

HEF4028B

BCD to decimal decoder

Rev. 8 — 17 November 2011

Product data sheet

1. General description

The HEF4028B is a 4-bit BCD to decimal decoder, a 4-bit BCO to octal decoder with active LOW enable or an 8-output (Y0 to Y7) inverting demultiplexer. The outputs are fully buffered for best performance.

When used as a BCD to decimal decoder a 1-2-4-8 BCD code applied to inputs A0 to A3 causes the selected output to be HIGH. The other nine outputs will be LOW.

To use the HEF4028B as a BCO to octal decoder, input A3 is an active LOW enable pin and outputs Y8 and Y9 are not used. A 1-2-4 BCO code applied to inputs A0 to A2 causes the selected output (Y0 to Y7) to be HIGH. The other seven outputs will be LOW. When A3 is HIGH outputs (Y0 to Y7) will be forced LOW.

When used as an 8-output (Y0 to Y7) inverting demultiplexer A0 to A2 are used as address inputs and A3 is the data input. Outputs Y8 and Y9 are not used.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$
- Complies with JEDEC standard JESD 13-B

3. Ordering information

Table 1. Ordering information

All types operate from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$.

| Type number | Package | | Version |
|-------------|---------|--|----------|
| | Name | Description | |
| HEF4028BP | DIP16 | plastic dual in-line package; 16 leads (300 mil) | SOT38-4 |
| HEF4028BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |



4. Functional diagram

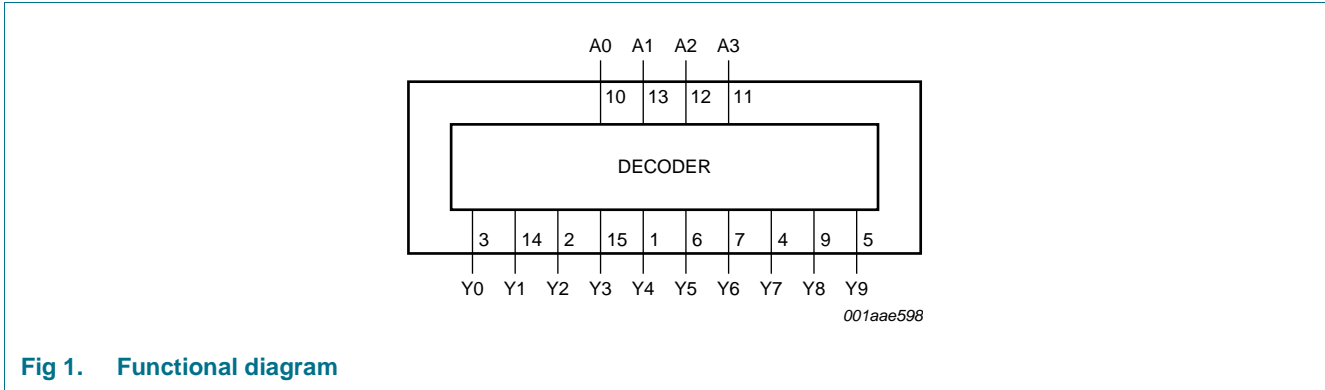


Fig 1. Functional diagram

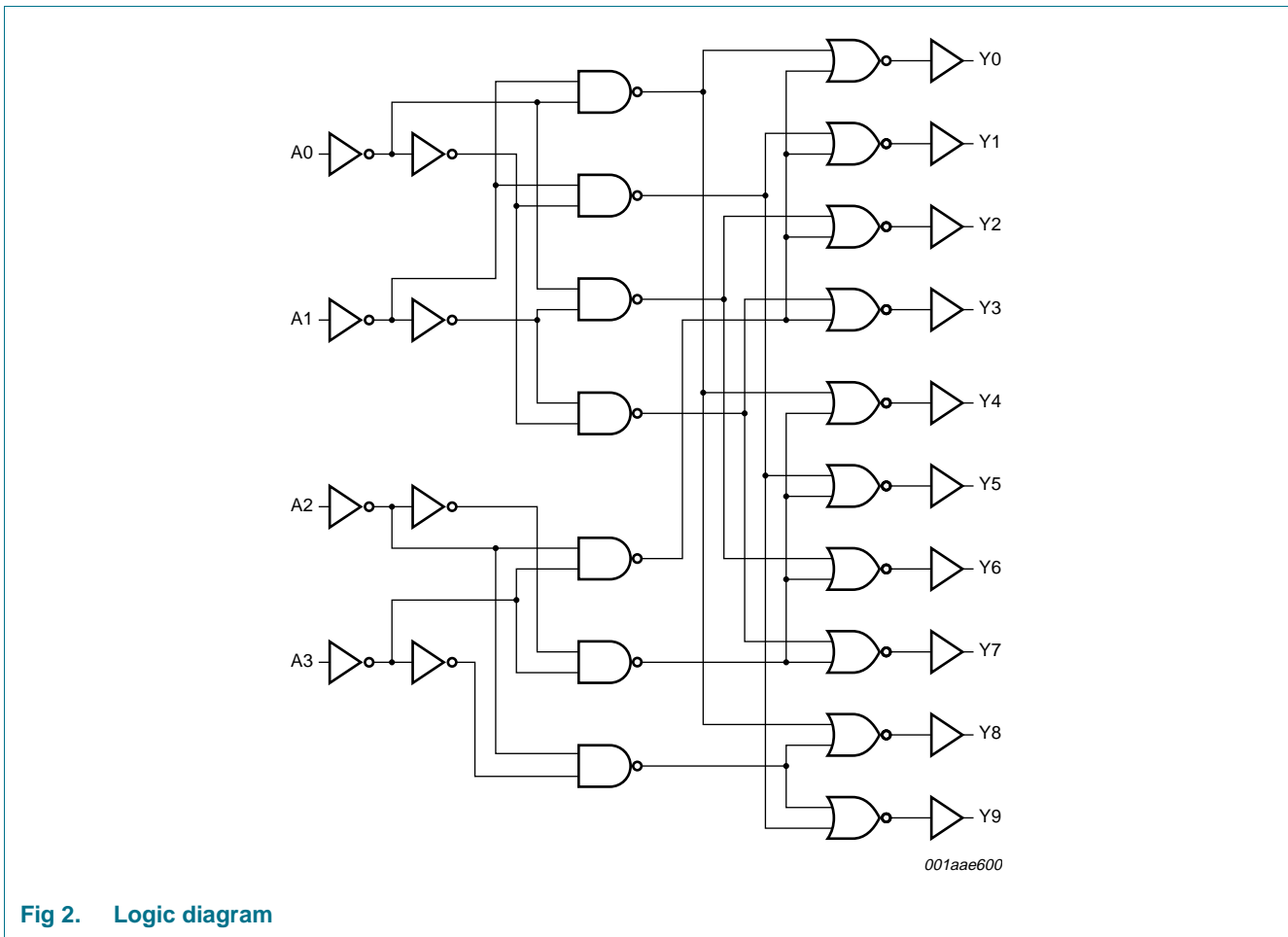


Fig 2. Logic diagram

5. Pinning information

5.1 Pinning

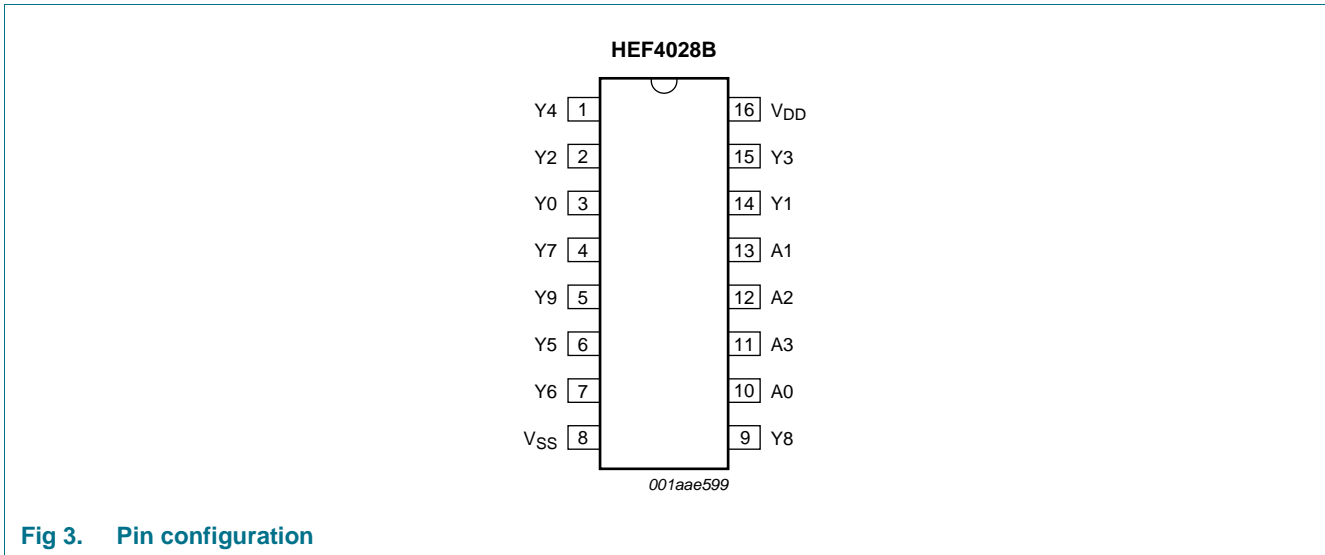


Fig 3. Pin configuration

5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|--------------------------------|-----------------------|
| Y0 to Y9 | 3, 14, 2, 15, 1, 6, 7, 4, 9, 5 | output (active HIGH) |
| V _{SS} | 8 | ground supply voltage |
| A0 to A3 | 10, 13, 12, 11 | address input |
| V _{DD} | 16 | supply voltage |

6. Functional description

Table 3. Function table [\[1\]](#)

| Inputs | | | | Outputs | | | | | | | | | |
|--------|----|----|----|---------|----|----|----|----|----|----|----|----|----|
| A3 | A2 | A1 | A0 | Y0 | Y1 | Y2 | Y3 | Y4 | Y5 | Y6 | Y7 | Y8 | Y9 |
| L | L | L | L | H | L | L | L | L | L | L | L | L | L |
| L | L | L | H | L | H | L | L | L | L | L | L | L | L |
| L | L | H | L | L | L | H | L | L | L | L | L | L | L |
| L | L | H | H | L | L | L | H | L | L | L | L | L | L |
| L | H | L | L | L | L | L | L | H | L | L | L | L | L |
| L | H | L | H | L | L | L | L | L | H | L | L | L | L |
| L | H | H | L | L | L | L | L | L | L | H | L | L | L |
| L | H | H | H | L | L | L | L | L | L | L | H | L | L |
| H | L | L | L | L | L | L | L | L | L | L | L | H | L |

Table 3. Function table [1] ...continued

| Inputs | | | | Outputs | | | | | | | | | |
|--------|----|----|----|---------|----|----|----|----|----|----|----|----|----|
| A3 | A2 | A1 | A0 | Y0 | Y1 | Y2 | Y3 | Y4 | Y5 | Y6 | Y7 | Y8 | Y9 |
| H | L | L | H | L | L | L | L | L | L | L | L | L | H |
| H | L | H | X | L | L | L | L | L | L | L | L | L | L |
| H | H | X | X | L | L | L | L | L | L | L | L | L | L |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care.

[2] Extraordinary states.

