120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to1.5Vdc output; 120A Output Current

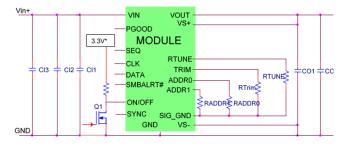




RoHS Compliant

Applications

- Networking equipment
- Telecommunications equipment
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to IPC-9592 (September 2008), Category 2
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- Wide Input voltage range (7Vdc-14 Vdc)
- Output voltage programmable from 0.6Vdc to 1.5Vdc via external resistor or PMBus™# commands
- Digital interface through the PMBus protocol
- Digital sequencing
- Fast digital loop control
- Power Good signal
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Output overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Cost efficient open frame design
- Small size: 53.8 x 31.7 x 13.3 mm [2.118" x 1.248" x 0.524"]
- Wide operating temperature range [-40°C to 85°C]
- ANSI/UL* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

The 120A Digital TeraDLynx™ power modules are non-isolated dc-dc converters that can deliver up to 120A of output current. These modules operate over a 7 to 14Vdc input range and provide a precisely regulated output voltage from 0.6 to 1.5Vdc. The output voltage is programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, Power Good signal and overcurrent, overvoltage and overtemperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes a real time compensation loop that allows optimizing the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- * CSA is a registered trademark of Canadian Standards Association.
- VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- ** ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



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Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are only absolute stress ratings, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage - Continuous	All	V_{IN}	-0.3	15	V
SEQ, ADDR0, ADDR1, RTUNE, RTRIM, SYNC, VS+, ON/OFF	All		-0.3	3.6	V
CLK, DATA, SMBALERT#	All		-0.3	3.6	V
Operating Ambient Temperature	All	T _A	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T_{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V _{IN}	7	_	14	Vdc
Maximum Input Current	All	I _{IN,max}			29	Adc
(V _{IN} =7V to 14V, I _O =I _{O, max})						
Input No Load Current	V _{O,set} = 0.6 Vdc	I _{IN,No load}		160		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V _{O,set} = 1.5Vdc	I _{IN1No load}		200		mA
Input Stand-by Current (V _{IN} = 12Vdc, module disabled)	All	I _{IN,stand-by}		62		mA
Inrush Transient	All	I ² t		1		A^2s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1μ H source impedance; V_{IN} =0 to 14V, I_{O} = I_{Omax} ; See Test Configurations)	All			5		mAp-p
Input Ripple Rejection (120Hz)	All			-54		dB
Output Voltage Set-point Tolerance over output voltage range from 0.5 to 1.5V						
0 to 85°C	All	$V_{O, set}$	-0.7		+0.7	% V _{O, set}
-40 to 85ºC	All	$V_{O,set}$	-1.0		+1.0	% V _{O, set}
Voltage Regulation ¹						
Line Regulation	(V _{IN} =V _{IN, min} to V _{IN, max})			2		mV
	(12V _{IN} ±20%)			1		mV
Load (I _O =I _{O, min} to I _{O, max}) Regulation	All			4		mV

 $^{^{1}}$ Worst case Line and load regulation data, all temperatures, from design verification testing as per IPC9592.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Adjustment Range (selected by an external resistor)	All	V _{OUT}	0.6		1.5	Vdc
PMBus Adjustable Output Voltage Range	All	V _{OUT}	0.6		1.5	Vdc
PMBus Output Voltage Adjustment Step Size	All			61 ²		μV
Remote Sense Range	All				0.3	Vdc
Output Ripple and Noise on nominal output $(V_{IN}{=}V_{IN,nom} \ and \ I_{O}{=}I_{O,min} \ to \ I_{O,max} \ Co = 1500 \ \mu F$						
Peak-to-Peak (Full bandwidth)					30	mV_{pk-pk}
RMS (Full bandwidth)	All				12	mV_{rms}
External Capacitance ³						
Minimum output capacitance	All	$C_{O,min}$	1500	_	_	μF
Maximum output capacitance	All	C _{O, max}	_	_	40000	μF
Output Current (in either sink or source mode)	All	Io	0.005 *		120	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		110		% I _{o,max}
Output Short-Circuit Current	All	$I_{O1, s/c}$, $I_{O1, s/c}$		40		Arms
(V _o ≤250mV) (Hiccup Mode)						
Efficiency	$V_{O,set} = 0.6Vdc$	η		88.2		%
	$V_{O, set} = 0.8Vdc$	η		90.9		%
V_{IN} = 12Vdc, T_A =25°C	$V_{O,set} = 1.0Vdc$	η		92.1		%
$I_O=I_{O, max}$, $V_O=V_{O, set}$	V _{O,set} = 1.2Vdc	η		93.0		%
	V _{O, set} = 1.5Vdc	η		94.0		%
Switching Frequency	All	f _{sw}	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-15		+15	%
High-Level Input Voltage	All	V _{IH} ,SYNC	2.5			V
Low-Level Input Voltage	All	V _{IL,SYNC}			1.1	V
Minimum Pulse Width, SYNC	All	tsync	256			ns

^{*} Minimum load on module should be 5mA

² this must be supported by an appropriate PMBus tool capable of writing at that resolution

³ External capacitors may require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop™ section for details.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I _O =0.8I _{O, max} , T _A =40°C) Telecordia Issue 2 Method 1 Case 3	All		11,556,226		Hours
Weight - Module with SMT Pins			57 (2.01)		g (oz.)
Module with Through Hole Pins			59 (2.08)		g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
$(V_{IN}=V_{IN,min}$ to $V_{IN,max}$; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
	A.II	1			4	A
Input High Current	All	Іін	_	_	1	mA
Input High Voltage	All	VIH	2	_	3.6*	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
Input High Current	All	Іін	_	_	10	μА
Input High Voltage	All	VIH	2	_	3.6*	Vdc
	All	VIII	2		3.0	Vuc
Logic Low (Module OFF)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times						
(V _{IN} =V _{IN, nom} , I _O =I _{O, max} , V _O to within $\pm 1\%$ of steady state)						
Case 1: On/Off input is enabled and then input power is						
applied (delay from instant at which $V_{IN} = V_{IN, min}$ until $V_0 = 100$ (eV)	All	Tdelay	_	30	_	ms
10% of Vo, set) Case 2: Input power is applied for at least one second and						
then the On/Off input is enabled (delay from instant at	All	Tdelay	_	15	_	ms
which Von/Off is enabled until Vo = 10% of Vo, set)		,				
Output voltage Rise time (time for Vo to rise from 10% of Vo, set to 90% of Vo, set)	All	Trise	_	10	_	msec
Output voltage overshoot (T _A = 25°C						
$V_{IN} = V_{IN, min}$ to $V_{IN, max}$, $I_O = I_{O, min}$ to $I_{O, max}$)		Output			3.0	% V _{O, set}
With or without maximum external capacitance						
Over Temperature Protection (See Thermal Considerations section)	All	T_{ref}		135		°C
<u>'</u>	ΔII	Turanu		125		°C
PMBus Over Temperature Warning Threshold	All	T _{WARN}		125		°C

^{*}Use external resistive voltage divider to step down higher logic voltages

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
Tracking Accuracy (Power-Up: 0.5V/ms)	All	VSEQ -Vo			100	mV
(Power-Down: 0.5V/ms)	All	VSEQ –Vo			100	mV
(V _{IN, min} to V _{IN, max} ; I _{O, min} to I _{O, max} V _{SEQ} < V _O)						
Input Undervoltage Lockout						
Turn-on Threshold	All				7	Vdc
Turn-off Threshold	All		6.75			Vdc
Hysteresis	All			0.25		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		7		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All				5.8	mV
PGOOD (Power Good) for output voltages set with Rtrim**						
Signal Interface Open Drain, $V_{supply} \le 5VDC$						
Overvoltage threshold for PGOOD ON	All			112.5		$%V_{O, set}$
Undervoltage threshold for PGOOD OFF	All			87.5		%V _{O, set}
Pulldown resistance of PGOOD pin	All				2	Ω
Sink current capability into PGOOD pin	All				50	mA

^{**}If output voltage is set using VOUT COMMAND(21h) then PGOOD ON and PGOOD OFF thresholds should be manually set through PMBus commands 5E and 5F

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		ViH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			1.1	V
Input high level current (CLK, DATA)		I _{IH}			0.5	μΑ
Input low level current (CLK, DATA)		IIL			4	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{out} =4mA	Vol			0.25	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	5		55	nA
Pin capacitance		Co			10	pF
PMBus Operating frequency range	Slave Mode	FРMВ	10		1000	kHz
Data hold time		thd:dat		0		ns
Data setup time		t su:dat		100		ns
Measurement System Characteristics	<u>.</u>					
Read delay time		tdly		110		μs
Output current measurement range		I _{RNG}	0		135	Α
Output current measurement resolution		IRES		250		mA
Output current measurement accuracy	-40°C to +85°C	I _{ACC}			±5	% of lo,max
V _{OUT} measurement range		V _{OUT}	0		2.0	V
V _{OUT} measurement accuracy		V _{OUT(gain)}		±1		% of Vo,max
V _{OUT} measurement resolution		V _{OUT(res)}		0.61		mV
V _{IN} measurement range		V _{IN}	0		16	V
V _{IN} measurement accuracy		V _{IN(gain)}		±2		%
V _{IN} measurement resolution		V _{IN(res)}		5.8		mV
Temperature measurement range		T _{MEAS}	-25		150	°C
Temperature measurement accuracy		T _{MEAS(gain)}	-8		8	°C
Temperature measurement resolution		T _{MEAS(res)}		0.08		°C

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 0.6Vo and 25°C.

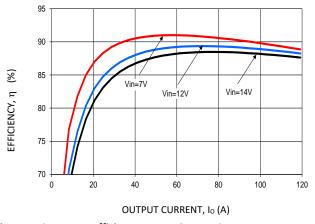


Figure 1. Converter Efficiency versus Output Current.

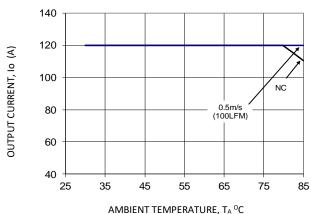
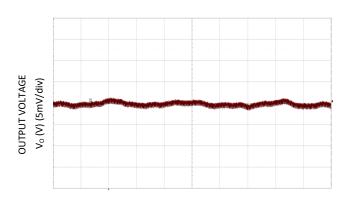
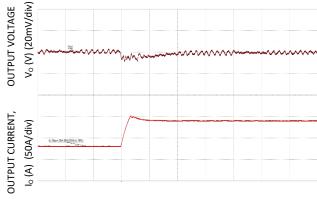


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

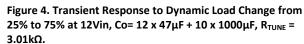


TIME, t (50μs/div)



TIME, t (200µs /div)

Figure 3. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{0,max_s}$).



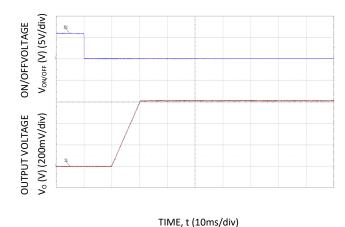


Figure 5. Typical Start-up Using On/Off Voltage (Io = Io, max).



Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

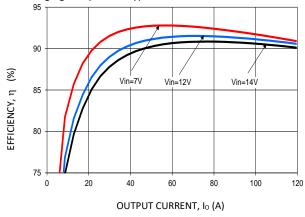
TIME, t (10ms/div)

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

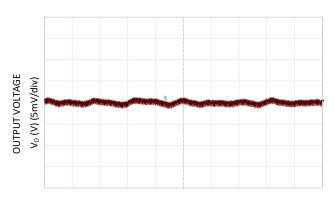
The following figures provide typical characteristics for the 120A TeraDLynx™ at 0.8Vo and 25°C

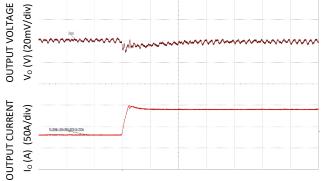


1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 NC 80 0.5m/s (100LFM) 60 40 25 35 55 65 75 85 AMBIENT TEMPERATURE, TA °C

Figure 7. Converter Efficiency versus Output Current.

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

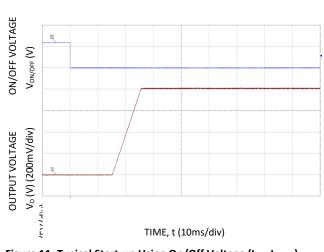




 $TIME, t~(50\mu s/div)$ Figure 9. Typical output ripple and noise (C₀=12x47 μ F ceramic + 10x470 μ F polymer, V_{IN} = 12V, I₀ = I_{0,max},)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .

TIME, t (200µs /div)



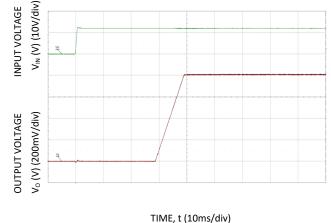


Figure 11. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).

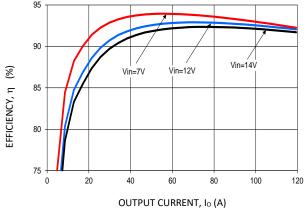
Figure 12. Typical Start-up Using Input Voltage (V_{IN} = 12V, I_0 = $I_{o,max}$).

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.0Vo and 25°C.



140 1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 80 0.5m/s (100LFM) 60 40 25 35 45 55 65 75 85 AMBIENT TEMPERATURE, TA OC

Figure 13. Converter Efficiency versus Output Current.

Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

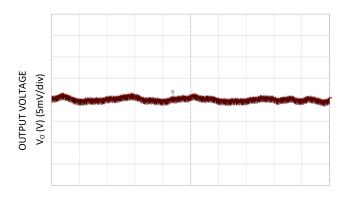


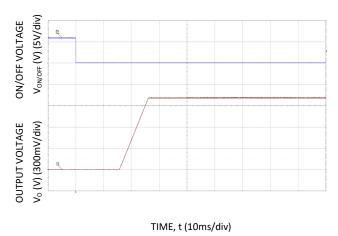


Figure 15. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{O,max}$,)

TIME, t (50µs/div)

Figure 16. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .

TIME, t (200µs /div)



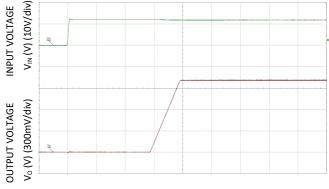


Figure 17. Typical Start-up Using On/Off Voltage (Io = Io,max).

Figure 18. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

TIME, t (10ms/div)

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.2Vo and 25°C.

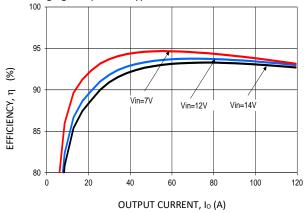


Figure 19. Converter Efficiency versus Output Current.

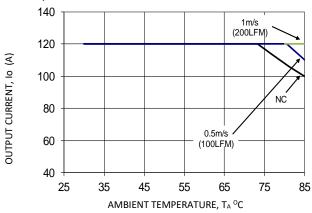
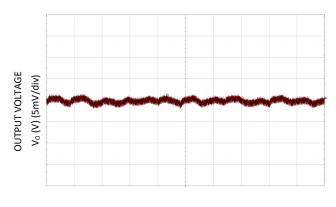
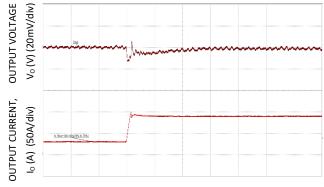


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

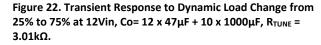


TIME, t (50µs/div)



TIME, t (200µs /div)

Figure 21. Typical output ripple and noise (C_0 =12x47 μ F ceramic + 10x470 μ F polymer, $V_{\rm IN}$ = 12V, I_0 = $I_{o,max,}$)



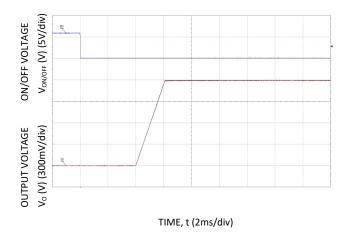
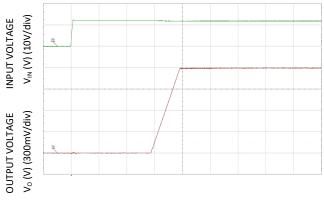


Figure 23. Typical Start-up Using On/Off Voltage (Io = Io,max).



TIME, t (10ms/div)

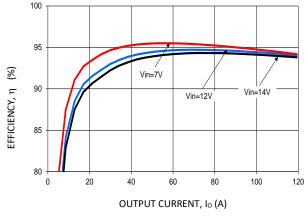
Figure 24. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

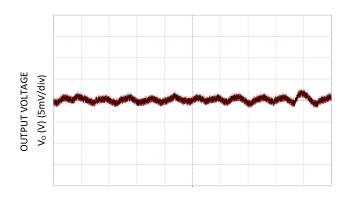
The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.5Vo and 25°C.



140 1m/s (200LFM) 120 OUTPUT CURRENT, Io (A) 100 80 NC 0.5m/s 60 (100LFM) 40 25 35 55 75 85 45 65 AMBIENT TEMPERATURE, TA °C

Figure 25. Converter Efficiency versus Output Current.

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.



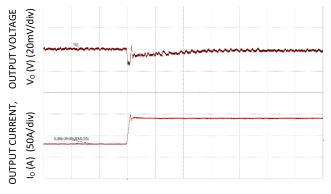
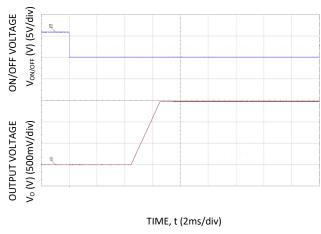


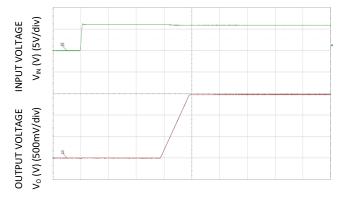
Figure 27. Typical output ripple and noise ($C_0=12x47\mu F$ ceramic + $10x470\mu F$ polymer, $V_{IN}=12V$, $I_0=I_{O,max,}$)

TIME, t (50µs/div)

Figure 28. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .

TIME, t (200µs /div)





Eigure 20 Tunical Start un Heing On/Off Voltage (L. - L.)

Eigura 20 Tunical Start un Heing Innut Valtaga (Vin - 12V I. -

TIME, t (2ms/div)

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Design Considerations

Input Filtering

The 120A TeraDLynx[™] module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 120A of load current with 4x470 + 12x22 + 12x4.7 μF and 2x470 + 6x22 + 12x4.7 μF input capacitor combinations.

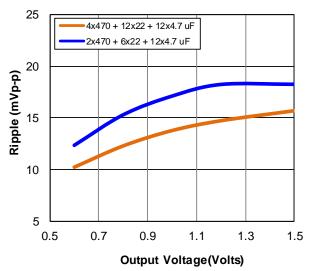


Figure 31. Input ripple voltage for various output voltages with two input capacitor combinations at 120A load. Input voltage is 12V.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of 12 x 22 μF ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 32 provides output ripple information for capacitance of ~3574uF (47µF (1210 ceramic) x 12 + 10µF (0805 ceramic) + 0.1µF (0402) x4 + 1000µF (polymer) x 3) at various Vo and a full load current of 120A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can

be achieved by using the Tunable Loop $^{\text{TM}}$ feature described later in this data sheet.

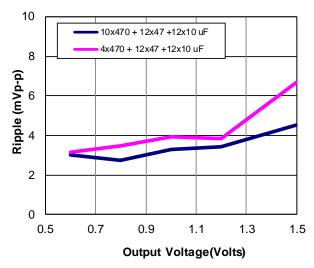


Figure 32. Peak to peak output ripple voltage for various output voltages with external capacitors at the output (120A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a slow-blow fuse. When the input voltage is \leq 8V, the recommendation is to use two 25A Littelfuse 456 series or equivalent fuses in parallel. For input voltages > 8V, a single 40A Littelfuse series 456 or equivalent fuse is recommended.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Analog Feature Descriptions

Remote On/Off

The TeraDLynx 120A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF can controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 120A Digital TeraDLynx™ power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

Digital On/Off

Please see the Digital Feature Descriptions section.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior on the output for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module will start into a pre biased output on output as long as the pre bias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.6 to 1.5Vdc, as shown in Table 1, by connecting a resistor between the Trim and SIG_GND pins of the module as shown in Fig 33.

Without an external resistor between the Trim pin and SIG_GND pins, the output of the module will be 0.1 Vdc. The

value of the trim resistor, R_{Trim} for a desired output voltage, should be selected as shown in Table 1.

The trim resistor is only determined during module initialization and hence cannot be used for dynamic output voltage adjustment

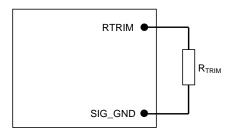


Figure 33. Circuit configuration for programming output voltage using an external resistor.

Table 1

V _{O, set} (V)	Rtrim (Ω)	V _{O, set} (V)	Rtrim (Ω)	V _{O, set} (V)	Rtrim (Ω)
0.600	1090	1.000	2870	1.400	18900
0.620	1140	1.020	3050	1.420	23200
0.640	1180	1.040	3240	1.440	29800
0.660	1230	1.060	3480	1.460	40200
0.680	1290	1.080	3700	1.480	60400
0.700	1330	1.100	3920	1.500	115000
0.720	1380	1.120	4220		
0.740	1470	1.140	4530		
0.760	1560	1.160	4990		
0.780	1640	1.180	5360		
0.800	1740	1.200	5900		
0.820	1820	1.220	6420		
0.840	1930	1.240	6980		
0.860	2030	1.260	7680		
0.880	2130	1.280	8450		
0.900	2230	1.300	9420		
0.920	2340	1.320	10400		
0.940	2460	1.340	11700		
0.960	2610	1.360	13500		
0.980	2710	1.380	15800		

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for the output. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.3V.

