Dual supply translating transceiver; 3-state Rev. 6 — 6 August 2012

Product data sheet

General description 1.

The 74LVC1T45; 74LVCH1T45 are single bit, dual supply transceivers with 3-state outputs that enable bidirectional level translation. They feature two 1-bit input-output ports (A and B), a direction control input (DIR) and dual supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). Both $V_{CC(A)}$ and $V_{CC(B)}$ can be supplied at any voltage between 1.2 V and 5.5 V making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and DIR are referenced to $V_{CC(A)}$ and pin B is referenced to V_{CC(B)}. A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

The devices are fully specified for partial power-down applications using I_{OFF}. The I_{OFF} circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either $V_{CC(A)}$ or $V_{CC(B)}$ are at GND level, both A port and B port are in the high-impedance OFF-state.

Active bus hold circuitry in the 74LVCH1T45 holds unused or floating data inputs at a valid logic level.

Features and benefits 2.

- Wide supply voltage range:
 - V_{CC(A)}: 1.2 V to 5.5 V
 - V_{CC(B)}: 1.2 V to 5.5 V
- High noise immunity
- Complies with JEDEC standards:
 - JESD8-7 (1.2 V to 1.95 V)
 - JESD8-5 (1.8 V to 2.7 V)
 - JESD8C (2.7 V to 3.6 V)
 - JESD36 (4.5 V to 5.5 V)
- ESD protection:
 - HBM JESD22-A114F Class 3A exceeds 4000 V
 - CDM JESD22-C101E exceeds 1000 V
- Maximum data rates:
 - 420 Mbps (3.3 V to 5.0 V translation)
 - 210 Mbps (translate to 3.3 V))
 - 140 Mbps (translate to 2.5 V)
 - 75 Mbps (translate to 1.8 V)
 - 60 Mbps (translate to 1.5 V)
- Suspend mode



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- Latch-up performance exceeds 100 mA per JESD 78 Class II
- ± 24 mA output drive (V_{CC} = 3.0 V)
- Inputs accept voltages up to 5.5 V
- Low power consumption: 16 μA maximum I_{CC}
- I_{OFF} circuitry provides partial Power-down mode operation
- Multiple package options
- Specified from –40 °C to +85 °C and –40 °C to +125 °C

3. Ordering information

| Type number | Package | | | | | | |
|--------------|------------------------|-------|---|---------|--|--|--|
| | Temperature range Name | | Description | Version | | | |
| 74LVC1T45GW | –40 °C to +125 °C | SC-88 | plastic surface-mounted package; 6 leads | SOT363 | | | |
| 74LVCH1T45GW | | | | | | | |
| 74LVC1T45GM | –40 °C to +125 °C | | | SOT886 | | | |
| 74LVCH1T45GM | | | 6 terminals; body $1 \times 1.45 \times 0.5$ mm | | | | |
| 74LVC1T45GF | –40 °C to +125 °C | XSON6 | (SON6 plastic extremely thin small outline package; no leads; | | | | |
| 74LVCH1T45GF | | | 6 terminals; body $1 \times 1 \times 0.5$ mm | | | | |
| 74LVC1T45GN | –40 °C to +125 °C | XSON6 | extremely thin small outline package; no leads; | SOT1115 | | | |
| 74LVCH1T45GN | | | 6 terminals; body $0.9 \times 1.0 \times 0.35$ mm | | | | |
| 74LVC1T45GS | –40 °C to +125 °C | XSON6 | ON6 extremely thin small outline package; no leads; | | | | |
| 74LVCH1T45GS | | | 6 terminals; body $1.0 \times 1.0 \times 0.35$ mm | | | | |

4. Marking

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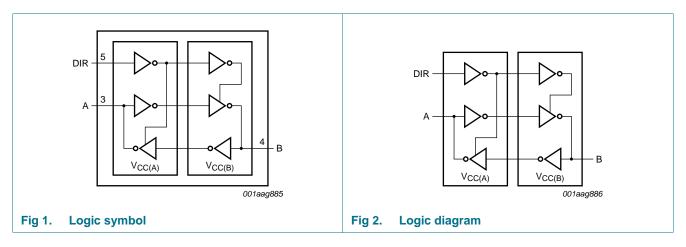
| Table 2. Marking | |
|------------------|-----------------------------|
| Type number | Marking code ^[1] |
| 74LVC1T45GW | V5 |
| 74LVCH1T45GW | X5 |
| 74LVC1T45GM | V5 |
| 74LVCH1T45GM | X5 |
| 74LVC1T45GF | V5 |
| 74LVCH1T45GF | X5 |
| 74LVC1T45GN | V5 |
| 74LVCH1T45GN | X5 |
| 74LVC1T45GS | V5 |
| 74LVCH1T45GS | X5 |

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.



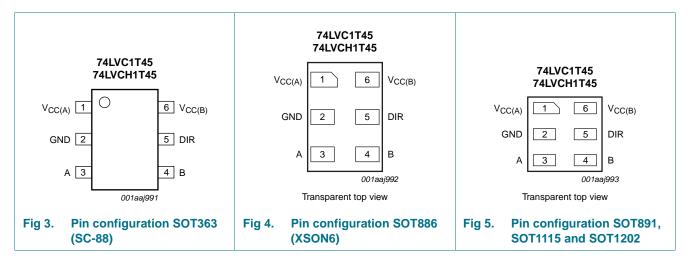
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5. Functional diagram



6. Pinning information

6.1 Pinning



6.2 Pin description

| SymbolPinDescriptionV _{CC(A)} 1supply voltage port A and DIRGND2ground (0 V)A3data input or outputB4data input or outputDIR5direction controlV _{CC(B)} 6supply voltage port B | Table 3. | Pin description | |
|---|--------------------|-----------------|-------------------------------|
| GND2ground (0 V)A3data input or outputB4data input or outputDIR5direction control | Symbol | Pin | Description |
| A3data input or outputB4data input or outputDIR5direction control | V _{CC(A)} | 1 | supply voltage port A and DIR |
| B4data input or outputDIR5direction control | GND | 2 | ground (0 V) |
| DIR 5 direction control | А | 3 | data input or output |
| | В | 4 | data input or output |
| V _{CC(B)} 6 supply voltage port B | DIR | 5 | direction control |
| | V _{CC(B)} | 6 | supply voltage port B |

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7. Functional description

| Supply voltage | Input | Input/output ^[2] | | |
|---|-------|-----------------------------|-------|--|
| V _{CC(A)} , V _{CC(B)} | DIR | Α | В | |
| 1.2 V to 5.5 V | L | A = B | input | |
| 1.2 V to 5.5 V | Н | input | B = A | |
| GND ^[3] | Х | Z | Z | |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] The input circuit of the data I/O is always active.

[3] When either $V_{CC(A)}$ or $V_{CC(B)}$ is at GND level, the device goes into suspend mode.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| | | | - | | - |
|--------------------|-------------------------|--|-----------------------|------------------------|------|
| Symbol | Parameter | Conditions | Min | Max | Unit |
| V _{CC(A)} | supply voltage A | | -0.5 | +6.5 | V |
| V _{CC(B)} | supply voltage B | | -0.5 | +6.5 | V |
| I _{IK} | input clamping current | V ₁ < 0 V | -50 | - | mA |
| VI | input voltage | | <u>[1]</u> –0.5 | +6.5 | V |
| Ι _{ΟΚ} | output clamping current | V _O < 0 V | -50 | - | mA |
| Vo | output voltage | Active mode | <u>[1][2][3]</u> _0.5 | V _{CCO} + 0.5 | V |
| | | Suspend or 3-state mode | <u>[1]</u> –0.5 | +6.5 | V |
| lo | output current | $V_{O} = 0 V$ to V_{CCO} | [2] _ | ±50 | mA |
| I _{CC} | supply current | I _{CC(A)} or I _{CC(B)} | - | 100 | mA |
| I _{GND} | ground current | | -100 | - | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| P _{tot} | total power dissipation | T_{amb} = -40 °C to +125 °C | [4] _ | 250 | mW |
| | | | | | |

[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCO} is the supply voltage associated with the output port.

[3] V_{CCO} + 0.5 V should not exceed 6.5 V.

[4] For SC-88 package: above 87.5 °C the value of P_{tot} derates linearly with 4.0 mW/K. For XSON6 package: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K.

9. Recommended operating conditions

Table 6. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------|------------------|------------|-----|-----|------|
| V _{CC(A)} | supply voltage A | | 1.2 | 5.5 | V |
| V _{CC(B)} | supply voltage B | | 1.2 | 5.5 | V |
| VI | input voltage | | 0 | 5.5 | V |

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| | Recommended operating condition | | | | |
|-----------------------|-------------------------------------|--|--------------|------------------|------|
| Symbol | Parameter | Conditions | Min | Max | Unit |
| Vo | output voltage | Active mode | <u>[1]</u> 0 | V _{CCO} | V |
| | | Suspend or 3-state mode | 0 | 5.5 | V |
| T _{amb} | ambient temperature | | -40 | +125 | °C |
| $\Delta t / \Delta V$ | input transition rise and fall rate | V _{CCI} = 1.2 V | [2] _ | 20 | ns/V |
| | | $V_{CCI} = 1.4 \text{ V} \text{ to } 1.95 \text{ V}$ | - | 20 | ns/V |
| | | V_{CCI} = 2.3 V to 2.7 V | - | 20 | ns/V |
| | | $V_{CCI} = 3 V \text{ to } 3.6 V$ | - | 10 | ns/V |
| | | V_{CCI} = 4.5 V to 5.5 V | - | 5 | ns/V |
| | | | | | |

Table 6. Recommended operating conditions ...continued

[1] V_{CCO} is the supply voltage associated with the output port.

[2] V_{CCI} is the supply voltage associated with the input port.