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|-------|----------------|------|
| V_{DD} | supply voltage | | -0.5 | +18 | V |
| I_{IK} | input clamping current | $V_I < -0.5\text{ V}$ or $V_I > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| V_I | input voltage | | -0.5 | $V_{DD} + 0.5$ | V |
| I_{OK} | output clamping current | $V_O < -0.5\text{ V}$ or $V_O > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| $I_{I/O}$ | input/output current | | - | ± 10 | mA |
| I_{DD} | supply current | | - | 50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| T_{amb} | ambient temperature | | -40 | +85 | °C |
| P_{tot} | total power dissipation | $T_{amb} = -40\text{ °C}$ to $+85\text{ °C}$ | | | |
| | | DIP16 package | [1] - | 750 | mW |
| | | SO16 package | [2] - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|----------|------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | - | 6.25 | ms/V |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | ms/V |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | ms/V |

9. Static characteristics

Table 6. Static characteristics
 $V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} .

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ }^{\circ}\text{C}$ | | $T_{amb} = 25\text{ }^{\circ}\text{C}$ | | $T_{amb} = 85\text{ }^{\circ}\text{C}$ | | Unit |
|----------|---------------------------|--------------------------------|----------|---|-----------|--|-----------|--|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$ | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

10. Dynamic characteristics

Table 7. Dynamic characteristics
 $V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$.

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|-----------|-------------------------------|---|----------|---|-----|-----|-----|------|
| t_{PHL} | HIGH to LOW propagation delay | An to Yn; see Figure 4 | 5 V | [1] $73\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 100 | 200 | ns |
| | | | 10 V | $29\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 40 | 80 | ns |
| | | | 15 V | $22\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 30 | 60 | ns |
| t_{PLH} | LOW to HIGH propagation delay | An to Yn; see Figure 4 | 5 V | [1] $63\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 90 | 180 | ns |
| | | | 10 V | $29\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 40 | 80 | ns |
| | | | 15 V | $22\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 30 | 60 | ns |

Table 7. Dynamic characteristics ...continued

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$.

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|--------|-----------------|------------------------------|----------|---|-----|-----|-----|------|
| t_t | transition time | see Figure 4 | 5 V | [1] $10\text{ ns} + (1.00\text{ ns/pF})C_L$ | - | 60 | 120 | ns |
| | | | 10 V | $9\text{ ns} + (0.42\text{ ns/pF})C_L$ | - | 30 | 60 | ns |
| | | | 15 V | $6\text{ ns} + (0.28\text{ ns/pF})C_L$ | - | 20 | 40 | ns |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0\text{ V}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$.

| Symbol | Parameter | V_{DD} | Typical formula for P_D (μW) | where: |
|--------|---------------------------|----------|--|---|
| P_D | dynamic power dissipation | 5 V | $P_D = 350 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f_i = input frequency in MHz; |
| | | 10 V | $P_D = 2200 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f_o = output frequency in MHz; |
| | | 15 V | $P_D = 7350 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | C_L = output load capacitance in pF; V_{DD} = supply voltage in V; $\Sigma(f_o \times C_L)$ = sum of the outputs. |

