1. General description

The HEF4516B is an edge-triggered synchronous 4-bit binary up/down counter with a clock input (CP), an up/down count control input (UP/DN), an active LOW count enable input (CE), an asynchronous active HIGH parallel load input (PL), four parallel inputs (D0 to D3), four parallel outputs (Q0 to Q3), an active LOW terminal count output (TC), and an overriding asynchronous master reset input (MR).

Information on D0 to D3 is loaded into the counter while PL is HIGH, independent of all other input conditions except for MR which must be LOW. When PL and \overline{CE} are LOW, the counter changes on the LOW-to-HIGH transition of CP. Input UP/DN determines the direction of the count, counting up when HIGH and counting down when LOW. When counting up, \overline{TC} is LOW when Q0 and Q3 are HIGH and \overline{CE} is LOW. When counting down, \overline{TC} is LOW when Q0 to Q3 and \overline{CE} are LOW. A HIGH on MR resets the counter (Q0 to Q3 = LOW) independent of all other input conditions.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD}, V_{SS}, or another input.

2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

3. Ordering information

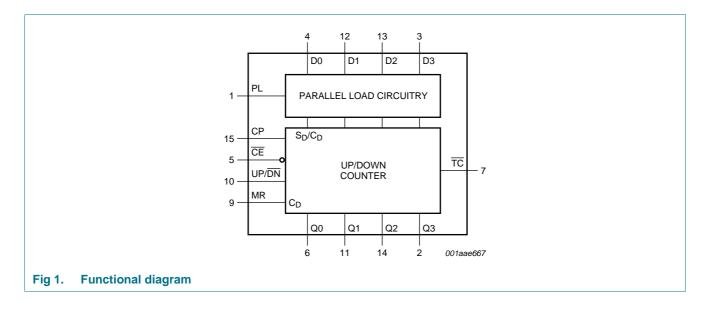
Table 1.Ordering information

All types operate from -40 °C to +85 °C.

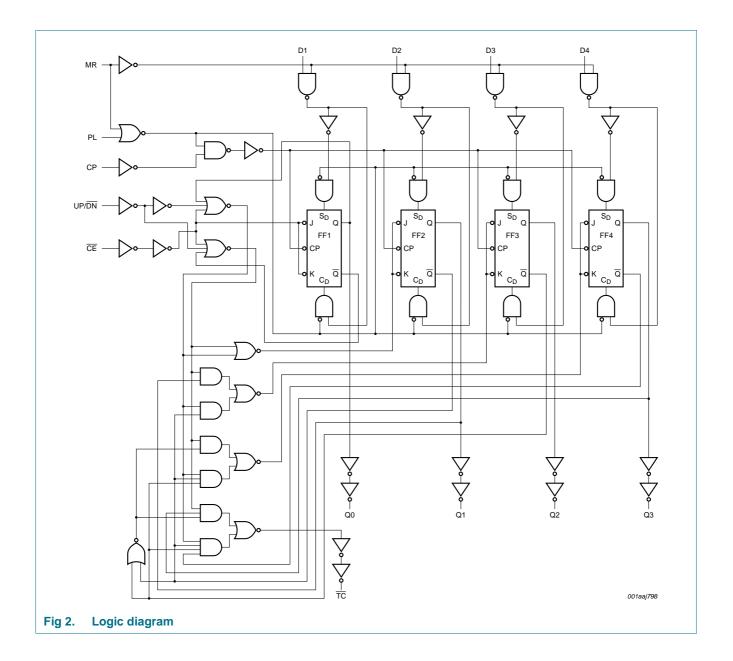
Type number	Package	Package						
	Name	Description	Version					
HEF4516BP	DIP16	plastic dual in-line package; 16-leads (300 mil)	SOT38-4					
HEF4516BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1					



