HEF4021B

8-bit static shift register Rev. 9 — 30 August 2013

Product data sheet

1. **General description**

The HEF4021B is an 8-bit static shift register (parallel-to-serial converter) with a synchronous serial data input (DS), a clock input (CP), an asynchronous active HIGH parallel load input (PL), eight asynchronous parallel data inputs (D0 to D7) and buffered parallel outputs from the last three stages (Q5 to Q7).

Each register stage is a D-type master-slave flip-flop with a set direct (SD) and clear direct (CD) input. Information on D0 to D7 is asynchronously loaded into the register while PL is HIGH, independent of CP and DS. When PL is LOW, data on DS is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD}, V_{SS}, or another input.

Features and benefits 2.

- Tolerant of slower rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from -40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

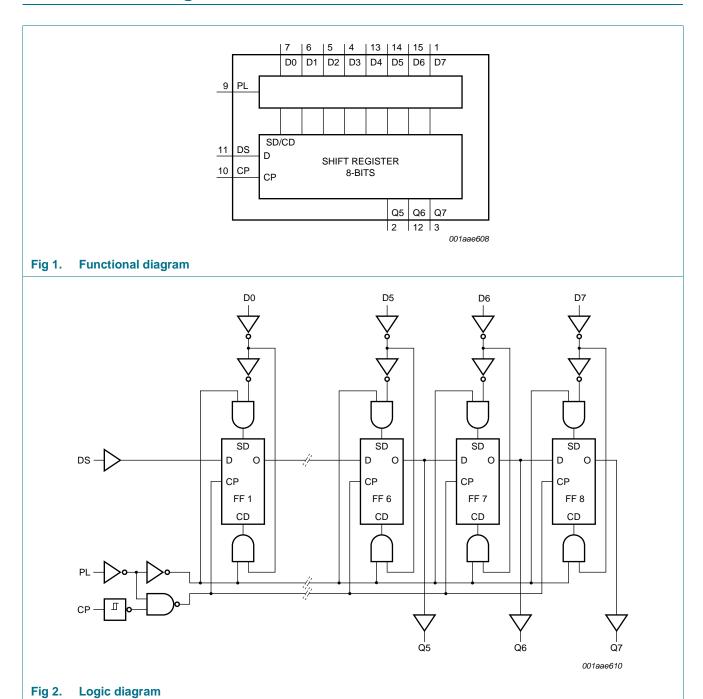
Table 1. **Ordering information**

All types operate from -40 °C to +125 °C.

| Type number | Package | | Version |
|-------------|---------|--|----------|
| | Name | Description | |
| HEF4021BP | DIP16 | plastic dual in-line package; 16 leads (300 mil) | SOT38-4 |
| HEF4021BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |
| HEF4021BTT | TSSOP16 | plastic thin shrink small outline package; 16 leads; body width 4.4 mm | SOT403-1 |

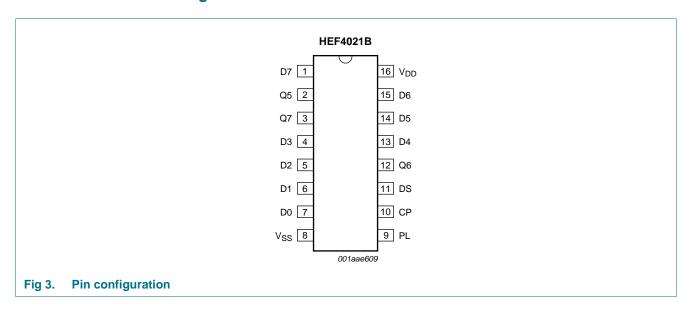


4. Functional diagram



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|--------------------------|---|
| Q5 to Q7 | 2, 12, 3 | buffered parallel output from the last three stages |
| D0 to D7 | 7, 6, 5, 4, 13, 14,15, 1 | parallel data input |
| V _{SS} | 8 | ground supply voltage |
| PL | 9 | parallel load input |
| СР | 10 | clock input (LOW-to-HIGH edge-triggered) |
| DS | 11 | serial data input |
| V_{DD} | 16 | supply voltage |

