



Very Low Power 4-Output PCIe Clock Buffer With On-chip Termination

Features

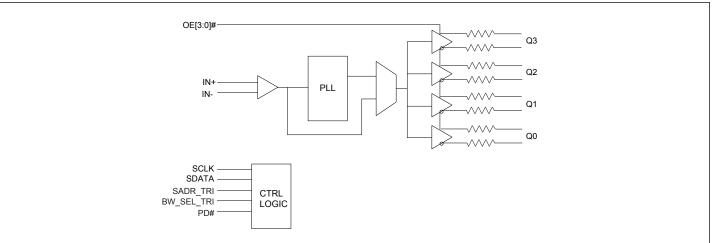
- → 1.8V supply voltage
- → HCSL input: 100MHz, also support 50MHz or 125MHz via **SMBus**
- → 4 differential low power HCSL outputs with on-chip termination
- → Individual output enable
- → Programmable Slew rate and output amplitute for each output
- → Differential outputs blocked until PLL is locked
- → Strapping pins or SMBus for configuration;
- → 3.3V tolerant SMBus interface support
- → Very low jitter outputs
 - Differential cycle-to-cycle jitter <50ps
 - Differential output-to-output skew <50ps
 - PCIe Gen1/Gen2/Gen3/Gen4 compliant
- → Packaging (Pb-free & Green): 32-lead 5×5mm TQFN

Block Diagram

Description

The PI6CB18401 is an 4-output very low power PCIe Gen1/Gen2/ Gen3/Gen4 clock buffer. It takes an reference input to fanout four 100MHz low power differential HCSL outputs with on-chip terminations. The on-chip termination can save 16 external resistors and make layout easier. Individual OE pin for each output provides easier power management.

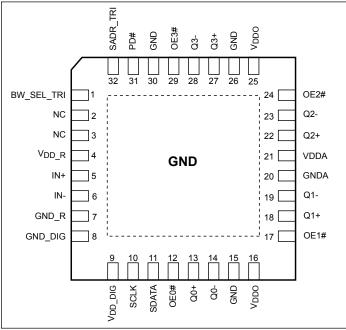
It uses Pericom proprietary PLL design to achieve very low jitter that meets PCIe Gen1/Gen2/Gen3/Gen4 requirements. Other than PCIe 100MHz support, this device also support Ethernet application with 50MHz or 125MHz via SMBus. It provides various options such as different slew rate and amplitude through strapping pins or SMBUS so that users can configure the device easily to get the optimized performance for their individual boards.







Pin Configuration



Pin Description

Pin Number	Pin Name	Ту	ре	Description
1	BW_SEL_TRI	Input	Tri-level	Latch to select low loop bandwidth, bypass PLL, and high loop band- width. This pin has both internal pull-up and pull-down
2	NC			Internal connected for feedback loop. Do not connect this pin
3	NC			Internal connected for feedback loop. Do not connect this pin
4	V _{DD} _R	Power		Power supply for input differential buffers
5	IN+	Input		Differential true clock input
6	IN-	Input		Differential complementary clock input
7	GND_R	Power		Ground for input differential buffers
8	GND_DIG	Power		Ground for digital circuitry
9	V _{DD} _DIG	Power		Power supply for digital circuitry, nominal 1.8V
10	SCLK	Input	CMOS	SMBUS clock input, 3.3V tolerant
11	SDATA	Input/ Output	CMOS	SMBUS Data line, 3.3V tolerant
10	0.004	T (01/00	Active low input for enabling Q0 pair. This pin has an internal pull-down.
12	OE0#	Input	CMOS	1 =disable outputs, 0 = enable outputs
13	Q0+	Output	HCSL	Differential true clock output
14	Q0-	Output	HCSL	Differential complementary clock output
15, 26, 30	GND	Power		Ground
16, 25	V _{DDO}	Power		Power supply for differential outputs
17	OE1#	Input	CMOS	Active low input for enabling Q1 pair. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs





Pin Description Cont.

