

## CLC1001 Ultra-Low Noise Amplifier

### **General Description**

The CLC1001 is a high-performance, voltage feedback amplifier with ultra-low input voltage noise, 0.6nV/√Hz. The CLC1001 provides 2.1GHz gain bandwidth product and 410V/µs slew rate making it well suited for high-speed data acquisition systems requiring high levels of sensitivity and signal integrity. This high-performance amplifier also offers low input offset voltage.

The CLC1001 is designed to operate from 4V to 12V supplies. It consumes only 12.5mA of supply current per channel and offers a power saving disable pin that disables the amplifier and decreases the supply current to below  $225\mu$ A. The CLC1001 amplifier operates over the extended temperature range of -40°C to +125°C.

If a lower minimum stable gain is required, the CLC1002 offers a minimum stable gain of 5.

### FEATURES

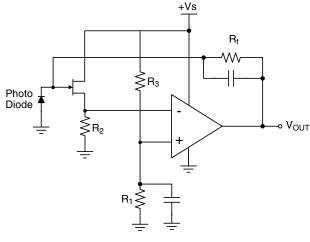
- 0.6nV/√Hz input voltage noise
- 1mV maximum input offset voltage
- 2.1GHz gain bandwidth product
- Minimum stable gain of 10
- 410V/µs slew rate
- 130mA output current
- -40°C to +125°C operating temperature range
- Fully specified at 5 and ±5V supplies
- CLC1001: ROHS compliant TSOT-6, SOIC-8 package options

#### APPLICATIONS

- Transimpedance amplifiers
- Pre-amplifier
- Low noise signal processing
- Medical instrumentation
- Probe equipment
- Test equipment
- Ultrasound channel amplifier

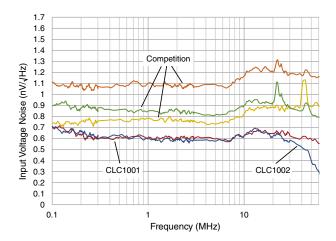
Ordering Information - back page

### **Typical Application**



Single Supply Photodiode Amplifier

### **Input Voltage Noise vs Competition**



### **Absolute Maximum Ratings**

Stresses beyond the limits listed below may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

V <sub>S</sub>	0V to +14V
V <sub>IN</sub> V <sub>S</sub> - 0	0.5V to +V <sub>S</sub> +0.5V

### **Operating Conditions**

Supply Voltage Range	4 to 12V
Operating Temperature Range	40°C to 125°C
Junction Temperature	150°C
Storage Temperature Range	65°C to 150°C
Lead Temperature (Soldering, 10s)	260°C

### **Package Thermal Resistance**

θ <sub>JA</sub> (TSOT-6)192°C/W
θ <sub>JA</sub> (SOIC-8)150°C/W
Package thermal resistance ( $\theta_{\text{JA}}), \; \text{JEDEC}$ standard, multi-layer test boards, still air.

### **ESD** Protection

CLC1001 (HBM)	2kV
ESD Rating for HBM (Human Body Model).	

### **Electrical Characteristics at +5V**

 $T_A$  = 25°C,  $V_S$  = +5V,  $R_f$  = 2000,  $R_L$  = 5000 to  $V_S/2;$  G = 10; unless otherwise noted.

