



SM-UART-04L Laser Dust Sensor is designed to operate in a moderate environment and provides excellent performance. It's embedded optical design leverages the strength from laser technology, which allows customers to achieve excellent performance with balanced reliability. SM-UART-04L is an ideal solution for industrial and consumer applications.

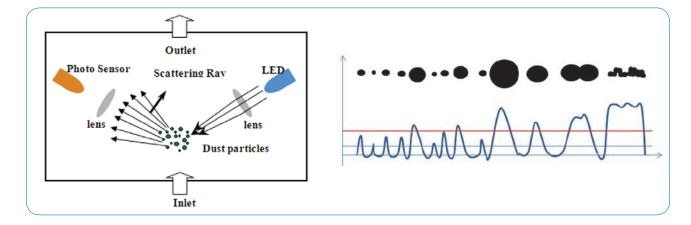
SM-UART-04L laser dust sensor detects dust particle concentration in air by using an optical sensing method. A laser light emitting diode (laser LED) and a photo sensor are optically arranged in the device. The photo sensor detects the reflected laser LED light by dust particles in air. The dust sensor can detect small particles such as, cigarette smoke and distinguish small particles, such as smoke from large house dust, by the pulse pattern of the signal output.

#### **Features**

- Laser Optical Dust
  - High Accuracy
  - Fast Response
- UART Output
- Compact in Size
- Flexible Mounting Style

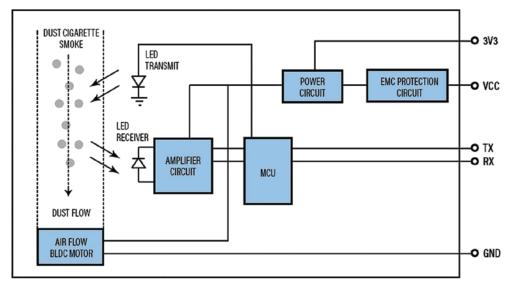
### **Applications**

- Indoor Air Quality Monitoring
- · Air Cleaners and Purifiers
- Air Conditioners and HVAC
- Outdoor Dust Monitoring





## **Block Diagram**



#### **Calibration**

Calibration carried out with cigarette smoke per GB/T1880

## **Absolute Maximum Ratings**

Absolute Maximum Ratings							
Parameter Symbol Rating Unit							
Supply Voltage	Vcc	0 to + 5.5	V				
Operating Temperature	Topr	-10 to 50	°C				
Storage Temperature	Tstg	-30 to 70	°C				
Operating Humidity (1)	RHopr	0 to 95	%				
Storage Humidity (1)	RHstg	0 to 95	%				

<sup>1)</sup> Non-condensing

#### **Electrical Characteristics**

Parameter		Symbol	Min.	Тур.	Max.	Unit
Particle Size	D	0.3	2.5	10	um	
Detection Range	Detection Range		1	_	999	µg/m³
Resolution	Resolution		_	1	_	μg /m³
Indication Funcy (2)	1 ~100 ug/m³	Ъ	_	_	+/-10	μg /m³
Indication Error (2)	100~999 ug/m³	- D <sub>err</sub>	_	_	+/-10	%
Warm-Up Time	t <sub>wup</sub> (2)	_	5	_	S	
Response Time	t <sub>rsp</sub> (2)	_	1	_	s	
Average Trouble-fre	Т	_	40000	_	hour	
Supply Voltage	Supply Voltage		4.8	5	5.2	V
Supply Voltage Rip	V <sub>cc</sub> Ripple	_	_	30	mV	
Current Consumption	I <sub>CC</sub> (2)	_	60	100	mA	
Output (UART)	3.3V					

