HEF40106B

Hex inverting Schmitt trigger Rev. 7 — 21 November 2011

Product data sheet

1. **General description**

The HEF40106B provides six inverting buffers. Each input has a Schmitt trigger circuit. The inverting buffer switches at different points for positive-going and negative-going signals. The difference between the positive voltage (V_{T+}) and the negative voltage (V_{T-}) is defined as hysteresis voltage (V_H).

The HEF40106B may be used for enhanced noise immunity or to "square up" slowly changing waveforms.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

Features and benefits 2.

- Schmitt trigger input discrimination
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. **Applications**

- Wave and pulse shapers
- Astable multivibrators
- Monostable multivibrators

Ordering information

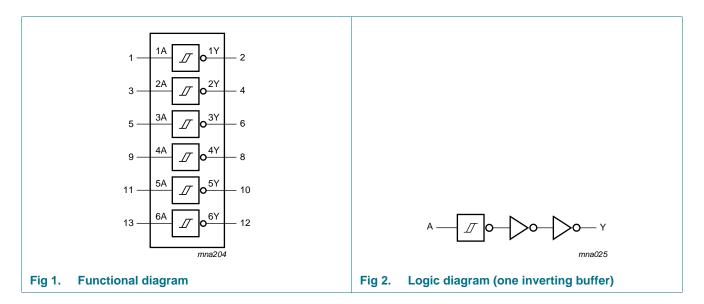
Ordering information

All types operate from -40 °C to +125 °C

Type number	Package										
	Name	Description	Version								
HEF40106BP	DIP14	plastic dual in-line package; 14 leads (300 mil)	SOT27-1								
HEF40106BT	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1								
HEF40106BTT	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1								

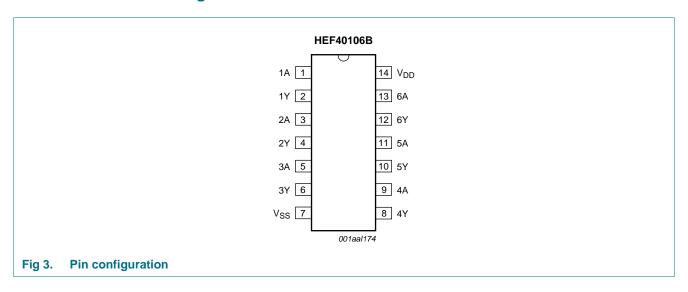


5. Functional diagram



6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
1A to 6A	1, 3, 5, 9, 11, 13	input
1Y to 6Y	2, 4, 6, 8, 10, 12	output
V_{DD}	14	supply voltage
V_{SS}	7	ground (0 V)

7. Functional description

Table 3. Function table[1]

Input	Output
nA	nY
L	Н
Н	L

^[1] H = HIGH voltage level; L = LOW voltage level.

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to $V_{SS} = 0 \text{ V}$ (ground).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		-0.5	+18	V
I _{IK}	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	$V_{DD} + 0.5$	V
I _{OK}	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I_{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+125	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}$			
		DIP14	<u>[1]</u> -	750	mW
		SO14	[2] _	500	mW
		TSSOP14	[3]	500	mW
Р	power dissipation	per output	-	100	mW

^[1] For DIP14 packages: above T_{amb} = 70 °C, P_{tot} derates linearly with 12 mW/K.

^[2] For SO14 packages: above T_{amb} = 70 °C, P_{tot} derates linearly with 8 mW/K.

^[3] For TSSOP14 packages: above T_{amb} = 60 °C, P_{tot} derates linearly with 5.5 mW/K.

9. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	supply voltage		3	15	V
VI	input voltage		0	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	+125	°C

10. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} ; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	T _{amb} =	–40 °C	T _{amb} =	+25 °C	T _{amb} =	+85 °C	T _{amb} =	+125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V_{OH}	HIGH-level	$ I_{O} < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V_{OL}	LOW-level	$ I_O < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I _{OH}	HIGH-level output current	$V_0 = 2.5 \text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mΑ
		$V_0 = 4.6 \text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mΑ
		V _O = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mΑ
		V _O = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mΑ
I _{OL}	LOW-level output current	$V_0 = 0.4 \ V$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mΑ
		$V_0 = 0.5 \ V$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mΑ
		V _O = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mΑ
I _I	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I _{DD}	supply current	all valid input	5 V	-	0.25	-	0.25	-	7.5	-	7.5	μΑ
		combinations; $I_0 = 0 A$	10 V	-	0.5	-	0.5	-	15.0	-	15.0	μΑ
			15 V	-	1.0	-	1.0	-	30.0	-	30.0	μΑ
Cı	input capacitance			-	-	-	7.5	-	-	-	-	pF

