $\mathrm{C}_{\mathrm{I/O}}$ | 8 | 10 | pF | $\mathrm{V}_{\text {OUT }}=0 \mathrm{~V} ; \mathrm{f}=1 \mathrm{MHz}$ |

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not $100 \%$ tested. The OGI pin (high-voltage pin during programming) has a maximum capacitance of 12 pF .

### 11.3 DC and AC Operating Conditions

Table 11-2. DC and AC Operating Conditions

|  | Commercial | Industrial |
| :--- | :---: | :---: |
| Operating Temperature (Ambient) | $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| $\mathrm{V}_{\mathrm{CC}}(5.0 \mathrm{~V})$ Power Supply | $5 \mathrm{~V} \pm 5 \%$ | $5 \mathrm{~V} \pm 10 \%$ |

### 11.4 DC Characteristics

Table 11-3. DC Characteristics

| Symbol | Parameter | Condition | Min | Typ | Max | Units |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathrm{I}_{\mathrm{IL}}$ | Input or I/O Low <br> Leakage Current | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{CC}}$ |  |  |  |  |

Notes: 1. Not more than one output at a time should be shorted. Duration of short circuit test should not exceed 30s.
2. $\mathrm{I}_{\mathrm{CC} 3}$ refers to the current in the reduced-power mode when macrocell reduced-power is turned on.

### 11.5 AC Characteristics

Table 11-4. AC Characteristics ${ }^{(11.9)}$

| Symbol | Parameter | -7 |  | -10 |  | -25 |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{t}_{\text {PD1 }}$ | Input or Feedback to Non-registered Output |  | 7.5 |  | 10 |  | 25 | ns |
| $\mathrm{t}_{\text {PD2 }}$ | I/O Input or Feedback to Non-registered Feedback |  | 7 |  | 9 |  | 25 | ns |
| $\mathrm{t}_{\text {SU }}$ | Global Clock Setup Time | 6 |  | 7 |  | 20 |  | ns |
| $t_{H}$ | Global Clock Hold Time | 0 |  | 0 |  | 0 |  | ns |
| $\mathrm{t}_{\text {FSU }}$ | Global Clock Setup Time of Fast Input | 3 |  | 3 |  | 5 |  | ns |
| $\mathrm{t}_{\mathrm{FH}}$ | Global Clock Hold Time of Fast Input | 0.5 |  | 0.5 |  | 2 |  | MHz |
| $\mathrm{t}_{\text {COP }}$ | Global Clock to Output Delay |  | 4.5 |  | 5 |  | 13 | ns |
| $\mathrm{t}_{\mathrm{CH}}$ | Global Clock High Time | 3 |  | 4 |  | 7 |  | ns |
| $\mathrm{t}_{\mathrm{CL}}$ | Global Clock Low Time | 3 |  | 4 |  | 7 |  | ns |
| $\mathrm{t}_{\text {ASU }}$ | Array Clock Setup Time | 3 |  | 3 |  | 5 |  | ns |
| $\mathrm{t}_{\text {AH }}$ | Array Clock Hold Time | 2 |  | 3 |  | 6 |  | ns |
| $\mathrm{t}_{\text {ACOP }}$ | Array Clock Output Delay |  | 7.5 |  | 10 |  | 25 | ns |
| $\mathrm{t}_{\mathrm{ACH}}$ | Array Clock High Time | 3 |  | 4 |  | 10 |  | ns |
| $\mathrm{t}_{\text {ACL }}$ | Array Clock Low Time | 3 |  | 4 |  | 10 |  | ns |
| $\mathrm{t}_{\mathrm{CNT}}$ | Minimum Clock Global Period |  | 8 |  | 10 |  | 22 | ns |
| $\mathrm{f}_{\mathrm{CNT}}$ | Maximum Internal Global Clock Frequency | 125 |  | 100 |  | 50 |  | MHz |
| $\mathrm{t}_{\text {ACNT }}$ | Minimum Array Clock Period |  | 8 |  | 10 |  | 22 | ns |
| $\mathrm{f}_{\text {ACNT }}$ | Maximum Internal Array Clock Frequency | 125 |  | 100 |  | 50 |  | MHz |
| $\mathrm{f}_{\text {MAX }}$ | Maximum Clock Frequency | 166.7 |  | 125 |  | 60 |  | MHz |
| $\mathrm{t}_{\mathrm{IN}}$ | Input Pad and Buffer Delay |  | 0.5 |  | 0.5 |  | 2 | ns |
| $\mathrm{t}_{10}$ | I/O Input Pad and Buffer Delay |  | 0.5 |  | 0.5 |  | 2 | ns |
| $\mathrm{t}_{\text {FIN }}$ | Fast Input Delay |  | 1 |  | 1 |  | 2 | ns |
| $\mathrm{t}_{\text {SEXP }}$ | Foldback Term Delay |  | 4 |  | 5 |  | 12 | ns |
| $t_{\text {PEXP }}$ | Cascade Logic Delay |  | 0.8 |  | 0.8 |  | 2 | ns |
| $t_{\text {LAD }}$ | Logic Array Delay |  | 3 |  | 5 |  | 8 | ns |
| $\mathrm{t}_{\text {LAC }}$ | Logic Control Delay |  | 3 |  | 5 |  | 8 | ns |
| $\mathrm{t}_{\text {IOE }}$ | Internal Output Enable Delay |  | 2 |  | 2 |  | 4 | ns |
| $\mathrm{t}_{\mathrm{OD} 1}$ | Output Buffer and Pad Delay <br> (Slow slew rate $=$ OFF; $\mathrm{V}_{\mathrm{CC}}=5.0 \mathrm{~V} ; \mathrm{C}_{\mathrm{L}}=35 \mathrm{pF}$ ) |  | 2 |  | 1.5 |  | 6 | ns |