11. Waveforms

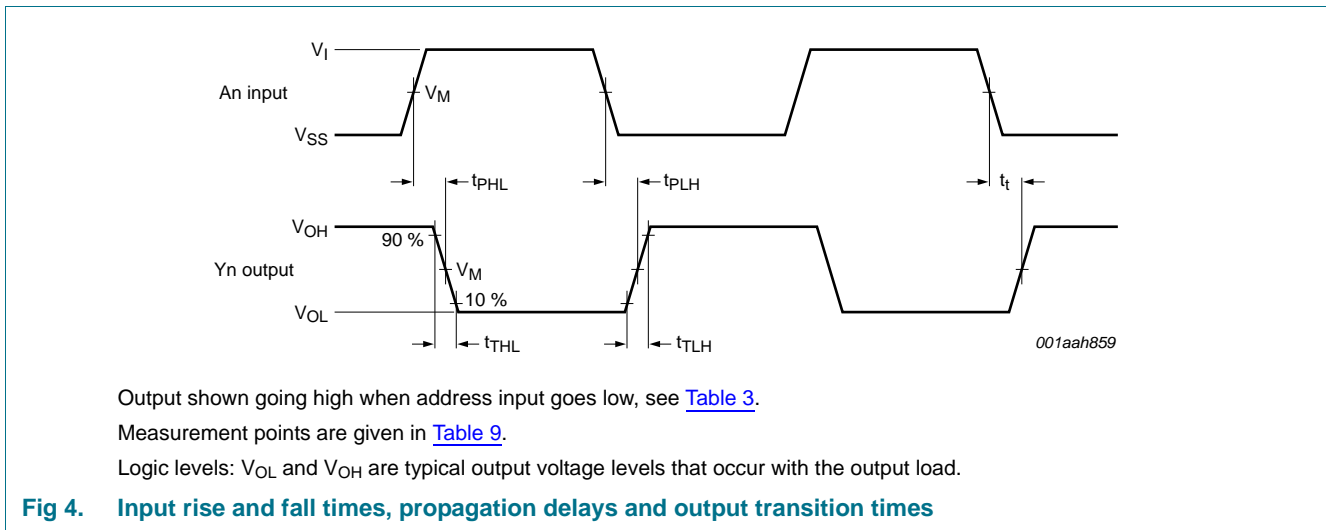
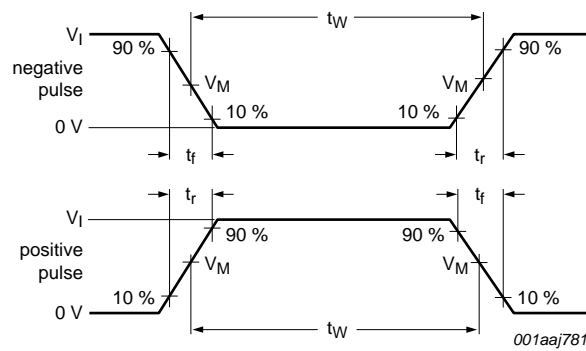
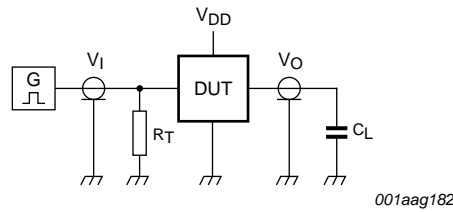


Table 9. Measurement points

| Supply voltage | Input | Output |
|----------------|-------------|-------------|
| V_{DD} | V_M | V_M |
| 5 V to 15 V | $0.5V_{DD}$ | $0.5V_{DD}$ |



a. Input waveforms



b. Test circuit

Test data is given in [Table 10](#).

Definitions for test circuit:

DUT = Device Under Test;

C_L = load capacitance including jig and probe capacitance;

R_T = termination resistance should be equal to the output impedance Z_o of the pulse generator.

Fig 5. Test circuit for switching times

Table 10. Test data

| Supply voltage | Input | | Load |
|----------------|----------------------|--------------|-------|
| V_{DD} | V_I | t_r, t_f | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | 50 pF |

12. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4

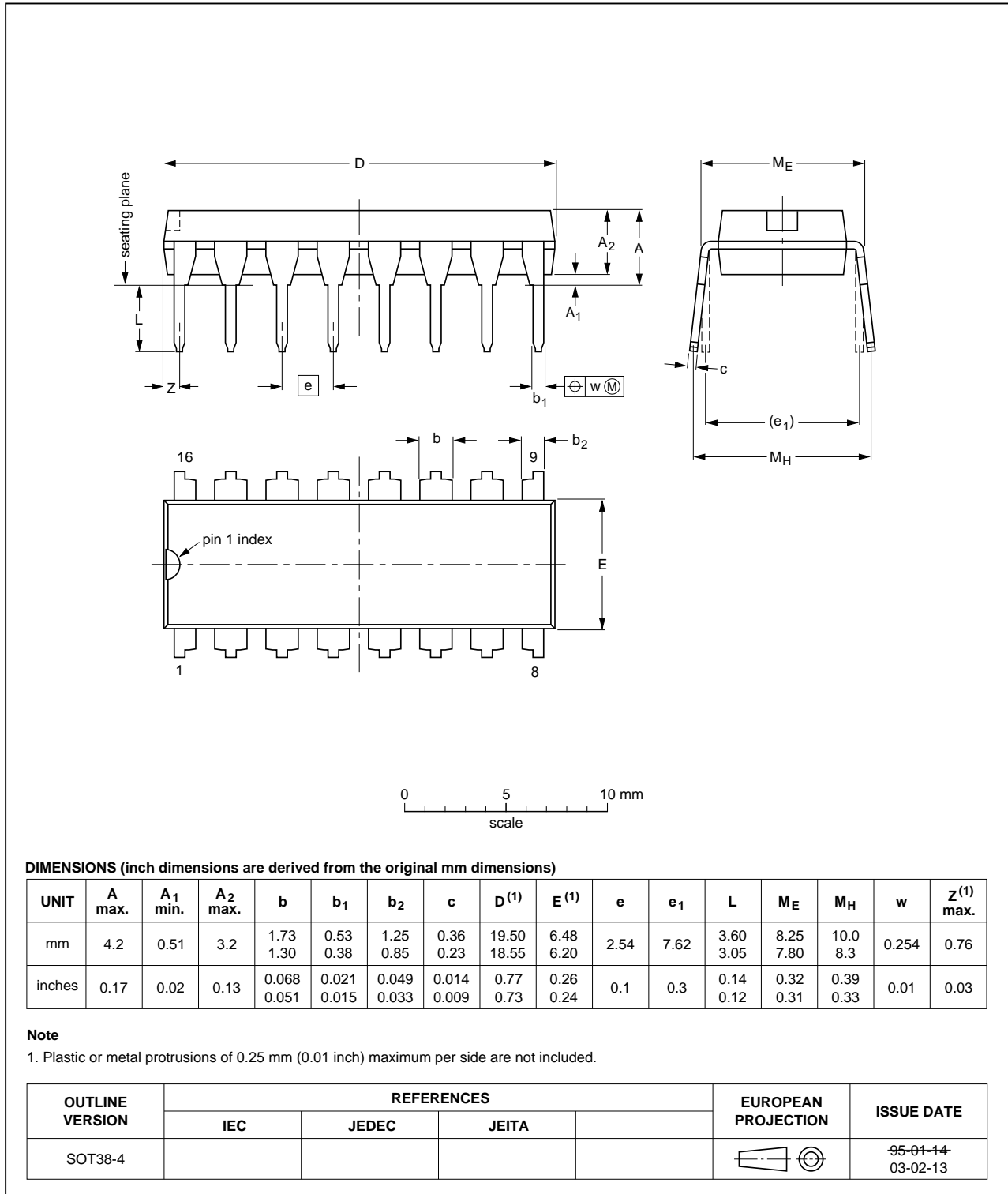


Fig 6. Package outline SOT38-4 (DIP16)

