

# 2-/4-/8-Channel, 1 MSPS, Ultralow Power, 12-Bit SAR ADC

# Data Sheet **AD7091R-2/AD7091R-4/AD7091R-8**

### **FEATURES**

**Ultralow system power Flexible power/throughput rate management Normal mode 1.4 mW at 1 MSPS Power-down mode 550 nA typical at V<sub>DD</sub> = 5.25 V 435 nA typical at**  $V_{DD} = 3 V$ **Programmable ALERT interrupt pin (4-/8-channel models) High performance 1 MSPS throughput with no latency/pipeline delay SNR: 70 dB typical at 10 kHz input frequency THD: −80 dB typical at 10 kHz input frequency INL: ±0.7 LSB typical, ±1.0 LSB maximum Small system footprint On-chip accurate 2.5 V reference, 5 ppm/°C typical drift MUXOUT/ADCIN to allow single buffer amplifier Daisy-chain mode 16-lead, 20-lead, and 24-lead 4 mm × 4 mm LFCSP packages 16-lead, 20-lead, and 24-lead TSSOP packages Easy to use SPI/QSPI™/MICROWIRE™/DSP compatible digital interface Integrated programmable channel sequencer BUSY indication available (4-/8-channel models) Built in features for control and monitoring applications GPOx pins available (4-/8-channel models) Wide operating range Temperature range: −40°C to +125°C Specified for V<sub>DD</sub> of 2.7 V to 5.25 V** 

#### **APPLICATIONS**

**Battery-powered systems Personal digital assistants Medical instruments Mobile communications Instrumentation and control systems Data acquisition systems Optical sensors Diagnostic/monitoring functions**

## **FUNCTIONAL BLOCK DIAGRAM**



## **GENERAL DESCRIPTION**

The AD7091R-2/AD7091R-4/AD7091R-8 family is a multichannel 12-bit, ultralow power, successive approximation analog-todigital converter (ADC) that is available in two, four, or eight analog input channel options. The AD7091R-2/AD7091R-4/ AD7091R-8 operate from a single 2.7 V to 5.25 V power supply and are capable of achieving a sampling rate of 1 MSPS.

The AD7091R-2/AD7091R-4/AD7091R-8 family offers up to eight single-ended analog input channels with a channel sequencer that allows a preprogrammed selection of channels to be converted sequentially. The AD7091R-2/AD7091R-4/ AD7091R-8 also feature an on-chip conversion clock, an on-chip accurate 2.5 V reference, and a high speed serial interface.

The AD7091R-2/AD7091R-4/AD7091R-8 have a serial port interface (SPI) that allows data to be read after the conversion while achieving a 1 MSPS throughput rate. The conversion process and data acquisition are controlled using the CONVST pin.

The AD7091R-2/AD7091R-4/AD7091R-8 use advanced design techniques to achieve ultralow power dissipation at high throughput rates. They also feature flexible power management options. An on-chip configuration register allows the user to set up different operating conditions. These include power management, alert functionality, busy indication, channel sequencing, and general-purpose output pins. The  $MUX<sub>OUT</sub>$  and  $ADC<sub>IN</sub>$  pins allow signal conditioning of the multiplexer output prior to acquisition by the ADC.

**Rev. C Document Feedback**

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### **REVISION HISTORY**



### $11/14$ –Rev. A to Rev. B







12/13-Revision 0: Initial Version

# SPECIFICATIONS

 $V_{DD} = 2.7$  V to 5.25 V,  $V_{DRIVE} = 1.8$  V to 5.25 V,  $V_{REF} = 2.5$  V internal reference,  $f_{SAMPLE} = 1$  MSPS,  $f_{SCLK} = 50$  MHz,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.





<sup>1</sup> Multiplexer input voltage should not exceed  $V_{DD}$ .

<sup>2</sup> Sample tested during initial release to ensure compliance.

<sup>3</sup> When referring to a single function of a multifunction pin in the parameters, only the portion of the pin name that is relevant to the specification is listed. For full pin names of multifunction pins, refer to the Pin Configurations and Function Descriptions section.

 $^4$  Device is functional and meets dynamic performance/dc accuracy specifications with V $_{\mathrm{DRVE}}$  down to 1.8 V, but the device is not capable of achieving a throughput of 1 MSPS.

 $^5$  SCLK operates in burst mode, and CS idles high. With a free running SCLK and CS pulled low, the I $_{\text{DD}}$  static current is increased by 30 µA typical at V $_{\text{DD}}$  = 5.25 V.

 $^6$  SCLK operates in burst mode, and CS idles high. With a free running SCLK and CS pulled low, the I<sub>DRIVE</sub> static current is increased by 32 µA typical at V<sub>DRIVE</sub> = 5.25 V. <sup>7</sup> Total power dissipation includes contributions from  $V_{DD}$ ,  $V_{DRIVE}$ , and REF<sub>IN</sub> (see Note 2).

### **TIMING SPECIFICATIONS**

 $V_{DD}$  = 2.7 V to 5.25 V,  $V_{DRIVE}$  = 1.8 V to 5.25 V,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.





