## **Built-in Amplifier Photoelectric Sensor (Medium Size)**



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Be sure to read Safety Precautions on page 10.

## **Ordering Information**

Built-in Amplifier Photoelectric Sensors							Red light	Infrared light
Sensing method	Appearance	Connection	Sensing of	lietance		Functions	Мо	del
ochishing method	Appearance	method	Ochsing (	iistarioc		Tunctions	NPN output	PNP output
							E3S-AT11	E3S-AT31
	Horizontal	Pre-wired				Timer Turbo  Self Diagnosis External Diagnosis	E3S-AT21	E3S-AT41
Through-beam		Connector (M12)					E3S-AT16	E3S-AT36
Sensors				7 m	n		E3S-AT61	E3S-AT81
	Vertical ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	Pre-wired				Timer Turbo  Self Diagnosis External Diagnosis	E3S-AT71	E3S-AT91
		Connector (M12)					E3S-AT66	E3S-AT86
							E3S-AR11	E3S-AR31
	Horizontal	Pre-wired				Timer Turbo  Self Diagnosis External Diagnosis	E3S-AR21	E3S-AR41
Retro-reflective		Connector (M12)		2 m			E3S-AR16	E3S-AR36
Sensors				(100 mm)			E3S-AR61	E3S-AR81
	Vertical	Pre-wired		*1		Timer Turbo  Self Diagnosis External Diagnosis	E3S-AR71	E3S-AR91
	A 1	Connector (M12)					E3S-AR66	E3S-AR86

Canaina mathad	Annoovenee	Connection	Consinu distance	Functions	Mod	Model	
Sensing method	Appearance	method	Sensing distance	Functions	NPN output	PNP output	
					E3S-AD13 *2	E3S-AD33	
			100 mm (wide view)	Timer Self Diagnosis	E3S-AD23	E3S-AD43	
					E3S-AD11	E3S-AD31	
	Harimantal	Pre-wired	200 mm	Timer Turbo Self Diagnosis	E3S-AD21	E3S-AD41	
	Horizontal				E3S-AD12	E3S-AD32	
	ਰ•→		700 mm	Timer Turbo Self Diagnosis	E3S-AD22	E3S-AD42	
		Connector (M12)	100 mm (wide view)		E3S-AD18	E3S-AD38	
			200 mm	<b></b>	E3S-AD16	E3S-AD36	
Diffuse-reflective			700 mm	1	E3S-AD17	E3S-AD37	
Sensors	Vertical	Pre-wired	] 100 mm (wide view)		E3S-AD63 *2	E3S-AD83	
				Timer Self Diagnosis	E3S-AD73	E3S-AD93	
					E3S-AD61	E3S-AD81	
			200 mm	Timer Turbo Self Diagnosis	E3S-AD71	E3S-AD91	
					E3S-AD62	E3S-AD82	
			700 mm	Timer Self Diagnosis	E3S-AD72	E3S-AD92	
			100 mm (wide view)		E3S-AD68	E3S-AD88	
		Connector	200 mm		E3S-AD66	E3S-AD86	
		(M12)	700 mm	†	E3S-AD67	E3S-AD87	

<sup>\*1.</sup> Values in brackets are the minimum required distance between the Sensor and Reflector.

## **Accessories (Order Separately)**

## **Insert-type Long Slit**

Slit width	Sensing distance	Minimum sensing object (typical)	Model	Quantity	Remarks
0.5 mm × 11.1 mm	500 mm	0.2-mm dia.		1 of each for Emitter/	Slits can be used with the E3S-
1 mm × 11.1 mm	1.1 m	0.4-mm dia.	E39-S46	Receiver (4 Slits total)	AT Through-beam
2 mm × 13.6 mm	2.5 m	0.8-mm dia.	209-340	1 of each for Emitter/ Receiver (2 Slits total)	Sensor.→Page 10

## **Mutual Interference Prevention Filters**

Sensing distance	Model	Quantity	Remarks
2.4 m	E39-E6	2 of each for Emitter/Receiver (4 Filters total)	Can be used with the E3S-AT□□ Through-beam Sensor.  → Page 11

## **Reflectors/Other Accessories**

Name	Sensing distance (typical)	Model	Quantity	Remarks
Reflectors	2 m (100 mm) * (rated value)	E39-R1	1	Provided with E3S-AR□□ Retro-reflective Sensor.
Small Reflectors	1.3 m (100 mm) *	E39-R3	1	
Siliali nellectors	600 mm (70 mm) *	E39-R4	1	
	450 mm (100 mm) *	E39-RS1	1	
Tape Reflectors	700 mm (100 mm) *	E39-RS2	1	Enables MSR function.
	900 mm (100 mm) *	E39-RS3	1	
Optical Axis Confirmation Reflector		E39-R5	1	Used to check optical axis for the E3S-AT□□ Through-beam Sensor.

Note: When using any Reflector other than the provided one, use a sensing distance of approximately 0.7 times the typical value as a guide. \*Values in brackets are the minimum required distance between the Sensor and Reflector.

<sup>\*2.</sup> The following models are available with 200-mm sensing distances: E3S-AD14 and E3S-AD64.

## **Mounting Brackets/Other**

Appearance	Model	Quantity	Remarks
	E39-L69	1	Provided with E3S-A Horizontal Sensors.
	E39-L70	1	Provided with E3S-A Vertical Sensors.
(1) = 1 = 1 = 1 = 1 = 1 = 1 = 1 = 1 = 1 =	E39-L59	1	Provided with E3S-A Vertical Pre-wired Sensors.
	E39-L81	1	Provided with E3S-A Vertical Connector Sensors.
	E39-L97	1	Protective Cover for Horizontal Sensors Note: When mounting Sensors with Connectors, the Sensor I/O Connector will come into contact with the Bracket. Mount the Sensor with care.
	E39-L98	1	Protective Cover for Vertical Sensors Note: When mounting Sensors with Connectors, the Sensor I/O Connector will be longer. Mount the Sensor with care.
	E39-L60	1	Close Mounting Plate: Provided with E3S-A Connector Sensors.

Note: If a Through-beam Model is used, order two Mounting Brackets, one for the Emitter and one for the Receiver.

## **Sensors I/O Connectors**

Model	Quantity	Remarks
E39-G2	1	Provided with product.

## **Sensors I/O Connectors**

Cable	Appearance	Cable type		Model
	Straight	2 m		XS2F-D421-DC0-A
Standard		5 m	3-wire	XS2F-D421-GC0-A
Staridard	L-shaped	2 m	3-WIIE	XS2F-D422-DC0-A
	L-snaped	5 m	-	XS2F-D422-GC0-A

