## General Description

The AOZ1212 is a high efficiency, simple to use, 3A buck regulator flexible enough to be optimized for a variety of applications. The AOZ1212 works from a 4.5 V to 27 V input voltage range, and provides up to 3A of continuous output current on each buck regulator output. The output voltage is adjustable down to 0.8 V .

The AOZ1212 comes in an SO-8 or DFN-8 package and is rated over a $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ ambient temperature range.

## Features

- 4.5 V to 27 V operating input voltage range
- $70 \mathrm{~m} \Omega$ internal NFET, efficiency: up to $95 \%$
- Internal soft start
- Output voltage adjustable down to 0.8 V
- 3A continuous output current
- Fixed 370 kHz PWM operation
- Cycle-by-cycle current limit
- Short-circuit protection
- Thermal shutdown
- Small size SO-8 or DFN-8 package


## Applications

- Point of load DC/DC conversion
- Set top boxes
- DVD drives and HDD
- LCD monitors and TVs
- Cable modems
- Telecom/networking/datacom equipment


## Typical Application



Figure 1. 3.3V/3A Buck Regulator

## Ordering Information

| Part Number | Ambient Temperature Range | Package | Environmental |
| :---: | :---: | :---: | :---: |
| $\mathrm{AOZ1212AI}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | SO-8 | RoHS Compliant <br> Green Product |
| $\mathrm{AOZ1212DI}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $5 \times 4 \mathrm{DFN}-8$ |  |

AOS Green Products use reduced levels of Halogens, and are also RoHS compliant.
Please visit www.aosmd.com/web/quality/rohs_compliant.jsp for additional information.

## Pin Configuration



## Pin Description

| Pin Number | Pin Name | Pin Function |
| :---: | :---: | :--- |
| 1 | LX | PWM output connection to inductor. LX pin needs to be connected externally. Thermal connection <br> for output stage. |
| 2 | BST | Bootstrap voltage input. High side driver supply. Connected to $0.1 \mu \mathrm{~F}$ capacitor between BST and <br> LX. |
| 3 | GND | Ground. |
| 4 | FB | Feedback input. It is regulated to 0.8 V . The FB pin is used to determine the PWM output voltage <br> via a resistor divider between the output and GND. |
| 5 | COMP | External loop compensation. Output of internal error amplifier. Connect a series RC network to <br> GND for control loop compensation. |
| 7 | EN | Enable pin. The enable pin is active HIGH. Connect EN pin to $\mathrm{V}_{\text {IN }}$ if not used. Do not leave the EN <br> pin floating. |
| 8 | VBIAS | Supply voltage input. Range from 4.5V to 27V. When $\mathrm{V}_{\text {IN }}$ rises above the UVLO threshold the <br> device starts up. All $\mathrm{V}_{\text {IN }}$ pins need to be connected externally. |
| Compensation pin of internal linear regulator. Place put a $1 \mu \mathrm{~F}$ capacitor between this pin and <br> ground. |  |  |

## Block Diagram



## Absolute Maximum Ratings

Exceeding the Absolute Maximum Ratings may damage the device.

| Parameter | Rating |
| :--- | ---: |
| Supply Voltage $\left(\mathrm{V}_{\mathrm{IN}}\right)$ | -0.7 V to $\mathrm{V}_{\mathrm{IN}}+0.3 \mathrm{~V}$ |
| LX to GND | -0.3 V to $\mathrm{V}_{\mathrm{IN}}+0.3 \mathrm{~V}$ |
| EN to GND | -0.3 V to 6 V |
| FB to GND | -0.3 V to 6 V |
| COMP to GND | $\mathrm{V}_{\mathrm{LX}}+6 \mathrm{~V}$ |
| BST to GND | -0.3 V to 6 V |
| VBIAS to GND | $+150^{\circ} \mathrm{C}$ |
| Junction Temperature $\left(\mathrm{T}_{\mathrm{J}}\right)$ | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Storage Temperature ( $\left.\mathrm{T}_{\mathrm{S}}\right)$ | 2 kV |
| ESD Rating: Human Body Model ${ }^{(1)}$ |  |

## Note:

1. Devices are inherently ESD sensitive, handling precautions are required. Human body model rating: $1.5 \mathrm{k} \Omega$ in series with 100 pF .