Digital Output Voltage Margining

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Please see the Digital Feature Descriptions section.

Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

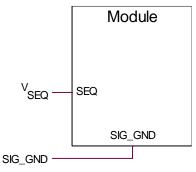


Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Digital Sequencing

The module can support digital sequencing by allowing control of the turn-on delay and rise times as well as turn-off and fall times.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Overcurrent Protection (OCP)

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. OCP response time is programmable through manufacturer specific commands. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable Overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 135 °C (typ) is exceeded at the thermal reference point T_{ref} . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Adjustable Overcurrent Warning/Shutdown

Please see the Digital Feature Descriptions section.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation for the associated output is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Synchronization

The module switching frequency is capable of being synchronized to an external signal frequency within a specified range. Synchronization is done by using the external signal applied to the SYNC pin of the module as shown in Fig. 35, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

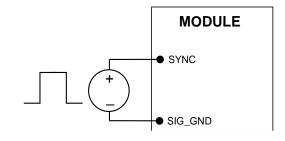


Figure 35. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Digital Compensator

The TJT120 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The TJT120 comes with default compensation values programmed into the non-volatile memory of the module. These digital compensation values can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This can be done by two different methods.

- By allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. This selection is made via a resistor RTune connected between the RTUNE and SIG_GND pins as shown in Fig. 35. Table 2 shows various pre-tuned compensation combinations recommended for various external capacitor combinations.
- Using PMBus to change compensation parameters in the module.

Note that during initial startup of the module, compensation values that are stored in non-volatile memory are used. If a resistor RTune is connected to the module, then the compensation values are changed to ones that correspond to the value of RTUNE. If RTUNE is open however, no change in compensation values is made. Finally, if the user chooses to do so, they can overwrite the compensation values via PMBus commands.

Recommended values of R_{TUNE} for different output capacitor combinations are given in Table 2. If no RTUNE is used, the default compensation values are used.

The TJT120 pre-tuned compensation can be divided into three different banks (COMP1, COMP2, COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of 20 different sets of compensation coefficients precalculated for different values of output capacitance. The three banks are set up as follows:

 COMP1: Recommended for the case where all of the output capacitance is composed of only ceramic

- capacitors. The range of external output capacitance is from 1470 μF to a maximum value of 17640 $\mu F)$
- COMP2: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size. The range of output capacitance is from 2564 μ F to a maximum of 30564 μ F. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 12 x 47 μ F ceramics + 25 x 1000 μ F polymer capacitors, and selecting RTUNE = 5.36 μ KQ, transient deviation can be as low as 25 mV, for a 50% load step (0 to 85A).
- COMP3: Suitable for a mix of ceramic and higher ESR polymers or electrolytic capacitors, with output capacitance ranging from a minimum of 2204 μF to a maximum of 30084 μF.

Selecting R_{TUNE} according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of an 60A to 120A step change (50% of full load), with an input voltage of 12V. Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select

details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.

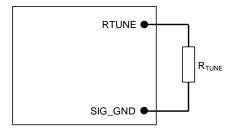


Figure 36. Circuit diagram showing connection of R_{TUNE} to tune the control loop of the module.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 2. Recommended R_{TUNE} Compensation.

Output Capacitance	Number of Output	Total Output	R _{TUNE}	R _{TUNE}	1/0	171	L/D	4.5
Туре	Capacitors**	Capacitance (μF)**	resistor (Ω)	Index	KD	KI	KP	AP
D	efault Compensation Value	S	OPEN		375	2	37	150
Ceramic	10 x 47μF + 10 x 100μF	1398	29.1	0	375	2	37	150
Ceramic	12 x 47μF + 12 x 100μF	1644	88.7	1	441	3	44	150
Ceramic	14 x 47μF + 14 x 100μF	1890	150	2	506	3	51	150
Ceramic	16 x 47μF + 16 x 100μF	2136	213	3	572	3	57	150
Ceramic	19 x 47μF + 19 x 100μF	2505	280	4	671	3	67	150
Ceramic	22 x 47μF + 22 x 100μF	2874	348	5	770	4	77	150
Ceramic	25 x 47μF + 25 x 100μF	3243	417	6	869	4	87	150
Ceramic	28 x 47μF + 28 x 100μF	3612	493	7	968	4	97	150
Ceramic	31 x 47μF + 31 x 100μF	3981	569	8	1067	4	107	150
Ceramic	34 x 47μF + 34 x 100μF	4350	642	9	1166	4	117	150
Ceramic	38 x 47μF + 38 x 100μF	4842	723	10	1297	5	130	150
Ceramic	42 x 47μF + 42 x 100μF	5334	806	11	1429	5	143	150
Ceramic	48 x 47μF + 48 x 100μF	6072	898	12	1627	5	163	150
Ceramic	55 x 47μF + 55 x 100μF	6933	938	13	1858	5	186	150
Ceramic	63 x 47μF + 63 x 100μF	7917	1090	14	2121	6	212	150
Ceramic	72 x 47μF + 72 x 100μF	9024	1180	15	2418	6	242	150
Ceramic	82 x 47μF + 82 x 100μF	10254	1290	16	2748	7	275	150
Ceramic	93 x 47μF + 93 x 100μF	11607	1400	17	3110	7	311	150
Ceramic	105 x 47μF + 105 x 100μF	13083	1520	18	3506	7	351	150
Ceramic	120 x 47μF + 120 x 100μF	14928	1640	19	4000	8	400	150
Ceramic + Polymer	12 x 47μF + 2 x 1000μF	2672	1760	20	501	3	300	220
Ceramic + Polymer	12 x 47μF + 3 x 1000μF	3672	1890	21	688	3	413	220
Ceramic + Polymer	12 x 47μF + 4 x 1000μF	4672	2030	22	876	3	525	220
Ceramic + Polymer	12 x 47μF + 5 x 1000μF	5672	2150	23	1063	4	638	220
Ceramic + Polymer	12 x 47μF + 6 x 1000μF	6672	2320	24	1250	4	750	220
Ceramic + Polymer	12 x 47μF + 7 x 1000μF	7672	2460	25	1438	4	860	220
Ceramic + Polymer	12 x 47μF + 8 x 1000μF	8672	2640	26	1625	5	975	220
Ceramic + Polymer	12 x 47μF + 9 x 1000μF	9672	2840	27	1813	5	1088	220
Ceramic + Polymer	12 x 47μF + 10 x 1000μF	10672	3010	28	2000	5	1200	220
Ceramic + Polymer	12 x 47μF + 11 x 1000μF	11672	3200	29	2187	5	1312	220
Ceramic + Polymer	12 x 47μF + 12 x 1000μF	12672	3400	30	2375	5	1425	220
Ceramic + Polymer	12 x 47μF + 13 x 1000μF	13672	3650	31	2562	6	1537	220
Ceramic + Polymer	12 x 47μF + 15 x 1000μF	15672	3880	32	2937	6	1762	220
Ceramic + Polymer	12 x 47μF + 17 x 1000μF	17672	4120	33	3312	6	1987	220
Ceramic + Polymer	12 x 47μF + 19 x 1000μF	19672	4420	34	3687	7	2212	220
Ceramic + Polymer	12 x 47μF + 21 x 1000μF	21672	4700	35	4061	7	2437	220
Ceramic + Polymer	12 x 47μF + 23 x 1000μF	23672	5050	36	4436	7	2662	220
Ceramic + Polymer	12 x 47μF + 25 x 1000μF	25672	5360	37	4811	8	2887	220
Ceramic + Polymer	12 x 47μF + 27 x 1000μF	27672	5760	38	5186	8	3112	220
Ceramic + Polymer	12 x 47μF + 30 x 1000μF	30672	6120	39	5748	8	3449	220

^{**} Total output capacitance includes the capacitance inside the module is 4 x 47μ F (3m Ω ESR). Effective capacitance of 47uF cap taken as 42uF, 100uF cap taken as 81uF. Polymers taken at rated values of 100uF and 820uF

Note: The capacitors used in the digital compensation Loop tables are $47\mu F/3 \, m\Omega$ ESR ceramic, $100uF/3.2m\Omega$ ceramic, $1000 \, \mu F/6m\Omega$ ESR polymer capacitor and $820uF/19m\Omega$ ESR Polymer capacitor.

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7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 2 (continued). R_{TUNE} compensation table

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (μF)**	R_{TUNE} resistor (Ω)	R _{TUNE} Index	KD	KI	КР	AP
Ceramic + Electrolytic	12 x 47μF + 2 x 820μF	2312	6570	40	176	2	176	220
Ceramic + Electrolytic	12 x 47μF + 3 x 820μF	3312	7060	41	238	3	238	220
Ceramic + Electrolytic	12 x 47μF + 4 x 820μF	3952	7590	42	301	3	301	220
Ceramic + Electrolytic	12 x 47μF + 5 x 820μF	4772	8160	43	363	3	363	220
Ceramic + Electrolytic	12 x 47μF + 6 x 820μF	5592	8870	44	426	4	426	220
Ceramic + Electrolytic	12 x 47μF + 7 x 820μF	6412	9530	45	488	4	488	220
Ceramic + Electrolytic	12 x 47μF + 8 x 820μF	7312	10400	46	550	4	550	220
Ceramic + Electrolytic	12 x 47μF + 9 x 820μF	8052	11300	47	613	4	613	220
Ceramic + Electrolytic	12 x 47μF + 10 x 820μF	8872	12400	48	675	5	675	220
Ceramic + Electrolytic	12 x 47μF + 11 x 820μF	9692	13700	49	738	5	738	220
Ceramic + Electrolytic	12 x 47μF + 12 x 820μF	10512	15000	50	800	5	800	220
Ceramic + Electrolytic	12 x 47μF + 14 x 820μF	12152	16700	51	925	5	925	220
Ceramic + Electrolytic	12 x 47μF + 16 x 820μF	13792	18700	52	1050	6	1050	220
Ceramic + Electrolytic	12 x 47μF + 18 x 820μF	15432	21000	53	1174	6	1174	220
Ceramic + Electrolytic	12 x 47μF + 20 x 820μF	17072	24000	54	1299	6	1299	220
Ceramic + Electrolytic	12 x 47μF + 23 x 820μF	19532	28000	55	1486	7	1486	220
Ceramic + Electrolytic	12 x 47μF + 26 x 820μF	21992	33000	56	1674	7	1674	220
Ceramic + Electrolytic	12 x 47μF + 29 x 820μF	24452	40200	57	1861	8	1861	220
Ceramic + Electrolytic	12 x 47μF + 32 x 820μF	26912	50500	58	2048	8	2048	220
Ceramic + Electrolytic	12 x 47μF + 36 x 820μF	30192	68000	59	2298	8	2298	220

^{**} Total output capacitance includes the capacitance inside the module is $4 \times 47 \mu F$ ($3 m\Omega$ ESR). Effective capacitance of 47uF cap taken as 42uF, 100uF cap taken as 81uF. Polymers taken at rated values of 100uF and 820uF

Note: The capacitors used in the digital compensation Loop tables are $47\mu F/3 m\Omega$ ESR ceramic, $100uF/3.2m\Omega$ ceramic, $1000 \mu F/6m\Omega$ ESR polymer capacitor and $820uF/19m\Omega$ ESR Electrolytic capacitor.