10. Static characteristics

Table 7.Typical static characteristics at T_{amb} = 25 °C

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|-------------------|------------------------------------|---|--------------|------|-----|------|
| V _{OH} | HIGH-level output voltage | $V_{I} = V_{IH} \text{ or } V_{IL}$ | | | | |
| | | $I_{O} = -3 \text{ mA}; V_{CCO} = 1.2 \text{ V}$ | <u>[1]</u> - | 1.09 | - | V |
| V _{OL} | LOW-level output voltage | $V_{I} = V_{IH} \text{ or } V_{IL}$ | | | | |
| | | $I_0 = 3 \text{ mA}; V_{CCO} = 1.2 \text{ V}$ | <u>[1]</u> - | 0.07 | - | V |
| l _l | input leakage current | DIR input; $V_I = 0 V$ to 5.5 V; $V_{CCI} = 1.2 V$ to 5.5 V | [2] _ | - | ±1 | μA |
| I _{BHL} | bus hold LOW current | A or B port; V_I = 0.42 V; V_{CCI} = 1.2 V | [2] _ | 19 | - | μA |
| I _{BHH} | bus hold HIGH current | A or B port; $V_I = 0.78 \text{ V}$; $V_{CCI} = 1.2 \text{ V}$ | [2] - | -19 | - | μA |
| I _{BHLO} | bus hold LOW overdrive current | A or B port; $V_{CCI} = 1.2 V$ | [2][3] _ | 19 | - | μΑ |
| I _{BHHO} | bus hold HIGH overdrive current | A or B port; $V_{CCI} = 1.2 V$ | [2][3] _ | -19 | - | μA |
| I _{OZ} | OFF-state output current | A or B port; $V_0 = 0$ V or V_{CCO} ; $V_{CCO} = 1.2$ V to 5.5 V | <u>[1]</u> - | - | ±1 | μΑ |
| I _{OFF} | power-off leakage current | A port; V ₁ or V _O = 0 V to 5.5 V; V _{CC(A)} = 0 V; V _{CC(B)} = 1.2 V to 5.5 V | - | - | ±1 | μA |
| | | B port; V ₁ or V _O = 0 V to 5.5 V; V _{CC(B)} = 0 V; V _{CC(A)} = 1.2 V to 5.5 V | - | - | ±1 | μΑ |
| CI | input capacitance | DIR input; $V_I = 0 V \text{ or } 3.3 V$; $V_{CC(A)} = V_{CC(B)} = 3.3 V$ | - | 2.2 | - | pF |
| C _{I/O} | input/output capacitance | A and B port; suspend mode; V _O = 3.3 V or 0 V; V _{CC(A)} = V _{CC(B)} = 3.3 V | - | 6.0 | - | pF |

[1] V_{CCO} is the supply voltage associated with the output port.

[2] V_{CCI} is the supply voltage associated with the data input port.

[3] To guarantee the node switches, an external driver must source/sink at least I_{BHLO}/I_{BHHO} when the input is in the range V_{IL} to V_{IH} .

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Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditions | | –40 °C to +85 °C | | –40 °C to +125 °C | | Unit |
|-----------------|-----------------------------|--|------------|------------------------|------------------------|------------------------|------------------------|------|
| | | | | Min | Max | Min | Max | |
| / _{IH} | HIGH-level input voltage | data input | <u>[1]</u> | | | | | |
| | | V _{CCI} = 1.2 V | | 0.8V _{CCI} | - | 0.8V _{CCI} | - | V |
| | | V _{CCI} = 1.4 V to 1.95 V | | 0.65V _{CCI} | - | 0.65V _{CCI} | - | V |
| | | $V_{CCI} = 2.3 \text{ V} \text{ to } 2.7 \text{ V}$ | | 1.7 | - | 1.7 | - | V |
| | | $V_{CCI} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$ | | 2.0 | - | 2.0 | - | V |
| | | $V_{CCI} = 4.5 \text{ V} \text{ to } 5.5 \text{ V}$ | | 0.7V _{CCI} | - | 0.7V _{CCI} | - | V |
| | | DIR input | | | | | | |
| | | V _{CCI} = 1.2 V | | 0.8V _{CC(A)} | - | 0.8V _{CC(A)} | - | V |
| | | $V_{CCI} = 1.4 \text{ V}$ to 1.95 V | | 0.65V _{CC(A)} | - | 0.65V _{CC(A)} | - | V |
| | | $V_{CCI} = 2.3 \text{ V} \text{ to } 2.7 \text{ V}$ | | 1.7 | - | 1.7 | - | V |
| | | $V_{CCI} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$ | | 2.0 | - | 2.0 | - | V |
| | | $V_{CCI} = 4.5 \text{ V}$ to 5.5 V | | 0.7V _{CC(A)} | - | 0.7V _{CC(A)} | - | V |
| | LOW-level input voltage | data input | <u>[1]</u> | | | | | |
| | | V _{CCI} = 1.2 V | | - | 0.2V _{CCI} | - | 0.2V _{CCI} | V |
| | | $V_{CCI} = 1.4 \text{ V} \text{ to } 1.95 \text{ V}$ | | - | 0.35V _{CCI} | - | 0.35V _{CCI} | V |
| | | V_{CCI} = 2.3 V to 2.7 V | | - | 0.7 | - | 0.7 | V |
| | | $V_{CCI} = 3.0 V \text{ to } 3.6 V$ | | - | 0.8 | - | 0.8 | V |
| | | $V_{CCI} = 4.5 \text{ V}$ to 5.5 V | | - | 0.3V _{CCI} | - | 0.3V _{CCI} | V |
| | | DIR input | | | | | | |
| | | V _{CCI} = 1.2 V | | - | 0.2V _{CC(A)} | - | 0.2V _{CC(A)} | V |
| | | $V_{CCI} = 1.4 \text{ V to } 1.95 \text{ V}$ | | - | 0.35V _{CC(A)} | - | 0.35V _{CC(A)} | V |
| | | V_{CCI} = 2.3 V to 2.7 V | | - | 0.7 | - | 0.7 | V |
| | | $V_{CCI} = 3.0 \text{ V} \text{ to } 3.6 \text{ V}$ | | - | 0.8 | - | 0.8 | V |
| | | $V_{CCI} = 4.5 \text{ V} \text{ to } 5.5 \text{ V}$ | | - | 0.3V _{CC(A)} | - | 0.3V _{CC(A)} | V |
| V _{он} | HIGH-level | $V_{I} = V_{IH}$ | | | | | | |
| | output voltage | $I_{O} = -100 \ \mu A;$ $V_{CCO} = 1.2 \ V \text{ to } 4.5 \ V$ | [2] | V _{CCO} - 0.1 | - | $V_{CCO}-0.1$ | - | V |
| | | $I_0 = -6 \text{ mA}; V_{CCO} = 1.4 \text{ V}$ | | 1.0 | - | 1.0 | - | V |
| | | $I_{O} = -8 \text{ mA}; V_{CCO} = 1.65 \text{ V}$ | | 1.2 | - | 1.2 | - | V |
| | | $I_0 = -12 \text{ mA}; V_{CCO} = 2.3 \text{ V}$ | | 1.9 | - | 1.9 | - | V |
| | | $I_{O} = -24 \text{ mA}; V_{CCO} = 3.0 \text{ V}$ | | 2.4 | - | 2.4 | - | V |
| | | | | | | | | |

Table 8. **Static characteristics**

 $I_0 = -32 \text{ mA}; V_{CCO} = 4.5 \text{ V}$

3.8

-

3.8

V

-

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| Symbol | Parameter | Conditions | | -40 °C te | o +85 °C | -40 °C to | +125 °C | Uni |
|-----------------|-----------------------------|---|---------------|-----------|----------|-----------|---------|-----|
| | | | Ī | Min | Max | Min | Max | |
| / _{OL} | LOW-level | $V_{I} = V_{IL}$ | [2] | | | | | |
| | output voltage | I _O = 100 μA; V _{CCO} = 1.2 V to 4.5 V | | - | 0.1 | - | 0.1 | V |
| | | $I_0 = 6 \text{ mA}; V_{CCO} = 1.4 \text{ V}$ | | - | 0.3 | - | 0.3 | V |
| | | $I_0 = 8 \text{ mA}; V_{CCO} = 1.65 \text{ V}$ | | - | 0.45 | - | 0.45 | V |
| | | $I_0 = 12 \text{ mA}; V_{CCO} = 2.3 \text{ V}$ | | - | 0.3 | - | 0.3 | V |
| | | $I_0 = 24 \text{ mA}; V_{CCO} = 3.0 \text{ V}$ | | - | 0.55 | - | 0.55 | V |
| | | $I_0 = 32 \text{ mA}; V_{CCO} = 4.5 \text{ V}$ | | - | 0.55 | - | 0.55 | V |
| I | input leakage current | DIR input; $V_I = 0 V$ to 5.5 V; $V_{CCI} = 1.2 V$ to 5.5 V | | - | ±2 | - | ±10 | μA |
| BHL | bus hold LOW | A or B port | <u>[1]</u> | | | | | |
| | current | $V_{I} = 0.49 \text{ V}; V_{CCI} = 1.4 \text{ V}$ | | 15 | - | 10 | - | μΑ |
| | | $V_{I} = 0.58 \text{ V}; V_{CCI} = 1.65 \text{ V}$ | | 25 | - | 20 | - | μΑ |
| | | $V_{I} = 0.70 \text{ V}; V_{CCI} = 2.3 \text{ V}$ | | 45 | - | 45 | - | μA |
| | | $V_{I} = 0.80 \text{ V}; V_{CCI} = 3.0 \text{ V}$ | | 100 | - | 80 | - | μA |
| | | $V_{I} = 1.35 \text{ V}; V_{CCI} = 4.5 \text{ V}$ | | 100 | - | 100 | - | μA |
| BHH | bus hold HIGH | A or B port | <u>[1]</u> | | | | | |
| | current | $V_{I} = 0.91 \text{ V}; V_{CCI} = 1.4 \text{ V}$ | | -15 | - | -10 | - | μA |
| | | $V_{I} = 1.07 \text{ V}; V_{CCI} = 1.65 \text{ V}$ | | -25 | - | -20 | - | μA |
| | | $V_{I} = 1.60 \text{ V}; V_{CCI} = 2.3 \text{ V}$ | | -45 | - | -45 | - | μA |
| | | $V_{I} = 2.00 \text{ V}; V_{CCI} = 3.0 \text{ V}$ | | -100 | - | -80 | - | μA |
| | | $V_{I} = 3.15 \text{ V}; V_{CCI} = 4.5 \text{ V}$ | | -100 | - | -100 | - | μA |
| BHLO | bus hold LOW | A or B port | <u>[1][3]</u> | | | | | |
| | overdrive current | $V_{CCI} = 1.6 V$ | | 125 | - | 125 | - | μA |
| | current | V _{CCI} = 1.95 V | | 200 | - | 200 | - | μA |
| | | $V_{CCI} = 2.7 V$ | | 300 | - | 300 | - | μA |
| | | V _{CCI} = 3.6 V | | 500 | - | 500 | - | μA |
| | | $V_{CCI} = 5.5 V$ | | 900 | - | 900 | - | μA |
| BHHO | bus hold HIGH | A or B port | <u>[1][3]</u> | | | | | |
| | overdrive current | $V_{CCI} = 1.6 V$ | | -125 | - | -125 | - | μA |
| | Garrent | V _{CCI} = 1.95 V | | -200 | - | -200 | - | μA |
| | | $V_{CCI} = 2.7 V$ | | -300 | - | -300 | - | μA |
| | | $V_{CCI} = 3.6 V$ | | -500 | - | -500 | - | μΑ |
| | | $V_{CCI} = 5.5 V$ | | -900 | - | -900 | - | μA |
| OZ | OFF-state output current | A or B port; $V_0 = 0$ V or V_{CCO} ; $V_{CCO} = 1.2$ V to 5.5 V | [2] | - | ±2 | - | ±10 | μA |

