3A Digital PicoDLynx™: Non-Isolated DC-DC Power Modules

3Vdc -14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

RoHS Compliant





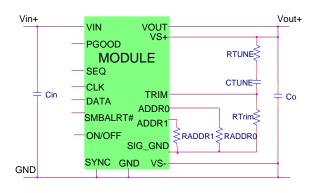
Applications

Industrial equipment

Distributed power architectures

Intermediate bus voltage applications

Telecommunications equipment



Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863.
- Compliant to REACH Directive (EC) No 1907/2006.
- Compatible in a Pb-free or SnPb reflow environment.
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Use ABB specified module version and process for SMT placement on bottom side of board (-D version only)
- DOSA based
- Wide Input voltage range (3Vdc-14.4Vdc)
- Output voltage programmable from 0.6Vdc to 5.5Vdc via external resistor. Digitally adjustable down to 0.45Vdc
- Digital interface through the PMBus™ # protocol
- Tunable Loop™ to optimize dynamic output voltage response
- Flexible output voltage sequencing EZ-SEQUENCE
- Power Good signal
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Cost efficient open frame design
- Small size: 12.2 mm x 12.2 mm x 6.25 mm (0.48 in x 0.48 in x 0.246 in)
- Wide operating temperature range [-40°C to 105°C (Ruggedized: -D), 85°C(Regular)]
- ANSI/UL* 62368-1 and CAN/CSA[†] C22.2 No. 62368-1 Recognized, DIN VDE[‡] 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

The 3A Digital PicoDLynxTM power modules are non-isolated dc-dc converters that can deliver up to 3A of output current. These modules operate over a wide range of input voltage ($V_{IN} = 3Vdc-14.4Vdc$) and provide a precisely regulated output voltage from 0.45Vdc to 5.5Vdc, programmable via an external resistor and PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current and over temperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable LoopTM feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- [†] CSA is a registered trademark of Canadian Standards Association.
- [‡] VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- ** ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	V _{IN}	-0.3	15	V
Continuous					
SEQ, SYNC, VS+	All			7	V
CLK, DATA, SMBALERT	All			3.6	V
Operating Ambient Temperature	All	TA	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T _{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V _{IN}	3		14.4	Vdc
Maximum Input Current	All	l _{IN,max}			2.8	Adc
(V _{IN} =3V to 14V, I _O =I _{O, max})						
Input No Load Current	V _{O,set} = 0.6 Vdc	I _{IN,No} load		17.5		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V _{0,set} = 5Vdc	I _{IN,No load}		43		mA
Input Stand-by Current (V _{IN} = 12Vdc, module disabled)	All	I _{IN,stand-by}		6.4		mA
Inrush Transient	All	l²t			1	A ² s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; V _{IN} =0 to 14V. Io= Iomax; See Test Configurations)	All			100		mAp-p
Input Ripple Rejection (120Hz)	All			-57		dB

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point (with 0.1% tolerance for external resistor used to set output voltage)	All	V _{O, set}	-1.0		+1.0	% V _{O, set}
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	V _{O, set}	-3.0	_	+3.0	% V _{O, set}
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	Vo	0.6		5.5	Vdc
PMBus Adjustable Output Voltage Range	All	V _o ,adj	-25	0	+25	%V _{O,set}
PMBus Output Voltage Adjustment Step Size	All		0.4			%V _{0,set}
Remote Sense Range	All				0.5	Vdc
Output Regulation (for $V_0 \ge 2.5 Vdc$)						
Line ($V_{IN}=V_{IN, min}$ to $V_{IN, max}$)	All			_	+0.4	% V _{O, set}
Load (Io=Io, min to Io, max)	All			_	10	mV
Output Regulation (for $V_0 < 2.5$ Vdc)						
Line (V _{IN} =V _{IN, min} to V _{IN, max})	All			_	5	mV
Load (Io=Io, min to Io, max)	All			_	10	mV
Temperature (T _{ref} =T _{A, min} to T _{A, max})	All			_	0.4	% V _{O, set}
Output Ripple and Noise on nominal output ($V_{IN}=V_{IN,nom}$ and $I_{O}=I_{O,min}$ to $I_{O,max}$ Co = $0.1\mu F // 22 \mu F$ ceramic capacitors)						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		—	50	100	mV _{pk-pk}
RMS (5Hz to 20MHz bandwidth)	All			20	38	mV _{rms}
External Capacitance ¹						
Without the Tunable Loop™						
ESR≥1mΩ	All	C _{O, max}	10	_	22	μF
With the Tunable Loop™						
ESR ≥ 0.15 mΩ	All	C _{0, max}	22	_	1000	μF
$\text{ESR} \ge 10 \text{ m}\Omega$	All	C _{O, max}	22	_	3000	μF
Output Current (in either sink or source mode)	All	lo	0		3	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		270		% l _{o,max}
Output Short-Circuit Current	All	I _{O, s/c}		268		mArms
(V₀≤250mV) (Hiccup Mode)						
Efficiency	V _{0,set} = 0.6Vdc	η		72.4		%
V _{IN} = 12Vdc, T _A =25°C	V _{0, set} = 1.2Vdc	η		83.2		%
$I_{O}=I_{O, max}, V_{O}=V_{O,set}$	$V_{0,set} = 1.8Vdc$	η		87.5		%
	$V_{0,set} = 2.5Vdc$	η		90.1		%
	$V_{0,set} = 2.3 \text{ Vdc}$ $V_{0,set} = 3.3 \text{ Vdc}$	η		91.9		%
	$V_{0,set} = 5.0 V dc$ $V_{0,set} = 5.0 V dc$	η		94.0		%
Switching Frequency	All	f _{sw}		600		kHz

¹ External capacitors may require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop™ section for details.

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Frequency Synchronization	All					
Synchronization Frequency Range	All		510		720	kHz
High-Level Input Voltage	All	VIH	2.0			V
Low-Level Input Voltage	All	VIL			0.4	V
Input Current, SYNC	All	I _{SYNC}			100	nA
Minimum Pulse Width, SYNC	All	tsync	100			ns
Maximum SYNC rise time	All	tsync_sh	100			ns

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I_0=0.8I_0, _max, T_A=40°C) Telecordia Issue 2 Method 1 Case 3	All		19,508,839		Hours
Weight			0.96(0.034)		g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
$(V_{\text{IN}}{=}V_{\text{IN},\text{min}}$ to $V_{\text{IN},\text{max}}$; open collector or equivalent,						
Signal referenced to GND)						
Device code with suffix "4" – Positive Logic (See Ordering Information)						
Logic High (Module ON)						
Input High Current	All	Іін			1	mA
Input High Voltage	All	Vih	2		V _{IN,max}	V
Logic Low (Module OFF)						
Input Low Current	All	liL	_		1	mA
Input Low Voltage	All	VIL	-0.2		0.6	V
Device Code with no suffix – Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current		Іін	_	—	1	mA
Input High Voltage		Vih	2.0	—	V _{IN, max}	Vdc
Logic Low (Module ON)						
Input low Current		lı.	—	—	10	μA
Input Low Voltage	All	VIL	-0.2	-	0.6	Vdc

Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
Turn-On Delay and Rise Times						
(V_{IN}=V_{IN, nom,} l_0=l_{0,max,} V_0 to within ±1% of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until Vo = 10% of Vo, set)	All	Tdelay	_	0.4	_	msec
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo, set)	All	Tdelay	_	0.4	_	msec
Output voltage Rise time (time for Vo to rise from 10% of Vo, set to 90% of Vo, set)	All	Trise	_	2.4	_	msec
Output voltage overshoot ($T_A = 25^{\circ}C$ $V_{IN} = V_{IN, min}$ to $V_{IN, max}$, $I_O = I_{O, min}$ to $I_{O, max}$) With or without maximum external capacitance					3.0	% V _{O, set}
Over Temperature Protection (See Thermal Considerations section)	All	T _{ref}		150		°C
PMBus Over Temperature Warning Threshold*	All	T _{WARN}		130		°C
Tracking Accuracy (Power-Up: 2V/ms)	All	VSEQ –Vo			100	mV
(Power-Down: 2V/ms)	All	VSEQ –Vo			100	mV
(V_{IN,min} to V_{IN,max};I_{0,min} to $I_{0,max}$ VSEQ < Vo)						
Input Undervoltage Lockout						
Turn-on Threshold	All			2.71		Vdc
Turn-off Threshold	All			2.41		Vdc
Hysteresis	All			0.3		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		2.5		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All				500	mV
PGOOD (Power Good)						
Signal Interface Open Drain, $V_{supply} \leq 5VDC$						
Overvoltage threshold for PGOOD ON	All			108		%V _{O, set}
Overvoltage threshold for PGOOD OFF	All			110		%V _{O, set}
Undervoltage threshold for PGOOD ON	All			92		%V _{0, set}
Undervoltage threshold for PGOOD OFF	All			90		%V _{0, set}
Pulldown resistance of PGOOD pin	All				50	Ω
Sink current capability into PGOOD pin	All				5	mA

* Over temperature Warning – Warning may not activate before alarm and unit may shutdown before warning

Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		Vih	2.1		3.6	V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Input high level current (CLK, DATA)		Ін	-10		10	μA
Input low level current (CLK, DATA)		IL	-10		10	μA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{OUT} =2mA	Vol			0.4	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	0		10	μΑ
Pin capacitance		Co		0.7		pF
PMBus Operating frequency range	Slave Mode	Fрмв	10		400	kHz
Data hold time	Receive Mode Transmit Mode	thd:dat	0 300			ns
Data setup time		tsu:dat	250			ns
Measurement System Characteristics						·
Read delay time		tdly	153	192	231	μs
Output current measurement range		I _{RNG}	0		18	А
Output current measurement resolution		IRES	62.5			mA
Output current measurement gain accuracy accuracy at 25°C (with $I_{\text{OUT, CORR}})$		IACC			±5	%
Output current measurement offset		IOFST			0.1	А
V _{OUT} measurement range		VouT(rng)	0		5.5	V
V _{OUT} measurement resolution		V _{OUT(res)}		15.625		mV
V _{OUT} measurement accuracy		V _{OUT} (gain)	-15		15	%
V _{OUT} measurement offset		V _{OUT(ofst)}	-3		3	%
V _{IN} measurement range		V _{IN(rng)}	3		14.4	V
V _{IN} measurement resolution		VIN(res)		32.5		mV
V _{IN} measurement accuracy		V _{IN(gain)}	-15		15	%
V _{IN} measurement offset		VIN(ofst)	-5.5		1.4	LSB

Characteristic Curves

The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 0.6Vo and 25°C.

