P5 series instrument gearheads conform to the international ovoid standard. The units have established a reputation for excellent running consistency, strength and reliability & have been engineered to enable a wide range of permanent magnet stepper motors, ac synchronous & instrument dc servo motors to be readily fitted.

Typical applications include:

- Scientific instrument drives
- Medical instruments drives
- Laboratory & test equipment drives
- Optical equipment drives
- Valve actuators
- Process control equipment

Precision construction with built-in flexibility:

P5 series gearheads incorporate precision spur cut brass gears and steel pinions mounted on spindles running in bronze alloy bearings which feature lubrication reservoirs for extended life, control accuracy and high dynamic performance. P5 series units have been designed to readily accept a wide range of motors and offer a comprehensive programme of options including integral torque limiting clutches and freewheels. These, together with three standard shaft options and the ability to offer customised versions make the P5 series gearhead an ideal choice where precision control of a wide variety of mechanisms where high control accuracy is required.

Standard gear ratios:

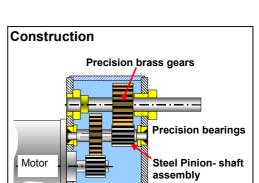
Fast-track delivery of a wide range of P5 series gearheads ensures rapid response to customer demand. The wide range of stock ratios are ideal when using permanent magnet stepper motors, ac synchronous motors and high quality dc instrument motors

| Order | Ratio | Efficiency | Max Output | Steps per rev | Output speed using | Output speed |
|----------|---|------------|------------|-----------------------------------|--------------------|----------------|
| Code | | (%) | Torque | @ output using. synchronous motor | | Using dc motor |
| | | | (Nm) | Stepper motor * | (rpm) # | (rpm) ** |
| P5-G01 | 25:6 | 80 | 0.20 | 200 | 60 | 720-1200 |
| P5-G03 | 25:4 | 80 | 0.25 | 300 | 40 | 500-800 |
| P5-G04 | 25:3 | 80 | 0.35 | 400 | 30 | 360-600 |
| P5-G05 | 10:1 | 70 | 0.40 | 480 | 25 | 300-500 |
| P5-G06 | 25:2 | 70 | 0.45 | 600 | 20 | 240-400 |
| P5-G08 | 50:3 | 70 | 0.60 | 800 | 15 | 180-300 |
| P5-G09 | 20:1 | 70 | 0.65 | 960 | 12.5 | 150-250 |
| P5-G11 | 25:1 | 70 | 0.70 | 1200 | 10 | 120-200 |
| P5-G14 | 100:3 | 70 | 0.75 | 1600 | 7.5 | 90-150 |
| P5-G16 | 125:3 | 70 | 0.80 | 2000 | 6 | 72-120 |
| P5-G17 | 50:1 | 70 | 0.80 | 2400 | 5 | 60-100 |
| P5-G19 | 125:2 | 65 | 0.80 | 3000 | 4 | 48-80 |
| P5-G21 | 250:3 | 65 | 0.80 | 4000 | 3 | 36-60 |
| P5-G23 | 125:1 | 65 | 0.80 | 6000 | 2 | 24-40 |
| P5-G27 | 250:1 | 65 | 0.80 | 12000 | 1 | 12-20 |
| P5-G34 | 500:1 | 58 | 0.85 | 24000 | 0.5 | 6-10 |
| P5-G41 | 1250:1 | 58 | 0.90 | 60000 | 12 revs/hour | 2.4 - 4 |
| P5-G62 | 15,000:1 | 43 | 1.0 | 720,000 | 1 rev / hour | 0.1-0.3 |
| Notes: * | tes: * Based on the use of a stepper motor with 7.5 degree step angle | | | | | |