Power Module Wizard

GE offers a free web based easy to use tool that helps users simulate the Tunable Loop performance of the TJT120. Go to http://ge.transim.com/pmd/Home and sign up for a free account and use the module selector tool. The tool also offers downloadable Simplis/Simetrix models that can be used to assess transient performance, module stability, etc.

Bin 'a' and Bin 'b' settings using the models available through Power Module Wizard

The TJT120 module has a built-in non-linear compensation adjustment to speed up its transient response to dynamic loading conditions. When the module senses a load transition in progress, it automatically adjusts the KD, KI, KP settings to higher values and then reverts to the values set before the transient conditions. The adjustment of the PID coefficients is as follows:

Steady State			Transient Condition			
Bin 'a' – User set valu	ies based on RTUNE or	programmed	Bin 'b' – Controller adjusted values for duration of transient			
KD	KI	KP	KD KI KP			
Α	В	Х	1.5 x A 2 x B 2 x C			

For determining the voltage response to a current load transient, it is more accurate to use the Bin 'b' settings corresponding to the selected KD, KI, KP values. For Loop Stability Simulations, the selected PID values corresponding to Bin 'a' should be used.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Digital Feature Descriptions

PMBus Interface Capability

The 120A TeraDLynx power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from www.pmbus.org. The modules support a subset of version 1.1 of the specification (see Table 4 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

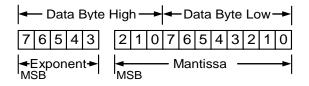
Communication over the module PMBus interface supports the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 4 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two-byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa \times 2 Exponent

PMBus Addressing

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 3 (E96 series resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

The user must know which I²C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the

Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

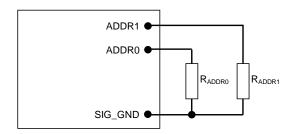


Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

т	h	_	2
ıa	ום	ıe	3

				PMBus	Address						
		ADDR1 Resistor Values									
ADDR0 Resistor Values	4.99K	15.4k	27.4K	41.2K	54.9K	71.5K	90.9K	110K	137K	162K	191K
4.99K	1	13	25	37	49	61	73	85	97	109	121
15.4K	2	14	26	38	50	62	74	86	98	110	122
27.4K	3	15	27	39	51	63	75	87	99	111	123
41.2K	4	16	28	40	52	64	76	88	100	112	124
54.9K	5	17	29	41	53	65	77	89	101	113	125
71.5K	6	18	30	42	54	66	78	90	102	114	126
90.9K	7	19	31	43	55	67	79	91	103	115	127
110K	8	20	32	44	56	68	80	92	104	116	64
137K	9	21	33	45	57	69	81	93	105	117	64
162K	10	22	34	46	58	70	82	94	106	118	64
191K	11	23	35	47	59	71	83	95	107	119	64
232K	12	24	©2 % 7 Ge	ner 4 8Elec	tric 60mp	any.7A1 rig	hts Æserv	ed. 96	108	120	64

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120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Operation (01h)

This is a paged register. The OPERATION command can be used to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	Х	CPA
Default Value	1	0	1	х	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION
Ü	command
1	Module responds to the ON bit in the
	OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
	Module ignores the analog ON/OFF pin, i.e.
0	ON/OFF is only controlled through the
	PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to
1	be asserted to start the unit

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

PMBus Adjustable Soft Start Rise Time

The soft start rise time of module output is adjustable in the module via PMBus. The TON_RISE command can set the rise time in ms, and allows choosing soft start times between 1 and 1000ms. Rise time below 10msec may cause the module it overshoot its voltage setpoint during startup

Output Voltage Adjustment Using the PMBus

Two PMBus commands are available to change the output voltage setting. The first, VOUT_COMMAND can set the output voltage directly. The second, VOUT_TRIM is used to apply an offset to the commanded output voltage.

Since the output voltage can be set using an external RTrim resistor as well, an additional PMBus command MFR_VOUT_SET_MODE is used to tell the module whether the VOUT_COMMAND is used to directly set output voltage or whether RTrim is to be used. If MFR_VOUT_SET_MODE is set to where bit position 7 is set at 1, then VOUT_COMMAND is ignored and output voltage is set solely by RTrim. If bit 7 of MFR_VOUT_SET_MODE is set to 0, then output voltage is set using VOUT_COMMAND, and the value of RTrim is only used at startup to set the output voltage.

The second output voltage adjustment command VOUT_TRIM works in either case to provide a fixed offset to the output voltage. This allows PMBus adjustment of the output voltage irrespective of how MFR_VOUT_SET_MODE is set and allows digital adjustment of the output voltage setting even when RTrim is used.

For all digital commands used to set or adjust the output voltage via PMBus, the resolution is 98µV.

Output Voltage Margining Using the PMBus

The output voltage of the module can be margined via PMBus between 0.6 and 1.5V. The margining voltage can be adjusted in $98\mu V$ steps.

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ_TEMPERATURE1, READ_TEMPERATURE_2 are mapped to module temperature and internal temperature of the PWM controller, respectively. The temperature readings are returned in °C and in two bytes.

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PMBus Adjustable Output Over, Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold. The default value is configured to be 112.5% of the commanded output. The command VOUT_UV_FAULT_LIMIT sets the threshold that detects an output under voltage fault. The default values are 87.5% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command possible values are 7 to 14V and for the VIN_OFF command, possible values are 6.75V to 14V. Both VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes.

Measurement of Output Current, Output Voltage and Input Voltage

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

Measuring Output Current Using the PMBus

The module measures output current by using a signal derived from the switching FET currents. The current gain factor is accessed using the IOUT_CAL_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The READ_IOUT command provides module average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the Linear data format.

Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ_VOUT command. The command returns two bytes of data in Linear format.

Measuring Input Voltage Using the PMBus

The module provides input voltage information using the READ_VIN command. The command returns two bytes of data in the Linear format.

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Low Byte

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

High Byte

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	VOUT_OV_WARNING	0
5	VOUT_UV_WARNING	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

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STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Data	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	Х	0

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001101 corresponds to the TJT120 series of module), while bits [7:3] in the high byte indicate the revision number of the module.

Low	Byte

Bit Position	Flag	Default Value
7:2	Module Name	001101

1:0 Reserved	10
--------------	----

High Byte

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

User-Programmable Compensation Coefficients

The output voltage control compensation coefficients can be changed by the user via PMBus commands. On startup, the module uses stored values of the four compensation parameters KD, KI, KP and ALPHA. If the module detects a valid value of RTUNE connected to the module, the values of KD, KI, KP and ALPHA are then changed to the appropriate values. Beyond this, the user can use the PMBus commands listed below to overwrite the values of KD, KP, KI and ALPHA.

MFR_SPECIFIC_KP: Allows the user to program the value of the KP compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR_SPECIFIC_KI: Allows the user to program the value of the KI compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR_SPECIFIC_KD: Allows the user to program the value of the KD compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, the maximum allowed value is 10922

MFR_SPECIFIC_ALPHA: Allows the user to program the value of the ALPHA compensation coefficient. The allowed range is -256 to 256. The entire 16 bits are used to enter this range of integer values in two's complement binary format. For stable operation, use positive values only as suggested with the maximum allowed value being 256.

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Summary of Supported PMBus Commands

Please refer to the PMBus 1.1 specification for more details of these commands. For the registers where a range is specified, any value outside the range is ignored and the module continues to use the previous value.

Table 4

Han				New Voletile										
Hex Code	Command				Brief D	escripti	on					Non-Volatile Memory Storage		
		Turn Module on or o	off. Also	used to	margin	the out	put volt	age						
		Format				Unsigne	d Binary	,			1			
		Bit Position	7	6	5	4	3	2	1	0				
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r		YES		
					1/W			1/W						
		Function	On	Χ	_		rgin	· -	Х	X				
		Default Value	1	0	0	0	0	0	Χ	X				
		Configures the ON/O	OFF fund	ctionalit	y as a co	mbinat	ion of a	nalog O	N/OFF p	oin and F	PMBus			
		Format												
02	ON OFF CONFIG	Bit Position	Bit Position 7 6 5 4 3 2 1 0											
		Access	r	r	r	r/w	r/w	r/w	r	r	1			
		Function	Χ	Х	Х	pu	cmd	cpr	Х	сра				
		Default Value	0	0	0	1	0	1	X	1				
				_				l						
03	CLEAR_FAULTS	device has been ass	ar any fault bits that may have been set, also releases the SMBALERT# signal if the vice has been asserting it. ed to control writing to the module via PMBus. Copies the current register setting in											
			_				-		_		_			
					matches	the val	ue in th	e data b	yte into	o non-vo	latile			
		memory (EEPROM)	ne module whose command code matches the value in the data byte into non-volatile nemory (EEPROM) on the module											
		Format				Unsigne	d Binary	/						
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	Х	x	Х	Х	х				
		Function	bit7	bit6	bit5	X	X	X	X	X				
										1				
10	WRITE BROTECT	Default Value	0	0 .	0	X	X	Х	Х	Х	1	YES		
10	WRITE_PROTECT	Bit5: 0 – Enables all										163		
		1 – Disables all				_		ERATIO	N					
		and ON_OFF	_											
		Bit 6: 0 – Enables all												
		1 – Disables all	writes e	except for	or the W	/RITE_P	ROTECT	and						
		OPERATION	comma	ands (bit	t5 and b	it7 mus	t be 0)							
		Bit7: 0 - Enables all	writes a	s permi	tted in b	it5 or b	it6							
		1 – Disables all	writes e	xcept fo	r the W	RITE PE	ROTECT	comma	nd					
		(bit5 and bit		-		_								
		Copies all current re			n the m	ndule in	to non-v	volatile	memor	v (FFPRC	OM) on			
11	STORE_DEFAULT_ALL	the module. Takes a	_	_						y (3141, 311			
		Restores all current							tho mo	dula nan	volatilo			
12	RESTORE_DEFAULT_ALL		register	setting	s III tile	module	II OIII Va	iues iii	tile illo	uule Holl	-voiatile			
		memory (EEPROM)												
		The module has MO	DE set t	o Linea	r and Ex	ponent	set to -1	.4. Thes	e value	s cannot	be			
		changed									-			
20	VOLIT MODE	Bit Position	7	6	5	4	3	2	1	0				
20	VOUT_MODE	Access	r	r	r	r	r	r	r	r				
		Function		Mode		2	's comp	lement	Expone	nt				
		Default Value	0	0	0	1	0	0	1	0				
		Set desired output v												
		VOUT_MODE comm	and. Va	ilid rang							7			
		Format			U	nsigned	Mantis	sa						
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1			
21	VOUT COMMAND	Function	-				tissa				1	YES		
		Default Value					able				1	5		
		Bit Position	7	c	г	4		2	1	^	1			
			7	6	5		3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1			
		Function					itissa]			
	Default Value Variable													