## **Ratings and Specifications**

	Sensing method	Through-beam Sensors	Retro-reflective Sensors (with MSR function)		Diffuse-reflective Senso	rs		
Item	Model	E3S-AT11, 16, 21, 31, 36, 41, 61, 66, 71, 81, 86, 91	E3S-AR11, 16, 21, 31, 36, 41, 61, 66, 71, 81, 86, 91	E3S-AD13, 18, 23, 33, 38, 43, 63, 68, 73, 83, 88, 93 E3S-AD11, 16, 21, 31, 36, 41, 61, 66, 71, 81, 86, 91		E3S-AD12, 17, 22, 32, 37, 42, 62, 67, 72, 82, 87, 92		
Sensing distance 7 l		7 m 2 m (100 mm) *1 (When using E39-R1)		100 mm (wide view) (white paper 100 × 100 mm)	10 to 200 mm (white paper 100 × 100 mm)	700 mm (white paper 200 × 200 mm)		
Standard sen	sing object	Opaque: Opaque: 75-mm dia. min.						
Differential tr	avel			20% max. of sensing distance	10% max. of sensing distance	20% max. of sensing distance		
Directional ar	<u> </u>	Both Emitter and Receiver: 3° to 15°	3 to 10°					
Light source	• • •	Red LED (700 nm)		Infrared LED (880 nm)	Red LED (700 nm)	Infrared LED (880 nm		
Power supply	voltage	10 to 30 VDC, including r	ipple (p-p) 10%					
Current cons	umption	Both Emitter and Receiver: 20 mA max. (plus approx. 15 mA with turbo function)	30 mA max. (plus approx. 15 mA with turbo function)	35 mA max.	30 mA max. (plus approx. 15 mA with turbo function)	35 mA max.		
Control outpu	ıt		je: 30 VDC max., Load cu PN or PNP depending on i					
	ic output (Only vith self-diagnos-	(Only Sensors with self-d Load current: 50 mA max	iagnostic function) Load p (residual voltage: 1 V ma PN or PNP depending on i	ower supply voltage: 30 V				
External diagnostic input (Only on Sensors with external diagnostic    Input		with Emitter OFF: 0 V sho (source current: 1 mA ma with Emitter ON: Open (leakage current: 0.1 mA	max.) nort-circuit or –1.5 VDC max.)					
outputs)  Response time		0.5 ms max.	,	-				
Protection circuits  Power supply reverse polarity protection, Output short-circuit protection  Power supply reverse Power supply reverse			Power supply reverse po	larity protection, Output sl	nort-circuit protection, Mut	ual interference prevention		
Response tim	ne	Operation or reset: 0.5 m	s max.	nax.				
Sensitivity ad	ljustment	Two-turn endless adjuster with an indicator						
	n (Only on Sen- timer function)	0 to 100 ms OFF-delay variable adjuster						
sors with the	n (Only on Sen- turbo function)	Yes (with turbo switch)						
Ambient illun er side)	nination (Receiv-	Incandescent lamp: 5,000 Sunlight: 10,000 lx max.						
Ambient temp	perature	Storage: -40°C to 70°C (	(with no icing or condens with no icing or condensat					
Ambient hum		Operating: 35% to 85% (v Storage: 35% to 95% (with	th no condensation)	anta and				
Insulation res			petween current-carrying p					
Dielectric stre		1,000 VAC, 50/60 Hz for	1 min. between current-ca	rrying parts and case				
Vibration resi (destruction)		10 to 55 Hz, 1.5-mm doul	ole amplitude for 2 hours e	each in X, Y, and Z direction	ons			
Shock resista (destruction)		·	mes each in X, Y, and Z d	irections				
Degree of pro		IEC IP67; NEMA: 4X (ind	• • • • • • • • • • • • • • • • • • • •					
Connection n Weight (pack		Pre-wired (standard lengt Pre-wired cable: Approx. 150 g	h: 2 m) or M12 connector Pre-wired cable: Approx. 110 g	Pre-wired cable: Approx				
		Connector: Approx. 70 g		Connector: Approx. 50 g				
	Case							
Material	Lens Mounting	Denatured polyallylate Stainless steel (SUS304)						
	Bracket							

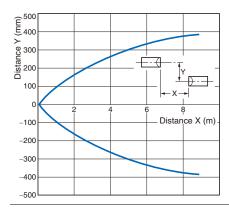
<sup>\*1.</sup> Values in brackets are the minimum required distance between the Sensor and Reflector. \*2. National Electrical Manufacturers Association

## **Engineering Data (Typical)**

## **Parallel Sensing Range**

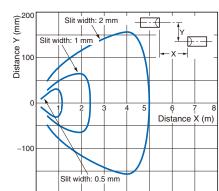
## **Through-beam Sensors**

E3S-AT□□



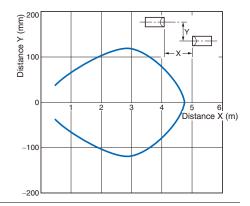
# Through-beam Sensors E3S-AT□□ + E39-S46

(Slit Sold Separately)



## **Through-beam Sensors**

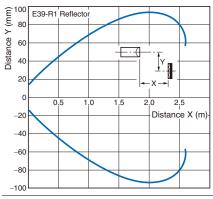
E3S-AT□□ + E39-E6 (Filter Sold Separately)



### **Parallel Sensing Range**

## **Retro-reflective Sensors**

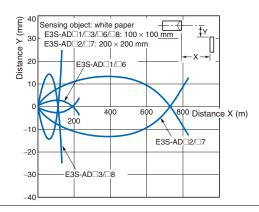
E3S-AR□□ + E39-R1 (with Reflector)



### **Sensing Range**

## **Diffuse-reflective Sensors**

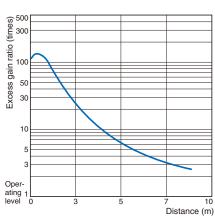
E3S-AD 1/AD 2/AD 3/AD 6/AD 7/AD 8



## **Excess Gain vs. Set Distance**

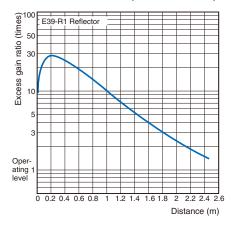
## **Through-beam Sensors**

E3S-AT□□



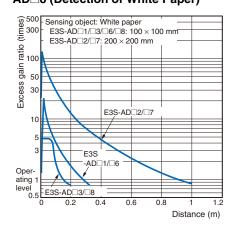
## **Retro-reflective Sensors**

E3S-AR□□ + E39-R1 (with Reflector)



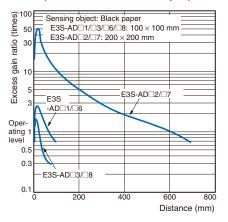
#### **Diffuse-reflective Sensor**

# E3S-AD 1/AD 2/AD 3/AD 6/AD 7/AD 8 (Detection of White Paper)



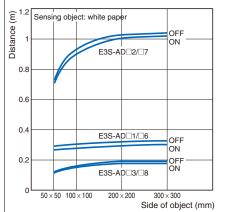
#### **Diffuse-reflective Sensor**

## E3S-AD\(\text{1/AD}\(\text{2/AD}\(\text{3/AD}\(\text{6/AD}\(\text{7/AD}\) AD\(\text{8}\) (Detection of Black Paper)



## Sensing Object Size vs. Sensing Distance

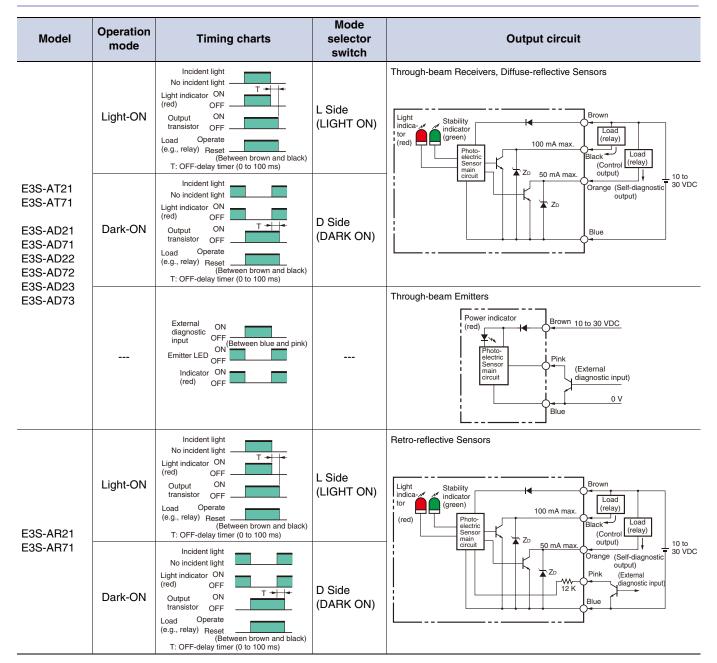
## E3S-AD $\square$ 1/AD $\square$ 2/AD $\square$ 3/AD $\square$ 6/AD $\square$ 7/AD $\square$ 8



