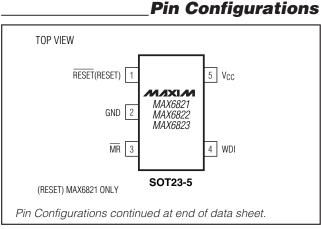
## **General Description**

The MAX6821–MAX6825 are low-voltage microprocessor ( $\mu$ P) supervisory circuits that combine voltage monitoring, watchdog timer, and manual reset input functions in a 5-pin SOT23 package. Microprocessor supervisory circuits significantly improve system reliability and accuracy compared to separate ICs or discrete components. These devices assert a reset signal whenever the monitored voltage drops below its preset threshold, keeping it asserted for a minimum timeout period after V<sub>CC</sub> rises above the threshold. In addition, a watchdog timer monitors against code execution errors. A debounced manual reset is also available. The MAX6821–MAX6825 monitor voltages from +1.8V to +5.0V. These outputs are guaranteed to be in the correct state for V<sub>CC</sub> down to +1.0V.

Nine preprogrammed reset threshold voltages are available (see the *Threshold Suffix Guide*). The MAX6821, MAX6822, and MAX6823 all have a manual reset input and a watchdog timer. The MAX6821 has push-pull RESET, the MAX6822 has open-drain RESET, and the MAX6823 has push-pull RESET. The MAX6824 has a watchdog timer and both push-pull RESET and push-pull RESET. The MAX6825 has a manual reset input and both push-pull RESET and push-pull RESET. The *Selector Guide* explains the functions offered in this series of parts.

## Applications

Set-Top Boxes Computers and Controllers Embedded Controllers Intelligent Instruments Automotive Systems Critical µP Monitoring Portable/Battery-Powered Equipment



Typical Operating Circuit appears at end of data sheet.

# M/IXI/M

#### \_Features

Monitors +1.8V, +2.5V, +3.0V, +3.3V, +5.0V
 Supplies

МЛХГМ

- 140ms (min) Reset Timeout Delay
- 1.6s Watchdog Timeout Period (MAX6821/MAX6822/MAX6823/MAX6824)
- Manual Reset Input (MAX6821/MAX6822/MAX6823/MAX6825)
- Three Reset Output Options
   Push-Pull RESET
   Push-Pull RESET
   Open-Drain RESET
- ♦ Guaranteed Reset Valid to V<sub>CC</sub> = +1.0V
- Immune to Short Negative VCC Transients
- No External Components
- ♦ Small 5-Pin SOT23 Packages

## **\_Ordering Information**

PART*	TEMP RANGE	PIN-PACKAGE
MAX6821_UK-T	-40°C to +125°C	5 SOT23-5
MAX6822_UK-T	-40°C to +125°C	5 SOT23-5
MAX6823_UK-T	-40°C to +125°C	5 SOT23-5
MAX6824_UK-T	-40°C to +125°C	5 SOT23-5
MAX6825_UK-T	-40°C to +125°C	5 SOT23-5

\* Insert the desired suffix letter (from the table below) into the blank to complete the part number

Devices are available in both leaded and lead-free packaging. Specify lead-free by replacing "-T" with "+T" when ordering.

# Threshold Suffix Guide

SUFFIX	RESET THRESHOLD (V)		
L	4.63		
М	4.38		
Т	3.08		
S	2.93		
R	2.63		
Z	2.32		
Y	2.19		
W	1.67		
V	1.58		

**Note:** Bold indicates standard versions. Samples are typically available for standard versions only. All parts require a 2.5k minimum order increment. Contact factory for availability.

Selector Guide appears at end of data sheet.

#### Maxim Integrated Products 1

res

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

## **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub> to GND0.3V to +6.0V
Open-Drain RESET0.3V to +6.0V
Push-Pull RESET, RESET, MR, WDI0.3V to (V <sub>CC</sub> + 0.3V)
Input Current (V <sub>CC</sub> )20mA
Output Current (RESET, RESET)20mA
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
5-Pin SOT23 (derate 7.1mW/°C above +70°C)571mW

Operating Temperature Range	40°C to +125°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

