# **Reversible AC Synchronous Motors**

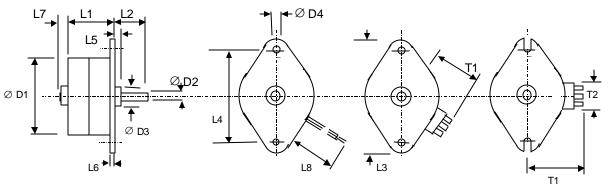
The 9904 111 series reversible ac synchronous motors provide fixed speed operation and are ideally suited to a wide range of control & instrumentation applications. The units low speed, either 250 or 500 rpm, ensure low mechanical noise and smooth operation when used with additional gearing in low speed drives.

The motors may be specified with a wide range of factory fitted gearheads where increased torque and reduced operating speed is required. Gearheads for the 35 & 51 mm options provide a choice of standard ratios with output speed options from 1 rev/second down to 1 rev/hour. while the high torque 56 mm model may be fitted with gearheads providing speeds down to 30 revs/hour.



### Reversible ac synchronous motor dimensions

The motors are either provided with leads (Form 1 A) or solder terminals (Forms 1B & 1C) as shown below:



Form 1 Form 1A Form 1B Form 1C

motor type	form	dimensions mm													
9904-111-		D1	D2	D3	D4	L1	L2	L3	L4	L5	L6	L7	L8	T1	T2
32 series	1 A	35	2	10	3.2	21.5	8.8	50	42	1.2	0.8	2.2	175	N/A	N/A
31- x11	1 A	51	1.8	10	3.5	25	8.2	70.5	60.2	1.5	1.0	3	175	N/A	N/A
31- x01	1 A	51	3	10	3.5	25	8.2	70.5	60.2	1.5	1.0	3	175	N/A	N/A
31- x14	1 B	51	1.8	10	3.5	25	8.2	70.5	60.2	1.5	1.0	3	N/A	38.5	18.3
31- x04	1 B	51	3	10	3.5	25	8.2	70.5	60.2	1.5	1.0	3	N/A	38.5	18.3
35 series	1 C	56.3	3	12	4.4	33.5	8.2	76.5	66	1.5	1.5	3.8	N/A	37.1	20
36 series	1 C	56.3	3	12	4.4	33.5	8.2	76.5	66	1.5	1.5	3.8	N/A	37.1	20

## **Reversible AC Synchronous Motor Performance**

motor type	Supply Voltage coils connected in		Speed @50Hz	Working Torque coils connected in		Current	Phasing Capacitor coils connected in		Mass
	Parallel Vac	<b>Series</b> Vac	rpm	Parallel Ncm	Series Ncm	m A	Parallel μF	<b>Series</b> μF	grams
9904 111 <b>32 311</b> 9904 111 <b>32 511</b>	110 48	220 24	250	0.4	0.7	8 35	0.1 2.2	0.22 4.7	80
9904 111 <b>31 111</b> 9904 111 <b>31 104</b>	220					16	0.1		
9904 111 <b>31 311</b> 9904 111 <b>31 304</b>	110		250	2.0		30	0.39		160
9904 111 <b>31 511</b> 9904 111 <b>31 504</b>	24		 			150	8		
9904 111 <b>35 104</b> 9904 111 <b>35 504</b>	220 24		250	3.3		15 140	0.12 10		300
9904 111 <b>36 104</b> 9904 111 <b>36 504</b>	220 24		500	3.3		30 280	0.22 18		300

note\*\* The above motors are rated for continuous operation. except the 36 series which is rated for a 50% duty cycle

The 250 rpm motors may be used on a 60Hz supply to provide 300 rpm using different phasing capacitors

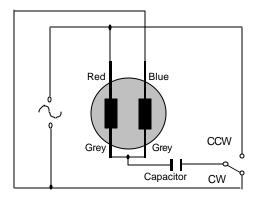


# **AC Synchronous Motor General Specification**

	Units	32 series	31xx 1 series	31xx 4 series	35 series	36 series	
Input Power:							
Coils in parallel	Watts	0.8	3.5		3.5	6	
Coils in series		1.7	1.7				
Permissible voltage tolerance	%	-15 / +10	-15 / +10		-15 / +10		
Maximum recommended load inertia	Kgcm <sup>2</sup>	0.005	0.02		0.09	0.05	
Maximum Radial force on shaft	N	2.5	5.0		10		
Maximum Axial force on shaft	N	0.75	1.5		1.5		
Insulation according to CEE10		class 1	class 2	class 1	clas	ss 1	
Insulation test voltage	V	1500	2500	1500	15	500	
Ambient temperature range		-20 to +60			-20 to +70		
operating	Deg. C	-40 to + 100 -40 to +				+ 1000	
storage							
bearings		Sintered bronze					
Housing Zinc plated						•	

### **AC Synchronous Motor Connections for Operation on 50Hz Supplies:**

#### Series connected coils



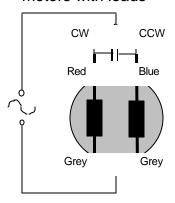
#### Application notes

The direction of rotation of the ac synchronous motors can be determined by simply connecting a capacitor and a switch across the two windings as shown. The motors run at a fixed speed synchronous with mains frequency, at any torque up to the motor's operating limit. They are therefore ideal for high accuracy fixed speed drives.

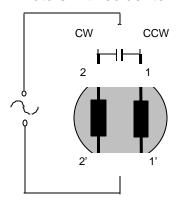
The motors will accelerate to operating speed in typically 100 msecs. and will stop within typically 60 degrees once power is removed, depending on the load inertia. They are therefore suitable for positioning applications where the high accuracy of a stepper motor, for example, is not required If starting problems are experienced in applications featuring low friction torque it is usually because the load inertia is too high. In these cases a coupling with some compliance often helps to overcome this problem. When a gearhead is used for reduced speed operation the reflected load inertia at the motor is reduced by the square of the gear ratio.

#### **AC Synchronous Motor Connections: Parallel Connected Coils**

#### motors with leads



#### motors with solder terminals



The motors may also be operated on 60Hz supplies. If this is required please contact us for connection details

### **Geared AC Synchronous Motors**

A wide range of gearheads providing reduced speed operation from1 rev/second to 1 rev per hour may be specified, factory fitted to the ac synchronous motor range. For further details please see the section entitled 'Geared synchronous motors'



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