<sup>1)</sup> Non-condensing

<sup>2)</sup> Testing at T=25°C, RH=40-60%

#### Connector

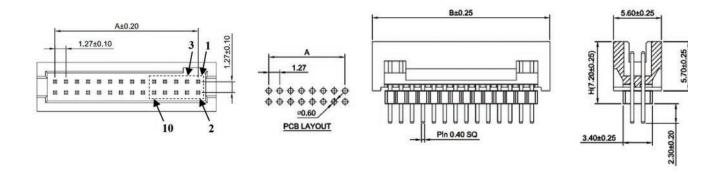
**Sensor Connector:** 

CJT A1276WVA-N-2x5P-H72

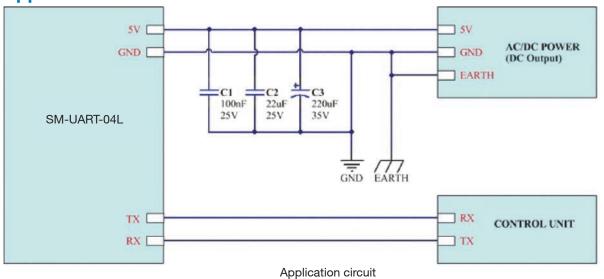
**Equivalent Connector:** 

Harwin, Inc. M50-3000545; Amphenol FCI 20021311-00010T4LF

Pin #	Pin Name	Description	
1	5V	Input Supply Voltage	
2	5V	Input Supply Voltage	
3	GND	Ground	
4	GND	Ground	
5	RESET	Reset Pin @3.3V TTL, Low level reset	
6	NC	-	
7	RXD	UART Receiver @ 3.3V TTL	
8	NC	-	
9	TXD	UART Transceiver @ 3.3V TTL	
10	SET/SLEEP	Working Mode Pin @ 3.3V TTL Floating or high level for normal working condit Low level for dormancy mode.	



## **Application Circuit**



## SM-UART-04L Laser Dust Sensor - Communication Protocol

#### **UART**

UART Serial Configuration					
Baud Rate 9600 bps					
Data Bits	8				
Parity	None				
Stop Bits	1				

## **Default Output UART Frame Format**

		Attitiane i omat				
Head 1	0x42					
Head 2	0x4D					
H_Length		Length = 2 * 13 + 2 (Data+CS)				
L_Length		Length = 2 10 + 2 (Data+00)				
H_D1		PM1 = H_D1 * 256 + L_D1 ug/m3 (Standard Smoke, Calculated Value				
L_D1		TWT = TI_DT 250 + L_DT ug/mo (otalidard officiel, Calculated Value				
H_D2		PM2.5 = H_D2 * 256 + L_D2 ug/m3 (Standard Smoke, Calculated Value)				
L_D2		T W.Z.3 = TI_DZ 230 + L_DZ ug/TI3 (Standard Sittoke, Galculated Value)				
H_D3		PM10 = H_D3 * 256 + L_D3 ug/m3 (Standard Smoke, Calculated Value)				
L_D3		FINITO = H_D3 250 + L_D3 ug/III3 (Standard Silloke, Calculated Value)				
H_D4		DM1 - H D4 * 256 + L D4 ug/m2 (Environment Calculated Value)				
L_D4		PM1 = H_D4 * 256 + L_D4 ug/m3 (Environment, Calculated Value)				
H_D5		DM2.5 _ H_D5 * 256 + L_D5 ug/m2 (Environment, Coloulated Value)				
L_D5		PM2.5 = H_D5 * 256 + L_D5 ug/m3 (Environment, Calculated Value)				
H_D6		DM40 II DC * OFC . I DC/reQ /Free discrepance to Colorada de Voltas				
L_D6		PM10 = H_D6 * 256 + L_D6 ug/m3 (Environment, Calculated Value)				
H_D7						
L_D7						
H_D8						
L_D8						
H_D9						
L_D9						
H_D10						
L_D10						
H_D11						
L_D11						
H_D12						
L_D12						
H_D13		Version number				
L_D13		Error code 0b0ABCDEFG  A = 1 Laser error B = 1 Laser alarm C = 1 High temperature alarm D = 1 Low temperature alarm E = 1 Fan error F = 1 Fan speed compensation start G = 1 Fan speed alarm				
H_CS						
L_CS		CS = HEAD1 + HEAD2 + + L_D13				

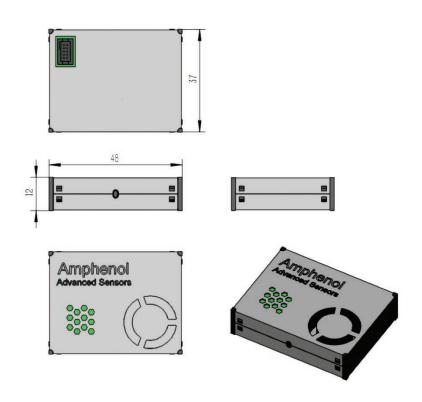
<sup>\*</sup> We recommend the customers use PM values with the standard smoke.

