E6B2-C

CSM_F6B2-C_DS_F_3

General-purpose Encoder with Diameter of 40 mm

- A wide operating voltage range of 5 to 24 VDC (Open-collector Models).
- Resolution of 2,000 pules/rotation in 40-mm housing.
- Phase Z can be adjusted with ease using the origin indicating function.
- Shaft loading of 30 N radial and 20 N thrust.
- Improved reliability with reverse connection and load short-circuit protection (except for line-driver outputs).





Be sure to read *Safety Precautions* on page 4.

Ordering Information

Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configura- tion	Resolution (pulses/rotation)	Model	
5 to 24 VDC	NPN open-collector output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6B2-CWZ6C (resolution) 0.5M Example: E6B2-CWZ6C 10P/R 0.5M	
		720, 800, 1,000, 1,024		
		1,200, 1,500, 1,800, 2,000		
12 to 24 VDC	PNP open-collector output	100, 200, 360, 500, 600	E6B2-CWZ5B (resolution) 0.5M Example: E6B2-CWZ5B 100P/R 0.5M	
		1,000		
		2,000		
5 to 12 VDC	Voltage output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	FOR OWITOF (see a leaking) O. F.M.	
		1,000	E6B2-CWZ3E (resolution) 0.5M Example: E6B2-CWZ3E 10P/R 0.5M	
		1,200, 1,500, 1,800, 2,000		
5 VDC	Line-driver output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600		
		1,000, 1,024	E6B2-CWZ1X (resolution) 0.5M Example: E6B2-CWZ1X 10P/R 0.5M	
		1,200, 1,500, 1,800, 2,000		

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks	
	E69-C06B	Provided with the product.	
Couplings	E69-C68B	Different end diameter	
Coupings	E69-C610B	Different end diameter	
	E69-C06M	Metal construction	
Flanges	E69-FBA		
rianges	E69-FBA02	E69-2 Servo Mounting Bracket provided.	
Servo Mounting Bracket	E69-2		

Refer to *Accessories* for details.

OMRON 1

Ratings and Specifications

Item	Model	E6B2-CWZ6C	E6B2-CWZ5B	E6B2-CWZ3E	E6B2-CWZ1X		
Power s	upply	5 VDC -5% to 24 VDC	12 VDC –10% to 24 VDC	5 VDC –5% to 12 VDC	5 VDC ±5%, ripple (p-p):		
voltage		+15%, ripple (p-p): 5% max.	+15%, ripple (p-p): 5% max.	+10%, ripple (p-p): 5% max.	5% max.		
Current consumption *1		80 mA max.	100 mA max.		160 mA max.		
Resolution (pulses/rotation)		10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	100, 200, 360, 500, 600, 1,000, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,200, 1,500, 1,800, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		
Output phases		Phases A, B, and Z	Phases A, \overline{A} , B, \overline{B} , Z, and \overline{Z}				
	lifference n outputs	90°±45° between A and B (1/4 T ± 1/8 T)					
Output configuration		NPN open-collector output	PNP open-collector output	Voltage output (NPN output)	Line driver output *2		
Output capacity		Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)	Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Output resistance: 2 kΩ Sink current: 20 mA max. Residual voltage: 0.4 V max. (at sink current of 20 mA)	AM26LS31 equivalent Output current High level: lo = -20 mA Low level: ls = 20 mA Output voltage: Vo = 2.5 V min. Vs = 0.5 V max.		
Maximum response frequency *3		100 kHz	50 kHz	100 kHz			
Rise and fall times of output		1 μ s max. (Control output voltage: 5 V, Load resistance: 1 $k\Omega$, Cable length: 2 m max.)	1 μs max. (Cable length: 2 m max., Sink current: 10 mA)		0.1 μs max. (Cable length: 2 m max., lo = -20 mA, ls = 20 mA)		
Starting torque 0		0.98 mN·m max.					
Moment	of inertia	1×10 ⁻⁶ kg⋅m² max.; 3 × 10 ⁻⁷ k					
Shaft	Radial	30 N					
load- ing	Thrust	20 N					
Maximum permissible speed		6,000 r/min					
Protection circuits		Power supply reverse polarity protection, Load short-circuit protection					
Ambient temperature range		Operating: -10 to 70°C (with no icing), Storage: -25 to 85°C (with no icing)					
Ambient humidity range		Operating/Storage: 35% to 85% (with no condensation)					
Insulation		20 M Ω min. (at 500 VDC) between current-carrying parts and case					
Dielectri	ic strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case					
Vibratio resistan		Destruction: 10 to 500 Hz, 150 m/s² or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions					
Shock re	esistance	Destruction: 1,000m/s² 3 times each in X, Y, and Z directions					
Degree o		IEC 60529 IP50					
Connect	tion	Pre-wired Models (Standard cable length: 500 mm)					
Material	s	Case: ABS, Main unit: Aluminum, Shaft: SUS420J2					
Weight (packed	state)	Approx. 100 g					
Accesso	ories	Coupling, Hexagonal wrench, Instruction manual					
	An invest current of approximately 0.4 will flow for approximately 0.2 ms when the power is turned ON						