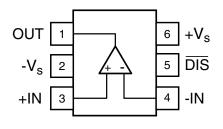
Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency I	Domain Response	· · · · · · · · · · · · · · · · · · ·		, , ,		
GBWP	-3dB Gain Bandwidth Product	$G = +40, V_{OUT} = 0.2V_{pp}$		2000		MHz
BW <sub>SS</sub>	-3dB Bandwidth	$G = +10, V_{OUT} = 0.2V_{pp}$		265		MHz
f <sub>0.1dBSS</sub>	0.1dB Gain Flatness Small Signal	$G = +10, V_{OUT} = 0.2V_{pp}$		37		MHz
BW <sub>LS</sub>	Large Signal Bandwidth	$G = +10, V_{OUT} = 2V_{pp}$		105		MHz
f <sub>0.1dBLS</sub>	0.1dB Gain Flatness Large Signal	$G = +10, V_{OUT} = 2V_{pp}$		36		MHz
Time Doma	in					
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		2.4		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 1V step		11		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		6		%
SR	Slew Rate	4V step		360		V/µs
Distortion/N	loise Response					
HD2	2nd Harmonic Distortion	$10MHz, V_{OUT} = 1V_{pp}$		80		dBc
HD3	3rd Harmonic Distortion	10MHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		83		dBc
THD	Total Harmonic Distortion	$10MHz, V_{OUT} = 1V_{pp}$		79		dB
e <sub>n</sub>	Input Voltage Noise	>100kHz		0.6		nV/√Hz
i <sub>n</sub>	Input Current Noise	>100kHz		4.2		pA/√Hz
DC Perform	ance					
V <sub>IO</sub>	Input Offset Voltage			0.1		mV
d <sub>VIO</sub>	Average Drift			2.7		µV/°C
I <sub>B</sub>	Input Bias Current			28		μA
dl <sub>B</sub>	Average Drift			45		nA/°C
I <sub>OS</sub>	Input Offset Current			0.5		μA
PSRR	Power Supply Rejection Ratio	DC		83		dB
A <sub>OL</sub>	Open Loop Gain	$V_{OUT} = V_S / 2$		82		dB
I <sub>S</sub>	Supply Current	per channel		12		mA
Disable Cha	aracteristics					
t <sub>ON</sub>	Turn On Time	1V step, 1% settling		100		ns
t <sub>OFF</sub>	Turn Off Time			900		ns
OFFISO	Off Isolation	2V <sub>pp</sub> , 5MHz		80		dB
OFFC <sub>OUT</sub>	Off Output Capacitance			5.7		pF
V <sub>OFF</sub>	Power Down Voltage	Disabled if DIS pin is grounded or pulled below VOFF	Disa	bled if $\overline{\text{DIS}}$ < 1	1.5	V
V <sub>ON</sub>	Enable Voltage	Enabled if $\overline{\text{DIS}}$ pin is floating or pulled above V <sub>ON</sub>	Ena	abled if DIS >	3	V
I <sub>SD</sub>	Disable Supply Current	No Load, DIS pin tied to ground		130		μA
Input Chara	icteristics					
R <sub>IN</sub>	Input Resistance	Non-inverting		2.6		MΩ
C <sub>IN</sub>	Input Capacitance			1.6		pF
CMIR	Common Mode Input Range			0.8 to 5.1		V
CMRR	Common Mode Rejection Ratio	DC, $V_{CM} = 1.5V$ to 4V		85		dB
Output Cha	racteristics	· · · · · · · · · · · · · · · · · · ·				
N/	Outrust Outrust	$R_L = 500\Omega$		0.93 to 4		V
V <sub>OUT</sub>	Output Swing	$R_L = 2k\Omega$		0.9 to 4.1		V
IOUT	Output Current			±130		mA
I <sub>SC</sub>	Short Circuit Current	$V_{OUT} = V_S / 2$		±150		mA

### **Electrical Characteristics at ±5V**

 $T_A$  = 25°C,  $V_S$  = ±5V,  $R_f$  = 2000,  $R_L$  = 5000 to GND; G = 10; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency [	Domain Response	· · · · · · · · · · · · · · · · · · ·				
GBWP	-3dB Gain Bandwidth Product	$G = +40, V_{OUT} = 0.2V_{pp}$		2100		MHz
BW <sub>SS</sub>	-3dB Bandwidth	$G = +10, V_{OUT} = 0.2V_{pp}$		284		MHz
f <sub>0.1dBSS</sub>	0.1dB Gain Flatness Small Signal	$G = +10, V_{OUT} = 0.2V_{pp}$		42		MHz
BW <sub>LS</sub>	Large Signal Bandwidth	$G = +10, V_{OUT} = 2V_{pp}$		117		MHz
f <sub>0.1dBLS</sub>	0.1dB Gain Flatness Large Signal	$G = +10, V_{OUT} = 2V_{pp}$		47		MHz
Time Doma	in					
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		2.2		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 1V step		11		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		3		%
SR	Slew Rate	4V step		410		V/µs
Distortion/N	oise Response					
HD2	2nd Harmonic Distortion	$10MHz, V_{OUT} = 2V_{pp}$		81		dBc
HD3	3rd Harmonic Distortion	$10MHz, V_{OUT} = 2V_{pp}$		75		dBc
THD	Total Harmonic Distortion	$10MHz, V_{OUT} = 2V_{pp}$		74		dB
e <sub>n</sub>	Input Voltage Noise	>100kHz		0.6		nV/√Hz
i <sub>n</sub>	Input Current Noise	>100kHz		4.2		pA/√Hz
DC Perform	ance					
V <sub>IO</sub>	Input Offset Voltage		-1	0.35	1	mV
d <sub>VIO</sub>	Average Drift			4.4		μV/°C
I <sub>B</sub>	Input Bias Current		-60	30	60	μA
dl <sub>B</sub>	Average Drift			44		nA/°C
I <sub>OS</sub>	Input Offset Current			0.8	6	μA
PSRR	Power Supply Rejection Ratio	DC	78	83		dB
A <sub>OL</sub>	Open Loop Gain	$V_{OUT} = V_S / 2$	74	83		dB
I <sub>S</sub>	Supply Current	per channel		12.5	16	mA
Disable Cha	aracteristics					
t <sub>ON</sub>	Turn On Time	1V step, 1% settling		125		ns
t <sub>OFF</sub>	Turn Off Time			840		ns
OFFISO	Off Isolation	2V <sub>pp</sub> , 5MHz		80		dB
OFFC <sub>OUT</sub>	Off Output Capacitance			5.6		pF
V <sub>OFF</sub>	Power Down Voltage	Disabled if DIS pin is grounded or pulled below VOFF	Disa	bled if DIS	< 1.3	V
V <sub>ON</sub>	Enable Voltage	Enabled if $\overline{\text{DIS}}$ pin is floating or pulled above $\text{V}_{\text{ON}}$	Ena	abled if DIS	> 3	V
I <sub>SD</sub>	Disable Supply Current	No Load, DIS pin tied to ground		180	225	μA
Input Chara	cteristics					
R <sub>IN</sub>	Input Resistance	Non-inverting		4		MΩ
C <sub>IN</sub>	Input Capacitance			1.5		pF
CMIR	Common Mode Input Range			-4.3 to 5.1		V
CMRR	Common Mode Rejection Ratio	DC, $V_{CM} = -3.5V$ to 4V	75	90		dB
Output Cha	racteristics					
N/	Output Curing	$R_L = 500\Omega$	-3.8	±4	3.8	V
V <sub>OUT</sub>	Output Swing	$R_L = 2k\Omega$		±4		V
I <sub>OUT</sub>	Output Current			±130		mA
I <sub>SC</sub>	Short Circuit Current	$V_{OUT} = V_S / 2$		±160		mA

