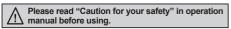
Shaft Type Ø50mm Absolute Rotary Encoder

Features

- Compact size of external diameter: Ø50mm
- Various output code: BCD, Binary, Gray code
- Various and high resolution (720, 1024-division)
- Protection structure IP64 (dust-proof, oil-proof)

Applications

• Precision machine tool, Fabric machinery, Robot, Parking system





Ordering Information

EP50S	8 -	1024	- 1	R ·	- P	- 24				
Series	Shaft diameter	Steps/revolution	Output code	Revolution direction	Control output	Power supply				
50mm shaft type	Ø8mm	Refer to resolution	1: BCD code 2: Binary code 3: Gray code	at the shaft	P: PNP open collector output N: NPN open collector output	5 : 5VDC±5% 24: 12-24VDC ±5%				

Specifications

	Item		Shaft Type Ø50mm Absolute Rotary Encoder													
de	PNP open collector output NPN open collector output	EP50S8														
₽	NPN open collector output	EP508	88													
Re	solution	6, 8, 1	0, 12, 16, 20, 24,	32, 40, 45, 48, 64				1-division								
	Output code	Division	BCD code	Binary code	Gray code	Division	BCD code	Binary code	Gray code							
		1024	TS: 0.3515°±15' (13-bit)	TS: 0.3515°±15' (10-bit)	TS: 0.703°±15' (10-bit)		TP1: 12°+60' (1-hit)	TP1: 12°±60' (1-bit)	TP1: 12°+60' (1-hit)							
		720	TS: 0.5°±25' (11-bit)	TS: 0.5°±25' (10-bit)	(10-bit)	20	TP2: 2°±60' (1-bit) TS: 18°±60' (5-bit)	TP2: 2°±60' (1-bit) TS: 18°±60' (5-bit)	TP2: 2°±60' (1-bit) TS: 36°±60' (5-bit)							
		512	TS: 0.703°±15' (11-bit)	TS: 0.703°±15' (9-bit)	TS: 1.406°±15' (9-bit)		EP: 18°±60' (1-bit)	EP: 18°±60' (1-bit)	EP: 18°±60' (1-bit)							
		360	TS: 1°±25' (10-bit)	TS: 1°±25' (9-bit)	TS: 2°±25' (9-bit)											
		256	TS: 1.406°±15' (10-bit)	TS: 1.406°±15' (8-bit)	TS: 2.8125°±15' (8-bit)		TP1: 15°±60' (1-bit)	TP1: 15°±60' (1-bit)								
		180	TS: 2°±25' (9-bit)	TS: 2°±25' (8-bit)	TS: 4°±25' (8-bit)	16	TP2: 2°±60' (1-bit) TS: 22.5°±60' (5-bit) EP: 22.5°±60' (1-bit)	TS: 22.5°±60' (4-bit)	TP2: 2°±60' (1-bit) TS: 45°±60' (4-bit) EP: 22.5°±60' (1-bit)							
		128	TS: 2.8125°±15' (9-bit)	TS: 2.8125°±15' (7-bit)	TS: 5.625°±15' (7-bit)		LI . 22.5 100 (1-bit)	L1 . 22.3 ±00 (1-bit)	60' (1-bit) EP: 22.5°±60' (1-bit)							