4. Functional diagram



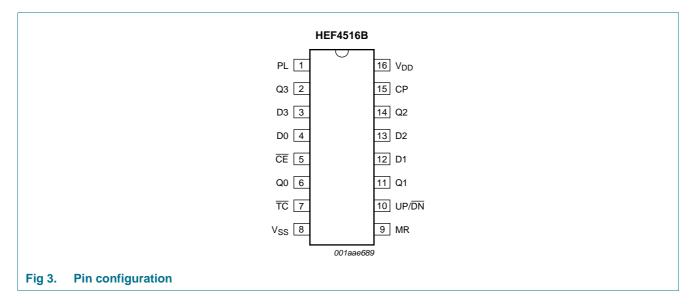
Binary up/down counter



3 of 17

5. Pinning information

5.1 Pinning



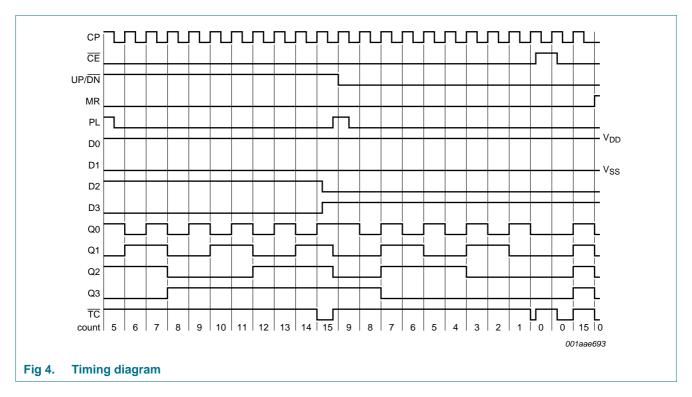
5.2 Pin description

Table 2.	Pin description	
Symbol	Pin	Description
PL	1	parallel load input (active HIGH)
D0 to D3	4, 12, 13, 3	parallel input
CE	5	count enable input (active LOW)
Q0 to Q3	6, 11, 14, 2	parallel output
V _{SS}	8	ground supply voltage
TC	7	terminal count output (active LOW)
MR	9	master reset input
UP/DN	10	up/down count control input
CP	15	clock pulse input (LOW to HIGH, edge triggered)
V _{DD}	16	supply voltage

6. Functional description

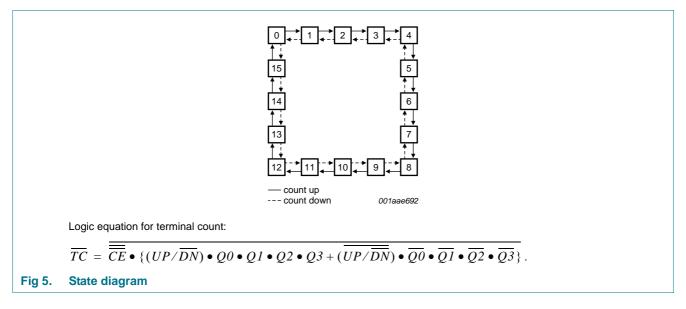
Table 3.	Function table ^[1]				
MR	PL	UP/DN	CE	СР	MODE
L	Н	Х	Х	Х	parallel load
L	L	Х	Н	Х	no change
L	L	L	L	↑	count down
L	L	Н	L	1	count up
Н	Х	Х	Х	Х	reset

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; $\uparrow = positive-going transition.$



HEF4516B

Binary up/down counter



7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{DD}	supply voltage		-0.5	+18	V
l _{IK}	input clamping current	V_{I} < -0.5 V or V_{I} > V_{DD} + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V _{DD} + 0.5	V
I _{OK}	output clamping current	$V_{\rm O}$ < –0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I _{I/O}	input/output current		-	±10	mA
I _{DD}	supply current		-	50	mA
T _{stg}	storage temperature		-65	+150	°C
T _{amb}	ambient temperature		-40	+85	°C
P _{tot}	total power dissipation	DIP16 package	<u>[1]</u> _	750	mW
		SO16 package	[2] _	500	mW
Р	power dissipation	per output	-	100	mW

[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{DD}	supply voltage		3	-	15	V
VI	input voltage		0	-	V_{DD}	V
T _{amb}	ambient temperature	in free air	-40	-	+85	°C

HEF4516B

Binary up/down counter

Table 5.	Recommended operating conditionscontinued							
Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
$\Delta t/\Delta V$	input transition rise and fall rate	t transition rise and fall rate $V_{DD} = 5 V$		-	3.75	μs/V		
		V _{DD} = 10 V	-	-	0.5	μs/V		
		V _{DD} = 15 V	-	-	0.08	μs/V		