# **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = +4.5V \text{ to } +5.5V \text{ for MAX682_L/M}, V_{CC} = +2.7V \text{ to } +3.6V \text{ for MAX682_T/S/R}, V_{CC} = +2.1V \text{ to } +2.75V \text{ for MAX682_Z/Y}, V_{CC} = +1.53V \text{ to } +2.0V \text{ for MAX682_W/V}, T_A = -40^{\circ}C \text{ to } +125^{\circ}C, \text{ unless otherwise specified. Typical values are at T_A = +25^{\circ}C.}$  (Note 1)

PARAMETER	SYMBOL	COND	MIN	ТҮР	MAX	UNITS	
Operating Voltage Range		$T_A = 0^{\circ}C$ to $+85^{\circ}C$	1.0		5.5		
	Vcc	$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$	1.2		5.5	V	
		$V_{CC} = +5.5V$ , no load	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$		10	20	
			$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$			30	
V <sub>CC</sub> Supply Current		$V_{CC} = +3.6V$ , no load	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$		7	16	
(MR and WDI Unconnected)	lcc	$V_{CC} = +3.0V, 11010a0$	$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$			25	μA
		$V_{CC} = +3.6V$ , no load	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$		5	12	
		(MAX6825 only)	$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$			20	1
		MAX682_L	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	4.50	4.63	4.75	V
		WAX002_L	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	4.47	4.63	4.78	
		MAX682_M	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	4.25	4.38	4.50	
			$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	4.22	4.38	4.53	
	VTH	MAX682_T	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	3.00	3.08	3.15	
			$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$	2.97	3.08	3.17	
		MAX682_S	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	2.85	2.93	3.00	
			$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	2.83	2.93	3.02	
V <sub>CC</sub> Reset Threshold (V <sub>CC</sub> Falling)		MAX682_R	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	2.55	2.63	2.70	
(VCC Failing)			$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$	2.53	2.63	2.72	
		MAX682_Z	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	2.25	2.32	2.38	
			$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	2.24	2.32	2.40	
		MAX682_Y	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	2.12	2.19	2.25	
			$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$	2.11	2.19	2.27	
		MAX682_W	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	1.62	1.67	1.71	
			$T_A = -40^{\circ}C \text{ to } + 125^{\circ}C$	1.61	1.67	1.72	
		MAX682_V	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	1.52	1.58	1.62	<u> </u>
Reset Threshold Temperature Coefficient					60		ppm/°C
Reset Threshold Hysteresis					$2 \times V_{TH}$		mV
V <sub>CC</sub> to Reset Output Delay	t <sub>RD</sub>	$V_{CC} = V_{TH}$ to ( $V_{TH} - 10$	0mV)		20		μs

## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = +4.5V \text{ to } +5.5V \text{ for MAX682}_L/M, V_{CC} = +2.7V \text{ to } +3.6V \text{ for MAX682}_T/S/R, V_{CC} = +2.1V \text{ to } +2.75V \text{ for MAX682}_Z/Y, V_{CC} = +1.53V \text{ to } +2.0V \text{ for MAX682}_W/V, T_A = -40^{\circ}C \text{ to } +125^{\circ}C, \text{ unless otherwise specified. Typical values are at } T_A = +25^{\circ}C.) (Note 1)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS		
		$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	140	200	280			
Reset Timeout Period	t <sub>RP</sub>	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	100	ms				
		$V_{CC} \ge 1.0V$ , $I_{SINK} = 50\mu A$ , reset asserted, $T_A = 0^{\circ}C$ to +85°C			0.3			
RESET Output LOW (Push-Pull or Open-Drain)	VOL	$V_{CC} \ge 1.2V$ , $I_{SINK} = 100\mu A$ , reset asserted			0.3	V		
		$V_{CC} \ge 2.55V$ , $I_{SINK} = 1.2mA$ , reset asserted			0.3			
		$V_{CC} \ge 4.25V$ , $I_{SINK} = 3.2mA$ , reset asserted			0.4			
		$V_{CC} \ge 1.8V$ , $I_{SOURCE} = 200\mu$ A, reset not asserted	0.8 × V <sub>CC</sub>					
RESET Output HIGH (Push-Pull Only)	V <sub>OH</sub>	$V_{CC} \ge 3.15V$ , $I_{SOURCE} = 500\mu$ A, reset not asserted	0.8 × V <sub>CC</sub>			v		
		$V_{CC} \ge 4.75V$ , $I_{SOURCE} = 800\mu$ A, reset not asserted	$0.8 \times V_{CC}$			-		
Open-Drain RESET Output Leakage Current (Note 1)	ILKG	$V_{CC} > V_{TH}$ , $\overline{RESET}$ not asserted			1.0	μA		
RESET Output HIGH (Push-Pull Only)		$V_{CC} \ge 1.0V$ , $I_{SOURCE} = 1\mu A$ , reset asserted, $T_A = 0^{\circ}C$ to $+85^{\circ}C$	$0.8 \times V_{CC}$					
	VOH	$V_{CC} \ge 1.50V$ , $I_{SOURCE} = 100\mu A$ , reset asserted	0.8×VCC			V		
(i dairi di only)		$V_{CC} \ge 2.55V$ , $I_{SOURCE} = 500\mu$ A, reset asserted	$0.8 \times VCC$					
		$V_{CC} \ge 4.25V$ , $I_{SOURCE} = 800\mu$ A, reset asserted	$0.8 \times VCC$					
		$V_{CC} \ge 1.8V$ , $I_{SINK} = 500 \mu$ A, reset not asserted			0.3			
RESET Output LOW (Push-Pull Only)	VOL	$V_{CC} \ge 3.15V$ , $I_{SINK} = 1.2mA$ , reset not asserted			0.3	V		
(ruorrium ormy)		$V_{CC} \ge 4.75 V,  I_{SINK} = 3.2 m A,  reset  not  asserted$			0.4			
MANUAL RESET INPUT (MAX	6821/MAX6822	/MAX6823/MAX6825)						
MR Input Voltage	VIL				$0.3 \times V_{CC}$	V		
Inin input voltage	VIH		$0.7 \times V_{CC}$			v		
MR Minimum Input Pulse			1			μs		
MR Glitch Rejection				100		ns		
MR to Reset Delay				200		ns		
MR Pullup Resistance			25	50	75	kΩ		
WATCHDOG INPUT (MAX682	1/MAX6822/MA	X6823/MAX6824)						
Wetcheler: Time en et Denie d		$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	1.12	1.60	2.40	_		
Watchdog Timeout Period	twd	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$	0.80		2.60	S		
WDI Pulse Width (Note 2)	twdi		50			ns		
	VIL				$0.3 \times V_{CC}$	N/		
WDI Input Voltage	VIH		0.7×V <sub>CC</sub>			V		
		WDI = V <sub>CC</sub> , time average			160			
WDI Input Current	IWDI	WDI = 0, time average	-20 -15			μA		

**Note 1:** Over-temperature limits are guaranteed by design and not production tested. Devices tested at  $T_A = +25$ °C. **Note 2:** Guaranteed by design and not production tested.



## **Typical Operating Characteristics**

**SUPPLY CURRENT RESET TIMEOUT PERIOD** V<sub>CC</sub> TO RESET OUTPUT DELAY vs. TEMPERATURE vs. TEMPERATURE vs. TEMPERATURE 13 250 35 V<sub>CC</sub> FALLING, V<sub>CC</sub> = V<sub>TH</sub> - 100mV 240 12 30  $V_{CC} = +5V$ , L VERSION 11 230 (ms) PROPAGATION DELAY (µs) SUPPLY CURRENT (µA) 25 10 220 TIMEOUT PERIOD 9 210 20 8 200 V<sub>CC</sub> = +3.3V, S VERSION 15 7 190 RESET 1 6 180  $V_{CC} = +1.8V, V VERSION$ 10 5 170 5 4 160 3 150 0 -40 -20 0 20 40 60 80 100 120 -40 -20 0 20 40 60 80 100 120 -40 -20 0 20 40 60 80 100 120 TEMPERATURE (°C) TEMPERATURE (°C) TEMPERATURE (°C) WATCHDOG TIMEOUT PERIOD NORMALIZED RESET THRESHOLD MAXIMUM VCC TRANSIENT DURATION vs. TEMPERATURE **DELAY vs. TEMPERATURE** vs. RESET THRESHOLD OVERDRIVE 2.0 1.06 120 1.9 1.04 100 WATCHDOG TIMEOUT PERIOD (s) 1.8 **ΓRANSIENT DURATION** (μs) (N) 1.02 1.00 1.7 80 RESET OCCURS 1.6 ABOVE CURVE 1.5 60 1.4 L 198 40 1.3 1.2 0.96 20 1.1 0.94 1.0 0 40 60 -40 -20 0 20 80 100 120 -40 -20 0 20 40 60 80 100 120 0 20 40 60 80 100 120 140 160 180 200 TEMPERATURE (°C) TEMPERATURE (°C) RESET THRESHOLD OVERDRIVE (mV), VTH - VCC **VOLTAGE OUTPUT LOW VOLTAGE OUTPUT HIGH** vs. SINK CURRENT vs. SOURCE CURRENT 0.35 2.92  $V_{CC} = +2.9V$  $V_{CC} = +2.9V$ 2.90 0.30 2.88 0.25 2.86 0.20 S Vour (V) 2.84 V0U 2.82 0.15 2.80 0.10 2.78 0.05 2.76 0 2.74 2 3 5 6 0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0 0 1 4 7 I<sub>SINK</sub> (mA) ISOURCE (mA)