Table 8. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

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| Symbol | Parameter | Conditions | | –40 °C t | o +85 °C | -40 °C to | o +125 °C | Unit |
|------------------|---------------------------------|--|------------|----------|----------|-----------|-----------|------|
| | | | | Min | Max | Min | Max | |
| I _{OFF} | power-off leakage current | A port; V ₁ or V ₀ = 0 V to 5.5 V; V _{CC(A)} = 0 V; V _{CC(B)} = 1.2 V to 5.5 V | ' | - | ±2 | - | ±10 | μA |
| | | B port; V ₁ or V ₀ = 0 V to 5.5 V; V _{CC(B)} = 0 V; V _{CC(A)} = 1.2 V to 5.5 V | | - | ±2 | - | ±10 | μΑ |
| I _{CC} | supply current | A port; $V_I = 0 V \text{ or } V_{CCI}$; $I_O = 0 A$ | [1] | | | | | |
| | | $V_{CC(A)}$, $V_{CC(B)}$ = 1.2 V to 5.5 V | | - | 8 | - | 8 | μΑ |
| | | $V_{CC(A)}$, $V_{CC(B)}$ = 1.65 V to 5.5 V | | - | 3 | - | 3 | μΑ |
| | | $V_{CC(A)} = 5.5 \text{ V}; V_{CC(B)} = 0 \text{ V}$ | | - | 2 | - | 2 | μA |
| | | $V_{CC(A)} = 0 V; V_{CC(B)} = 5.5 V$ | | -2 | - | -2 | - | μA |
| | | B port; $V_I = 0$ V or V_{CCI} ; $I_O = 0$ A | | | | | | |
| | | $V_{CC(A)}$, $V_{CC(B)}$ = 1.2 V to 5.5 V | | - | 8 | - | 8 | μA |
| | | $V_{CC(A)},~V_{CC(B)}$ = 1.65 V to 5.5 V | | - | 3 | - | 3 | μA |
| | | $V_{CC(B)} = 5.5 \text{ V}; V_{CC(A)} = 0 \text{ V}$ | | - | 2 | - | 2 | μA |
| | | $V_{CC(B)} = 0 V; V_{CC(A)} = 5.5 V$ | | -2 | - | -2 | - | μΑ |
| | | A plus B port ($I_{CC(A)} + I_{CC(B)}$); $I_O = 0$ A; $V_I = 0$ V or V_{CCI} | | | | | | |
| | | $V_{CC(A)}$, $V_{CC(B)} = 1.2$ V to 5.5 V | | - | 16 | - | 16 | μA |
| | | $V_{CC(A)}$, $V_{CC(B)}$ = 1.65 V to 5.5 V | | - | 4 | - | 4 | μA |
| ΔI_{CC} | additional | $V_{CC(A)},V_{CC(B)}$ = 3.0 V to 5.5 V | | | | | | |
| | supply current | A port; A port at $V_{CC(A)} - 0.6$ V; DIR at $V_{CC(A)}$; B port = open | <u>[4]</u> | - | 50 | - | 75 | μΑ |
| | | DIR input; DIR at $V_{CC(A)} - 0.6$ V; A port at $V_{CC(A)}$ or GND; B port = open | | - | 50 | - | 75 | μΑ |
| | | B port; B port at $V_{CC(B)} - 0.6$ V; DIR at GND; A port = open | <u>[4]</u> | - | 50 | - | 75 | μΑ |

Table 8. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

[1] V_{CCI} is the supply voltage associated with the data input port.

[2] V_{CCO} is the supply voltage associated with the output port.

[3] To guarantee the node switches, an external driver must source/sink at least I_{BHLO}/I_{BHHO} when the input is in the range V_{IL} to V_{IH} .

[4] For non bus hold parts only (74LVC1T45).

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11. Dynamic characteristics

Table 9.

Table 9.Typical dynamic characteristics at $V_{CC(A)} = 1.2$ V and $T_{amb} = 25$ °CVoltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for waveforms see <u>Figure 6</u> and <u>Figure 7</u>

| Symbol | Parameter | Conditions | | | Vco | C(B) | | | Unit |
|------------------|-------------------|--------------|-------|-------|-------|-------|-------|-------|------|
| | | | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V | |
| t _{PLH} | LOW to HIGH | A to B | 10.6 | 8.1 | 7.0 | 5.8 | 5.3 | 5.1 | ns |
| | propagation delay | B to A | 10.6 | 9.5 | 9.0 | 8.5 | 8.3 | 8.2 | ns |
| t _{PHL} | HIGH to LOW | A to B | 10.1 | 7.1 | 6.0 | 5.3 | 5.2 | 5.4 | ns |
| | propagation delay | B to A | 10.1 | 8.6 | 8.1 | 7.8 | 7.6 | 7.6 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 9.4 | 9.4 | 9.4 | 9.4 | 9.4 | 9.4 | ns |
| | propagation delay | DIR to B | 12.0 | 9.4 | 9.0 | 7.8 | 8.4 | 7.9 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 7.1 | 7.1 | 7.1 | 7.1 | 7.1 | 7.1 | ns |
| | propagation delay | DIR to B | 9.5 | 7.8 | 7.7 | 6.9 | 7.6 | 7.0 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A [1] | 20.1 | 17.3 | 16.7 | 15.4 | 15.9 | 15.2 | ns |
| | propagation delay | DIR to B [1] | 17.7 | 15.2 | 14.1 | 12.9 | 12.4 | 12.2 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A [1] | 22.1 | 18.0 | 17.1 | 15.6 | 16.0 | 15.5 | ns |
| | propagation delay | DIR to B [1] | 19.5 | 16.5 | 15.4 | 14.7 | 14.6 | 14.8 | ns |

[1] t_{PZH} and t_{PZL} are calculated values using the formula shown in Section 14.4 "Enable times"

Table 10. Typical dynamic characteristics at $V_{CC(B)}$ = 1.2 V and T_{amb} = 25 $^{\circ}C$ Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | | | V | CC(A) | | | Unit |
|------------------|-------------------|------------|------|---------|-------|-------|-------|-------|------|
| | | | 1.2 | V 1.5 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V | |
| t _{PLH} | LOW to HIGH | A to B | 10.6 | 9.5 | 9.0 | 8.5 | 8.3 | 8.2 | ns |
| | propagation delay | B to A | 10.6 | 8.1 | 7.0 | 5.8 | 5.3 | 5.1 | ns |
| t _{PHL} | HIGH to LOW | A to B | 10.1 | 8.6 | 8.1 | 7.8 | 7.6 | 7.6 | ns |
| | propagation delay | B to A | 10.1 | 7.1 | 6.0 | 5.3 | 5.2 | 5.4 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 9.4 | 6.5 | 5.7 | 4.1 | 4.1 | 3.0 | ns |
| | propagation delay | DIR to B | 12.0 |) 6.1 | 5.4 | 4.6 | 4.3 | 4.0 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 7.1 | 4.9 | 4.5 | 3.2 | 3.4 | 2.5 | ns |
| | propagation delay | DIR to B | 9.5 | 7.3 | 6.6 | 5.9 | 5.7 | 5.6 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A | 20.1 | 15.4 | 13.6 | 11.7 | 11.0 | 10.7 | ns |
| | propagation delay | DIR to B | 17.7 | 7 14.4 | 13.5 | 11.7 | 11.7 | 10.7 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A | 22. | 13.2 | 11.4 | 9.9 | 9.5 | 9.4 | ns |
| | propagation delay | DIR to B | 19.8 | 5 15.1 | 13.8 | 11.9 | 11.7 | 10.6 | ns |

[1] t_{PZH} and t_{PZL} are calculated values using the formula shown in Section 14.4 "Enable times"

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| Symbol | Parameter | Conditions | | V _{CC(A)} ar | nd V _{CC(B)} | | Unit |
|-----------------|-------------------------------|---|-------|-----------------------|-----------------------|-------|------|
| | | | 1.8 V | 2.5 V | 3.3 V | 5.5 V | |
| C _{PD} | power dissipation capacitance | A port: (direction A to B); B port: (direction B to A) | 2 | 3 | 3 | 4 | pF |
| | | A port: (direction B to A); B port: (direction A to B) | 15 | 16 | 16 | 18 | pF |

Table 11. Typical power dissipation capacitance at $V_{CC(A)} = V_{CC(B)}$ and $T_{amb} = 25 \text{ °C}$ [1][2] *Voltages are referenced to GND (ground = 0 V).*

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:

 f_i = input frequency in MHz;

 $f_o = output frequency in MHz;$

 C_L = load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

 $\label{eq:constraint} \mbox{[2]} \quad f_i = 10 \mbox{ MHz; } V_I = GND \mbox{ to } V_{CC}; \mbox{ } t_r = t_f = 1 \mbox{ ns; } C_L = 0 \mbox{ pF; } R_L = \infty \ \Omega.$