Figure 2. Load Circuit for Digital Interface Timing Figure 3. Voltage Levels for Timing Figure 3. Voltage Levels for Timing



**NOTES**

 $1$ FOR  $V_{DRIVE}$  ≤ 3.0V, X = 90 AND Y = 10; FOR  $V_{DRIVE}$  > 3.0V, X = 70 AND Y = 30. **2MINIMUM VIH AND MAXIMUM VIL USED. SEE SPECIFICATIONS FOR DIGITAL INPUTS PARAMETER IN TABLE 2.** 10891-139 **V<sub>DRIVE</sub> ≤ 3.0V, X = 90 AND Y = 10; FOR V<sub>DRIVE</sub>** 

## **Timing Diagram**



Figure 4. Serial Port Timing

# ABSOLUTE MAXIMUM RATINGS

 $T_A = 25$ °C, unless otherwise noted.

#### **Table 3.**



<sup>1</sup> The digital input pins include the following: RESET, CONVST, SDI, SCLK, and CS.

<sup>2</sup> The digital output pins include the following: SDO, GPO<sub>1</sub>, and ALERT/BUSY/GPO<sub>0</sub>.

<sup>3</sup> Transient currents of up to 100 mA do not cause SCR latch-up.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **THERMAL RESISTANCE**

 $\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

#### **Table 4. Thermal Resistance**



#### **ESD CAUTION**



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS









#### **Table 6. 4-Channel, 20-Lead LFCSP and 20-Lead TSSOP Pin Function Descriptions**









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10891-004

#### **Table 7. 8-Channel, 24-Lead LFCSP and 24-Lead TSSOP Pin Function Descriptions**





# TYPICAL PERFORMANCE CHARACTERISTICS



Figure 11. Integral Nonlinearity vs. Code



Figure 12. Histogram of a DC Input at Code Center







Figure 14. Differential Nonlinearity vs. Code



Figure 15. Histogram of a DC Input at Code Transition



Figure 16. 10 kHz FFT,  $V_{DD} = 3.0$  V, VREF = 2.5 V Internal



Figure 17. SNR vs. Analog Input Frequency for Various Supply Voltages



Figure 18. SINAD vs. Analog Input Frequency for Various Supply Voltages



Figure 19. SNR, SINAD, and ENOB vs. Reference Voltage



Figure 20. THD vs. Analog Input Frequency for Various Supply Voltages











Figure 25. Operating Current vs. Throughput



Figure 26. Operational I<sub>DD</sub> Supply Current vs. Temperature for Various  $V_{DD}$  Supply Voltages



Figure 27. Operational I<sub>DRIVE</sub> Supply Current vs. Temperature for Various V<sub>DRIVE</sub> Supply Voltages



Figure 28. Total Power-Down Current vs. Temperature for Various Supplies



Figure 29. t<sub>DSDO</sub> Delay vs. SDO Capacitance Load and Supply







Figure 31. Offset Error Match vs. Temperature



Figure 32. PSRR vs. Ripple Frequency







Figure 34. Gain Error Match vs. Temperature



Figure 35. Channel-to-Channel Isolation vs. Input Frequency











Figure 39. Internal Reference Voltage vs. Temperature

# **TERMINOLOGY**

### **Integral Nonlinearity (INL)**

INL is the maximum deviation from a straight line passing through the endpoints of the ADC transfer function. For the AD7091R-2/AD7091R-4/AD7091R-8, the endpoints of the transfer function are zero scale, a point ½ LSB below the first code transition, and full scale, a point ½ LSB above the last code transition.

### **Differential Nonlinearity (DNL)**

DNL is the difference between the measured and the ideal 1 LSB change between any two adjacent codes in the ADC.

#### **Offset Error**

The offset error is the deviation of the first code transition (00 … 000 to 00 … 001) from the ideal (such as GND + 0.5 LSB).

#### **Offset Error Match**

Offset error match is the difference in offset error between any two input channels.

#### **Gain Error**

For the AD7091R-2/AD7091R-4/AD7091R-8, the gain error is the deviation of the last code transition (111 … 110 to 111 … 111) from the ideal (such as  $V_{REF}$  – 1.5 LSB) after the offset error has been adjusted out.

#### **Gain Error Match**

Gain error match is the difference in gain error between any two input channels.

#### **Transient Response Time**

The track-and-hold amplifier returns to track mode after the end of conversion. The track-and-hold acquisition time is the time required for the output of the track-and-hold amplifier to reach its final value, within ±0.5 LSB, after the end of conversion. See the Serial Port Interface section for more details.

#### **Signal-to-Noise-and-Distortion (SINAD) Ratio**

SINAD is the measured ratio of signal-to-noise-and-distortion at the output of the ADC. The signal is the rms amplitude of the fundamental. Noise is the sum of all nonfundamental signals up to half the sampling frequency  $(f_s/2)$ , excluding dc.

The ratio is dependent on the number of quantization levels in the digitization process; the more levels, the smaller the quantization noise. The theoretical SINAD ratio for an ideal N-bit converter with a sine wave input is given by

 $SINAD = (6.02N + 1.76)$  dB

Thus, for a 12-bit converter, the SINAD ratio is 74 dB.

#### **Channel-to-Channel Isolation**

Channel-to-channel isolation is a measure of the level of crosstalk between the selected channel and all of the other channels. It is measured by applying a full-scale, 10 kHz sine wave signal to all unselected input channels and determining the degree to which the signal attenuates in the selected channel that has a dc signal applied to it. Figure 35 shows the worst case across all channels for the AD7091R-2/AD7091R-4/AD7091R-8.

#### **Total Harmonic Distortion (THD)**

THD is the ratio of the rms sum of harmonics to the fundamental. For the AD7091R-2/AD7091R-4/AD7091R-8, it is defined as

$$
THD(dB) = 20 \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2 + V_6^2}}{V_1}
$$

where:

*V*<sup>1</sup> is the rms amplitude of the fundamental. *V*2, *V*3, *V*4, *V*5, and *V*<sup>6</sup> are the rms amplitudes of the second through the sixth harmonic.