6. Functional description

Table 3. Function table[1]

| Number of clock | Inputs | | | Outputs | | | | |
|------------------|------------------|--------|----|---------|--------|----|--|--|
| transitions | СР | DS | PL | Q5 | Q6 | Q7 | | |
| Serial operation | Serial operation | | | | | | | |
| 1 | ↑ | data 1 | L | X | X | Χ | | |
| 2 | \uparrow | data 2 | L | X | X | X | | |
| 3 | \uparrow | data 3 | L | Χ | Χ | Χ | | |
| 6 | ↑ | Χ | L | data 1 | X | Χ | | |
| 7 | \uparrow | X | L | data 2 | data 1 | Χ | | |

Table 3. Function table 1... continued

| Number of clock | Inputs | | | Outputs | | |
|--------------------|------------|----|----|-----------|-----------|-----------|
| transitions | СР | DS | PL | Q5 | Q6 | Q7 |
| 8 | \uparrow | X | L | data 3 | data 2 | data 1 |
| | \ | Χ | L | no change | no change | no change |
| Parallel operation | | | | | | |
| | Χ | Χ | Н | D5 | D6 | D7 |

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care;

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| $ \begin{array}{cccccccccccccccccccccccccccccccccccc$ | |
|--|------------------|
| | |
| I_{IK} input clamping current $V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$ | ±10 mA |
| | |
| V _I input voltage -0.5 | $V_{DD} + 0.5 V$ |
| I_{OK} output clamping current $V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$ - | ±10 mA |
| $I_{I/O}$ input/output current - | ±10 mA |
| I _{DD} supply current - | 50 mA |
| T_{stg} storage temperature -65 | 5 +150 °C |
| T _{amb} ambient temperature -40 |) +125 °C |
| P _{tot} total power dissipation T _{amb} –40 °C to +125 °C | |
| DIP16 package [1] - | 750 mW |
| SO16 and TSSOP16 package [2] - | 500 mW |
| P power dissipation per output - | 100 mW |

^[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 $^{\circ}\text{C}.$

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|---------------------|-------------------------------------|-------------------------|-----|-----|----------|------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_{I} | input voltage | | 0 | - | V_{DD} | V |
| T _{amb} | ambient temperature | in free air | -40 | - | +125 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5 V$ | - | - | 3.75 | μs/V |
| | | $V_{DD} = 10 \text{ V}$ | - | - | 0.5 | μs/V |
| | | V _{DD} = 15 V | - | - | 0.08 | μs/V |

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 $[\]uparrow$ = LOW to HIGH clock transition; \downarrow = HIGH to LOW clock transition; data n = data (HIGH or LOW) on the DS input at the nth \uparrow CP transition.

^[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C. For TSSOP16 package: P_{tot} derates linearly with 5.5 mW/K above 60 °C.

9. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | T _{amb} = | –40 °C | T _{amb} = | 25 °C | T _{amb} = 85 °C | | T _{amb} = | 125 °C | Unit | | |
|-----------------|------------------------------|-------------------------|----------------|-------------------------|--------|--------------------|-------|--------------------------|------|--------------------|--------|------|-------|----|
| | | | | Min | Max | Min | Max | Min | Max | Min | Max | | | |
| V _{IH} | HIGH-level | $ I_{O} < 1 \mu A$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | 3.5 | - | V | | |
| | input voltage | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | 7.0 | - | V | | |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | 11.0 | - | V | | |
| V _{IL} | LOW-level | $ I_{O} < 1 \mu A$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | - | 1.5 | V | | |
| | input voltage | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | - | 3.0 | V | | |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | - | 4.0 | V | | |
| V _{OH} | HIGH-level | $ I_{O} < 1 \mu A$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | 4.95 | - | V | | |
| | output | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | 9.95 | - | V | | |
| | voltage | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | 14.95 | - | V | | |
| V _{OL} | LOW-level | $ I_{O} < 1 \mu A$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V | | |
| | output voltage | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V | | |
| | voltage | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V | | |
| I _{OH} | HIGH-level output current | $V_0 = 2.5 \text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | - | -1.1 | mΑ | | |
| | | output current | output current | $V_{O} = 4.6 \text{ V}$ | 5 V | - | -0.64 | - | -0.5 | - | -0.36 | - | -0.36 | mΑ |
| | | $V_0 = 9.5 V$ | 10 V | - | -1.6 | - | -1.3 | - | -0.9 | - | -0.9 | mΑ | | |
| | | $V_0 = 13.5 \text{ V}$ | 15 V | - | -4.2 | - | -3.4 | - | -2.4 | - | -2.4 | mΑ | | |
| I _{OL} | LOW-level | $V_0 = 0.4 \ V$ | 5 V | 0.64 | - | 0.5 | - | 0.36 | - | 0.36 | - | mΑ | | |
| | output current | $V_0 = 0.5 \ V$ | 10 V | 1.6 | - | 1.3 | - | 0.9 | - | 0.9 | - | mΑ | | |
| | | V _O = 1.5 V | 15 V | 4.2 | - | 3.4 | - | 2.4 | - | 2.4 | - | mΑ | | |
| I _I | input leakage current | $V_{DD} = 15 \text{ V}$ | 15 V | - | ±0.1 | - | ±0.1 | - | ±1.0 | - | ±1.0 | μΑ | | |
| I _{DD} | supply | $I_O = 0 A$ | 5 V | - | 5 | - | 5 | - | 150 | - | 150 | μΑ | | |
| | current | ent | 10 V | - | 10 | - | 10 | - | 300 | - | 300 | μΑ | | |
| | | | 15 V | - | 20 | - | 20 | - | 600 | - | 600 | μΑ | | |
| C _I | input capacitance | | - | - | - | - | 7.5 | - | - | - | - | pF | | |

10. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0 \text{ V; } T_{amb} = 25 \text{ °C; for test circuit see } Figure 7; unless otherwise specified.}$

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Тур | Max | Unit |
|-----------|--------------------------------|---------------------|----------|---------------------------------------|-----|-----|-----|------|
| t_{PHL} | HIGH to LOW | CP to Qn | 5 V | 11 98 ns + (0.55 ns/pF)C _L | - | 125 | 250 | ns |
| | propagation delay see Figure 4 | see <u>Figure 4</u> | 10 V | 44 ns + (0.23 ns/pF)C _L | - | 55 | 110 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| | | PL to Qn | 5 V | 93 ns + (0.55 ns/pF)C _L | - | 120 | 240 | ns |
| | | see <u>Figure 4</u> | 10 V | 44 ns + (0.23 ns/pF)C _L | - | 55 | 110 | ns |
| | | | 15 V | 32 ns + $(0.16 \text{ ns/pF})C_L$ | - | 40 | 80 | ns |

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 Table 7.
 Dynamic characteristics ...continued

 $V_{SS} = 0 \text{ V; } T_{amb} = 25 \text{ °C; for test circuit see } \underline{Figure 7}; unless otherwise specified.$

