# **HEF4020B**

# 14-stage binary counter Rev. 9 — 21 March 2016

Product data sheet

#### 1. **General description**

The HEF4020B is a 14-stage binary counter with a clock input (CP), an overriding asynchronous master reset input (MR) and twelve fully buffered outputs (Q0, and Q3 to Q13). The counter advances on the HIGH to LOW transition of  $\overline{\text{CP}}$ . A HIGH on MR clears all counter stages and forces all outputs LOW, independent of the state of  $\overline{CP}$ . Each counter stage is a static toggle flip-flop. A feature of the device is its high speed (typ. 35 MHz at  $V_{DD} = 15 \text{ V}$ ).

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$ (usually ground). Unused inputs must be connected to  $V_{\text{DD}},\,V_{\text{SS}},$  or another input.

#### **Features and benefits** 2.

- High speed operation
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

#### 3. Ordering information

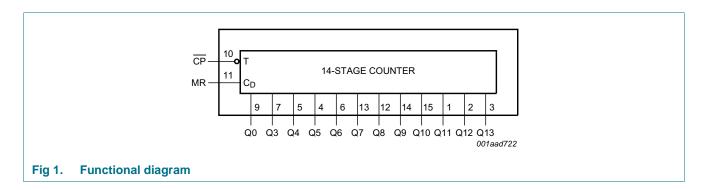
#### Table 1. **Ordering information**

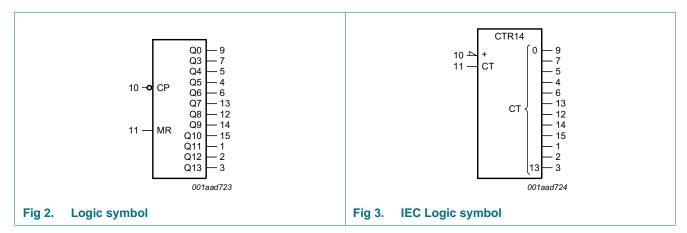
All types operate from -40 °C to +85 °C.

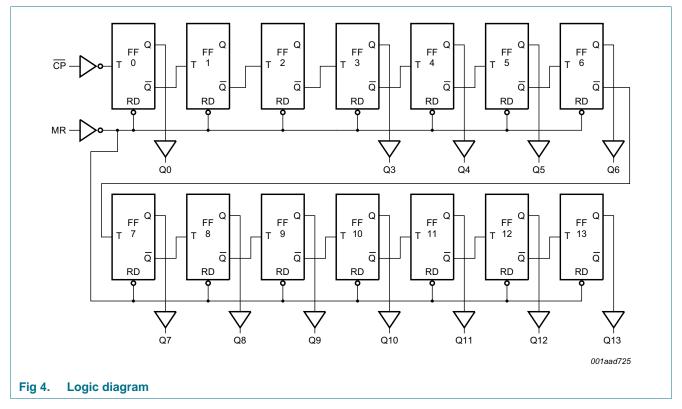
Type number	Package						
	Name	Description	Version				
HEF4020BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1				



# 4. Functional diagram



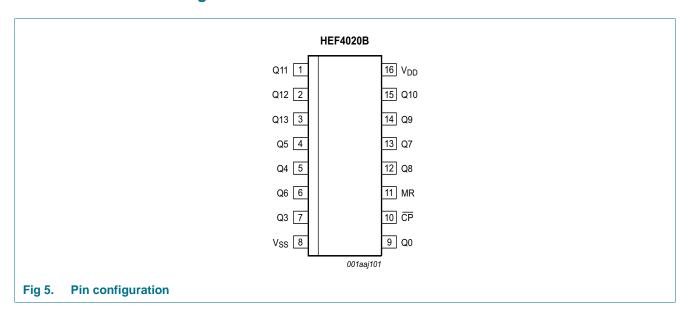




HEF4020B

# 5. Pinning information

## 5.1 Pinning



## 5.2 Pin description

Table 2. Pin description

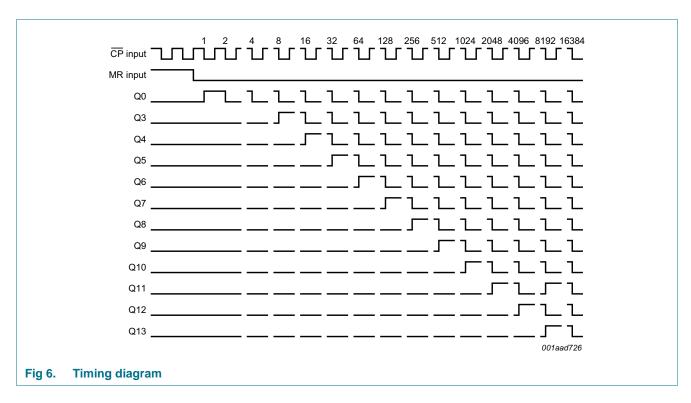
Symbol	Pin	Description
Q3 to Q13	7, 5, 4, 6, 13, 12, 14, 15, 1, 2, 3	parallel output (Q3 to Q13)
$V_{SS}$	8	ground supply voltage
Q0	9	parallel output
CP	10	clock input (HIGH-to-LOW edge triggered)
MR	11	master reset input (active HIGH)
$V_{DD}$	16	supply voltage