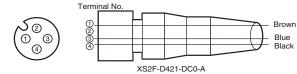
## I/O Circuit Diagrams

## **NPN Output**

Model	Operation mode	Timing charts	Mode selector switch	Output circuit
E3S-AT11 E3S-AT16 E3S-AT61 E3S-AT66 E3S-AR11 E3S-AR16	Light-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black)	L Side (LIGHT ON)	Through-beam Receivers, Retro-reflective Sensors, Diffuse-reflective Sensors  Light indi-cator (green)  (Control output)  (Relay)  100 mA max. To to make the control output of the control output out
E3S-AR16 E3S-AR66 E3S-AD11 E3S-AD16 E3S-AD61 E3S-AD66 E3S-AD12	Dark-ON	Incident light No incident light Light indicator ON (red) OFF Output ON transistor OFF Load Operate (e.g., relay) Reset (Between brown and black)	D Side (DARK ON)	Connector Pin Arrangement  O O O O O O O O O O O O O O O O O O O
E3S-AD17 E3S-AD62 E3S-AD67 E3S-AD13 E3S-AD18 E3S-AD63 E3S-AD68	Through-be	Power indication of the control of t	Brown	To to T 30 VDC  Connector Pin Arrangement  O T O T O T O T O T O T O T O T O T O



## Structure of Sensor I/O Connector

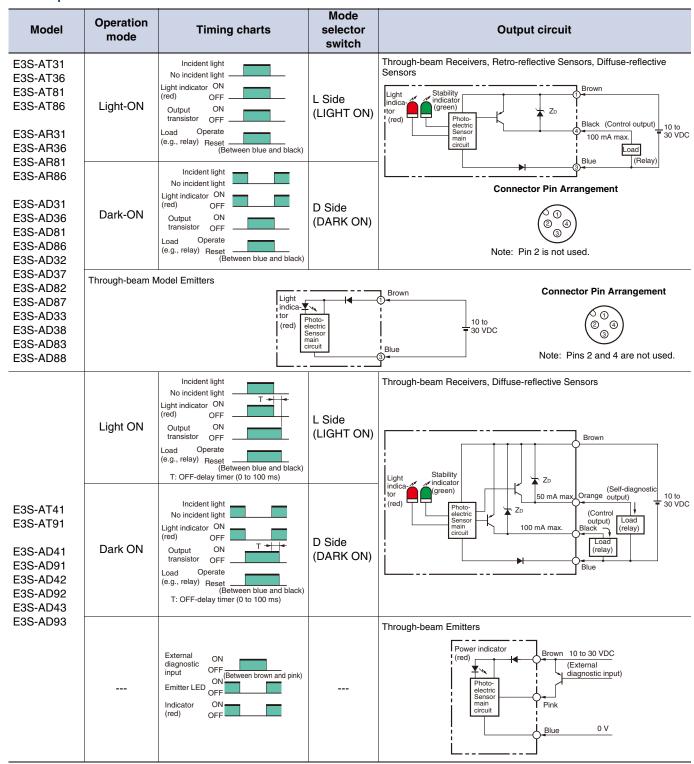


Classification	Wire color	Connection Pin No.	Application
For DC	Brown	1	+V
		2	
	Blue	3	0 V
	Black	4	Output

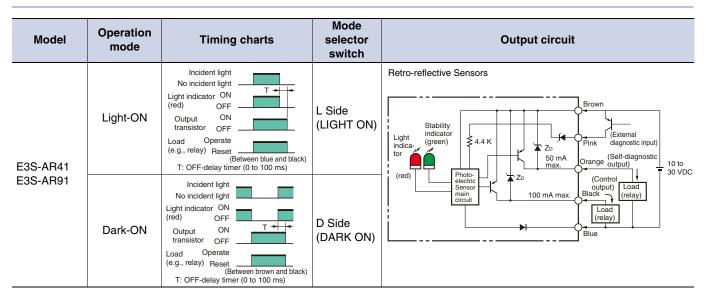
(c)Copyright OMRON Corporation 2008 All Rights Reserved.

Note: Pin No. 2 is not used.

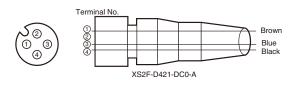
#### **PNP Output**



http://www.ia.omron.com/



## Structure of Sensor I/O Connector



Classification	Wire color	Connection Pin No.	Application
For DC	Brown	1	+V
		2	
	Blue	3	0 V
	Black	4	Output

Note: Pin 2 is not used.

## **Adjustment Methods**

## Sensitivity Adjustment for Diffuse-reflective Sensors Set to Light ON

Item	Sensing condition	Sensitivity adjuster	Indic	ators	Procedure
1) Position A	Photoelectric Sensor Sensing object  Backg- round object	Min. Max.	ON → <b>OFF</b> Stability indicator (green)	OFF → <b>ON</b> Light indicator (red)	Locate a sensing object at the sensing distance, set the sensitivity adjuster to the minimum scale position, and gradually increase sensitivity by turning the sensitivity adjuster clockwise until the incident light indicator (red LED) is ON. Position A is where the indicator has
2) Position B	Photoelectric Sensor Backg- round object Sensing object	Min. (C) (B) Max.	ON → <b>OFF</b> Stability indicator (green)	ON → <b>OFF</b> Light indicator (red)	turned ON.  Position B is when the sensing object is removed and the sensitivity adjuster is turned clockwise until the incident light indicator (red LED) is ON. Position C is where the adjuster is turned counterclockwise (reducing the sensitivity) from position B until the incident light indicator (red LED) is OFF. When there are no background objects, the maximum sensitivity is position C.
3) Setting		Min. (C)	Stability indicator (green)	ON → <b>OFF</b> Light indicator (red)	Set the sensitivity adjuster to halfway between (A) and (C) (at the optimum sensitivity). Check that the stability indicator (green LED) turns ON according to whether the sensing object is there or not. There is not sufficient margin if it does not turn ON. If this is the case, reconsider the detection method.

Unlike conventional Photoelectric Sensors, the variation in the sensitivity of E3S-A Photoelectric Sensors is minimal. This means the sensitivity can be adjusted on only a single Photoelectric Sensor, and then the adjusters on the other Photoelectric Sensors can be set to the same scale position. There is no need to adjust the sensitivity of each Photoelectric Sensor individually.

## Safety Precautions

## **WARNING**

This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes.



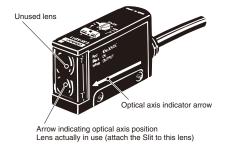
#### **Precautions for Correct Use**

Do not use the product in atmospheres or environments that exceed product ratings.