# CLC1001 Pin Configurations

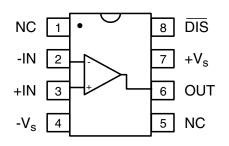


### **CLC1001 Pin Assignments**

### TSOT-6

Pin No.	Pin Name	Description
1	OUT	Output
2	-V <sub>S</sub>	Negative supply
3	+IN	Positive input
4	-IN	Negative input
5	DIS	Disable. Enabled if pin is left floating or pulled above $V_{ON}$ , disabled if pin is grounded or pulled below $V_{OFF}$ .
6	+V <sub>S</sub>	Positive supply

### SOIC-8

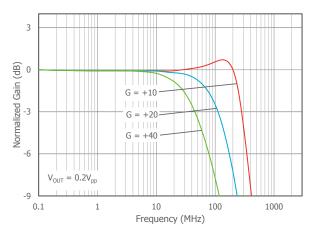


#### SOIC-8

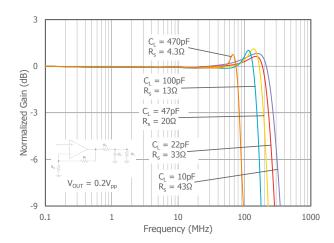
Pin No.	Pin Name	Description
1	NC	No Connect
2	-IN	Negative input
3	+IN	Positive input
4	-V <sub>S</sub>	Negative supply
5	NC	No Connect
6	OUT	Output
7	+V <sub>S</sub>	Positive supply
8	DIS	Disable. Enabled if pin is left floating or pulled above $V_{ON}$ , disabled if pin is grounded or pulled below $V_{OFF}$ .

 $T_A$  = 25°C,  $V_S$  = ±5V,  $R_f$  = 200Ω,  $R_L$  = 500Ω, G = +10; unless otherwise noted.

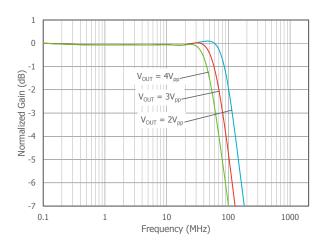
### Non-Inverting Frequency Response



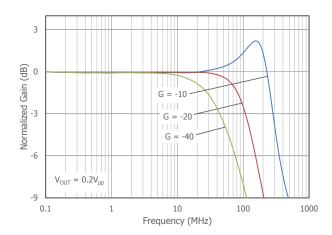
### Frequency Response vs. CL



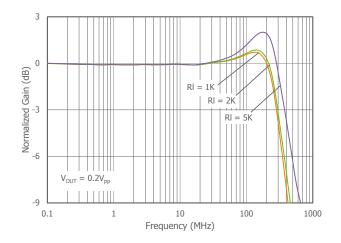
#### Frequency Response vs. VOUT

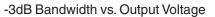


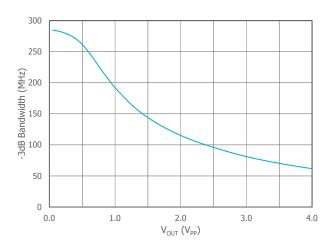
### Inverting Frequency Response



### Frequency Response vs. RL

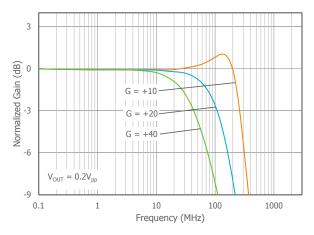




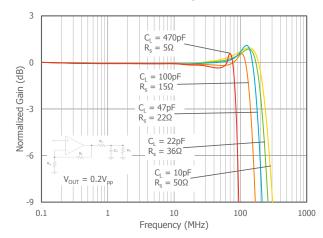


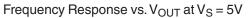
 $T_A$  = 25°C,  $V_S$  = ±5V,  $R_f$  = 200 $\Omega,~R_L$  = 500 $\Omega,~G$  = +10; unless otherwise noted.

