

### FEATURES

**Complete, Fully Calibrated Log-Limiting IF Amplifier**  
**100 dB Dynamic Range: –91 dBV to +9 dBV**  
**Stable RSSI Scaling Over Temperature and Supplies:**  
 20 mV/dB Slope, –95 dBm Intercept  
 ±0.4 dB RSSI Linearity up to 200 MHz  
**Programmable Limiter Gain and Output Current**  
 Differential Outputs to 10 mA, 2.4 V p-p  
 Overall Gain 90 dB, Bandwidth 400 MHz  
 Constant Phase (Typical ±56 ps Delay Skew)  
 Single Supply of +2.7 V to +6.5 V at 16 mA Typical  
 Fully Differential Inputs,  $R_{IN} = 1\text{ k}\Omega$ ,  $C_{IN} = 2.5\text{ pF}$   
 500 ns Power-Up Time, <1  $\mu\text{A}$  Sleep Current

### APPLICATIONS

Receivers for Frequency and Phase Modulation  
 Very Wide Range IF and RF Power Measurement  
 Receiver Signal Strength Indication (RSSI)  
 Low Cost Radar and Sonar Signal Processing  
 Instrumentation: Network and Spectrum Analyzers

### PRODUCT DESCRIPTION

The AD8306 is a complete IF limiting amplifier, providing both an accurate logarithmic (decibel) measure of the input signal (the RSSI function) over a dynamic range of 100 dB, and a programmable limiter output, useful from 5 MHz to 400 MHz.

It is easy to use, requiring few external components. A single supply voltage of +2.7 V to +6.5 V at 16 mA is needed, corresponding to a power consumption of under 50 mW at 3 V, plus the limiter bias current, determined by the application and typically 2 mA, providing a limiter gain of 90 dB when using 200  $\Omega$  loads. A CMOS-compatible control interface can enable the AD8306 within about 500 ns and disable it to a standby current of under 1  $\mu\text{A}$ .

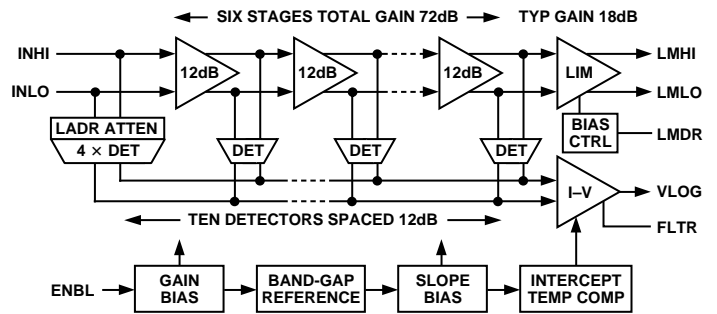
The six cascaded amplifier/limiter cells in the main path have a small signal gain of 12.04 dB ( $\times 4$ ), with a –3 dB bandwidth of 850 MHz, providing a total gain of 72 dB. The programmable output stage provides a further 18 dB of gain. The input is fully differential and presents a moderately high impedance (1 k $\Omega$  in parallel with 2.5 pF). The input-referred noise-spectral-density, when driven from a terminated 50  $\Omega$ , source is 1.28 nV/ $\sqrt{\text{Hz}}$ , equivalent to a noise figure of 3 dB. The sensitivity of the AD8306 can be raised by using an input matching network.

Each of the main gain cells includes a full-wave detector. An additional four detectors, driven by a broadband attenuator, are used to extend the top end of the dynamic range by over 48 dB.

### REV. A

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### FUNCTIONAL BLOCK DIAGRAM



The overall dynamic range for this combination extends from –91 dBV (–78 dBm at the 50  $\Omega$  level) to a maximum permissible value of +9 dBV, using a balanced drive of antiphase inputs each of 2 V in amplitude, which would correspond to a sine wave power of +22 dBm if the differential input were terminated in 50  $\Omega$ . Through laser trimming, the slope of the RSSI output is closely controlled to 20 mV/dB, while the intercept is set to –108 dBV (–95 dBm re 50  $\Omega$ ). These scaling parameters are determined by a band-gap voltage reference and are substantially independent of temperature and supply. The logarithmic law conformance is typically within ±0.4 dB over the central 80 dB of this range at any frequency between 10 MHz and 200 MHz, and is degraded only slightly at 400 MHz.

The RSSI response time is nominally 73 ns (10%–90%). The averaging time may be increased without limit by the addition of an external capacitor. The full output of 2.34 V at the maximum input of +9 dBV can drive any resistive load down to 50  $\Omega$  and this interface remains stable with any value of capacitance on the output.

The AD8306 is fabricated on an advanced complementary bipolar process using silicon-on-insulator isolation techniques and is available in the industrial temperature range of –40°C to +85°C, in a 16-lead narrow body SO package. The AD8306 is also available for the full military temperature range of –55°C to +125°C, in a 16-lead side-brazed ceramic DIP.

# AD8306—SPECIFICATIONS ( $V_S = +5\text{ V}$ , $T_A = +25^\circ\text{C}$ , $f = 10\text{ MHz}$ , unless otherwise noted)

Parameter	Conditions	Min <sup>1</sup>	Typ	Max <sup>1</sup>	Units
<b>INPUT STAGE</b>					
Maximum Input <sup>2</sup>	(Inputs INHI, INLO) Differential Drive, p-p	±3.5	±4		V
Equivalent Power in 50 Ω	Terminated in 52.3 Ω    R <sub>IN</sub>		+9		dBV
Noise Floor	Terminated 50 Ω Source		+22		dBm
Equivalent Power in 50 Ω	400 MHz Bandwidth		1.28		nV/√Hz
Input Resistance	From INHI to INLO	800	1000	1200	Ω
Input Capacitance	From INHI to INLO		2.5		pF
DC Bias Voltage	Either Input		1.725		V
<b>LIMITING AMPLIFIER</b>					
(Outputs LMHI, LMLO)					
Usable Frequency Range		5		400	MHz
At Limiter Output	R <sub>LOAD</sub> = R <sub>LIM</sub> = 50 Ω, to -10 dB Point		585		MHz
Phase Variation at 100 MHz	Over Input Range -73 dBV to -3 dBV		±2		Degrees
Limiter Output Current	Nominally 400 mV/R <sub>LIM</sub>	0	1	10	mA
Versus Temperature	-40°C ≤ T <sub>A</sub> ≤ +85°C		-0.008		%/°C
Input Range <sup>3</sup>		-78		+9	dBV
Maximum Output Voltage	At Either LMHI or LMLO, wrt VPS2	1	1.25		V
Rise/Fall Time (10%–90%)	R <sub>LOAD</sub> = 50 Ω, 40 Ω ≤ R <sub>LIM</sub> ≤ 400 Ω		0.6		ns
<b>LOGARITHMIC AMPLIFIER</b>					
(Output VLOG)					
±3 dB Error Dynamic Range	From Noise Floor to Maximum Input		100		dB
Transfer Slope <sup>4</sup>	f = 10 MHz	19.5	20	20.5	mV/dB
	f = 100 MHz		19.6		mV/dB
Over Temperature	-40°C < T <sub>A</sub> < +85°C	19.3	20	20.7	mV/dB
Intercept (Log Offset) <sup>4</sup>	f = 10 MHz	-109.5	-108	-106.5	dBV
	f = 100 MHz		-108.4		dBV
Over Temperature	-40°C ≤ T <sub>A</sub> ≤ +85°C	-111	-108	-105	dBV
Temperature Sensitivity			-0.009		dB/°C
Linearity Error (Ripple)	Input from -80 dBV to +0 dBV		±0.4		dB
Output Voltage	Input = -91 dBV, V <sub>S</sub> = +5 V, +2.7 V		0.34		V
	Input = +9 dBV, V <sub>S</sub> = +5 V		2.34	2.75	V
	Input = -3 dBV, V <sub>S</sub> = +3 V		2.10		V
Minimum Load Resistance, R <sub>L</sub>		40	50		Ω
Maximum Sink Current	To Ground	0.75	1.0	1.25	mA
Output Resistance			0.3		Ω
Small-Signal Bandwidth			3.5		MHz
Output Settling Time to 2%	Large Scale Input, +3 dBV, R <sub>L</sub> ≥ 50 Ω, C <sub>L</sub> ≤ 100 pF		120	220	ns
Rise/Fall Time (10%–90%)	Large Scale Input, +3 dBV, R <sub>L</sub> ≥ 50 Ω, C <sub>L</sub> ≤ 100 pF		73	100	ns
<b>POWER INTERFACES</b>					
Supply Voltage, V <sub>S</sub>		2.7	5	6.5	V
Quiescent Current	Zero-Signal, LMDR Open	13	16	20	mA
Over Temperature	-40°C < T <sub>A</sub> < +85°C	11	16	23	mA
Disable Current	-40°C < T <sub>A</sub> < +85°C		0.01	4	μA
Additional Bias for Limiter	R <sub>LIM</sub> = 400 Ω (See Text)		2.0	2.25	mA
Logic Level to Enable Power	HI Condition, -40°C < T <sub>A</sub> < +85°C	2.7		V <sub>S</sub>	V
Input Current when HI	3 V at ENBL, -40°C < T <sub>A</sub> < +85°C		40	60	μA
Logic Level to Disable Power	LO Condition, -40°C < T <sub>A</sub> < +85°C	-0.5	1		V
<b>TRANSISTOR COUNT</b>					
	# of Transistors		207	207	

## NOTES

<sup>1</sup>Minimum and maximum specified limits on parameters that are guaranteed but not tested are six sigma values.

