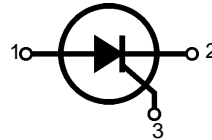


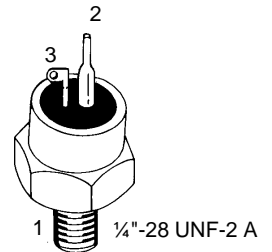
Phase Control Thyristors

$V_{RRM} = 800-1400 \text{ V}$
 $I_{T(RMS)} = 120 \text{ A}$
 $I_{T(AV)M} = 69 \text{ A}$

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
900	800	CS 35-08io4
1300	1200	CS 35-12io4
1500	1400	CS 35-14io4



TO-208AC
(TO-65)



1 = Anode, 2 = Cathode, 3 = Gate

Symbol	Test Conditions	Maximum Ratings	
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	120	A
	$T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine	63	A
$I_{T(AV)M}$	$T_{case} = 80^{\circ}\text{C}; 180^{\circ}$ sine	69	A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	t = 10 ms (50 Hz), sine	1200 A
		t = 8.3 ms (60 Hz), sine	1340 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	t = 10 ms (50 Hz), sine	7200 A ² s
		t = 8.3 ms (60 Hz), sine	7550 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}; f = 50\text{Hz}; t_p = 200\mu\text{s}; V_D = 2/3 V_{DRM}; I_G = 0.5 \text{ A}$	repetitive, $I_T = 150 \text{ A}$	150 A/ μs
	$di_G/dt = 0.5 \text{ A}/\mu\text{s}$	non repetitive, $I_T = I_{T(AV)M}$	400 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}; R_{GK} = \infty; \text{method 1 (linear voltage rise)}$	$V_{DR} = 2/3 V_{DRM}$	1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}; t_p = 30 \mu\text{s}$	10	W
$P_{G(AV)}$	$I_T = I_{T(AV)M}; t_p = 500 \mu\text{s}$	5	W
V_{RGM}		0.5	W
T_{VJ}		10	V
T_{VJM}		-40...+125	$^{\circ}\text{C}$
T_{stg}		125	$^{\circ}\text{C}$
T_{stg}		-40...+125	$^{\circ}\text{C}$
M_d	Mounting torque	2.5	Nm
		22	lb.in.
Weight		20	g

Features

- Thyristor for line frequencies
- International standard package JEDEC TO-208AC
- Planar glassivated chip
- Long-term stability of blocking currents and voltages

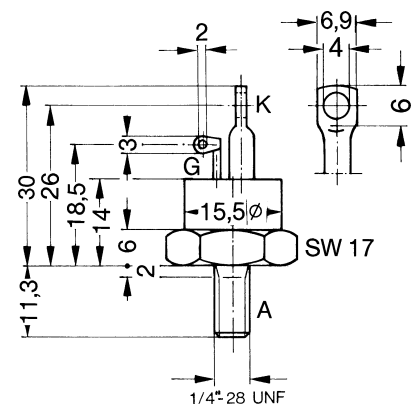
Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values	
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	\leq	10 mA
V_T	$I_T = 150 \text{ A}; T_{VJ} = 25^\circ\text{C}$	\leq	1.5 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)		0.85 V
r_T			3.5 m Ω
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	\leq	1.5 V
	$T_{VJ} = -40^\circ\text{C}$	\leq	1.9 V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	\leq	100 mA
	$T_{VJ} = -40^\circ\text{C}$	\leq	200 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	\leq	0.2 V
I_{GD}		\leq	1 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 30 \mu\text{s}$ $I_G = 0.1 \text{ A}; di_G/dt = 0.1 \text{ A}/\mu\text{s}$	\leq	100 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	\leq	80 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.1 \text{ A}; di_G/dt = 0.1 \text{ A}/\mu\text{s}$	\leq	2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 50 \text{ A}, t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}; dv/dt = 10 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	typ.	100 μs
R_{thJC}	DC current		0.4 K/W
R_{thJH}	DC current		0.6 K/W
d_s	Creepage distance on surface		1.7 mm
d_A	Strike distance through air		1.7 mm
a	Max. acceleration, 50 Hz		50 m/s ²