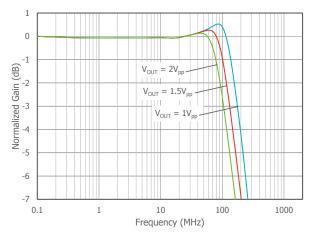
Non-Inverting Frequency Response at  $V_S = 5V$ 



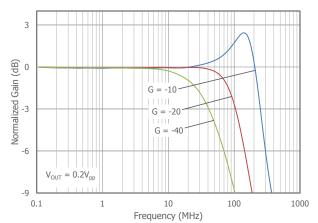
Frequency Response vs.  $C_L$  at  $V_S = 5V$ 



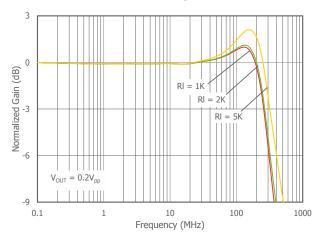




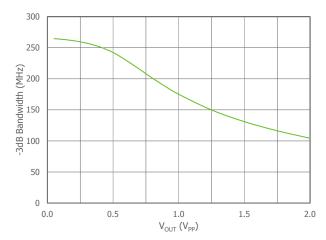
### Inverting Frequency Response at $V_S = 5V$



Frequency Response vs.  $R_L$  at  $V_S = 5V$ 

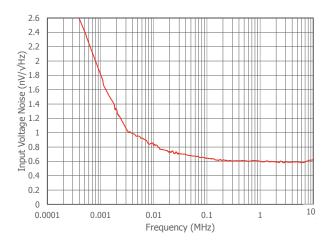




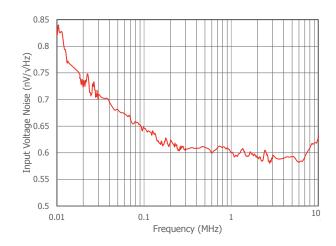


 $T_A = 25^{\circ}C$ ,  $V_S = \pm 5V$ ,  $R_f = 200\Omega$ ,  $R_L = 500\Omega$ , G = +10; unless otherwise noted.

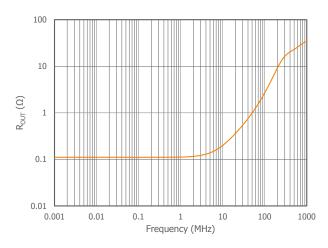
#### Input Voltage Noise



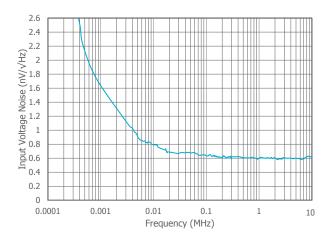
Input Voltage Noise (>10kHz)



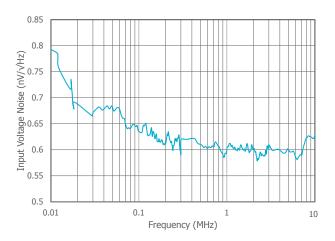
R<sub>OUT</sub> vs. Frequency



#### Input Voltage Noise at $V_S = 5V$

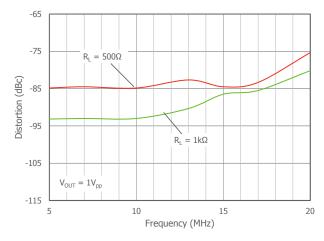


Input Voltage Noise at V<sub>S</sub> = 5V (>10kHz)

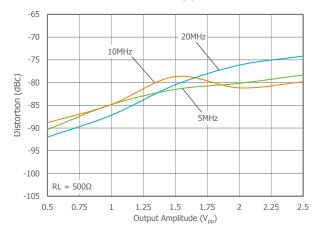


 $T_A$  = 25°C,  $V_S$  = ±5V,  $R_f$  = 200Ω,  $R_L$  = 500Ω, G = +10; unless otherwise noted.

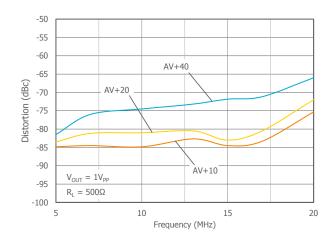
#### 2nd Harmonic Distortion vs. $\mathsf{R}_\mathsf{L}$



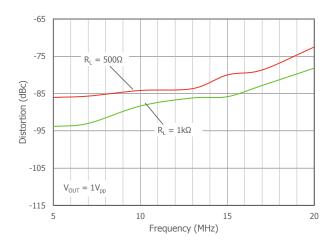
#### 2nd Harmonic Distortion vs. VOUT



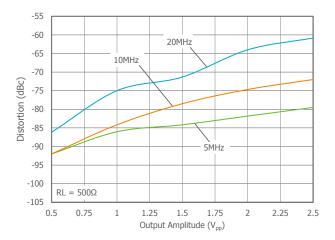
#### 2nd Harmonic Distortion vs. Gain



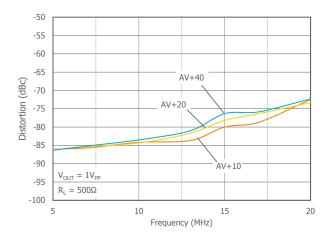
### 3rd Harmonic Distortion vs. RL



### 3rd Harmonic Distortion vs. VOUT

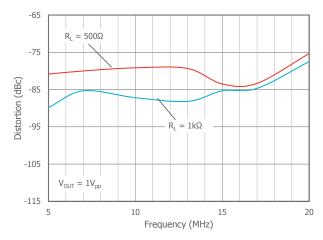


#### 3rd Harmonic Distortion vs. Gain

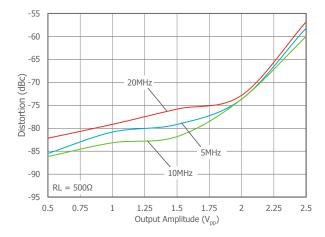


 $T_A$  = 25°C,  $V_S$  = ±5V,  $R_f$  = 200 $\Omega,~R_L$  = 500 $\Omega,~G$  = +10; unless otherwise noted.