9. Static characteristics

Table 6. Static characteristics

 $V_{SS} = 0$ V; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

Symbol	Parameter	Conditions	V _{DD}	T _{amb} =	–40 °C	T _{amb} =	: 25 °C	T _{amb} =	85 °C	Unit
				Min	Max	Min	Max	Min	Max	
V _{IH}	HIGH-level input voltage	I _O < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V _{IL}	LOW-level input voltage	$ I_0 < 1 \ \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V _{ОН}	HIGH-level output voltage	I _O < 1 μA;	5 V	4.95	-	4.95	-	4.95	-	V
		$V_{I} = V_{SS} \text{ or } V_{DD}$	10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
/ _{OL} LOW-level output voltage	$ I_0 < 1 \ \mu A;$	5 V	-	0.05	-	0.05	-	0.05	V	
		$V_I = V_{SS} \text{ or } V_{DD}$	10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
l _{он}	HIGH-level output current	V _O = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V _O = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V _O = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V _O = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
l _{ol}	LOW-level output current	$V_0 = 0.4 V$	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_{O} = 0.5 V$	10 V	1.3	-	1.1	-	0.9	-	mA
		V _O = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
l,	input leakage current	$V_{DD} = 15 V$	15 V	-	±0.3	-	±0.3	-	±1.0	μA
DD	supply current	I _O = 0 A;	5 V	-	20	-	20	-	150	μA
		$V_I = V_{SS} \text{ or } V_{DD}$	10 V	-	40	-	40	-	300	μA
			15 V	-	80	-	80	-	600	μA
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

10. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0$ V; $T_{amb} = 25$ °C; for test circuit see <u>Figure 8</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit
PHL	HIGH to LOW	CP to Qn	5 V	118 ns + (0.55 ns/pF)C _L	-	145	290	ns
	propagation delay		10 V	49 ns + (0.23 ns/pF)C _L	-	60	120	ns
			15 V	37 ns + (0.16 ns/pF)C _L	-	45	90	ns
		CP to TC	5 V	233 ns + (0.55 ns/pF)C _L	-	260	525	ns
			10 V	94 ns + (0.23 ns/pF)C _L	-	105	210	ns
			15 V	67 ns + (0.16 ns/pF)C _L	-	75	150	ns
		PL to Qn	5 V	98 ns + (0.55 ns/pF)C _L	-	125	255	ns
			10 V	44 ns + (0.23 ns/pF)C _L	-	55	110	ns
		15 V	32 ns + (0.16 ns/pF)C _L	-	40	85	ns	
	PL to TC	5 V	223 ns + (0.55 ns/pF)C _L	-	250	500	ns	
		10 V	99 ns + (0.23 ns/pF)C _L	-	110	220	ns	
			15 V	72 ns + (0.16 ns/pF)C _L	-	80	160	ns
	CE to TC	5 V	138 ns + (0.55 ns/pF)C _L	-	165	330	ns	
		10 V	54 ns + (0.23 ns/pF)C _L	-	65	135	ns	
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	100	ns
		MR to Qn, TC		205	405	ns		
			10 V	54 ns + (0.23 ns/pF)C _L	-	65	130	ns
			15 V	37 ns + (0.16 ns/pF)C _L	-	45	85	ns
LH	LOW to HIGH	CP to Qn	5 V	128 ns + (0.55 ns/pF)CL	-	155	310	ns
	propagation delay		10 V	54 ns + (0.23 ns/pF)C _L	-	65	130	ns
			15 V	37 ns + (0.16 ns/pF)C _L	-	45	90	ns
		CP to TC	5 V	153 ns + (0.55 ns/pF)C _L	-	180	360	ns
			10 V	64 ns + (0.23 ns/pF)C _L	-	75	150	ns
			15 V	47 ns + (0.16 ns/pF)C _L	-	55	115	ns
		PL to Qn	5 V	143 ns + (0.55 ns/pF)C _L	-	170	340	ns
			10 V	59 ns + (0.23 ns/pF)C _L	-	70	140	ns
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	105	ns
		PL to TC	5 V	223 ns + (0.55 ns/pF)C _L	-	250	500	ns
			10 V	99 ns + (0.23 ns/pF)C _L	-	110	220	ns
			15 V	72 ns + (0.16 ns/pF)C _L	-	80	160	ns
		CE to TC	5 V	118 ns + (0.55 ns/pF)C _L	-	145	290	ns
			10 V	49 ns + (0.23 ns/pF)C _L	-	60	125	ns
			15 V	37 ns + (0.16 ns/pF)C _L	-	45	95	ns
		MR to \overline{TC}	5 V	198 ns + (0.55 ns/pF)C _L	-	225	450	ns
			10 V	64 ns + (0.23 ns/pF)C _L	-	75	150	ns
			15 V	42 ns + (0.16 ns/pF)C _L	-	50	100	ns