11. Dynamic characteristics

Table 7. Dynamic characteristics

 T_{amb} = 25 °C; C_L = 50 pF; t_r = t_f ≤ 20 ns; wave forms see <u>Figure 4</u>; test circuit see <u>Figure 5</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula[1]	Min	Тур	Max	Unit
t _{PHL}	HIGH to LOW	nA or nB to nY	5 V	63 ns + (0.55 ns/pF)C _L	-	90	180	ns
	propagation delay		10 V	29 ns + (0.23 ns/pF)C _L	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C _L	-	30	60	ns
t _{PLH}	LOW to HIGH	nA or nB to nY	5 V	58 ns + (0.55 ns/pF)C _L	-	75	150	ns
	propagation delay		10 V	29 ns + (0.23 ns/pF)C _L	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C _L	-	30	60	ns
t _{THL}	HIGH to LOW output transition time	nY to LOW	5 V	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns
t _{TLH}	LOW to HIGH output	nA or nB to HIGH	5 V	10 ns + (1.00 ns/pF)C _L	-	60	120	ns
	transition time		10 V	9 ns + (0.42 ns/pF)C _L	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns

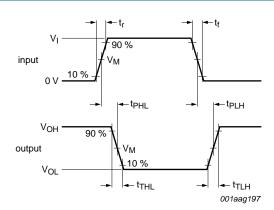
^[1] Typical value of the propagation delay and output transition time can be calculated with the extrapolation formula (C_L in pF).

Table 8. Dynamic power dissipation

 $V_{SS} = 0 \ V; \ t_f = t_f \le 20 \ ns; \ T_{amb} = 25 \ ^{\circ}C.$

Symbol	Parameter	V_{DD}	Typical formula	where:		
_	dynamic power	5 V	$P_D = 2300 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 (\mu W)$	f_i = input frequency in MHz;		
	dissipation	10 V	$P_D = 9000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 (\mu W)$	f _o = output frequency in MHz;		
		15 V	$P_D = 20000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2 (\mu W)$	C_L = output load capacitance in pF; $\Sigma(f_o \times C_L)$ = sum of the outputs; V_{DD} = supply voltage in V.		

12. Waveforms



Measurement points are given in Table 9.

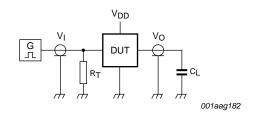
Logic levels: V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

 $t_{\rm r}$, $t_{\rm f}$ = input rise and fall times.

Fig 4. Propagation delay and output transition time

Table 9. Measurement points

Supply voltage	Input	Output
V_{DD}	V _M	V _M
5 V to 15 V	0.5V _{DD}	0.5V _{DD}



Test data given in Table 10.

Definitions for test circuit:

DUT = Device Under Test.

 C_L = load capacitance including jig and probe capacitance.

 R_T = termination resistance should be equal to the output impedance Z_0 of the pulse generator.

Fig 5. Test circuit

Table 10. Test data

Supply voltage	Input	Load	
V_{DD}	V _I	C _L	
5 V to 15 V	V _{SS} or V _{DD}	≤ 20 ns	50 pF

13. Transfer characteristics

Table 11. Transfer characteristics

 $V_{SS} = 0 V$; see <u>Figure 6</u> and <u>Figure 7</u>.

Symbol	Parameter	Conditions	V _{DD}	T _{amb} = -	–40 °C to	+85 °C	T _{amb} = to +1	Unit	
				Min	Typ[1]	Max	Min	Max	
V_{T+}	positive-going threshold voltage		5 V	2.0	3.0	3.5	2.0	3.5	V
			10 V	3.7	5.8	7.0	3.7	7.0	V
			15 V	4.9	8.3	11.0	4.9	11.0	V
V_{T-}	negative-going threshold voltage		5 V	1.5	2.2	3.0	1.5	3.0	V
			10 V	3.0	4.5	6.3	3.0	6.3	V
			15 V	4.0	6.5	10.1	4.0	10.1	V
V_{H}	hysteresis voltage		5 V	0.5	8.0	-	0.5	-	V
			10 V	0.7	1.3	-	0.7	-	V
			15 V	0.9	1.8	-	0.9	-	V

[1] All typical values are at T_{amb} = 25 °C.