Pin Number	Pin Name	Ту	pe	Description
18	Q1+	Output	HCSL	Differential true clock output
19	Q1-	Output	HCSL	Differential complementary clock output
20	GNDA	Power		Ground for analog circuitry
21	V _{DDA}	Power		Power supply for analog circuitry
22	Q2+	Output	HCSL	Differential true clock output
23	Q2-	Output	HCSL	Differential complementary clock output
24	OE2#	Input	CMOS	Active low input for enabling Q2 pair. This pin has an internal pull- down. 1 =disable outputs, 0 = enable outputs
27	Q3+	Output	HCSL	Differential true clock output
28	Q3-	Output	HCSL	Differential complementary clock output
29	OE3#	Input	CMOS	Active low input for enabling Q3 pair. This pin has an internal pull- down. 1 =disable outputs, 0 = enable outputs
				Input notifies device to sample latched inputs and start up on first high
31 PD#		Input	CMOS	assertion. Low enters Power Down Mode, subsequent high assertions exit Power Down Mode. This pin has internal pull-up resistor.
32	SADR_TRI	Input	Tri-level	Latch to select SMBus Address. This pin has an internal pull-down





SMBus Address Selection Table

	SADR	Address	+Read/Write Bit
	0	1101011	Х
State of SADR on first application of PD#	М	1101100	Х
	1	1101101	Х

Power Management Table

PD#	IN	SMBus OE bit	OEn#	Qn+	Qn-	PLL Status
0	Х	X	Х	Low	Low	Off
1	Running	0	Х	Low	Low	On ¹
1	Running	1	0	Running	Running	On ¹
1	Running	1	1	Low	Low	On ¹

Note:

1. If PLL Bypass mode is selected, the PLL will be off and outputs will be running.

PLL Operating Mode Select Table

BW_SEL_TRI	Operating Mode	Byte1 [7:6] Readback	Byte1 [4:3] Readback
0	PLL with low Bandwidth	00	00
М	PLL Bypass	01	01
1	PLL with high Bandwidth	11	11

Frequency Select table

Freq. Select Byte 3 [4:3]	IN (MHz)	Qn (MHz)
00 (default)	100	100
01	50	50
10	125	125
11	Reserved	Reserved





Maximum Ratings

(Above which useful life may be impaired. For user guidelines, not tested.)	_
Storage Temperature65°C to +150°C	N
Supply Voltage to Ground Potential, $V_{ m DDxx}$ 0.5V to +2.5V	S
Input Voltage –0.5V to $\mathrm{V_{DD+0.5V}}$, not exceed 2.5V	n r
SMBus, Input High Voltage 3.6V	a
ESD Protection (HBM)	S S
Junction Temperature125 °C max	a

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress cating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Operating Conditions

Temperature = T_A ; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Conditions	Min	Тур.	Max.	Units
V _{DD} , V _{DDA} , V _{DD} _R, V _{DD} _DIG	Power Supply Voltage		1.7	1.8	1.9	V
V _{DDO}	Output Power Supply Voltage		1.7	1.8	1.9	V
I _{DDA}	Analog Power Supply Current	$V_{DDA} + V_{DD}R$, PLL mode, All outputs active @100MHz		11	15	mA
I _{DD}	Power Supply Current	$V_{DD} + V_{DD_DIG}$, All outputs active @100MHz		8	10	mA
I _{DDO}	Power Supply Current for Outputs	All outputs active @100MHz		17	25	mA
I _{DDA_PD}	Analog Power Supply Power Down ¹ Current	$V_{DDA} + V_{DD}R$, PLL mode, All outputs active @100MHz		0.7	1	mA
I _{DD_PD}	Power Supply Power Down ¹ Current	$V_{DD} + V_{DD_DIG+} V_{DDO}$, All outputs LOW/LOW			1.2	mA
т.	Ambient Temperature	Commercial grade	0		70	°C
T _A	Ambient Temperature	Industrial grade	-40		85	

Note:

1. Input clock is not running.

Input Electrical Characteristics

Symbol	Parameters	Conditions	Min.	Тур.	Max.	Units
R _{pu}	Internal pull up resistance			120		KΩ
R _{dn}	Internal pull down resistance			120		KΩ
L _{PIN}	Pin inductance				7	nH