#### **Spurious-Free Dynamic Range (SFDR)**

SFDR is the difference, in decibels, between the rms amplitude of the input signal and the peak spurious signal.

## THEORY OF OPERATION **CIRCUIT INFORMATION**

The AD7091R-2/AD7091R-4/AD7091R-8 are 12-bit, fast (1 MSPS), ultralow power, single-supply ADCs. The devices operate from a 2.7 V to 5.25 V supply. The AD7091R-2/ AD7091R-4/AD7091R-8 are capable of throughput rates of 1 MSPS.

The AD7091R-2/AD7091R-4/AD7091R-8 provide an on-chip, track-and-hold ADC and a serial interface housed in a 16-lead, 20-lead, or 24-lead TSSOP or LFCSP package, which offers considerable space-saving advantages over alternative solutions. The serial clock input accesses data from the device. The clock for the successive approximation ADC is generated internally. The reference voltage for the AD7091R-2/AD7091R-4/AD7091R-8 is provided externally, or it is generated internally by an accurate on-chip reference source. The analog input range for the AD7091R-2/AD7091R-4/AD7091R-8 is 0 V to VREF.

The AD7091R-2/AD7091R-4/AD7091R-8 also feature a powerdown option to save power between conversions. The power-down feature is implemented across the standard serial interface as described in the Modes of Operation section.

### **CONVERTER OPERATION**

The AD7091R-2/AD7091R-4/AD7091R-8 are successive approximation ADCs based on a charge redistribution digitalto-analog converter (DAC). Figure 40 and Figure 41 show simplified schematics of the ADC. Figure 40 shows the ADC during its acquisition phase. When SW2 is closed and SW1 is in Position A, the comparator is held in a balanced condition, and the sampling capacitor acquires the signal on  $V_{\text{IN}}$ .





Figure 41. ADC Conversion Phase

When the ADC starts a conversion, SW2 opens and SW1 moves to Position B, causing the comparator to become unbalanced (see Figure 41). Using the control logic, the charge redistribution DAC adds and subtracts fixed amounts of charge from the sampling capacitor to bring the comparator back into a balanced condition. When the SAR decisions are made, the comparator inputs are rebalanced. From these SAR decisions, the control logic generates the ADC output code.

### **ADC TRANSFER FUNCTION**

The output coding of the AD7091R-2/AD7091R-4/AD7091R-8 is straight binary. The designed code transitions occur midway between successive integer LSB values, such as ½ LSB, 1½ LSB, and so on. The LSB size for the AD7091R-2/AD7091R-4/AD7091R-8 is V<sub>REF</sub>/4096. The ideal transfer characteristic for the AD7091R-2/ AD7091R-4/AD7091R-8 is shown in Figure 42.



Figure 42. AD7091R-2/AD7091R-4/AD7091R-8 Transfer Characteristic

### **REFERENCE**

The AD7091R-2/AD7091R-4/AD7091R-8 can operate with either the internal 2.5 V on-chip reference or an externally applied reference. The logic state of the P\_DOWN LSB bit in the configuration register determines whether the internal reference is used. The internal reference is selected for the ADCs when the P\_DOWN LSB bit is set to 1.

When the P\_DOWN LSB bit is set to 0, supply an external reference in the range of 1.0 V to  $V_{DD}$  through the  $REF_{IN}/REF_{OUT}$ pin. At power-up, the internal reference disables by default.

The internal reference circuitry consists of a 2.5 V band gap reference and a reference buffer. When operating the AD7091R-2/ AD7091R-4/AD7091R-8 in internal reference mode, the 2.5 V internal reference is available at the REF<sub>IN</sub>/REF<sub>OUT</sub> pin, which is typically decoupled to GND using a 2.2 μF capacitor. It is recommended to buffer the internal reference before applying it elsewhere in the system.

The reference buffer requires 50 ms to power up and charge the 2.2 μF decoupling capacitor during the power-up time.

### **POWER SUPPLY**

The AD7091R-2/AD7091R-4/AD7091R-8 use two power supply pins: a core supply  $(V_{DD})$  and a digital input/output interface supply (V<sub>DRIVE</sub>). V<sub>DRIVE</sub> allows direct interface with any logic between 1.8 V and 5.25 V. To reduce the number of supplies needed, VDRIVE and VDD can be tied together depending upon the logic levels of the system. Additionally, the AD7091R-2/ AD7091R-4/AD7091R-8 are insensitive to power supply variation over a wide frequency range, as shown in Figure 32. AD7091R-2/ AD7091R-4/AD7091R-8 operation is independent of power supply sequencing between V<sub>DRIVE</sub> and V<sub>DD</sub>.

The AD7091R-2/AD7091R-4/AD7091R-8 power down automatically at the end of each conversion phase; therefore, the power scales linearly with the sampling rate. The automatic power-down feature makes the AD7091R-2/AD7091R-4/ AD7091R-8 devices ideal for low sampling rates (of even a few hertz) and battery-powered applications.

**Table 8. Recommended Power Management Devices1**

<b>Product</b> Description
ADP7102 20 V, 300 mA, low noise, CMOS LDO
ADM7160 Ultralow noise, 200 mA linear regulator
ADP162   Ultralow quiescent current, CMOS linear regulator

<sup>1</sup> For the latest recommended power management devices, see the AD7091R-2/ AD7091R-4/AD7091R-8 product pages.