| frequency see Figure 5 10 V 15 30 - MHz | Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Тур | Max | Unit |
|--|-----------------------|-------------------|---------------------|----------|---------------------------------------|-----|-----|-----|------|
| Figure F | t _{PLH} | | | 5 V | 11 88 ns + (0.55 ns/pF)C _L | - | 115 | 230 | ns |
| PL to Qn see Figure 4 10 V 39 ns + (0.28 ns/pF)CL - 105 210 ns 15 V 39 ns + (0.28 ns/pF)CL - 50 100 ns 15 V 32 ns + (0.16 ns/pF)CL - 50 100 ns 15 V 32 ns + (0.16 ns/pF)CL - 60 120 ns 15 V 10 ns + (1.00 ns/pF)CL - 60 120 ns 15 V 10 ns + (1.00 ns/pF)CL - 20 30 60 ns 15 V 10 ns + (0.28 ns/pF)CL - 20 30 60 ns 15 V 10 ns + (0.28 ns/pF)CL - 20 30 60 ns 15 V 10 ns + (0.28 ns/pF)CL - 20 30 60 ns 15 V 10 ns + (0.28 ns/pF)CL - 20 30 60 ns 15 V 15 | | propagation delay | see <u>Figure 4</u> | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 100 | ns |
| See Figure 4 10 V 39 ns + (0.23 ns/pF)CL - 50 100 ns 15 V 32 ns + (0.16 ns/pF)CL - 40 80 ns 15 V 32 ns + (0.16 ns/pF)CL - 40 80 ns 15 V 32 ns + (0.16 ns/pF)CL - 60 120 ns 15 V 9 ns + (0.42 ns/pF)CL - 30 60 ns 15 V 6 ns + (0.28 ns/pF)CL - 20 40 ns 15 V 6 ns + (0.28 ns/pF)CL - 20 40 ns 15 V 6 ns + (0.28 ns/pF)CL - 20 40 ns 15 V 6 ns + (0.28 ns/pF)CL - 20 40 ns 15 V 6 ns + (0.28 ns/pF)CL - 20 40 ns 15 V 15 | | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| t₁ transition time | | | | 5 V | 78 ns + (0.55 ns/pF)C _L | - | 105 | 210 | ns |
| | | | see <u>Figure 4</u> | 10 V | 39 ns + (0.23 ns/pF)C _L | - | 50 | 100 | ns |
| 10 V 9 ns + (0.42 ns/pF)CL | | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| t _{su} | t _t | transition time | Qn; see Figure 4 | 5 V | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |
| $t_{h} = \frac{15 \text{V}}{15 \text{V}} + \frac{15 \text{J}}{50} = \frac{10 \text{V}}{10 \text{N}} + \frac{15 \text{J}}{50} = \frac{10 \text{N}}{10 \text{N}} + \frac{15 \text{J}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{V}} + \frac{15 \text{J}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{N}} + \frac{15 \text{J}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{N}} + \frac{15 \text{J}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{V}} + \frac{15 \text{J}}{10 \text{V}} = \frac{10 \text{N}}{10 \text{N}} = \frac{10 \text{N}}{10 $ | t _{su} | set-up time | | 5 V | | +25 | -15 | - | ns |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | see Figure 5 | 10 V | | +25 | -10 | - | ns |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | | 15 V | | +15 | -5 | - | ns |
| $t_{h} \\ \begin{tabular}{ l l l l l l l l l l l l l l l l l l l$ | | | | 5 V | | 50 | 25 | - | ns |
| | | | see <u>Figure 6</u> | 10 V | | 30 | 10 | - | ns |
| | | | | 15 V | | 20 | 5 | - | ns |
| $t_{W} \text{pulse width} \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | t _h | hold time | • | 5 V | | 40 | 20 | - | ns |
| $t_{W} = \frac{10 \text{ to PL; see Figure 6}}{10 \text{ V}} = \frac{5 \text{ V}}{15 \text{ V}} + 115 -10 - \text{$ | | | | 10 V | | 20 | 10 | - | ns |
| | | | | 15 V | | 15 | 8 | - | ns |
| $t_{W} \text{pulse width} \begin{array}{c} CP = LOW; \\ \text{minimum width;} \\ \text{see Figure 5} \end{array} \begin{array}{c} 5 \ V \\ \\ 10 \ V \\ \end{array} \begin{array}{c} 30 \ 15 \\ \\ 15 \ V \\ \end{array} \begin{array}{c} 30 \ 15 \\ \\ 24 \ 12 \\ \end{array} \begin{array}{c} - \ \text{ns} \\ \end{array} \begin{array}{c} \\ 15 \ V \\ \end{array} \begin{array}{c} 10 \ V \\ \\ \end{array} \begin{array}{c} 10 \ V \\ \end{array} \begin{array}{c} 30 \ 15 \\ \end{array} \begin{array}{c} - \ \text{ns} \\ \end{array} \begin{array}{c} \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$ | | | , | 5 V | | +15 | -10 | - | ns |
| $t_{W} \ \ \text{Pulse width} \ \ \begin{array}{llllllllllllllllllllllllllllllllll$ | | | see <u>Figure 6</u> | 10 V | | 15 | 0 | - | ns |
| | | | | 15 V | | 15 | 0 | - | ns |
| | t_{W} | pulse width | • | 5 V | | 70 | 35 | - | ns |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | • | 10 V | | 30 | 15 | - | ns |
| | | | occ <u>rigure o</u> | 15 V | | 24 | 12 | - | ns |
| | | | | 5 V | | 70 | 35 | - | ns |
| | | | • | 10 V | | 30 | 15 | - | ns |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | occ <u>rigure c</u> | 15 V | | 24 | 12 | - | ns |
| $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | t _{rec} | recovery time | • | 5 V | | 50 | 10 | - | ns |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | | | see <u>Figure 6</u> | 10 V | | 40 | 5 | - | ns |
| frequency see Figure 5 10 V 15 30 - MHz | | | | 15 V | | 35 | 5 | - | ns |
| 10 0 10 10 10 10 10 10 10 10 10 10 10 10 | f _{clk(max)} | | | 5 V | | 6 | 13 | - | MHz |
| 15 V 20 40 - MHz | | trequency | see <u>Figure 5</u> | 10 V | | 15 | 30 | - | MHz |
| | | | | 15 V | | 20 | 40 | - | MHz |