SMBus Electrical Characteristics

Temperature = T_A; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Conditions	Min.	Тур.	Max.	Units
V _{DDSMB}	Nominal bus voltage		1.7		3.6	V
		SMBus, $V_{DDSMB} = 3.3V$	2.1		3.6	
V _{IHSMB}	SMBus Input High Voltage	SMBus, V _{DDSMB} < 3.3V	0.65 V _{DDSMB}			V
N	SMBus Input Low Voltage	SMBus, V _{DDSMB} = 3.3V			0.6	V
V _{ILSMB}		SMBus, V _{DDSMB} < 3.3V			0.6	
I _{SMBSINK}	SMBus sink current	SMBus, at V _{OLSMB}	4			mA
VOLSMB	SMBus Output Low Voltage	SMBus, at I _{SMBSINK}			0.4	V
f _{MAXSMB}	SMBus operating frequency	Maximum frequency			400	kHz
t _{RMSB}	SMBus rise time	(Max V_{IL} - 0.15) to (Min V_{IH} + 0.15)			1000	ns
t _{FMSB}	SMBus fall time	(Min V_{IH} + 0.15) to (Max V_{IL} - 0.15)			300	ns

LVCMOS DC Electrical Characteristics

Temperature = T_A; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Conditions	Min.	Тур.	Max.	Units
V _{IH}	Input High Voltage	Single-ended inputs, except SMBus	0.75 V _{DD}		V _{DD} +0.3	V
V _{IM}	Input Mid Voltage	SADR_TRI, BW_SEL_TRI	$0.4 V_{DD}$	$0.5 V_{DD}$	$0.6V_{DD}$	V
V _{IL}	Input Low Voltage	Single-ended inputs, except SMBus	-0.3		0.25 V _{DD}	V
I _{IH}	Input High Current	Single-ended inputs, $V_{IN} = V_{DD}$			20	mA
I _{IL}	Input Low Current	Single-ended inputs, $V_{IN} = 0V$	-20			μΑ
I _{IH}	Input High Current	Single-ended inputs with pull up / pull down resistor, $V_{\rm IN}$ = $V_{\rm DD}$			220	mA
I _{IL}	Input Low Current	Single-ended inputs with pull up / pull down resistor, $V_{IN} = 0V$	-220			μΑ
C _{IN}	Input Capacitance		1.5		5	pF





LVCMOS AC Electrical Characteristics

Temperature = T_A; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Conditions	Min.	Тур.	Max.	Units
t _{OELAT}	Output enable latency	Q start after OE# assertion	1		3	clocks
		Q stop after OE# deassertion	1			
t _{PDLAT}	PD# de-assertion	Differential outputs enable after PD# de- assertion		20	300	us

HCSL Input Characteristics ¹

Temperature = T_A; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Conditions	Min.	Typ.	Max.	Units
V _{IHDIF}	Diff. Input High Voltage ³	IN+, IN-, single-end measurement	600	800	1150	mV
V _{ILDIF}	Diff. Input Low Voltage ³	IN+, IN-, single-end measurement	-300	0	300	mV
V _{COM}	Diff. Input Common Mode Voltage		150		1000	mV
V _{SWING}	Diff. Input Swing Voltage	Peak to peak value (V_{IHDIF} - V_{ILDIF})	300		1450	mV
f _{INBP}	Input Frequency	PLL Bypass mode	1		200	MHz
f _{IN100}	Input Frequency	100MHz PLL	60	100	110	MHz
f _{IN125}	Input Frequency	125MHz PLL	75	125	137.5	MHz
f _{IN156}	Input Frequency	50MHz PLL	30	50	65	MHz
t _{STAB}	Clock stablization	From V_{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock		0.6	1.0	ms
t _{RF}	Diff. Input Slew Rate ²	Measured differentially	0.4			V/ns
I _{IN}	Diff. Input Leakage Current	$V_{IN} = V_{DD}, V_{IN} = GND$	-5	0.01	5	uA
t _{DC}	Diff. Input Duty Cycle	Measured differentially	45		55	%
tj _{c-c}	Diff. Input Cycle to cycle jitter	Measured differentially			125	ps