Recommended Operating Conditions
The device is not guaranteed to operate beyond the Recommended Operating Conditions.

| Parameter | Rating |
| :--- | ---: |
| Supply Voltage $\left(\mathrm{V}_{\mathrm{IN}}\right)$ | 4.5 V to 27 V |
| Output Voltage Range | 0.8 V to $0.85^{*} \mathrm{~V}_{\mathrm{IN}}$ |
| Ambient Temperature $\left(\mathrm{T}_{\mathrm{A}}\right)$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Package Thermal Resistance $\left(\Theta_{\mathrm{JA}}\right)^{(2)}$ |  |
| SO-8 | $105^{\circ} \mathrm{C} / \mathrm{W}$ |
| DFN-8 | $53^{\circ} \mathrm{C} / \mathrm{W}$ |

## Note:

2. The value of $\Theta_{J A}$ is measured with the device mounted on $1-\mathrm{in}^{2}$ FR-4 board with 20 . Copper, in a still air environment with $T_{A}=$ $25^{\circ} \mathrm{C}$. The value in any given application depends on the user's specific board design.

## Electrical Characteristics

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {EN }}=12 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=3.3 \mathrm{~V}$ unless otherwise specified $^{(3)}$

| Symbol | Parameter | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IN }}$ | Supply Voltage |  | 4.5 |  | 27 | V |
| $\mathrm{V}_{\text {UVLO }}$ | Input Under-Voltage Lockout Threshold | $V_{\text {IN }}$ Rising <br> $V_{\text {IN }}$ Falling |  | $\begin{aligned} & 4.3 \\ & 4.1 \end{aligned}$ |  | V |
| IN | Supply Current (Quiescent) | $\mathrm{l}_{\text {OUT }}=0, \mathrm{~V}_{\mathrm{FB}}=1.2 \mathrm{~V}, \mathrm{~V}_{\mathrm{EN}}>2 \mathrm{~V}$ |  | 2 | 3 | mA |
| IOFF | Shutdown Supply Current | $\mathrm{V}_{\mathrm{EN}}=0 \mathrm{~V}$ |  | 3 | 20 | $\mu \mathrm{A}$ |
| $V_{\text {FB }}$ | Feedback Voltage |  | 0.782 | 0.8 | 0.818 | V |
|  | Load Regulation |  |  | 0.5 |  | \% |
|  | Line Regulation |  |  | 0.08 |  | \% / V |
| $\mathrm{I}_{\text {FB }}$ | Feedback Voltage Input Current |  |  |  | 200 | nA |
| ENABLE |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{EN}}$ | EN Input Threshold | Off Threshold On Threshold | 2.5 |  | 0.6 | V |
| $\mathrm{V}_{\mathrm{HYS}}$ | EN Input Hysteresis |  |  | 200 |  | mV |
| $\mathrm{I}_{\text {EN }}$ | Enable Sink/Source Current |  |  |  | 50 | nA |
| MODULATOR |  |  |  |  |  |  |
| $\mathrm{f}_{0}$ | Frequency |  | 315 | 370 | 425 | kHz |
| $\mathrm{D}_{\text {MAX }}$ | Maximum Duty Cycle |  | 85 |  |  | \% |
| $\mathrm{D}_{\text {MIN }}$ | Minimum Duty Cycle |  |  |  | 6 | \% |
| $\mathrm{G}_{\text {VEA }}$ | Error Amplifier Voltage Gain |  |  | 500 |  | V/V |
| $\mathrm{G}_{\mathrm{EA}}$ | Error Amplifier Transconductance |  |  | 200 |  | $\mu \mathrm{A} / \mathrm{V}$ |
| PROTECTION |  |  |  |  |  |  |
| ILIM | Current Limit |  | 4.0 |  | 6.0 | A |
|  | Over-Temperature Shutdown Limit | $T_{J}$ Rising $\mathrm{T}_{\mathrm{J}}$ Falling |  | $\begin{aligned} & 145 \\ & 100 \end{aligned}$ |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{f}_{\text {SC }}$ | Short Circuit Hiccup Frequency | $\mathrm{V}_{\mathrm{FB}}=0 \mathrm{~V}$ |  | 24 |  | kHz |
| $t_{\text {SS }}$ | Soft Start Interval |  |  | 6 |  | ms |
| PWM OUTPUT STAGE |  |  |  |  |  |  |
| $\mathrm{R}_{\mathrm{DS} \text { (ON) }}$ | High-Side Switch On-Resistance |  |  | 70 | 100 | $\mathrm{m} \Omega$ |
|  | High-Side Switch Leakage | $\mathrm{V}_{\mathrm{EN}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{LX}}=0 \mathrm{~V}$ |  |  | 10 | $\mu \mathrm{A}$ |

## Note:

3. Specification in BOLD indicate an ambient temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$. These specifications are guaranteed by design.