Notes: 1. See ordering information for valid part numbers.
2. The $t_{\text {RPA }}$ parameter must be added to the $t_{\text {LAD }}, t_{\text {LAC }}, t_{T I C}, t_{\text {ACL }}$, and $t_{\text {SEXP }}$ parameters for macrocells running in the reduced-power mode.

Table 11-4. AC Characteristics ${ }^{(11.9)}$ (Continued)

| Symbol | Parameter | -7 |  | -10 |  | -25 |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{t}_{\mathrm{zx} 1}$ | Output Buffer Enable Delay <br> (Slow slew rate $=$ OFF; $\mathrm{V}_{\mathrm{CCIO}}=5.0 \mathrm{~V} ; \mathrm{C}_{\mathrm{L}}=35 \mathrm{pF}$ ) |  | 4.0 |  | 5.0 |  | 10 | ns |
| $\mathrm{t}_{\mathrm{zx} 2}$ | Output Buffer Enable Delay <br> (Slow slew rate $=$ OFF; $\mathrm{V}_{\text {CCIO }}=3.3 \mathrm{~V} ; \mathrm{C}_{\mathrm{L}}=35 \mathrm{pF}$ ) |  | 4.5 |  | 5.5 |  | 10 | ns |
| $\mathrm{t}_{\mathrm{zx} 3}$ | Output Buffer Enable Delay <br> (Slow slew rate $=\mathrm{ON} ; \mathrm{V}_{\mathrm{CCIO}}=5.0 \mathrm{~V} / 3.3 \mathrm{~V} ; \mathrm{C}_{\mathrm{L}}=35 \mathrm{pF}$ ) |  | 9 |  | 9 |  | 12 | ns |
| $t_{x z}$ | Output Buffer Disable Delay ( $\left.\mathrm{C}_{\mathrm{L}}=5 \mathrm{pF}\right)$ |  | 4 |  | 5 |  | 8 | ns |
| $t_{s u}$ | Register Setup Time | 3 |  | 3 |  | 6 |  | ns |
| $t_{H}$ | Register Hold Time | 2 |  | 3 |  | 6 |  | ns |
| $\mathrm{t}_{\text {FSU }}$ | Register Setup Time of Fast Input | 3 |  | 3 |  | 3 |  | ns |
| $\mathrm{t}_{\text {FH }}$ | Register Hold Time of Fast Input | 0.5 |  | 0.5 |  | 5 |  | ns |
| $\mathrm{t}_{\mathrm{RD}}$ | Register Delay |  | 1 |  | 2 |  | 2 | ns |
| $\mathrm{t}_{\text {COMB }}$ | Combinatorial Delay |  | 1 |  | 2 |  | 2 | ns |
| $\mathrm{t}_{1 \mathrm{C}}$ | Array Clock Delay |  | 3 |  | 5 |  | 8 | ns |
| $\mathrm{t}_{\mathrm{EN}}$ | Register Enable Time |  | 3 |  | 5 |  | 8 | ns |
| $\mathrm{t}_{\text {GLOB }}$ | Global Control Delay |  | 1 |  | 1 |  | 1 | ns |
| $t_{\text {PRE }}$ | Register Preset Time |  | 2 |  | 3 |  | 6 | ns |
| $\mathrm{t}_{\text {CLR }}$ | Register Clear Time |  | 2 |  | 3 |  | 6 | ns |
| $t_{\text {UIM }}$ | Switch Matrix Delay |  | 1 |  | 1 |  | 2 | ns |
| $\mathrm{t}_{\text {RPA }}$ | Reduced-power Adder ${ }^{(2)}$ |  | 10 |  | 11 |  | 15 | ns |