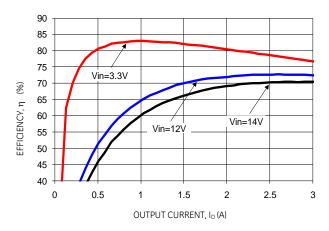
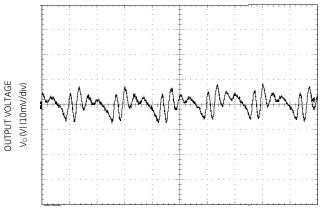


Figure 1. Converter Efficiency versus Output Current.



TIME, t (1µs/div)

Figure 3. Typical output ripple and noise (C_0=10 μF ceramic, V_{IN} = 12V, I_0 = I_{0,max_i}).

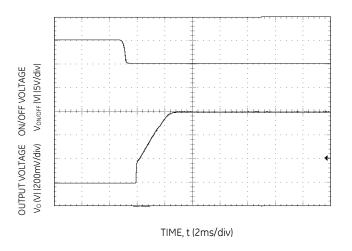


Figure 5. Typical Start-up Using On/Off Voltage (Io = Io,max).

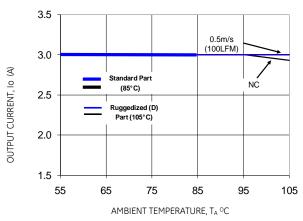
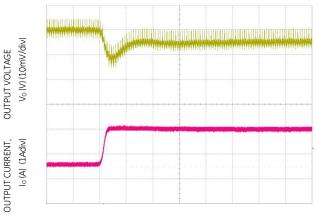
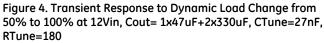


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (20µs /div)



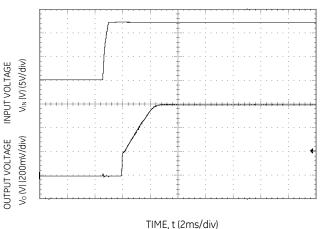
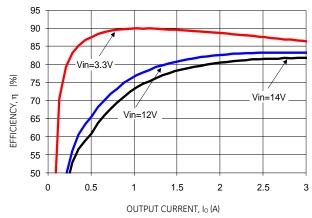
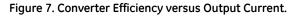


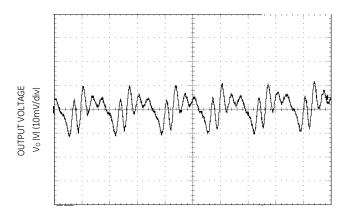
Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

Characteristic Curves

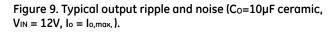
The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 1.2Vo and 25°C.







TIME, t (1µs/div)



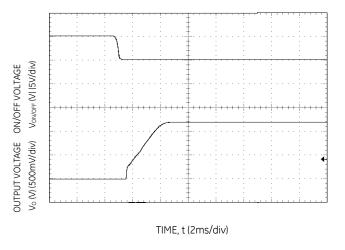


Figure 11. Typical Start-up Using On/Off Voltage (Io = Io,max).

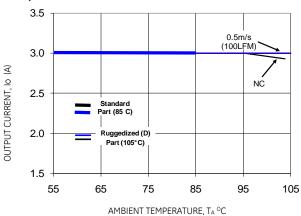
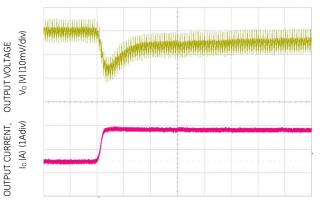
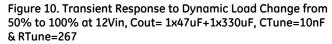
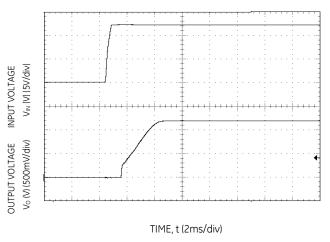


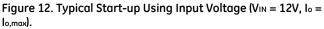
Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (20µs /div)

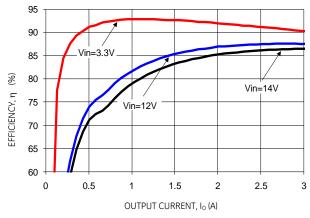


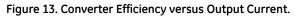




Characteristic Curves

The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 1.8Vo and 25℃.





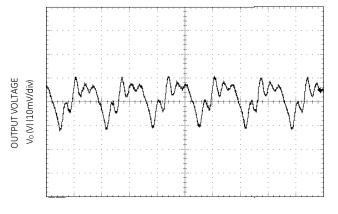




Figure 15. Typical output ripple and noise (C_0=10 μF ceramic, V_IN = 12V, I_0 = I_{0,max_i}).

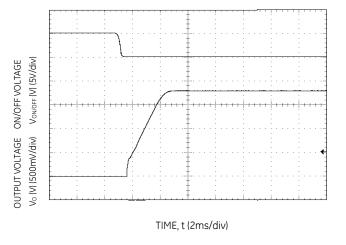


Figure 17. Typical Start-up Using On/Off Voltage (Io = Io,max).

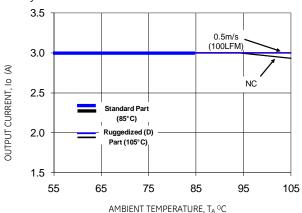
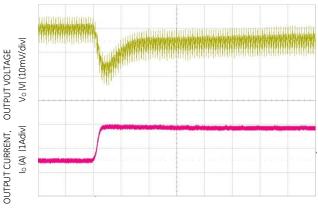
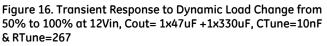
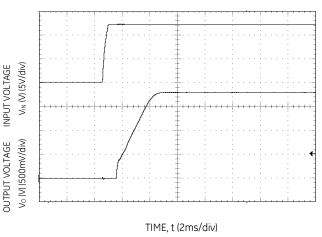


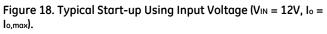
Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (20µs /div)

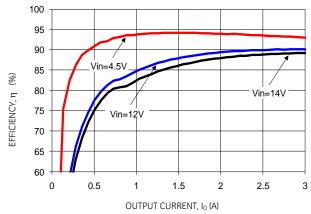




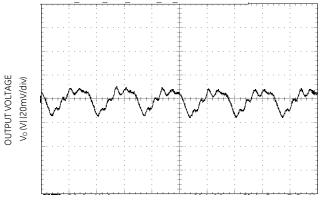


Characteristic Curves

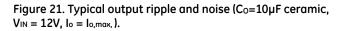
The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 2.5Vo and 25°C.

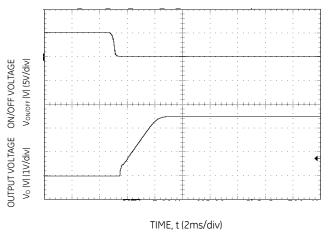


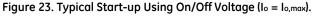






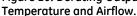






3.5 0.5m/s (100LFM) 3.0 OUTPUT CURRENT, Io (A) NC 2.5 Standard Part (85°C) 2.0 ized (D) Part (105°C) 1.5 55 65 75 85 95 105 AMBIENT TEMPERATURE, TA °C

Figure 20. Derating Output Current versus Ambient



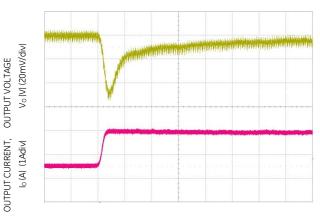




Figure 22. Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 2x47uF, CTune=2700pF & RTune=267

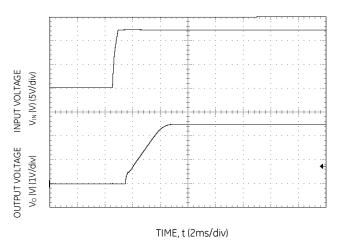
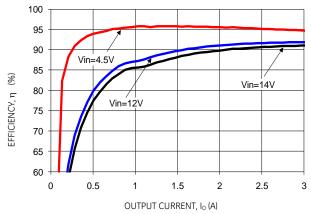
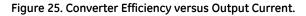


Figure 24. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

Characteristic Curves

The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 3.3Vo and 25°C.