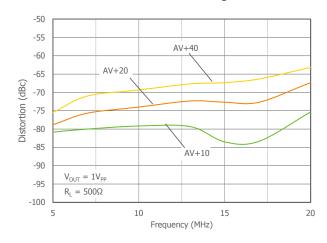
### 2nd Harmonic Distortion vs. $R_L$ at $V_S\,{=}\,5V$



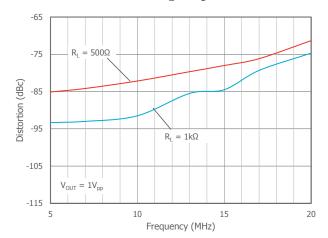
### 2nd Harmonic Distortion vs. $V_{OUT}$ at $V_S$ = 5V



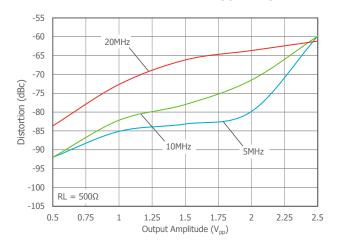
2nd Harmonic Distortion vs. Gain at  $V_S = 5V$ 



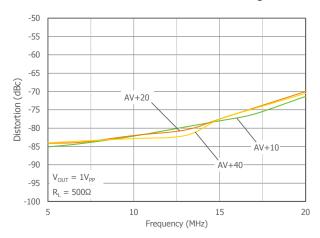
### 3rd Harmonic Distortion vs. $R_L$ at $V_S$ = 5V



3rd Harmonic Distortion vs.  $V_{OUT}$  at  $V_S = 5V$ 

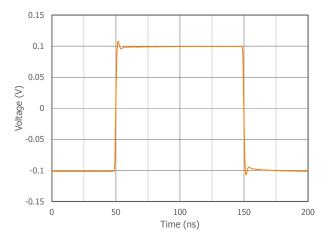


3rd Harmonic Distortion vs. Gain at  $V_S = 5V$ 

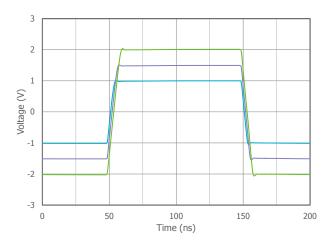


 $T_A = 25^{\circ}C$ ,  $V_S = \pm 5V$ ,  $R_f = 200\Omega$ ,  $R_L = 500\Omega$ , G = +10; unless otherwise noted.

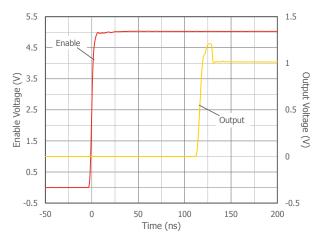
### Small Signal Pulse Response



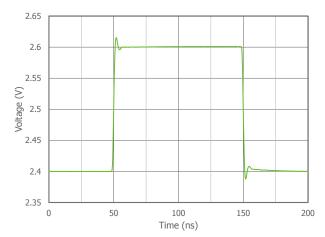
Large Signal Pulse Response



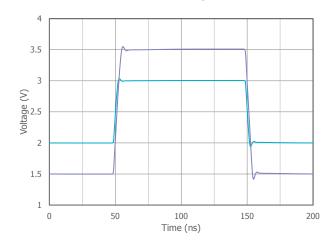




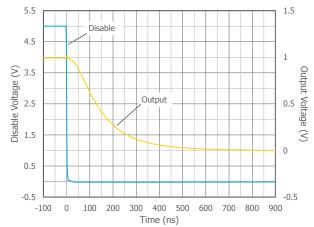
### Small Signal Pulse Response at $V_S = 5V$



Large Signal Pulse Response at  $V_S = 5V$ 

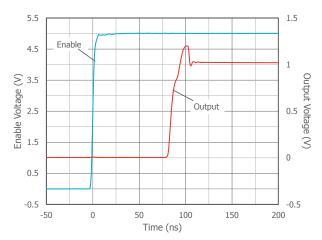




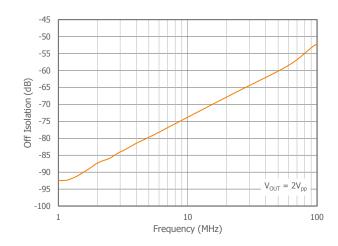


 $T_A = 25^{\circ}C$ ,  $V_S = \pm 5V$ ,  $R_f = 200\Omega$ ,  $R_L = 500\Omega$ , G = +10; unless otherwise noted.

