# Micriµm



# µC/OS-III™ Real-Time Operating System

### DESCRIPTION

The  $\mu$ C/OS-III is Micrium's newest RTOS, designed to save time on embedded system projects. In addition to the features inherent in  $\mu$ C/OS-II,  $\mu$ C/OS-III also manages an unlimited number of application tasks, and features an interrupt disable time of near zero.

Micrium's  $\mu$ C/OS-III supports ARM7/9, Cortex-MX, Nios-II, PowerPC, Coldfire, i.MX, Microblaze, H8, SH, M16C, M32C, Blackfin, and more. Ports are available for download from the Micrium website.

 $\mu C/OS\text{-III}$  manages unlimited application tasks, constrained only by a processor's access to memory.  $\mu C/OS\text{-III}$  supports an unlimited number of priority levels. Typically, configuring  $\mu C/OS\text{-III}$  for between 32 and 256 different priority levels is adequate for most embedded applications.

 $\mu C/OS\text{-III}$  allows for unlimited tasks, semaphores, mutexes, event flags, message queues, timers and memory partitions. The user allocates all kernel objects at run time.  $\mu C/OS\text{-III}$  provides features to allow stack growth of tasks to bemonitored. While task size is not limited, they need to have a minimum size based on the CPU used.

 $\mu$ C/OS-III allows multiple tasks to run at the same priority level. When equal priority tasks are ready to run,  $\mu$ C/OS-III runs each for a userspecified time. Each task can define its own time quanta and give up its time slice if it does not require the full time quanta.

 $\mu C/OS\text{-III}$  has a number of internal data structures and variables that it needs to access atomically. It protects these critical regions by disabling interrupts for almost zero clock cycles, ensuring that it is able to respond to some of the fastest interrupt sources. Interrupt response with  $\mu C/OS\text{-III}$  is deterministic.

 $\mu$ C/OS-III ensures that NULL pointers are not passed, task level services fromISRs aren't called, arguments are within allowable range, and specified options are valid. Each API function provides an error code regarding the outcome of the function call.

 $\mu$ C/OS-III's footprint can be scaled to only contain the features required for a specific application. The execution time for most services provided by  $\mu$ C/OS-III is both constant and deterministic; execution times do not depend on the number of tasks running in the application.

#### **APPLICATIONS**

- Data Communications Equipment
- White Goods (Appliances)
- Mobile Phones, PDAs, MIDs
- Industrial Controls
- Consumer Electronics
- Automotive
- A Wide-Range of Embedded Applications

#### **FEATURES**

- Delivered with complete 100% ANSI C source code and in-depth documentation.
- Preemptive Multitasking: Runs the most important task that is ready.
- Unlimited tasks, priorities, kernel objects
- Round-Robin Scheduling
- Near Zero Interrupt Disable Time
- Scalable to contain only required features.

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## **MULTI-THREADED APPLICATIONS**

 $\mu$ C/OS-II allows developers to produce multi-threaded applications, vital to the development of safety-critical systems. Thanks to improved integration with IAR Embedded Workbench for ARM, developers can access all the inherent non-reentrant features of C/C++ in a thread-safe manner.

Application developers who write code for use in multi-threaded environments will find the support critical when protecting shared objects using system locks, file-stream locks, and thread-local storage (TLS) in multi-threaded environments.

Micrium and IAR collaborated in providing the first thread-safe support in  $\mu$ C/OS-II for the IAR DLIB run-time library. Protection for such non-reentrant functions as strtok(), rand(), errno() and more are local to each thread. Global and static variables typically used by these functions are protected by the Micrium kernel.

### µC/OS-III™ REAL-TIME OPERATING SYSTEM

Who should use this RTOS?	Developers who want to save time on their current and future embedded system projects, and who require a robust RTOS built on clean, easy-to- implement code.
Supported Processors	See complete list in Processor Chart for $\mu\text{C}/\text{OS-III}$
Maximum ROM Footprint (Unscaled)	24 Kbytes
Minimum ROM Footprint (Scaled)	6 Kbytes
Number of Kernel Services	10 different using 80 API calls
Multitasking Model	Preemptive
Code Execution Entities	Tasks, ISRs
Dynamic Objects	Static and Dynamic
Data Movement	Message Queues (unlimited)
Semaphores - Full Counting	Yes (unlimited)
Mutexes - With Priority Inheritance	Yes (priority ceiling)
Event Flags	Yes (unlimited), configurable for 8, 16, or 32 bits
Memory Partitions - RAM Management	Yes (unlimited)
Timers	Yes (unlimited)
Number of tasks	Unlimited
Interrupt Disable Time	Near Zero

For pricing, delivery, and ordering information, please contact Micrium at (sales number), or visit Micrium's website at: **www.micrium.com**.