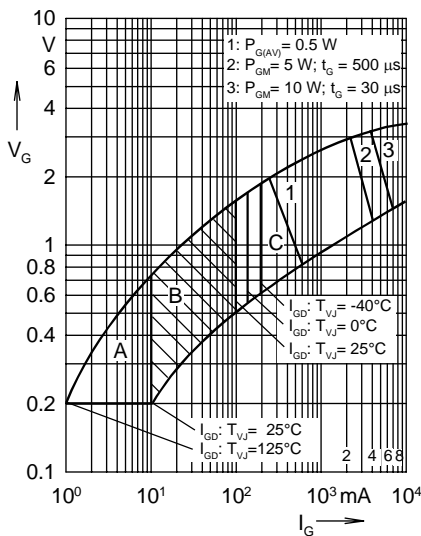


Fig. 1 Gate trigger range
Triggering:
A = no; B = possible, C = safe

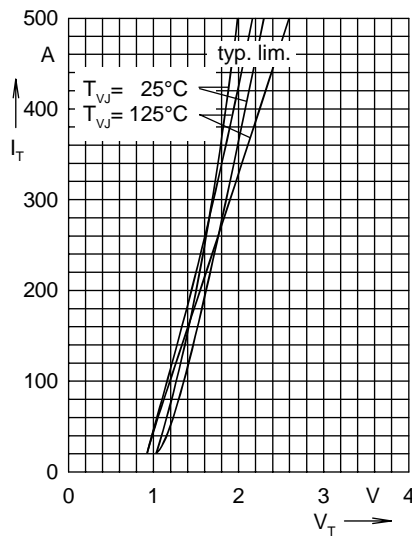


Fig. 2 On-state characteristics

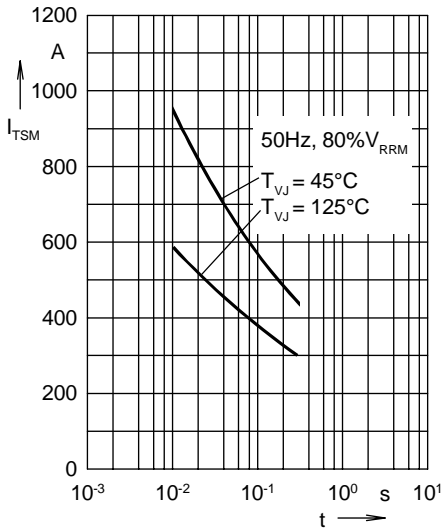


Fig. 3 Surge overload current
 I_{TSM} : crest value, t : duration

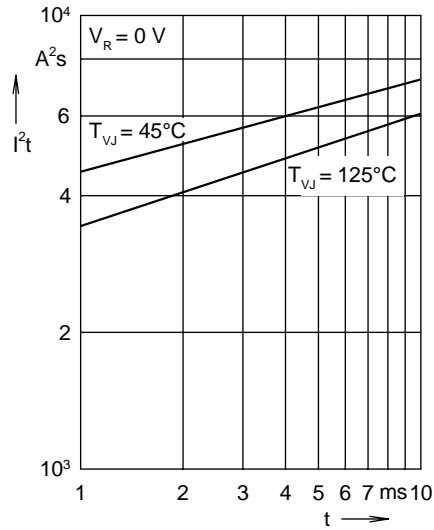


Fig. 4 I^2t versus time (1-10 ms)