<sup>2</sup>The input level is specified in “dBV” since logarithmic amplifiers respond strictly to voltage, not power. 0 dBV corresponds to a sinusoidal single-frequency input of 1 V rms. A power level of 0 dBm (1 mW) in a 50 Ω termination corresponds to an input of 0.2236 V rms. Hence, in the special case of 50 Ω termination, dBV values can be converted into dBm by adding a fixed offset of +13 to the dBV rms value.

<sup>3</sup>Due to the extremely high Gain Bandwidth Product of the AD8306, the output of either LMHI or LMLO will be unstable for levels below -78 dBV (-65 dBm, re 50 Ω).

<sup>4</sup>Standard deviation remains essentially constant over frequency. See Figures 13, 14, 16 and 17.

Specifications subject to change without notice.

### ABSOLUTE MAXIMUM RATINGS\*

Supply Voltage $V_S$ .....	7.5 V
Input Level, Differential (re 50 $\Omega$ ) .....	+26 dBm
Input Level, Single-Ended (re 50 $\Omega$ ) .....	+20 dBm
Internal Power Dissipation .....	800 mW
$\theta_{JA}$ .....	125°C/W
$\theta_{JC}$ .....	25°C/W
Maximum Junction Temperature .....	+125°C
Operating Temperature Range .....	-40°C to +85°C

Storage Temperature Range	-65°C to +150°C
Lead Temperature Range (Soldering 60 sec)	+300°C

\*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may effect device reliability.

### ORDERING GUIDE

Model	Temperature Range	Package Description	Package Options
AD8306AR	-40°C to +85°C	16-Lead Narrow Body SO	SO-16
AD8306AR-REEL	-40°C to +85°C	13" Tape and Reel	SO-16
AD8306AR-REEL7	-40°C to +85°C	7" Tape and Reel	SO-16
AD8306ACHIPS	-40°C to +85°C	Die	
5962-9864601QEA	-55°C to +125°C	16-Lead Side-Brazed Ceramic DIP	D-16
AD8306-EVAL		Evaluation Board	

### CAUTION

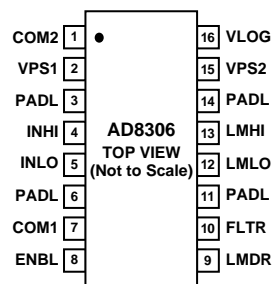
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD8306 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



### PIN FUNCTION DESCRIPTIONS

Pin	Name	Function
1	COM2	Special Common Pin for RSSI Output.
2	VPS1	Supply Pin for First Five Amplifier Stages and the Main Biasing System.
3, 6, 11, 14	PADL	Four Tie-Downs to the Paddle on which the IC Is Mounted; Grounded.
4	INHI	Signal Input, HI or Plus Polarity.
5	INLO	Signal Input, LO or Minus Polarity.
7	COM1	Main Common Connection.
8	ENBL	Chip Enable; Active When HI.
9	LMDR	Limiter Drive Programming Pin.
10	FLTR	RSSI Bandwidth-Reduction Pin.
12	LMLO	Limiter Output, LO or Minus Polarity.
13	LMHI	Limiter Output, HI or Plus Polarity.
15	VPS2	Supply Pin for Sixth Gain Stage, Limiter and RSSI Output Stage Load Current.
16	VLOG	Logarithmic (RSSI) Output.

### PIN CONFIGURATION



# AD8306—Typical Performance Characteristics

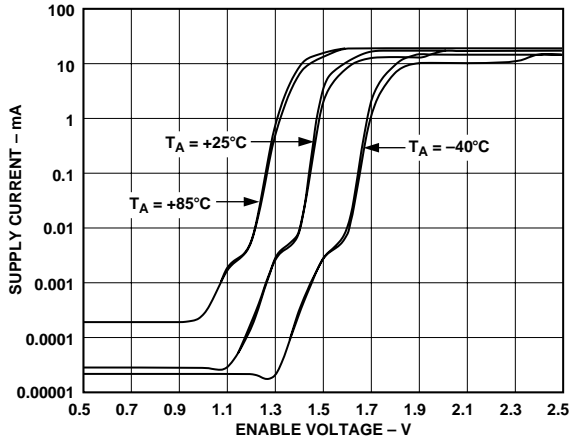


Figure 1. Supply Current vs. Enable Voltage @  $T_A = -40^\circ\text{C}$ ,  $+25^\circ\text{C}$  and  $+85^\circ\text{C}$

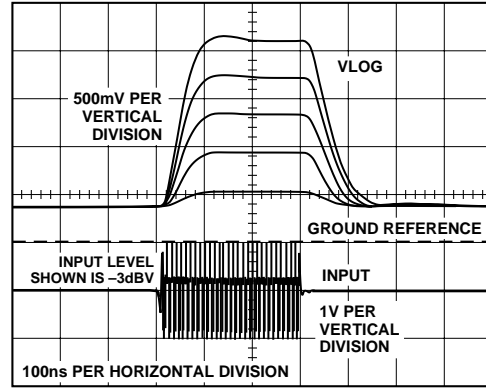


Figure 4. RSSI Pulse Response for Inputs Stepped from Zero to  $-83\text{ dBV}$ ,  $-63\text{ dBV}$ ,  $-43\text{ dBV}$ ,  $-23\text{ dBV}$ ,  $-3\text{ dBV}$

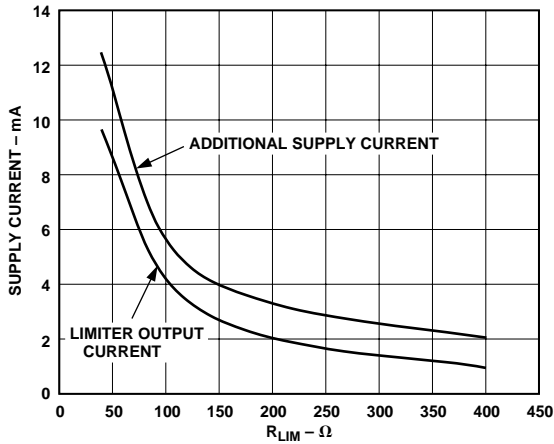


Figure 2. Additional Supply Current and Limiter Output Current vs.  $R_{LIM}$

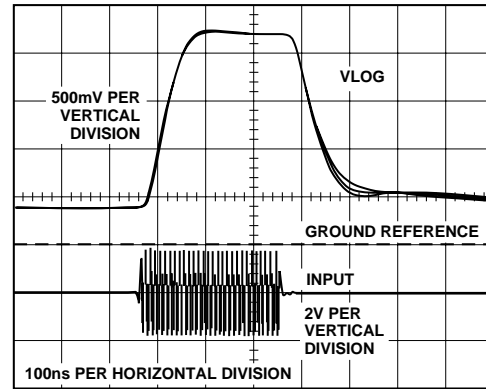


Figure 5. Large Signal RSSI Pulse Response with  $R_L = 100\ \Omega$  and  $C_L = 33\text{ pF}$ ,  $100\text{ pF}$  and  $330\text{ pF}$  (Overlapping Curves)

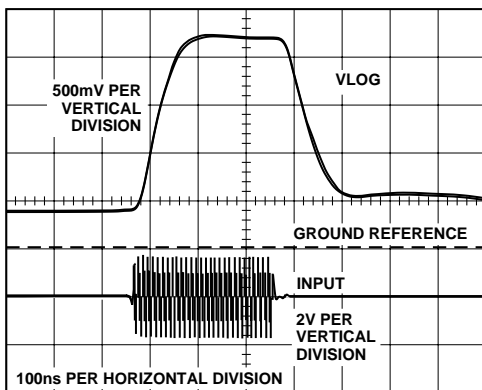


Figure 3. Large Signal RSSI Pulse Response with  $C_L = 100\text{ pF}$  and  $R_L = 50\ \Omega$  and  $75\ \Omega$  (Curves Overlap)

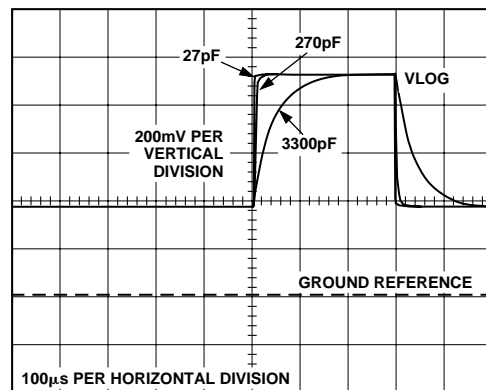


Figure 6. Small Signal AC Response of RSSI Output with External Filter Capacitance of  $27\text{ pF}$ ,  $270\text{ pF}$  and  $3300\text{ pF}$

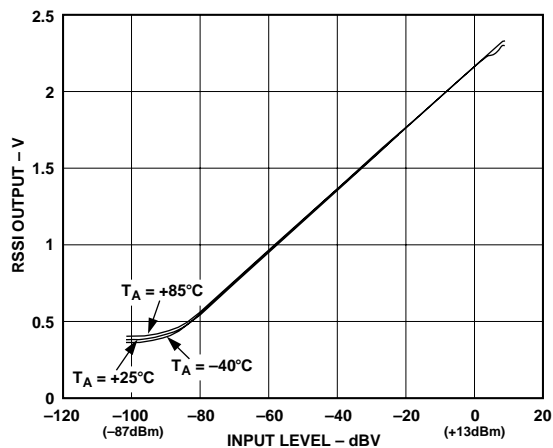


Figure 7. RSSI Output vs. Input Level, 100 MHz Sine Input, at  $T_A = -40^\circ\text{C}$ ,  $+25^\circ\text{C}$  and  $+85^\circ\text{C}$ , Single-Ended Input