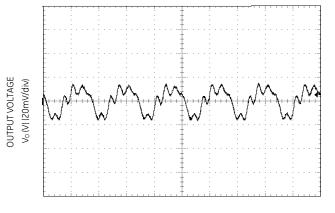
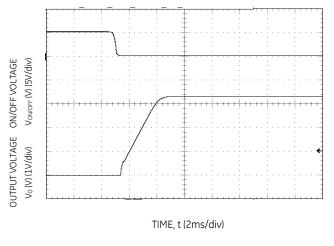




Figure 27. Typical output ripple and noise (C_0=10µF ceramic, V_IN = 12V, I_0 = I_{0,max_i}).





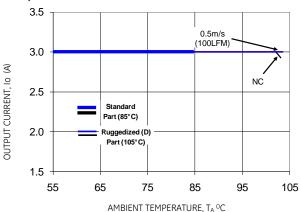
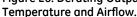


Figure 26. Derating Output Current versus Ambient



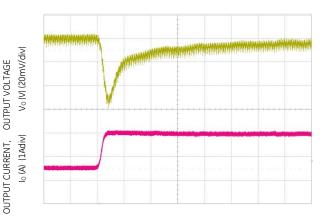




Figure 28 Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 2x47uF, CTune=2200pF & RTune=267

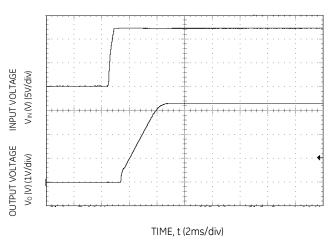
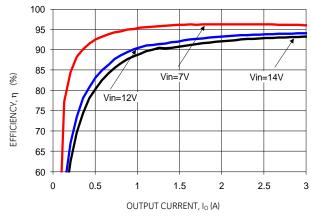
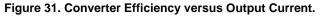


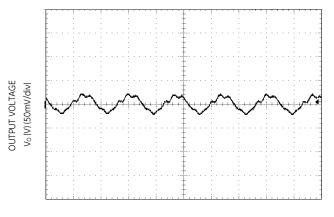
Figure 30. Typical Start-up Using Input Voltage (V $_{\rm IN}$ = 12V, $I_{\rm o}$ = $I_{\rm o,max}$).

Characteristic Curves

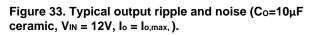
The following figures provide typical characteristics for the 3A Digital PicoDLynx™ at 5Vo and 25°C.







TIME, t (1µs/div)



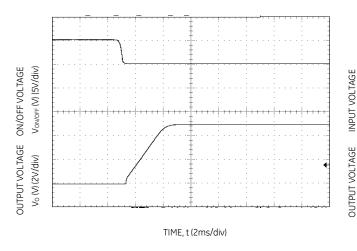


Figure 35. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).

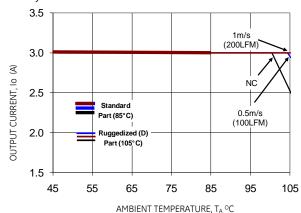
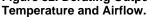
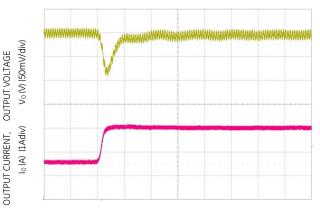
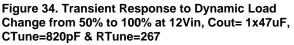


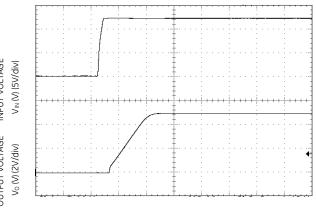
Figure 32. Derating Output Current versus Ambient





TIME, t (20µs /div)





TIME, t (2ms/div)



Design Considerations

Input Filtering

GF

The 3A Digital PicoDLynx[™] module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability. High frequency switching noise can be reduced by using suitable decoupling ceramic caps. Refer to AN04-006 and AN04-002 for more guidelines

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at 3A of load current with 1x22 μ F or 2x22 μ F ceramic capacitors and an input of 12V.

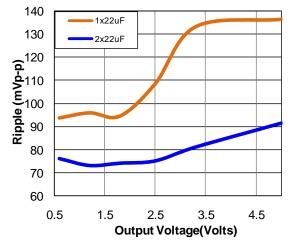


Figure 37. Input ripple voltage for various output voltages with 2x22 μF or 3x22 μF ceramic capacitors at the input (3A load). Input voltage is 12V.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1 μ F ceramic and 22 μ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information for different external capacitance values at various Vo and a full load current of 3A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop[™] feature described later in this data sheet.

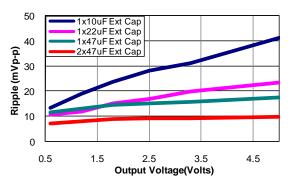


Figure 38. Output ripple voltage for various output voltages with external 1x10 μ F, 1x22 μ F, 1x47 μ F or 2x47 μ F ceramic capacitors at the output (3A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the Requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV. The input to these units is to be provided with a fast acting fuse with a maximum rating of 5 A in the positive input lead. An example of such a fuse is the ABC series by Littelfuse.

Analog Feature Descriptions

Remote On/Off

GF

The module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the two ON/OFF inputs:

- Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can be controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 3A Digital PicoDLynx[™] power modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "4" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (no device code suffix, see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor Q2 is in the OFF state, the internal transistor Q1 is turned ON, and the internal PWM #Enable signal is pulled low causing the module to be ON. When transistor Q2 is turned ON, the On/Off pin is pulled low and the module is OFF. A suggested value for R_{pullup} is $20k\Omega$.

For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. The On/Off pin should be pulled high with an external pull-up resistor (suggested value for the 3V to 14V input range is 20Kohms). When transistor Q2 is in the OFF state, the On/Off pin is pulled high, transistor Q1 is turned ON and the module is OFF. To turn the module ON, Q2 is turned ON pulling the On/Off pin low, turning transistor Q1 OFF resulting in the PWM Enable pin going high.

Digital On/Off

Please see the Digital Feature Descriptions section.

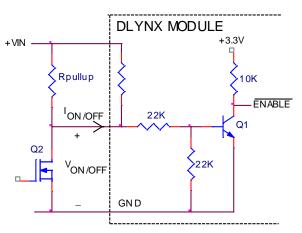


Figure 39. Circuit configuration for using positive On/Off logic.

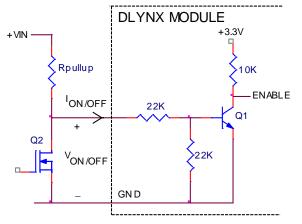


Figure 40. Circuit configuration for using negative On/Off logic.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module can start into a prebiased output as long as the prebias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.6dc to 5.5Vdc by connecting a resistor between the Trim and SIG_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 41. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 3V.

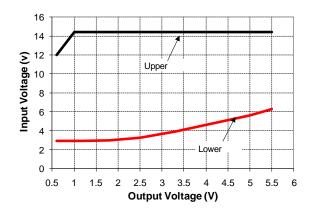
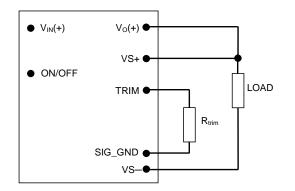


Figure 41. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.



Caution – Do not connect SIG_GND to GND elsewhere in the layout

Figure 42. Circuit configuration for programming output voltage using an external resistor.

Without an external resistor between Trim and SIG_GND pins, the output of the module will be 0.6Vdc.To calculate the value of the trim resistor, *Rtrim* for a desired output voltage, should be as per the following equation:

$$Rtrim = \left[\frac{12}{(Vo - 0.6)}\right] k\Omega$$

Rtrim is the external resistor in $k\Omega$

Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

Table 1

V _{O, set} (V)	Rtrim (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V.

Analog Voltage Margining

Output voltage margining can be implemented in the module by connecting a resistor, R_{margin-up}, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, R_{margin-down}, from the Trim pin to output pin for margining-down. Figure 43 shows the circuit configuration for output voltage margining. The POL Programming Tool, available at www.gecriticalpower.com under the Downloads section, also calculates the values of R_{margin-up} and R_{margin-down} for a specific output voltage and % margin. Please consult your local GE technical representative for additional details.

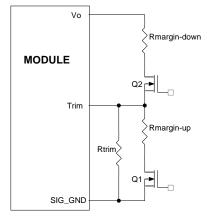


Figure 43. Circuit Configuration for margining Output voltage.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 44. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For all DLynx modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

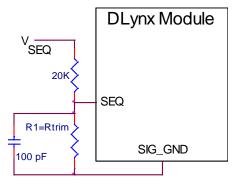


Figure 44. Circuit showing connection of the sequencing signal to the SEQ pin.

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Note that in all digital DLynx series of modules, the PMBus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS_WORD and STATUS_VOUT PMBus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the PMBus command VOUT_UV_FAULT_RESPONSE for additional information).

Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable Overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of $150^{\circ}C(typ)$ is exceeded at the thermal reference point T_{ref} . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Synchronization

The module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 45, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency. **If synchronization is not being used, connect the SYNC pin to GND.**

GF

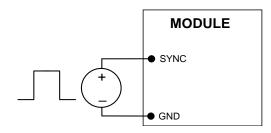


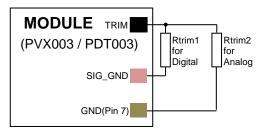
Figure 45. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

Dual Layout

Identical dimensions and pin layout of Analog and Digital PicoDLynx modules permit migration from one to the other without needing to change the layout. To support this, 2 separate Trim Resistor locations have to be provided in the layout. As shown in Fig. 46, for the digital modules, the resistor is connected between the TRIM pad and SGND and in the case of the analog module it is connected between TRIM and GND.



Caution – For digital modules, do not connect SIG_GND to GND elsewhere in the layout

Figure 46. Connections to support either Analog or Digital PicoDLynx on the same layout.

Tunable Loop™

The module has a feature that optimizes transient response of the module called Tunable Loop^TM.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable LoopTM allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable LoopTM is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 47. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

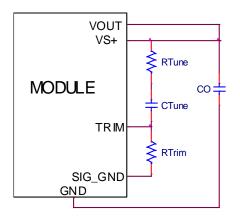


Figure. 47. Circuit diagram showing connection of R_{TUME} and C_{TUNE} to tune the control loop of the module.

Recommended values of R_{TUNE} and C_{TUNE} for different output capacitor combinations are given in Table 2. Table 2 shows the recommended values of R_{TUNE} and C_{TUNE} for different values of ceramic output capacitors up to 1000uF that might be needed for an application to meet output ripple and noise requirements. Selecting R_{TUNE} and C_{TUNE} according to Table 2 will ensure stable operation of the module. In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} and C_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 1.5A to 3.0A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Table 2. General recommended values of of R_{TUNE} and C_{TUNE} for Vin=12V and various external ceramic capacitor combinations.

Со	1x47μF	2x47µF	4x47μF	6x47μF	10x47µF
R _{TUNE}	270	220	180	180	180
CTUNE	1500pF	1800pF	3300pF	4700pF	4700pF

Table 3. Recommended values of R_{TUNE} and C_{TUNE} to obtain transient deviation of 2% of Vout for a 1.5A step load with Vin=12V.

V	0	5V	3.3V	2.5V	1.8V	1.2V	0.6V
с	o	1x47µF	1x47µF	2x47µF	1×330µF Polymer	1x330µF Polymer	2x330µF Polymer
Rτι	UNE	270	220	180	180	180	180
Ст	UNE	1500pF	1800pF	3300pF	8200pF	8200pF	33nF
Δ	V	68mV	60mV	37mV	18mV	18mV	10mV

Note: The capacitors used in the Tunable Loop tables are 47 μ F/3 m Ω ESR ceramic and 330 μ F/12 m Ω ESR polymer capacitors.

Digital Feature Descriptions

PMBus Interface Capability

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The 3A Digital PicoDLynx[™] power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from <u>www.pmbus.org</u>. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

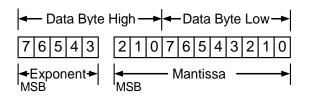
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

Value = Mantissa x 2 Exponent

PMBus Addressing

The power module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127. **Table 4**

Digit	Resistor Value (KΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

The user must know which I²C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

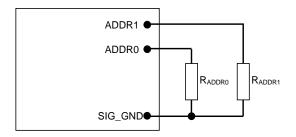


Figure 48. Circuit showing connection of resistors used to set the PMBus address of the module.

PMBus Enabled On/Off

0

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

- : Output is disabled
- 1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	1

3A Digital PicoDLynx[™]: Non-Isolated DC-DC Power Modules 3Vdc −14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

PMBus Adjustable Soft Start Rise Time

The soft start rise time can be adjusted in the module via PMBus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON_RISE command sets the rise time in ms, and allows choosing soft start times between 600µs and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

Table 5

Rise Time	Exponent	Mantissa
600µs	11100	0000001010
900µs	11100	0000001110
1.2ms	11100	0000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

Output Voltage Adjustment Using the PMBus

The VOUT_SCALE_LOOP parameter is important for a number of PMBus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is set as the combination of the voltage divider formed by RTrim and a $20k\Omega$ upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage V_{REF} is nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT} = \left[\frac{20000 + RTrim}{RTrim}\right] \times V_{REF}$$

Hence the module output voltage is dependent on the value of RTrim which is connected external to the module. The information on the output voltage divider ratio is conveyed to the module through the VOUT_SCALE_LOOP parameter which is calculated as follows:

$$VOUT_SCALE_LOOP = \frac{RTrim}{20000 + RTrim}$$

The VOUT_SCALE_LOOP parameter is specified using the "Linear" format and two bytes. The upper five bits [7:3] of the high byte are used to set the exponent which is fixed at -9 (decimal). The remaining three bits of the high byte [2:0] and the eight bits of the lower byte are used for the mantissa. The default value of the mantissa is 0010000000 corresponding to 256 (decimal), corresponding to a divider ratio of 0.5. The maximum value of the mantissa is 512 corresponding to a divider ratio of 1. Note that the resolution of the VOUT_SCALE_LOOP command is 0.2%.

When PMBus commands are used to trim or margin the output voltage, the value of V_{REF} is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module can be adjusted with a minimum step size of 0.4% over a \pm 25% range from nominal using the VOUT_TRIM command over the PMBus.

The VOUT_TRIM command is used to apply a fixed offset voltage to the output voltage command value using the "Linear" mode with the exponent fixed at –10 (decimal). The value of the offset voltage is given by

$V_{OUT(offset)} = VOUT _TRIM \times 2^{-10}$

This offset voltage is added to the voltage set through the divider ratio and nominal V_{REF} to produce the trimmed output voltage. The valid range in two's complement for this command is -4000h to 3FFFh. The high order two bits of the high byte must both be either 0 or 1. If a value outside of the +/-25% adjustment range is given with this command, the module will set it's output voltage to the nominal value (as if VOUT_TRIM had been set to 0), assert SMBALRT#, set the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

Output Voltage Margining Using the PMBus

The module can also have its output voltage margined via PMBus commands. The command VOUT_MARGIN_HIGH sets the margin high voltage, while the command VOUT_MARGIN_LOW sets the margin low voltage. Both the VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW commands use the "Linear" mode with the exponent fixed at -10 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the high byte fixed at 0. The actual margined output voltage is a combination of the VOUT_MARGIN_HIGH or VOUT_MARGIN_LOW and the VOUT_TRIM values as shown below.

 $V_{OUT(MH)} =$

 $(VOUT _ MARGIN _ HIGH + VOUT _ TRIM) \times 2^{-10}$

 $V_{OUT(ML)} =$

$(VOUT _ MARGIN _ LOW + VOUT _ TRIM) \times 2^{-10}$

Note that the sum of the margin and trim voltages cannot be outside the ±25% window around the nominal output voltage. The data associated with VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

The module is commanded to go to the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX	:	Margin Off
0101	:	Margin Low (Ignore Fault)
0110	:	Margin Low (Act on Fault)
1001	:	Margin High (Ignore Fault)

1010 : Margin High (Act on Fault)

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at -1 (decimal). The upper six bits of the mantissa are fixed at 0 while the lower five bits are programmable. For production codes after April 2013, the value for IOUT_OC_WARN_LIMIT will be fixed at 5.0A. For earlier production codes the actual value for IOUT_OC_WARN_LIMIT will vary from module to module due to calibration during production testing. The resolution of this warning limit is 500mA. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module can provide information related to temperature of the module through the STATUS_TEMPERATURE command. The command returns information about whether the pre-set over temperature fault threshold and/or the warning threshold have been exceeded.

PMBus Adjustable Output Over and Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold from four possible values: 108%, 110%, 112% or 115% of the commanded output voltage. The command VOUT_UV_FAULT_LIMIT sets the threshold that causes an output under voltage fault and can also be selected from four possible values: 92%, 90%, 88% or 85%. The default values are 112% and 88% of commanded output voltage. Both commands use two data bytes formatted as two's complement binary integers. The "Linear" mode is used with the exponent fixed to -10 (decimal) and the effective over or under voltage trip points given by:

$V_{OUT(OV_REQ)} = (VOUT_OV_FAULT_LIMIT) \times 2^{-10}$

 $V_{OUT(UV_REQ)} = (VOUT_UV_FAULT_LIMIT) \times 2^{-10}$

Values within the supported range for over and undervoltage detection thresholds will be set to the nearest fixed percentage. Note that the correct value for VOUT_SCALE_LOOP must be set in the module for the correct over or under voltage trip points to be calculated.

In addition to adjustable output voltage protection, the 3A Digital PicoDLynxTM module can also be programmed for the response to the fault. The VOUT_OV_FAULT RESPONSE and VOUT_UV_FAULT_RESPONSE commands specify the response to the fault. Both these commands use a single data byte with the possible options as shown below.

- 1. Continue operation without interruption (Bits [7:6] = 00, Bits [5:3] = xxx)
- Continue for four switching cycles and then shut down if the fault is still present, followed by no restart or continuous restart (Bits [7:6] = 01, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart)
- Immediate shut down followed by no restart or continuous restart (Bits [7:6] = 10, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 4. Module output is disabled when the fault is present and the output is enabled when the fault no longer exists (Bits [7:6] = 11, Bits [5:3] = xxx).