Notes: 1. See ordering information for valid part numbers.
2. The $t_{\text {RPA }}$ parameter must be added to the $t_{\text {LAD }}, t_{\text {LAC }}, t_{T I C}, t_{A C L}$, and $t_{\text {SEXP }}$ parameters for macrocells running in the reduced-power mode.

### 11.6 Timing Model

Figure 11-1. Timing Model


### 11.7 Input Test Waveforms and Measurement Levels

Figure 11-2. Input Test Waveforms and Measurement Levels

AC
Driving
Levels


Note: $\quad t_{R}, t_{F}=1.5 n s$ typical

### 11.8 Output AC Test Loads

Figure 11-3. Output AC Test Loads


### 11.9 Power-down Mode

The ATF1502AS(L) includes an optional pin-controlled power-down feature. When this mode is enabled, the PD pin acts as the power-down pin. When the PD pin is high, the device supply current is reduced to less than 5 mA . During power-down, all output data and internal logic states are latched and held. Therefore, all registered and combinatorial output data remain valid. Any outputs that were in a high-Z state at the onset will remain at high-Z. During power-down, all input signals except the power-down pin are blocked. Input and I/O hold latches remain active to ensure the pins do not float to indeterminate levels, further reducing system power. The power-down pin feature is enabled in the logic design file. Designs using the power-down pin may not use the PD pin logic array input; however, all other PD pin macrocell resources may still be used, including the buried feedback and foldback product term array inputs.

### 11.9.1 Power-down AC Characteristics

Table 11-5. Power-down AC Characteristics ${ }^{(1)(2)}$

| Symbol | Parameter | -7 |  | -10 |  | -25 |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Min | Max | Min | Max |  |
| $\mathrm{t}_{\mathrm{IVDH}}$ | Valid I, I/O before PD High | 7 |  | 10 |  | 25 |  | ns |
| $\mathrm{t}_{\text {GVDH }}$ | Valid $\mathrm{OE}^{(2)}$ before PD High | 7 |  | 10 |  | 25 |  | ns |
| $\mathrm{t}_{\text {CVDH }}$ | Valid Clock $^{(2)}$ before PD High | 7 |  | 10 |  | 25 |  | ns |
| $\mathrm{t}_{\text {DHIX }}$ | I, I/O Don't Care after PD High |  | 12 |  | 15 |  | 35 | ns |
| $\mathrm{t}_{\text {DHGX }}$ | OE ${ }^{(2)}$ Don't Care after PD High |  | 12 |  | 15 |  | 35 | ns |
| $\mathrm{t}_{\text {DHCX }}$ | Clock ${ }^{(2)}$ Don't Care after PD High |  | 12 |  | 15 |  | 35 | ns |
| $\mathrm{t}_{\text {DLIV }}$ | PD Low to Valid I, I/O |  | 1 |  | 1 |  | 1 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {DLGV }}$ | PD Low to Valid OE (Pin or Term) |  | 1 |  | 1 |  | 1 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {DLCV }}$ | PD Low to Valid Clock (Pin or Term) |  | 1 |  | 1 |  | 1 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {DLov }}$ | PD Low to Valid Output |  | 1 |  | 1 |  | 1 | $\mu \mathrm{s}$ |

Notes: 1. For slow slew outputs, add $\mathrm{t}_{\text {sso }}$.
2. Pin or product term.