Note:

1. Guaranteed by design and characterization, not 100% tested in production

2. Slew rate measured through +/-75mV window centered around differential zero

3. The device can be driven by a single-ended clock by driving the true clock and biasing the complement clock input to the V bias, where V bias is $(V_{IH}-V_{IL})/2$





HCSL Output Characteristics

Temperature = T_A; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Condition	Min.	Тур.	Max.	Units
V _{OH}	Output Voltage High ¹	Statistical measurement on single-ended	660	774	900	mV
V _{OL}	Output Voltage Low ¹	signal using oscilloscope math function	-150		150	mV
V _{OMAX}	Output Voltage Maximum ¹	Measurement on single ended signal using		821	1150	mV
V _{OMIN}	Output Voltage Minimum ¹	absolute value	-300	-15		mV
VOSWING	Output Swing Voltage ^{1,2,3}	Scope averaging off	300	1536		mV
V _{OC}	Output Cross Voltage ^{1,2,4}		250	430	550	mV
DV _{OC}	V _{OC} Magnitude Change ^{1,2,5}			12	140	mV

Note:

1. At default SMBUS amplitude settings

2. Guaranteed by design and characterization, not 100% tested in production

3. Measured from differential waveform

4. This one is defined as voltage where Q + = Q- measured on a component test board and only applied to the differential rising edge

5. The total variation of all Vcross measurements in any particular system. This is a subset of Vcross_min/max allowed.

HCSL Output AC Characteristics

Temperature = T_A ; Supply voltages per normal operation conditions; See test circuits for the load conditions

Symbol	Parameters	Condition	Min.	Тур.	Max.	Units
fout	Output Frequency			100		MHz
BW	PLL bandwidth ^{1, 8}	-3dB point in High Bandwidth Mode	2	2.7	4	MHz
DVV	PLL bandwidth	-3dB point in Low Bandwidth Mode	1	1.4	2	MHz
tj _{peak}	PLL Jitter Peaking	Peak pass band gain		1.2	2	dB
t	Slew rate ^{1,2,3}	Scope averaging on fast setting	2.2	3	6.5	V/ns
t _{RF}	Slew fale	Scope averaging on slow setting	0.4	2	3	V/ns
Dt _{RF}	Slew rate matching ^{1,2,4}	Scope averaging on		7	20	%
t _{SKEW}	Output Skew ^{1,2}	Averaging on, $V_T = 50\%$		43	50	ps
	Dromagation dalay	PLL Bypass mode, $V_T = 50\%$	3000	3600	4500	ps
tpdelay	Propagation delay	PLL mode, $V_T = 50\%$	0	90	200	ps
tj _{c-c}	Cycle to cycle jitter ^{1,2}			14	50	ps
		PCIe Gen 1	20	22	86	ps
		PCIe Gen 2 Low Band, 10kHz < f < 1.5MHz	0.2	0.3	3.0	ps
tjphase	Integrated phase jitter (RMS)	PCIe Gen 2 High Band, 1.5MHz < f < Ny- quist (50MHz)	1.6	2.0	3.1	ps
UPHASE	1,5,6	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR =10MHz)	0.3	0.35	1.0	ps
		125MHz, 1.5MHz to 20MHz, -20dB/decade Rollover < 1.5MHz, -40dB/decade rolloff > 10MHz ⁹		1.9	2	ps





HCSL Output AC Characteristics Cont.