	Output phase /	90	TS: 4°±25' (8-bit)	TS: 4°±25' (7-bit)	TS: 8°±25' (7-bit)											
_	Output phase / Output angle ^{*1}	64	TS: 5.625°±15' (7-bit)	TS: 5.625°±15' (6-bit)	TS: 11.25°±15' (6-bit)	12 TP2: 3°±60' (1-bit) TS: 30°±60' (5-bit)			TP1: 15°±60' (1-bit) TP2: 3°±60' (1-bit)							
ation		48	TS: 7.5°±25' (7-bit)	TS: 7.5°±25' (6-bit)	TS: 15°±25' (6-bit)			TS: 30°±60' (4-bit)	TS: 60°±60' (4-bit) EP: 30°±60' (1-bit)							
cific		45	TS: 8°±25' (7-bit)	TS: 8°±25' (6-bit)	TS: 16°±25' (6-bit)											
Electrical specification		40	TP2: 2°±60' (1-bit) TS: 9°±60' (6-bit)	TP2: 2°±60' (1-bit) TS: 9°±60' (6-bit)	TP1: 5°±60' (1-bit) TP2: 2°±60' (1-bit) TS: 18°±60' (6-bit) EP: 9°±60' (1-bit)	10		TP2: 12°±60' (1-bit) TS: 36°±60' (4-bit)	TP1: 30°±60' (1-bit) TP2: 12°±60' (1-bit) TS: 72°±60' (4-bit) EP: 36°±60' (1-bit)							
Elect		32		TS: 11.25°±60' (5-bit)		8	TP1: 39°±60' (1-bit) TP2: 15°±60' (1-bit) TS: 45°±60' (3-bit) EP: 45°±60' (1-bit)	TP2: 15°±60' (1-bit) TS: 45°±60' (3-bit)	TP1: 39°±60' (1-bit) TP2: 15°±60' (1-bit) TS: 90°±60' (3-bit) EP: 45°±60' (1-bit)							
		24			TP1: 8°±60' (1-bit) TP2: 3°±60' (1-bit) TS: 30°±60' (5-bit) EP: 15°±60' (1-bit)	6	TP2: 15°±60' (1-bit)	TP2: 15°±60' (1-bit) TS: 60°±60' (3-bit)	TP1: 53°±60' (1-bit) TP2: 15°±60' (1-bit) TS: 120°±60' (3-bit) EP: 60°±60' (1-bit)							
	PNP open Control collector output	Output voltage: Min. (power supply-1.5)VDC, Load current: Max. 32mA														
	output NPN open collector output	Load current: Max. 32mA, Residual voltage: Max. 1VDC==														
	Response time (rise, fall)	Ton=800nsec, Toff=Max. 800nsec (cable: 2m, I sink = 32mA)														
	Max. response frequency	35kHz														
	Power supply	• 5VDC=±5% (ripple P-P: max. 5%) • 12-24VDC=±5% (ripple P-P: max. 5%)														
	Current consumption	Max. 100mA (disconnection of the load)														
	Insulation resistance	Over 1	00MΩ (at 500VD	C megger betwee	en all terminals an	d case)									
	Dielectric strength	750VA	C 50/60Hz for 1 r	nin (between all to	erminals and case	e)										
	Connection	Axial c	able type (cable o	gland)		•										
.V. 1	· TS=Signal Pulse TP=			· · · · · · · · · · · · · · · · · · ·												