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | | | | | Vcc | C(B) | | | | | Unit |
|----------------------|-------------------|--------------|---------|---------|---------|--------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.5 V ± | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V = | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = | 1.4 V to 1.6 V | | | | | | | | | | | | |
| t _{PLH} | LOW to HIGH | A to B | 2.8 | 21.3 | 2.4 | 17.6 | 2.0 | 13.5 | 1.7 | 11.8 | 1.6 | 10.5 | ns |
| | propagation delay | B to A | 2.8 | 21.3 | 2.6 | 19.1 | 2.3 | 14.9 | 2.3 | 12.4 | 2.2 | 12.0 | ns |
| t _{PHL} | HIGH to LOW | A to B | 2.6 | 19.3 | 2.2 | 15.3 | 1.8 | 11.8 | 1.7 | 10.9 | 1.7 | 10.8 | ns |
| | propagation delay | B to A | 2.6 | 19.3 | 2.4 | 17.3 | 2.3 | 13.2 | 2.2 | 11.3 | 2.3 | 11.0 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | 3.0 | 18.7 | ns |
| | propagation delay | DIR to B | 3.5 | 24.8 | 3.5 | 23.6 | 3.0 | 11.0 | 3.3 | 11.3 | 2.8 | 10.3 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | 2.4 | 11.4 | ns |
| | propagation delay | DIR to B | 2.8 | 18.3 | 3.0 | 17.2 | 2.5 | 9.4 | 3.0 | 10.1 | 2.5 | 9.4 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A [1] | - | 39.6 | - | 36.3 | - | 24.3 | - | 22.5 | - | 21.4 | ns |
| | propagation delay | DIR to B [1] | - | 32.7 | - | 29.0 | - | 24.9 | - | 23.2 | - | 21.9 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A [1] | - | 44.1 | - | 40.9 | - | 24.2 | - | 22.6 | - | 21.3 | ns |
| | propagation delay | DIR to B [1] | - | 38.0 | - | 34.0 | - | 30.5 | - | 29.6 | - | 29.5 | ns |
| $V_{CC(A)} =$ | 1.65 V to 1.95 V | | | | | | | | | | | | |
| t _{PLH} | LOW to HIGH | A to B | 2.6 | 19.1 | 2.2 | 17.7 | 2.2 | 9.3 | 1.7 | 7.2 | 1.4 | 6.8 | ns |
| | propagation delay | B to A | 2.4 | 17.6 | 2.2 | 17.7 | 2.3 | 16.0 | 2.1 | 15.5 | 1.9 | 15.1 | ns |
| t _{PHL} | HIGH to LOW | A to B | 2.4 | 17.3 | 2.0 | 14.3 | 1.6 | 8.5 | 1.8 | 7.1 | 1.7 | 7.0 | ns |
| | propagation delay | B to A | 2.2 | 15.3 | 2.0 | 14.3 | 2.1 | 12.9 | 2.0 | 12.6 | 1.8 | 12.2 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | 2.9 | 17.1 | ns |
| | propagation delay | DIR to B | 3.2 | 24.1 | 3.2 | 21.9 | 2.7 | 11.5 | 3.0 | 10.3 | 2.5 | 8.2 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | 2.4 | 10.5 | ns |
| | propagation delay | DIR to B | 2.5 | 17.6 | 2.6 | 16.0 | 2.2 | 9.2 | 2.7 | 8.4 | 2.4 | 6.4 | ns |

Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditio | าร | | | | | Vcc | С(В) | | | | | Uni |
|----------------------|-------------------------------------|----------|-------------|---------|---------|--------------------|----------|-----|------|----------|---------|---------|---------|-----|
| | | | | 1.5 V : | ± 0.1 V | 1.8 V 1 | : 0.15 V | - | | 3.3 V : | ± 0.3 V | 5.0 V - | E 0.5 V | 1 |
| | | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| PZH | OFF-state to HIGH | DIR to A | <u>[1]</u> | - | 35.2 | - | 33.7 | - | 25.2 | - | 23.9 | - | 21.8 | ns |
| | propagation delay | DIR to B | [1] | - | 29.6 | - | 28.2 | - | 19.8 | - | 17.7 | - | 17.3 | ns |
| PZL | OFF-state to LOW | DIR to A | [1] | - | 39.4 | - | 36.2 | - | 24.4 | - | 22.9 | - | 20.4 | ns |
| | propagation delay | DIR to B | [1] | - | 34.4 | - | 31.4 | - | 25.6 | - | 24.2 | - | 24.1 | ns |
| V _{CC(A)} = | 2.3 V to 2.7 V | | | | | | | | | | | | | |
| PLH | LOW to HIGH | A to B | | 2.3 | 17.9 | 2.3 | 16.0 | 1.5 | 8.5 | 1.3 | 6.2 | 1.1 | 4.8 | ns |
| | propagation delay | B to A | | 2.0 | 13.5 | 2.2 | 9.3 | 1.5 | 8.5 | 1.4 | 8.0 | 1.0 | 7.5 | ns |
| PHL | HIGH to LOW | A to B | | 2.3 | 15.8 | 2.1 | 12.9 | 1.4 | 7.5 | 1.3 | 5.4 | 0.9 | 4.6 | ns |
| | propagation delay | B to A | | 1.8 | 11.8 | 1.9 | 8.5 | 1.4 | 7.5 | 1.3 | 7.0 | 0.9 | 6.2 | ns |
| PHZ | HIGH to OFF-state | DIR to A | | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | 2.1 | 8.1 | ns |
| | propagation delay | DIR to B | | 3.0 | 22.5 | 3.0 | 21.4 | 2.5 | 11.0 | 2.8 | 9.3 | 2.3 | 6.9 | ns |
| PLZ | LOW to OFF-state | DIR to A | | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | 1.7 | 5.8 | ns |
| | propagation delay | DIR to B | | 2.3 | 14.6 | 2.5 | 13.2 | 2.0 | 9.0 | 2.5 | 8.4 | 1.8 | 5.3 | ns |
| PZH | OFF-state to HIGH | DIR to A | [1] | - | 28.1 | - | 22.5 | - | 17.5 | - | 16.4 | - | 12.8 | ns |
| | propagation delay | DIR to B | [1] | - | 23.7 | - | 21.8 | - | 14.3 | - | 12.0 | - | 10.6 | ns |
| PZL | OFF-state to LOW | DIR to A | [1] | - | 34.3 | - | 29.9 | - | 18.5 | - | 16.3 | - | 13.1 | ns |
| | propagation delay | DIR to B | [1] | - | 23.9 | - | 21.0 | - | 15.6 | - | 13.5 | - | 12.7 | ns |
| V _{CC(A)} = | 3.0 V to 3.6 V | | | | | | | | | | | | | |
| PLH | LOW to HIGH | A to B | | 2.3 | 17.1 | 2.1 | 15.5 | 1.4 | 8.0 | 0.8 | 5.6 | 0.7 | 4.4 | ns |
| | propagation delay | B to A | | 1.7 | 11.8 | 1.7 | 7.2 | 1.3 | 6.2 | 0.7 | 5.6 | 0.6 | 5.4 | ns |
| PHL | HIGH to LOW | A to B | | 2.2 | 15.6 | 2.0 | 12.6 | 1.3 | 7.0 | 0.8 | 5.0 | 0.7 | 4.0 | ns |
| | propagation delay | B to A | | 1.7 | 10.9 | 1.8 | 7.1 | 1.3 | 5.4 | 0.8 | 5.0 | 0.7 | 4.5 | ns |
| PHZ | HIGH to OFF-state | DIR to A | | 2.3 | 7.3 | 2.3 | 7.3 | 2.3 | 7.3 | 2.3 | 7.3 | 2.7 | 7.3 | ns |
| | propagation delay | DIR to B | | 2.9 | 18.0 | 2.9 | 16.5 | 2.3 | 10.1 | 2.7 | 8.6 | 2.2 | 6.3 | ns |
| PLZ | LOW to OFF-state propagation delay | DIR to A | | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | 2.0 | 5.6 | ns |
| | | DIR to B | | 2.3 | 13.6 | 2.4 | 12.5 | 1.9 | 7.8 | 2.3 | 7.1 | 1.7 | 4.9 | ns |
| PZH | OFF-state to HIGH propagation delay | DIR to A | [<u>1]</u> | - | 25.4 | - | 19.7 | - | 14.0 | - | 12.7 | - | 10.3 | ns |
| | | DIR to B | [1] | - | 22.7 | - | 21.1 | - | 13.6 | - | 11.2 | - | 10.0 | ns |
| PZL | OFF-state to LOW propagation delay | DIR to A | [1] | - | 28.9 | - | 23.6 | - | 15.5 | - | 13.6 | - | 10.8 | ns |
| | | DIR to B | [1] | - | 22.9 | - | 19.9 | - | 14.3 | - | 12.3 | - | 11.3 | ns |
| | 4.5 V to 5.5 V | | | 0.0 | 46.5 | 4.0 | 45 4 | 4.0 | | <u> </u> | | 0 - | • • | |
| PLH | LOW to HIGH propagation delay | A to B | | 2.2 | 16.6 | 1.9 | 15.1 | 1.0 | 7.5 | 0.7 | 5.4 | 0.5 | 3.9 | ns |
| | | B to A | | 1.6 | 10.5 | 1.4 | 6.8 | 1.0 | 4.8 | 0.7 | 4.4 | 0.5 | 3.9 | ns |
| PHL | HIGH to LOW propagation delay | A to B | | 2.3 | 15.3 | 1.8 | 12.2 | 1.0 | 6.2 | 0.7 | 4.5 | 0.5 | 3.5 | ns |
| | | B to A | | 1.7 | 10.8 | 1.7 | 7.0 | 0.9 | 4.6 | 0.7 | 4.0 | 0.5 | 3.5 | ns |
| PHZ | HIGH to OFF-state propagation delay | DIR to A | | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | 1.7 | 5.4 | ns |
| | propagation delay | DIR to B | | 2.9 | 17.3 | 2.9 | 16.1 | 2.3 | 9.7 | 2.7 | 8.0 | 2.5 | 5.7 | ns |

Table 12. Dynamic characteristics for temperature range $-40 \degree$ C to $+85 \degree$ C ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure

Dual supply translating transceiver; 3-state

| Symbol | Parameter | Conditions | | | | | Vcc | ;(B) | | | | | Unit |
|------------------|-------------------|--------------|---------|---------|---------|--------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.5 V ± | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V ± | ± 0.2 V | 3.3 V ± | E 0.3 V | 5.0 V ± | : 0.5 V | |
| | | | Min | Max | Min | Мах | Min | Мах | Min | Max | Min | Max | |
| t _{PLZ} | LOW to OFF-state | DIR to A | 1.4 | 3.7 | 1.4 | 3.7 | 1.3 | 3.7 | 1.0 | 3.7 | 0.9 | 3.7 | ns |
| | propagation delay | DIR to B | 2.3 | 13.1 | 2.4 | 12.1 | 1.9 | 7.4 | 2.3 | 7.0 | 1.8 | 4.5 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A [1] | - | 23.6 | - | 18.9 | - | 12.2 | - | 11.4 | - | 8.4 | ns |
| | propagation delay | DIR to B [1] | - | 20.3 | - | 18.8 | - | 11.2 | - | 9.1 | - | 7.6 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A [1] | - | 28.1 | - | 23.1 | - | 14.3 | - | 12.0 | - | 9.2 | ns |
| | propagation delay | DIR to B 🛄 | - | 20.7 | - | 17.6 | - | 11.6 | - | 9.9 | - | 8.9 | ns |