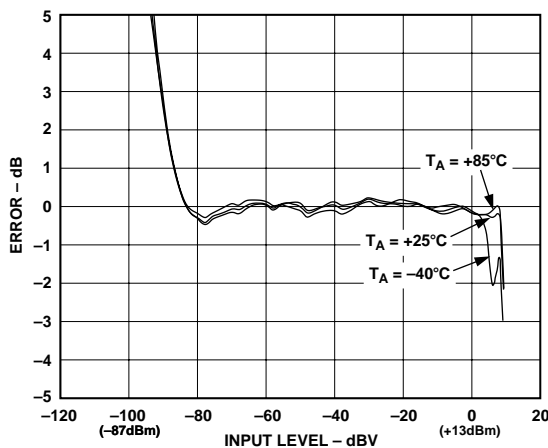


Figure 10. Log Linearity of RSSI Output vs. Input Level, 100 MHz Sine Input, at  $T_A = -40^\circ\text{C}$ ,  $+25^\circ\text{C}$ , and  $+85^\circ\text{C}$

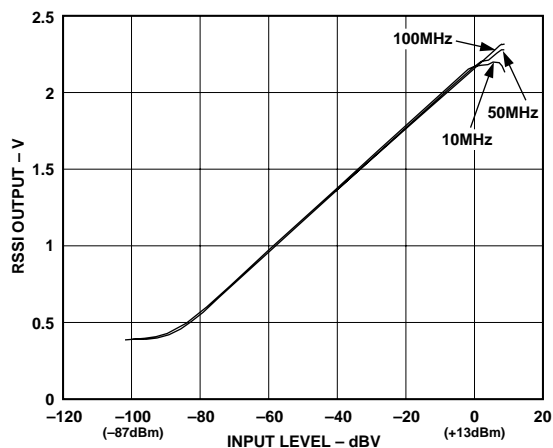


Figure 8. RSSI Output vs. Input Level, at  $T_A = +25^\circ\text{C}$ , for Frequencies of 10 MHz, 50 MHz and 100 MHz

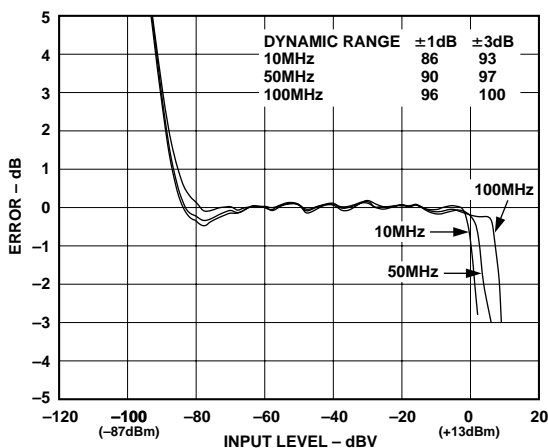


Figure 11. Log Linearity of RSSI Output vs. Input Level, at  $T_A = +25^\circ\text{C}$ , for Frequencies of 10 MHz, 50 MHz and 100 MHz

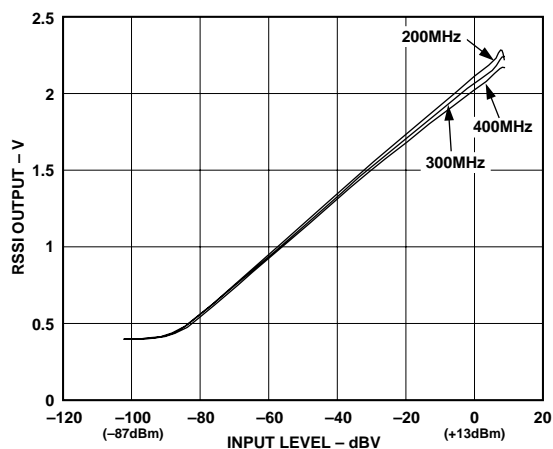


Figure 9. RSSI Output vs. Input Level, at  $T_A = +25^\circ\text{C}$ , for Frequencies of 200 MHz, 300 MHz and 400 MHz

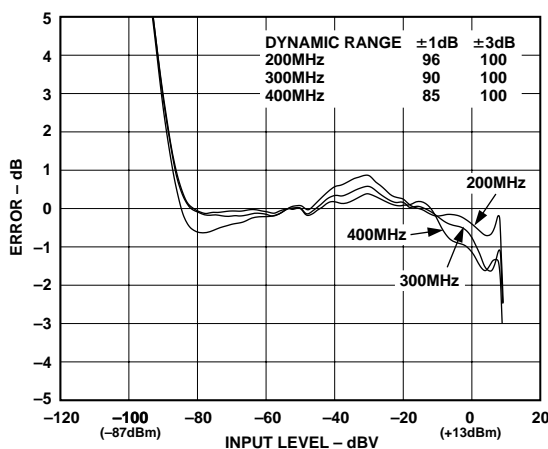


Figure 12. Log Linearity of RSSI Output vs. Input Level, at  $T_A = +25^\circ\text{C}$ , for Frequencies of 200 MHz, 300 MHz and 400 MHz

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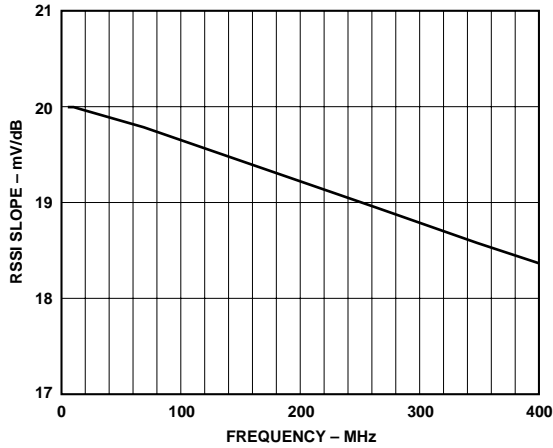


Figure 13. RSSI Slope vs. Frequency Using Termination of 52.3 Ω

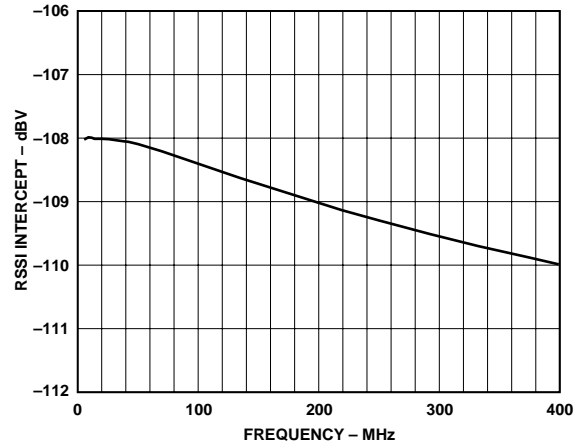


Figure 16. RSSI Intercept vs. Frequency Using Termination of 52.3 Ω

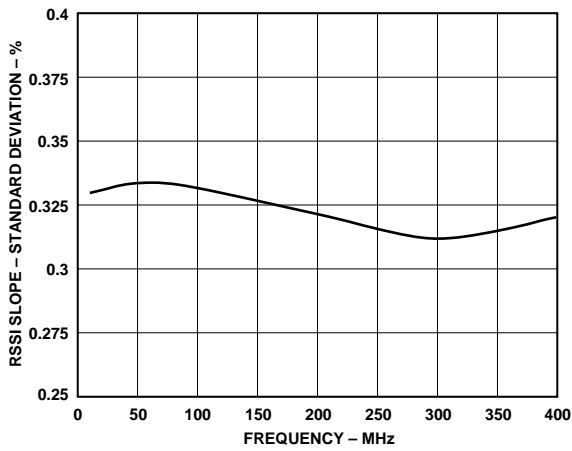


Figure 14. RSSI Slope Standard Deviation vs. Frequency

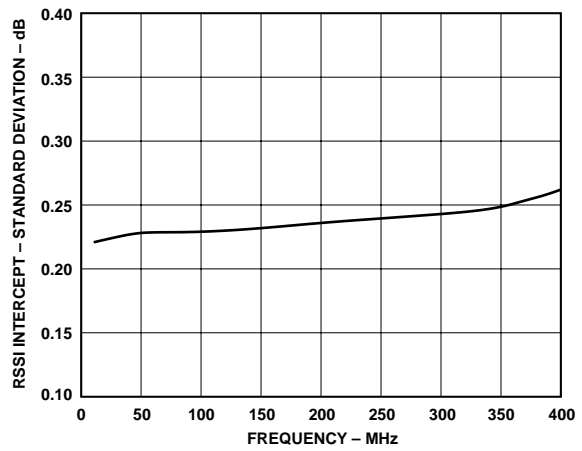


Figure 17. RSSI Intercept Standard Deviation vs. Frequency

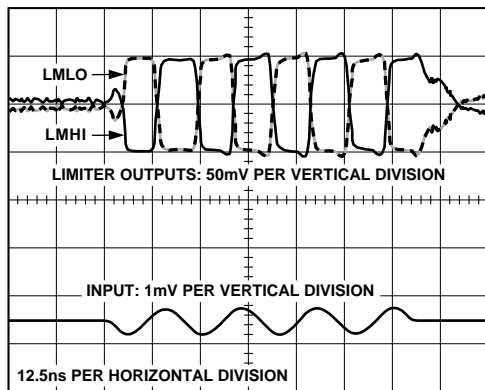


Figure 15. Limiter Response at LMHI, LMLO with Pulsed Sine Input of -73 dBV (-60 dBm) at 50 MHz;  $R_{LOAD} = 50 \Omega$ ,  $R_{LIM} = 200 \Omega$

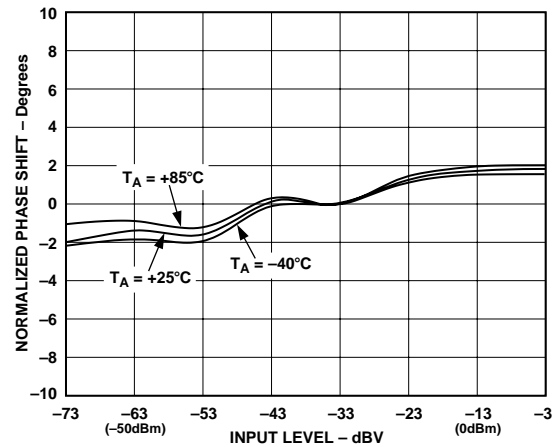


Figure 18. Normalized Limiter Phase Response vs. Input Level. Frequency = 100 MHz;  $T_A = -40^\circ\text{C}$ ,  $+25^\circ\text{C}$  and  $+85^\circ\text{C}$

## PRODUCT OVERVIEW

The AD8306 is built on an advanced dielectrically-isolated complementary bipolar process using thin-film resistor technology for accurate scaling. It follows well-developed foundations proven over a period of some fifteen years, with constant refinement. The backbone of the AD8306 (Figure 19) comprises a chain of six main amplifier/limiter stages, each having a gain of 12.04 dB ( $\times 4$ ) and small-signal  $-3$  dB bandwidth of 850 MHz. The input interface at INHI and INLO (Pins 4 and 5) is fully differential. Thus it may be driven from either single-sided or balanced inputs, the latter being required at the very top end of the dynamic range, where the total differential drive may be as large as 4 V in amplitude.