#### Mounting

## Position of Optical Axis of Through-beam Model

Unlike conventional through-beam sensors, the E3S-A Through-beam Photoelectric Sensor incorporates 2 lenses. The lens actually in use is the one marked with an arrow indicating the position of the optical axis. When using a Slit, attach it to the lens marked with the arrow.

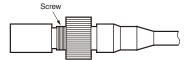


#### **Position of Arrow Indicating Optical Axis**

Model	Position of lens in use
E3S-A	Тор
(Vertical Sensors)	
E3S-A	
(Horizontal	Bottom
Sensors)	

#### **Tightening the Connector**

Manually tighten the connector until the threads have completely disappeared. If tightening is insufficient, the degree of protection may not be maintained, or the connector may become loose when it is subjected to vibration. Using pliers to tighten the connector may damage it.

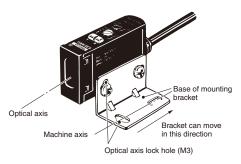


Use the E39-L60 Close Mounting Plate (provided) if the Sensor is mounted using mounting brackets or if it is mounted directly. (Refer to Dimensions.)

#### **Mounting Bracket (Provided)**

The direction of the optical axis coincides with the machine axis of the E3S-A when the mounting screw is inserted into the lock hole of the Mounting Bracket. If the mounting surface and the screw hole are correctly aligned toward the sensing object (or toward the Retroreflector for a Through-beam Sensor), the mechanical axis and optical axis will be aligned when the screw is inserted into the hole. Incident light will be detected, and time-consuming adjustment will not be necessary. (If, however, the mounting surface is not flat, adjustment of the optical axis may still be required.) Adjust the position of the Sensor so that incident light points at the center. Make sure that the incident light is at a fixed

The maximum tightening torque of the screw is 0.53 N.m max.

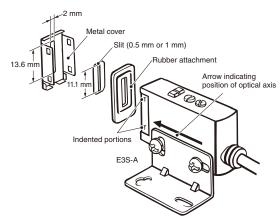


## Adjustments

### E39-S46 Through-beam Slits

(Accessory, order separately)

Use the rubber attachment with the metal cover if a slit width of 2 mm is required. (A Slit is not required in this case.) Insert the 0.5- or 1-mm Slit between the metal cover and rubber attachment if a slit width of 0.5 or 1 mm is desired. These Slits fit into the rubber attachment.

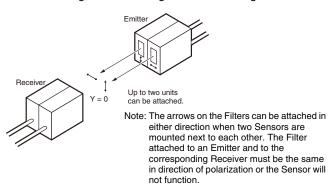


Apply the Slit to the lens of the Photoelectric Sensor marked with an arrow indicating the position of the optical axis (apply it to the bottom lens of Horizontal Sensors and the top lens of Vertical Sensors).

## E39-E6 Polarized Mutual Interference Prevention Filters for Through-beam Sensors

(Accessory, order separately)

- A set of 4 Filters are sold together for two Through-beam Sensors (for 2 each for Emitters and Receivers). Order one for every two sets of Photoelectric Sensors.
- For mounting, refer to the figure of the Through-beam Slits.

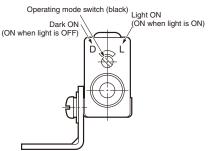


• The arrow printed on the cover indicates the direction of polarization. By attaching the Filters opposite to each other in polarization to the Emitters and the Receivers in rows, mutual interference can be prevented (in any case, the Filter attached to an Emitter and to the corresponding Receiver must be the same in direction of polarization or the Photoelectric Sensor will not function).

#### **Operating Mode Selection**

As shown in the following illustration, the E3S-A has an operating mode selector on the panel where the Receiver connector is located.

With this operating mode selector, the E3S-A is in either Dark-ON or Light-ON mode.



The default operating mode is shown in the following table.

Sensing method	Default switch setting	
Through-beam Sensors Retro-reflective Sensors	Dark-ON	
Diffuse-reflective Sensors	Light-ON	

#### Timer and Turbo Switch

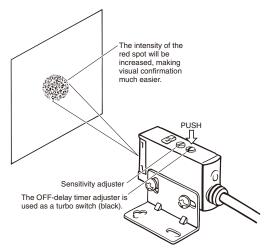
The Emitter of the Through-beam Sensor with the selfdiagnostic feature incorporates a turbo switch. When this switch is ON, the intensity of the red LED light source can be increased to make a brighter spot.

## Turbo Function ( Turbo Switch)

The turbo function is effective with the turbo switch pressed, and the function is reset automatically when released. With the turbo function switched ON, the light spot is visible even at a distance of 200 mm, making it easy to check the sensing position and the angle of the optical axis.

#### **Precautions**

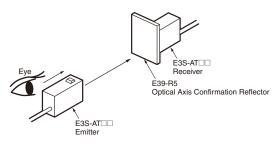
- (1)Do not keep the turbo switch pressed for longer than 3 minutes. (It will not break even if it is pressed for an extended period.)
- (2) Pressing the switch may change the timer delay settings. Set the timer after using the turbo function to check the optical axis.
- (3)To press the switch, use a force of 9.8 N max.



## Using the E39-R5 Optical Axis Reflector for Throughbeam Sensors

(Accessory, order Separately)

Use this attachment when the set distance is long and adjustment is mechanically difficult with a sensing object.



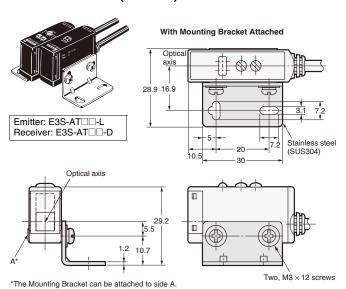
- Attach the Reflector to the Receiver.
- Look at the Reflector from right behind the Emitter. The Reflector should be bright with red light when the optical beam strikes the Reflector. If the Emitter has a turbo function, the Reflector looks brighter with the function switched ON.
- When the Reflector is removed, the light beam strikes the Receiver.

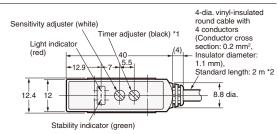
## E3S-A Built-in Amplifier Photoelectric Sensor

## **Through-beam Sensors (Horizontal)**

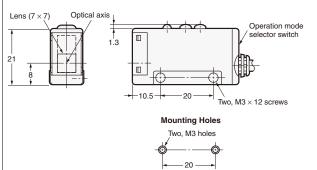
**Pre-wired Sensors** 

## E3S-AT11/21/31/41 (Receiver)

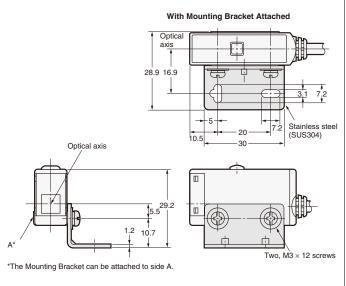




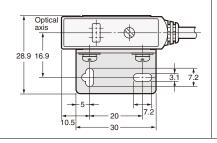
\*1. Not applicable to Sensors with timer adjusters (E3S-AT11 and E3S-AT31). \*2. The E3S-AT11 or E3S-AT31 has three conductors.