Symbol	Parameters	Condition	Min.	Тур.	Max.	Units
		PCIe Gen 1		0.6	5	ps
		PCIe Gen 2 Low Band, 10kHz < f < 1.5MHz		0.1	0.3	ps
		PCIe Gen 2 High Band, 1.5MHz < f < Ny- quist (50MHz)		0.05	0.1	ps
tj _{PHASEA}	Additive Integrated phase jitter (RMS) ^{1,5,10}	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR =10MHz)		0.05	0.1	ps
		PCIe Gen 4 (PLL BW of 2-4 or 2-5MHz, CDR =10MHz) (BW_SEL_TRI=M)		0.03	0.05	ps
		125MHz, 1.5MHz to 20MHz, -20dB/decade Rollover < 1.5MHz, -40dB/decade rolloff > 10MHz		0.15	0.3	ps
t _{DC}	Duty Cycle ^{1,2}	Measured differentially, PLL Mode	45	50	55	%
t _{DCD}	Duty Cycle Distortion ^{1,7}	Measured differentially, PLL Bypass Mode at 100MHz	-1	0	1	%
t _{STARTUP}	Start up time				10	ms
t _{LOCK}	PLL lock time				20	ms

Note:

1. Guaranteed by design and characterization, not 100% tested in production

2. Measured from differential waveform

3. Slew rate is measured through the Vswing voltage range centered around differential 0V, within +/-150mV window

4. Slew rate matching is measured using a +/-75mV window centered at differential zero

5. See http://www.pcisig.com for complete specs

6. Sample size of at least 100k cycles. This can be extrapolated to 108ps pk-pk @ 1M cycles for a BER of 10⁻¹²

7. Duty cycle distortion is the difference in duty cycle between the out and input clock when te device is operated in the PLL bypass mode

8. The Min and Max values of each BW setting track each other, low BW max will never occur with high BW min

9. Applies to all differential outputs

10. For additive jitter RMS value is calculated by the following equation = SQRT [(total jitter)^{*2} - (input jitter)^{*2}]





SMBus Serial Data Interface

PI6CB18401 is a slave only device that supports block read and block write protocol using a single 7-bit address and read/write bit as shown below.

Read and write block transfers can be stopped after any complete byte transfer.

Address Assignment

A6	A5	A4	A3	A2	A1	A0	R/W
1	1	0	1	See SBMus Ad	1/0		

Note: SMBus address is latched on SADR pin

How to Write

1 bit	7 bits	1 bit	1 bit	8 bits	1 bit	8 bits	1 bit	8 bits	1 bit	8 bits	1 bit	1 bit
Start bit	Add.	W(0)	Ack	Beginning Byte loca- tion = N	Ack	Data Byte count = X	Ack	Beginning Data Byte (N)	Ack	 Data Byte (N+X-1)	Ack	Stop bit

How to Read

1 bit	7 bits	1 bit	1 bit	8 bits	1 bit	1 bit	7 bits	1 bit	1 bit	8 bits	1 bit	8 bits	1 bit
Start bit	Address	W(0)	Ack	Beginning Byte loca- tion = N	Ack	Repeat Start bit	Address	R(1)	Ack	Data Byte count = X	Ack	Beginning Data Byte (N)	Ack

8 bits	1 bit	1 bit
Data Byte	NAck	Stop bit
(N+X-1)	INACK	3100 011





Byte 0: Output Enable Register ¹

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7	Reserved			1		
6	Q3_OE	Q6 output enable	RW	1	Low/Low	Enabled
5	Q2_OE	Q5 output enable	RW	1	Low/Low	Enabled
4	Reserved			1		
3	Q1_OE	Q3 output enable	RW	1	Low/Low	Enabled
2	Reserved			1		
1	Q0_OE	Q1 output enable	RW	1	Low/Low	Enabled
0	Reserved			1		

Note:

1. A low on these bits will override the OE# pins and force the differential outputs to Low/Low states

Power Up Condition Bit **Control Function** Description Type 0 1 7 PLL Mode Readback Bit1 R PLLMODERB1 Latch See PLL Operating Mode Table 6 PLLMODERB0 PLL Mode Readback Bit0 R Latch Values in Values in 5 PLLMODE_SWCTR Enable SW control of PLL Mode RW 0 B1[7:6] set PLL B1[4:3] set PLL Mode Mode RW^1 PLLMODE1 PLL Mode control Bit1 0 4 See PLL Operating Mode Table RW^1 PLLMODE0 PLL Mode control Bit0 0 3 2 Reserved 1 1 Amplitude1 RW 1 '00' = 0.6V, '01' = 0.7V, '10' = Control output applitude 0.8V, '11' = 0.9V0 Amplitude0 RW 0