X1: TS=Signal Pulse, TP=Timing Pulse, EP=Even Parity

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Absolute Ø50mm Shaft Type

Specifications

Item	Shaft Type Ø50mm Absolute Rotary Encoder										
ਲ 5 Starting torque	Max. 70gf·cm (0.0069N·m)										
ਵਿੱ ਤੁਂ Moment of inertia	Max. 40g·cm² (4×10-6kg·m²)										
ਨੂੰ ਨੂੰ Shaft loading	Radial: 10kgf, Thrust: 2.5kgf										
Starting torque Moment of inertia Shaft loading Max. allowable revolution*2	3,000rpm										
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours										
Shock	Approx. max. 50G										
Environ- Ambient temperature	-10 to 70°C, storage: -25 to 85°C										
ment Ambient humidity	35 to 85%RH, storage: 35 to 90%RH										
Protection structure	IP64 (IEC standard)										
Cable	Ø7mm, 15-wire, 2m, Shield cable										
Cable	(AWG28, core diameter: 0.08mm, number of cores: 40, insulator diameter: Ø0.8mm)										
Accessory	Bracket, Coupling										
Approval	CE										
Unit weight ^{**3}	Approx. 482g (approx. 398g)										

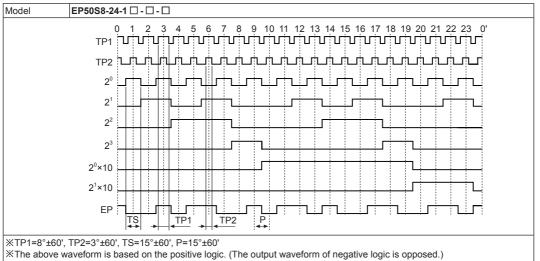
^{※2:} In case of Parallel type model, Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution (rpm)= | Max. response frequency | × 60 sec]

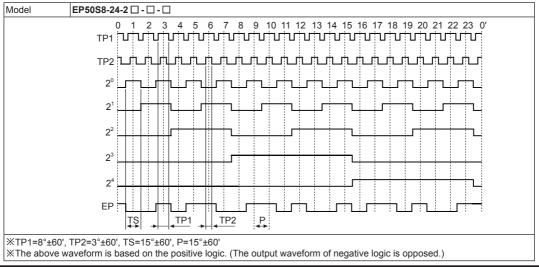
*3: The weight includes packaging. The weight in parenthesis is for unit only. *Environment resistance is rated at no freezing or condensation.

Output Waveform

• 24-division (BCD code output)



• 24-division (Binary code output)



(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

(F) Rotary Encoders

(G)
Connectors/
Connector Cables/
Sensor Distribution
Boxes/Sockets

(H) Temperature

(1)

(I) SSRs / Power Controllers

Timers

Panel Meters

Tacho / Speed / Puls Meters

> N) Display Jnits

O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers (R) Graphic/ Logic Panels

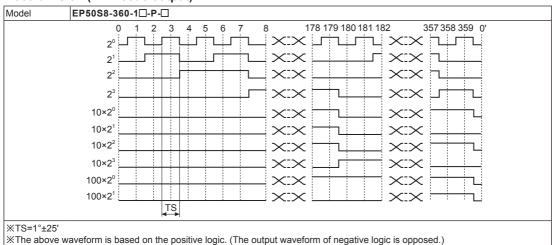
(S) Field Network Devices

(T) Software

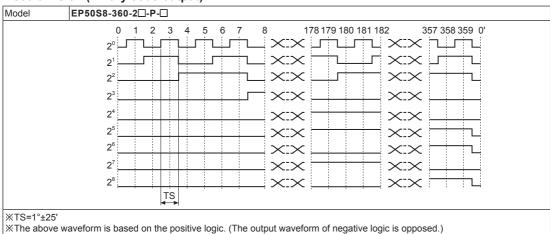
Autonics F-49

Output Waveform

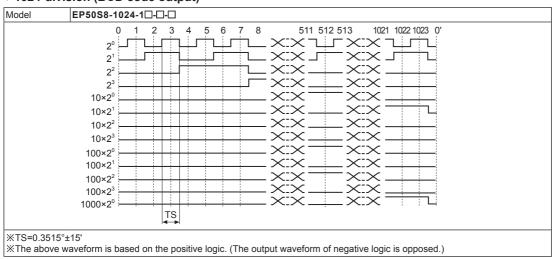
• 360-division (BCD code output)



• 360-division (Binary code output)



• 1024-division (BCD code output)

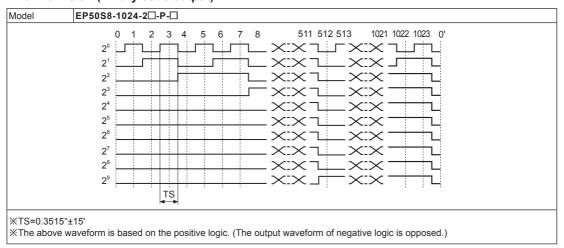


F-50 Autonics

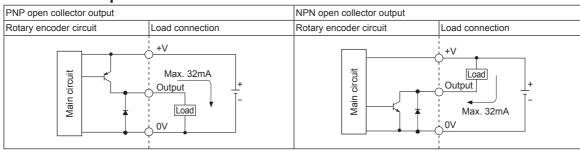
Absolute Ø50mm Shaft Type

Output Waveform

• 1024-division (Binary code output)



■ Control Output I/O Circuit



XEach bit of output has the same circuit.