The first six stages, also used in developing the logarithmic RSSI output, are followed by a versatile programmable-output, and thus programmable-gain, final limiter section. Its open-collector outputs are also fully differential, at LMHI and LMLO (Pins 12 and 13). This output stage provides a gain of 18 dB when using equal valued load and bias setting resistors and the pin-to-pin output is used. The *overall* voltage gain is thus 90 dB. When using  $R_{LIM} = R_{LOAD} = 200 \Omega$ , the additional current consumption in the limiter is approximately 2.8 mA, of which 2 mA goes to the load. The ratio depends on  $R_{LIM}$  (for example, when  $20 \Omega$ , the efficiency is 90%), and the voltage at the pin LMDR is rather more than 400 mV, but the total load current is accurately  $(400 \text{ mV})/R_{LIM}$ .

The rise and fall times of the hard-limited (essentially square-wave) voltage at the outputs are typically 0.6 ns, when driven by a sine wave input having an amplitude of 316  $\mu\text{V}$  or greater, and  $R_{LOAD} = 50 \Omega$ . The change in time-delay (“phase skew”) over the input range  $-73$  dBV (316  $\mu\text{V}$  in amplitude, or  $-60$  dBm in  $50 \Omega$ ) to  $-3$  dBV (1 V or  $+10$  dBm) is  $\pm 56$  ps ( $\pm 2^\circ$  at 100 MHz).

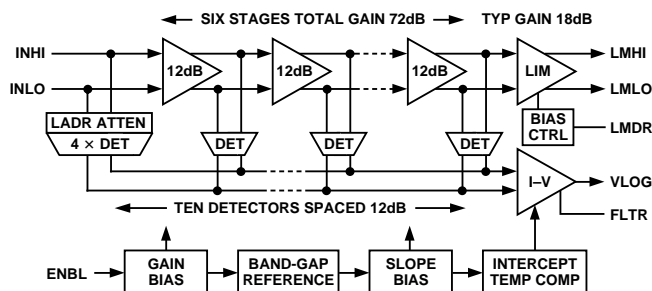


Figure 19. Main Features of the AD8306

The six main cells and their associated full-wave detectors, having a transconductance ( $g_m$ ) form, handle the lower part of the dynamic range. Biasing for these cells is provided by two references, one of which determines their gain, the other being a band-gap cell which determines the logarithmic slope, and stabilizes it against supply and temperature variations. A special dc-offset-sensing cell (not shown in Figure 19) is placed at the end of this main section, and used to null any residual offset at the input, ensuring accurate response down to the noise floor. The first amplifier stage provides a short-circuited voltage-noise spectral-density of  $1.07 \text{ nV}/\sqrt{\text{Hz}}$ .

The last detector stage includes a modification to temperature-stabilize the log-intercept, which is accurately positioned so as to make optimal use of the full output voltage range. Four further “top end” detectors are placed at 12.04 dB taps along a passive attenuator, to handle the upper part of the range. The

differential current-mode outputs of all ten detectors stages are summed with equal weightings and converted to a single-sided voltage by the output stage, generating the logarithmic (or RSSI) output at VLOG (Pin 16), nominally scaled 20 mV/dB (that is, 400 mV per decade). The junction between the lower and upper regions is seamless, and the logarithmic law-conformance is typically well within  $\pm 0.4$  dB over the 80 dB range from  $-80$  dBV to 0 dBV ( $-67$  dBm to  $+13$  dBm).

The full-scale rise time of the RSSI output stage, which operates as a two-pole low-pass filter with a corner frequency of 3.5 MHz, is about 200 ns. A capacitor connected between FLTR (Pin 10) and VLOG can be used to lower the corner frequency (see below). The output has a minimum level of about 0.34 V (corresponding to a noise power of  $-78$  dBm, or 17 dB above the nominal intercept of  $-95$  dBm). This rather high baseline level ensures that the pulse response remains unimpaired at very low inputs.

The maximum RSSI output depends on the supply voltage and the load. An output of 2.34 V, that is,  $20 \text{ mV/dB} \times (9 + 108) \text{ dB}$ , is guaranteed when using a supply voltage of 4.5 V or greater and a load resistance of  $50 \Omega$  or higher, for a differential input of 9 dBV (a 4 V sine amplitude, using balanced drives). When using a 3 V supply, the maximum differential input may still be as high as  $-3$  dBV (1 V sine amplitude), and the corresponding RSSI output of 2.1 V, that is,  $20 \text{ mV/dB} \times (-3 + 108) \text{ dB}$  is also guaranteed.

A fully-programmable output interface is provided for the hard-limited signal, permitting the user to establish the optimal output current from its differential current-mode output. Its magnitude is determined by the resistor  $R_{LIM}$  placed between LMDR (Pin 9) and ground, across which a nominal bias voltage of  $\sim 400$  mV appears. Using  $R_{LIM} = 200 \Omega$ , this dc bias current, which is commutated alternately to the output pins, LMHI and LMLO, by the signal, is 2 mA. (The *total* supply current is somewhat higher).

These currents may readily be converted to voltage form by the inclusion of load resistors, which will typically range from a few tens of ohms at 400 MHz to as high as 2 k $\Omega$  in lower frequency applications. Alternatively, a resonant load may be used to extract the fundamental signal and modulation sidebands, minimizing the out-of-band noise. A transformer or impedance matching network may also be used at this output. The peak voltage swing down from the supply voltage may be 1.2 V, before the output transistors go into saturation. (The Applications section provides further information on the use of this interface).

The supply current for all sections except the limiter output stage, and with no load attached to the RSSI output, is nominally 16 mA at  $T_A = 27^\circ\text{C}$ , substantially independent of supply voltage. It varies in direct proportion to the absolute temperature (PTAT). The RSSI load current is simply the voltage at VLOG divided by the load resistance (e.g., 2.4 mA max in a 1 k $\Omega$  load). The limiter supply current is 1.1 times that flowing in  $R_{LIM}$ . The AD8306 may be enabled/disabled by a CMOS-compatible level at ENBL (Pin 8).

In the following simplified interface diagrams, the components denoted with an uppercase “R” are thin-film resistors having a very low temperature-coefficient of resistance and high linearity under large-signal conditions. Their absolute value is typically within  $\pm 20\%$ . Capacitors denoted using an uppercase “C” have a typical tolerance of  $\pm 15\%$  and essentially zero temperature or

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voltage sensitivity. Most interfaces have additional small junction capacitances associated with them, due to active devices or ESD protection; these may be neither accurate nor stable. Component numbering in each of these interface diagrams is local.

## Enable Interface

The chip-enable interface is shown in Figure 20. The current in R1 controls the turn-on and turn-off states of the band-gap reference and the bias generator, and is a maximum of 100  $\mu$ A when Pin 8 is taken to 5 V. Left unconnected, or at any voltage below 1 V, the AD8306 will be disabled, when it consumes a sleep current of much less than 1  $\mu$ A (leakage currents only); when tied to the supply, or any voltage above 2 V, it will be fully enabled. The internal bias circuitry requires approximately 300 ns for either OFF or ON, while a delay of some 6  $\mu$ s is required for the supply current to fall below 10  $\mu$ A.

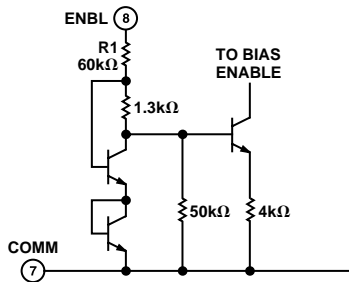


Figure 20. Enable Interface

## Input Interface

Figure 21 shows the essentials of the signal input interface. The parasitic capacitances to ground are labeled  $C_p$ ; the differential input capacitance,  $C_D$ , mainly due to the diffusion capacitance of Q1 and Q2. In most applications both input pins are ac-coupled. The switch S closes when Enable is asserted. When disabled, the inputs float, bias current  $I_E$  is shut off, and the coupling capacitors remain charged. If the log amp is disabled for long periods, small leakage currents will discharge these capacitors. If they are poorly matched, charging currents at power-up can generate a transient input voltage which may block the lower reaches of the dynamic range until it has become much less than the signal.