### **DEVICE RESET**

Upon power up, a reset pulse of at least 10 ns in width must be provided on the RESET pin to ensure proper initialization of the device. Failure to apply the reset pulse may result in a device malfunction. See Figure 43 for reset pulse timing relative to power supply establishment. If the system has a limited number of digital pins and one cannot be allocated to the reset pin of the ADC, a software reset may be issued in place of the hardware reset signal (see the Power-On Device Initialization section).



### **TYPICAL CONNECTION DIAGRAM**

#### Figure 45 shows a typical connection diagram for the AD7091R-2/ AD7091R-4/AD7091R-8.

Connect a positive power supply in the 2.7 V to 5.25 V range to the  $V_{DD}$  pin. Typical values for these decoupling capacitors are 0.1 μF and 10 μF. Place these capacitors near the device pins. Take care to decouple the REF<sub>IN</sub>/REF<sub>OUT</sub> pin to achieve specified performance. The typical value for the REFIN/REFOUT capacitor is 2.2  $\mu$ F, which provides an analog input range of 0 V to VREF.

The typical value for the regulator bypass (REGCAP) decoupling capacitor is 1.0  $\mu$ F. The voltage applied to the VDRIVE input controls the voltage of the serial interface; therefore, connect this pin to the supply voltage of the microprocessor. Set VDRIVE in the 1.8 V to 5.25 V range. Typical values for the  $V_{DRIVE}$ decoupling capacitors are 0.1 μF and 10 μF. The conversion result is output in a 16-bit word with the MSBs first.

When an externally applied reference is required, disable the internal reference using the configuration register. Choose the externally applied reference voltage in the 1.0 V to 5.25 V  $V_{DD}$ range and connect it to the REF<sub>IN</sub>/REF<sub>OUT</sub> pin.

For applications where power consumption is a concern, use the power-down mode of the ADC to improve power performance. See the Modes of Operation section for additional details.

### **ANALOG INPUT**

Figure 44 shows an equivalent circuit of the analog input structure of the AD7091R-2/AD7091R-4/AD7091R-8. The two diodes, D1 and D2, provide ESD protection for the analog input. Take care to ensure that the analog input signal never exceeds the supply rails by more than 300 mV because this causes these diodes to become forward-biased and start conducting current into the substrate. These diodes can conduct a maximum of 10 mA without causing irreversible damage to the device.



The C1 capacitor in Figure 44 is typically about 400 fF and can primarily be attributed to pin capacitance. The R1 resistor is a lumped component composed of the on resistance of a switch. This resistor is typically about 500  $\Omega$ . The C2 capacitor is the ADC sampling capacitor and typically has a capacitance of 3.6 pF.

In applications where harmonic distortion and signal-to-noise ratio are critical, drive the analog inputs from low impedance sources. Large source impedances significantly affect the ac performance of the ADC that can necessitate using input buffer amplifiers, as shown in Figure 45. The choice of the op amp is a function of the particular application.

When no amplifiers are used to drive the analog input, limit the source impedance to low values. The maximum source impedance depends on the amount of THD that can be tolerated. The THD increases as the source impedance increases and performance degrades.

Use an external filter on the analog input signal paths to the AD7091R-2/AD7091R-4/AD7091R-8  $V_{IN}x$  pins to achieve the specified performance. This filter can be a one-pole low-pass RC filter, or similar.

Connect the MUX<sub>OUT</sub> pin directly to the ADC<sub>IN</sub> pin. Insert a buffer amplifier in the path, if desired. When sequencing channels, do not place a filter between MUX<sub>OUT</sub> and the input to any buffering because doing so leads to crosstalk. If buffering is not employed, do not place a filter between  $MUX<sub>OUT</sub>$  and  $ADC<sub>IN</sub>$ when sequencing channels because doing so leads to crosstalk.

### **DRIVER AMPLIFIER CHOICE**

Although the AD7091R-2/AD7091R-4/AD7091R-8 are easy to drive, a driver amplifier must meet the following requirements:

The noise generated by the driver amplifier must be kept as low as possible to preserve the SNR and transition noise performance of the AD7091R-2/AD7091R-4/AD7091R-8. The noise from the driver is filtered by the one-pole, lowpass filter of the AD7091R-2/AD7091R-4/AD7091R-8 analog input circuit, made by R1 and C2, or by the external filter, if one is used. Because the typical noise of the AD7091R-2/AD7091R-4/AD7091R-8 is 280 µV rms, the SNR degradation due to the amplifier is

$$
SNR_{Loss} = 20 \log \left( \frac{280}{\sqrt{280^2 + \frac{\pi}{2} f_{-3dB} (Ne_N)^2}} \right)
$$

where:

*f−3dB* is the input bandwidth, in megahertz, of the AD7091R-2/ AD7091R-4/AD7091R-8 (1.5 MHz), or the cutoff frequency of the input filter, if one is used.

*N* is the noise gain of the amplifier (for example, gain = 1) in buffer configuration; see Figure 45).

*eN* is the equivalent input noise voltage of the op amp, in  $nV/\sqrt{Hz}$ .

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- For ac applications, the driver must have a THD performance that is commensurate with the AD7091R-2/ AD7091R-4/AD7091R-8.
- If the buffer is placed between  $MUX<sub>OUT</sub>$  and  $ADC<sub>IN</sub>$ , the driver amplifier and the AD7091R-2/AD7091R-4/AD7091R-8 analog input circuit must settle for a full-scale step onto the capacitor array at a 12-bit level (0.0244%, 244 ppm). In an amplifier data sheet, settling at 0.1% to 0.01% is more commonly specified and may differ significantly from the settling time at a 12-bit level. Be sure to verify the amplifier settling time prior to driver selection.