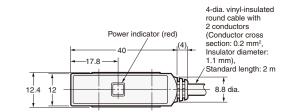


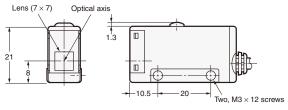
#### E3S-AT11/31 (Emitter)

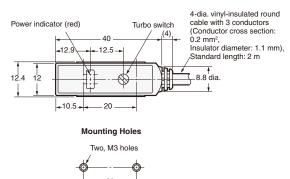


## E3S-AT21/41(Emitter)



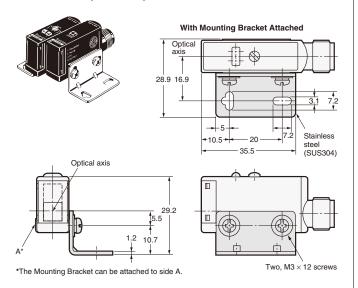


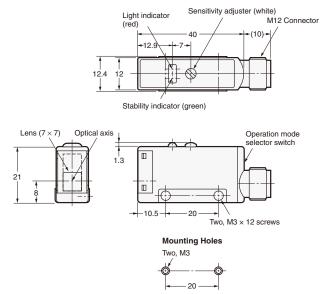




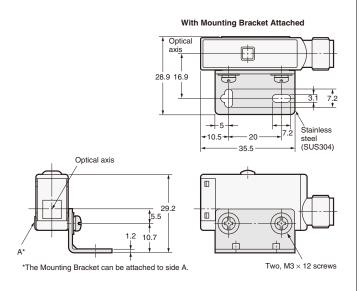
#### **Sensors with Standard Connectors**

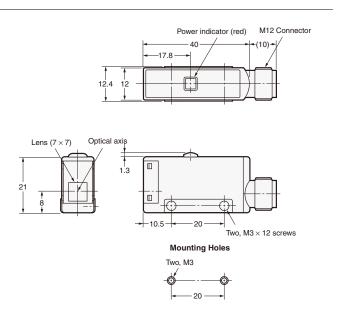
## E3S-AT16/36 (Receiver)





## E3S-AT16/36 (Emitter)

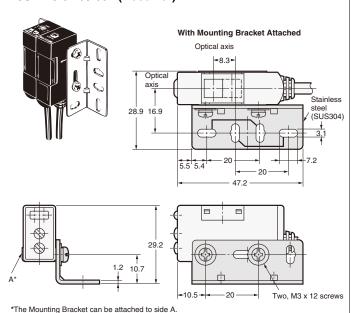




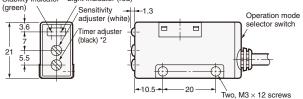
## **Through-beam Sensors (Vertical)**

### **Pre-wired Sensors**

## E3S-AT61/71/81/91 (Receiver)



## 

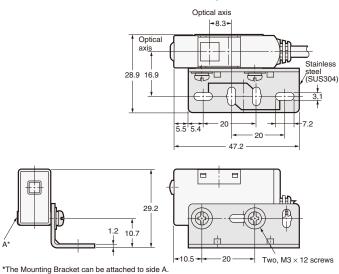


- \*1. The E3S-AT61 or E3S-AT81 has three conductors.
  \*2. Not applicable to timer adjuster models E3S-AT61 and E3S-AT81.
  - Mounting Holes

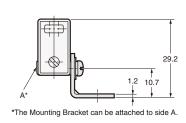


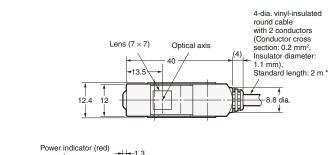
## E3S-AT61/81 (Emitter)

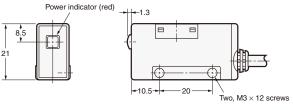
#### With Mounting Bracket Attached

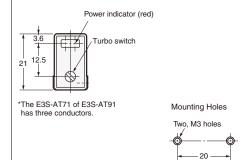






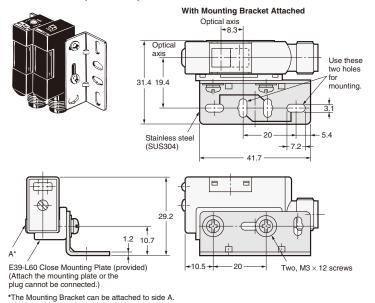


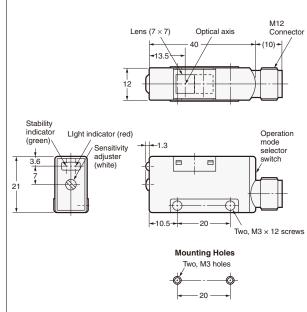




#### **Connector Sensors**

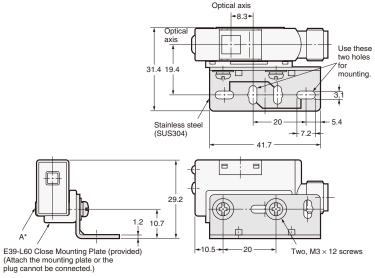
## E3S-AT66/86 (Receiver)

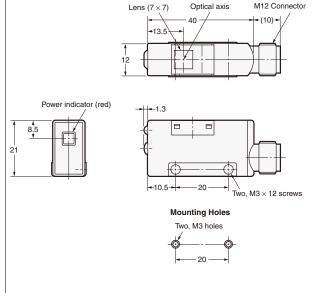




## E3S-AT66/86 (Emitter)

#### With Mounting Bracket Attached





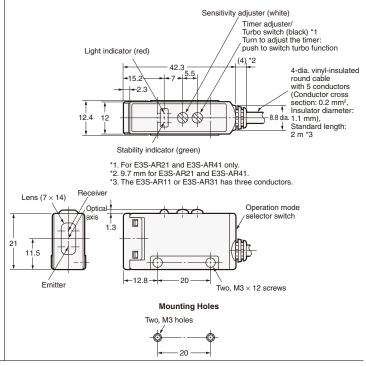
(c)Copyright OMRON Corporation 2008 All Rights Reserved.

\*The Mounting Bracket can be attached to side A.

#### **Retro-reflective Sensors (Horizontal)**

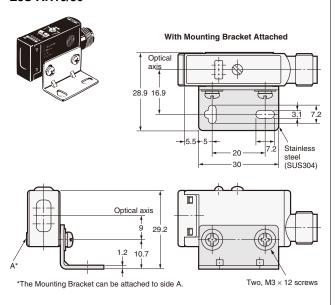
#### **Pre-wired Sensors**

## E3S-AR11/21/31/41 With Mounting Bracket Attached 28 9 16 9 10.5 steel (SUS304) 30 Optical axis 10.7 Two, M3 $\times$ 12 screws \*The Mounting Bracket can be attached to side A.