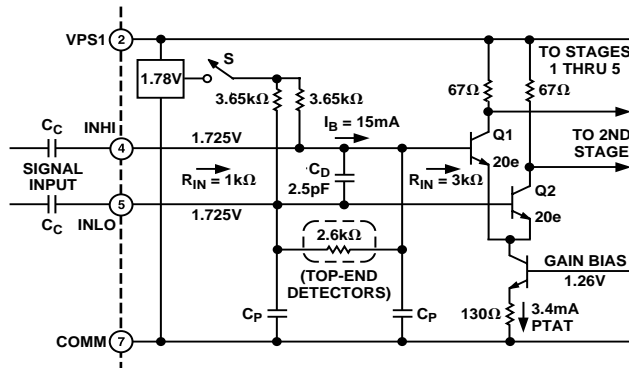


Figure 21. Signal Input Interface

In most applications, the input signal will be single-sided, and may be applied to either Pin 4 or 5, with the remaining pin ac-coupled to ground. Under these conditions, the largest input signal that can be handled is -3 dBV (sine amplitude of 1 V) when operating from a 3 V supply; a +3 dBV input may be

handled using a supply of 4.5 V or greater. When using a fully-balanced drive, the +3 dBV level may be achieved for the supplies down to 2.7 V and +9 dBV using >4.5 V. For frequencies in the range 10 MHz to 200 MHz these high drive levels are easily achieved using a matching network. Using such a network, having an inductor at the input, the input transient is eliminated.

## Limiter Output Interface

The simplified limiter output stage is shown in Figure 22. The bias for this stage is provided by a temperature-stable reference voltage of nominally 400 mV which is forced across the external resistor  $R_{LIM}$  connected from Pin 9 (LMDR, or limiter drive) by a special op amp buffer stage. The biasing scheme also introduces a slight “lift” to this voltage to compensate for the finite current gain of the current source Q3 and the output transistors Q1 and Q2. A maximum current of 10 mA is permissible ( $R_{LIM} = 40 \Omega$ ). In special applications, it may be desirable to modulate the bias current; an example of this is provided in the Applications section. Note that while the bias currents are temperature stable, the ac gain of this stage will vary with temperature, by -6 dB over a 120°C range.

A pair of supply and temperature stable complementary currents is generated at the differential output LMHI and LMLO (Pins 12 and 13), having a square wave form with rise and fall times of typically 0.6 ns, when load resistors of 50  $\Omega$  are used. The voltage at these output pins may swing to 1.2 V below the supply voltage applied to VPS2 (Pin 15).

Because of the very high gain bandwidth product of this amplifier considerable care must be exercised in using the limiter outputs. The minimum necessary bias current and voltage swings should be used. These outputs are best utilized in a fully-differential mode. A flux-coupled transformer, a balun, or an output matching network can be selected to transform these voltages to a single-sided form. Equal load resistors are recommended, even when only one output pin is used, and these should always be returned to the same well decoupled node on the PC board. When the AD8306 is used only to generate an RSSI output, the limiter should be completely disabled by omitting  $R_{LIM}$  and strapping LMHI and LMLO to VPS2.

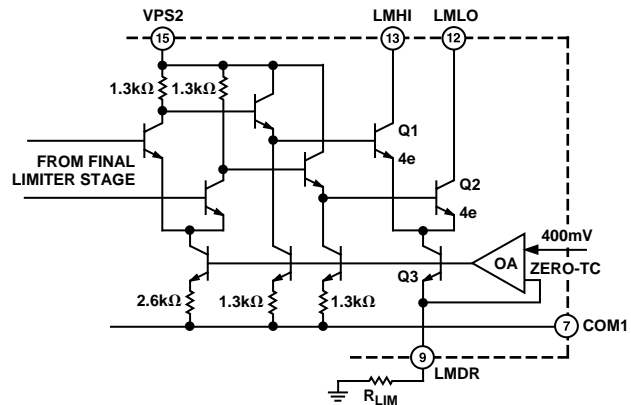


Figure 22. Limiter Output Interface

## RSSI Output Interface

The outputs from the ten detectors are differential currents, having an average value that is dependent on the signal input level, plus a fluctuation at twice the input frequency. The currents are summed at the internal nodes LGP and LGN shown in Figure 23. A further current  $I_T$  is added to LGP, to position



the intercept to  $-108$  dBV, by raising the RSSI output voltage for zero input, and to provide temperature compensation, resulting in a stable intercept. For zero signal conditions, all the detector output currents are equal. For a finite input, of either polarity, their difference is converted by the output interface to a single-sided voltage nominally scaled  $20$  mV/dB ( $400$  mV per decade), at the output VLOG (Pin 16). This scaling is controlled by a separate feedback stage, having a tightly controlled transconductance. A small uncertainty in the log slope and intercept remains (see Specifications); the intercept may be adjusted (see Applications).

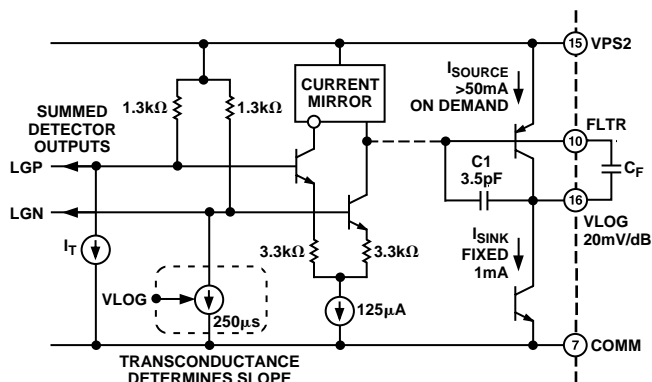


Figure 23. Simplified RSSI Output Interface

The RSSI output bandwidth,  $f_{LP}$ , is nominally  $3.5$  MHz. This is controlled by the compensation capacitor  $C_1$ , which may be increased by adding an external capacitor,  $C_F$ , between FLTR (Pin 10) and VLOG (Pin 16). An external  $33$  pF will reduce  $f_{LP}$  to  $350$  kHz, while  $360$  pF will set it to  $35$  kHz, in each case with an essentially one-pole response. In general, the relationships (for  $f_{LP}$  in MHz) are:

$$C_F = \frac{12.7 \times 10^{-10}}{f_{LP}} - 3.5 \text{ pF}; \quad f_{LP} = \frac{12.7 \times 10^{-6}}{C_F + 3.5 \text{ pF}} \quad (1)$$

Using a load resistance of  $50 \Omega$  or greater, and at any temperature, the peak output voltage may be at least  $2.4$  V when using a supply of  $4.5$  V, and at least  $2.1$  V for a  $3$  V supply, which is consistent with the maximum permissible input levels. The incremental output resistance is approximately  $0.3 \Omega$  at low frequencies, rising to  $1 \Omega$  at  $150$  kHz and  $18 \Omega$  at very high frequencies.

The output is unconditionally stable with load capacitance, but it should be noted that while the peak sourcing current is over  $100$  mA, and able to rapidly charge even large capacitances, the internally provided sinking current is only  $1$  mA. Thus, the fall time from the  $2$  V level will be as long as  $2 \mu\text{s}$  for a  $1$  nF load. This may be reduced by adding a grounded load resistance.

#### USING THE AD8306

The AD8306 exhibits very high gain from  $1$  MHz to over  $1$  GHz, at which frequency the gain of the main path is still over  $65$  dB. Consequently, it is susceptible to all signals, within this very broad frequency range, that find their way to the input terminals. It is important to remember that these are quite indistinguishable from the “wanted” signal, and will have the effect of raising the apparent noise floor (that is, lowering the useful dynamic range). Therefore, while the signal of interest may be an IF of, say,  $200$  MHz, any of the following could easily be larger than this signal at the lower extremities of its dynamic

range: a  $60$  Hz hum, picked up due to poor grounding techniques; spurious coupling from digital logic on the same PC board; a strong EMI source; etc.

Very careful shielding is essential to guard against such unwanted signals, and also to minimize the likelihood of instability due to HF feedback from the limiter outputs to the input. With this in mind, the *minimum possible limiter gain* should be used. Where only the logarithmic amplifier (RSSI) function is required, the limiter should be disabled by omitting  $R_{LIM}$  and tying the outputs LMHI and LMLO directly to VPS2. A good ground plane should be used to provide a low impedance connection to the common pins, for the decoupling capacitor(s) used at VPS1 and VPS2, and at the output ground. Note that COM2 is a special ground pin serving just the RSSI output.

The four pins labeled PADL tie down directly to the metallic lead frame, and are thus connected to the back of the chip. The process on which the AD8306 is fabricated uses a bonded-wafer technique to provide a silicon-on-insulator isolation, and there is no junction or other dc path from the back side to the circuitry on the surface. These paddle pins must be connected directly to the ground plane using the shortest possible lead lengths to minimize inductance.

The voltages at the two supply pins should not be allowed to differ greatly; up to  $500$  mV is permissible. It is desirable to allow VPS1 to be slightly more negative than VPS2. When the primary supply is greater than  $2.7$  V, the decoupling resistors  $R_1$  and  $R_2$  (Figure 24) may be increased to improve the isolation and lower the dissipation in the IC. However, since VPS2 supports the RSSI load current, which may be large, the value of  $R_2$  should take this into account.

#### Basic Connections for Log (RSSI) Output

Figure 24 shows the connections required for most applications. The AD8306 is enabled by connecting ENBL to VPS1. The device is put into the sleep mode by grounding this pin. The inputs are ac-coupled by  $C_1$  and  $C_2$ , which normally should have the same value ( $C_C$ ). The input is, in this case, terminated with a  $52.3 \Omega$  resistor that combines with the AD8306’s input resistance of  $1000 \Omega$  to give a broadband input impedance of  $50 \Omega$ . Alternatively an input matching network can be used (see Input Matching section).