## 12. JTAG-BST/ISP Overview

The JTAG boundary-scan testing is controlled by the Test Access Port (TAP) controller in the ATF1502AS(L). The boundary-scan technique involves the inclusion of a shift-register stage (contained in a Boundary-Scan Cell) adjacent to each component so signals at component boundaries can be controlled and observed using scan testing methods. Each input pin and I/O pin has its own Boundary-Scan Cell (BSC) to support Boundary-Scan Testing (BST). The ATF1502AS(L) does not include a Test Reset (TRST) input pin because the TAP controller is automatically reset at power-up. The five JTAG modes supported include:

- SAMPLE/PRELOAD
- EXTEST
- BYPASS
- IDCODE
- HIGHZ

The ATF1502AS(L) ISP can fully be described using JTAG's BSDL as described in IEEE Standard 1149.1b. This allows ATF1502AS(L) programming to be described and implemented using any one of the third-party development tools supporting this standard.
The ATF1502AS(L) has the option of using four JTAG-standard I/O pins for BST and ISP purposes. The ATF1502AS(L) is programmable through the four JTAG pins using the IEEE standard JTAG programming protocol established by IEEE Standard 1149.1 using 5V TTL-level programming signals from the ISP interface for in-system programming. The JTAG feature is a programmable option. If JTAG (BST or ISP) is not needed, then the four JTAG control pins are available as I/O pins.

## 13. JTAG Boundary-scan Cell (BSC) Testing

The ATF1502AS(L) contains up to 32 I/O pins and four input pins, depending on the device type and package type selected. Each input pin and I/O pin has its own BSC in order to support BST as described in detail by IEEE Standard 1149.1. A typical BSC consists of three capture registers or scan registers and up to two update registers. There are two types of BSCs, one for input or I/O pin and one for the macrocells. The BSCs in the device are chained together through the capture registers. Input to the capture register chain is fed in from the TDI pin while the output is directed to the TDO pin. Capture registers are used to capture active device data signals, to shift data in and out of the device, and to load data into the update registers. Control signals are generated internally by the JTAG TAP controller. The BSC configuration for the input and I/O pins and macrocells is shown below.

Figure 13-1. BSC Configuration for Input and I/O Pins (Except JTAG TAP Pins)


Note: 1. The ATF1502AS(L) has a pull-up option on TMS and TDI pins. This feature is selected as a design option.

Figure 13-2. BSC Configuration for Macrocell


BSC for I/O Pins and Macrocells

## 14. PCI Compliance

The ATF1502AS(L) supports the growing need in the industry to support the new Peripheral Component Interconnect (PCI) interface standard in PCl-based designs and specifications. The PCI interface calls for high current drivers, which are much larger than the traditional TTL drivers. In general, PLDs and FPGAs parallel outputs to support the high current load required by the PCI interface. The ATF1502AS(L) allows this without contributing to system noise while delivering low output to output skew. Having a programmable high drive option is also possible without increasing output delay or pin capacitance.

Figure 14-1. PCI Voltage-to-current Curves for +5.0V Signaling in Pull-up Mode

Figure 14-2. PCI Voltage-to-current Curves for +5.0V Signaling in Pull-down Mode

Table 14-1. PCI DC Characteristics

| Symbol | Parameter | Conditions | Min | Max | Units |
| :--- | :--- | :--- | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage |  | 4.75 | 5.25 | V |
| $\mathrm{~V}_{\text {IH }}$ | Input High Voltage |  | 2.0 | $\mathrm{~V}_{\mathrm{CC}}+0.5$ | V |
| $\mathrm{~V}_{\mathrm{IL}}$ | Input Low Voltage |  | -0.5 | 0.8 | V |
| $\mathrm{I}_{\mathrm{IH}}$ | Input High Leakage Current ${ }^{(1)}$ | $\mathrm{V}_{\text {IN }}=2.7 \mathrm{~V}$ |  | 70 | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{\mathrm{IL}}$ | Input Low Leakage Current ${ }^{(1)}$ | $\mathrm{V}_{\text {IN }}=0.5 \mathrm{~V}$ |  | -70 | $\mu \mathrm{~A}$ |
| $\mathrm{~V}_{\text {OH }}$ | Output High Voltage | $\mathrm{I}_{\text {OUT }}=-2 \mathrm{~mA}$ |  | 2.4 |  |
| $\mathrm{~V}_{\text {OL }}$ | Output Low Voltage | $\mathrm{I}_{\text {OUT }}=3 \mathrm{~mA}, 6 \mathrm{~mA}$ |  | 0.55 | V |
| $\mathrm{C}_{\text {IN }}$ | Input Pin Capacitance |  |  | 10 | pF |
| $\mathrm{C}_{\text {CLK }}$ | CLK Pin Capacitance |  |  | 12 | pF |
| $\mathrm{C}_{\text {IDSEL }}$ | IDSEL Pin Capacitance |  |  | 8 | pF |
| $\mathrm{L}_{\text {PIN }}$ | Pin Inductance |  |  | 20 | nH |

Note: 1. Leakage current is with pin-keeper off.