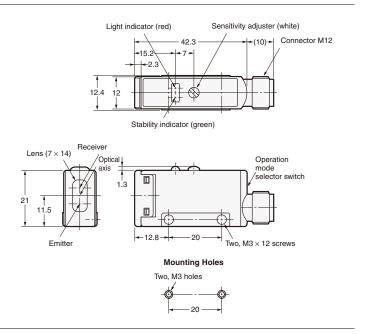


#### **Sensors with Connectors**

## E3S-AR16/36



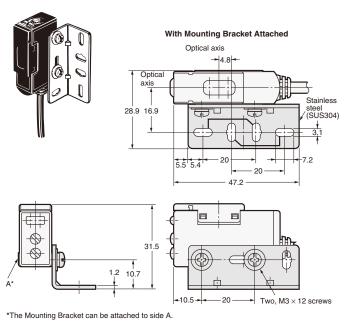
http://www.ia.omron.com/

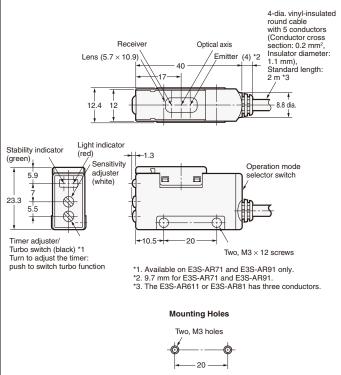


#### **Retro-reflective Sensors (Vertical)**

#### **Pre-wired Sensors**

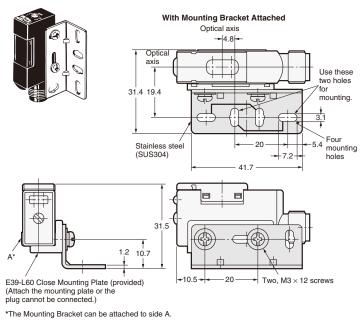
## E3S-AR61/71/81/91



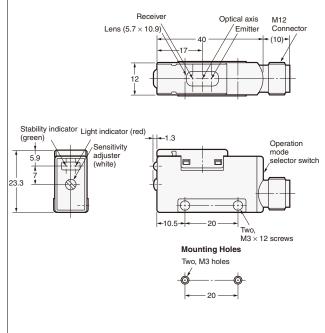


#### **Sensors with Connectors**

#### E3S-AR66/86



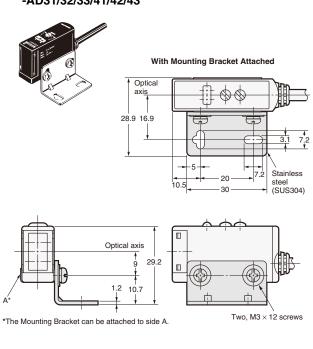
http://www.ia.omron.com/

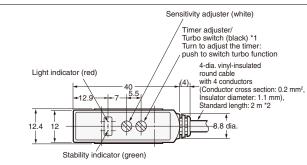


#### **Diffuse-reflective Sensors (Horizontal)**

#### **Pre-wired Sensors**

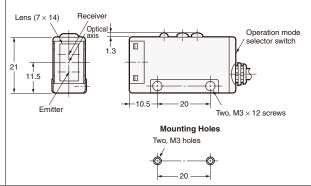
## E3S-AD11/12/13/21/22/23 -AD31/32/33/41/42/43





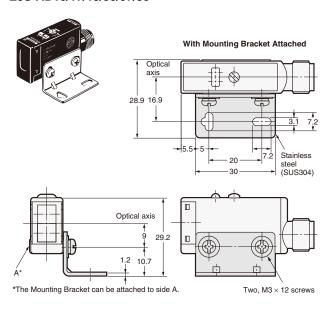
- \*1. Timer adjuster: Not available on E3S-AD11, E3S-AD12, E3S-AD13, E3S-AD31, E3S-AD32 and E3S-AD33.
- Turbo switch: Available on E3S-AD21 and E3S-AD41 only.

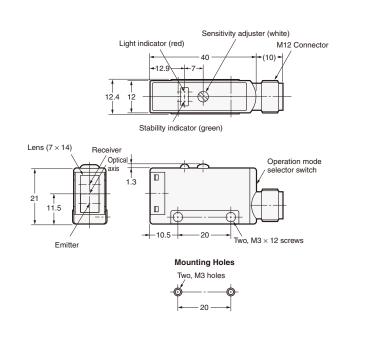
  \*2. The E3S-AD11, E3S-AD12, E3S-AD13, E3S-AD31, E3S-AD32, or E3S-AD33 has three conductors.



#### **Sensors with Connectors**

## E3S-AD16/17/18/36/37/38

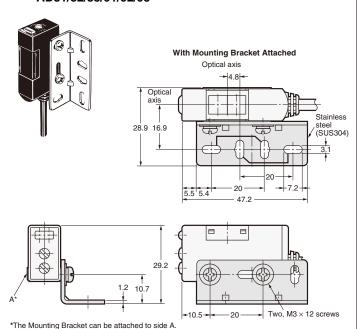


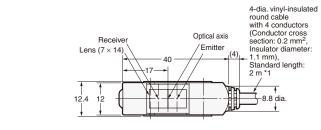


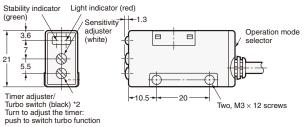
#### **Diffuse-reflective Sensors (Vertical)**

#### **Pre-wired Sensors**

## E3S-AD61/62/63/71/72/73 -AD81/82/83/91/92/93







- \*1, E3S-AD61, E3S-AD62, E3S-AD63, E3S-AD81, E3S-AD82, and E3S-AD83 have
- three conductors.

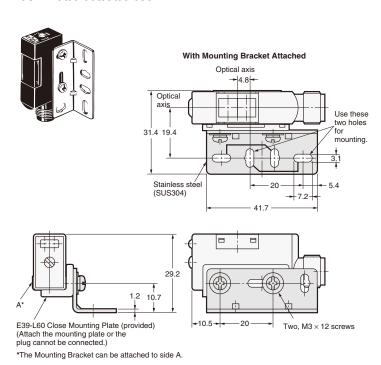
  2. Timer adjuster: Not available on E3S-AD61, E3S-AD62, E3S-AD63, E3S-AD61, E3S-AD63, E Turbo switch: Available on E3S-AD71 and E3S-AD91 only.

#### **Mounting Holes**

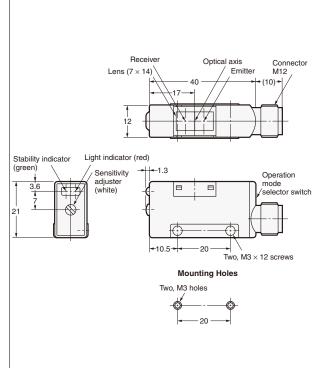


#### **Sensors with Connectors**

## E3S-AD66/67/68/86/87/88



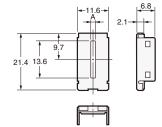
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## **Accessories (Order Separately)**

## Insert-type Long Slit (For Through-beam Model) E39-S46



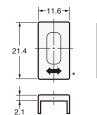


Name	Dimensions A	Material	Quantity
Supporter	2 mm	Stainless steel (SUS304)	One each for Emitter and Receiver (total of 2)
Slits	0.5 mm	PVC	One each for Emitter and
Sills	1 mm	FVC	Receiver (total of 4)

## **Filters for Mutual Interference Prevention** (For Through-beam Model)

## **È**39-E6

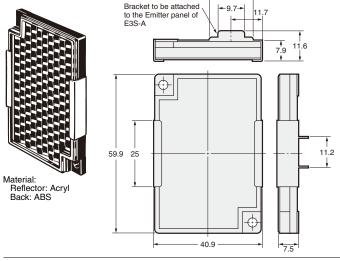




Material: Stainless steel (SUS304)

## **Optical Axis Confirmation Reflector** (For Through-beam Model)

## E39-R5



## Reflectors **Mounting Brackets**

In the interest of product improvement, specifications are subject to change without notice.

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<sup>\*</sup>Two of each for the Emitter and Receiver (total of four)

## **General Precautions**

For precautions on individual products, refer to Safety Precautions in individual product information.