#### **Table 9. Recommended Driver Amplifiers1**



<sup>1</sup> For the latest recommended ADC driver products, see the AD7091R-2/ AD7091R-4/AD7091R-8 product pages.



Figure 46. Typical Connection Diagram Without Optional Buffer **NOTES 1THIS PIN IS FOR THE AD7091R-4/AD7091R-8.**

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# **REGISTERS**

### The AD7091R-2/AD7091R-4/AD7091R-8 have user

programmable registers. Table 10 contains the complete list of registers.

The registers are either read/write (R/W) or read only (R). Data is written to or read back from the read/write registers. Read only registers is only read. Any write to a read only register or unimplemented register address is considered no operation (NOP). A NOP command is an SPI command that is ignored by the AD7091R-2/AD7091R-4/AD7091R-8. After a write to a read only register, the output on the subsequent SPI frame is all zeros if there was no conversion before the next SPI frame. Similarly, any read of an unimplemented register outputs zeros.

### **ADDRESSING REGISTERS**

A serial transfer on the AD7091R-2/AD7091R-4/AD7091R-8 consists of 16 SCLK cycles. The six MSBs on the SDI line during the 16 SCLK transfer are decoded to determine which register is addressed. The six MSBs consist of the register address (ADDx), Bits[4:0], and the read/write bit. The register address bits determine which of the on-chip registers are selected. The read/write bit determines if the data on the SDI line following the read/write bit loads into the addressed register. If the read/write bit is 1, the bits load into the register addressed by the register select bits. Data loads into the register on the rising edge of CS. If the read/write bit is 0, the command is seen as a read request. The requested register data is available on the subsequent message on the SDO line.

#### **Table 10. Register Description**



### **CONVERSION RESULT REGISTER**

The conversion result register is a 16-bit, read only register that stores the results from the most recent ADC conversion in straight binary format. The channel ID of the converted channel and the alert status are also included in the register.



#### *Figure 47. Conversion Result Register*

#### **Table 11. Conversion Result Register Map**



#### **Table 12. Bit Descriptions for the Conversion Result Register**



<sup>1</sup> Always zero on the AD7091R-4.

<sup>2</sup> Always zero on the AD7091R-2.

### **CHANNEL REGISTER**

The channel register on the AD7091R-2/AD7091R-4/AD7091R-8 is an 8-bit, read/write register. Each of the eight analog input channels has one corresponding bit in the channel register. To select a channel for inclusion in the channel conversion sequence, set the corresponding channel bit to 1 in the channel register. There is a latency of one conversion before the channel conversion sequence is updated. If the channel register is programmed with a new value, the conversion sequence is reset to the lowest numbered channel in the new value.



*Figure 48. Channel Registers*

**Table 13. Channel Register Map**



#### **Table 14. Bit Descriptions for the Channel Register**



### **CONFIGURATION REGISTER**

The configuration register is a 16-bit, read/write register that is used to set the operating modes of the AD7091R-2/AD7091R-4/AD7091R-8.





#### **Table 15. Configuration Register Map**



#### **Table 16. Bit Descriptions for the Configuration Register**





<sup>1</sup> When referring to a single function of a multifunction pin in the parameters, only the portion of the pin name that is relevant to the specification is listed. For full pin names of multifunction pins, refer to the Pin Configurations and Function Descriptions section.

### **ALERT INDICATION REGISTER**

The 16-bit, alert indication register is a read only register that provides information on an alert event. If a conversion result activates the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin, as described in the Channel x Low Limit Register section and the Channel x High Limit Register section, the alert register can be read to determine the source of the alert. The register contains two status bits per channel, one corresponding to the high limit, and the other to the low limit. The bit with a status equal to 1 shows where the violation occurred, that is, on which channel, and whether the violation occurred on the upper or lower limit.

If a second alert event occurs on another channel between receiving the first alert and interrogating the alert register, the corresponding bit for that alert event is also set.

The contents of the alert indication register are reset by reading it. The alert indication register is reset on the second SCLK cycle of the SPI frame where the ALERT data is read out. If a conversion happens in the meantime, the conversion result is sent instead of the alert indication register contents. The alert indication register is not reset in this case.

The alert bits for any unimplemented channels on the 2-channel and 4-channel devices always return zeros.



Figure 50. Alert Indication Register (Figure Shows Default Register Value of 0, Indicating No Alert Has Occurred)

#### **Table 17. Alert Indication Register Map**



#### **Table 18. Bit Descriptions for the Alert Indication Register**





### **CHANNEL x LOW LIMIT REGISTER**

Each analog input channel of the AD7091R-2/AD7091R-4/ AD7091R-8 has its own low limit register. The low limit registers are 16-bit read/write registers. See Table 10 for the register addresses. The low limit registers store the lower limit of the conversion value that activates the ALERT output.

Of the 16 bits, B15 to B9 are not used. Only the nine LSBs, B8 to B0, are used. These 9 bits, which are programmed by the user, are used as the MSBs of the internal 12-bit register. The 3 LSBs in the internal 12-bit registers are set to 000.

### **CHANNEL x HIGH LIMIT REGISTER**

Each analog input channel of the AD7091R-2/AD7091R-4/ AD7091R-8 has its own high limit register. The high limit registers are 16-bit read/write registers. See Table 10 for the register addresses. The high limit registers store the upper limit of the conversion value that activates the ALERT output.