Binary up/down counter

Symbol	Parameter	Conditions	V_{DD}	Extrapolation formula	Min	Тур	Max	Unit		
t _t	transition time		5 V	10 ns + (1.00 ns/pF)C _L	-	60	120	ns		
			10 V 9 ns + $(0.42 \text{ ns/pF})C_{L}$ -			30	60	ns		
			15 V	6 ns + (0.28 ns/pF)C _L	-	20	40	ns		
f _{max}	maximum frequency	see Figure 6	5 V		3	6	-	MHz		
			10 V		7	14	-	MHz		
			15 V		9	18	-	MHz		
t _W	pulse width	CP input LOW; minimum width; see Figure 6	5 V		95	45	-	ns		
			10 V		35	20	-	ns		
		<u>ga. o o</u>	15 V		25	15	-	ns		
		PL input HIGH; minimum width;	5 V		105	55	-	ns		
		minimum width; see <u>Figure 7</u>	10 V		45	25	-	ns		
			15 V		35	15	-	ns		
		MR input HIGH; minimum width; see <u>Figure 7</u>	5 V		120	60	-	ns		
			10 V		50	25	-	ns		
			15 V		40	20	-	ns		
t _{rec}	recovery time	MR input; see <u>Figure 7</u>	5 V		130	65	-	ns		
			10 V		45	20	-	ns		
			15 V		30	15	-	ns		
		PL input; see <u>Figure 7</u>	5 V		150	75	-	ns		
			10 V		50	25	-	ns		
			15 V		30	15	-	ns		
t _{su}	set-up time	Dn to PL; see Figure 7	5 V		100	50	-	ns		
		see <u>rigure r</u>	10 V				-	ns		
			15 V					ns		
		UP/DN to CP; see Figure 6	5 V					ns		
		<u>1 iguro o</u>	10 V					ns		
			15 V					ns		
		CE to CP; see Figure 6	5 V			40 20 - 250 125 - 100 50 - 75 35 - 120 60 -				
		<u>1 iguro o</u>	10 V					ns		
	hald the s	Data DL	15 V		25	10	-	ns		
t _h	hold time	Dn to PL; see <u>Figure 7</u>	5 V		+10	-40	-	ns		
		<u> </u>	10 V		+5	-20	-	ns		
		UP/DN to CP;	15 V		0	-20	-	ns		
		UP/DN to CP; see <u>Figure 6</u>	5 V		+35	-90	-	ns		
		<u> </u>	10 V		+15	-35	-	ns		
			15 V		+15	-25	-	ns		
		CE to CP; see Figure 6	5 V		+20	-40	-	ns		
		<u></u>	10 V		+5	-15	-	ns		
			15 V		+5	-10	-	ns		