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C ... continued Voltages are referenced to GND (ground = 0 V): for test circuit see Figure 8: for wave forms see Figure 6 and Figure 7

[1] t_{PZH} and t_{PZL} are calculated values using the formula shown in Section 14.4 "Enable times"

Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

| Symbol | Parameter | Conditions | | | | | Vcc | ;(B) | | | | | Unit |
|------------------|-------------------|--------------|---------|---------|---------|--------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.5 V : | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V ± | E 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} =$ | 1.4 V to 1.6 V | 1 | | | | | | | | | | | |
| t _{PLH} | LOW to HIGH | A to B | 2.5 | 23.5 | 2.1 | 19.4 | 1.8 | 14.9 | 1.5 | 13.0 | 1.4 | 11.6 | ns |
| | propagation delay | B to A | 2.5 | 23.5 | 2.3 | 21.1 | 2.0 | 16.4 | 2.0 | 13.7 | 1.9 | 13.2 | ns |
| t _{PHL} | HIGH to LOW | A to B | 2.3 | 21.3 | 1.9 | 16.9 | 1.6 | 13.0 | 1.5 | 12.0 | 1.5 | 11.9 | ns |
| | propagation delay | B to A | 2.3 | 21.3 | 2.1 | 19.1 | 2.0 | 14.6 | 1.9 | 12.5 | 2.0 | 12.1 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | 2.7 | 20.6 | ns |
| | propagation delay | DIR to B | 3.1 | 27.3 | 3.1 | 26.0 | 2.7 | 12.1 | 2.9 | 12.5 | 2.5 | 11.4 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | 2.1 | 12.6 | ns |
| | propagation delay | DIR to B | 2.5 | 20.2 | 2.7 | 19.0 | 2.2 | 10.4 | 2.7 | 11.2 | 2.2 | 10.4 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A [1] | - | 43.7 | - | 40.1 | - | 26.8 | - | 24.9 | - | 23.6 | ns |
| | propagation delay | DIR to B [1] | - | 36.1 | - | 32.0 | - | 27.5 | - | 25.6 | - | 24.2 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A [1] | - | 48.6 | - | 45.1 | - | 26.7 | - | 25.0 | - | 23.5 | ns |
| | propagation delay | DIR to B [1] | - | 41.9 | - | 37.5 | - | 33.6 | - | 32.6 | - | 32.5 | ns |
| $V_{CC(A)} =$ | 1.65 V to 1.95 V | | | | | | | | | | | | |
| t _{PLH} | LOW to HIGH | A to B | 2.3 | 21.1 | 1.9 | 19.5 | 1.9 | 10.3 | 1.5 | 8.0 | 1.2 | 7.5 | ns |
| | propagation delay | B to A | 2.1 | 19.4 | 1.9 | 19.5 | 2.0 | 17.6 | 1.8 | 17.1 | 1.7 | 16.7 | ns |
| t _{PHL} | HIGH to LOW | A to B | 2.1 | 19.1 | 1.8 | 15.8 | 1.4 | 9.4 | 1.6 | 7.9 | 1.5 | 7.7 | ns |
| | propagation delay | B to A | 1.9 | 16.9 | 1.8 | 15.8 | 1.8 | 14.2 | 1.8 | 13.9 | 1.6 | 13.5 | ns |
| t _{PHZ} | HIGH to OFF-state | DIR to A | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | 2.6 | 18.9 | ns |
| | propagation delay | DIR to B | 2.8 | 26.6 | 2.8 | 24.1 | 2.4 | 12.7 | 2.7 | 11.4 | 2.2 | 9.1 | ns |
| t _{PLZ} | LOW to OFF-state | DIR to A | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | 2.1 | 11.6 | ns |
| | propagation delay | DIR to B | 2.2 | 19.4 | 2.3 | 17.6 | 1.9 | 10.2 | 2.4 | 9.3 | 2.1 | 7.4 | ns |
| t _{PZH} | OFF-state to HIGH | DIR to A [1] | - | 38.8 | - | 37.1 | - | 27.8 | - | 26.4 | - | 24.1 | ns |
| | propagation delay | DIR to B [1] | - | 32.7 | - | 31.1 | - | 21.9 | - | 19.6 | - | 19.1 | ns |

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| Symbol | Parameter | Conditions | | | | | Vcc | (В) | | | | | Uni |
|----------------------|-------------------|--------------|-------|---------|---------|--------|---------|------|---------|---------|---------|---------|-----|
| | | | 1.5 V | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V : | | 3.3 V : | ± 0.3 V | 5.0 V - | ± 0.5 V | - |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | - |
| PZL | OFF-state to LOW | DIR to A [1] | - | 43.5 | - | 39.9 | - | 26.9 | - | 25.3 | - | 22.6 | ns |
| | propagation delay | DIR to B [1] | - | 38.0 | - | 34.7 | - | 28.3 | - | 26.8 | - | 26.6 | ns |
| V _{CC(A)} = | 2.3 V to 2.7 V | | | | | | | | | | | | |
| t _{PLH} | LOW to HIGH | A to B | 2.0 | 19.7 | 2.0 | 17.6 | 1.3 | 9.4 | 1.1 | 6.9 | 0.9 | 5.3 | ns |
| | propagation delay | B to A | 1.8 | 14.9 | 1.9 | 10.3 | 1.3 | 9.4 | 1.2 | 8.8 | 0.9 | 8.3 | ns |
| PHL | HIGH to LOW | A to B | 2.0 | 17.4 | 1.8 | 14.2 | 1.2 | 8.3 | 1.1 | 6.0 | 0.8 | 5.1 | ns |
| | propagation delay | B to A | 1.6 | 13.0 | 1.7 | 9.4 | 1.2 | 8.3 | 1.1 | 7.7 | 0.8 | 6.9 | ns |
| PHZ | HIGH to OFF-state | DIR to A | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | 1.8 | 9.0 | ns |
| | propagation delay | DIR to B | 2.7 | 24.8 | 2.7 | 23.6 | 2.2 | 12.1 | 2.5 | 10.3 | 2.0 | 7.6 | ns |
| PLZ | LOW to OFF-state | DIR to A | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | 1.5 | 6.4 | ns |
| | propagation delay | DIR to B | 2.0 | 16.1 | 2.2 | 14.6 | 1.8 | 9.9 | 2.2 | 9.3 | 1.6 | 5.9 | ns |
| PZH | OFF-state to HIGH | DIR to A [1] | - | 31.0 | - | 24.9 | - | 19.3 | - | 18.1 | - | 14.2 | ns |
| | propagation delay | DIR to B | - | 26.1 | - | 24.0 | - | 15.8 | - | 13.3 | - | 11.7 | ns |
| PZL | OFF-state to LOW | DIR to A [1] | - | 37.8 | - | 33.0 | - | 20.4 | - | 18.0 | - | 14.5 | ns |
| | propagation delay | DIR to B | - | 26.4 | - | 23.2 | - | 17.3 | - | 15.0 | - | 14.1 | ns |
| / _{CC(A)} = | 3.0 V to 3.6 V | | | | | | | | | | | | |
| PLH | LOW to HIGH | A to B | 2.0 | 18.9 | 1.8 | 17.1 | 1.2 | 8.8 | 0.7 | 6.2 | 0.6 | 4.9 | ns |
| | propagation delay | B to A | 1.5 | 13.0 | 1.5 | 8.0 | 1.1 | 6.9 | 0.6 | 6.2 | 0.5 | 6.0 | ns |
| PHL | HIGH to LOW | A to B | 1.9 | 17.2 | 1.8 | 13.9 | 1.1 | 7.7 | 0.7 | 5.5 | 0.6 | 4.4 | ns |
| | propagation delay | B to A | 1.5 | 12.0 | 1.6 | 7.9 | 1.1 | 6.0 | 0.7 | 5.5 | 0.6 | 5.0 | ns |
| PHZ | HIGH to OFF-state | DIR to A | 2.0 | 8.1 | 2.0 | 8.1 | 2.0 | 8.1 | 2.0 | 8.1 | 2.4 | 8.1 | ns |
| | propagation delay | DIR to B | 2.6 | 19.8 | 2.6 | 18.2 | 2.0 | 11.2 | 2.4 | 9.5 | 1.9 | 7.0 | ns |
| PLZ | LOW to OFF-state | DIR to A | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | 1.8 | 6.2 | ns |
| | propagation delay | DIR to B | 2.0 | 15.0 | 2.1 | 13.8 | 1.7 | 8.6 | 2.0 | 7.9 | 1.5 | 5.4 | ns |
| PZH | OFF-state to HIGH | DIR to A [1] | - | 28.0 | - | 21.8 | - | 15.5 | - | 14.1 | - | 11.4 | ns |
| | propagation delay | DIR to B [1] | - | 25.1 | - | 23.3 | - | 15.0 | - | 12.4 | - | 11.1 | ns |
| PZL | OFF-state to LOW | DIR to A [1] | - | 31.8 | - | 26.1 | - | 17.2 | - | 15.0 | - | 12.0 | ns |
| | propagation delay | DIR to B [1] | - | 25.3 | - | 22.0 | - | 15.8 | - | 13.6 | - | 12.5 | ns |
| $V_{CC(A)} =$ | 4.5 V to 5.5 V | | | | | | | | | | | | |
| PLH | LOW to HIGH | A to B | 1.9 | 18.3 | 1.7 | 16.7 | 0.9 | 8.3 | 0.6 | 6.0 | 0.4 | 4.3 | ns |
| | propagation delay | B to A | 1.4 | 11.6 | 1.2 | 7.5 | 0.9 | 5.3 | 0.6 | 4.9 | 0.4 | 4.3 | ns |
| PHL | HIGH to LOW | A to B | 2.0 | 16.9 | 1.6 | 13.5 | 0.9 | 6.9 | 0.6 | 5.0 | 0.4 | 3.9 | ns |
| | propagation delay | B to A | 1.5 | 11.9 | 1.5 | 7.7 | 0.8 | 5.1 | 0.6 | 4.4 | 0.4 | 3.9 | ns |
| PHZ | HIGH to OFF-state | DIR to A | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | 1.5 | 6.0 | ns |
| | propagation delay | DIR to B | 2.6 | 19.1 | 2.6 | 17.8 | 2.0 | 10.7 | 2.4 | 8.8 | 2.2 | 6.3 | ns |
| PLZ | LOW to OFF-state | DIR to A | 1.2 | 4.1 | 1.2 | 4.1 | 1.1 | 4.1 | 0.9 | 4.1 | 0.8 | 4.1 | ns |
| | propagation delay | DIR to B | 2.0 | 14.5 | 2.1 | 13.4 | 1.7 | 8.2 | 2.0 | 7.7 | 1.6 | 5.0 | ns |

 Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C ...continued

 Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure

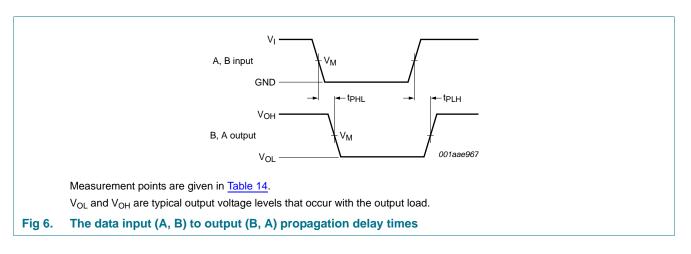
Dual supply translating transceiver; 3-state

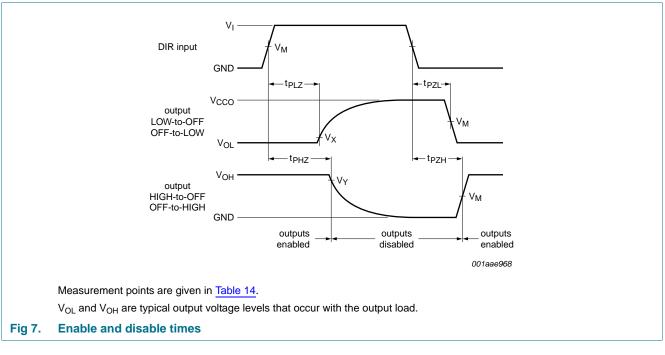
| Symbol | Parameter | Conditions | | | | | Vcc | с(В) | | | | | Unit |
|------------------|-------------------|------------|-------|---------|---------|--------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.5 V | ± 0.1 V | 1.8 V ± | 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V ± | E 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{PZH} | OFF-state to HIGH | DIR to A | 1 - | 26.1 | - | 20.9 | - | 13.5 | - | 12.6 | - | 9.3 | ns |
| | propagation delay | DIR to B | 1 - | 22.4 | - | 20.8 | - | 12.4 | - | 10.1 | - | 8.4 | ns |
| t _{PZL} | OFF-state to LOW | DIR to A | 1 - | 31.0 | - | 25.5 | - | 15.8 | - | 13.2 | - | 10.2 | ns |
| | propagation delay | DIR to B |] | 22.9 | - | 19.5 | - | 12.9 | - | 11.0 | - | 9.9 | ns |

Table 13 Dynamic characteristics for temperature range -40 °C to +125 °C continued

[1] t_{PZH} and t_{PZL} are calculated values using the formula shown in Section 14.4 "Enable times"

12. Waveforms





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Table 14.Measurement points

| Supply voltage | Input ^[1] | Output ^[2] | | |
|---|----------------------|-----------------------|--------------------------|--------------------------|
| V _{CC(A)} , V _{CC(B)} | V _M | V _M | V _X | V _Y |
| 1.2 V to 1.6 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.1 V | V _{OH} – 0.1 V |
| 1.65 V to 2.7 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} – 0.15 V |
| 3.0 V to 5.5 V | 0.5V _{CCI} | $0.5V_{CCO}$ | V _{OL} + 0.3 V | V _{OH} – 0.3 V |

[1] V_{CCI} is the supply voltage associated with the data input port.

[2] $\,\,$ V_{CCO} is the supply voltage associated with the output port.

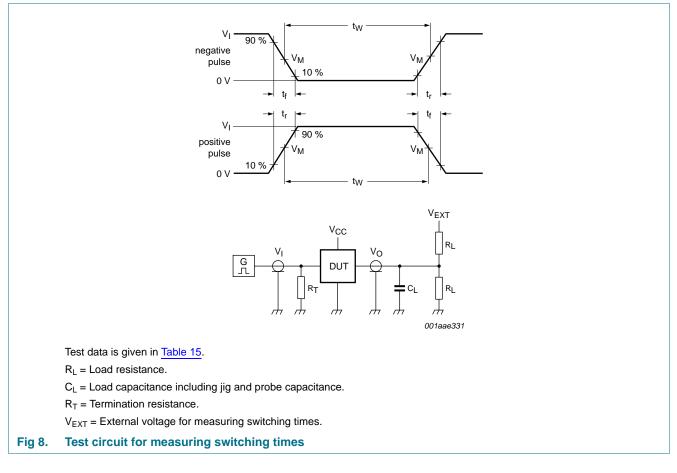


Table 15. Test data

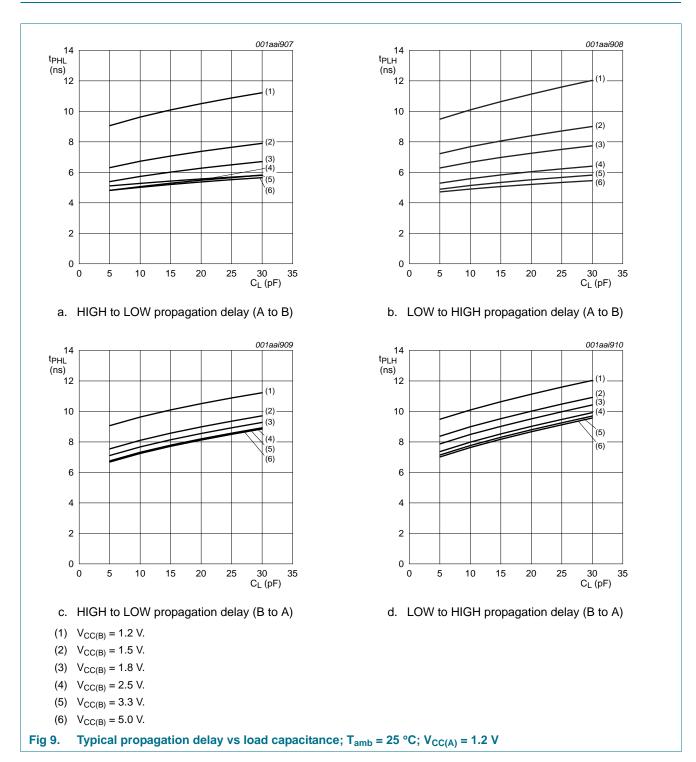
| Supply voltage | Input | | Load | | V _{EXT} | | |
|---|------------------|----------------------|-------|------|-------------------------------------|-------------------------------------|---|
| V _{CC(A)} , V _{CC(B)} | V [1] | Δt/ΔV ^[2] | CL | RL | t _{PLH} , t _{PHL} | t _{PZH} , t _{PHZ} | t _{PZL} , t _{PLZ} [3] |
| 1.2 V to 5.5 V | V _{CCI} | \leq 1.0 ns/V | 15 pF | 2 kΩ | open | GND | 2V _{CCO} |

[1] V_{CCI} is the supply voltage associated with the data input port.

[2] $dV/dt \ge 1.0 V/ns$

[3] V_{CCO} is the supply voltage associated with the output port.

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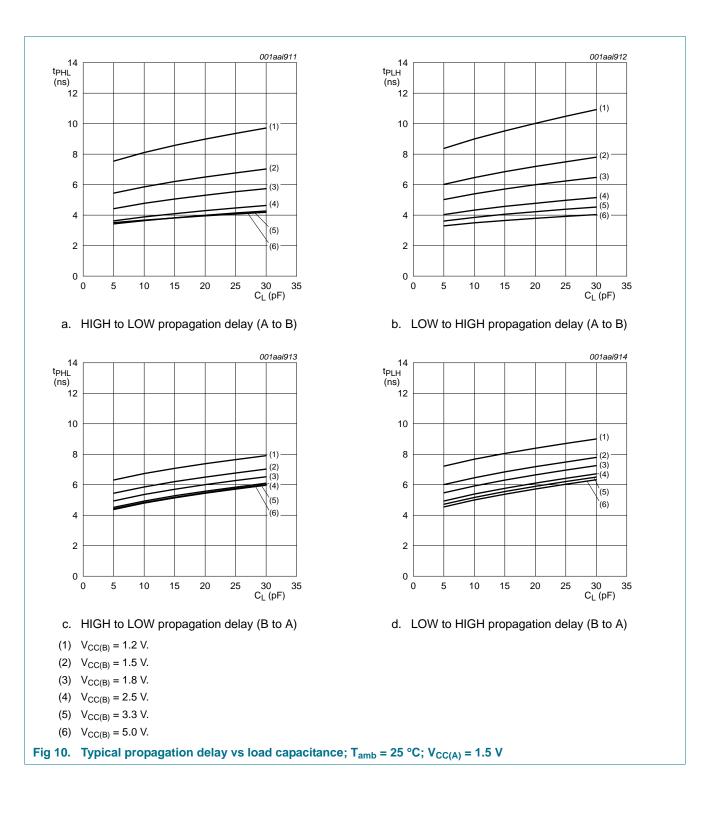


13. Typical propagation delay characteristics

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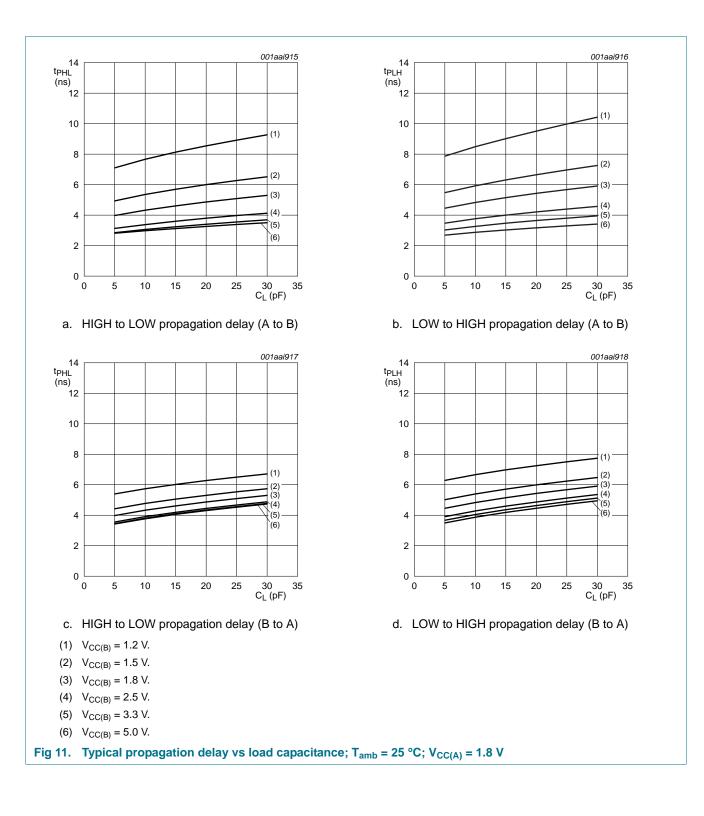
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74LVC1T45; 74LVCH1T45