## Typical Performance Characteristics

Circuit of Figure 1. $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{EN}}=24 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=3.3 \mathrm{~V}$ unless otherwise specified.

Light Load (DCM) Operation


Startup to Full Load


50\% to 100\% Load Transient


Full Load (CCM) Operation


Short Circuit Protection


Short Circuit Recovery


## Efficiency Curves




Efficiency


## Detailed Description

The AOZ1212 is a current-mode step down regulator with integrated high side NMOS switch. It operates from a 4.5 V to 27 V input voltage range and supplies up to 3 A of load current. The duty cycle can be adjusted from 6\% to $85 \%$ allowing a wide range of output voltages. Features include enable control, Power-On Reset, input under voltage lockout, fixed internal soft-start and thermal shut down.

The AOZ1212 is available in an SO-8 or DFN-8 package.

## Enable and Soft Start

The AOZ1212 has an internal soft start feature to limit in-rush current and ensure the output voltage ramps up smoothly to the regulation voltage. A soft start process begins when the input voltage rises to 4.1 V and voltage on EN pin is HIGH. In the soft start process, the output voltage is typically ramped to regulation voltage in 6.8 ms . The 6.8 ms soft start time is set internally.

If the enable function is not used, connect the EN pin to $\mathrm{V}_{\mathrm{IN}}$. Pulling EN to ground will disable the AOZ1212. Do not leave EN open. The voltage on the EN pin must be above 2.5 V to enable the AOZ1212. When voltage on EN pin falls below 0.6 V , the $\mathrm{AOZ1212}$ is disabled. If an application circuit requires the AOZ1212 to be disabled, an open drain or open collector circuit should be used to interface with the EN pin.

## Steady-State Operation

Under steady-state conditions, the converter operates in fixed frequency and Continuous-Conduction Mode (CCM).
The AOZ1212 integrates an internal N-MOSFET as the high-side switch. Inductor current is sensed by amplifying the voltage drop across the drain to source of the high side power MOSFET. Since the N-MOSFET requires a gate voltage higher than the input voltage, a boost capacitor connected between the LX and BST pins drives the gate. The boost capacitor is charged while LX is low. An internal $10 \Omega$ switch from LX to GND is used to ensure that LX is pulled to GND even in the light load. Output voltage is divided down by the external voltage divider at the FB pin. The difference of the FB pin voltage and reference is amplified by the internal transconductance error amplifier. The error voltage, which shows on the COMP pin, is compared against the current signal. The current signal is the sum of inductor current signal and ramp compensation signal, at the PWM comparator input. If the current signal is less than the error voltage, the internal high-side switch is on. The inductor current flows from the input through the inductor to the output. When the current signal exceeds the error voltage, the
high-side switch is off. The inductor current is freewheeling through the Schottky diode to the output.

## Switching Frequency

The AOZ1212 switching frequency is fixed and set by an internal oscillator. The switching frequency is set to 370kHz.

## Output Voltage Programming

Output voltage can be set by feeding back the output to the FB pin with a resistor divider network. In the application circuit shown in Figure 1. The resistor divider network includes $R_{1}$ and $R_{2}$. Typically, a design is started by picking a fixed $R_{2}$ value and calculating the required $R_{1}$ value with equation below.

$$
V_{O}=0.8 \times\left(1+\frac{R_{1}}{R_{2}}\right)
$$

Some standard values for $R_{1}$ and $R_{2}$ for the most commonly used output voltages are listed in Table 1.

Table 1.

| $\mathbf{V}_{\mathbf{0}}(\mathrm{V})$ | $\mathbf{R}_{\mathbf{1}}(\mathbf{k} \Omega)$ | $\mathbf{R}_{\mathbf{2}}(\mathbf{k} \Omega)$ |
| :--- | :--- | :--- |
| 0.8 | 1.0 | Open |
| 1.2 | 4.99 | 10 |
| 1.5 | 10 | 11.5 |
| 1.8 | 12.7 | 10.2 |
| 2.5 | 21.5 | 10 |
| 3.3 | 31.6 | 10 |
| 5.0 | 52.3 | 10 |

The combination of $R_{1}$ and $R_{2}$ should be large enough to avoid drawing excessive current from the output, which will cause power loss.

## Protection Features

The AOZ1212 has multiple protection features to prevent system circuit damage under abnormal conditions.