## **Response Mode - Command Frame**

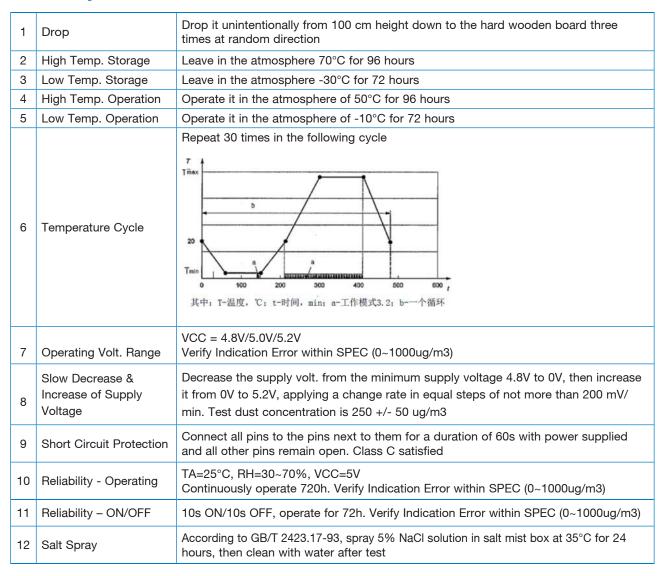
Head 1	Head 2	CMD	D1	D2	CRC1	CRC2
0x42	0x4D	CMD	DATAH	DATAL	LRCH	LRCL

CMD	DATAH	DATAL	Description	Response
0xE2	Х	X	Get reading	Same format as above table
0xE1	х	0x00 – Ask-answer mode 0x01 – Direct output mode	Output mode switch	0x42 0x4D 0x00 0x04 0xE1 0x00 0x01 0x74 0x42 0x4D 0x00 0x04 0xE1 0x01 0x01 0x75
0xE4	Х	0x00 - Standby mode 0x01 - Working mode	Standby control	0x42 0x4D 0x00 0x04 0xE4 0x00 0x01 0x77

### **Dimensions**



### Reliability

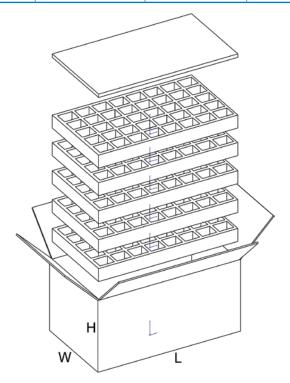


### **Data Consistency**



## **Packing Specifications**

Length (L)	Width (W)	Height (H)	Inner Qty	Total Qty	Weight
418.2mm	295mm	210mm	5 layer	200 pcs	5kg max



## **Application Notes**

## Grounding

The metal case is internally connected to GND. Do not strip the metal case.

#### Maintenance

The product is designed to be maintenance free.

Do not attempt to disassemble the device. There are no user-servicable parts in the module. Disassembly will invalidate warranty.

## Electro-Magnetic (EM) Noise

Excessive electro-magnetic (EM) noise may degrade sensor performance. Shield sensor from EM noise in application.

#### Vibration

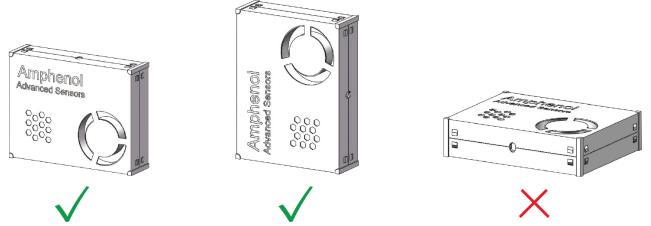
Excessive vibration may degrade sensor's performance. Please keep sensor far from vibration in application.

### **Ambient Light**

Excessive ambient light may degrade sensor performance. Keep sensor far from intense direct light.

## **Mounting Orientation**

Please take sensor mounting orientation into consideration to avoid the influence of adhered dust. The sensor is installed vertically as the best of below:



In addition, please avoid any adhesive particle (fur, oil, etc). If particles adhere to optical part, malfunction may occur.



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