## **WARNING**

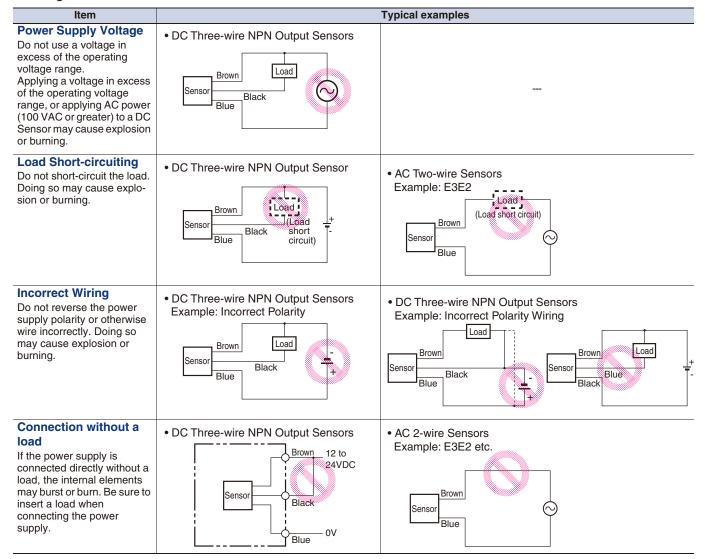
These Sensors cannot be used in safety devices for presses or other safety devices used to protect human life. These Sensors are designed for use in applications for sensing workpieces and workers that do not affect safety.



#### **Precautions for Safe Use**

To ensure safety, always observe the following precautions.

#### Wiring



#### Operating Environment

- (1) Do not use a Sensor in an environment where there are explosive or inflammable gases.
- (2) Do not use the Sensor in environments where the cables may become immersed in oil or other liquids or where liquids may penetrate the Sensor. Doing so may result in damage from burning and fire, particularly if the liquid is flammable.



## **Precautions for Correct Use**

#### Design

#### **Power Reset Time**

The Sensor will be ready to detect within approximately 100 ms after the power is turned ON.

If the Sensor and the load are connected to separate power supplies, turn ON the Sensor power before turning ON the load power. Any exceptions to this rule are indicated in *Safety Precautions* in individual product information.

### **Turning OFF Power**

An output pulse may be generated when the power is turned OFF. It is recommended that the load or load line power be turned OFF before the Sensor power is turned OFF.

## **Power Supply Types**

An unsmoothed full-wave or half-wave rectifying power supply cannot be used.

#### **Mutual Interference**

Mutual interference is a state where an output is unstable because the Sensors are affected by light from the adjacent Sensors. The following measures can be taken to avoid mutual interference.

Counter- measure	Concept	Through-beam Sensors	Reflective Sensors
1	Use a Sensor with the interference prevention function.	If Sensors are mounted in close proximity, use Sensors with the interference prevention function.  10 or fewer Sensors: E3X-DA□-S, E3X-MDA, E3C-LDA Fiber Sensors Performance, however, will depend on conditions. Refer to pages E3X-DA-S/E3X-MDA and E3C-LDA.  5 or fewer Sensors: E3X-NA Fiber Sensors 2 or fewer Sensors: E3T, E3Z, E3ZM, E3ZM-C, E3S-C, E3G-L1/L3, or E3S-C Built-in Amplifier Photoelectric Sensors (except Through-beam Sensors) E3C Photoelectric Sensor with separate amplifier	
2	Install an inference prevention filter.	A mutual interference prevention polarizing filter can be installed on only the E3Z-TA to allow close-proximity mounting of up to 2 Sensors.  Mutual Interference Prevention Polarizing Filter: E39-E11	
	Separate Sensors to distance where interference does not occur.	Check the parallel movement distance range in the catalog, verify the set distance between adjacent Sensors, and install the Sensors accordingly at a distance at least 1.5 times the parallel movement distance range.	If the workpieces move from far to near, chattering may occur in the vicinity of the operating point. For this type capplication, separate the Sensors by at least 1.5 times th operating range.  1.5 × L
3			Workpiece Sensor Sensor
4	Alternate Emitters and Receivers.	Close mounting of Sensors is possible by alternating the Emitters with the Receivers in a zigzag fashion (up to two Sensors). However, if the workpieces are close to the Photoelectric Sensors, light from the adjacent Emitter may be received and cause the Sensor to change to the incident light state.	
		Emitter Workpiece Receiver Emitter	
5	Offset the optical axes.	If there is a possibility that light from another Sensor may enter the Receiver, change the position of the Emitter and Receiver, place a light barrier between the Sensors, or take other measures to prevent the light from entering the Receiver.  (Light may enter even if the Sensors are separated by more than the sensing distance.)	If Sensors are mounted in opposite each other, slant the Sensors as shown in the following diagram. (This is because the Sensors may affect each other and cause output chattering even if separated by more than the Sensor sensing distance.)  Sensor  Bensor  Bensor
6	Adjust the sensitivity.	Lowering the sensitivity will generally help.	I

#### **Noise**

Countermeasures for noise depend on the path of noise entry, frequency components, and wave heights. Typical measures are as given in the following table.

Type of noise	Noise intrusion path and countermeasure			
Type of floise	Before countermeasure	After countermeasure		
Common mode noise (inverter noise)  Common noise applied between the mounting board and the +V and 0-V lines, respectively.	Noise enters from the noise source through the frame (metal).  Sensor  O+V Inverter motor OV IM Mounting block (metal)	<ul> <li>(1) Ground the inverter motor (to 100 Ω or less)</li> <li>(2) Ground the noise source and the power supply (0-V side) through a capacitor (film capacitor, 0.22 μF, 630 V).</li> <li>(3) Insert an insulator (plastic, rubber, etc.) between the Sensor and the mounting plate (metal).</li> </ul> Insert an insulator. OV Inverter motor ON Noise Mounting block (metal)		
Radiant noise  / Ingress of high-frequency electromagnetic waves directly into Sensor, from power line, etc.	Noise propagates through the air from the noise source and directly enters the Sensor.  Noise source	Insert a shield (copper) plate between the Sensor and the noise source e.g., a switching power supply).     Separate the noise source and the Sensor to a distance where noise does not affect operation.    Shield plate (copper)		
Power line noise  (Ingress of electromagnetic induction from high-voltage wires and switching noise from the switching power supply	Noise enters from the power line.  Sensor  Noise  Noise  O+V  Noise  O0V	Insert a capacitor (e.g., a film capacitor), noise filter (e.g., ferrite core or insulated transformer), or varistor in the power line.      Insert a capacitor, etc.      Sensor      Noise     O+V     OV		

#### Wiring

#### Cable

Unless otherwise indicated, the maximum length of cable extension is 100 m using wire that is  $0.3 \text{ mm}^2$  or greater.

Exceptions are indicated in *Safety Precautions* in individual product information.

## Cable Tensile Strength

When wiring the cable, do not subject the cable to a tension greater than that indicated in the following table.

Cable diameter	Tensile strength	
Less than 4 mm	30 N max.	
4 mm or greater	50 N max.	

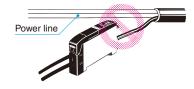
Note: Do not subject a shielded cable or coaxial cable to tension.

## **Repeated Bending**

Normally, the Sensor cable should not be bent repeatedly. (For bending-resistant cable, see *Attachment to Moving Parts* on page **C-4**.)

#### Separation from High Voltage (Wiring Method)

Do not lay the cables for the Sensor together with high-voltage lines or power lines. Placing them in the same conduit or duct may cause damage or malfunction due to induction interference. As a general rule, wire the Sensor in a separate system, use an independent metal conduit, or use shielded cable.



## **Work Required for Unconnected Leads**

Unused leads for self-diagnosis outputs or other special functions should be cut and wrapped with insulating tape to prevent contact with other terminals.