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7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Bri	ef Desci	ription					Non-Volatile Memory Storage
Couc		Apply a fixed offset VOUT_COMMAND. Allowed range is ±30	Implied							n resisto	or or the	memory ocorage
		Format		L	inear, t	wo's coi	mpleme	nt binar	У]	
		Bit Position	15	14	13	12	11	10	9	8		
22	VOLIT TRIM	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		YES
22	VOUT_TRIM	Function				Mar	tissa					163
		Default Value	0	0	0	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function Default Value	0	0	0	o iviar	itissa 0	0	0	0	-	
		Applies an offset to							_	_	na modulo	
		output voltage (bety			•	_					•	
		command VOUT_CO						•	_			
		Format						nt binar]	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r	r	r	r	r	r	r		
23	VOUT_CAL_OFFSET	Function		YES								
		Default Value		Va	riable b	ased on	factory	calibrat	ion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					itissa					
		Default Value						calibrat				
		Sets the target volta				utput hi	gh. Impl	ied expo	onent of	-14 per	· VOUT_MODE	
		command. Allowed	range is			1						
		Format Bit Position	15	14	13	12	npieme 11	nt binar 10	y 9	8	-	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
25	VOUT_MARGIN_HIGH	Function	17 00	1/ ٧٧	1/ 00		itissa	17 00	17 00	17 00		YES
23	VOOT_IVIARIOIIV_IIIOII	Default Value					iable				1	123
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function			•	Mar	itissa	•				
		Default Value				Vari	iable					
		Sets the target volta	_	_	-	utput lo	w. Impli	ed expo	nent of	-14 per	VOUT_MODE	
		command. Allowed	range is								1	
		Format	1.5					nt binar	•	0	1	
		Bit Position	15 r/w	14 r/w	13 r/w	12 r/w	11 r/w	10 r/w	9 r/w	8 r/w	-	
26	VOUT MARGIN LOW	Access Function	1 / W	1 / VV	1 / ٧٧		itissa	1 / VV	1 / W	1 / VV	1	YES
20	V001_IVII/IIIV	Default Value					iable					123
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Mar	itissa					
		Default Value				Vari	iable					
		Sets the value of inp	ut volta	ge at w	hich the	module	e turns o	n. Expo	nent is f	fixed at	-6. Allowed	
		range is 7 to 14V.									-	
		Format						nt binar		1	1	
		Bit Position	15	14	13	12	11	10	9	8	1	
		Access	r	r	r	r	r	r	r/w	r/w	1	
35	VIN_ON	Function	4		Exponer	1			Mantiss		4	YES
		Default Value	7	1	0	4	0	0	0	0	4	
		Bit Position	7	6	5		3	2	1		1	
		Access Function	r/w	r/w	r/w	r/w Mar	r/w ntissa	r/w	r/w	r/w	1	
		Default Value	1	1	0	0	0	0	0	0	1	
		Delaute value									1	

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex	Command				Brief	Descrip	tion					Non-Volatile
Code		Sate the value of in-	ust valta	go ot				ff Eva-	nont is 1	ivad at	6 Allowed	Memory Storage
		Sets the value of inprange is 6.75 to 14V		ige at w	nich the	module	turns o	п. Ехро	nent is i	ixed at	-6. Allowed	
		Format	· I		inoar t	wo's con	anlamai	at hinan	.,			
		Bit Position	15	14	13	12	11	10	y 9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
36	VIN OFF	Function	'		xponen		'		Mantissa			YES
30	VIN_OFF	Default Value	1	1	0	1	0	0	0	1		TES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	17 00	17 00	17 00	Man		1/ 00	1/ ٧٧	17 00		
		Default Value	1	0	1	1	0	0	0	0		
			pplies a gain correction to the READ_IOUT command results to calibrate out gain errors in									
		module measureme										
		to generate the corr							eg.ste		, 0151	
		Format				vo's con			v			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r/w		
38	IOUT_CAL_GAIN	Function		ı		Inte	ger			,		YES
		Default Value		Va	riable ba	sed on		calibrati	ion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Inte	ger					
		Default Value		Va	riable ba	sed on	factory	calibrati	ion			
		Returns the value of	ut current.									
		The exponent is fixe										
		Format		L	inear. tv	vo's con	nplemei	nt binar	v			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r/w	r	r		
39	IOUT_CAL_OFFSET	Function		E	xponen	t		ľ	Mantissa	1		YES
		Default Value	1	1	1	1	0	,	Variable			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function			•	Man	tissa					
		Default Value		Va	riable ba	ased on	factory	calibrati	ion			
		Sets the voltage leve	el for an	output	overvol	tage fau	lt. Impl	ied expo	onent of	-14 per	•	
		VOUT_MODE comm	and. All								_	
		Format			Linear, 1	wo's co	mplime	nt binar	у			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
40	VOUT_OV_FAULT_LIMIT	Function				Man	itissa					YES
		Default Value				Vari	able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	itissa					
		Default Value				Vari	able					
		Instructs the module	e on wh	at action					ut over	voltage	fault	
		Format				Unsigne	d Binary]	
		Bit Position	7	6	5	4	3	2	1	0]	
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r]	YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0]	

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief	Descri	otion					Non-Volatile			
Code		Sets the value of ou	tnut vol	tage at	which +h	ne modi	الم مممم	rates wa	rning fo	or over s	voltage	Memory Storage			
		Exponent is fixed at								or over-	voitage.				
			-14. All					nt binar			1				
		Format Bit Position	15	14	13	12			y 9	8					
							11	10 r/w	r/w						
42	VOLIT OV MARNI LINAIT	Access Function	r	r	r	r +	r		Mantissa	r/w		YES			
42	VOUT_OV_WARN_LIMIT	Default Value			Exponen		able		viaiitissa	1		1E3			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function	1, 00	1, 00	1, 00		itissa	17 00	17 00	17 00					
		Default Value					able								
		Sets the value of ou	<u> </u>		العامة عادد				: f.						
		Exponent is fixed at									-voitage.				
		Format	-14. AIII					_		·]				
			Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8												
		Access	r	r	r	r	r	r/w	r/w	r/w					
43	VOUT UV WARN LIMIT	Function	<u> </u>		YES										
75	VOOT_OV_WARRIV_ERWIT	Default Value			123										
		Bit Position	7	6	5	4	able 3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function	<i>'</i>				tissa	, ,		,					
		Default Value				Vari	able								
		Sets the voltage leve	el for an	output	underv	oltage fa	ault. Exp	ponent i	s fixed a	it -14. <i>F</i>	Allowed				
			ets the voltage level for an output undervoltage fault. Exponent is fixed at -14. Allowed ange is 0.05 to 2V. Triggers SMBALERT.												
		Format													
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r	r	r	r	r	r/w	r/w	r/w					
44	VOUT_UV_FAULT_LIMIT	Function			Exponen	t		1	Mantissa	a		YES			
		Default Value				Vari	able		1	1					
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function					tissa								
		Default Value				Vari	able								
		Instructs the module	e on wh	at actio	n to take	e in resp	onse to	an outp	ut unde	rvoltag	e fault				
		Format				Unsigne	d Binary	/	1	1					
		Bit Position	7	6	5	4	3	2	1	0					
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES			
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х					
		Default Value	1	0	1	1	1	0	0	0					
		Sets the current leve	el for an	output	overcur	rent fai	ılt (can d	only be I	owered	below 1	the				
		maximum of 140A).		-			-	-		,	. -				
]				
		Format Pit Position	15	14			· • • • • • • • • • • • • • • • • • • •	nt binar	y 9	0					
		Bit Position	15 r		13 r	12 r	11	10 r	r/w	8 r/w					
46	IOUT_OC_FAULT_LIMIT	Access Function	r	r	xponen	t	r		Mantissa Mantissa			YES			
	.5000//02/_200//	Default Value	1	1	1	1	0	0	1	0		5			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function	-, ••	., ••	., ••		itissa	., ••	., ••	., ••					
		Default Value	0	0	0	0	1	0	0	0					
											ı				

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex					(COIIIII	•						Non-Volatile			
Code	Command				Brie	Descri	otion					Memory Storage			
		Sets the value of cu	rrent lev	el at wl	nich the	module	generat	tes warr	ning for	overcur	rent.				
		Allowed range is 0 t	o 140A.	The exp	onent i	s fixed a	t -2. Trig	ggers SN	/IBALER1	ī	•				
		Format					npleme		<i>-</i>						
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r	r	r	r	r	r	r	r/w					
4A	IOUT_OC_WARN_LIMIT	Function			xponen				Mantissa			YES			
		Default Value	1	1	1	1	0	0	1	0					
		Bit Position	7	6	5	4	3	2	1	0					
		Access Function	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Default Value	1	0	1	0	tissa 1	0	0	0					
		<u> </u>				_		_			ngo ic 25 to				
		•	ets the temperature level above which over-temperature fault occurs. Allowed range is 35 t .40°C. The exponent is fixed at 0. Triggers SMBALERT.												
		Format	TIC IS TIXE				npleme	nt hinar	V						
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r	r	r	r	r	r/w	r	r					
4F	OT FAULT LIMIT	Function			xponen		-		 Mantissa			YES			
		Default Value	0	0	0	0	0	0	0	0					
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function				Man	tissa								
		Default Value	1	0	0	0	1	0	1	0					
		Configures the over	nfigures the over temperature fault response												
		Format				Unsigne	d Binary								
	OT_FAULT_RESPONSE	Bit Position	7	6	5	4	3	2	1	0					
50		Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES			
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Χ					
		Default Value	1	0	1	1	1	0	0	0					
		Sets the over temper fixed at 0. Triggers S			level in	°C. Allo	wed rar	nge is 30) to 130°	C. The e	exponent is				
		Format			inear t	wo's roi	mpleme	nt hinar	'V]				
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r	r	r	r	r	r	r	r					
51	OT_WARN_LIMIT	Function		·	Exponer	l			Mantissa			YES			
		Default Value	0	0	0	0	0	0	0	0					
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function				Mar	tissa								
		Default Value	0	1	1	1	1	1	0	1					
		Sets the input overv Triggers SMBALERT	oltage f	ault lim	it. Expo	nent is f	ixed at	-6. Allov	ved rang	ge is 6.7	5 to 15V.				
		Format		L	inear, tv	vo's cor	nplemei	nt binar	у.						
		Bit Position	15	14	13	12tr	11	10	9	8					
		Access	r	r	r	r	r	r	r/w	r/w					
55	VIN_OV_FAULT_LIMIT	Function			Exponer	it			Mantissa	9		YES			
		Default Value	1	1	0	1	0	0	1	1					
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function				Mar	tissa								
		Default Value	1	0	1	0	0	0	0	0					