 $^{[1] \}quad \text{The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).}$

Table 8. Dynamic power dissipation P_D

 P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

| Symbol | Parameter | V_{DD} | Typical formula for P _D (μW) | where: |
|--------|---------------|----------|--|---|
| P_D | dynamic power | 5 V | $P_D = 900 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$ | f_i = input frequency in MHz, |
| | dissipation | 10 V | $P_D = 4300 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$ | f_o = output frequency in MHz, |
| | | 15 V | $P_D = 12000 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$ | C_L = output load capacitance in pF, V_{DD} = supply voltage in V, $\Sigma(f_o \times C_L)$ = sum of the outputs. |

11. Waveforms

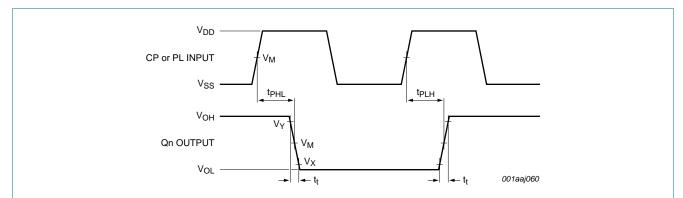


Fig 4. Waveforms showing propagation delays for CP and PL inputs to Qn output and Qn transition times

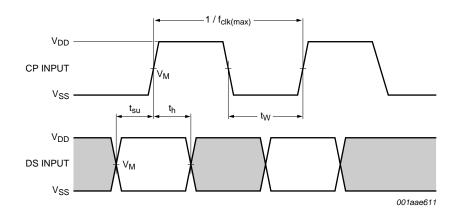


Fig 5. Waveforms showing minimum clock pulse width, set-up time, and hold time for CP and DS.