Table 14-2. PCI AC Characteristics

| Symbol | Parameter | Conditions | Min | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{OH}(\mathrm{AC})}$ | Switching Current High (Test High) | $0<\mathrm{V}_{\text {OUT }} \leq 1.4$ | -44 |  | mA |
|  |  | $1.4<\mathrm{V}_{\text {OUT }}<2.4$ | $-44+\left(\mathrm{V}_{\text {OUT }}-1.4\right) / 0.024$ |  | mA |
|  |  | $3.1<\mathrm{V}_{\text {OUT }}<\mathrm{V}_{\text {CC }}$ |  | Equation A | mA |
|  |  | $\mathrm{V}_{\text {OUT }}=3.1 \mathrm{~V}$ |  | -142 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {OL(AC) }}$ | Switching Current Low (Test Point) | $\mathrm{V}_{\text {OUT }}>2.2 \mathrm{~V}$ | 95 |  | mA |
|  |  | $2.2>\mathrm{V}_{\text {OUT }}>0$ | $\mathrm{V}_{\text {OUT }} / 0.023$ |  | mA |
|  |  | $0.1>\mathrm{V}_{\text {OUT }}>0$ |  | Equation B | mA |
|  |  | $\mathrm{V}_{\text {OUT }}=0.71$ |  | 206 | mA |
| $\mathrm{I}_{\mathrm{CL}}$ | Low Clamp Current | $-5<\mathrm{V}_{\text {IN }} \leq-1$ | $-25+\left(\mathrm{V}_{\text {IN }}+1\right) / 0.015$ |  | mA |
| SLEW $_{\text {R }}$ | Output Rise Slew Rate | 0.4 V to 2.4 V Load | 1 | 5 | V/ns |
| SLEW $_{\text {F }}$ | Output Fall Slew Rate | 2.4V to 0.4V Load | 1 | 5 | V/ns |

Notes: 1. Equation $\mathrm{A}: \mathrm{I}_{\mathrm{OH}}=11.9\left(\mathrm{~V}_{\mathrm{OUT}}-5.25\right)^{*}\left(\mathrm{~V}_{\mathrm{OUT}}+2.45\right)$ for $\mathrm{V}_{\mathrm{CC}}>\mathrm{V}_{\mathrm{OUT}}>3.1 \mathrm{~V}$.
2. Equation $\mathrm{B}: \mathrm{I}_{\mathrm{OL}}=78.5^{*} \mathrm{~V}_{\text {OUT }}{ }^{*}\left(4.4-\mathrm{V}_{\text {OUT }}\right)$ for $\mathrm{OV}<\mathrm{V}_{\text {OUT }}<0.71 \mathrm{~V}$.

## 15. Pinouts

### 15.1 ATF1502AS(L) Dedicated Pinouts

| Dedicated Pin | 44-lead <br> TQFP | $44-l e a d$ <br> J-lead |
| :--- | :---: | :---: |
| INPUT/OE2/GCLK2 | 40 | 2 |
| INPUT/GCLR | 39 | 1 |
| INPUT/OE1 | 38 | 44 |
| INPUT/GCLK1 | 37 | 43 |
| I/O / GCLK3 | 35 | 41 |
| I/O / PD (1,2) | 5,19 | 11,25 |
| I/O / TDI (JTAG) | 1 | 7 |
| I/O / TMS (JTAG) | 7 | 13 |
| I/O / TCK (JTAG) | 26 | 32 |
| I/O / TDO (JTAG) | 32 | 38 |
| GND | $4,16,24,36$ | $10,22,30,42$ |
| VCC | $9,17,29,41$ | $3,15,23,35$ |
| \# of Signal Pins | 36 | 36 |
| \# User I/O Pins | 32 | 32 |