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

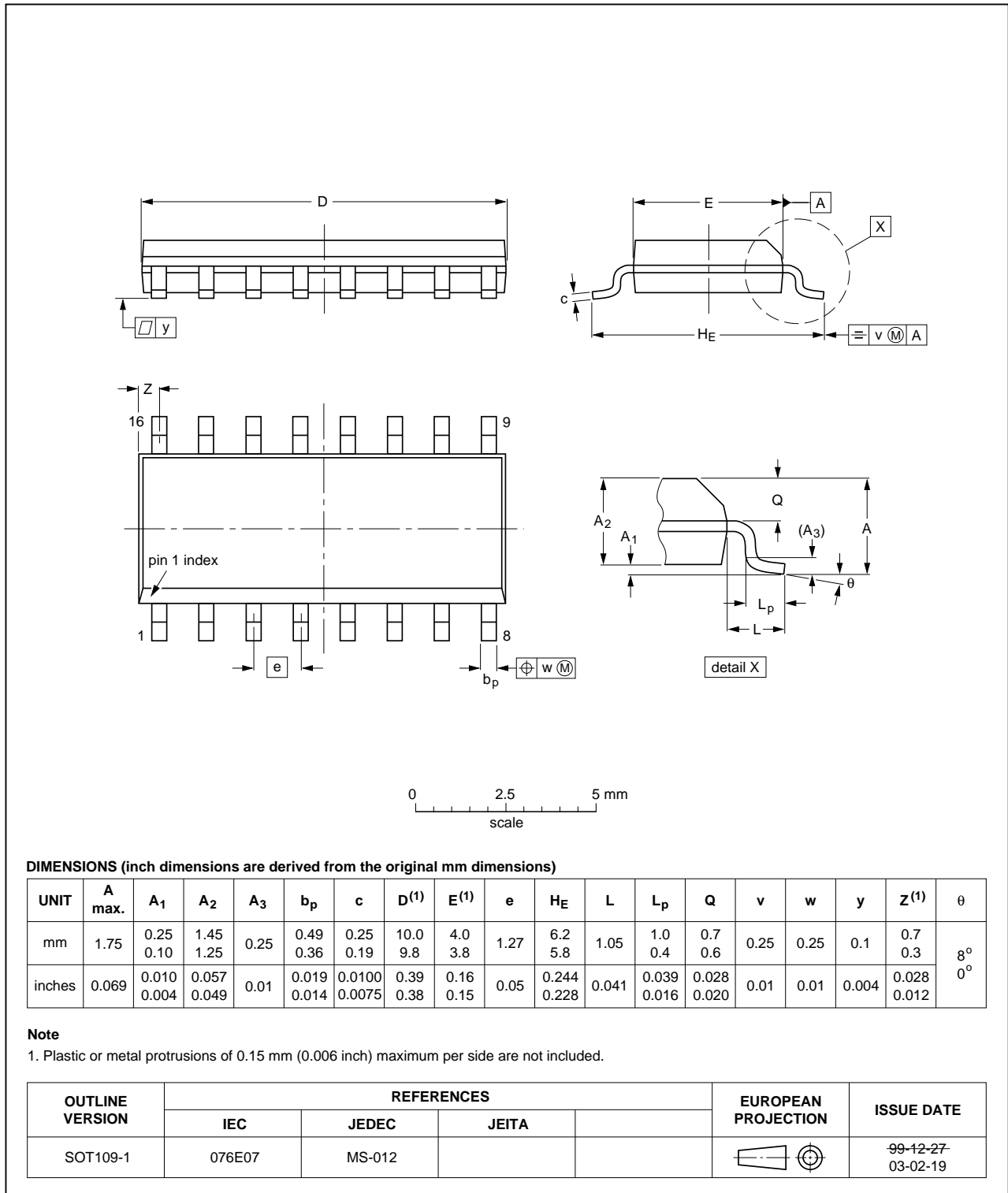


Fig 7. Package outline SOT109-1 (SO16)

13. Abbreviations

Table 11. Abbreviations

| Acronym | Description |
|---------|----------------------|
| BCD | Binary Coded Decimal |
| BCO | Binary Coded Octal |

14. Revision history

Table 12. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|--|-----------------------|---------------|------------------|
| HEF4028B v.8 | 20111117 | Product data sheet | - | HEF4028B v.7 |
| Modifications: | <ul style="list-style-type: none"> • Legal pages updated. • Changes in “General description” and “Features and benefits”. • Section “Applications” removed. | | | |
| HEF4028B v.7 | 20111010 | Product data sheet | - | HEF4028B v.6 |
| HEF4028B v.6 | 20091125 | Product data sheet | - | HEF4028B v.5 |
| HEF4028B v.5 | 20090707 | Product data sheet | - | HEF4028B v.4 |
| HEF4028B v.4 | 20090304 | Product data sheet | - | HEF4028B_CNV v.3 |
| HEF4028B_CNV v.3 | 19950101 | Product specification | - | HEF4028B_CNV v.2 |
| HEF4028B_CNV v.2 | 19950101 | Product specification | - | - |

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| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
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