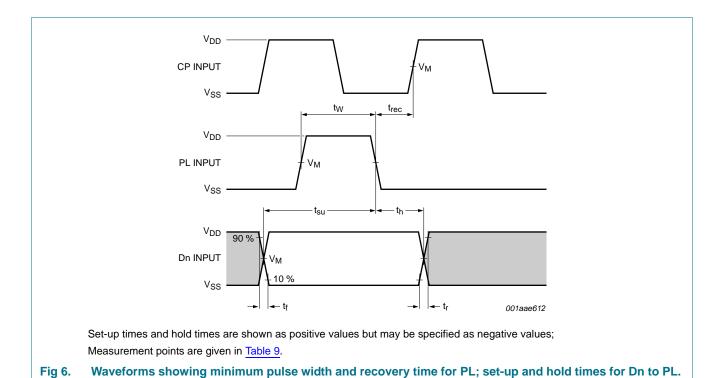
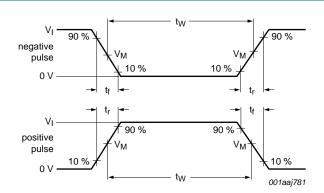
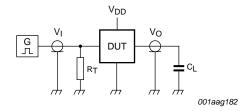


Table 9. Measurement points

| Supply voltage | Input | Output | | |
|----------------|--------------------|--------------------|--------------------|--------------------|
| V_{DD} | V _M | V _M | V _X | V _Y |
| 5 V to 15 V | 0.5V _{DD} | 0.5V _{DD} | 0.1V _{DD} | 0.9V _{DD} |



a. Input waveform



b. Test circuit

Test data is given in Table 10.

Definitions for test circuit:

DUT = Device Under Test.

C_L = load capacitance including jig and probe capacitance.

 R_T = termination resistance should be equal to the output impedance Z_0 of the pulse generator.

Fig 7. Test circuit for measuring switching times

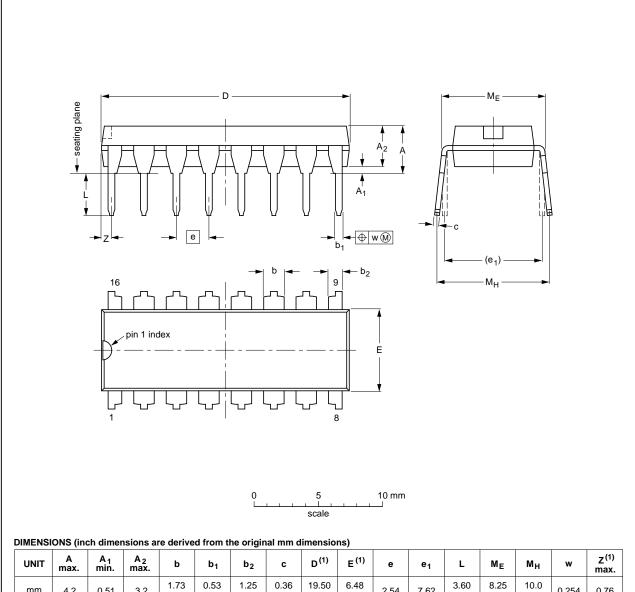
Table 10. Test data

| Supply voltage | Input | Load | |
|----------------|------------------------------------|---------------------------------|-------|
| V_{DD} | VI | t _r , t _f | CL |
| 5 V to 15 V | V _{SS} or V _{DD} | ≤ 20 ns | 50 pF |

12. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4



| UNIT | A max. | A ₁ min. | A ₂ max. | b | b ₁ | b ₂ | С | D ⁽¹⁾ | E ⁽¹⁾ | е | e ₁ | L | ME | Мн | w | Z ⁽¹⁾ max. |
|--------|-----------|------------------------|------------------------|----------------|----------------|----------------|----------------|------------------|------------------|------|----------------|--------------|--------------|--------------|-------|--------------------------|
| mm | 4.2 | 0.51 | 3.2 | 1.73 1.30 | 0.53 0.38 | 1.25 0.85 | 0.36 0.23 | 19.50 18.55 | 6.48 6.20 | 2.54 | 7.62 | 3.60 3.05 | 8.25 7.80 | 10.0 8.3 | 0.254 | 0.76 |
| inches | 0.17 | 0.02 | 0.13 | 0.068 0.051 | 0.021 0.015 | 0.049 0.033 | 0.014 0.009 | 0.77 0.73 | 0.26 0.24 | 0.1 | 0.3 | 0.14 0.12 | 0.32 0.31 | 0.39 0.33 | 0.01 | 0.03 |