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex	Command			Non-Volatile													
Code	Commitatio	0 6				f Descri	etion -					Memory Storage					
		Configures the VIN o	overvolt	age fau			-l D'				Ī						
		Format				Unsigne											
5.0	WIN ON FAULT DESCRONSE	Bit Position	7	6	5	4	3	2	1	0		VEC					
56	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES					
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	Х	Х							
		Default Value	[1] 1	[0] 0	0	0	0	0	0	0							
-		L.									. 6						
		Sets the value of the	•	_			_	e low w	arning.	Exponer	it fixed at -						
		6. Allowed range is	5.75 to .					nt binan]						
		Format Bit Position	15			wo's cor	·		y 9	8							
		Access	15	14 r	13 r	12 r	11 r	10 r	r/w	r/w							
	VIN OV MARN LIMIT	Function			I	l			Mantiss			YES					
57	VIN_OV_WARN_LIMIT	Default Value	1	1	Exponer 0	1	0	0	1	1		1 E 3					
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w							
		Function	1/ ٧٧	1 / ٧٧	1/ ٧٧		itissa	1 / VV	1 / VV	1 / VV							
		Default Value	1	0	0	0	0	0	0	0							
		<u> </u>									l 						
			ets the value of the input voltage that causes input voltage low warning. Exponent fixed at Allowed range is 5 to 14V. Triggers SMBALERT														
		Format) IU 14V			WO'S CO	nnloma	nt hina-	3/]						
		Bit Position	15	14	13	12	npieme 11	nt binar 10	y 9	8							
		Access	r	r	r	r	r	r	r/w	r/w							
58	VINI LIV WAARN LINAT	Function	'	l	Exponer	1			Mantiss			YES					
36	VIN_UV_WARN_LIMIT	Default Value	1	1	0	1	0	0	0	1		TES					
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w							
		Function	1, 44	1, 00	1/ **		itissa	1/ ٧٧	1, 00	1700							
		Default Value	1	0	1	0	0	0	0	0							
			innut	oltago t	that cau	coc an ir	nut une	lonuolta		Evnone	nt fixed at						
			e value of the input voltage that causes an input undervoltage fault. Exponent fixed at ved range is 5 to 14V. Triggers SMBALERT														
		Format	10 110			wo's cor	nnleme	nt binar	v								
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r	r	r	r	r	r	r/w	r/w							
59	VIN_UV_FAULT_LIMIT	Function			Exponer	nt			Mantiss			YES					
		Default Value	1	1	0	1	0	0	0	1							
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w							
		Function				Man	tissa										
		Default Value	1	0	1	0	0	0	0	0							
		Instructs the module	e on wh	at actio	n to tak	e in resn	onse to	an inni	ıt under	voltage	fault.						
		Format				Unsigne											
		Bit Position	7	6	5	4	3	2	1	0							
5A	VIN_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES					
			RSP	RSP													
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	X	Х	Х							
		Default Value	1	0	1	1	1	0	0	0							
		Sets the output volt	age leve	el at whi	ich the F	GOOD r	oin is ass	erted h	igh. Im	olied exi	onent of -						
		14 per VOUT_MODE															
		Format				wo's cor			У								
		Bit Position	15	14	13	12	11	10	9	8							
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w							
5E	POWER_GOOD_ON	Function			•		tissa					YES					
		Default Value				Vari	able										
		Bit Position	7	6	5	4	3	2	1	0							
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w							
		Function				Man	itissa										
		Default Value				Vari	able										
							Default Value Variable										

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex			Non-Volatile									
Code	Command				Bri	ef Descr	ription					Memory Storage
		Sets the output volt							ed low.	Implied ex	ponent of -	
		14 per VOUT_MODI	E comm	and. All							7	
		Format					mplem			,		
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5F	POWER_GOOD_OFF	Function					ntissa					YES
		Default Value					riable	1		1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					ntissa				1	
		Default Value	<u> </u>				riable				1	
		Sets the delay time	in ms of	the out	tput volt	age dur	ing star	tup. Allo	owed rai	nge is 0 to	1000ms.	
		Format			Linear,	two's co	mplem	ent bina	ary		1	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
60	TON_DELAY	Function			Exponen	it			Mantis	sa		YES
	. 55.6.	Default Value	0	0	0	0	0	0	0	0]	. 23
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Ma	ntissa					
		Default Value	0	0	0	0	0	0	1	0		
		Sets the rise time in	ms of t	he outp	ut volta	ge durin	g startu	p. The e	exponen	t is fixed a	t 0. Allowed	
		range is 1 to 1000m	S.								-	
		Format					mplem	ent bina		1		
	TON_RISE	Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	R	r	r	r	r/w	r/w		
61		Function			Exponen		1		Mantis			YES
		Default Value	0	0	0	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					ntissa					
		Default Value	0	0	0	0	0	1	0	1	1 - 1 - 0	
		Sets the delay time			tput voit	age dur	ing turn	-off. Th	e expon	ent is fixe	d at U.	
		Allowed range is 0 t	0 1000r	ns.	1:						7	
		Format Pit Position	10	1.1			mplem		9	0	1	
		Bit Position	15	14	13 R	12 r	11 r	10	r/w	8 r/w	1	
64	TOFF_DELAY	Access Function	r	r	<u>к</u> Exponen	r +	r	r	Mantis		1	YES
04	TOFF_DELAT	Default Value	0	0	0	0	0	0	0	0	1	IES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	1 / ٧٧	1 / VV	1 / VV		ntissa	1 / VV	1 / VV	1 / VV	1	
		Default Value	0	0	0	0	0	0	1	0	1	
		Sets the fall time in							_		Allowed	
		range is 0 to 1000m		.c outpt	at voitag	,	5 0	<u>L</u> APO	13 1			
		Format			Linear.	two's co	mplem	ent bina	ary		1	
		Bit Position	15	14	13	12	11	10	9	8	1	
		Access	r	r	R	r	r	r	r/w	r/w	1	
65	TOFF_FALL	Function			Exponen				Mantis		1	YES
	_	Default Value	0	0	0	0	0	0	0	0	1	-
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function				Ma	ntissa					
		Default Value	0	0	0	0	0	1	0	1]	
		1.		•						•	4	

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				В	rief Des	criptio	n						Non-Volatile Memory Storage
		Returns one byte of	informa	ation wi	th a su	mmary	of the	most	critical	module	faults			,
		Format					nsigned							
		Bit Position	7	6	5		4		3	2	1	0		
78	STATUS_BYTE	Access	r	r	R		r	+	r	r	r	r	1	
		Flag	Х	OFF	VOUT	r_0 IO			_UV T			THER		
		Default Value					Varia	ble					1	
		Returns two bytes of	f inform	nation w	vith a s	ummar			dule's fa	ıult/warı	ning co	nditio	ons	
		Format					Jnsigne							
		Bit Position	15	14		13	12	2	11	10	9	8		
		Access	r	r		R	r		r	r	r	r		
		Flag	VOUT	IOUT_0	OC II	NPUT	Х		PGOOD	x	Х	Х		
79	STATUS_WORD	Default Value					Var	iable						
		Bit Position	7	6		5	4		3	2	1	0		
		Access	r	r		R	r		r	r	r	r		
		Flag	Х	OFF	vo		IOUT	ОС	VIN_U\	/ TEMP	CML	OTH	IER	
		Default Value										<u> </u>		
			Value Variable e byte of information with the status of the module's output voltage related faults											
			informa	ation wi	th the					out volta	ge rela	ated f	aults	
		Format					Unsign	ed Bii						
		Bit Position	7		6		5		4	3	2	1	0	
7A	STATUS_VOUT	Access	r		r		r		r	r	r	r	r	
		Flag	VOUT_	()//	OUT_O\ Warn	/_ VC	OUT_U\ Warn	/_ \	/OUT_U	v x	х	х	х	
		Default Value		Variable										
		Returns one byte of	informa											
		Format	e of information with the status of the module's output current related faults Unsigned Binary											
		Bit Position	7		6 5	4	Биса Б	3		2 1	0	1		
7B	STATUS_IOUT	Access	r		r r	r		r		rr	r	1		
		Flag	IOUT		X X		IOUT_		VARN	XX	_	1		
		Default Value	1001_	_00	<u> </u>		/ariable		•,	XX	<u> </u>	-		
		Returns one l	oyte of i	nforma	tion wi				module	e's input	relate	d faul	ts	
		Format	<u>, </u>											
				7	-		Unsign			1 2	1 2 1	4	0	
		Bit Position		7		6	-	5	4	3	2	1	0	
7C	STATUS_INPUT	Access	\ //N! O	r	T \//\	r		r	r	r	r	r	r	
		Flag	VIN_O	V_FAUL		_OV_W RNING		_UV_ RNING			Х	Х	Х	
		Default Value			I AI	UNIING		iable	, I _ i AC	<u></u>				
		Delaute value	<u> </u>				vai							
		Returns one byte of	inform	tion w	th tha	ctatus	of the -	nod	lo'c +om	noratur	rola+	nd far	l+c	
		Format	miorina	ation Wi	ui uie				ic s tem	perature	reidi	u idl	ııtə	
		Bit Position	7	1	(ned Bir 5	ary 4	3 2	1 1	0			
7D	STATUS_TEMPERATURE						-				_			
		Access	OT F	+		/ADNI	r	r	r r	_	r			
		Flag	OT_F/	HULI	UI_V	VARN	X	Χ	X X	X	Х			
		Default Value	İ			Vä	ariable							
		Returns one byte of	informa	ation wi	th the					nmunica	tion re	lated	faults	
			7	 1	6		Unsign				1		0	
		Bit Position			6	5	4	3	2			-	0	
7E	STATUS_CML	Access	r		r	r	r	r	r	- 1	•		r	
		Flag	Inva Comm		nvalid Data	PEC Fail	х	х	х	ther Co	mm Fa	ult	х	
		Default Value				1	Var	iable						
		Default Value Variable												

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief De	escriptio	n						/olatile y Storage	
Code		Returns the value o	f the inn	ut volta	ge anni	ied to th	ne modu	le le				Wiellion	y Storage	
		Format	Т				npleme				l			
		Bit Position	15	14	13	12	11	10	y 9	8				
				-						1				
		Access	r	r	r	r	r	r	r	r				
88	READ_VIN	Function		Exponent Mantissa Variable										
	_	Default Value			F _			_						
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
	Function					itissa								
		Default Value												
		Returns the value of	f the ou	tput vol	tage of	the mod	lule. Exp	onent is	s fixed a	ıt -14				
		Format		l	inear, t	wo's cor	mpleme	nt binar	У					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r	r				
65	DEAD WOUT	Function				Man	tissa							
8B	READ_VOUT	Default Value				Vari	able							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function			· · ·		tissa		· · · · · ·					
		Default Value					able							
		Returns the value of	f tha au	tout cur	ront of									
			T the ou	•				nt hinar	.,					
8C READ_IOUT		Format	15				npleme		y 9	0				
		Bit Position	15	14	13	12	11	10		8				
		Access	r	r	r	r	r	r .	r	r				
	READ IOUT	Function			xponen			ı	Mantiss	a				
	_	Default Value					able	_						
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	Mantissa											
		Default Value					able							
		Returns a module F	ET packa	age tem	peratur	e in ºC.								
		Format		l	inear, t	wo's cor	mpleme	nt binar	У					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r	r				
0.0	DEAD TENADEDATURE (Function		[xponen	it		1	Mantiss	a				
8D	READ_TEMPERATURE_1	Default Value				Vari	able							
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	İ	•	•	Man	tissa	•		•				
		Default Value	İ				able							
		Returns the module	PWM c	ontrolle	r tempe									
		Format		L	inear, t	wo's cor	npleme	nt binar	у					
		Bit Position	15	14	13	12	11	10	9	8				
		Access	r	r	r	r	r	r	r	r				
		Function		1	xponen				Mantiss	l .				
8E	READ_TEMPERATURE_2	Default Value			., 561		able			-				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	- '-	<u> </u>	<u>' ' </u>		tissa		<u> </u>	<u>' ' </u>				
		Default Value	1				able							
		Delault Value	<u> </u>			vari	avie							