Note that separate response choices are possible for output over voltage or under voltage faults.

PMBus Adjustable Input Undervoltage Lockout

3A Digital PicoDLynxTM: Non-Isolated DC-DC Power Modules 3Vdc -14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command, possible values are 2.75V, and 3V to 14V in 0.5V steps. For the VIN_OFF command, possible values are 2.5V to 14V in 0.5V steps. If other values are entered for either command, they will be mapped to the closest of the allowed values.

VIN_ON must be set higher than VIN_OFF. Attempting to write either VIN_ON lower than VIN_OFF or VIN_OFF higher than VIN_ON results in the new value being rejected, SMBALERT being asserted along with the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

Both the VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes. The upper five bits represent the exponent (fixed at -2) and the remaining 11 bits represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

Power Good

The module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds are user selectable via the PMBus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The POWER_GOOD_ON command sets the output voltage level above which PGOOD is asserted (lower threshold). For example, with a 1.2V nominal output voltage, the POWER_GOOD_ON threshold can set the lower threshold to 1.14 or 1.1V. Doing this will automatically set the upper thresholds to 1.26 or 1.3V.

The POWER_GOOD_OFF command sets the level below which the PGOOD command is de-asserted. This command also sets two thresholds symmetrically placed around the nominal output voltage. Normally, the POWER_GOOD_ON threshold is set higher than the POWER_GOOD_OFF threshold.

Both POWER_GOOD_ON and POWER_GOOD_OFF commands use the "Linear" format with the exponent fixed at –10 (decimal). The two thresholds are given by

 $V_{OUT(PGOOD_ON)} = (POWER_GOOD_ON) \times 2^{-10}$

 $V_{OUT(PGOOD_OFF)} = (POWER_GOOD_OFF) \times 2^{-10}$

Both commands use two data bytes with bit [7] of the high byte fixed at 0, while the remaining bits are r/w and used to set the mantissa using two's complement representation. Both commands also use the VOUT_SCALE_LOOP parameter so it must be set correctly. The default value of POWER_GOOD_ON is set at 1.1035V and that of the POWER_GOOD_OFF is set at 1.08V. The values associated with these commands can be stored in non-volatile memory using the STORE_DEFAULT_ALL command. The PGOOD terminal can be connected through a pullup resistor (suggested value $100 \mbox{K}\Omega)$ to a source of 5VDC or lower.

Measurement of Output Current, Output Voltage and Input Voltage

The module is capable of measuring key module parameters such as output current and voltage and input voltage and providing this information through the PMBus interface. Roughly every 200µs, the module makes 16 measurements each of output current, voltage and input voltage. Average values of of these 16 measurements are then calculated and placed in the appropriate registers. The values in the registers can then be read using the PMBus interface.

Measuring Output Current Using the PMBus

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA. During manufacture, each module is calibrated by measuring and storing the current gain factor and offset into non-volatile storage.

The READ_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at – 4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Note that the current reading provided by the module is not corrected for temperature. The temperature corrected current reading for module temperature T_{Module} can be estimated using the following equation

$$I_{OUT,CORR} = \frac{I_{READ_OUT}}{1 + [(T_{IND} - 30) \times 0.00393]}$$

where I_{OUT_CORR} is the temperature corrected value of the current measurement, I_{READ_OUT} is the module current measurement value, T_{IND} is the temperature of the inductor winding on the module. Since it may be difficult to measure

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 $T_{\text{IND,}}$ it may be approximated by an estimate of the module temperature.

Measuring Output Voltage Using the PMBus

The module can provide output voltage information using the READ_VOUT command. The command returns two bytes of data all representing the mantissa while the exponent is fixed at -10 (decimal).

During manufacture of the module, offset and gain correction values are written into the non-volatile memory of the module. The command VOUT_CAL_OFFSET can be used to read and/or write the offset (two bytes consisting of a 16bit mantissa in two's complement format) while the exponent is always fixed at -10 (decimal). The allowed range for this offset correction is -125 to 124mV. The command VOUT_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$\begin{split} V_{OUT} & (Final) = \\ & [V_{OUT} & (Initial) \times (1 + VOUT _ CAL _ GAIN)] \\ & + VOUT _ CAL _ OFFSET \end{split}$$

Measuring Input Voltage Using the PMBus

The module can provide output voltage information using the READ_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data form the two's complement representation of the exponent which is fixed at –5 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.

During module manufacture, offset and gain correction values are written into the non-volatile memory of the module. The command VIN_CAL_OFFSET can be used to read and/or write the offset - two bytes consisting of a five-bit exponent (fixed at -5) and a11-bit mantissa in two's complement format. The allowed range for this offset correction is -2 to 1.968V, and the resolution is 32mV. The command VIN_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$\begin{split} &V_{IN} \left(Final \right) = \\ &\left[V_{IN} \left(Initial \right) \times \left(1 + VIN _ CAL _ GAIN \right) \right] \\ &+ VIN _ CAL _ OFFSET \end{split}$$

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged. STATUS_BYTE : Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	Х	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD : Returns two bytes of information with a summary of the module's fault/warning conditions.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

High Byte

Thigh byte				
Bit Position	Flag	Default Value		
7	VOUT fault or warning	0		
6	IOUT fault or warning	0		
5	X	0		
4	Х	0		
3	POWER_GOOD# (is negated)	0		
2	Х	0		
1	X	0		
0	Х	0		

STATUS_VOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	Х	0
5	Х	0
4	VOUT UV Fault	0
3	Х	0
2	Х	0
1	X	0
0	Х	0

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STATUS_IOUT : Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	Х	0
3	Х	0
2	Х	0
1	X	0
0	Х	0

STATUS_TEMPERATURE : Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	×	0
4	Х	0
3	×	0
2	Х	0
1	×	0
0	×	0

STATUS_CML : Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	Х	0
3	×	0
2	Х	0
1	Other Communication Fault	0
0	×	0

MFR_VIN_MIN : Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR_VOUT_MIN : Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR_SPECIFIC_00 : Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001000 corresponds to the PDT003 series of module). Bits 1:0 in the High Byte are used to indicate the manufacturer ID, with 00 reserved for GE.

	Low Byte							
Bit Position	Elaa							
7:2	Module Name	001000						
1:0	Reserved	10						

High Byte

Bit Position	Flag	Default Value
7:0	Module Revision Number	None
1:0	Reserved	00

Summary of Supported PMBus Commands Please refer to the PMBus 1.1 specification for more details of these commands.

Table 6

Hex	Command		Brief Description												
Code		Turn Module on or o	off Also	used to	marai	a the ou		ltage			Memory Storage				
		Format		useu it	5		d Binar	5							
		Bit Position	7	6	5	4	3	2	1	0					
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r					
		Function	On	X			rgin		X	X					
		Default Value	0	0	0	0	0	0	Х	Х					
		Configures the ON/ and PMBus commo Format	F pin												
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES				
		Access	r	r	r	r/w	r/w	r/w	r/w	r					
		Function	Х	Х	Х	pu	cmd	cpr	pol	сра					
		Default Value	0	0	0	1	0	1	1	1					
03	CLEAR_FAULTS	Clear any fault bits if the device has be	en asse	erting it.						5					
		setting in the modu	Used to control writing to the module via PMBus. Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory (EEPROM) on the module Format Unsigned Binary												
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	×	×	×	×	X					
	WRITE PROTECT	Function	bit7	bit6	bit5	Х	Х	Х	Х	Х					
10		Default Value Bit5: 0 – Enables all	0	0	0	Х	Х	Х	Х	Х	YES				
		1 – Disables all and ON_OF Bit 6: 0 – Enables al 1 – Disables al OPERATION Bit7: 0 – Enables all 1 – Disables all (bit5 and bit)	F_CONF I writes I writes V comm writes writes t6 must	FIG (bit 6 as pern except ands (b as perm except f be 0)	5 and bi hitted in for the ' it5 and itted in for the V	t7 must i bit5 or WRITE_ bit7 mu bit5 or VRITE_F									
11	STORE_DEFAULT_ALL	Copies all current re (EEPROM) on the me													
12	RESTORE_DEFAULT_ALL	Restores all current non-volatile memo			gs in the	e modul	e from v	values ir	n the m	odule					
13	STORE DEFAULT CODE	Copies the current matches the value module		ata byte	e into no	on-volat	tile men	nory (EE		on the					
15		Bit Position	7	6	5	4	3	2	1	0					
		Access	W	W	W	W Commo	W nd code	W	W	W					
14	RESTORE DEFAULT CODE	Restores the currer matches the value memory (EEPROM)	Function Command code Restores the current register setting in the module whose command code matches the value in the data byte from the value in the module non-volatile memory (EEPROM)												
17		Bit Position	7	6	5	4	3	2	1	0					
		Access Function	W	W	W	w Comma	w nd code	W	W	W					
20	VOUT_MODE	The module has MC cannot be changed Bit Position Access Function		to Linec 6 r Mode			t set to 3 r		1 r	es 0 r					
		Default Value	0	0	0	1	0	1	1	0					
		1									1				