Of the 16 bits, B15 to B9 are not used. Only the nine LSBs, B8 to B0, are used. These 9 bits, which are programmed by the user, are used as the MSBs of the internal 12-bit register. The 3 LSBs in the internal 12-bit registers are set to 111.

### **CHANNEL x HYSTERESIS REGISTER**

Each analog input channel of the AD7091R-2/AD7091R-4/ AD7091R-8 has its own hysteresis register, which are 16-bit read/write registers. See Table 10 for the register addresses. The hysteresis register stores the hysteresis value (N) when using the limit registers. The hysteresis value determines the reset point for the ALERT/BUSY/GPO<sub>0</sub> pin if a violation of the limits has occurred.

Of the 16 bits, B15 to B9 are not used. Only the nine LSBs, B8 to B0, are used. These 9 bits, which are programmed by the user, are used as the MSBs of the internal 12-bit register. The 3 LSBs in the internal 12-bit registers are set to 000.

### **Table 19. Channel x Low Limit Register Map**



#### **Table 20. Bit Descriptions for the Channel x Low Limit Register**



## **Table 21. Channel x High Limit Register Map**



#### **Table 22. Bit Descriptions for the Channel x High Limit Register**



#### **Table 23. Channel x Hysteresis Register Map**



#### **Table 24. Bit Descriptions for the Channel x Hysteresis Register**



# SERIAL PORT INTERFACE

The SPI is a 4-wire interface (three inputs and one output) for serial data communication. It has a chip select (CS) line, a serial clock (SCLK), a serial data input (SDI), and a serial data output (SDO). Data transfers on SDI and SDO take place with respect to SCLK.  $\overline{\text{CS}}$  is used to frame the data and is active low. When  $\overline{CS}$  is high, SDO is kept in high impedance. The falling edge of  $\overline{CS}$  takes the SDO line out of the high impedance state. A rising edge on  $\overline{CS}$  returns the SDO to a high impedance state.

The SPI implemented on the AD7091R-2/AD7091R-4/AD7091R-8 can support both of the following: CPHA and CPOL = 0, and CPHA and CPOL = 1. This support ensures that the device can interface to microcontrollers and DSPs that keep either SCLK high or SCLK low when  $\overline{CS}$  is not asserted. The device ignores SCLK toggling when  $\overline{CS}$  is not asserted.

### **READING CONVERSION RESULT**

The CONVST signal is used to initiate the conversion process. A high-to-low transition on the CONVST signal puts the trackand-hold into hold mode and samples the analog input at this point. A conversion is initiated and requires 600 ns to complete. Before the end of the conversion, take the CONVST signal high again. When the conversion process is finished, the track-andhold mode goes back into track mode. Then, take the CS pin low, and the conversion result clocks out on the SDO pin. The data is shifted out of the device as a 16-bit word under the control of the serial clock (SCLK) input. The data is shifted out on the falling edge of SCLK, and the data bits are valid on both the rising edge and the falling edge. The MSB is shifted out on the falling edge of CS. The final bit in the data transfer is valid



on the 16th rising edge and the 16th falling edge, having clocked out on the previous (15th) falling edge. After the 16th falling edge, take CS high again to return the SDO to a high impedance state. If another conversion is required, take the CONVST pin low again (after at least 1 μs), and repeat the read cycle. The timing diagram for this operation is shown in Figure 52.

### **WRITING DATA TO THE REGISTERS**

All the read/write registers in the device can be written over the SPI. A register write command is performed by a single 16-bit SPI access. The format for a write command is shown in Table 25. Bits[B15:B11] contain the register address. See Table 10 for the complete list of register addresses. Setting Bit B10 to 1 selects a write command. The subsequent 10 bits (Bits[B9:B0]) contain the data to be written to the selected register.

### **READING DATA FROM THE REGISTERS**

All the registers in the device can be read over the SPI. A register read is performed by issuing a register read command followed by an additional SPI command that can be either a valid command or NOP. The format for a read command is shown in Table 26. Bits[B15:B11] contain the register address. See Table 10 for the complete list of register addresses. Setting Bit B10 to 0 selects a read command. The device ignores the subsequent bits (Bits[B9:B0]).

Any conversion event is treated as a special case and overrides a previous read command. The AD7091R-2/AD7091R-4/ AD7091R-8 always drive out the conversion result register on SDO after a conversion even though a register read was initiated in the previous SPI frame.



#### **Table 26. Read Command Message Configuration MSB LSB B15 B14 B13 B12 B11 B10 B9 B8 B7 B6 B5 B4 B3 B2 B1 B0**  Register Address[4:0] 0 Don't Care **CONVST CS SDI READ REG 1 READ REG 2 READ REG 3** 10891-025 10891-025**CONV RES REG 1 DATA REG 2 DATA SDO**

Figure 52. Serial Interface Register Read

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### **POWER-ON DEVICE INITIALIZATION**

In lieu of applying a pulse to the  $\overline{\text{RESET}}$  pin from the digital host at initial power up, it is possible to replicate the behavior of the hardware reset function through the application of an alternative stimulus to the CONVST pin. Once the internal regulator voltage has been established by V<sub>DD</sub> reaching a voltage of 2.1 V, a series of CONVST pulses must be sent to the ADC. Following the subsequent procedure will reset the device, allowing for proper and expected operation.