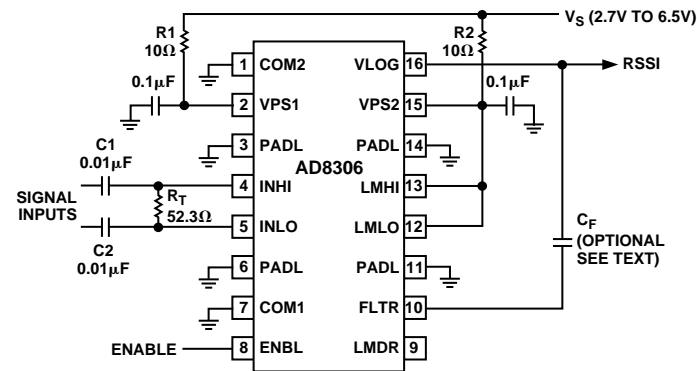


Figure 24. Basic Connections for RSSI (Log) Output

The  $0.01 \mu\text{F}$  coupling capacitors and the resulting  $50 \Omega$  input impedance give a high-pass corner frequency of around  $600$  kHz ( $1/(2 \pi RC)$ ), where  $C = (C_1)/2$ . In high frequency applications, this corner frequency should be placed as high as possible, to minimize the coupling of unwanted low frequency signals. In

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low frequency applications, a simple RC network forming a low-pass filter should be added at the input for the same reason.

If the limiter output is not required, Pin 9 (LMDR) should be left open and Pins 12 and 13 (LMHI, LMLO) should be tied to VPS2 as shown in Figure 24.

Figure 25 shows the output versus the input level in dBV, for sine inputs at 10 MHz, 50 MHz and 100 MHz (add 13 to the dBV number to get dBm Re 50 Ω. Figure 26 shows the typical logarithmic linearity (log conformance) under the same conditions.

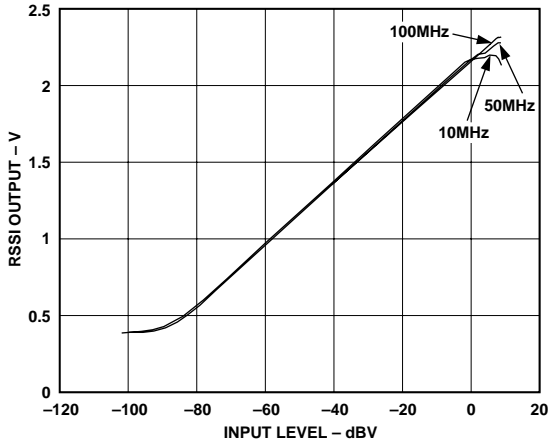


Figure 25. RSSI Output vs. Input Level at  $T_A = +25^\circ\text{C}$  for Frequencies of 10 MHz, 50 MHz and 100 MHz

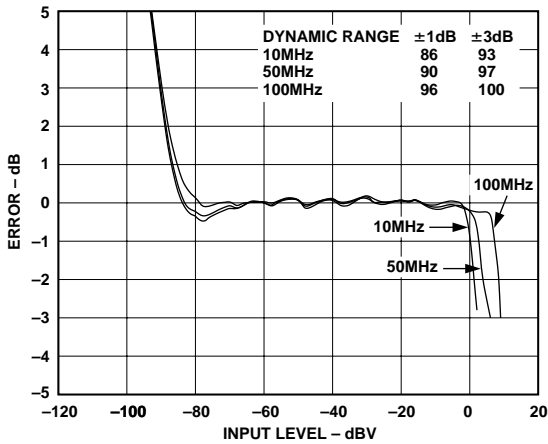


Figure 26. Log Linearity vs. Input Level at  $T_A = +25^\circ\text{C}$ , for Frequencies of 10 MHz, 50 MHz and 100 MHz

### Transfer Function in Terms of Slope and Intercept

The transfer function of the AD8306 is characterized in terms of its Slope and Intercept. The logarithmic slope is defined as the change in the RSSI output voltage for a 1 dB change at the input. For the AD8306 the slope is calibrated to be 20 mV/dB.

The intercept is the point at which the extrapolated linear response would intersect the horizontal axis. For the AD8306 the intercept is calibrated to be -108 dBV (-95 dBm). Using the slope and intercept, the output voltage can be calculated for any input level within the specified input range using the equation:

$$V_{OUT} = V_{SLOPE} \times (P_{IN} - P_O) \quad (2)$$

where  $V_{OUT}$  is the demodulated and filtered RSSI output,  $V_{SLOPE}$  is the logarithmic slope, expressed in V/dB,  $P_{IN}$  is the input signal, expressed in decibels relative to some reference level (either dBm or dBV in this case) and  $P_O$  is the logarithmic intercept, expressed in decibels relative to the same reference level.

For example, for an input level of -33 dBV (-20 dBm), the output voltage will be

$$V_{OUT} = 0.02 \text{ V/dB} \times (-33 \text{ dBV} - (-108 \text{ dBV})) = 1.5 \text{ V} \quad (3)$$

The most widely used convention in RF systems is to specify power in dBm, that is, decibels above 1 mW in 50 Ω. Specification of log amp input level in terms of power is strictly a concession to popular convention; they do not respond to power (tacitly “power absorbed at the input”), but to the input voltage. The use of dBV, defined as decibels with respect to a 1 V rms sine wave, is more precise, although this is still not unambiguous because waveform is also involved in the response of a log amp, which, for a complex input (such as a CDMA signal) will not follow the rms value exactly. Since most users specify RF signals in terms of power—more specifically, in dBm/50 Ω—we use both dBV and dBm in specifying the performance of the AD8306, showing equivalent dBm levels for the special case of a 50 Ω environment. Values in dBV are converted to dBm re 50 Ω by adding 13.

### Output Response Time and $C_F$

The RSSI output has a low-pass corner frequency of 3.5 MHz, which results in a 10% to 90% rise time of 73 ns. For low frequency applications, the corner frequency can be reduced by adding an external capacitor,  $C_F$ , between FLTR (Pin 10) and VLOG (Pin 16) as shown in Figure 24. For example, an external 33 pF will reduce the corner frequency to 350 kHz, while 360 pF will set it to 35 kHz, in each case with an essentially one-pole response.

### Using the Limiter

Figure 27 shows the basic connections for operating the limiter and the log output concurrently. The limiter output is a pair of differential currents of magnitude,  $I_{OUT}$ , from high impedance (open-collector) sources. These are converted to equal-amplitude voltages by supply-referenced load resistors,  $R_{LOAD}$ . The limiter output current is set by  $R_{LIM}$ , the resistor connected between Pin 9 (LMDR) and ground. The limiter output current is set according the equation:

$$I_{OUT} = -400 \text{ mV}/R_{LIM} \quad (5)$$

and has an absolute accuracy of ±5%.

The supply referenced voltage on each of the limiter pins will thus be given by:

$$V_{LIM} = V_S - 400 \text{ mV} \times R_{LOAD}/R_{LIM} \quad (6)$$

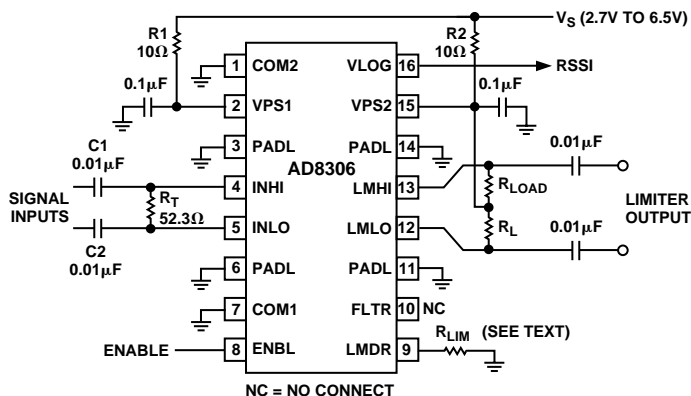


Figure 27. Basic Connections for Operating the Limiter

Depending on the application, the resulting voltage may be used in a fully balanced or unbalanced manner. It is good practice to retain both load resistors, even when only one output pin is used. These should always be returned to the same well decoupled node on the PC board (see layout of evaluation board). The unbalanced, or single-sided mode, is more inclined to result in instabilities caused by the very high gain of the signal path. The limiter current may be set as high as 10 mA (which requires  $R_{LIM}$  to be 40  $\Omega$ ) and can be optionally increased somewhat beyond this level. It is generally inadvisable, however, to use a high bias current, since the gain of this wide bandwidth signal path is proportional to the bias current, and the risk of instability is elevated as  $R_{LIM}$  is reduced (recommended value is 400  $\Omega$ ).

However, as the size of  $R_{LOAD}$  is increased, the bandwidth of the limiter output decreases from 585 MHz for  $R_{LOAD} = R_{LIM} = 50 \Omega$  to 50 MHz for  $R_{LOAD} = R_{LIM} = 400 \Omega$  (bandwidth = 210 MHz for  $R_{LOAD} = R_{LIM} = 100 \Omega$  and 100 MHz for  $R_{LOAD} = R_{LIM} = 200 \Omega$ ). As a result, the minimum necessary limiter output level should be chosen while maintaining the required limiter bandwidth. For  $R_{LIM} = R_{LOAD} = 50 \Omega$ , the limiter output is specified for input levels between -78 dBV (-65 dBm) and +9 dBV (+22 dBm). The output of the limiter may be unstable for levels below -78 dBV (-65 dBm). However, keeping  $R_{LIM}$  above 100  $\Omega$  will make instabilities on the output less likely for input levels below -78 dBV.

A transformer or a balun (e.g., MACOM part number ETC1-1-13) can be used to convert the differential limiter output voltages to a single-ended signal.

### Input Matching

Where either a higher sensitivity or a better high frequency match is required, an input matching network is valuable. Using a flux-coupled transformer to achieve the impedance transformation also eliminates the need for coupling capacitors, lowers any dc offset voltages generated directly at the input, and usefully balances the drives to INHI and INLO, permitting full utilization of the unusually large input voltage capacity of the AD8306.