Based on the use of a stepper motor with 7.5 degree step angle

Based on the use of a 250 rpm ac synchronous motor

** Based on the use of instrument dc motors with speed ratings of 3000 & 5000 rpm.

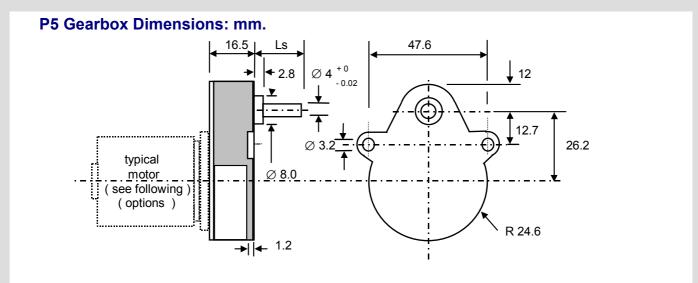




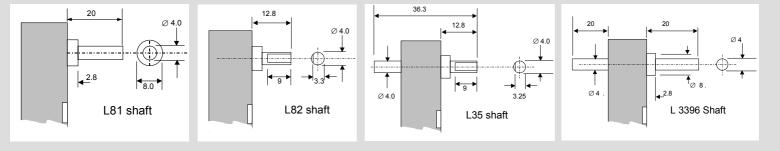


P5 series

P5 series



Standard output shaft dimensions: mm.



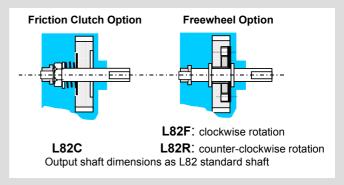
L82 shaft with internal clutch & freewheel

P5 series gearbox may be specified with optional internal friction clutch or freewheels.

The L82C internal clutch is set to a slip torque of 0.6 Nm and is designed to protect the gearhead against damage resulting from excessive torque in a stall condition.

The freewheel options provide a maximum torque of 0.4 Nm and provide free rotation in the direction of drive.

Typical applications include chart recorder paper feeds.



General specification:

| Max recommended input speed | | rpm | 5000 | |
|---|--|---------------|----------------------------------|--|
| Max Radial load | | N | 50 (@ 8 mm from mounting face) | |
| Max Static Axial load | | Ν | 150 N (for press fit on shaft) | |
| Ambient temperature range | | Deg. C | -30 to +65 | |
| Max Axial shaft play | | μm | 250 | |
| Max radial shaft play | | μm | 25 | |
| Direction of rotation @ output with respect to input: | | | | |
| Ratio Codes Num | | ber of stages | Direction of rotation | |
| P5-G01 to G04 | | 2 | Same | |
| P5-G05 to G17 | | 3 | Opposite | |
| P5-G19-G27 | | 4 | Same | |
| P5-G34-G41 | | 5 | Opposite | |
| P5-G62 | | 7 | Opposite | |



Positional Servodrive assembly

P5 series

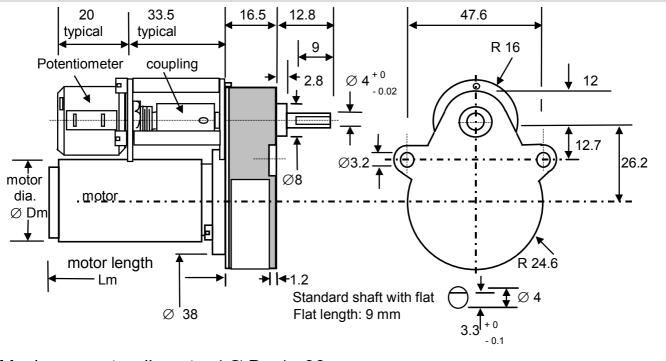
The P5 positional servodrive incorporates a potentiometer which is connected to the output shaft to provide an analogue reference signal proportional to output shaft position.

A variety of potentiometer options are available to provide the choice of single or multi-turn operation. Although conforming to the standard panel mount design, the feedback potentiometers utilised in P5 positional *servodrives* have a reinforced internal construction to provide long life in motor driven applications.