To issue a software initialization,

- 1. Establish the V<sub>DD</sub> and V<sub>DRIVE</sub> supplies for the AD7091R-2/ AD7091R-4/ AD7091R-8. The power-on time will depend upon the supply pin decoupling load and drive strength of the supply resource.
- 2. Provide 66 pulses on the  $\overline{CONVST}$  pin that are spaced a minimum of 2 μs apart. The pulse width on the CONVST pin must adhere to the t<sub>CNVPW</sub> timing specification.
- 3. At the end of the  $66<sup>th</sup>$  pulse, the ADC is initialized and in a ready state. The device can now be configured by the user.
- 4. At this point, all internal registers will be in an unknown state. Write the desired device configuration as described in the Writing Data to the Registers section. To place all write enabled internal registers in a known state, writing to all device registers is required.
- 5. Reset the read-only registers by activating the software reset bit of the Configuration Register when performing the write actions described in Step 4. See details in the Configuration Register section.

If using the on-chip internal reference, to meet specified performance, the user should wait until the reference capacitor is fully charged. The reference buffer requires 50 ms to power up and charge the 2.2 μF decoupling capacitor during the power-up time.

In digital pin limited applications, the RESET pin of the AD7091R-2/AD7091R-4/AD7091R-8 should be tied to the VDRIVE supply either directly or via a pull-up resistor.

Figure 53 shows the timing diagram for this operation.



## MODES OF OPERATION **NORMAL MODE**

The user controls whether the device remains in normal mode or enters power-down mode. These modes of operation provide flexible power management options, allowing optimization of the power dissipation and throughput rate ratio for different application requirements.

To achieve the fastest throughput rate performance, use normal mode. Power-up times are not an issue for the AD7091R-2/ AD7091R-4/AD7091R-8 because they remain fully powered at all times. Figure 54 shows the general diagram of the AD7091R-2/ AD7091R-4/AD7091R-8 in normal mode. The conversion initiates on the falling edge of CONVST, as described in the Serial Port Interface section. To ensure that the device remains fully powered up at all times, return CONVST high before tCONVERT and keep it high until the conversion has finished. The end of conversion (EOC) point shown in Figure 54 indicates the end of EOC and the moment when the logic level of CONVST is tested.

To read back data stored in the conversion result register, wait until the conversion is completed. Then, take CS low, and the conversion data clocks out on the SDO pin. The output shift register is 16 bits wide. Data is shifted out of the device as a 16-bit word under the control of the serial clock (SCLK) input. The full timing diagram for this operation is shown in Figure 4. When the conversion read is completed, pull CONVST low again to start another conversion.

### **POWER-DOWN MODE**

When slower throughput rates and lower power consumption are required, use power-down mode by either powering down the ADC between each conversion or by performing a series of conversions at a high throughput rate and then powering down the ADC for a relatively long duration between these burst conversions. When the AD7091R-2/AD7091R-4/AD7091R-8 are in power-down mode, all analog circuitry power down; however, the serial interface is active.

To enter power-down mode, write to the power-down configuration bits in the configuration register, as seen in Table 15. To enter full power-down mode, set the sleep mode/bias generator bit to 1, and set the internal reference bit to 0, which ensures that all analog circuitry and the internal reference power down. When the internal reference is enabled, it consumes power anytime Bit 0 of the configuration register is set to 1.

The serial interface of the AD7091R-2/AD7091R-4/AD7091R-8 is functional in power-down; therefore, the user can read back the results of the conversion after the device enters power-down mode.

To exit this mode of operation and to power up the AD7091R-2/ AD7091R-4/AD7091R-8 again, write to the power-down configuration bits in the configuration register (see Table 15). On the rising edge of CONVST, the device begins to power up. The power-up time of the AD7091R-2/AD7091R-4/AD7091R-8 is typically 1 μs. After power-up is complete, the ADC is fully powered up, and the input signal is properly acquired. To start the next conversion, operate the interface as described in the Normal Mode section. When using the internal reference, and the device is in full power-down mode, the user must wait to perform conversions until the internal reference has had time to power up and settle. The reference buffer requires 50 ms to power up and charge the 2.2 μF decoupling capacitor during the power-up time.

By using the power-down mode on the AD7091R-2/AD7091R-4/ AD7091R-8 when this device is not converting, the average power consumption of the ADC decreases at lower throughput rates. Use power-down mode with lower throughput rates. When there is not a significant time interval between bursts of conversions, use normal mode (see the Normal Mode section).



Figure 54. Serial Interface Read Timing in Normal Mode

### **ALERT (AD7091R-4 AND AD7091R-8 ONLY)**

The alert functionality is used as an out-of-range indicator. An alert event is triggered when the value in the conversion result register exceeds the CHx HIGH LIMIT value in the channel high limit register or falls below the CHx LOW LIMIT value in the channel low limit register for a selected channel.

Detailed alert information is accessible in the alert register. The register contains two status bits per channel, one corresponding to the high limit, and the other to the low limit. A logical OR of alert signals for all channels creates a common alert value. This value can be accessed by the alert bit in the conversion result register and configured to drive out on the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin. The ALERT/BUSY/GPO<sub>0</sub> pin is configured as ALERT by configuring the following bits in the configuration register:

- Set the ALERT\_EN\_OR\_GPO0 bit, Bit 4, to 1.
- Set the BUSY bit, Bit 5, to 0.
- Set the ALERT\_POL\_OR\_GPO0 bit, Bit 3, to 0 for the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin to be active low, and set it to 1 for the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin to be active high.