## Note:

OE $(1,2) \ldots \ldots . .$. . . . . . . Global OE pins
GCLR . . . . . . . . . . Global Clear pin
$\operatorname{GCLK}(1,2,3) \ldots . . . .$. . Global Clock pins
PD $(1,2)$. . . . . . . . . . . . . Power-down pins
TDI, TMS, TCK, TDO . . . JTAG pins used for boundary-scan testing or in-system programming GND . . . . . . . . . . . . . . . Ground pins
$\mathrm{V}_{\mathrm{CC}} \ldots \ldots \ldots . . . . . . . \mathrm{V}_{\mathrm{CC}}$ pins for the device $(+5 \mathrm{~V})$

### 15.2 ATF1502AS(L) I/O Pinouts

| MC | PLC | 44-lead PLCC | 44-lead TQFP |
| :---: | :---: | :---: | :---: |
| 1 | A | 4 | 42 |
| 2 | A | 5 | 43 |
| 3 | A/PD1 | 6 | 44 |
| 4/TDI | A | 7 | 1 |
| 5 | A | 8 | 2 |
| 6 | A | 9 | 3 |
| 7 | A | 11 | 5 |
| 8 | A | 12 | 6 |
| 9/TMS | A | 13 | 7 |
| 10 | A | 14 | 8 |
| 11 | A | 16 | 10 |
| 12 | A | 17 | 11 |
| 13 | A | 18 | 12 |
| 14 | A | 19 | 13 |
| 15 | A | 20 | 14 |
| 16 | A | 21 | 15 |
| 17 | B | 41 | 35 |
| 18 | B | 40 | 34 |
| 19 | B | 39 | 33 |
| 20/TDO | B | 38 | 32 |
| 21 | B | 37 | 31 |
| 22 | B | 36 | 30 |
| 23 | B | 34 | 28 |
| 24 | B | 33 | 27 |
| 25/TCK | B | 32 | 26 |
| 26 | B | 31 | 25 |
| 27 | B | 29 | 23 |
| 28 | B | 28 | 22 |
| 29 | B | 27 | 21 |
| 30 | B | 26 | 20 |
| 31 | B | 25 | 19 |
| 32 | B | 24 | 18 |

SUPPLY CURRENT VS. SUPPLY VOLTAGE AS VERSION ( $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{F}=0$ )


SUPPLY CURRENT VS.SUPPLY VOLTAGE PIN-CONTROLLED POWER-DOWN MODE $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{F}=0\right)$


SUPPLY CURRENT VS. FREQUENCY
AS VERSION $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$


OUTPUT SOURCE CURRENT VS. SUPPLY VOLTAGE
$\left(\mathrm{V}_{\mathrm{OH}}=2.4 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$


SUPPLY CURRENT VS. SUPPLY VOLTAGE ( $\mathrm{T}=25^{\circ} \mathrm{C}$, NON - TURBO, BIT6 $=0$, BIT $30=0$ )


SUPPLY CURRENT VS. FREQUENCY ASL (LOW-POWER) VERSION ( $\mathrm{T}_{\mathrm{A}}=\mathbf{2 5}{ }^{\circ} \mathrm{C}$ )


INPUT CLAMP CURRENT VS. INPUT VOLTAGE


OUTPUT SOURCE CURRENT VS. OUTPUT VOLTAGE $\left(\mathrm{V}_{\mathrm{cC}}=5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$


OUTPUT SINK CURRENT VS. SUPPLY VOLTAGE $\left(\mathrm{VOL}=0.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$


INPUT CURRENT VS.INPUT VOLTAGE


NORMALIZED TPD
VS.TEMPERATURE ( $\mathrm{V}_{\mathrm{cc}}=5.0 \mathrm{~V}$ )


NORMALIZEDTSU VS.SUPPLY VOLTAGE $\left(\mathrm{T}_{\mathrm{A}}=\mathbf{2 5}{ }^{\circ} \mathrm{C}\right)$


NORMALIZED TPD
VS. SUPPLY VOLTAGE $\left(\mathrm{T}_{\mathrm{A}}=\mathbf{2 5}{ }^{\circ} \mathrm{C}\right)$


OUTPUT SINK CURRENT VS. OUTPUT VOLTAGE


NORMALIZED TCO
VS. SUPPLY VOLTAGE ( $\mathrm{T}_{\mathrm{A}}=\mathbf{2 5}{ }^{\circ} \mathrm{C}$ )


NORMALIZED TCO VS. TEMPERATURE ( $\mathrm{V}_{\mathrm{cc}}=5.0 \mathrm{~V}$ )