The feedback potentiometer is coupled directly to the *servodrive's* output shaft via a backlash-free coupling which incorporates a friction clutch to protect the potentiometer against an overtravel condition when an option fitted with end stops is specified.

P5 series *Servodrives* may be specified with any of the gear ratios shown on earlier pages to provide a wide choice of speed options.

P5 series Positional Servodrive assembly Dimensions: mm



Maximum motor diameter (\varnothing Dm) : 36 mm

Standard Potentiometer options

| Gearhead ratio code | Potentiometer code | Description | Electrical rotation |
|---------------------|--------------------|----------------------------------|--------------------------|
| P5-G01 to G62- | L100 | Single turn, continuous rotation | > 340 degrees |
| | L101 | Single turn with end stops | > 300 degrees |
| | L102 | Three turn with end stops | > 1080 degrees |
| | L103 | Ten turn with end stops | <u>></u> 3600 degrees |



Issue 001

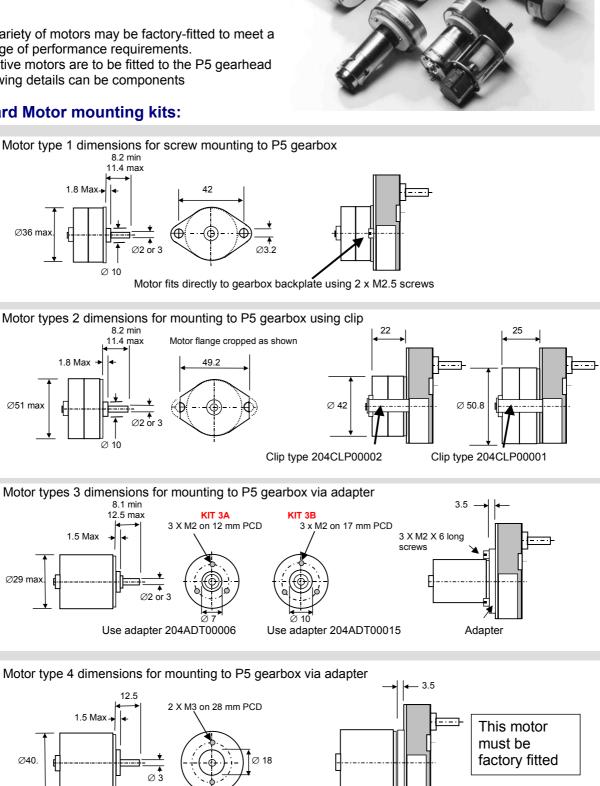
P5 series

Motor options

A wide range of permanent magnet stepper motors, instrument dc motors and ac synchronous motors may be fitted to the P5 gearhead using standard mounting kits.

A wide variety of motors may be factory-fitted to meet a wide range of performance requirements. If alternative motors are to be fitted to the P5 gearhead the following details can be components

Standard Motor mounting kits:



Use adapter 204ADT00007

Tel: +44 (0)8707 700 700

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Adapter



Issue 001

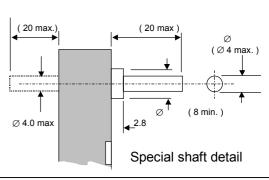


P5 series

Ordering code

Example: <u>**P5-G17**</u> <u>**L82**</u>

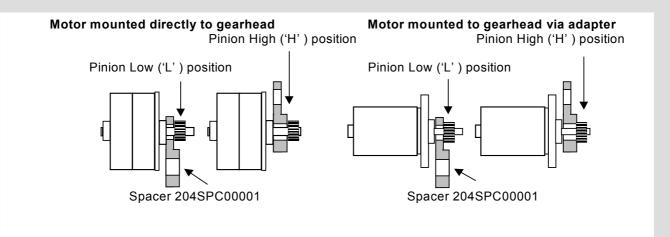
Gearbox Code Ratio Code Shaft or Potentiometer code