## Over Current Protection (OCP)

The sensed inductor current signal is also used for over current protection. Since the AOZ1212 employs peak current mode control, the COMP pin voltage is proportional to the peak inductor current. The COMP pin voltage is limited to be between 0.4 V and 2.5 V internally. The peak inductor current is automatically limited cycle by cycle.
The cycle-by-cycle current limit threshold is internally set. When the load current reaches the current limit threshold, the cycle-by-cycle current limit circuit turns off the
high side switch immediately to terminate the current duty cycle. The inductor current stops rising. The cycle-by-cycle current limit protection directly limits inductor peak current. The average inductor current is also limited due to the limitation on the peak inductor current. When cycle-by-cycle current limit circuit is triggered, the output voltage drops as the duty cycle decreases.

The AOZ1212 has internal short circuit protection to protect itself from catastrophic failure under output short circuit conditions. The FB pin voltage is proportional to the output voltage. Whenever the FB pin voltage is below 0.2 V , the short circuit protection circuit is triggered. To prevent current limit running away when the comp pin voltage is higher than 2.1 V , the short circuit protection is also triggered. As a result, the converter is shut down and hiccups at a frequency equals to $1 / 16$ of normal switching frequency. The converter will start up via a soft start once the short circuit condition is resolved. In short circuit protection mode, the inductor average current is greatly reduced because of the low hiccup frequency.

## Power-On Reset (POR)

A power-on reset circuit monitors the input voltage. When the input voltage exceeds 4.3 V , the converter starts operation. When input voltage falls below 4.1V, the converter will stop switching.

## Thermal Protection

An internal temperature sensor monitors the junction temperature. It shuts down the internal control circuit and high side NMOS if the junction temperature exceeds $145^{\circ} \mathrm{C}$. The regulator will restart automatically under the control of soft-start circuit when the junction temperature decreases to $100^{\circ} \mathrm{C}$.

## Application Information

The basic AOZ1212 application circuit is shown in Figure 1. Component selection is explained below.

## Input Capacitor

The input capacitor ( $\mathrm{C}_{1}$ in Figure 1) must be connected to the $\mathrm{V}_{\mathrm{IN}}$ pin and GND pin of the AOZ1212 to maintain steady input voltage and filter out the pulsing input current. The voltage rating of the input capacitor must be greater than maximum input voltage + ripple voltage.
The input ripple voltage can be approximated by equation below:

$$
\Delta V_{I N}=\frac{I_{O}}{f \times C_{I N}} \times\left(1-\frac{V_{O}}{V_{I N}}\right) \times \frac{V_{O}}{V_{I N}}
$$

Since the input current is discontinuous in a buck converter, the current stress on the input capacitor is
another concern when selecting the capacitor. For a buck circuit, the RMS value of input capacitor current can be calculated by:

$$
I_{C I N_{-} R M S}=I_{O} \times \sqrt{\frac{V_{O}}{V_{I N}}\left(1-\frac{V_{O}}{V_{I N}}\right)}
$$

if let $m$ equal the conversion ratio:
$\frac{V_{O}}{V_{I N}}=m$
The relationship between the input capacitor RMS current and voltage conversion ratio is calculated and shown in Figure 2. It can be seen that when $\mathrm{V}_{\mathrm{O}}$ is half of $\mathrm{V}_{\mathrm{IN}}, \mathrm{C}_{\mathrm{IN}}$ is under the worst current stress. The worst current stress on CIN is $0.5 \times \mathrm{I}_{\mathrm{O}}$.


Figure 2. ICIN vs. Voltage Conversion Ratio
For reliable operation and best performance, the input capacitors must have a current rating higher than $\mathrm{I}_{\mathrm{CIN} \_ \text {RMS }}$ at the worst operating conditions. Ceramic capacitors are preferred for input capacitors because of their low ESR and high ripple current rating. Depending on the application circuits, other low ESR tantalum capacitor or aluminum electrolytic capacitor may also be used. When selecting ceramic capacitors, X5R or X7R type dielectric ceramic capacitors are preferred for their better temperature and voltage characteristics. Note that the ripple current rating from capacitor manufactures is based on certain amount of life time. Further de-rating may be necessary for practical design requirement.