**Please be aware of the fact that overload and short circuit may cause circuit break.

Connections

• BCD Code

	Resolution	6	8	10	12	16	20	24	32	40	45	48	64	90	128	180	256	360	512	720	1024	
Col	or																					
Power	White											+V									,	
Ро	Boack	0V																				
	Brown		2º																			
	Red	21																				
	Orange	2^2																				
	Yellow	N·C 2 ³																				
	Blue	N·C										2°×10										
ē	Purple	N·C									2 ¹ ×10											
>	Gray					N·C			2 ² ×10													
Outpur wire	White/Brown					TP1			_									2 ³ ×10	×10			
ō	White/Red					TP2						N·C						2°×100				
	White/Orange					EP						N·C								2 ¹ ×100		
	White/Yellow									N·C		2									100	
	White/Blue										N-C										2 ³ ×100	
	White/Purple	N·C 2												2°×1000								
	Shield wire									Sig	nal sh	nield c	able (F.G.)								

XUnused wires must be insulated.

XEncoder metal case and shield cable must be grounded (F.G.).

※N.C (Not Connected): Not using.

**Please use caution to avoid short circuit when connecting output cables because I/O circuit uses the dedicated driver IC.

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

nits

Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network

> (T) Software

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EP50S Series

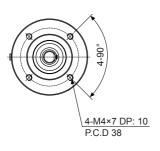
Connections

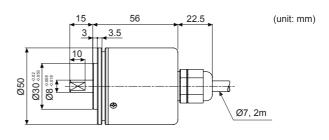
• Binary code/Gray code

	Resolution	6	8	10	12	16	20	24	32	40	45	48	64	90	128	180	256	360	512	720	1024		
Со		U		10	12	10	20	27	32	10	1-3	1-0	04	30	120	100	230	300	312	120	1024		
Power	White	+V																					
Po	Black		0V																				
	Brown	20																					
	Red		21																				
	Orange											2 ²											
	Yellow	١	√.C										2 ³										
wire	Blue	N·C										2 ⁴											
μ	Purple				N	l·C		2 ⁵															
Output	Gray						N	·C			2 ⁶												
~	White/Brown					TP1							N·C		27			27					
	White/Red	TP2									N·C							2 ⁸					
	White/Orange	EP									N·C 2 ⁹									2 ⁹			
	Shield wire	Signal si										shield cable (F.G.)											

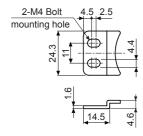
XUnused wires must be insulated.

Dimensions

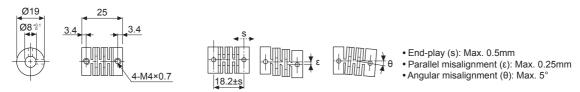




Bracket



• Coupling (EP50S)



**When mounting the coupling to encoder shaft, if there is combined misalignment (parallel, angular misalignment) between rotating encoder shaft and mate shaft, it may shorten life cycle of encoder and coupling.

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XEncoder metal case and shield cable must be grounded (F.G.).

XN.C (Not Connected): Not using.

^{**}Please use caution to avoid short circuit when connecting output cables because I/O circuit uses the dedicated driver IC.

X Do not load overweight on the shaft.

^{**}For parallel misalignment, angular misalignment, end-play terms, refer to page F-87.

[※]For flexible coupling (ERB series) information, refer to page F-80.

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