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command		Brief Description												
Couc		Returns the switchin			f the cor	nverter.	The Fre	quency	is in Kilo	hertz an	ıd is	Memory Storage			
		read only, consisting	g of two												
		Format	4.5			wo's cor									
		Bit Position	15	14	13	12	11	10	9	8					
95	DEAD EDECLIENCY	Access	r	r	r	r	r	r	r	r					
95	READ_FREQUENCY	Function	0		1 0		eger	_		1					
		Default Value	7	0 6	5	0	0 3	0 2	0	0					
		Bit Position Access	r	r	r	r		r	1 r						
		Function	'		1 '	l	r eger		'	r					
		Default Value	1	0	0	1	0	0	0	0					
		Returns one byte in					_	_		U					
		Format	l	the mo		Unsigne			.c. 1.1						
98	PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0		YES			
30	98 PIVIBUS_REVISION	Access	r	r	r	r	r	r	r	r		123			
		Default Value	0	0	0	1	0	0	0	1					
		Value used to progr		_		l	_		_		lock				
		Do not use value his				ii cociii(ACTIL OI	LIC FID	compet	isatiOII B	IOCK.				
		Format	, ici tila			wo's cor	npleme	nt binar	v						
		Bit Position	15	14	13	12	11	10	y 9	8					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
во	MFR SPECIFIC KP	Function	., .,	.,	., .,			., ••	1,, **	., ,,		YES			
50	1411 14_31 2611 16_1KI	Default Value	Integer Variable								123				
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function		· ·	1 -		eger								
		Default Value				Vari	_								
		Value used to progr	am spec	ific inte	egral coe	fficient	of the P	ID comp	ensatio	n Block.					
		Do not use value hig													
		Format				wo's cor	npleme	nt binar	у						
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
B1	MFR_SPECIFIC_KI	Function	Integer							YES					
ы	WII N_3FECII IC_KI	Default Value	Variable						ILS						
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function					eger								
		Default Value	ue Variable												
		Value con de con	alue used to program specific differential coefficient of the PID compensation. Do not												
					erential	coefficie	ent of th	ie PID C	mpens	ation. D	o not				
		use value higher that Format	1092		linear +	wo's cor	nnlomo	nt hinar	v						
		Bit Position	15	14	13	12	npieme 11	nt binar 10	y 9	8					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
В2	MFR_SPECIFIC_KD	Function	1 / ٧٧	1 / VV	1 / VV		eger	1 / VV	1/ ٧٧	1 / VV					
DZ	WII N_SI ECII IC_ND	Default Value					able					YES			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function	-,	,	1 .,		eger	,	,	.,					
		Default Value					able								
		Value used to progr	am spec	ific alph	ha value			pensatio	n block	[
		Format		l	Linear, t	wo's cor	npleme	nt binar	У						
		Bit Position	15	14	13	12	11	10	9	8					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
В3	MFR_SPECIFIC_ALPHA	Function Integer							YES						
	-	Default Value				Vari	able								
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function					eger								
		Default Value				Vari	able								

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Hex		Non-Volatile										
Code	Command				Brie	ef Descri	ption					Memory Storage
		Returns module nan	ne inform	nation (read or	nly)						
		Format				Unsigne	d Binary	У				
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r		
		Function	1			Rese	erved					
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0		YES
	Bit Position	7	6	5	4	3	2	1	0			
	Access	r	r	r	r	r	r	r	r			
			'	'				' '	_			
		Function	_			e Name		1	1	served		
		Default Value	0	0	1	1	0	1	0	0		
		Applies an offset to measurements of th		voltage	e (betw		5mV an	d +124r	nV). E			
]	Bit Position	15	14	13	12	11	10	9	8			
			r/w	r/w	r/w	r/w	r/w	r/w	r/w			
D.4	MFR_READ_VOUT_CAL_OF	Access	I/W	I/W	I/W	<u> </u>		1/W	I/W	I/W		VEC
D4	FSET	Function		17.	الالماماة		ntissa factorio	19				YES
		Default Value				ased on						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					ntissa					
		Default Value		Var	riable b	ased on	factory	calibrat	ion		<u> </u>	
	Applies a gain correc	rtion to t	ho DEA	ם אסו	T comm	and roc	ulto to o	alibra	to out gair	orrors in		
		Applies a gain correct module measureme generate the correct	nts of the	e outpu or.	ıt volta	ge. The	number	in this r	egiste	_		
D5		Format	1		inear, t	wo's co		nt binar		1		
		Bit Position	15	14	13	12	11	10	9	8		
	MFR_READ_VOUT_CAL_GA	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		VEC
	IN	Function				Inte	eger					YES
		Default Value		Var	iable b	ased on	factory	calibrat	ion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function				· · · · · · · · · · · · · · · · · · ·	eger		<u> </u>			
		Default Value Variable based on factory calibration										
		Applies an offset to the commanded output voltage to calibrate out errors in setting module output voltage (between -63mV and +62mV) when using Trim resistor. Exponent is fixed at -										
		14.										
		Format		Li	inear, t	wo's co	mpleme	nt binar	γ			
		Bit Position	15	14	13	12	11	10	9	8		
	1455 VOUT 200 2555	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		\/F6
D7	MFR_VOUT_CAL_OFFSET	Function				<u> </u>	ntissa			<u> </u>		YES
		Default Value		Var	iable b	ased on		calibrat	ion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	_		
		Function	,	,	,	<u> </u>	ntissa		.,.,.,	.,		
		Default Value		Var	iahle h	ased on		calibrat	ion			
			nine who							e VOLIT C	OMMAND	YFS
		Bit 7 used to deterr Bit 7: 1 – Output vo the VOUT_TRIM co	ltage is s		-	_		-		_		YES
		Bit 7: 0 – Output vo		olelv se	et hv V	סטד רח	MMANI	D and ca	n he :	adiusted fr	om set	
1		value using the VOI	_	-	-					anjusticu II	J.11 JCC	
		Bit 0: Used to indica	_			avo hoo	n mada	to the V	/out cc	t noint D	G On/Off	
1		levels, margin level			_						-	
D8	MFR_VOUT_SET_MODE	more of the values used.				-		-				
		Format				Hne	igned B	inan,				
			7	c	-				1	0		
		Bit Position		6		4	3	2	1		. 	
		Access	r/w	r/v	v r/w	/ r/w	r/w	r/w	r/w	r/w	<u>'</u>	
		Flag	VOUT_: T_MOE	DE ^		Х	Х	Х	Х	USER_CH	ANGES	
		Default Value	1	0	0	0	0	0	0	0		

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Table 4 (Continued)

Hex					`								Non-Volatile
Code	Command				Brie	f Descri	ption						Memory Storage
		Value used to progr	am the	firmwar	e revisio	n. This	commai	nd is rea	d only.				, ,
	MFR_FW_REVISION	Format						nt binar	•				
		Bit Position	15	14	13	12	11	10	9	8			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function Integer – Major Version											
DB		Default Value	Variable										
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function		•	Inte	ger – M	inor Ver	sion					
		Default Value				Vari	able						
		Returns the index defrom 0 to 59.	erived fr	om the	resistor	strappe	ed to the	e RTUNE	pin of	the mo	dule. R	ange is	
	MFR_RTUNE_INDEX	Format				Unsigne	d Binary	/					
DD		Bit Position	7	6	5	4	3	2	1	0			YES
		Access	r	r	r	r	r	r	r	r			
		Function				Inte	eger						
		Default Value				Vari	able						
		Gets or sets the write protection status of various PMBus commands. When a bit is set, the corresponding PMBus command is write protected and can only be read. Format Unsigned Binary								the			
		Bit Position	15	14	13	12	. 1	1 1	LO	9	8		
		Access	r	r	r	r	r	•	r	r	r		
		Function	Reserved										
		Default Value	х	х	х	х	>	(х	х	х		
DF	MFR WRITE PROTECT	Bit Position	7	6	5	4	3	3	2	1	0		YES
-		Access	r	r	r	r	r/	w r	/w	r/w	r/w		. 20
		Function		Res	served				Used				
		Default Value	х	х	Х	х	1	L	1	1	0		
		Bit 0: ON_OFF_CON											
		Bit 1: IOUT_OC_FAU	_	IT									
		Bit 2: OT_FAULT_LIN											
		Bit 3: OT_FAULT_RE											
		Bits 4 – 15: Reserve			40 1- 1		1	- () () (= =	3404000				
		Read only command		returns	12 byte	s with th	ne value	OT YYFF	WWXX	XXXX, \	wnere		
	MFR_MODULE_DATE_LOC_	YY : year of manufactory where m		urod									YES
F0	SN	WW: Fiscal week of			unit was	manuf	actured						
	JIV	XXXXXX: Unique nur						ing to se	rial nur	nher o	n the la	hel of	
		the unit.	11561 101	the spe	Lerric ull		сэрони	g se	ai iiui	iibei 0	ii uic ia	DEI OI	
	1	and dille											1

SMBALERT# is also triggered:

- when an invalid/unrecognized PMBus command (write or read) is issued
- By invalid PMBus data (write)
- By PEC Failure (when used)
- By Enable OFF (when used)
- Module is out of Power Good Range

Digital Power Insight (DPI)

GE offers a software tool that set helps users evaluate and simulate the PMBus performance of the TJT120A modules without the need to write software.

The software can be downloaded for free at http://go.ge-energy.com/DigitalPowerInsight.html. A GE USB to I2C adapter and associated cable set are required for proper functioning of the software suite. For first time users, the GE DPI Evaluation Kit can be purchased from leading distributors at a nominal price and can be used across the entire range of GE Digital POL Modules.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 37. The preferred airflow direction for the module is in Figure 38.

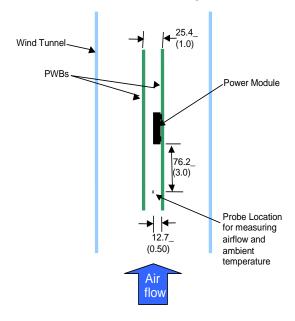


Figure 37. Thermal Test Setup.

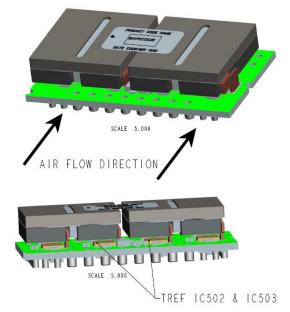


Figure 38. Preferred airflow direction and location of hotspots of the module (Tref).