## Inductor

The inductor is used to supply constant current to output when it is driven by a switching voltage. For given input and output voltage, inductance and switching frequency together decide the inductor ripple current, which is,

$$
\Delta I_{L}=\frac{V_{O}}{f \times L} \times\left(1-\frac{V_{O}}{V_{I N}}\right)
$$

The peak inductor current is:

$$
I_{\text {Lpeak }}=I_{O}+\frac{\Delta I_{L}}{2}
$$

High inductance gives low inductor ripple current but requires larger size inductor to avoid saturation. Low ripple current reduces inductor core losses. It also reduces RMS current through inductor and switches, which results in less conduction loss.
When selecting the inductor, make sure it is able to handle the peak current without saturation even at the highest operating temperature.
The inductor takes the highest current in a buck circuit. The conduction loss on inductor needs to be checked for thermal and efficiency requirements.
Surface mount inductors in different shape and styles are available from Coilcraft, Elytone and Murata. Shielded inductors are small and radiate less EMI noise. But they cost more than unshielded inductors. The choice depends on EMI requirement, price and size.

## Output Capacitor

The output capacitor is selected based on the DC output voltage rating, output ripple voltage specification and ripple current rating.
The selected output capacitor must have a higher rated voltage specification than the maximum desired output voltage including ripple. De-rating needs to be considered for long term reliability.
Output ripple voltage specification is another important factor for selecting the output capacitor. In a buck converter circuit, output ripple voltage is determined by inductor value, switching frequency, output capacitor value and ESR. It can be calculated by the equation below:

$$
\Delta V_{O}=\Delta I_{L} \times\left(E S R_{C O}+\frac{1}{8 \times f \times C_{O}}\right)
$$

where;
$\mathrm{C}_{\mathrm{O}}$ is output capacitor value and
$E S R_{\mathrm{CO}}$ is the Equivalent Series Resistor of output capacitor.
When low ESR ceramic capacitor is used as output capacitor, the impedance of the capacitor at the switching frequency dominates. Output ripple is mainly caused by capacitor value and inductor ripple current. The output ripple voltage calculation can be simplified to:
$\Delta V_{O}=\Delta I_{L} \times\left(\frac{1}{8 \times f \times C_{O}}\right)$

If the impedance of ESR at switching frequency dominates, the output ripple voltage is mainly decided by capacitor ESR and inductor ripple current. The output ripple voltage calculation can be further simplified to:

$$
\Delta V_{O}=\Delta I_{L} \times E S R_{C O}
$$

For lower output ripple voltage across the entire operating temperature range, X5R or X7R dielectric type of ceramic, or other low ESR tantalum capacitor or aluminum electrolytic capacitor may also be used as output capacitors.
In a buck converter, output capacitor current is continuous. The RMS current of output capacitor is decided by the peak to peak inductor ripple current. It can be calculated by:

$$
I_{C O_{-} R M S}=\frac{\Delta I_{L}}{\sqrt{12}}
$$

Usually, the ripple current rating of the output capacitor is a smaller issue because of the low current stress. When the buck inductor is selected to be very small and inductor ripple current is high, output capacitor could be overstressed.

## Schottky Diode Selection

The external freewheeling diode supplies the current to the inductor when the high side NMOS switch is off. To reduce the losses due to the forward voltage drop and recovery of diode, a Schottky diode is recommended. The maximum reverse voltage rating of the chosen Schottky diode should be greater than the maximum input voltage, and the current rating should be greater than the maximum load current.

## Loop Compensation

The AOZ1212 employs peak current mode control for easy use and fast transient response. Peak current mode control eliminates the double pole effect of the output L\&C filter. It greatly simplifies the compensation loop design.
With peak current mode control, the buck power stage can be simplified to be a one-pole and one-zero system in frequency domain. The pole is the dominant pole and can be calculated by:

$$
f_{p 1}=\frac{1}{2 \pi \times C_{O} \times R_{L}}
$$

The zero is a ESR zero due to output capacitor and its ESR. It is can be calculated by:

$$
f_{Z 1}=\frac{1}{2 \pi \times C_{O} \times E S R_{C O}}
$$

where;
$\mathrm{C}_{\mathrm{O}}$ is the output filter capacitor,
$R_{L}$ is load resistor value, and
$\mathrm{ESR}_{\mathrm{CO}}$ is the equivalent series resistance of output capacitor.
The compensation design is actually to shape the converter close loop transfer function to get desired gain and phase. Several different types of compensation network can be used for AOZ1212. For most cases, a series capacitor and resistor network connected to the COMP pin sets the pole-zero and is adequate for a stable high-bandwidth control loop.
In the AOZ1212, FB pin and COMP pin are the inverting input and the output of internal transconductance error amplifier. A series $R$ and $C$ compensation network connected to COMP provides one pole and one zero. The pole is:

$$
f_{p 2}=\frac{G_{E A}}{2 \pi \times C_{C} \times G_{V E A}}
$$

where;
$G_{E A}$ is the error amplifier transconductance, which is $200 \times 10^{-6}$ $\mathrm{A} / \mathrm{V}$,
$G_{\text {VEA }}$ is the error amplifier voltage
The zero given by the external compensation network, capacitor $\mathrm{C}_{\mathrm{C}}$ (C5 in Figure 1) and resistor $\mathrm{R}_{\mathrm{C}}(\mathrm{R} 1$ in Figure 1), is located at:

$$
f_{Z 2}=\frac{1}{2 \pi \times C_{C} \times R_{C}}
$$

To design the compensation circuit, a target crossover frequency $\mathrm{f}_{\mathrm{C}}$ for close loop must be selected. The system crossover frequency is where the control loop has unity gain. The crossover frequency is also called the converter bandwidth. Generally a higher bandwidth means faster response to load transient. However, the bandwidth should not be too high due to system stability concern. When designing the compensation loop, converter stability under all line and load condition must be considered.

Usually, it is recommended to set the bandwidth to be less than $1 / 10$ of switching frequency. It is recommended to choose a crossover frequency less than 30 kHz .

$$
f_{C}=30 \mathrm{kHz}
$$

The strategy for choosing $\mathrm{R}_{\mathrm{C}}$ and $\mathrm{C}_{\mathrm{C}}$ is to set the cross over frequency with $\mathrm{R}_{\mathrm{C}}$ and set the compensator zero with $\mathrm{C}_{\mathrm{C}}$. Using selected crossover frequency, $\mathrm{f}_{\mathrm{C}}$, to calculate $\mathrm{R}_{\mathrm{C}}$ :

$$
R_{C}=f_{C} \times \frac{v_{O}}{v_{F B}} \times \frac{2 \pi \times C_{O}}{G_{E A} \times G_{C S}}
$$

where;
$\mathrm{f}_{\mathrm{C}}$ is desired crossover frequency,
$V_{F B}$ is 0.8 V ,
$G_{E A}$ is the error amplifier transconductance, which is $200 \times 10^{-6}$ A/V, and
$\mathrm{G}_{\mathrm{CS}}$ is the current sense circuit transconductance, which is $5.64 \mathrm{~A} / \mathrm{V}$

The compensation capacitor $\mathrm{C}_{\mathrm{C}}$ and resistor $\mathrm{R}_{\mathrm{C}}$ together make a zero. This zero is put somewhere close to the dominate pole fp1 but lower than $1 / 5$ of the selected crossover frequency. $\mathrm{C}_{\mathrm{C}}$ can is selected by:

$$
C_{C}=\frac{1.5}{2 \pi \times R_{C} \times f_{p 1}}
$$

The equation above can also be simplified to:

$$
c_{C}=\frac{C_{O} \times R_{L}}{R_{C}}
$$

An easy-to-use application software which helps to design and simulate the compensation loop can be found at www.aosmd.com.

## Thermal Management and Layout Consideration

In the AOZ1212 buck regulator circuit, high pulsing current flows through two circuit loops. The first loop starts from the input capacitors, to the $\mathrm{V}_{\text {IN }}$ pin, to the LX pins, to the filter inductor, to the output capacitor and load, and then returns to the input capacitor through ground. Current flows in the first loop when the high side switch is on. The second loop starts from inductor, to the output capacitors and load, to the GND pin of the AOZ1212, to the LX pins of the AZO1212. Current flows in the second loop when the low side diode is on.

In PCB layout, minimizing the two loops area reduces the noise of this circuit and improves efficiency. A ground plane is recommended to connect input capacitor, output capacitor, and GND pin of the AOZ1212.
In the AOZ1212 buck regulator circuit, the three major power dissipating components are the AOZ1212, external diode and output inductor. The total power
dissipation of converter circuit can be measured by input power minus output power.

$$
P_{\text {total_loss }}=V_{I N} \times I_{I N}-V_{O} \times I_{O}
$$

The power dissipation of inductor can be approximately calculated by output current and DCR of the inductor.

$$
P_{\text {inductor_loss }}=I_{O}^{2} \times R_{\text {inductor }} \times 1.1
$$

The power dissipation of the diode is:

$$
P_{\text {diode_loss }}=I_{O} \times V_{F} \times\left(1-\frac{V_{O}}{V_{I N}}\right)
$$