The choice of turns ratio will depend somewhat on the frequency. At frequencies below 30 MHz, the reactance of the input capacitance is much higher than the real part of the input impedance. In this frequency range, a turns ratio of 2:9 will lower the effective input impedance to 50  $\Omega$  while raising the input voltage by 13 dB. However, this does not lower the effect of the short circuit noise voltage by the same factor, since there

will be a contribution from the input noise current. Thus, the total noise will be reduced by a smaller factor. The intercept at the primary input will be lowered to -121 dBV (-108 dBm).

Impedance matching and drive balancing using a flux-coupled transformer is useful whenever broadband coupling is required. However, this may not always be convenient. At high frequencies, it will often be preferable to use a narrow-band matching network, as shown in Figure 28, which has several advantages. First, the same voltage gain can be achieved, providing increased sensitivity, but now a measure of selectivity is simultaneously introduced. Second, the component count is low: two capacitors and an inexpensive chip inductor are needed. Third, the network also serves as a balun. Analysis of this network shows that the amplitude of the voltages at INHI and INLO are quite similar when the impedance ratio is fairly high (i.e., 50  $\Omega$  to 1000  $\Omega$ ).

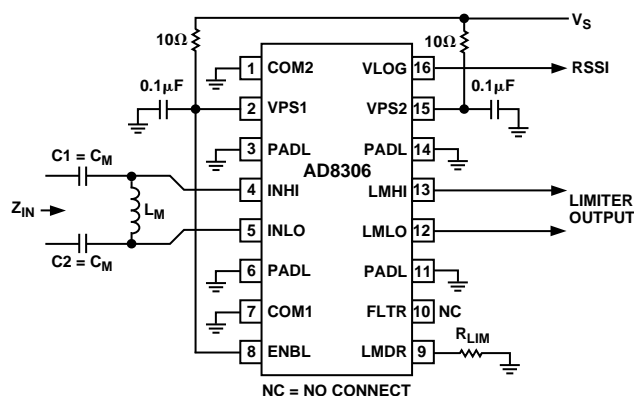


Figure 28. High Frequency Input Matching Network

Figure 29 shows the response for a center frequency of 100 MHz. The response is down by 50 dB at one-tenth the center frequency, falling by 40 dB per decade below this. The very high frequency attenuation is relatively small, however, since in the limiting case it is determined simply by the ratio of the AD8306's input capacitance to the coupling capacitors. Table I provides solutions for a variety of center frequencies  $f_c$  and matching from impedances  $Z_{IN}$  of nominally 50  $\Omega$  and 100  $\Omega$ . Exact values are shown, and some judgment is needed in utilizing the nearest standard values.

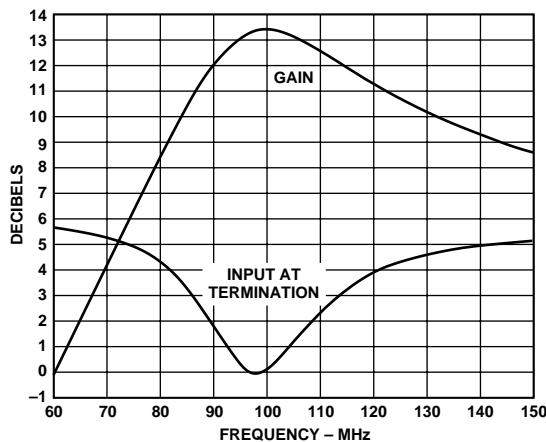


Figure 29. Response of 100 MHz Matching Network

# AD8306

Table I.

$f_C$ MHz	Match to 50 $\Omega$ (Gain = 13 dB)		Match to 100 $\Omega$ (Gain = 10 dB)	
	$C_M$ pF	$L_M$ nH	$C_M$ pF	$L_M$ nH
10	140	3500	100.7	4790
10.7	133	3200	94.1	4460
15	95.0	2250	67.1	3120
20	71.0	1660	50.3	2290
21.4	66.5	1550	47.0	2120
25	57.0	1310	40.3	1790
30	47.5	1070	33.5	1460
35	40.7	904	28.8	1220
40	35.6	779	25.2	1047
45	31.6	682	22.4	912
50	28.5	604	20.1	804
60	23.7	489	16.8	644
80	17.8	346	12.6	448
100	14.2	262	10.1	335
120	11.9	208	8.4	261
150	9.5	155	6.7	191
200	7.1	104	5.03	125
250	5.7	75.3	4.03	89.1
300	4.75	57.4	3.36	66.8
350	4.07	45.3	2.87	52.1
400	3.57	36.7	2.52	41.8
450	3.16	30.4	2.24	34.3
500	2.85	25.6	2.01	28.6

### General Matching Procedure

For other center frequencies and source impedances, the following method can be used to calculate the basic matching parameters.

#### Step 1: Tune Out $C_{IN}$

At a center frequency  $f_C$ , the shunt impedance of the input capacitance  $C_{IN}$  can be made to disappear by resonating with a temporary inductor  $L_{IN}$ , whose value is given by

$$L_{IN} = 1 / \{ (2 \pi f_C)^2 C_{IN} \} = 10^{10} / f_C^2 \quad (7)$$

when  $C_{IN} = 2.5$  pF. For example, at  $f_C = 100$  MHz,  $L_{IN} = 1$   $\mu$ H.

#### Step 2: Calculate $C_O$ and $L_O$

Now having a purely resistive input impedance, we can calculate the nominal coupling elements  $C_O$  and  $L_O$ , using

$$C_O = \frac{1}{2 \pi f_C \sqrt{(R_{IN} R_M)}}; \quad L_O = \frac{\sqrt{(R_{IN} R_M)}}{2 \pi f_C} \quad (8)$$

For the AD8306,  $R_{IN}$  is 1 k $\Omega$ . Thus, if a match to 50  $\Omega$  is needed, at  $f_C = 100$  MHz,  $C_O$  must be 7.12 pF and  $L_O$  must be 356 nH.

#### Step 3: Split $C_O$ Into Two Parts

Since we wish to provide the fully-balanced form of network shown in Figure 28, two capacitors  $C_1 = C_2$  each of nominally twice  $C_O$ , shown as  $C_M$  in the figure, can be used. This requires a value of 14.24 pF in this example. Under these conditions, the voltage amplitudes at INHI and INLO will be similar. A somewhat better balance in the two drives may be achieved when  $C_1$  is made slightly larger than  $C_2$ , which also allows a wider range of choices in selecting from standard values. For example, capacitors of  $C_1 = 15$  pF and  $C_2 = 13$  pF may be used (making  $C_O = 6.96$  pF).

#### Step 4: Calculate $L_M$

The matching inductor required to provide both  $L_{IN}$  and  $L_O$  is just the parallel combination of these:

$$L_M = L_{IN} L_O / (L_{IN} + L_O) \quad (9)$$

With  $L_{IN} = 1$   $\mu$ H and  $L_O = 356$  nH, the value of  $L_M$  to complete this example of a match of 50  $\Omega$  at 100 MHz is 262.5 nH. The nearest standard value of 270 nH may be used with only a slight loss of matching accuracy. The voltage gain at resonance depends only on the ratio of impedances, as is given by

$$GAIN = 20 \log \left( \sqrt{\frac{R_{IN}}{R_S}} \right) = 10 \log \left( \frac{R_{IN}}{R_S} \right) \quad (10)$$

### Altering the Logarithmic Slope

Simple schemes can be used to increase and decrease the logarithmic slope as shown in Figure 30. For the AD8306, only power, ground and logarithmic output connections are shown; refer to Figure 24 for complete circuitry. In Figure 30(a), the op amp's gain of +2 increases the slope to 40 mV/dB. In Figure 30(b), the AD8031 buffers a resistive divider to give a slope of

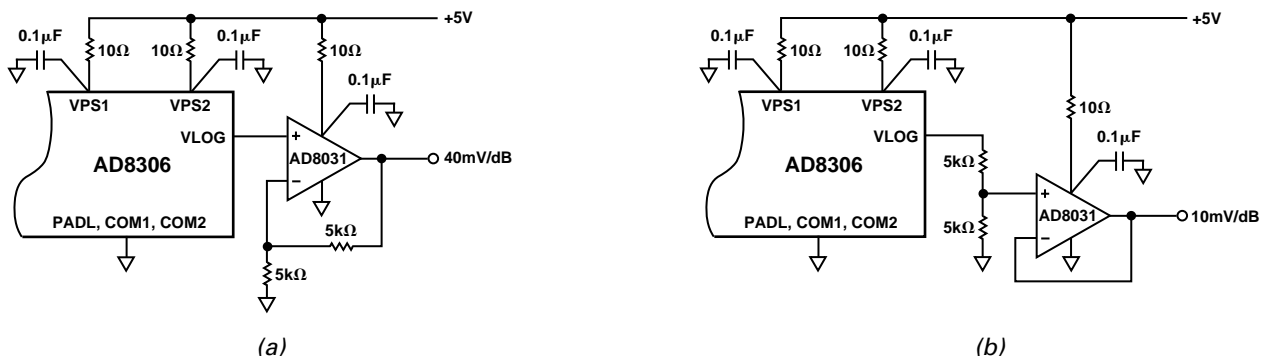


Figure 30. Altering the Logarithmic Slope

10 mV/dB The AD8031 rail-to-rail op amp, used in both examples, can swing from 50 mV to 4.95 mV on a single +5 V supply. If high output current is required (> 10 mA), the AD8051, which also has rail-to-rail capability but can deliver up to 45 mA of output current, can be used.

## APPLICATIONS

The AD8306 is a versatile and easily applied log-limiting amplifier. Being complete, it can be used with very few external components, and most applications can be accommodated using the simple connections shown in the preceding section. A few examples of more specialized applications are provided here.