Hex Code	Command			Br	ief Desc	ription					Non-Volatile Memory Storage	
ooue		Apply a fixed offset	voltage	to the		oltage	commo	nd valu			rientory beorage	
		Format	Vontage		inear, tv							
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1/ 00		17 VV		Byte	17 VV	17 VV	17 VV		
22	VOUT_TRIM	Default Value	0	0	0	0	0	0	0	0	YES	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1/ 00	17 VV	17 VV		Byte	17 VV	17 VV	17 VV		
		Default Value	0	0	0	0	0	0	0	0		
				-				v	Ŭ	U		
		Sets the target volt	age for									
		Format	~		inear, tv					<u> </u>		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
25	VOUT_MARGIN_HIGH	Function	<u> </u>				Byte	1		1	YES	
		Default Value	0	0	0	0	0	1	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	0	1	0		Byte	1	1	1		
		Default Value	0	1	0	0	0	1	1	1		
		Sets the target volt	ets the target voltage for margining the output low									
		Format		L	inear, tv	vo's cor	npleme	nt bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
20		Function				High	Byte					
26	VOUT_MARGIN_LOW	Default Value	0	0	0	0	0	1	0	0	YES	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	1	0	1	0	0	0	1		
		Sets the scaling of t ratio	the outp	out volte	age – eq	jual to t	he feed	back re	sistor di	ivider		
		Format		1	inear, tv	vo's cor	npleme	nt bina	rv			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r/w	r/w		
29	VOUT SCALE LOOP	Function			Exponen				Mantiss		YES	
		Default Value	1	0	1	1	1	0	0	1	. 20	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	<u> </u>				tissa			<u> </u>		
		Default Value	0	0	0	0	0	0	0	0		
		Sets the value of input voltage at which the module turns on										
			put volt						~ .	1		
		Format Bit Desition	7		inear, tv			1	<u> </u>			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
35	VIN_ON	Function	1		Exponen		<u> </u>		Mantiss	-	YES	
	_	Default Value	1	1	1	1	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	-				tissa	0	1	1		
		Default Value	0	0	0	0	1	0	1	1		

Hex Code	Command		Brief Description										
		Sets the value of in	put volt	aae at v	which th	e modu	ile turns	soff					
		Format			inear, tv				rv				
		Bit Position	7	6	5	4	3	2	Í 1	0			
		Access	r	r	r	r	r	r	r	r			
76	1411 055	Function			Exponen	t			Mantiss	a	1/50		
36	VIN_OFF	Default Value	1	1	1	1	0	0	0	0	YES		
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function				Man	tissa						
		Default Value	0	0	0	0	1	0	1	0			
		Returns the value c output current											
		Format											
		Bit Position	7	6	inear, tv 5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r/w			
38	IOUT CAL GAIN	Function			- Exponen				Mantiss		YES		
		Default Value	1	0	0	0	1	0	0	V	. 20		
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function				Man	tissa						
		Default Value		V: Vo	ariable b	ased or	n factor	y calibr	ation				
		Returns the value c output current Format	of the of	fset cor		term us	ed to co	orrect th	ne meas	sured			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r/w	r	r			
39	IOUT CAL OFFSET	Function	'		Exponen				Mantiss		YES		
55	IOUT_CAL_OITSET	Default Value	1	1	1	0	0	V	0	0	TLS		
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w			
		Function			.,		tissa			.,			
		Default Value	0	0	V: Vc	-		n factor	v calibr	ation			
		Suggested value sh	Sets the voltage level for an output overvoltage fault. Exponent is fixed at -10. Suggested value shown for 1.2Vo. Should be changed for different output voltage. Values can be 108%, 110%, 112% or 115% of output voltage										
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
40	VOUT_OV_FAULT_LIMIT	Function		17.00	1, 17		Byte	17.00	1, 17	.,	YES		
		Default Value	0	0	0	0	0	1	0	1			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w				r/w			r/w			
		Function					Byte						
		Default Value	0	1	1	0	0	0	0	0			
		Instructs the modu fault	le on wł	nat acti					tput ove	rvoltage			
		Format	<u> </u>				d Binar		1				
41	VOUT OV FAULT RESPONSE	Bit Position	7	6	5	4	3	2	1	0	YES		
		Access	r/w	r/w	r/w	r/w	r/w	r	r	r	. 20		
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	×			
		Default Value	1	1	1	1	1	1	0	0			

Hex Code	Command			Bri	ief Desc	ription					Non-Volatile Memory Storage
		Sets the voltage lev Suggested value sh voltage. Values car	nown fo	r 1.2Vo. 6, 90%,	Should 88% or	be char 85% of	nged for output	[.] differe voltage	nt outpi	d at -10. ut	
		Format	7	1	inear, tv	1	-				
		Bit Position Access	7 r	6 r/w	5 r/w	4 r/w	3 r/w	2 r/w	1 r/w	0 r/w	
44	VOUT_UV_FAULT_LIMIT	Function		1,	1,		Byte	1, 11	17.00	1,00	YES
		Default Value	0	0	0	0	0	1	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function Default Value	0	0	1	Low 1	Byte 1	0	0	1	
		undervoltage fault	Instructs the module on what action to take in response to a output undervoltage fault								
		Format		-			d Binary				
45	VOUT_UV_FAULT_RESPONSE	Bit Position	7 r/w	6 r/w	5 r/w	4 r/w	3 r/w	2 r	1 r	0 r	YES
		Access Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	X	X	
		Default Value	[1] 0	[0] 0	0	0	0	1	0	0	
				ا بدا م							
		Sets the output ove	rcurren		ever in A .inear. tv				Ω.		
		Bit Position	7	6	5	4	3	2	y 1	0	
		Access	r	r	r	r	r	r	r	r	
1.5		Function		-	Exponen				Mantiss		1/50
46	IOUT_OC_FAULT_LIMIT	Default Value	1	1	1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	R	
		Function	<u> </u>				tissa				
		Default Value	0	0	0	0	1	0	1	1	
		Sets the output ove	ercurren								
		Format			inear, tv	1					
		Bit Position	7	6	5	4	3	2	1	0	
		Access Function	r	r	r	r	r	r	r Mantiss	r	
4A	IOUT_OC_WARN_LIMIT	Default Value	1	1	Exponen 1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Man	tissa				
		Default Value	0	0	0	0	1	0	1	0	
		Sets the output vol	tage lev								
		Format			inear, tv				ŕ		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5E	POWER_GOOD_ON	Function Default Value	0	0	0	Hign 0	Byte 0	1	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-
		Function					Byte				
		Default Value	0	1	1	0	1	0	1	0	
			0	Т	1	U	Т	U	T	0	

Table 6 (continued)

Hex Code	Command			Br	ief Desc	ription					Non-Volatile Memory Storage
		Sets the output vol	tage lev	vel at wł	nich the	PGOOD	pin is d	e-asser	ted low	,	
		Format					npleme				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5F	POWER GOOD OFF	Function		1	1	. J	Byte				YES
0.		Default Value	0	0	0	0	0	1	0	0	120
		Bit Position	7	6	5 r/w	4 r/w	3 r/w	2	1	0 r/w	
		Access Function	r/w	r/w	1/W		Byte	r/w	r/w	1/W	
		Default Value	0	1	0	1	0 O	0	1	0	
		•	÷			· ·			-	Ű	
		Sets the rise time o	f the ou								
		Format Bit Position	7	6	linear, ti 5		npleme 3	nt binai 2	y 1	0	
		Access	r	r	r	4 r	r	r	r I	r/w	
		Function	'		Exponer				Mantiss		
61	TON_RISE	Default Value	1	1	1	0	0	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Man	tissa		•		
		Default Value	0	0	1	0	1	0	1	1	
		Returns one byte of information with a summary of the most critical module faults									
		Format		1			d Binary				
78	STATUS_BYTE	Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Flag	Х	OFF	VOUT OV	IOUT_ OC	VIN_U V	TEMP	CML	OTHE R	
		Default Value	0	0	0	0	0	0	0	0	
		Returns two bytes of conditions	of inforr	mation \					's fault/	warning	
		Format		1			d Binary				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	n TUOL	r	r	r	r	r	r	
79	STATUS_WORD	Flag	VOUT	IOUT_ OC	Х	Х	PGOO D	Х	Х	Х	
		Default Value	0	0	0	0	0	0	0	0	
		Bit Position Access	7 r	6 r	5 r	4 r	3 r	2 r	1 r	0 r	
		Flag	X	OFF	VOUT OV	IOUT_	VIN_U V	TEMP	CML	OTHE	
		Default Value	0	0	0	0C 0	0	0	0	R 0	
		Returns one byte o related faults	f inform	nation w	ith the s	status o	f the mo	odule's (output v	voltage	
		Format				Jnsigne	d Binary	/			
7A	STATUS_VOUT	Bit Position	7	7	6 5		4		2 1	0	
	—	Access	r		r r		r		r r	r	
		Flag Default Value	VOU ⁻		X X 0 0		JT_UV 0		X X 0 0	X 0	
		Returns one byte o related faults	f inform	iation w	ith the s	status o	f the mo	odule's (output o	current	
		Format					ed Binary				
7B	STATUS_IOUT	Bit Position	7	7	6	5		4 3		1 0	
		Access	n		r	r		r r		r r	
		Flag Default Value	IOUT (X IO 0	UT_OC_ 0	_warn	X X 0 0		X X 0 0	
L											1