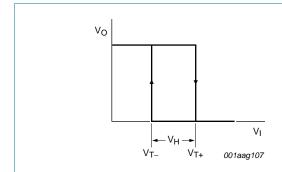


Fig 6. Transfer characteristic

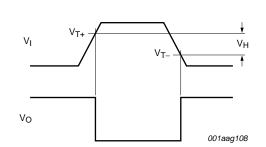
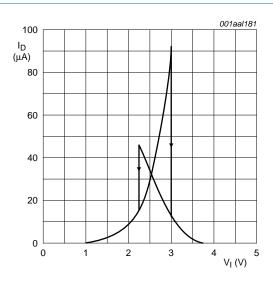
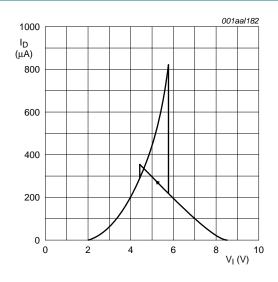
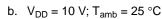


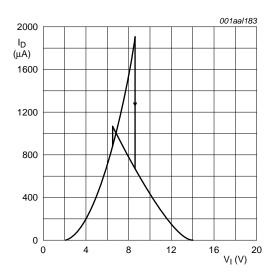
Fig 7. Waveforms showing definition of V_{T+} and V_{T-} (between limits at 30 % and 70 %) and V_H





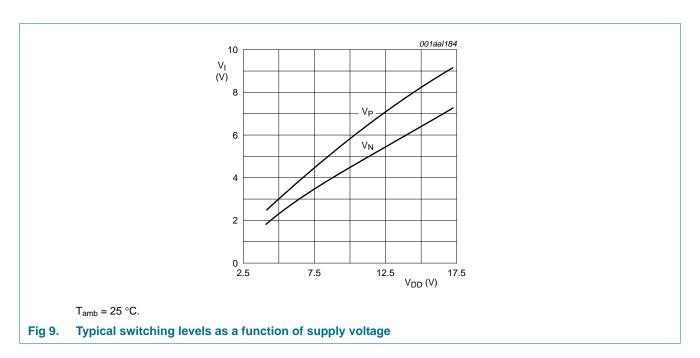
a.
$$V_{DD} = 5 \text{ V}$$
; $T_{amb} = 25 ^{\circ}\text{C}$





c. $V_{DD} = 15 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$

Fig 8. Typical drain current as a function of input



14. Application information

Some examples of applications for the HEF40106B are:

- · Wave and pulse shapers
- Astable multivibrators
- Monostable multivibrators

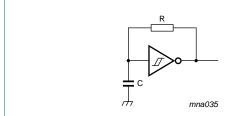


Fig 10. Astable multivibrator

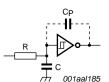


Fig 11. Schmitt trigger driven via a high-impedance input

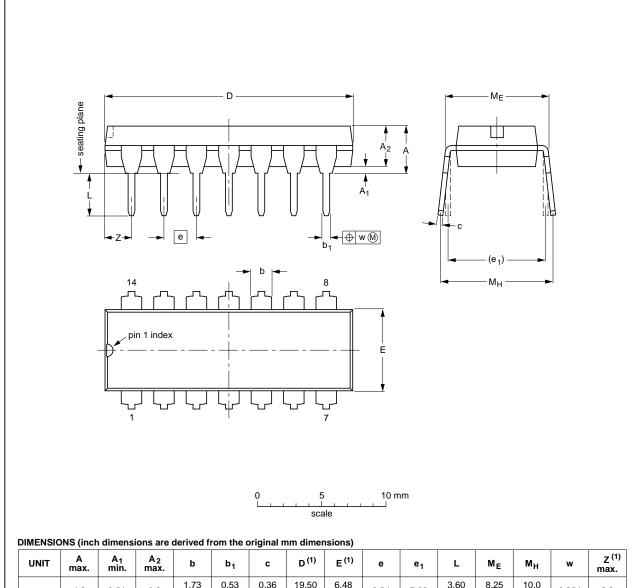
If a Schmitt trigger is driven via a high-impedance (R > 1 k Ω), then it is necessary to incorporate a capacitor C with a value of $\frac{C}{C_P} > \frac{V_{DD} - V_{SS}}{V_H}$; otherwise oscillation can occur on the edges of a pulse.

 C_{p} is the external parasitic capacitance between inputs and output; the value depends on the circuit board layout.