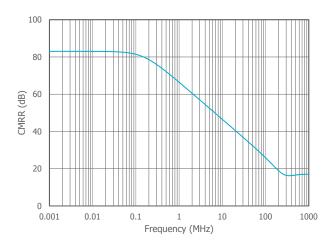
#### Enable Response at $V_S = 5V$



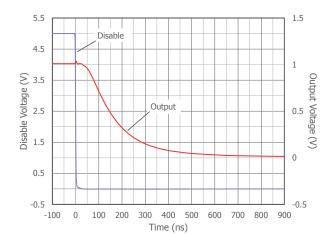
### Off Isolation



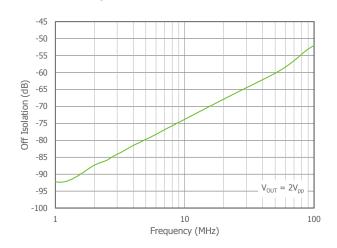
CMRR vs. Frequency



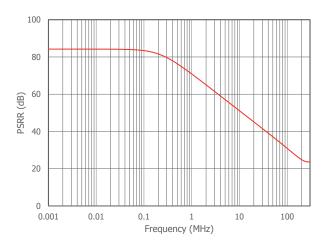
#### Disable Response at $V_S = 5V$



Off Isolation at  $V_{\rm S} = 5V$ 







### **Application Information**

#### **Basic Information**

Figures 1 and 2 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations.

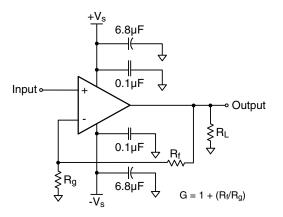


Figure 1: Typical Non-Inverting Gain Circuit

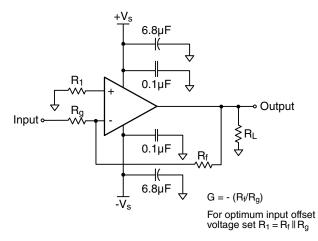


Figure 2: Typical Inverting Gain Circuit

### Achieving Low Noise in an Application

Making full use of the low noise of the CLC1001 requires careful consideration of resistor values. The feedback and gain set resistors (R<sub>f</sub> and R<sub>g</sub>) and the non-inverting source impedance (R<sub>source</sub>) all contribute noise to the circuit and can easily dominate the overall noise if their values are too high. The datasheet is specified with an R<sub>g</sub> of 22.1 $\Omega$ , at which point the noise from R<sub>f</sub> and R<sub>g</sub> is about equal to the noise from the CLC1001. Lower value resistors could be used at the expense of more distortion. Figure 3 shows total input voltage noise (amp+resistors) versus R<sub>f</sub> and R<sub>g</sub>. As the value of R<sub>f</sub> increases, the total input referred noise also increases.

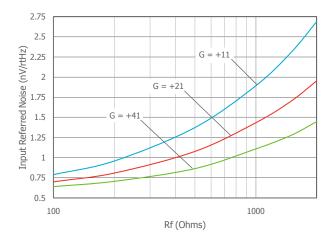


Figure 3: Input Referred Voltage Noise vs. Rf and Rg

The noise caused by a resistor is modeled with either a voltage source in series with the resistance:

√4kTR

Or a current source in parallel with it:

$$i_R = \sqrt{\frac{4kT}{R}}$$

Op amp noise is modeled with three noise sources,  $e_n$ ,  $i_n$ ,  $i_n$  and  $i_i$ . These three sources are analogous to the DC input voltage and current errors  $V_{os}$ ,  $I_{bn}$  and  $I_{bi}$ .

The noise models must be analyzed in-circuit to determine the effect on the op amp output noise.

Since noise is statistical in nature rather than a continuous signal, the set of noise sources in circuit add in an RMS (root mean square) fashion rather than in a linear fashion. For uncorrelated noise sources, this means you add the squares of the noise voltages. A typical non-inverting application (see figure 1) results in the following noise at the output of the op amp:

$$e_{o}^{2} = e_{n}^{2} \left(1 + \frac{R_{f}}{R_{g}}\right)^{2} + in^{2}R_{s}^{2}\left(1 + \frac{R_{f}}{R_{g}}\right)^{2} + i_{i}^{2}R_{f}^{2}$$

op amp noise terms  $e_n$ ,  $i_n$  and  $i_i$ 

+ 
$$e_{Rs}^2 \left(1 + \frac{R_f}{R_g}\right)^2$$
 +  $e_{Rg}^2 \left(\frac{R_f}{R_g}\right)^2$  +  $e_{Rf}^2$ 

external resistor noise terms for R<sub>S</sub>, R<sub>g</sub> and R<sub>f</sub>

High source impedances are sometimes unavoidable, but they increase noise from the source impedance and also make the circuit more sensitive to the op amp current noise. Analyze all noise sources in the circuit, not just the op amp itself, to achieve low noise in your application.