Note

1. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

| OUTLINE | | REFER | EUROPEAN | ISSUE DATE | | |
|---------|-----|-------|----------|------------|------------|---------------------------------|
| VERSION | IEC | JEDEC | JEITA | | PROJECTION | ISSUE DATE |
| SOT38-4 | | | | | | 95-01-14 03-02-13 |
| | | | | | | |

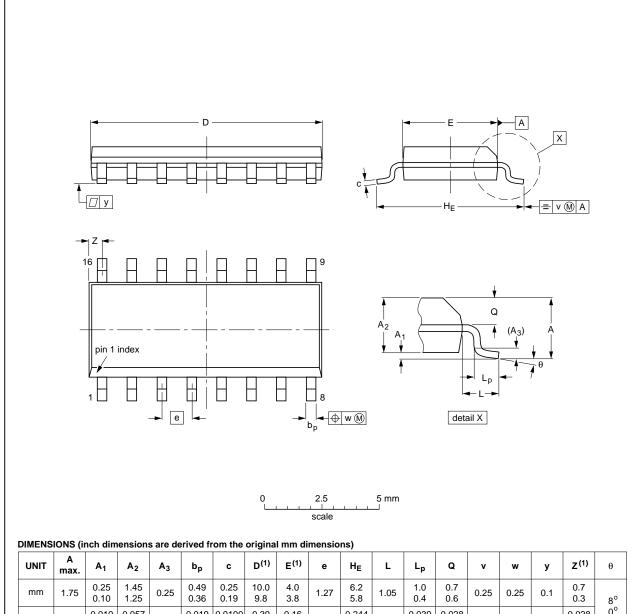
Fig 8. Package outline SOT38-4 (DIP16)

HEF4021B

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SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



| UNIT | A max. | A ₁ | A ₂ | A ₃ | bp | С | D ⁽¹⁾ | E ⁽¹⁾ | е | HE | L | Lp | Q | v | w | у | Z ⁽¹⁾ | θ |
|--------|-----------|----------------|----------------|----------------|--------------|------------------|------------------|------------------|------|----------------|-------|----------------|------------|------|------|-------|------------------|----|
| mm | 1.75 | 0.25 0.10 | 1.45 1.25 | 0.25 | 0.49 0.36 | 0.25 0.19 | 10.0 9.8 | 4.0 3.8 | 1.27 | 6.2 5.8 | 1.05 | 1.0 0.4 | 0.7 0.6 | 0.25 | 0.25 | 0.1 | 0.7 0.3 | 8° |
| inches | 0.069 | 0.010 0.004 | 0.057 0.049 | 0.01 | l | 0.0100 0.0075 | 0.39 0.38 | 0.16 0.15 | 0.05 | 0.244 0.228 | 0.041 | 0.039 0.016 | | 0.01 | 0.01 | 0.004 | 0.028 0.012 | 0° |