Table 7. Dynamic characteristics ... continued

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

HEF4516B Product data sheet

HEF4516B

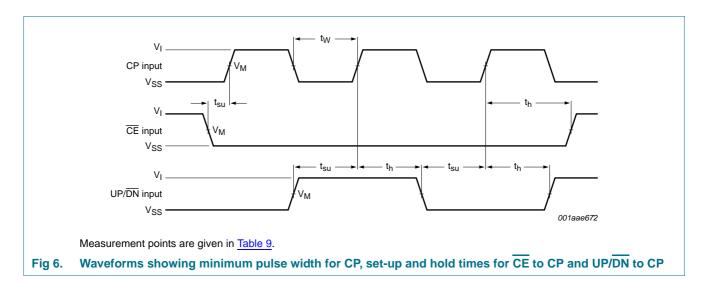
Binary up/down counter

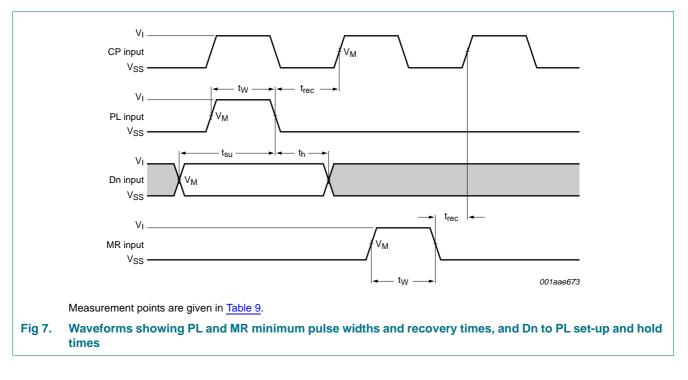
Table 8.	Dynamic	power	dissipation	PD
				· •

 P_D can be calculated from the formulas shown. $V_{SS} = 0$ V; $C_L = 50$ pF; $t_r = t_f \le 20$ ns; $T_{amb} = 25$ °C.

2				anno
Symbol	Parameter	V_{DD}	Typical formula for P_D (μ W)	Where:
PD	dynamic power	5 V	$P_{D} = 1000 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	f _i = input frequency in MHz;
	dissipation	10 V	$P_D = 4500 \times f_i + \Sigma (f_o \times C_L) \times V_DD^2$	$f_o = output frequency in MHz;$
		15 V	$P_D = 11200 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	C_L = output load capacitance in pF;
				V _{DD} = supply voltage in V;
				$\Sigma(f_o \times C_L)$ = sum of the outputs.

11. Waveforms





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Binary up/down counter

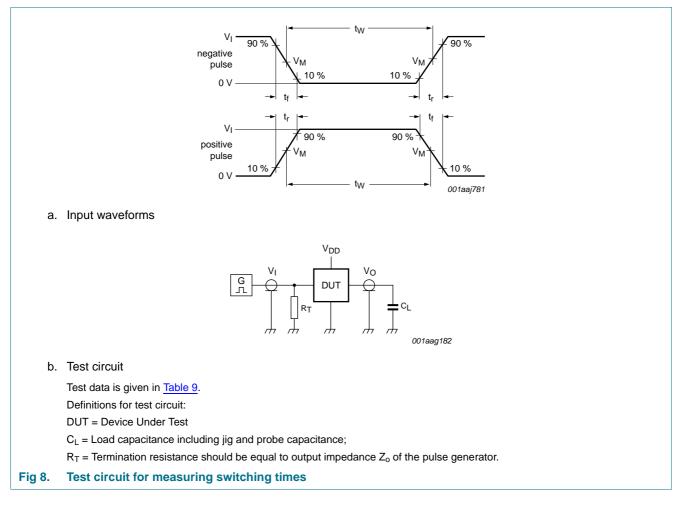


Table 9. Measurement points and test data

Supply voltage	Input	Input				
	VI	V _M	t _r , t _f	CL		
5 V to 15 V	V _{DD}	0.5V _I	≤ 20 ns	50 pF		