#### **Power Dissipation**

Power dissipation should not be a factor when operating under the stated  $500\Omega$  load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond it's intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value Theta<sub>JA</sub> ( $\theta_{JA}$ ) is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\theta_{JA} \times P_D)$$

Where  $\mathsf{T}_{\mathsf{Ambient}}$  is the temperature of the working environment.

In order to determine  $P_D$ , the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{supply} - P_{load}$$

Supply power is calculated by the standard power equation.

$$P_{supply} = V_{supply} \times I_{RMSsupply}$$
$$V_{supply} = V_{S+} - V_{S-}$$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{load})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rload\_{eff}) will need to include the effect of the feedback network. For instance,

Rload<sub>eff</sub> in Figure 3 would be calculated as:

$$R_L \parallel (R_f + R_g)$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here,  $P_D$  can be found from

 $P_D = P_{Quiescent} + P_{Dynamic} - P_{load}$ 

Quiescent power can be derived from the specified  $I_{\rm S}$  values along with known supply voltage,  $V_{supply}$ . Load power can be calculated as above with the desired signal amplitudes using:

#### $(V_{load})_{RMS} = V_{peak} / \sqrt{2}$

$$(I_{load})_{RMS} = (V_{load})_{RMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

 $P_{Dynamic} = (V_{S+} - V_{load})_{RMS} \times (I_{load})_{RMS}$ 

Assuming the load is referenced in the middle of the power rails or  $V_{supply}/2$ .

Figure 4 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

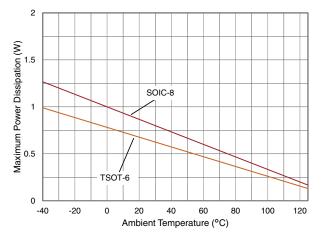


Figure 4. Maximum Power Derating

#### **Driving Capacitive Loads**

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance,  $R_S$ , between the amplifier and the load to help improve stability and settling performance. Refer to Figure 5.

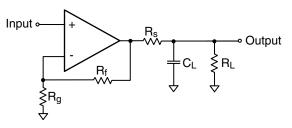


Figure 5. Addition of R<sub>S</sub> for Driving Capacitive Loads

Table 1 provides the recommended  $R_S$  for various capacitive loads. The recommended  $R_S$  values result in approximately <1dB peaking in the frequency response. The Frequency Response vs.  $C_L$  plots, on page 6 and 7, illustrate the response of the CLC1001.

C <sub>L</sub> (pF)	R <sub>S</sub> (Ω)	-3dB BW (MHz)
10	43	266
22	33	228
47	20	192
100	13	155
470	4.3	84

Table 1: Recommended R<sub>S</sub> vs. C<sub>L</sub>

For a given load capacitance, adjust  ${\sf R}_S$  to optimize the tradeoff between settling time and bandwidth. In general, reducing  ${\sf R}_S$  will increase bandwidth at the expense of additional overshoot and ringing.

#### **Overdrive Recovery**

For an amplifier, an overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies based on whether the input or output is overdriven and by how much the ranges are exceeded. The CLC1001 will typically recover in less than 25ns from an overdrive condition. Figure 6 shows the CLC1001 in an overdriven condition.

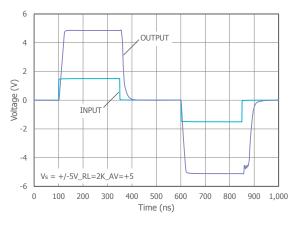


Figure 6: Overdrive Recovery

#### **Layout Considerations**

General layout and supply bypassing play major roles in high frequency performance. Exar has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

 Include 6.8µF and 0.1µF ceramic capacitors for power supply decoupling

- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

#### **Evaluation Board Information**

The following evaluation boards are available to aid in the testing and layout of these devices:

Evaluation Board #	Products
CEB002	CLC1001 in TSOT
CEB003	CLC1001 in SOIC

#### **Evaluation Board Schematics**

Evaluation board schematics and layouts are shown in Figures 7-11 These evaluation boards are built for dualsupply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -V<sub>S</sub> to ground.
- 2. Use C3 and C4, if the  ${\rm -V}_{\rm S}$  pin of the amplifier is not directly connected to the ground plane.