- Specify motor shaft diameter so correct pinion bore is provided
- Specify fitting components such as adapter or fixing clip
- If in doubt please contact your local sales office
- If a special output shaft is required enter details in drawing provided:

Fitting the motor to P5 gearheads:

The pinion is either fitted to the motor shaft by means of high strength Loctitie 638 adhesive or it is press fitted when the motor rear shaft can be supported. The pinion can be accurately located, in one of two positions, using the pinion fitting tool 204SPC00001 as shown below:



Pinion Positions

| Order | Ratio | Pinion | Standard Pinion bores (motor shaft diameters) | | Maximum Pinion bore | | |
|--------|----------|----------|--|--------|---------------------|-----------------------------|--|
| Code | | Position | | | | (max. motor shaft diameter) | |
| P5-G01 | 25:6 | Н | 1.8 mm | 2.0 mm | 3.0 mm | 3 mm | |
| P5-G03 | 25:4 | н | 1.8 mm | 2.0 mm | 3.0 mm | 4 mm | |
| P5-G04 | 25:3 | н | 1.8 mm | 2.0 mm | 3.0 mm | 3 mm | |
| P5-G05 | 10:1 | \sim | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G06 | 25:2 | | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G08 | 50:3 | | 1.8 mm | 2.0 mm | 3.0 mm | > 5 mm | |
| P5-G09 | 20:1 | | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G11 | 25:1 | | 1.8 mm | 2.0 mm | 3.0 mm | J | |
| P5-G14 | 100:3 | | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G16 | 125:3 | | 1.8 mm | 2.0 mm | 3.0 mm |] | |
| P5-G17 | 50:1 | ノ | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G19 | 125:2 | | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G21 | 250:3 | | 1.8 mm | 2.0 mm | 3.0 mm | └───── 5 mm | |
| P5-G23 | 125:1 | | 1.8 mm | 2.0 mm | 3.0 mm | | |
| P5-G27 | 250:1 | H | 1.8 mm | 2.0 mm | 3.0 mm | 3 mm | |
| P5-G34 | 500:1 | | 1.8 mm | 2.0 mm | 3.0 mm | 5 mm | |
| P5-G41 | 1250:1 | ノ | 1.8 mm | 2.0 mm | 3.0 mm | 3 mm | |
| P5-G62 | 15,000:1 | L | 1.8 mm | 2.0 mm | 3.0 mm | 3 mm | |

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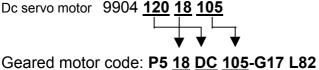
Complete geared motor assemblies

A wide range of complete assemblies with factory fitted motors can be provided, data on which is available on request.

When supplied as a complete assembly the motor part number is inserted in the geared motor order code

Examples:

Dc servo motor 9904 120 18 105



Stepper motor 9904 112 32 101 P5 32 ST 101-G17 L82

Typical factory fitted geared motor assemblies



Reversible geared ac synchronous motors

- Reversible fixed speed operation
- Choice of two motor power options
- Choice of output speeds from 1 rev/second to 1 rev/ hour
- Choice of 24, 110 or 230 Vac 50 Hz operation

P532 & P531 SP series Geared reversible ac synchronous motors

Geared permanent magnet stepper motors

- High precision 7.5 degree stepper motors Choice of 5V or 12 V windings •
- Choice of four power options
 - Optional positional feedback potentiometer assembly



P531 ST series Geared stepper motors

Geared ironless rotor dc servo motors

- High precision coreless servo motors •
- Choice of 6, 12 or 24 Vdc windings .
- Standard speed options from 1200 0.1 rpm .



P522 DC series Geared dc motors



P532 ST & P535 series **Geared stepper motors**



P542 series **Geared stepper motors**

- Choice of 6 power options from 22 –40 mm diameter •
- Optional dc tachogenerator or encoder feedback •
- Optional positional feedback potentiometer assembly



P528 DC Series Geared dc motors



P518 DC series Geared dc motors with position feedback

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