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

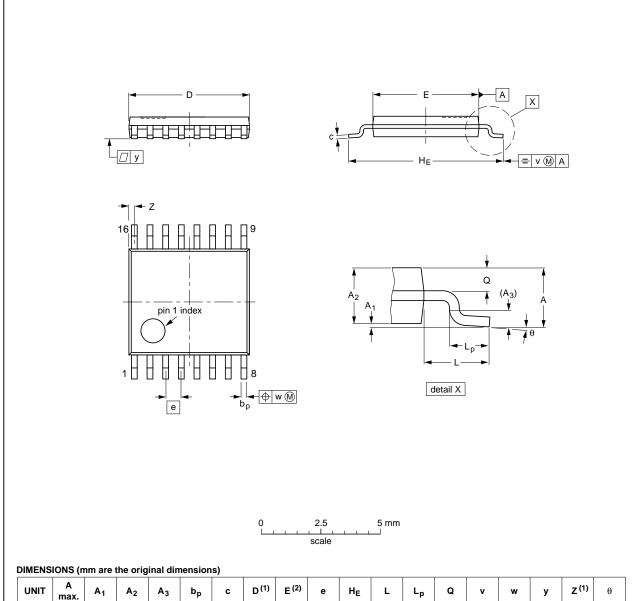
| | OUTLINE | | REFER | EUROPEAN | ISSUE DATE | | | |
|--|----------|--------|--------|----------|------------|------------|---------------------------------|--|
| | VERSION | IEC | JEDEC | JEITA | | PROJECTION | ISSUE DATE | |
| | SOT109-1 | 076E07 | MS-012 | | | | 99-12-27 03-02-19 | |
| | | | | | | | | |

Fig 9. Package outline SOT109-1 (SO16)

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TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1



| UNIT | A max. | A ₁ | A ₂ | A ₃ | bp | С | D ⁽¹⁾ | E (2) | е | HE | L | Lp | Q | v | w | у | Z ⁽¹⁾ | θ |
|------|-----------|----------------|----------------|----------------|--------------|------------|------------------|------------|------|------------|---|--------------|------------|-----|------|-----|------------------|----------|
| mm | 1.1 | 0.15 0.05 | 0.95 0.80 | 0.25 | 0.30 0.19 | 0.2 0.1 | 5.1 4.9 | 4.5 4.3 | 0.65 | 6.6 6.2 | 1 | 0.75 0.50 | 0.4 0.3 | 0.2 | 0.13 | 0.1 | 0.40 0.06 | 8° 0° |

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

| OUTLINE | | REFER | EUROPEAN | ISSUE DATE | | | | |
|----------|-----|--------|----------|------------|------------|----------------------------------|--|--|
| VERSION | IEC | JEDEC | JEITA | | PROJECTION | ISSUE DATE | | |
| SOT403-1 | | MO-153 | | | | -99-12-27 03-02-18 | | |
| | | | | | | | | |

Fig 10. Package outline SOT403-1 (TSSOP16)

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13. Revision history

Table 11. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes | | | | | | | |
|------------------|---------------------------------|---|---------------|------------------|--|--|--|--|--|--|--|
| HEF4021B v.9 | 20130830 | Product data sheet | - | HEF4021B v.8 | | | | | | | |
| Modifications: | added type | number HEF4021BTT. | | | | | | | | | |
| HEF4021B v.8 | 20111118 | Product data sheet | - | HEF4021B v.7 | | | | | | | |
| Modifications: | Legal page: | Legal pages updated. | | | | | | | | | |
| | Changes in | Changes in "General description" and "Features and benefits". | | | | | | | | | |
| | Section "Ap | plications" removed. | | | | | | | | | |
| HEF4021B v.7 | 20111010 | Product data sheet | - | HEF4021B v.6 | | | | | | | |
| HEF4021B v.6 | 20091127 | Product data sheet | - | HEF4021B v.5 | | | | | | | |
| HEF4021B v.5 | 20090707 | Product data sheet | - | HEF4021B v.4 | | | | | | | |
| HEF4021B v.4 | 20081110 | Product data sheet | - | HEF4021B_CNV v.3 | | | | | | | |
| HEF4021B_CNV v.3 | 19950101 | Product specification | - | HEF4021B_CNV v.2 | | | | | | | |
| HEF4021B_CNV v.2 | 19950101 | Product specification | - | - | | | | | | | |
| | | | | | | | | | | | |

14. Legal information

14.1 Data sheet status

| Document status[1][2] | Product status[3] | Definition |
|--------------------------------|-------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
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8-bit static shift register

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