HEF4516B Binary up/down counter

12. Package outline

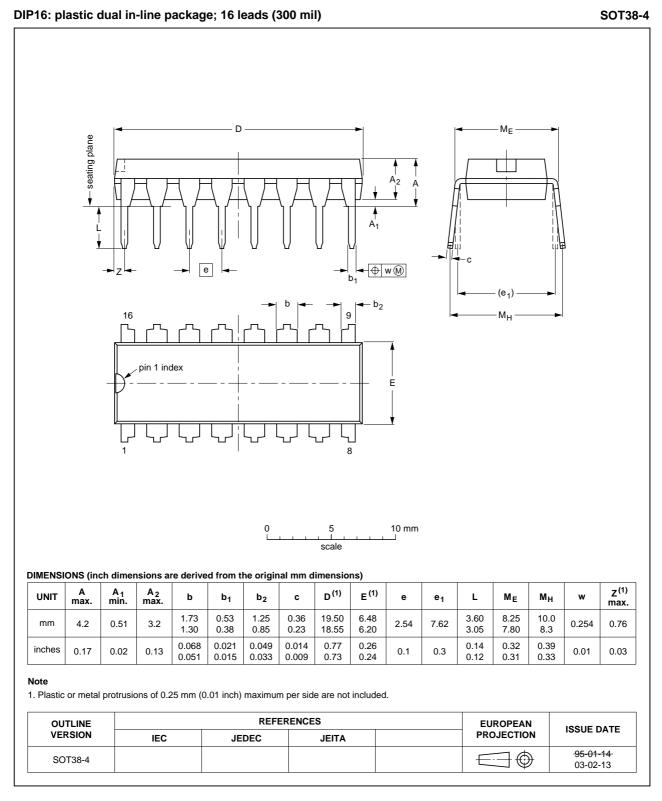


Fig 9. Package outline SOT38-4 (DIP16)

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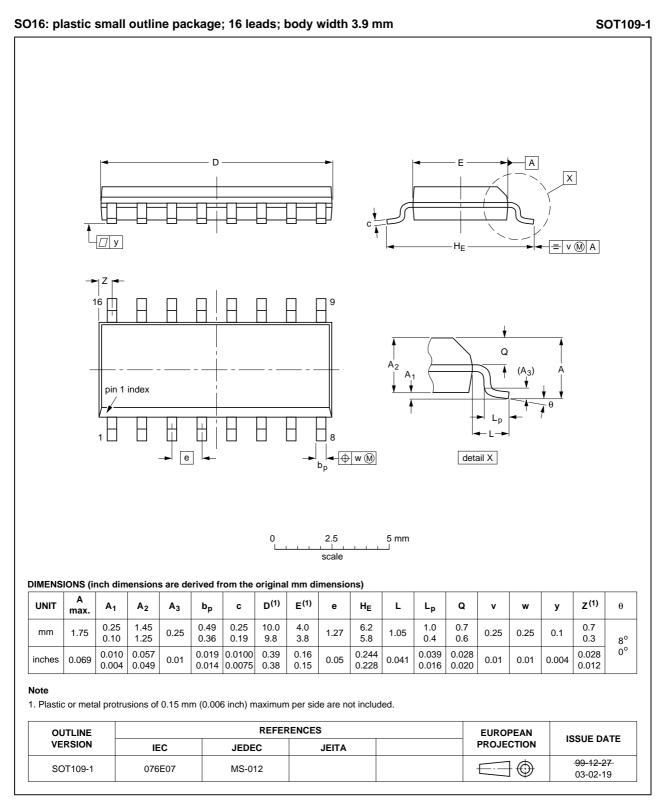


Fig 10. Package outline SOT109-1 (SO16)

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13. Revision history

Table 10. Revision history					
Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4516B v.7	20111111	Product data sheet	-	HEF4516B v.6	
Modifications:	Section Applications removed				
	• Table 6: I _{OH}	minimum values changed t	o maximum		
HEF4516B v.6	20091211	Product data sheet	-	HEF4516B v.5	
HEF4516B v.5	20090812	Product data sheet	-	HEF4516B v.4	
HEF4516B v.4	20090312	Product data sheet	-	HEF4516B_CNV v.3	
HEF4516B_CNV v.3	19950101	Product specification	-	HEF4516B_CNV v.2	
HEF4516B_CNV v.2	19950101	Product specification	-	-	

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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HEF4516B

Rev. 7 — 11 November 2011

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16. Contents

1	General description 1
2	Features and benefits 1
3	Ordering information 1
4	Functional diagram 2
5	Pinning information 4
5.1 5.2	Pinning
6	Functional description 5
7	Limiting values
8	Recommended operating conditions
9	Static characteristics 7
10	Dynamic characteristics 8
11	Waveforms 10
12	Package outline 12
13	Revision history 14
14	Legal information 15
14.1	Data sheet status 15
14.2	Definitions 15
14.3	Disclaimers
14.4	Trademarks 16
15	Contact information 16
16	Contents 17

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