 $(T_A = +25^{\circ}C, \text{ unless otherwise noted.})$ 

# \_Pin Description

	PIN NUMBERS							
MAX6821	MAX6822	MAX6823	MAX6824	MAX6825	NAME	FUNCTION		
	1	1	1	1	RESET	Active-Low Open-Drain or Push-Pull Reset Output. $\overrightarrow{\text{RESET}}$ changes from high to low when the V <sub>CC</sub> input drops below the selected reset threshold, $\overrightarrow{\text{MR}}$ is pulled low, or the watchdog triggers a reset. $\overrightarrow{\text{RESET}}$ remains low for the reset timeout period after V <sub>CC</sub> exceeds the device reset threshold, $\overrightarrow{\text{MR}}$ goes low to high, or the watchdog triggers a reset.		
1			3	3	RESET	Active-High Push-Pull Reset Output. RESET changes from low to high when the V <sub>CC</sub> input drops below the selected reset threshold, $\overline{\text{MR}}$ is pulled low, or the watchdog triggers a reset. RESET remains high for the reset timeout period after V <sub>CC</sub> exceeds the device reset threshold, $\overline{\text{MR}}$ goes low to high, or the watchdog triggers a reset.		
2	2	2	2	2	GND	Ground		
3	3	3		4	MR	Active-Low Manual Reset Input. Internal $50k\Omega$ pullup to V <sub>CC</sub> . Pull low to force a reset. Reset remains active as long as $\overline{MR}$ is low and for the reset timeout period after $\overline{MR}$ goes high. Leave unconnected or connect to V <sub>CC</sub> if unused.		
4	4	4	4		WDI	Watchdog Input. If WDI remains high or low for longer than the watchdog timeout period, the internal watchdog timer runs out and a reset is triggered for the reset timeout period. The internal watchdog timer clears whenever reset is asserted, the manual reset is asserted, or WDI sees a rising or falling edge. If WDI is left unconnected or is connected to a three-stated buffer output, the watchdog feature is disabled.		
5	5	5	5	5	V <sub>CC</sub>	Supply Voltage and Input for Reset Threshold Monitor		

## **Detailed Description**

#### **RESET**/RESET Output

A  $\mu$ P's reset input starts the  $\mu$ P in a known state. The MAX6821–MAX6825  $\mu$ P supervisory circuits assert a reset to prevent code-execution errors during powerup, power-down, and brownout conditions. Whenever V<sub>CC</sub> falls below the reset threshold, the reset output asserts low for RESET and high for RESET. Once V<sub>CC</sub> exceeds the reset threshold, an internal timer keeps the reset output asserted for the specified reset timeout period (t<sub>RP</sub>); after this interval, reset output returns to its original state (see Figure 2).

#### **Manual Reset Input**

Many  $\mu$ P-based products require manual reset capability, allowing the operator, a test technician, or external logic circuitry to initiate a reset. On the MAX6821/ MAX6822/MAX6823/MAX6825, a logic low on MR asserts a reset. Reset remains asserted while MR is low, and for the timeout period (140ms min) after it so it can be left open if not used. This input can be driven with CMOS logic levels or with open-drain/collector outputs. Connect a normally open momentary switch from  $\overline{\text{MR}}$  to GND to create a manual reset function; external debounce circuitry is not required. If  $\overline{\text{MR}}$  is driven from long cables or the device is used in a noisy environment, connect a 0.1µF capacitor from  $\overline{\text{MR}}$  to GND to provide additional noise immunity.

returns high.  $\overline{MR}$  has an internal 50k $\Omega$  pullup resistor,

#### Watchdog Input

In the MAX6821–MAX6824, the watchdog circuit monitors the  $\mu$ P's activity. If the  $\mu$ P does not toggle (low to high or high to low) the watchdog input (WDI) within the watchdog timeout period (1.6s nominal), reset asserts for the reset timoeout period. The internal 1.6s timer can be cleared by either a reset pulse or by toggling WDI. The WDI can detect pulses as short as 50ns. While reset is asserted, the timer remains cleared and does not count. As soon as reset is released, the timer starts counting (see Figure 3).