The alert register, alert bit, and the ALERT function of the  $ALERT/BUSY/GPO<sub>0</sub>$  pin are cleared by reading the alert register contents. Additionally, if the conversion result goes beyond the hysteresis value for a selected channel, the alert bit corresponding to that channel is reset automatically. The automatic clearing of the alert status can be disabled by setting the ALERT\_STICKY bit in the configuration register to 1. If the ALERT\_STICKY bit is set when an alert occurs, it can only be reset by a read of the alert register. Issuing a software reset also clears the alert status.

The  $ALERT/BUSY/GPO<sub>0</sub>$  pin has an open-drain configuration that allows the alert outputs of several AD7091R-4/AD7091R-8 devices to be wired together when the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin is active low. The ALERT\_DRIVE\_TYPE bit (Bit 6) of the configuration register controls the ALERT/ BUSY/GPO<sub>0</sub> pin configuration.

Use the ALERT\_POL\_OR\_GPO0 bit (Bit 3) of the configuration register to set the active polarity of the alert output. The power-up default is active low.

When using the ALERT function of the ALERT/BUSY/GPO $_0$ pin and the open-drain configuration, an external pull-up resistor is required. Connect the external pull-up resistor to VDRIVE. The resistor value is application dependent; however, it must be large enough to avoid excessive sink currents when the ALERT function of the ALERT/BUSY/GPO<sub>0</sub> pin is triggered.

### **BUSY (AD7091R-4 AND AD7091R-8 ONLY)**

When configuring the ALERT/BUSY/GPO<sub>0</sub> pin as a BUSY output, use the pin to indicate when a conversion is taking place. To configure the  $ALERT/BUSY/GPO<sub>0</sub>$  pin as BUSY, use the following bits in the configuration register:

- Set the ALERT\_EN\_OR\_GPO0 bit, Bit 4, to 1.
- Set the BUSY bit, Bit 5, to 1.
- Set the ALERT\_POL\_OR\_GPO0 bit, Bit 3, to 0 for the BUSY pin to be active low, and set it to 1 for the BUSY pin to be active high.

When using the BUSY function of the ALERT/BUSY/GPO<sub>0</sub> pin, an external pull-up resistor is required because the output is an open-drain configuration. Connect the external pull-up resistor to V<sub>DRIVE</sub>. The resistor value is application dependent; however, it must be large enough to avoid excessive sink currents when the BUSY function of the ALERT/BUSY/GPO<sub>0</sub> pin is triggered.

### **CHANNEL SEQUENCER**

The AD7091R-2/AD7091R-4/AD7091R-8 include a channel sequencer that is useful for scanning channels in a repeated fashion. Channels included in the sequence are configured in the channel register. If all the bits in the channel register are 0, Channel 0 is selected by default, and all conversions happen on this channel. If the channel register is nonzero, the conversion sequence starts from the lowest numbered channel enabled in

the channel register. The sequence cycles through all the enabled channels in ascending order. After all the channels in the sequence are converted, the sequence starts again.

There is a latency of one conversion before the channel conversion sequence is updated. If the channel register is programmed with a new value, the conversion sequence is reset to the lowest numbered channel in the new value.



Figure 56. Channel Sequencer Multiple Channel Write

### **DAISY CHAIN**

Daisy-chain mode is intended for applications where multiple AD7091R-2/AD7091R-4/AD7091R-8 devices are used. This feature is useful for reducing component count and wiring connections, for example, in isolated multiconverter applications or for systems with a limited interfacing capacity.

All ADC slaves are addressed by the same  $\overline{\text{CS}}, \overline{\text{CONVST}},$  and SCLK signals. The SDI of the first AD7091R-2/AD7091R-4/ AD7091R-8 slave in the chain is driven directly by the master output, slave input (MOSI) pin of the SPI master. The SDO of the first slave is connected to the SDI of the second slave. All the subsequent slaves are connected in this fashion, and the SDO of the last slave drives the master input, slave output (MISO) pin of the master. A connection diagram example using two AD7091R-2/AD7091R-4/AD7091R-8 devices is shown in Figure 57.

Each AD7091R-2/AD7091R-4/AD7091R-8 slave in the chain requires a 16-bit SPI command. If there are N slaves, each SPI frame must have  $N \times 16$  bits of data. In the AD7091R-2/ AD7091R-4/AD7091R-8, when the bit counter crosses 16 bits, all of the received bits are sent out over the SDO. The output from the first slave is the input of the second slave. Effectively, each slave ignores all the incoming 16-bit SPI commands except the last one. The SPI command received just before the CS rising edge is the only valid SPI command for a given device in the daisy chain. The output on the next SPI frame is determined by the valid SPI command or any conversion event.

The methods for reading a conversion result to configuring the slave registers are outlined in Figure 58 to Figure 62 for a twoslave example. Additional slave devices can be added to the chain by following the same principles defined for the twodevice configuration.

10891-031



Figure 57. Daisy-Chain Configuration



Figure 58. Conversion in a Two-Slave Daisy-Chain Mode Configuration

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10891-035



Figure 59. Single Register Write in a Two-Slave Daisy-Chain Mode Configuration



Figure 60. Single Register Read in a Two-Slave Daisy-Chain Mode Configuration



Figure 61. Multiple Register Read in a Two-Slave Daisy-Chain Mode Configuration



Figure 62. Multiple Register Write in a Two-Slave Daisy-Chain Mode Configuration

# OUTLINE DIMENSIONS





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**03-11-2013-A**

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Dimensions shown in millimeters

### **ORDERING GUIDE**



 $1 Z =$  RoHS Compliant Part.

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