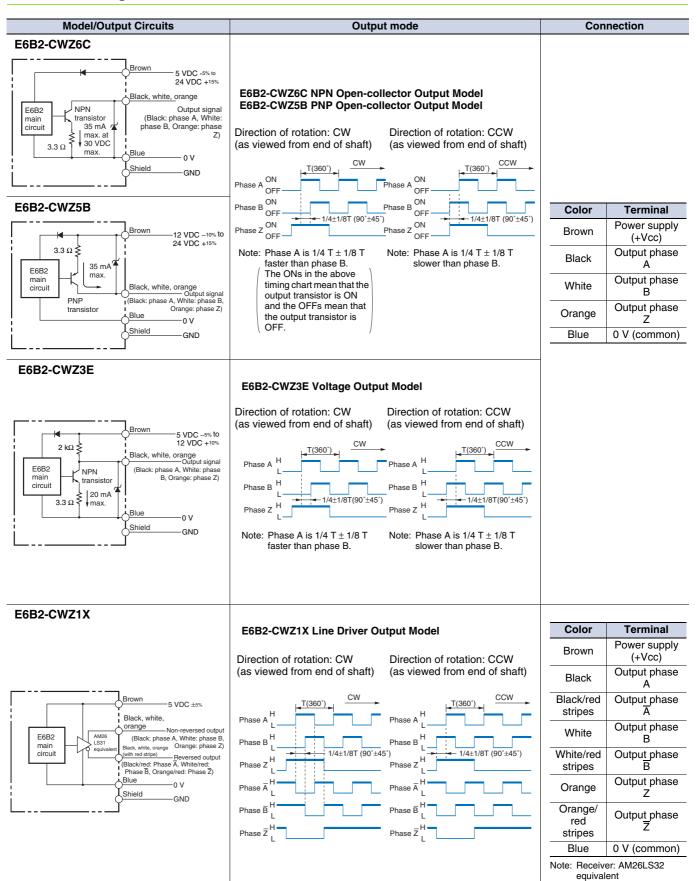
Maximum response frequency ×60 Maximum electrical response speed (rpm) = -Resolution

This means that the E6B2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

^{*1.} An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.

^{*3.} The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

2. The phase A, phase B, and phase Z circuits are all identical.

3. Normally, connect GND to 0 V or to an external ground.

Safety Precautions

Refer to Warranty and Limitations of Liability.

WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Safe Use

Incorrect wiring may damage internal circuits.

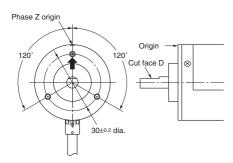
Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Mounting

Origin Indication

It is easy to adjust the position of phase Z with the origin indication function. The following illustration shows the relationship between phase Z and the origin. Set cut face D to the phase Z origin as shown in the illustration.



 Do not extend the length of the cable to more than 2 m. If the cable must be more than 2 m, use a Model with a Line-driver Output (max. length: 100 m).

Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

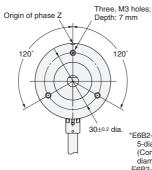
Dimensions

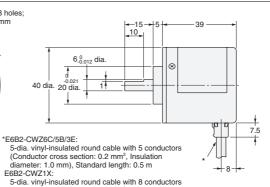
Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder









5-dia. vinyl-insulated round cable with 8 conductors (Conductor cross section: 0.2 mm², Insulation diameter: 1.0 mm), Standard length: 0.5 m

Accessories (Order Separately)

Couplings Flanges

E69-C06B E69-FBA E69-FBA02

E69-C610B E69-C06M

Refer to Accessories for details.

Servo Mounting Bracket

E69-2

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