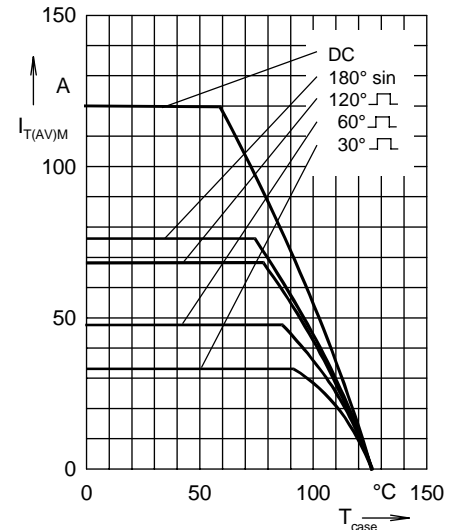


Fig. 5 Maximum forward current at case temperature

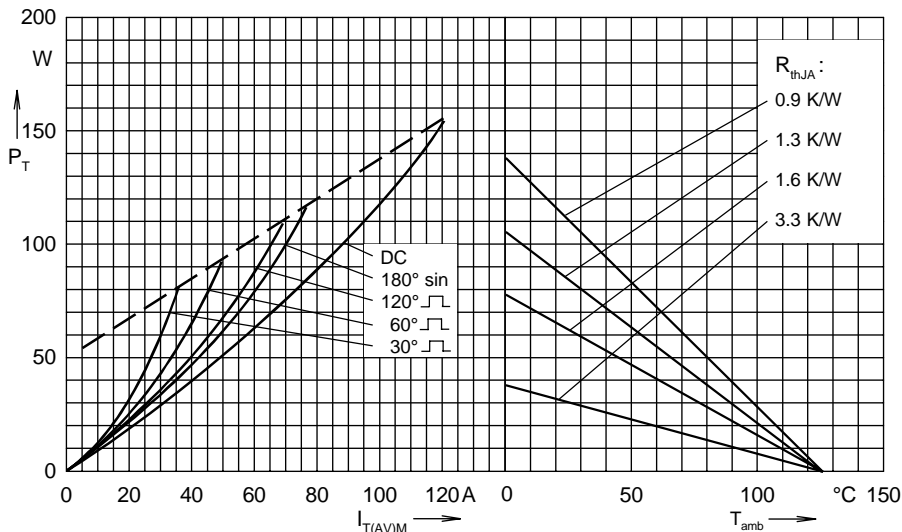


Fig. 6 Power dissipation versus on-state current and ambient temperature

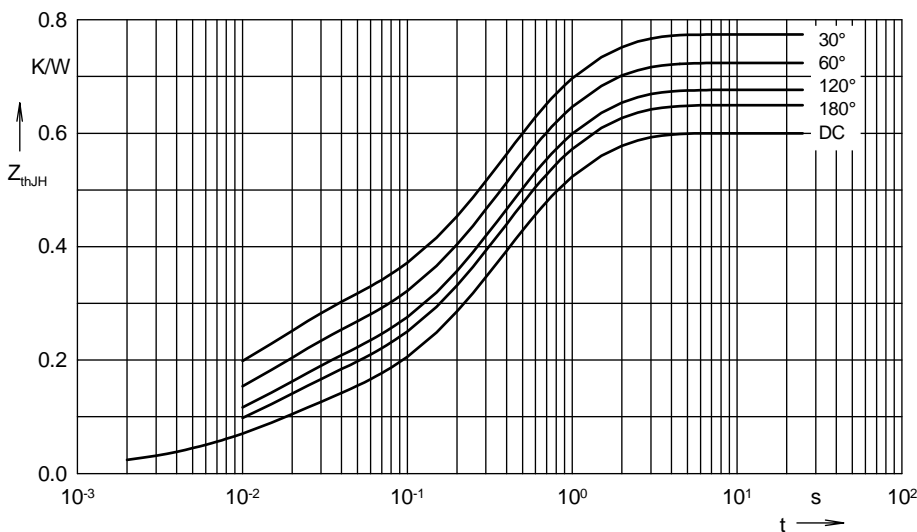


Fig. 7 Transient thermal impedance junction to heatsink

R_{thJH} for various conduction angles d :

d	R_{thJH} (K/W)
DC	0.6
180°	0.65
120°	0.677
60°	0.725
30°	0.775

Constants for Z_{thJH} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.01	0.001
2	0.09	0.013
3	0.30	0.3
4	0.20	0.9