## 16. Ordering Information

### 16.1 Green Package Options (Pb/Halide-free/RoHS Compliant)

| $\begin{gathered} \mathrm{t}_{\mathrm{PD}} \\ \text { (ns) } \end{gathered}$ | $\mathrm{t}_{\mathrm{CO} 1}$ <br> (ns) | $\mathbf{f}_{\text {MAX }}$ $(\mathrm{MHz})$ | Ordering Code | Package | Operation Range |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7.5 | 4.5 | 166.7 | ATF1502AS-7AX44 | 44A | Commercial $\left(0^{\circ} \mathrm{C}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
|  |  |  | ATF1502AS-7JX44 | 44J |  |
| 10 | 5 | 125 | ATF1502AS-10AU44 | 44A | Industrial$\left(-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C}\right)$ |
|  |  |  | ATF1502AS-10JU44 | 44J |  |
| 25 | 13 | 60 | ATF1502ASL-25AU44 | 44A | $\begin{gathered} \text { Industrial } \\ \left(-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C}\right) \end{gathered}$ |
|  |  |  | ATF1502ASL-25JU44 | 44J |  |

## Package Type

44A 44-lead, Thin Plastic Gull Wing Quad Flatpack Package (TQFP)
44J 44-lead, Plastic J-leaded Chip Carrier OTP (PLCC)

## 17. Packaging Information

### 17.1 44A - 44-lead TQFP



COMMON DIMENSIONS
(Unit of Measure $=\mathrm{mm}$ )

| COMMON DIMENSIONS <br> (Unit of Measure $=$ mm $)$ |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| SYMBOL MIN NOM MAX NOTE   <br> A - - 1.20    <br> A1 0.05 - 0.15    <br> A2 0.95 1.00 1.05    <br> D 11.75 12.00 12.25    <br> D1 9.90 10.00 10.10 Note 2   <br> E 11.75 12.00 12.25    <br> E1 9.90 10.00 10.10 Note 2   <br> B 0.30 - 0.45    <br> C 0.09 - 0.20    <br> L 0.45 - 0.75    <br> e 0.80 TYP      |  |  |  |  |  |

Notes: 1. This package conforms to JEDEC reference MS-026, Variation ACB.
2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.
3. Lead coplanarity is 0.10 mm maximum.

1/10/13

| Atmel <br> Package Drawing Contact: packagedrawings@atmel.com | TITLE <br> 44A, 44-lead $10.0 \times 10.0 \times 1.0 \mathrm{~mm}$ Body, 0.80 mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP) | GPC AIX | DRAWING NO. 44A | REV. <br> D |
| :---: | :---: | :---: | :---: | :---: |

### 17.2 44J - 44-lead PLCC



Notes: 1. This package conforms to JEDEC reference MS-018, Variation AC.
2. Dimensions D1 and E1 do not include mold protrusion.

Allowable protrusion is .010 " $(0.254 \mathrm{~mm}$ ) per side. Dimension D1 and E1 include mold mismatch and are measured at the extreme material condition at the upper or lower parting line.
3. Lead coplanarity is $0.004^{\prime \prime}(0.102 \mathrm{~mm})$ maximum.

COMMON DIMENSIONS
(Unit of Measure $=\mathrm{mm}$ )

| SYMBOL | MIN | NOM | MAX | NOTE |
| :---: | :---: | :---: | :---: | :---: |
| A | 4.191 | - | 4.572 |  |
| A1 | 2.286 | - | 3.048 |  |
| A2 | 0.508 | - | - |  |
| D | 17.399 | - | 17.653 |  |
| D1 | 16.510 | - | 16.662 | Note 2 |
| E | 17.399 | - | 17.653 |  |
| E1 | 16.510 | - | 16.662 | Note 2 |
| D2/E2 | 14.986 | - | 16.002 |  |
| B | 0.660 | - | 0.813 |  |
| B1 | 0.330 | - | 0.533 |  |
| e | 1.270 TYP |  |  |  |

10/04/01

## Atmel

Package Drawing Contact: packagedrawings@atmel.com

## TITLE

44J, 44-lead, Plastic J-leaded Chip Carrier (PLCC)

| DRAWING NO. | REV. |
| :---: | :---: |
| 44 J | B |

## 18. Revision History

| Revision | Date | Comments |
| :---: | :---: | :--- |
| 0995 L | $03 / 2014$ | Remove lead based package offering and 15ns speed grade. <br> Update template, logos, and disclaimer page. |
| 0995 K | $06 / 2005$ | Green package options added. |

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