## Angle Position Sensors

## AN8 Sensors

Programmable, non-contact magnetic position sensors capable of continuous rotation


## Description

The AN8 Series sensors are non-contact, intrinsically linear angle position sensors. The sensors operate through the use of Hall Effect technology with magnetic fields generated by permanent magnets. They provide a linear change in voltage output (ratiometric to the input voltage) corresponding to an angular rotation of the input shaft.

## Features

- Angular position sensor with high tolerance for misalignment
- Non-contact angular position sensing and full $360^{\circ}$ rotation
- Custom programming available for: angle range, slope, PWM output, custom magnets - contact factory
- No mechanical interface means no parts to wear out or jam
- Available with Delphi connector or 12" ( 305 mm ) wire leads
- RoHS compliant
- IP67
- Maximum air gap of $5.5 \mathrm{~mm}\left(0.22\right.$ ") ${ }^{\star}$


## Typical Applications

- Implement (fork lift, agricultural trailer hitch, etc.) position sensing
- Steer, throttle by wire
- Gear selection
- Zero-contact encoder alternative
- Replacement for smart bearings
- Outboard trim sensing


## Environmental Specifications

| Vibration | 6 g sinusoidal, 8 g RMS axial; $40 \mathrm{~Hz}-2 \mathrm{kHz}$ all 3 axes |
| :--- | :--- |
| Operating Temperature | $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.257{ }^{\circ} \mathrm{F}\right)$ with Delphi connectors, |
|  | $-40^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.302{ }^{\circ} \mathrm{F}\right)$ with wire leads |
| Storage Temperature | $-40^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $\left.302^{\circ} \mathrm{F}\right)$ |
| Ingress Protection | IP 67 |

## Electrical Specifications

| Input Voltage | $5.0 \mathrm{VDC} \pm 10 \%$ |
| :--- | :--- |
| Output Voltage | $10 \%$ to $90 \%$ of input (see graph for voltage vs. rotation angle |
|  | characteristics) |
| Input Current | 14 mA typ., 16 mA max. |
| Output Current | -8 mA to 8 mA |
| Output Accuracy | $\pm 3.5 \%$ |
| Output Linearity | $\pm 3.5 \%$ |
| Maximum Overvoltage | 16 VDC |
| Absolute Max. Output Current | $\pm 30 \mathrm{~mA}$ |
| Output Type | Analog (PWM available) |

Mechanical Specifications

| Housing Material | Glass Reinforced Plastic |
| :--- | :--- |
| Mechanical Travel | $0^{\circ}$ to $360^{\circ}$ (continuous) |
| Mating Connector | Delphi Metri-pak 150.2 12162185; Terminal 1214075/2047680 |
| Maximum Air Gap* <br> *with AS500106 magnet carrier | $5.5 \mathrm{~mm}\left(0.22^{\prime \prime}\right)$ |
| Maximum Center-To-Center Offset | 2 mm radial (magnet to center) |

Products

| Part Number (Sensor) | Sensor (incl. AS500106 magnet) | Sensing Range | Wires | Connectors | Terminals |
| :---: | :---: | :---: | :---: | :---: | :---: |
| AN820001 | CU103601 | $180^{\circ}$ | N/A | Packard Metri-pack | 1214075 / 2047680 |
| AN820002 | CU103602 | $360^{\circ}$ | N/A | Packard Metri-pack | 1214075 / 2047680 |
| AN820003* | CU103603 | $45^{\circ}$ | N/A | Packard Metri-pack | 1214075 / 2047680 |
| AN820031 | -------- | $180^{\circ}$ | 18 AWG x 305 mm (12") | N/A | N/A |
| AN820032 | -------- | $360^{\circ}$ | 18 AWG x 305 mm (12") | N/A | N/A |
| AN820033* | -------- | $45^{\circ}$ | 18 AWG x 305 mm (12") | N/A | N/A |

## Sensor Output




These charts show the output voltage as a percentage of the input voltage for a given angle of rotation. Example: $180^{\circ}$ sensing range, magnet rotated $135^{\circ}$, output voltage will be $70 \%$ of input voltage (see dashed lines in graph above).