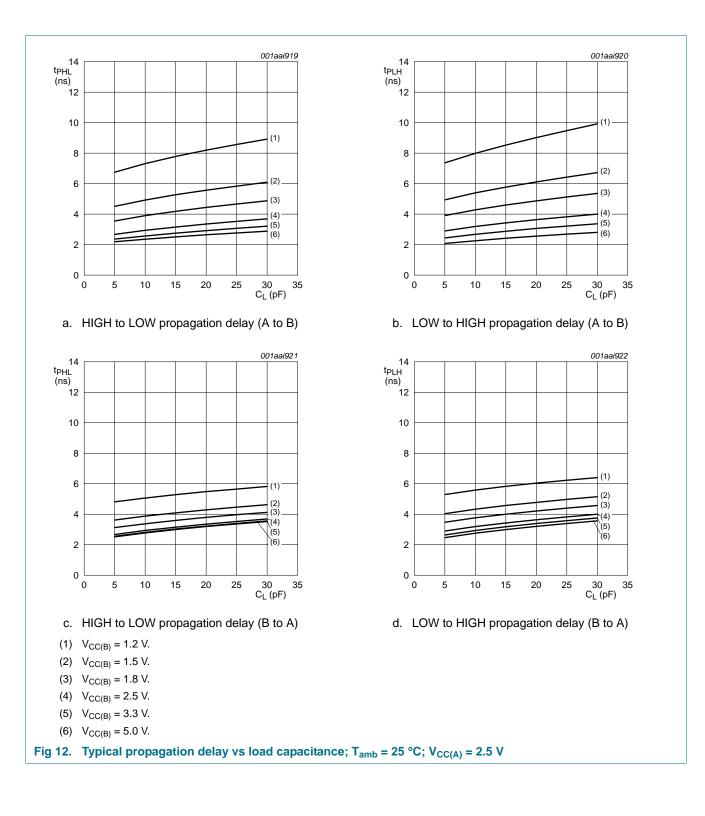
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74LVC_LVCH1T45

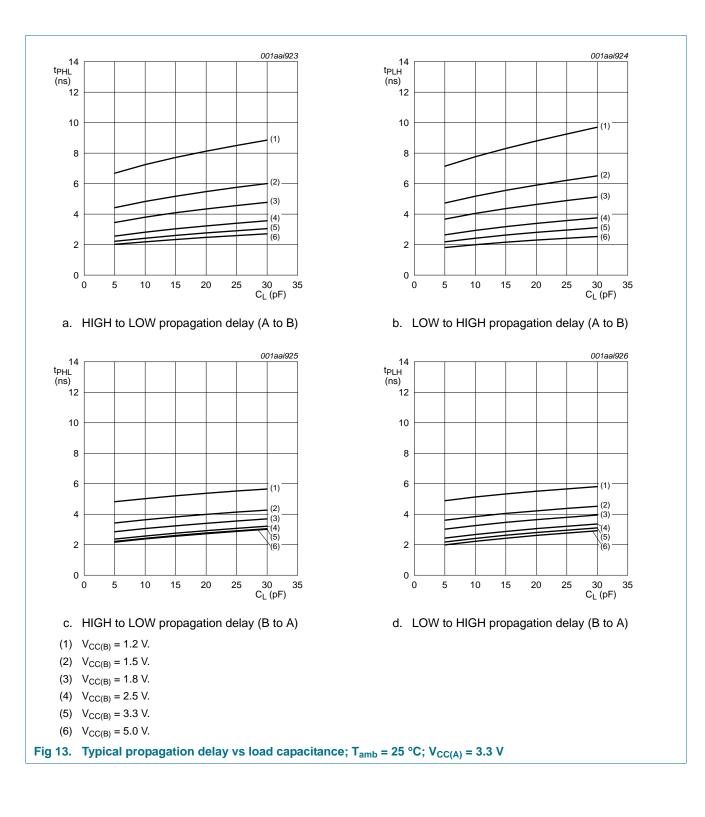
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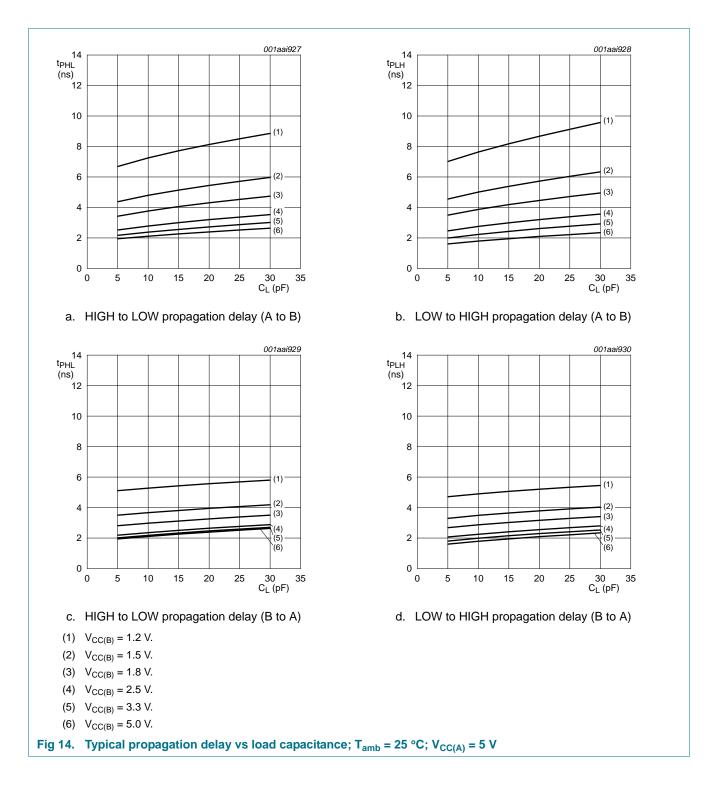
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14. Application information

14.1 Unidirectional logic level-shifting application

The circuit given in <u>Figure 15</u> is an example of the 74LVC1T45; 74LVCH1T45 being used in a unidirectional logic level-shifting application.

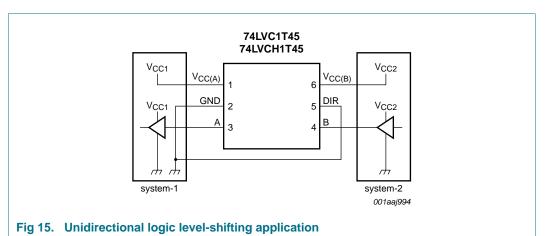


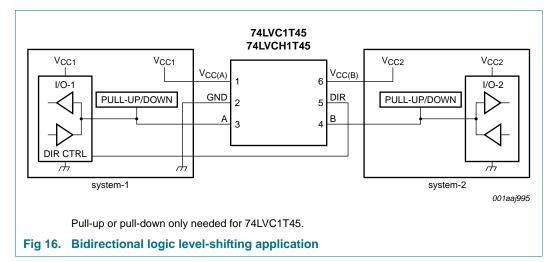
Table 16. Description unidirectional logic level-shifting application

| | - | | • • • • • |
|-----|--------------------|------------------|---|
| Pin | Name | Function | Description |
| 1 | V _{CC(A)} | V _{CC1} | supply voltage of system-1 (1.2 V to 5.5 V) |
| 2 | GND | GND | device GND |
| 3 | А | OUT | output level depends on V_{CC1} voltage |
| 4 | В | IN | input threshold value depends on V_{CC2} voltage |
| 5 | DIR | DIR | the GND (LOW level) determines B port to A port direction |
| 6 | V _{CC(B)} | V _{CC2} | supply voltage of system-2 (1.2 V to 5.5 V) |

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14.2 Bidirectional logic level-shifting application

Figure 16 shows the 74LVC1T45; 74LVCH1T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.



<u>Table 17</u> provides a sequence that illustrates data transmission from system-1 to system-2 and then from system-2 to system-1.

| State | DIR CTRL | I/O-1 | I/O-2 | Description |
|-------|----------|--------|--------|---|
| 1 | Н | output | input | system-1 data to system-2 |
| 2 | Η | Z | Z | system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold. |
| 3 | L | Z | Z | DIR bit is set LOW. I/O-1 and I/O-2 are still disabled. The bus-line state depends on bus hold. |
| 4 | L | input | output | system-2 data to system-1 |

Table 17. Description bidirectional logic level-shifting application^[1]

[1] H = HIGH voltage level;

L = LOW voltage level;

Z = high-impedance OFF-state.