The actual AOZ1212 junction temperature can be calculated with power dissipation in the AOZ1212 and thermal impedance from junction to ambient.

$$
\begin{aligned}
T_{\text {junction }}= & \left(P_{\text {total_loss }}-P_{\text {inductor_loss }}\right) \times \Theta_{J A} \\
& +T_{\text {ambient }}
\end{aligned}
$$

The maximum junction temperature of AOZ1212 is $145^{\circ} \mathrm{C}$, which limits the maximum load current capability.
The thermal performance of the AOZ1212 is strongly affected by the PCB layout. Care should be taken by users during design process to ensure that the IC will operate under the recommended environmental conditions.

Several layout tips are listed below for the best electric and thermal performance. Figure 3a and Figure 3b show layout examples for the AOZ1212A and AOZ1212D respectively.

1. Do not use thermal relief connection to the $\mathrm{V}_{\mathrm{IN}}$ and the GND pin. Pour a maximized copper area to the GND pin and the $\mathrm{V}_{\text {IN }}$ pin to help thermal dissipation.
2. Input capacitor should be connected as close as possible to the $\mathrm{V}_{\mathrm{IN}}$ and GND pins.
3. Make the current trace from $L X$ pins to $L$ to $C_{O}$ to GND as short as possible.
4. Pour copper plane on all unused board area and connect it to stable DC nodes, like $\mathrm{V}_{\mathrm{IN}}$, GND or $\mathrm{V}_{\text {OUT }}$.
5. Keep sensitive signal traces such as the trace connecting FB and COMP pins away from the LX pins.


Figure 3a. Layout Example for AOZ1212AI


Figure 3b. Layout Example for AOZ1212DI

## Package Dimensions, SO-8




Unit: mm

Dimensions in millimeters

| Symbols | Min. | Nom. | Max. |
| :---: | :---: | :---: | :---: |
| A | 1.35 | 1.65 | 1.75 |
| A1 | 0.10 | - | 0.25 |
| A2 | 1.25 | 1.50 | 1.65 |
| b | 0.31 | - | 0.51 |
| c | 0.17 | - | 0.25 |
| D | 4.80 | 4.90 | 5.00 |
| E1 | 3.80 | 3.90 | 4.00 |
| e | 1.27 BSC |  |  |
| E | 5.80 | 6.00 | 6.20 |
| h | 0.25 | - | 0.50 |
| L | 0.40 | - | 1.27 |
| $\theta$ | $0^{\circ}$ | - | $8^{\circ}$ |

Dimensions in inches

| Symbols | Min. | Nom. | Max. |
| :---: | :---: | :---: | :---: |
| A | 0.053 | 0.065 | 0.069 |
| A1 | 0.004 | - | 0.010 |
| A2 | 0.049 | 0.059 | 0.065 |
| b | 0.012 | - | 0.020 |
| c | 0.007 | - | 0.010 |
| D | 0.189 | 0.193 | 0.197 |
| E1 | 0.150 | 0.154 | 0.157 |
| e | 0.050 BSC |  |  |
| E | 0.228 | 0.236 | 0.244 |
| h | 0.010 | - | 0.020 |
| L | 0.016 | - | 0.050 |
| $\theta$ | $0^{\circ}$ | - | $8^{\circ}$ |

## Notes:

1. All dimensions are in millimeters.
2. Dimensions are inclusive of plating
3. Package body sizes exclude mold flash and gate burrs. Mold flash at the non-lead sides should be less than 6 mils.
4. Dimension $L$ is measured in gauge plane.
5. Controlling dimension is millimeter, converted inch dimensions are not necessarily exact.

## Tape and Reel Dimensions, SO-8

## SO-8 Carrier Tape



Unit: mm

| Package | A0 | B0 | K0 | D0 | D1 | E | E1 | E2 | P0 | P1 | P2 | T |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SO-8 | 6.40 | 5.20 | 2.10 | 1.60 | 1.50 | 12.00 | 1.75 | 5.50 | 8.00 | 4.00 | 2.00 | 0.25 |
| $(12 \mathrm{~mm})$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ |

## SO-8 Reel


$\rightarrow \mid-w$

| Tape Size | Reel Size | $\mathbf{M}$ | $\mathbf{N}$ | $\mathbf{W}$ | $\mathbf{W} 1$ | $\mathbf{H}$ | $\mathbf{K}$ | $\mathbf{S}$ | $\mathbf{G}$ | $\mathbf{R}$ | $\mathbf{V}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 12 mm | $\varnothing 330$ | $\varnothing 330.00$ | $\varnothing 97.00$ | 13.00 | 17.40 | $\varnothing 13.00$ | 10.60 | 2.00 | - | - | - |
|  |  | $\pm 0.50$ | $\pm 0.10$ | $\pm 0.30$ | $\pm 1.00$ | $+0.50 /-0.20$ |  | $\pm 0.50$ |  |  |  |

SO-8 Tape
Leader/Trailer \& Orientation


## Package Dimensions, 5x4A DFN-8



## Notes:

1. Dimensions and tolerancing conform to ASME Y14.5M-1994.
2. All dimensions are in millimeters.
3. The location of the terminal \#1 identifier and terminal numbering convention conforms to JEDEC publication 95 SP-002.
4. Dimension b applies to metallized terminal and is measured between 0.15 mm and 0.30 mm from the terminal tip. If the terminal has the optional radius on the other end of the terminal, the dimension $b$ should not be measured in that radius area.
5. Coplanarity applies to the terminals and all other bottom surface metallization.
6. Drawing shown are for illustration only.
7. The dimensions with * are just for reference
8. Pin \#3 and Pin \#7 are fused to DAP.

## Tape and Reel Dimensions, 5x4A DFN-8

Tape


Feeding Direction

UNIT: mm

| Package | A0 | B0 | K0 | D0 | D1 | E | E1 | E2 | P0 | P1 | P2 | T |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DFN $5 \times 4$ |  |  |  |  |  |  |  |  |  |  |  |  |
| $(12 \mathrm{~mm})$ | 5.30 <br> $\pm 0.10$ | 4.30 | 1.20 | 1.50 |  |  |  |  |  |  |  |  |
| $\pm 0.10$ | $\pm 0.10$ | 1.50 <br> Min. <br> Typ. | $+0.10 /-0$ | 12.00 | 1.75 | 5.50 | 8.00 | 4.00 | 2.00 | 0.30 |  |  |
| $\pm 0.10$ | $\pm 0.10$ | $\pm 0.10$ | $\pm 0.20$ | $\pm 0.10$ | $\pm 0.05$ |  |  |  |  |  |  |  |

## Leader/Trailer and Orientation



## Reel



| Tape Size | Reel Size | $\mathbf{M}$ | W1 | B | P |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 12 mm | $\varnothing 330$ | $\varnothing 330$ <br> +0.3 <br> -4.0 | 12.40 <br> +2.0 <br> -0.0 | 2.40 | 0.5 |
|  |  |  |  |  |  |

$$
\frac{\text { II }}{\text { Zoom ln }}
$$



## Part Marking

AOZ1212AI


## AOZ1212DI



Year \& Week Code

This data sheet contains preliminary data; supplementary data may be published at a later date.
Alpha \& Omega Semiconductor reserves the right to make changes at any time without notice.

## LIFE SUPPORT POLICY

ALPHA \& OMEGA SEMICONDUCTOR PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS.

As used herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body or (b) support or sustain life, and (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury of the user.
2. A critical component in any component of a life support, device, or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

## X-ON Electronics

Largest Supplier of Electrical and Electronic Components
Click to view similar products for Voltage Regulators - Switching Regulators category:
Click to view products by Alpha \& Omega manufacturer:

Other Similar products are found below :
LX7186A 622616F 632259F FAN53610AUC33X MP2148GQD-33-P MP2374DS-LF-Z EN6310QA NCP81108MNTXG NCP81109BMNTXG L79M05TL-E FAN48610BUC45X R3 LV5710GP-TE-L-H 430464BB 455605G AZ7500BMTR-E1 MIC23156-0YML-T5 MIC4930YFL-T5 MP8763GLE-P KE177614 418569H 455596X 511087D 030908C 063375FB 067501FB 099508GB EP5358LUA NCP81102MNTXG 715715H FAN48611UC53X FAN53611AUC12X MAX809TTR MAX77596ETBC+T MAX77596ETBB+T MAX16905AUE/V+ NCP6332CMTAATBG NCV890203MWTXG LX7176A ISL8018IRAJZ MP2162AGQH-Z MAX17544ATP+T MCP1623T-IMC MCP1642B-18IMC MCP1642BT-30I/MS MCP1642D-50IMC MCP1642D-50IMS MCP1642DADJIMC MC34063LBBGEVB MCP1252T-33X50IMS