## **Power Supply**

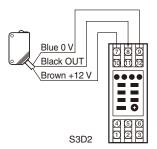
When using a commercially available switching regulator, ground the FG (frame ground) and G (ground) terminals.

If not grounded, switching noise in the power supply may cause malfunction.

#### **Example of Connection with S3D2 Sensor Controller**

#### **DC Three-wire NPN Output Sensors**

Reverse operation is possible using the signal input switch on the  ${\sf S3D2}.$ 



#### Mounting

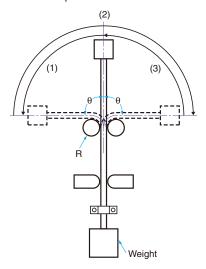
## **Attachment to Moving Parts**

To mount the Photoelectric Sensor to a moving part, such as a robot hand, consider using a Sensors that uses a bending-resistant cable (robot cable).

Although the bending repetition tolerance of a standard cable is approximately 13,000 times, robot cable has an excellent bending tolerance of approximately 500,000 times.

## Cable Bending Destruction Test (Tough Wire Breaking Test)

With current flowing, bending is repeated to check the number of bends until the current stops.



Specimen Test		Standard cable VR (H) 3 x18/0.12	Robot cable: Strong, conductive electrical wire 2 x 0.15 mm <sup>2</sup> , shielded
v	Bending angle (θ)	Left/right 90° each	Left/right 45° each
dition	Bending repetitions		60 bends/minute
Son	Weight	300g	200g
Description/conditions	Operation per bending	(1) through (3) in figure once	(1) through (3) in figure once
Descri	Bending radius of support points (R)	5 mm	2.5 mm
Result		Approx. 13,000 times	Approx. 500,000 times

The testing conditions of the standard cable and robot cable are different.

Refer to the values in the above table to check bend-resistant performance under actual working conditions.

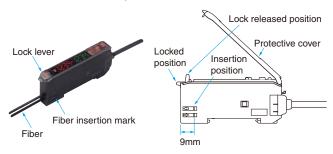


#### **Securing Fibers**

The E3X Fiber Unit uses a one-touch locking mechanism. Use the following methods to attach and remove Fiber Units.

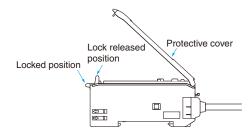
#### (1) Attaching Fibers

Open the protective cover, insert the fiber up to the insertion mark on the side of the Fiber Unit, and then lower the lock lever.



#### (2) Removing Fibers

Open the protective cover, lift up the lock lever, and pull out the fibers.



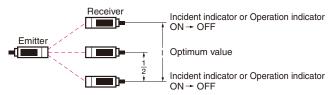
Note: 1. To maintain the fiber characteristics, make sure that the lock is released before removing the fibers.

2. Lock and unlock the fibers at an ambient temperature of  $-10\ \text{to}\ 40^{\circ}\text{C}.$ 

#### Adjustments

#### **Optical Axis Adjustment**

Move the Photoelectric Sensor both vertically and horizontally and set it in the center of the range in which the operation indicator is lit or not lit. For the E3S-C, the optical axis and the mechanical axis are the same, so the optical axis can be easily adjusted by aligning the mechanical axis.

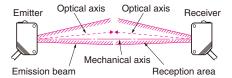


Optical axis: The axis from the center of the lens to the center of the beam for the Emitter and the axis from the

center of the lens to the center of the reception area for the Receiver.

ioi ille neceiver.

Mechanical axis: The axis perpendicular to the center of the lens.



#### Operating Environment

#### **Water Resistance**

Do not use in water, in rain, or outside.

#### **Ambient Conditions**

Do not use this Sensor in the following locations. Otherwise, it may malfunction or fail.

- (1) Locations exposed to excessive dust and dirt
- (2) Locations exposed to direct sunlight
- (3) Locations with corrosive gas vapors
- (4) Locations where organic solvents may splash onto the Sensor
- (5) Locations subject to vibration or shock
- (6) Locations where there is a possibility of direct contact with water, oil, or chemicals
- (7) Locations with high humidity and where condensation may result

#### **Environmentally Resistive Sensors**

The E32-T11F/T12F/T14F/T81F-S/D12F/D82F and E3HQ can be used in locations (3) and (6) above.

## Optical Fiber Photoelectric Sensors in Explosive Gas Atmospheres

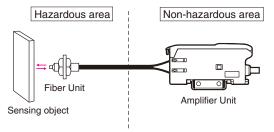
The Fiber Unit can be installed in the hazardous area, and the Amplifier Unit can be installed in a non-hazardous area.

#### <Reason>

For explosion or fire due to electrical equipment to occur, both the hazardous atmosphere and a source of ignition must be in the same location. Optical energy does not act as an ignition source, thus there is no danger of explosion or fire. The lens, case, and fiber covering are made of plastic, so this setup cannot be used if there is a possibility of contact with solvents that will corrode or degrade (e.g., cloud) the plastic.

#### <Ignition Source>

Electrical sparks or high-temperature parts that have sufficient energy to cause explosion in a hazardous atmosphere are called ignition sources.



#### **Influence from External Electrical Fields**

Do not bring a transceiver near the Photoelectric Sensor or its wiring, because this may cause incorrect operation.

#### Maintenance and Inspection

#### Points to Check When the Sensor Does Not Operate

- If the Sensor does not operate, check the following points.
- (1) Are the wiring and connections correct?
- (2) Are any of the mounting screws loose?
- (3) Are the optical axis and sensitivity adjusted correctly?
- (4) Do the sensing object and the workpiece speed satisfy the ratings and specifications?
- (5) Are any foreign objects, such as debris or dust, adhering to the Emitter lens or Receiver lens?
- (6) Is strong light, such as sunlight (e.g., reflected from a wall), shining on the Receiver?
- (7) Do not attempt to disassemble or repair the Sensor under any circumstances.
- (8) If you determine that the Sensor clearly has a failure, immediately turn OFF the power supply.

#### **Lens and Case**

The lens and case of the Photoelectric Sensor are primarily made of plastic. Dirt should be gently wiped off with a dry cloth. Do not use thinner or other organic solvents.

 The case of the E3ZM, E3ZM-C and E3S-C is metal. The lens, however, is plastic.

#### Accessories

## Using a Reflector (E39-R3/R37/RS1/RS2/RS3) During Application

- (1) When using adhesive tape on the rear face, apply it after washing away oil and dust with detergent. The Reflector cannot be mounted if there is any oil or dirt remaining.
- (2) Do not press on the E39-RS1/RS2/RS3 with metal or a fingernail. This may weaken performance.
- (3) This Sensor cannot be used in locations where oil or chemicals may splash on the Sensor.

#### M8 and M12 Connectors

- Be sure to connect or disconnect the connector after turning OFF the Sensor.
- Hold the connector cover to connect or disconnect the connector.
- Secure the connector cover by hand. Do not use pliers, otherwise the connector may be damaged.
- If the connector is not connected securely, the connector may be disconnected by vibration or the proper degree of protection of the Sensor may not be maintained.

## Others

#### **Values Given in Typical Examples**

The data and values given as typical examples are not ratings and performance and do not indicate specified performance. They are rather values from samples taken from production lots, and are provided for reference as guidelines. Typical examples include the minimum sensing object, engineering data, step (height) detection data, and selection list for specifications.

## Cleaning

- Keep organic solvents away from the Sensor. Organic solvents will dissolve the surface.
- Use a soft, dry cloth to clean the Sensor.



#### **Read and Understand This Catalog**

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