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 38. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Example Application Circuit

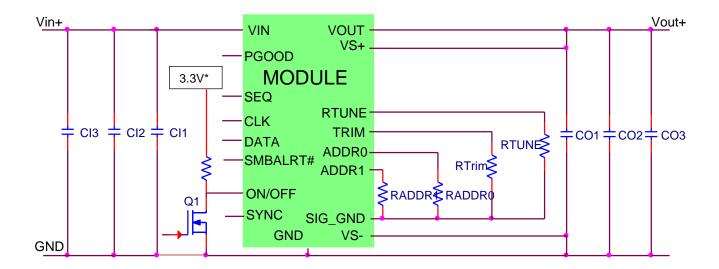
Requirements:

Vin: 12V Vout: 1.2V

lout: 120A max., worst case load transient is from 60A to 90A, 10A/usec

ΔVout: 25mV for worst case load transient

Vin, ripple 2% of Vin (240mV p-p)



3.3V* can be derived from Vin through a suitable voltage divider network

CI1 $4 \times 0.047 \mu F$ (high-frequency decoupling ceramic capacitor)

CI2 12 x 22 µF Ceramic

CI3 $4 \times 470 \mu F$ (polymer or electrolytic)

CO1 $4 \times 0.047 \mu F$ (high-frequency decoupling ceramiccapacitor)

CO2 $12 \times 47 \ \mu\text{F}$, Ceramic CO3 $7 \times 1000 \ \mu\text{F}$ RTune 2460Ω , RTrim $5.9 \text{K}\Omega$

Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the PMBus master controller will have pull-up resistors as well as provide the driving source for these signals.

If running the simulation at ge.transim.com remember to use bin 'a' parameters to determine the Loop Stability, and bin 'b' parameters to determine the transient response.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

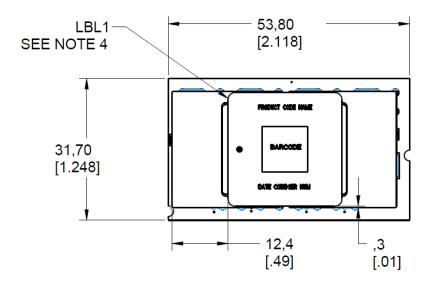
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Mechanical Outline (SMT)

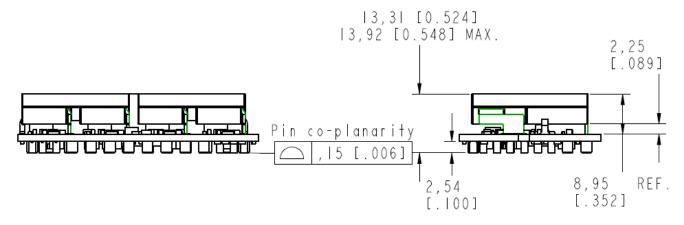
Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

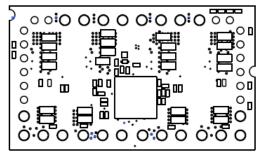
x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



TOP VIEW



FRONT VIEW SIDE VIEW



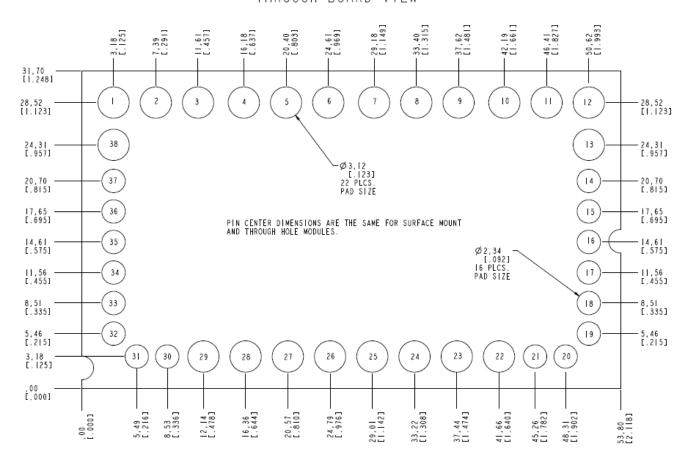
BOTTOM VIEW

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Recommended SMT Pad Layout

RECOMMENDED SMT FOOTPRINT -THROUGH BOARD VIEW -



PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

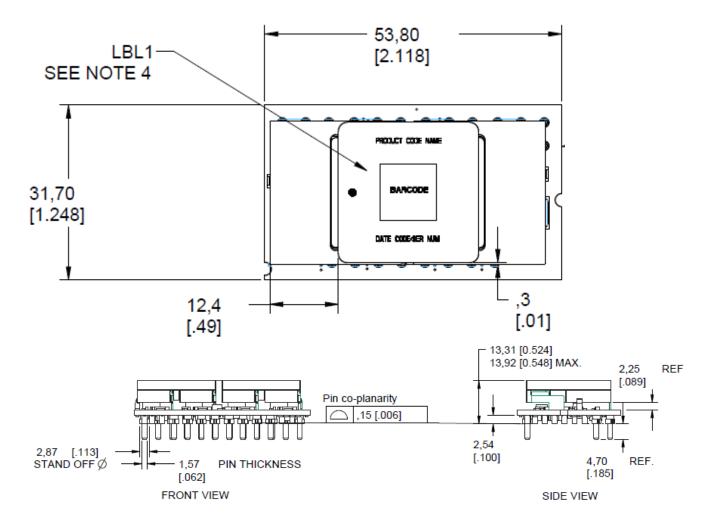
4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

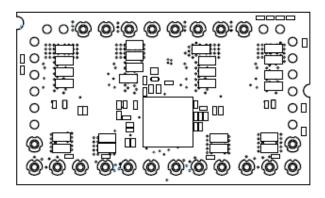
Mechanical Outline (Through hole)

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



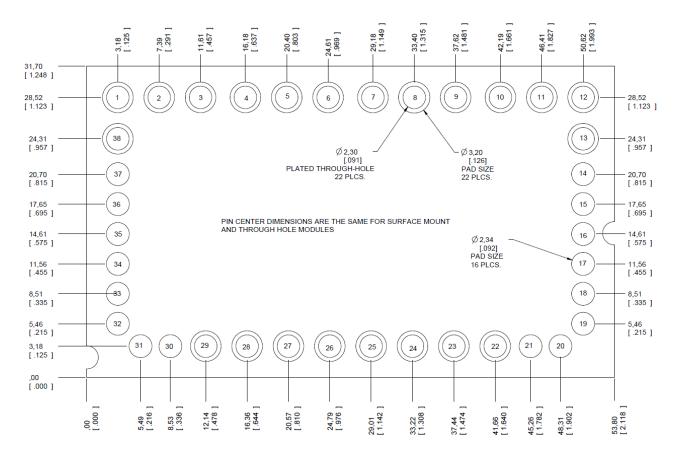


BOTTOM VIEW

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Recommended Through-hole Layout



Note: In the Through-Hole version of the TJT120, pins 1-13, 22-29 and 38 are Through-Hole pins, pins 14-21, 30-37 are SMT pins. The drawing above shows the recommended layout as a combination of holes in the PWB to accommodate the Through-Hole pins and pads on the top layer to accommodate the SMT pins.

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE/NC
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND*	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

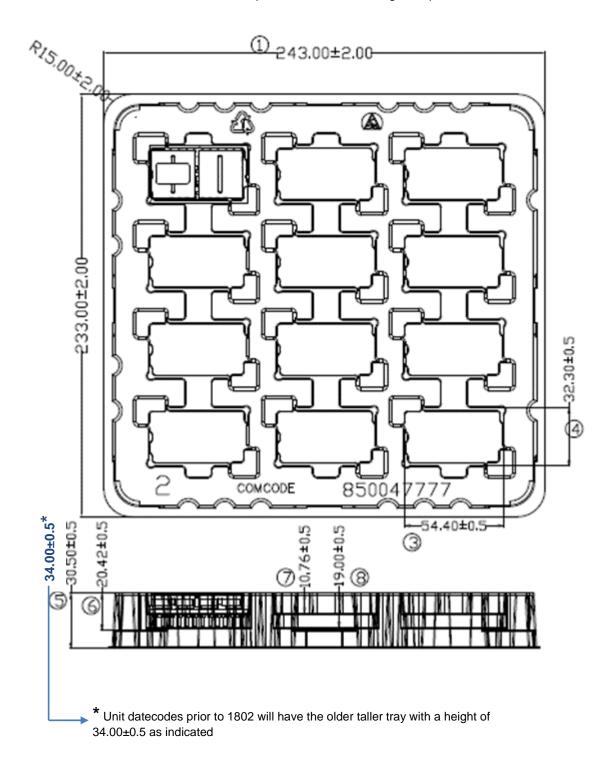
^{*}Do not connect SIG_GND to any other GND paths. It needs to be kept separate from other grounds on the board external to the module

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Packaging Details

The 120A TeraDLynx[™] modules are supplied in trays. Modules are shipped in quantities of 12 modules per layer, 24 per box. All Dimensions are in millimeters. All radius unspecified are R2.0mm. All angles unspecified are 5°.



120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Surface Mount Information Pick and Place

The 120A TeraDLynx™ modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 15mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 22 mm.

Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 120A TeraDLynx[™] modules have a MSL rating of 3.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is

broken, the floor life of the product at conditions of $\leq 30^{\circ}$ C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: $< 40^{\circ}$ C, < 90% relative humidity.

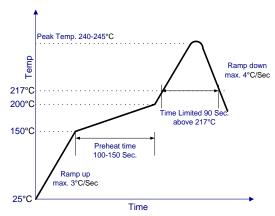


Figure 39. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (ANO4-001).

Through Hole Information

The 120A TeraDLynx™ modules are lead-free (Pb-free) and RoHS compliant and fully compatible in an Pb-free soldering process. For the through-hole application, it is recommended that the modules are assembled in the pin and paste reflow process, not in the wave solder process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 1.5Vdc output; 120A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 5. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Interconnect	Comcodes
TJT120A0X3Z#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	TH	150043982
TJT120A0X43Z#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Positive	TH	150049601
TJT120A0X3-SZ#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Negative	SMT	150041745
TJT120A0X43-SZ#	7 – 14Vdc	0.6 – 1.5 Vdc	120A	Positive	SMT	150049603

⁻Z refers to RoHS compliant parts

*TJT120A0X3-SZ, TJT120A0X3Z, TJT120A0X43-SZ, and TJT120A0X43Z are End of Life (EOL). Last Time Buy September 30, 2020. Orders after September 30, 2020 will continue to be accepted until supplies last.

Table 6. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options		ROHS Compliance
Т	J	Т	120A0	Х		3	-SR	-H	Z
P=Pico U=Micro M=Mega G=Giga T=Tera	J = DLynx II	T=with EZ Sequence X=without sequencing	120A	X = programm able output	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel No entry = Through hole	Extra Ground Pins	Z = ROHS6

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