## 6. Functional description

Table 3. Functional table[1]

Input	Output	
СР	MR	Q0, Q3 to Q13
$\uparrow$	L	no change
<b>↓</b>	L	count
Х	Н	L

[1]  $H = HIGH \text{ voltage level}; L = LOW \text{ voltage level}; X = don't care; \uparrow = positive-going transition; } \downarrow = negative-going transition.$ 



## 7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I} < 05 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	$V_{DD} + 0.5$	V
I <sub>OK</sub>	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
$I_{DD}$	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> –40 °C to +85 °C			
		SO16 package [1]	-	500	mW
Р	power dissipation	per output	-	100	mW

[1] For SO16 package:  $P_{tot}$  derates linearly with 8 mW/K above 70 °C.

# 8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
VI	input voltage		0	-	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

## 9. Static characteristics

#### Table 6. Static characteristics

 $V_{SS} = 0$  V;  $V_I = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	T <sub>amb</sub> = -40 °C		-40 °C T <sub>amb</sub> = 25 °C		T <sub>amb</sub> = 85 °C	
				Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	I <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		$V_0 = 4.6 \text{ V}$	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		$V_0 = 9.5 \text{ V}$	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		$V_0 = 13.5 \text{ V}$	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_0 = 0.5 \text{ V}$	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
I <sub>I</sub>	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μА
			10 V	-	40	-	40	-	300	μА
			15 V	-	80	-	80	-	600	μА
Cı	input capacitance		-	-	-	-	7.5	-	-	pF

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14-stage binary counter

# 10. Dynamic characteristics

Table 7. Dynamic characteristics

 $V_{SS} = 0$  V;  $T_{amb} = 25$  °C; for test circuit see <u>Figure 8</u>.

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula[1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	CP to Q0;	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
	propagation delay	see Figure 7	10 V	34 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	65	ns
		Qn to Qn + 1	5 V	53 ns + (0.55 ns/pF)C <sub>L</sub>	-	80	160	ns
			10 V	19 ns + (0.23 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	12 ns + (0.16 ns/pF)C <sub>L</sub>	-	20	40	ns
		MR to Qn;	5 V	153 ns + (0.55 ns/pF)C <sub>L</sub>	-	180	360	ns
		see Figure 7	10 V	79 ns + (0.23 ns/pF)C <sub>L</sub>	-	90	180	ns
			15 V	62 ns + (0.16 ns/pF)C <sub>L</sub>	-	70	140	ns
t <sub>PLH</sub>	LOW to HIGH	CP to Q0;	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
	propagation delay	see Figure 7	10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	95	ns
			15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
		Qn to Qn + 1	5 V	43 ns + (0.55 ns/pF)C <sub>L</sub>	-	70	140	ns
			10 V	14 ns + (0.23 ns/pF)C <sub>L</sub>	-	25	50	ns
		15 V	12 ns + (0.16 ns/pF)C <sub>L</sub>	-	20	40	ns	
t <sub>t</sub>	transition time	see Figure 7	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>W</sub>	pulse width	CP = HIGH;	5 V		50	25	-	ns
		minimum width; see Figure 7	10 V		25	15	-	ns
		see <u>rigure 7</u>	15 V		20	10	-	ns
		MR = HIGH;	5 V		130	65	-	ns
		minimum width;	10 V		95	50	-	ns
		see Figure 7	15 V		90	45	-	ns
t <sub>rec</sub>	recovery time	MR input;	5 V		115	60	-	ns
		see Figure 7	10 V		65	35	-	ns
			15 V		55	25	-	ns
f <sub>max</sub>	maximum	see Figure 7	5 V		5	10	-	MHz
	frequency		10 V		13	25	-	MHz
			15 V		18	35	-	MHz

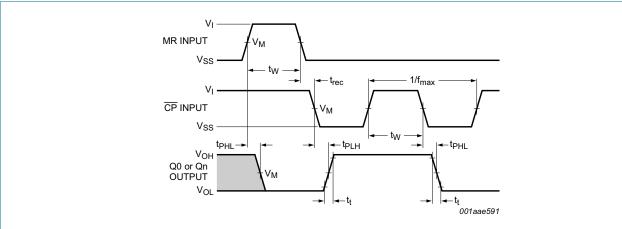
<sup>[1]</sup> The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).

Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0 \ V$ ;  $t_r = t_f \le 20 \ ns$ ;  $T_{amb} = 25 \ ^{\circ}C$ .

Symbol	Parameter	$V_{DD}$	Typical formula for P <sub>D</sub> (μW)	where:
$P_D$	dynamic power	5 V	$P_D = 600 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	$f_i$ = input frequency in MHz,
	dissipation	10 V	$P_D = 2800 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	fo = output frequency in MHz,
		15 V	$P_D = 8200 \times f_i + \Sigma (f_o \times C_L) \times V_{DD}^2$	$C_L$ = output load capacitance in pF,
				V <sub>DD</sub> = supply voltage in V,
				$\Sigma(f_0 \times C_L)$ = sum of the outputs.

## 11. Waveforms

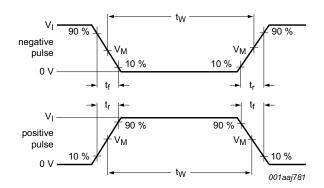


Measurement points are given in Table 9.

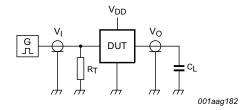
Fig 7. Propagation delays, minimum pulse widths, transition and recovery times and maximum clock frequency

Table 9. Measurement points

Supply voltage	Input	Output
$V_{DD}$	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



#### a. Input waveforms



#### b. Test circuit

Test data is given in Table 10.

Definitions for test circuit:

DUT = Device Under Test.

 $C_L$  = load capacitance including jig and probe capacitance.

 $R_T$  = termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

Fig 8. Test circuit for measuring switching times

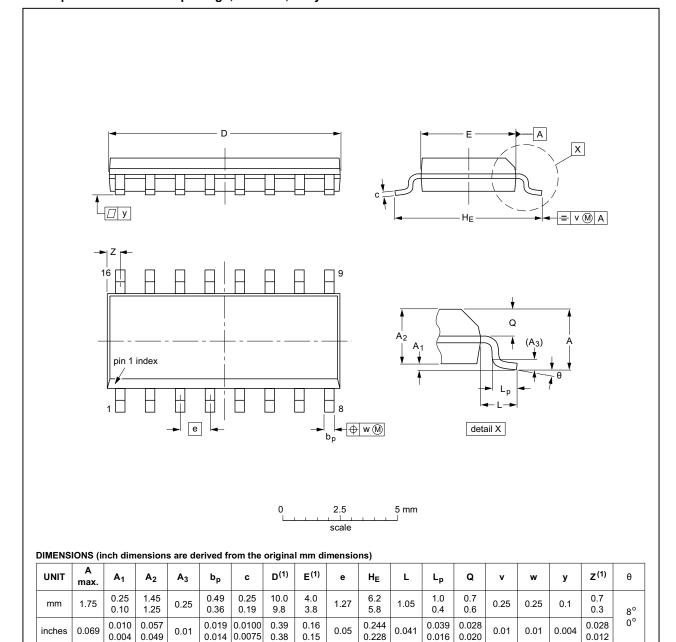
#### Table 10. Test data

Supply voltage	Input	Load	
$V_{DD}$	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

## 12. Package outline

#### SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE	TLINE REFERENCES				EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT109-1	076E07	MS-012				<del>99-12-27</del> 03-02-19	

Fig 9. Package outline SOT109-1 (SO16)

HEF4020B

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# 13. Revision history

### Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes				
HEF4020B v.9	20160321	Product data sheet	-	HEF4020B v.8				
Modifications:	• Type number HEF4020BP (SOT38-4) removed.							
HEF4020B v.8	20111118	Product data sheet	-	HEF4020B v.7				
Modifications:	Legal pages	updated.						
	<ul> <li>Changes in</li> </ul>	"General description" and "Fea	tures and benefits".					
	Section "Apple of the section "Apple of	olications" removed.						
HEF4020B v.7	20111010	Product data sheet	-	HEF4020B v.6				
HEF4020B v.6	20091127	Product data sheet	-	HEF4020B v.5				
HEF4020B v.5	20090707	Product data sheet	-	HEF4020B v.4				
HEF4020B v.4	20081204	Product data sheet	-	HEF4020B_CNV v.3				
HEF4020B_CNV v.3	19950101	Product specification	-	HEF4020B_CNV v.2				
HEF4020B_CNV v.2	19950101	Product specification	-	-				

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Document status[1][2]	Product status[3]	Definition
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