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14.3 Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

| V _{CC(A)} | V _{CC(B)} | V _{CC(B)} | | | | | |
|--------------------|--------------------|--------------------|-------|-------|-------|----|--|
| | 0 V | 1.8 V | 2.5 V | 3.3 V | 5.0 V | | |
| 0 V | 0 | < 1 | < 1 | < 1 | < 1 | μA | |
| 1.8 V | < 1 | < 2 | < 2 | < 2 | 2 | μA | |
| 2.5 V | < 1 | < 2 | < 2 | < 2 | < 2 | μA | |
| 3.3 V | < 1 | < 2 | < 2 | < 2 | < 2 | μA | |
| 5.0 V | < 1 | 2 | < 2 | < 2 | < 2 | μA | |

Table 18. Typical total supply current (I_{CC(A)} + I_{CC(B)})

14.4 Enable times

Calculate the enable times for the 74LVC1T45; 74LVCH1T45 using the following formulas:

- t_{PZH} (DIR to A) = t_{PLZ} (DIR to B) + t_{PLH} (B to A)
- t_{PZL} (DIR to A) = t_{PHZ} (DIR to B) + t_{PHL} (B to A)
- t_{PZH} (DIR to B) = t_{PLZ} (DIR to A) + t_{PLH} (A to B)
- t_{PZL} (DIR to B) = t_{PHZ} (DIR to A) + t_{PHL} (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74LVC1T45; 74LVCH1T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

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15. Package outline

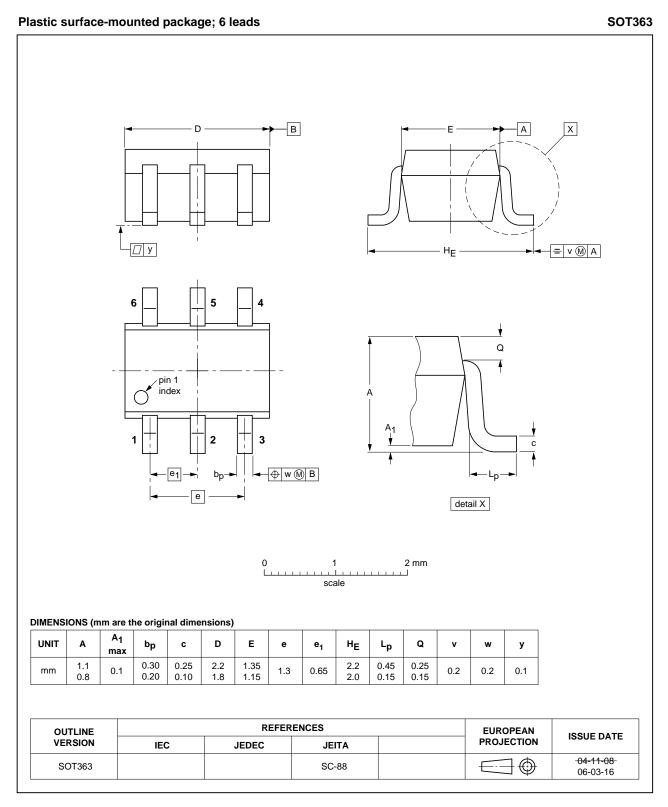


Fig 17. Package outline SOT363 (SC-88)

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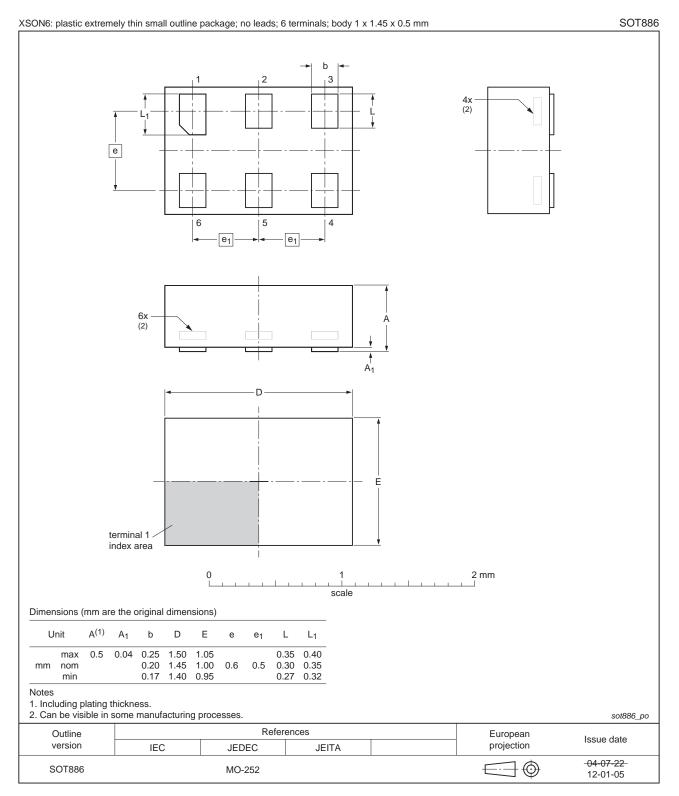


Fig 18. Package outline SOT886 (XSON6)

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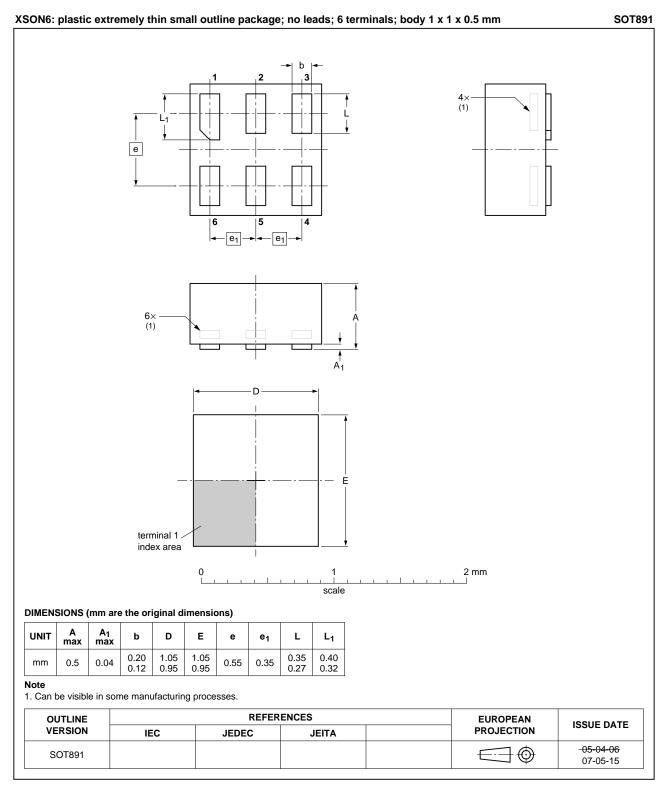
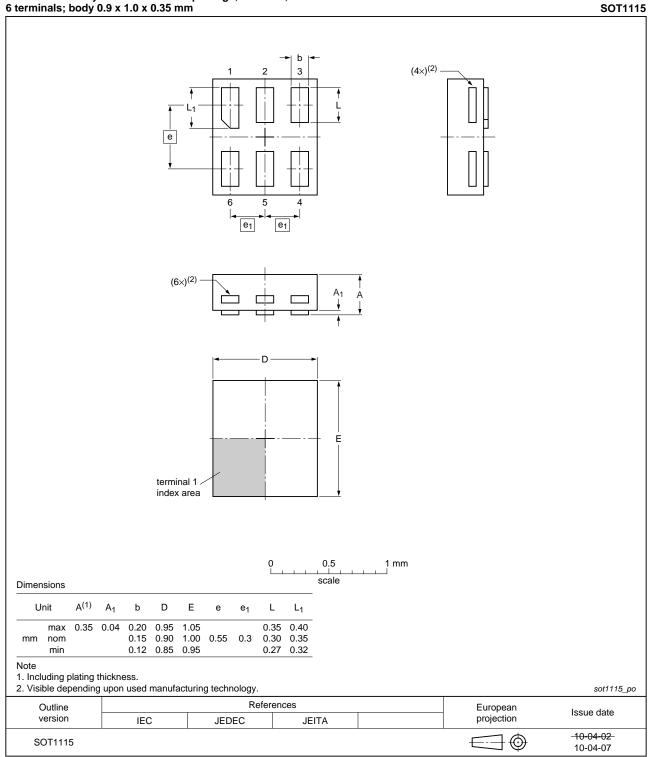


Fig 19. Package outline SOT891 (XSON6)

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XSON6: extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm

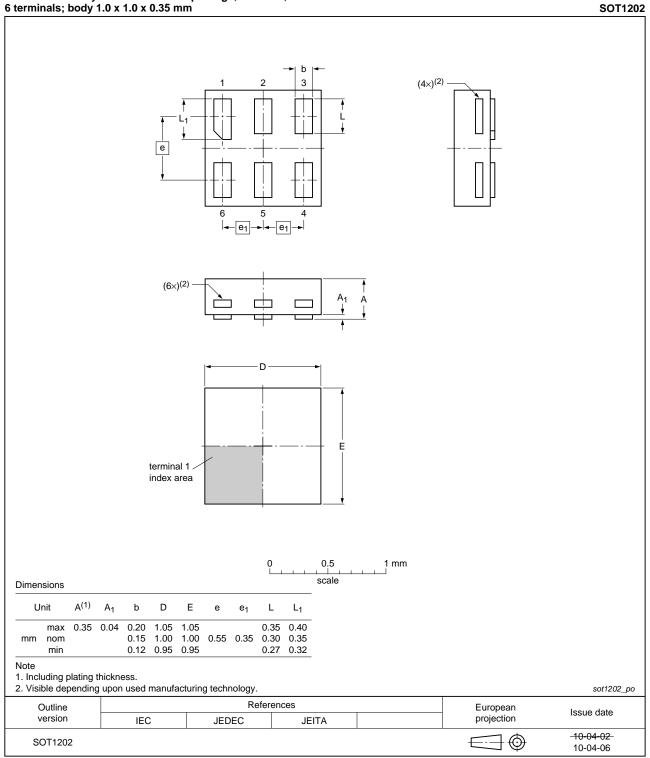
Fig 20. Package outline SOT1115 (XSON6)

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|--------------------|--------------------|-----------------------|-----------------|
| | | | |

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All

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XSON6: extremely thin small outline package; no leads; 6 terminals; body 1.0 x 1.0 x 0.35 mm

Fig 21. Package outline SOT1202 (XSON6)

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16. Abbreviations

| Table 19. Abbreviations | | | | |
|-------------------------|-------------------------|--|--|--|
| Acronym | Description | | | |
| CDM | Charged Device Model | | | |
| DUT | Device Under Test | | | |
| ESD | ElectroStatic Discharge | | | |
| HBM | Human Body Model | | | |

17. Revision history

Table 20.Revision history

| | • | | | |
|--------------------|---------------------------------|--|------------------|--------------------|
| Document ID | Release date | Data sheet status | Change notice | Supersedes |
| 74LVC_LVCH1T45 v.6 | 20120806 | Product data sheet | - | 74LVC_LVCH1T45 v.5 |
| Modifications: | Package out | line drawing of SOT886 (<mark>Figu</mark> | re 18) modified. | |
| 74LVC_LVCH1T45 v.5 | 20111219 | Product data sheet | - | 74LVC_LVCH1T45 v.4 |
| Modifications: | Legal pages | updated. | | |
| 74LVC_LVCH1T45 v.4 | 20110927 | Product data sheet | - | 74LVC_LVCH1T45 v.3 |
| 74LVC_LVCH1T45 v.3 | 20100819 | Product data sheet | - | 74LVC_LVCH1T45 v.2 |
| 74LVC_LVCH1T45 v.2 | 20100119 | Product data sheet | - | 74LVC_LVCH1T45 v.1 |
| 74LVC_LVCH1T45 v.1 | 20090511 | Product data sheet | - | - |
| | | | | |

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18. Legal information

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|--------------------------------|-------------------------------|---|
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[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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