Byte 1: PLL Pperating Mode and Output Amplitude Control Register

Note:

1. B1[5] must be set to a 1 for these bits to have any effect on the part





Byte 2: Differential Output Slew Rate Control Register

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7	Reserved			1		
6	SLEWRATECTR_Q3	Control slew rate of Q6	RW	1	Slow setting	Fast setting
5	SLEWRATECTR_Q2	Control slew rate of Q5	RW	1	Slow setting	Fast setting
4	Reserved			1		
3	SLEWRATECTR_Q1	Control slew rate of Q3	RW	1	Slow setting	Fast setting
2	Reserved			1		
1	SLEWRATECTR_Q0	Control slew rate of Q1	RW	1	Slow setting	Fast setting
0	Reserved			1		

Byte 3: Frequency Select Control Register

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7	Reserved			1		
6	Reserved			1		
5	FREQ_SEL_EN	Enable SW selection of frequency	RW	0	SW Freq. selection disabled	SW Freq. selection enabled
4	FSEL1	Freq. Select Bit 1	RW ¹	0	с Б	C 1 (T 1 1
3	FSEL0	Freq. Select Bit 0	RW ¹	0	See Frequency	Select Table
2	Reserved			1		
1	Reserved			1		
0	SLEWRATESEL FB	Adjust Slew Rate of Feedback signal	RW	1	2.0V/ns	3.0V/ns

Note:

1. B1[5] must be set to a 1 for these bits to have any effect on the part

Byte 4: Reserved

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7:0	Reserved			1		





Power Up Bit **Control Function** Description Type Condition 0 1 7 RID3 R 0 RID2 R 0 6 Revision ID rev = 0000 R 5 RID1 0 4 RID0 R 0 PVID3 R 0 3 2 R 0 PVID3 Vendor ID Pericom = 0011PVID3 R 1 1 0 PVID3 R 1

Byte 5: Revision and Vendor ID Register

Byte 6: Device Type/Device ID Register

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7	DTYPE1	Device type	R	0	'00' = CG, '01' =	ZDB,
6	DTYPE0		R	1	'10' = Reserve, '11' = ZDB	
5	DID5	- Device ID	R	0	- 000100 binary, 04Hex	
4	DID4		R	0		
3	DID3		R	0		
2	DID2		R	1		
1	DID1		R	0		
0	DID0		R	0		

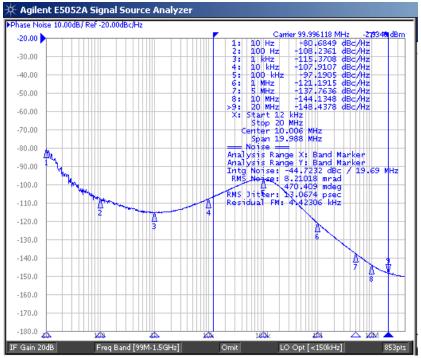
Byte 7: Byte Count Register

Bit	Control Function	Description	Туре	Power Up Condition	0	1
7	Reserved			0		
6	Reserved			0		
5	Reserved			0		
4	BC4		RW	0		
3	BC3		RW	1	Writing to this register will configure how many bytes wil be read back, default is 8 bytes	
2	BC2	Byte count programming	RW	0		
1	BC1		RW	0		
0	BC0		RW	0		