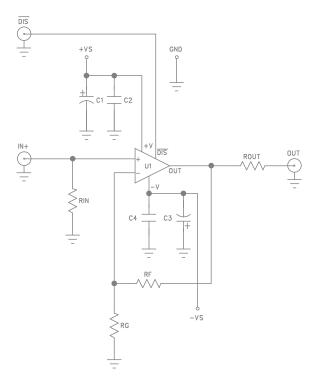


Figure 7. CEB002 & CEB003 Schematic

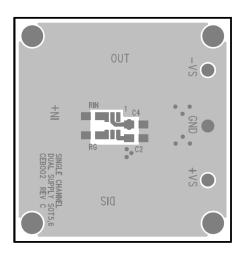


Figure 8. CEB002 Top View

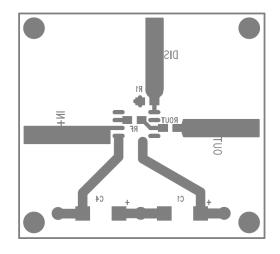


Figure 11. CEB003 Bottom View

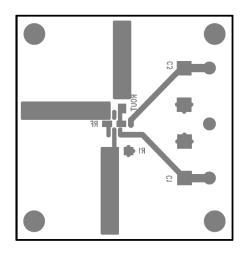


Figure 9. CEB002 Bottom View

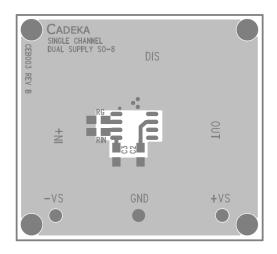
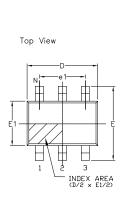
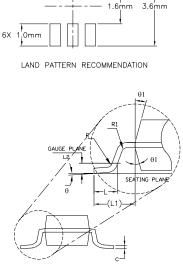


Figure 10. CEB003 Top View

### **Mechanical Dimensions**

### TSOT-6 Package





- 6X 0.65mm

-----

6 PIN TSOT (OPTION 2)								
SYMBOLS		DIMENSION IN MM (Control Unit)			DIMENSION IN INCH (Reference Unit)			
	MIN	NOM	MAX	MIN	NOM	MAX		
A	0.75	-	0.80	0.030	—	0.031		
A1	0.00	_	0.05	0.000	_	0.002		
A2	0.70	0.75	0.78	0.028	0.036	0.031		
b	0.35	—	0.50	0.012	—	0.020		
с	0.10	-	0.20	0.003	_	0.008		
D	2	2.90 BS	SC	C	.114 B	SC		
E	2	2.80 BS	SC	C	.110 B	SC		
E1	1	.60 BS	SC	C	.063 B	SC		
е	0	).95 BS	SC	C	.038 B	SC		
e1	1.90 BSC			C	.075 B	SC		
L	0.37	0.45	0.60	0.012	0.018	0.024		
L1	0.60 REF			0	.024 RE	F		
L2	0.25 BSC			0	.010 BS	C		
R	0.10	-	—	0.004	-	-		
R1	0.10	_	0.25	0.004	_	0.010		
θ	0.	4.	8*	0.	4.	8'		
θ1	4*	10'	12'	4'	10°	12*		
N	6 6							

Side View

**SOIC-8 Package** 

Front View

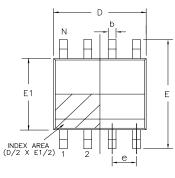
A'2 A1

4X 0.95mm-

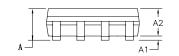
RECOMMENDED PCB LAND PATTERN 0.53mm

Ν

1.98mm

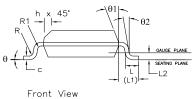


Top View



Side View

8	Pin	SOICN	JED	EC MS-	-012	Variatio	n AA
SYMBOLS		DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
		MIN	NOM	MAX	MIN	NOM	MAX
	A	1.35	-	1.75	0.053	-	0.069
A	4	0.10	-	0.25	0.004	-	0.010
A	2	1.25	-	1.65	0.049	-	0.065
	b	0.31	-	0.51	0.012	-	0.020
	с	0.17	-	0.25	0.007	-	0.010
	E		5.00 BS		0	.236 BS	с
E	1	3.90 BSC			0	).154 BS	с
	e	1.27 BSC			0	.050 BS	с
	h	0.25	-	0.50	0.010	-	0.020
	L	0.40	-	1.27	0.016	-	0.050
	1	1.04 REF				.041 REF	
ι	2		0.25 BSC			.010 BS	2
	R	0.07	-	-	0.003	-	-
F	21	0.07	-	-	0.003	-	-
	θ	0.	-	8.	0.	-	8.
(	€1	5'	-	15'	5'	-	15
(	32	0.	-	-	0.	-	-
	D	L -	4.90 BSC 0.193 BSC				c
	N		8			8	



1.27mm

4.93mm



### **Ordering Information**

Part Number	Package	Green	Operating Temperature Range	Packaging Quantity	
CLC1001 Ordering Information					
CLC1001IST6X	TSOT-6	Yes	-40°C to +125°C	2.5k Tape & Reel	
CLC1001IST6MTR	TSOT-6	Yes	-40°C to +125°C	250 Tape & Reel	
CLC1001IST6EVB	Evaluation Board	N/A	N/A	N/A	
CLC1001ISO8X	SOIC-8	Yes	-40°C to +125°C	2.5k Tape & Reel	
CLC1001ISO8MTR	SOIC-8	Yes	-40°C to +125°C	250 Tape & Reel	
CLC1001ISO8EVB	Evaluation Board	N/A	N/A	N/A	

Moisture sensitivity level for all parts is MSL-1.

### **Revision History**

Revision	Date	Description
1H (ECN 1441-02)	September 2014	Reformat into Exar data sheet template. Updated ordering information table to include MTR and EVB part numbers. Increased "I" temperature range from +85 to +125°C. Removed "A" temp grade parts, since "I" is now equivalent. Updated thermal resistance numbers and package outline drawings.

#### For Further Assistance:

Email: CustomerSupport@exar.com or HPATechSupport@exar.com Exar Technical Documentation: http://www.exar.com/techdoc/

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