Hex Code	Command			В	rief Des	criptio	n						Non-Volatile Memory Storage
		Returns one byte o related faults	f inform	ation \	with the	status	of th	e mo	dule's	tempe	eratu	ure	
		Format				Unsign	ed B	inary	,				
7D	STATUS_TEMPERATURE	Bit Position	7		6		5	4	3	2	1	0	
		Access	r		r		r	r	r	r	r	R	
		Flag	OT_F/		OT_W		X	X	X 0	X	X	X	
		Default Value	C)		,	0	0	0	0	0	0	
		related faults											
		Format				Unsign						-	
75		Bit Position	7		6	5	4	3	2	1		0	
7E	STATUS_CML	Access	r		r	r	r	r	r	r Othe		r	
		Flag	Inva Comm		Invalid Data	PEC Fail	Х	х	х	Com Fau	m	х	
		Default Value	0		0	0	0	0	0	0		0	
		Returns the value of	of the in										
		Format			Linear,						-		
		Bit Position	7	6	5	4		3	2	1		0	
		Access Function	r	r	r	r		r	r	r Mantis	200	r	
88	READ_VIN	Default Value	1	1	Expone 0	1		1	0	0	ssu	0	
		Bit Position	7	6	5	4		3	2	1		0	
		Access	r	r	r	r	-	r	r	r		r	
		Function				Ма	ntiss	a					
		Default Value	0	0	0	0		0	0	0		0	
		Returns the value c	of the ou	itput v	oltaae c	of the m	odul	е					
		Format			Linear, 1				nt binc	iry			
		Bit Position	7	6	5	4		3	2	1		0	
		Access	r	r	r	r		r	r	r		r	
8B	READ_VOUT	Function			T -	1	ntiss					_	
		Default Value	0	0	0	0		0	0	0		0	
		Bit Position Access	7 r	6 r	5 r	4 r	-	3 r	2 r	1 r	_	0 r	
		Function					ntiss		I			I	
		Default Value	0	0	0	0		0	0	0		0	
		Returns the value c	of the ou	itput c	urrent o	f the m	odul	e					
		Format			Linear, t	two's co	ompl	emer		iry			
		Bit Position	7	6	5	4		3	2	1		0	
		Access	r	r	r	l r		r	r	r		r	
8C	READ_IOUT	Function	1	1	Expone			0		Mantis	ssa	0	
	_	Default Value Bit Position	1	1 6	1	0		0 3	0 2	0	_	0	
		Access	r	r	r	r		r	r	r		r	
		Function	<u> </u>			Ma	ntiss	a		. '		•	
		Default Value	0	0	0	0		0	0	0		0	
		Returns one byte indicating the module is compliant to PMBus Spec. 1.1 (read only)											
98	PMBUS REVISION	Format	<u> </u>		_	Unsign				-			YES
90	FIIDOS_NEVISION	Bit Position	7	6	5	4	-	3	2	1		0	IL3
		Access	r	r	r	r 1	_	r O	r	r		r 1	
		Default Value	0	0	0	1		0	0	0		1	

Hex Code	Command				Brief D	escripti	ion					Non-Volatile Memory Storage
couc		Returns the minimu	ım inpu	t voltaa	e the m	odule is	specifie	ed to or	perate a	t (read (only)	Tieniory Storage
		Format	l		_inear, tv					t fredd t]	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function			Exponer	nt			Mantiss	a		
AO	MFR_VIN_MIN	Default Value	1	1	1	1	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0	-	
		Access	r	r	r	r	r	r	r	r		
		Function				Man	tissa					
		Default Value	0	0	0	0	1	1	0	0		
		Returns the minimu	im outr	out volto	nae poss	ible fro	m the m	nodule (read on	lv)		
		Format			_inear. tv					.,,	1	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function				Man	tissa					
A4	MFR_VOUT_MIN	Default Value	0	0	0	0	0	0	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function				Man	itissa					
		Default Value	0	1	1	0	0	1	1	0		
		Returns module na	me info	rmatior	n (read o	nly)						
		Format			I	Jnsigne	ed Binar	У				
	D0 MFR SPECIFIC 00	Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
DO		Function				Rese	erved					YES
DU	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function		1		e Name				erved		
		Default Value	0	0	1	0	0	0	1	0		
		Applies an offset to	the RE/	AD VOL	JT comn	hand re	sults to	calibra	te out o	ffset err	ors in	
		module measurem									_	
		Format		l	_inear, tv	vo's cor	mpleme	nt bina	ry			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r	r	r	r	r	r	r		
D4	VOUT_CAL_OFFSET	Function			1		ntissa				-	YES
		Default Value	V	0	0	0	0	0	0	0	-	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	-	
		Function Default Value	V	V	V	Man V	ntissa V	V	V	V	-	
			V	V	V	V	V	V	V	V	1	
		Applies a gain corre	ection t	o the RI		UT com	mand r	esults t	o calibr	ate out :	nain	
		errors in module m										
		Format			_inear, tv						1	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r	1	
D5	VOUT CAL GAIN	Function			Exponer	nt	-		Mantiss		1	YES
_		Default Value	1	1	0	0	0	0	0	V		-
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value	V	V	V	V	V	V	V	V		
											-	

Hex Code	Command		Brief Description										
		Applies an offset co errors in module m											
		Format		L	inear, tv	vo's cor	npleme	nt binaı	ту –				
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r/w	r	r			
D6	VIN_CAL_OFFSET	Function		E	Exponer	nt		1	Mantiss	a		YES	
		Default Value	1	1	0	1	V	0	0	V			
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w			
		Function				Man	itissa						
		Default Value	0	0	V	V	V	V	V	V			
		Applies a gain corre errors in module m		ments o		out volto	age (bet	ween -().125 ar				
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r/w	r	r			
D7	VIN CAL GAIN	Function			Exponer	nt			Mantiss	а. С		YES	
01		Default Value	1	1	0	0	V	0	0	V		125	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w			
		Function			. · ·	· · ·	itissa						
		Default Value	0	0	0	V	V	V	V	V			

3A Digital PicoDLynx[™]: Non-Isolated DC-DC Power Modules 3Vdc −14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 49. The preferred airflow direction for the module is in Figure 50.

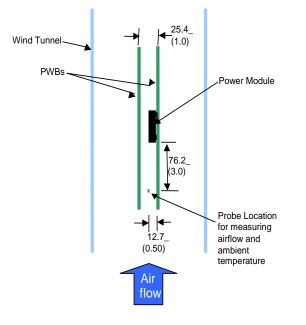
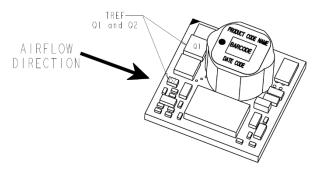
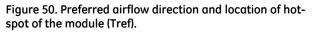


Figure 49. Thermal Test Setup.

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 50. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.





3A Digital PicoDLynx[™]: Non-Isolated DC-DC Power Modules

3Vdc –14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

Shock and Vibration

The ruggedized (-D version) of the modules are designed to withstand elevated levels of shock and vibration to be able to operate in harsh environments. The ruggedized modules have been successfully tested to the following conditions:

Non operating random vibration:

Random vibration tests conducted at 25C, 10 to 2000Hz, for 30 minutes each level, starting from 30Grms (Z axis) and up to 50Grms (Z axis). The units were then subjected to two more tests of 50Grms at 30 minutes each for a total of 90 minutes.

Operating shock to 40G per Mil Std. 810G, Method 516.4 Procedure I:

The modules were tested in opposing directions along each of three orthogonal axes, with waveform and amplitude of the shock impulse characteristics as follows:

All shocks were half sine pulses, 11 milliseconds (ms) in duration in all 3 axes.

Units were tested to the Functional Shock Test of MIL-STD-810, Method 516.4, Procedure I - Figure 516.4-4. A shock magnitude of 40G was utilized. The operational units were subjected to three shocks in each direction along three axes for a total of eighteen shocks.

Operating vibration per Mil Std 810G, Method 514.5 Procedure I:

The ruggedized (-D version) modules are designed and tested to vibration levels as outlined in MIL-STD-810G, Method 514.5, and Procedure 1, using the Power Spectral Density (PSD) profiles as shown in Table 1 and Table 2 for all axes. Full compliance with performance specifications was required during the performance test. No damage was allowed to the module and full compliance to performance specifications was required when the endurance environment was removed. The module was tested per MIL-STD-810, Method 514.5, Procedure I, for functional (performance) and endurance random vibration using the performance and endurance levels shown in Table 7 and Table 8 for all axes. The performance test has been split, with one half accomplished before the endurance test and one half after the endurance test (in each axis). The duration of the performance test was at least 16 minutes total per axis and at least 120 minutes total per axis for the endurance test. The endurance test period was 2 hours minimum per axis.