15. Package outline

DIP14: plastic dual in-line package; 14 leads (300 mil)

SOT27-1



UNIT	A max.	A ₁ min.	A ₂ max.	b	b ₁	С	D ⁽¹⁾	E ⁽¹⁾	е	e ₁	L	ME	Мн	w	Z ⁽¹⁾ max.
mm	4.2	0.51	3.2	1.73 1.13	0.53 0.38	0.36 0.23	19.50 18.55	6.48 6.20	2.54	7.62	3.60 3.05	8.25 7.80	10.0 8.3	0.254	2.2
inches	0.17	0.02	0.13	0.068 0.044	0.021 0.015	0.014 0.009	0.77 0.73	0.26 0.24	0.1	0.3	0.14 0.12	0.32 0.31	0.39 0.33	0.01	0.087

Note

1. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

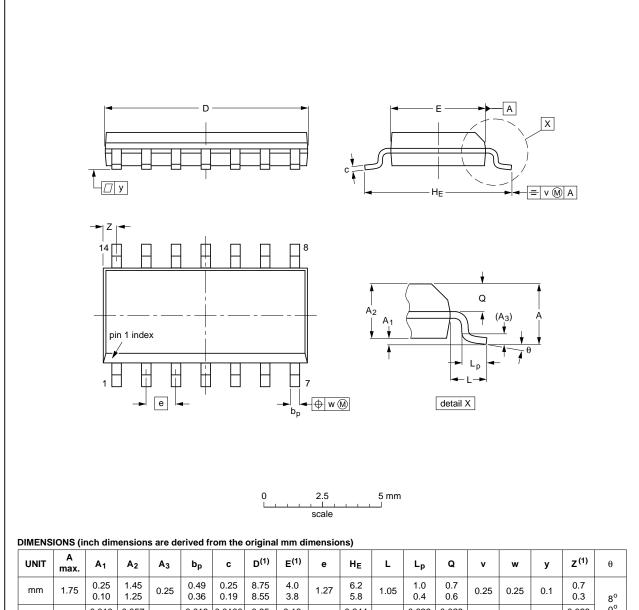
OUTLINE		REFER	ENCES	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT27-1	050G04	MO-001	SC-501-14			99-12-27 03-02-13	

Fig 12. Package outline SOT27-1 (DIP14)

HEF40106B

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1



UNIT	A max.	A ₁	A ₂	А3	bp	С	D ⁽¹⁾	E ⁽¹⁾	е	HE	L	Lp	Q	v	w	у	z ⁽¹⁾	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	8.75 8.55	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01	ı	0.0100 0.0075		0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	1	0.01	0.01	0.004	0.028 0.012	0°

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE		REFER	ENCES		EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT108-1	076E06	MS-012				99-12-27 03-02-19	

Fig 13. Package outline SOT108-1 (SO14)

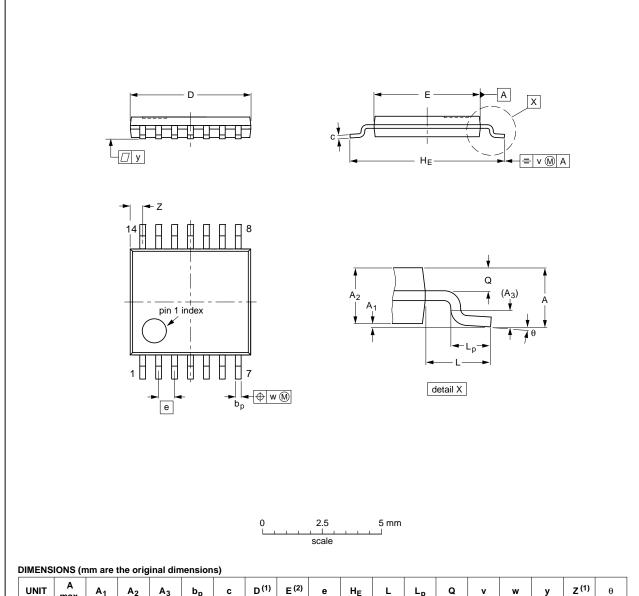
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TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1



						-,												
UNIT	A max.	A ₁	A ₂	A ₃	bp	С	D ⁽¹⁾	E (2)	е	HE	L	Lp	Q	٧	w	у	Z ⁽¹⁾	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.72 0.38	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT402-1		MO-153				99-12-27 03-02-18	
					·		

Fig 14. Package outline SOT402-1 (TSSOP14)

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16. Revision history

Table 12. Revision history

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Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF40106B v.7	20111121	Product data sheet	-	HEF40106B v.6
Modifications:	 Legal pages 	s updated.		
	 Changes in 	"General description" and "I	eatures and benefits".	
HEF40106B v.6	20110823	Product data sheet	-	HEF40106B v.5
HEF40106B v.5	20110511	Product data sheet	-	HEF40106B v.4
HEF40106B v.4	20101115	Product data sheet	-	HEF40106B_CNV v.3
HEF40106B_CNV v.3	19950101	Product specification	-	HEF40106B_CNV v.2
HEF40106B_CNV v.2	19950101	Product specification	-	-

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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18. Contact information

For more information, please visit: http://www.nxp.com

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