Plots 100MHz HCSL Clock



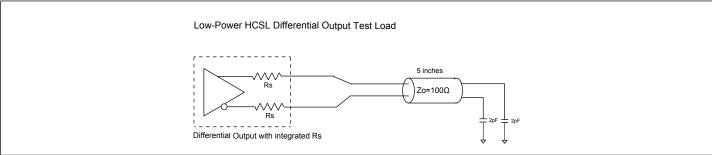


Figure 1. Low Power HCSL Test Circuit

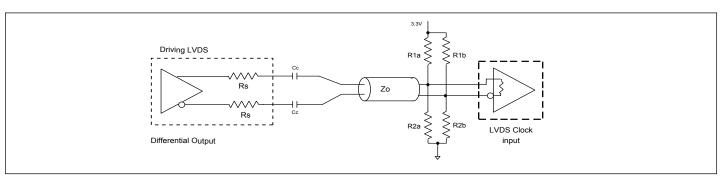


Figure 2. Differential Output driving LVDS





Alternate Differential Output Terminations

Component	Receiver with termination	Receiver without termination	Unit
R_{1a}, R_{1b}	10,000	140	Ω
R_{2a}, R_{2b}	5,600	75	Ω
C _C	0.1	0.1	μF
V _{CM}	1.2	1.2	V

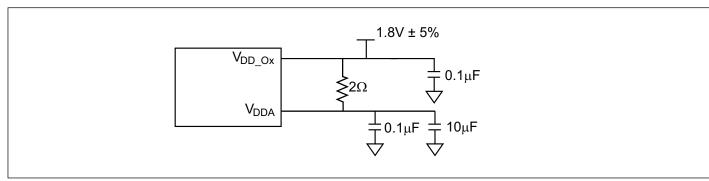


Figure 3. Power Supply Filter

Part Marking

ZH Package

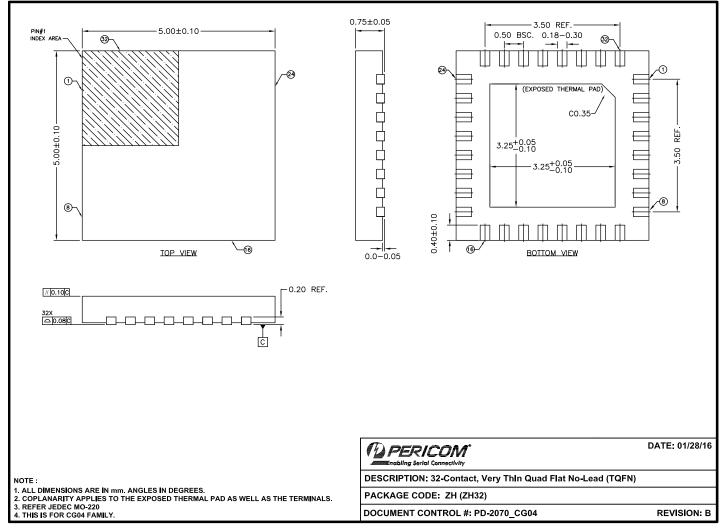


Z: Die Rev YY: Year WW: Workweek 1st X: Assembly Code 2nd X: Fab Code





Packaging Mechanical: 32-TQFN (ZH)



For latest package info.

please check: http://www.diodes.com/design/support/packaging/pericom-packaging/packaging-mechanicals-and-thermal-characteristics/

Ordering Information⁽¹⁻³⁾

Ordering Code	Package Code	Package Description	Operating Temperature
PI6CB18401ZHIEX	ZH	32-Contact, Very Thin Quad Flat No-Lead (TQFN)	Industrial

Notes:

1. EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant. All applicable RoHS exemptions applied.

2. See http://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free. Thermal characteristics can be found on the company web site at www.diodes.com/design/support/packaging/

3. E = Pb-free and Green

4. X suffix = Tape/Reel





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A. Life support devices or systems are devices or systems which:

1. are intended to implant into the body, or

2. support or sustain life and whose failure to perform when properly used in accordance with instructions for use provided in the labeling can be reasonably expected to result in significant injury to the user.

B. A critical component is any component in a life support device or system whose failure to perform can be reasonably expected to cause the

failure of the life support device or to affect its safety or effectiveness.

Customers represent that they have all necessary expertise in the safety and regulatory ramifications of their life support devices or systems, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of Diodes Incorporated products in such safety-critical, life support devices or systems, notwithstanding any devices- or systems-related information or support that may be provided by Diodes Incorporated. Further, Customers must fully indemnify Diodes Incorporated and its representatives against any damages arising out of the use of Diodes Incorporated products in such safety-critical, life support devices or systems.

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