Table 7. Performance vibration Qualification - All Akes													
Frequency (Hz)	PSD Level (G2/Hz)	Frequency (Hz)	PSD Level (G2/Hz)	Frequency (Hz)	PSD Level (G2/Hz)								
10	1.14E-03	170	2.54E-03	690	1.03E-03								
30	5.96E-03	230	3.70E-03	800	7.29E-03								
40	9.53E-04	290	7.99E-04	890	1.00E-03								
50	2.08E-03	340	1.12E-02	1070	2.67E-03								
90	2.08E-03	370	1.12E-02	1240	1.08E-03								
110	7.05E-04	430	8.84E-04	1550	2.54E-03								
130	5.00E-03	490	1.54E-03	1780	2.88E-03								
140	8.20E-04	560	5.62E-04	2000	5.62E-04								

Table 7: Performance Vibration Qualification - All Axes

Table 8: Endurance Vibration Qualification - All Axes

Frequency (Hz)	PSD Level (G2/Hz)	Frequency (Hz)	PSD Level (G2/Hz)	Frequency (Hz)	PSD Level (G2/Hz)			
10	0.00803	170	0.01795	690	0.00727			
30	0.04216	230	0.02616	800	0.05155			
40	0.00674	290	0.00565	890	0.00709			
50	0.01468	340	0.07901	1070	0.01887			
90	0.01468	370	0.07901	1240	0.00764			
110	0.00498	430	0.00625	1550	0.01795			
130	0.03536	490	0.01086	1780	0.02035			
140	0.0058	560	0.00398	2000	0.00398			

Example Application Circuit

Requirements:										
Vin: 12V										
Vout: 1.8V										
lout: 2.25A max., worst case load transient is from 1.5A to 2.25A										
ΔVout: 1.5% of Vout (27mV) for worst case load transient	1.5% of Vout (27mV) for worst case load transient									
Vin, ripple 1.5% of Vin (180mV, p-p)										
Vin+	Vout+									
VIN VOUT										
PGOOD VS+										
MODULE										
—— SEQ										
\pm CI3 \pm CI2 \pm CI1 TRIM $-$	=CO1									
DATA ADDR0										
ADDR1 RTrim										
$-ON/OFF$ \leq RADDR1 \leq RADDR0										
SIG_GND										
SYNC GND VS-										
GND										

CI1	Decoupling cap - 1x0.047 μ F/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)
CI2	1x22µF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)
CI3	470μF/16V bulk electrolytic
CO1	Decoupling cap - $1 \times 0.047 \mu$ F/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)
CO2	-
CO3	1x330uF
CTune	2200pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune	220 ohms SMT resistor (can be 1206, 0805 or 0603 size)
RTrim	$10 \mathrm{k}\Omega$ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

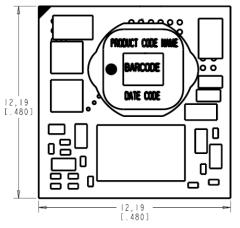
<u>Note:</u> The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.

Mechanical Outline

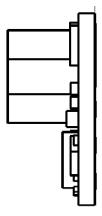
Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)







SIDE VIEW

FUNCTION

PGOOD

SYNC¹

VS-

SIG. GND

SMBALERT#

DATA

ADDR0

ADDR1

10

11

12

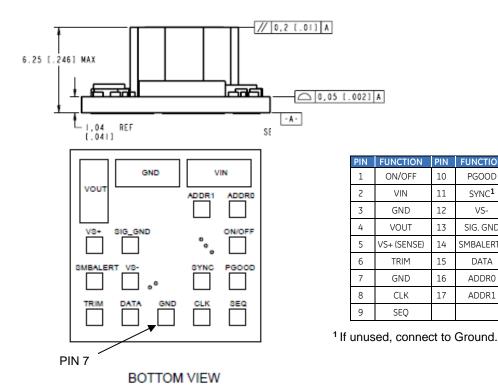
13

14

15

16

17

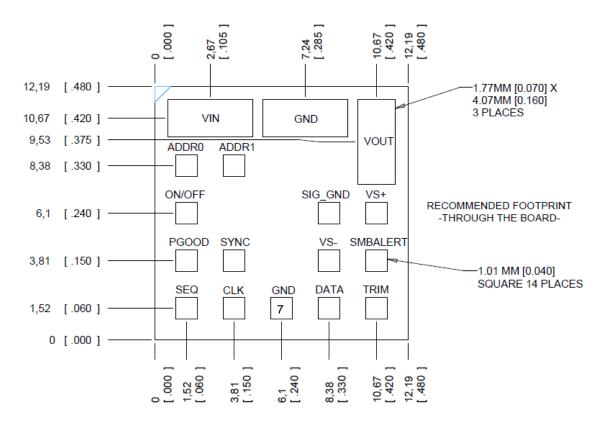


Recommended Pad Layout

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



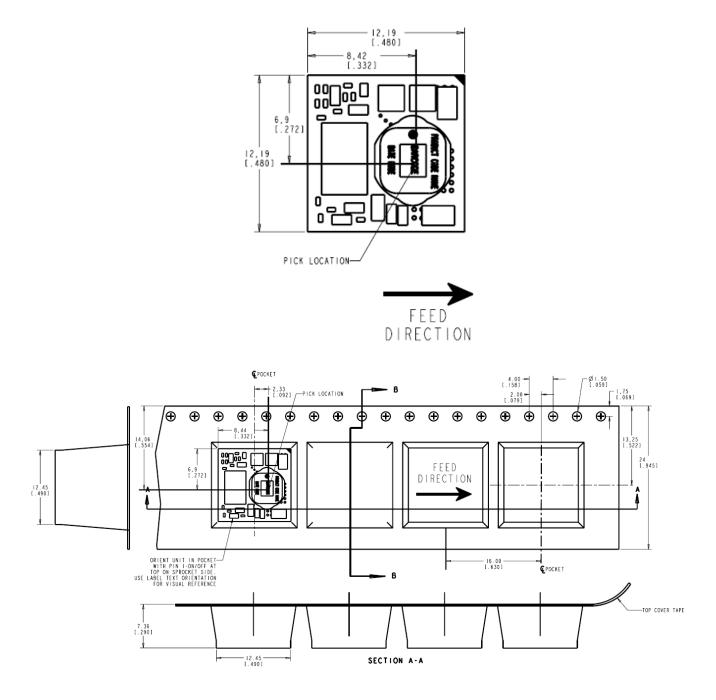
PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	10	PGOOD
2	VIN	11	SYNC ²
3	GND	12	VS-
4	VOUT	13	SIG_GND
5	VS+ (SENSE)	14	SMBALERT#
6	TRIM	15	DATA
7	GND	16	ADDR0
8	CLK	17	ADDR1
9	SEQ		

² If unused, connect to Ground

Packaging Details

The 12V Digital PicoDLynx[™] 3A modules are supplied in tape & reel as standard. Modules are shipped in quantities of 200 modules per reel.

All Dimensions are in millimeters and (in inches).



Reel Dimensions: Outside Dimensions: Inside Dimensions: Tape Width:

330.2 mm (13.00) 177.8 mm (7.00") 24.00 mm (0.945")

3A Digital PicoDLynx™: Non-Isolated DC-DC Power Modules

3Vdc -14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

Surface Mount Information

Pick and Place

GF

The 3A Digital PicoDLynx[™] modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

Bottom Side / First Side Assembly

Only the -D version of this module can be placed at the bottom side of the customer board. No additional glue or adhesive is required is required to hold the module during the top side reflow process

Lead Free Soldering

The 12VDigital PicoDLynx[™] 3A modules are lead-free (Pbfree) and RoHS compliant and are both forward and backward compatible in a Pb-free and a SnPb soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 5-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 51. Soldering outside of the recommended profile requires testing to verify results and performance.

It is recommended that the pad layout include a test pad where the output pin is in the ground plane. The thermocouple should be attached to this test pad since this will be the coolest solder joints. The temperature of this point should be:

Maximum peak temperature is 260 C. Minimum temperature is 235 C. Dwell time above 217 C: 60 seconds minimum Dwell time above 235 C: 5 to 15 second

MSL Rating

The 3A Digital PicoDLynx[™] modules have a MSL rating of 2a.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. B (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of \leq 30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: $< 40^{\circ}$ C, < 90% relative humidity.

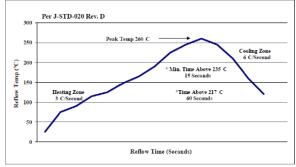


Figure 51. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (AN04-001).

3A Digital PicoDLynx™: Non-Isolated DC-DC Power Modules

3Vdc -14.4Vdc input; 0.45Vdc to 5.5Vdc output; 3A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 9. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Comcodes
PDT003A0X3-SRZ	3 – 14.4Vdc	0.45 – 5.5Vdc	3A	Negative	Yes	CC109159546
PDT003A0X3-SRDZ	3 – 14.4Vdc	0.45 – 5.5Vdc	3A	Negative	Yes	150021796
PDT003A0X43-SRZ	3 – 14.4Vdc	0.45 – 5.5Vdc	3A	Positive	Yes	CC109159554

-Z refers to RoHS compliant parts

Table 10. Coding Scheme

Package Identifier	Family	Sequencing Option		Output voltage		Remote Sense	Options		ROHS Compliance
Р	D	Т	003A0	×	4	3	-SR	-D	Z
P=Pico U=Micro M=Mega G=Giga	D=Dlynx Digital V = DLynx Analog.	T=with EZ Sequence X=without sequencing	3A	X = progra mmable output	4 = positive No entry = negative	3 = Remote Sense	S = Surfac e Mount R = Tape & Reel	D = 105°C operating ambient, 40G operating shock as per MIL Std 810G, placement on bottom side of board	Z = ROHS6

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