# MAX6821-MAX6825

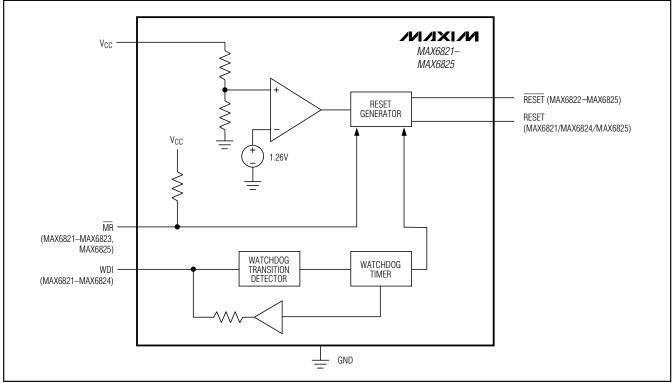


Figure 1. Functional Diagram

Disable the watchdog function by leaving WDI unconnected or by three-stating the driver connected to WDI. The watchdog input is internally driven low during the first 7/8 of the watchdog timeout period and high for the last 1/8 of the watchdog timeout period. When WDI is left unconnected, this internal driver clears the 1.6s timer every 1.4s. When WDI is three-stated or unconnected, the maximum allowable leakage current is 10µA and the maximum allowable load capacitance is 200pF.

# **Applications Information**

#### Watchdog Input Current

The MAX6821/MAX6822/MAX6823/MAX6824 WDI inputs are internally driven through a buffer and series resistor from the watchdog timer (Figure 1). When WDI is left unconnected, the watchdog timer is serviced within the watchdog timeout period by a low-high-low pulse from the counter chain. For minimum watchdog input current (minimum overall power consumption), leave WDI low for the majority of the watchdog timeout period, pulsing it low-high-low once within the first 7/8 of the watchdog timeout period to reset the watchdog timer. If WDI is externally driven high for the majority of the timeout period, up to 160µA can flow into WDI.

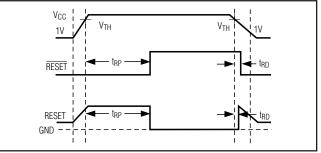


Figure 2. Reset Timing Diagram

#### Interfacing to µPs with Bidirectional Reset Pins

Since the  $\overline{\text{RESET}}$  output on the MAX6822 is open drain, it interfaces easily with  $\mu\text{Ps}$  that have bidirectional reset pins, such as the Motorola 68HC11. Connecting the  $\mu\text{P}$  supervisor's  $\overline{\text{RESET}}$  output directly to the microcontroller's  $\overline{\text{RESET}}$  pin with a single pullup resistor allows either device to assert reset (see Figure 4).

#### **Negative-Going VCC Transients**

These supervisors are relatively immune to short-duration, negative-going  $V_{CC}$  transients (glitches), which usually do not require the entire system to shut down.



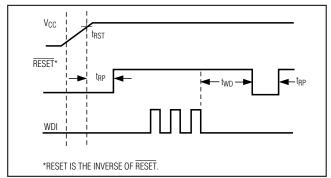


Figure 3. Watchdog Timing Relationship

Resets are issued to the µP during power-up, powerdown, and brownout conditions. The Typical Operating Characteristics show a graph of the MAX6821-MAX6825's Maximum V<sub>CC</sub> Transient Duration vs. Reset Threshold Overdrive, for which reset pulses are not generated. The graph was produced using negativegoing V<sub>CC</sub> pulses, starting at the standard monitored voltage and ending below the reset threshold by the magnitude indicated (reset threshold overdrive). The graph shows the maximum pulse width that a negativegoing V<sub>CC</sub> transient can typically have without triggering a reset pulse. As the amplitude of the transient increases (i.e., goes farther below the reset threshold), the maximum allowable pulse width decreases. Typically, a VCC transient that goes 100mV below the reset threshold and lasts for 20µs or less will not trigger a reset pulse.

#### Watchdog Software Considerations

One way to help the watchdog timer monitor software execution more closely is to set and reset the watchdog input at different points in the program, rather than pulsing the watchdog input high-low-high or low-highlow. This technique avoids a stuck loop, in which the watchdog timer would continue to be reset inside the loop, keeping the watchdog from timing out.

Figure 5 shows an example of a flow diagram where the I/O driving the watchdog input is set high at the beginning of the program, set low at the beginning of every subroutine or loop, then set high again when the program returns to the beginning. If the program should hang in any subroutine, the problem would quickly be corrected, since the I/O is continually set low and the watchdog timer is allowed to time out, causing a reset or interrupt to be issued. As described in the Watchdog Input Current section, this scheme results in higher time average WDI input current than does leaving WDI low for the majority of the timeout period and periodically pulsing it low-high-low.



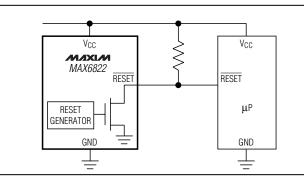


Figure 4. Interfacing Open-Drain  $\overrightarrow{\text{RESET}}$  to  $\mu\text{Ps}$  with Bidirectional Reset I/O

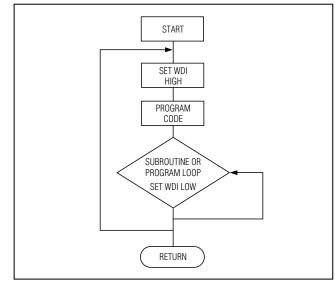
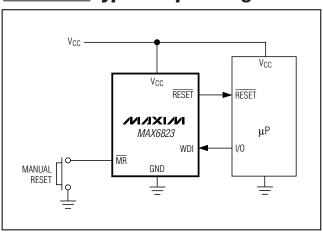


Figure 5. Watchdog Flow Diagram

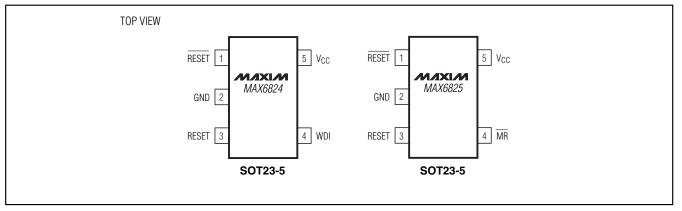
## \_Typical Operating Circuit



## **Selector Guide**

FUNCTION	ACTIVE-LOW RESET	ACTIVE-HIGH RESET	OPEN-DRAIN RESET	WATCHDOG INPUT	MANUAL RESET INPUT
MAX6821	—	~	—	~	~
MAX6822	—	—	~	~	~
MAX6823	<ul> <li>✓</li> </ul>	—	—	~	~
MAX6824	V	~	—	v	—
MAX6825	<ul> <li>✓</li> </ul>	~	—	—	~

# \_Pin Configurations (continued)



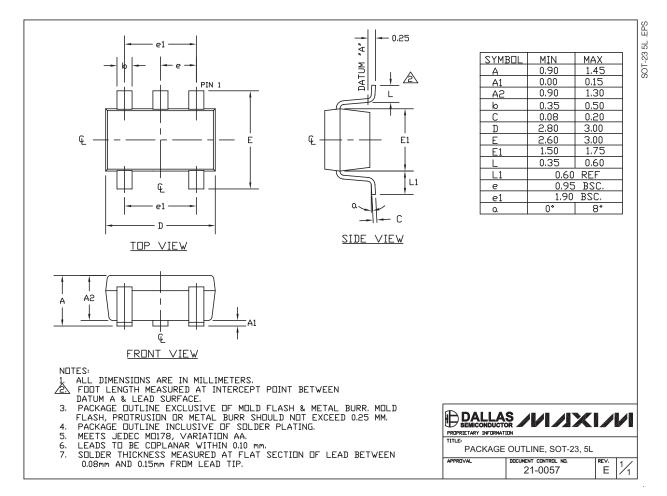
# Chip Information

TRANSISTOR COUNT: 750 PROCESS: BICMOS

<u>///XI///</u>

# **Package Information**

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



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