### High Output Limiter Loading

The AD8306 can generate a fairly large output power at its differential limiter output interface. This may be coupled into a 50 Ω grounded load using the narrow-band coupling network following similar lines to those provided for input matching. Alternatively, a flux-linked transformer, having a center-tapped primary, may be used. Even higher output powers can be obtained using emitter-followers. In Figure 31, the supply voltage to the AD8306 is dropped from 5 V to about 4.2 V, by the diode. This increases the available swing at each output to about 2 V. Taking both outputs differentially, a square wave output of 4 V p-p can be generated.

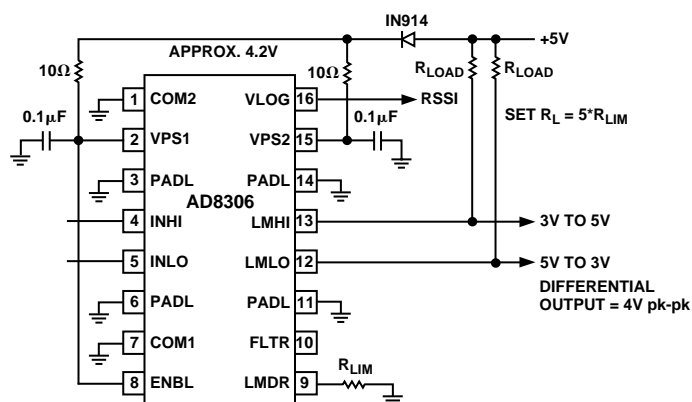


Figure 31. Increasing Limiter Output Voltage

When operating at high output power levels and high frequencies, very careful attention must be paid to the issue of stability. Oscillation is likely to be observed when the input signal level is low, due to the extremely high gain-bandwidth product of the AD8306 under such conditions. These oscillations will be less evident when signal-balancing networks are used, operating at frequencies below 200 MHz, and they will generally be fully quenched by the signal at input levels of a few dB above the noise floor.

### Modulated Limiter Output

The limiter output stage of the AD8306 also provides an analog multiplication capability: the amplitude of the output square wave can be controlled by the current withdrawn from LMDR (Pin 9). An analog control input of 0 V to +1 V is used to generate an exactly-proportional current of 0 mA to 10 mA in the npn transistor, whose collector is held at a fixed voltage of ~400 mV by the internal bias in the AD8306. When the input signal is above the limiting threshold, the output will then be a square-wave whose amplitude is proportional to the control bias.

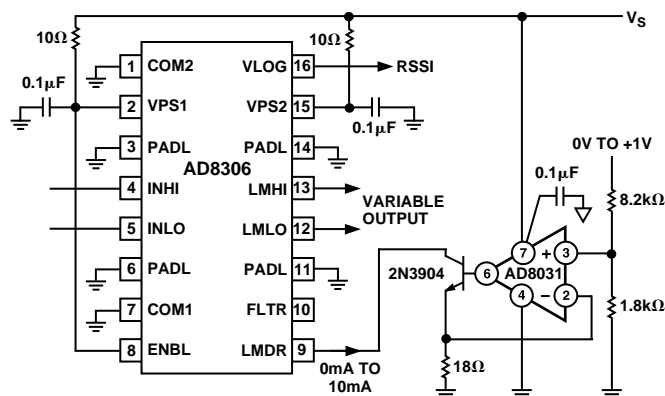


Figure 32. Variable Limiter Output Programming

### Effect of Waveform Type on Intercept

The AD8306 fundamentally responds to voltage and not to power. A direct consequence of this characteristic is that input signals of equal rms power, but differing crest factors, will produce different results at the log amp's output.

The effect of differing signal waveforms is to shift the effective value of the log amp's intercept. Graphically, this looks like a vertical shift in the log amp's transfer function. The device's logarithmic slope however is not affected. For example, consider the case of the AD8306 being alternately fed by an unmodulated sine wave and by a single CDMA channel of the same rms power. The AD8306's output voltage will differ by the equivalent of 3.55 dB (71 mV) over the complete dynamic range of the device (the output for a CDMA input being lower).

Table II shows the correction factors that should be applied to measure the rms signal strength of a various signal types. A *sine wave* input is used as a reference. To measure the rms power of a square wave, for example, the mV equivalent of the dB value given in the table (20 mV/dB times 3.01 dB) should be subtracted from the output voltage of the AD8306.

Table II. Shift in AD8306 Output for Signals with Differing Crest Factors

Signal Type	Correction Factor (Add to Output Reading)
Sine Wave	0 dB
Square Wave or DC	-3.01 dB
Triangular Wave	+0.9 dB
GSM Channel (All Time Slots On)	+0.55 dB
CDMA Channel (Forward Link, 9 Channels On)	+3.55 dB
CDMA Channel (Reverse Link)	+0.5 dB
PDC Channel (All Time Slots On)	+0.58 dB
Gaussian Noise	+2.51 dB

### Evaluation Board

An evaluation board, carefully laid out and tested to demonstrate the specified high speed performance of the AD8306 is available. Figure 33 shows the schematic of the evaluation board, which fairly closely follows the basic connections schematic shown in Figure 27. For ordering information, please refer to the Ordering Guide. Links, switches and component settings for different setups are described in Table III.

# AD8306

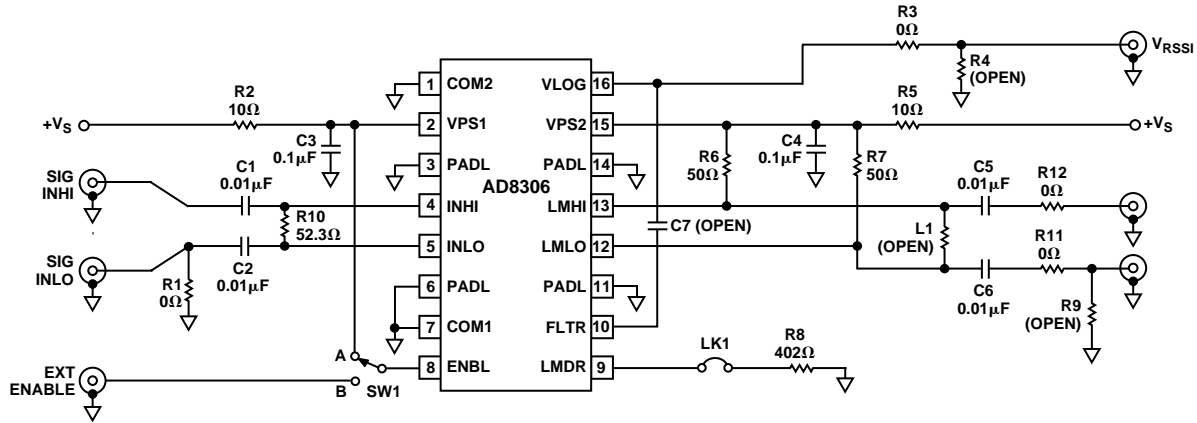


Figure 33. Evaluation Board Schematic

Table III. Evaluation Board Setup Options

Component	Function	Default Condition
SW1	<b>Device Enable.</b> When in Position A, the ENBL pin is connected to +V <sub>S</sub> and the AD8306 is in normal operating mode. In Position B, the ENBL pin is connected to an SMA connector labeled Ext Enable. A signal can be applied to this connector to enable/disable the AD8306.	SW1 = A
R1	This pad is used to ac-couple INLO to ground for single-ended input drive. To drive the AD8306 differentially, R1 should be removed.	R1 = 0 Ω
R/L, C1, C2	<b>Input Interface.</b> The 52.3 Ω resistor in position R10, along with C1 and C2, create a high-pass input filter whose corner frequency (640 kHz) is equal to $1/(2\pi RC)$ , where $C = (C1)/2$ and R is the parallel combination of 52.3 Ω and the AD8306's input impedance of 1000 Ω. Alternatively, the 52.3 Ω resistor can be replaced by an inductor to form an input matching network. See Input Matching Network section for more details.	R10 = 52.3 Ω C1 = C2 = 0.01 μF
R3/R4	<b>Slope Adjust.</b> A simple slope adjustment can be implemented by adding a resistive divider at the VLOG output. R3 and R4, whose sum should be about 1 kΩ, and never less than 40 Ω (see specs), set the slope according to the equation: $Slope = 20 \text{ mV/dB} \times R4/(R3 + R4)$ .	R3 = 0 Ω R4 = ∞
L1, C5, C6	<b>Limiter Output Coupling.</b> C5 and C6 ac-couple the limiter's differential outputs. By adjusting these values and installing an inductor in L1, an output matching network can be implemented. To convert the limiter's differential output to single-ended, R11 and R12 (nominally 0 Ω) can be replaced with a surface mount balun such as the ETC1-1-13 (Macom). The balun can be grounded by soldering a 0 Ω into Position R9 (nominally open).	L1 = Open C5 = 0.01 μF C6 = 0.01 μF R9 = Open R10 = R11 = 0 Ω
R8, LK1	<b>Limiter Output Current.</b> With LK1 installed, R8 enables and sets the limiter output current. The limiter's output current is set according to the equation ( $I_{OUT} = 400 \text{ mV}/R8$ ). The limiter current can be as high as 10 mA (R8 = 40 Ω). To disable the limiter (recommended if the limiter is not being used), LK1 should be removed.	LK1 Installed. R8 = 402 Ω R6, R7 (Limited Load Resistors) = 50 Ω
C7	<b>RSSI Bandwidth Adjust.</b> The addition of C7 (farads) will lower the RSSI bandwidth of the VLOG output according to the equation: $f_{CORNER} (Hz) = 12.7 \times 10^{-6}/(C7 + 3.5 \times 10^{-12})$ .	C7 = Open

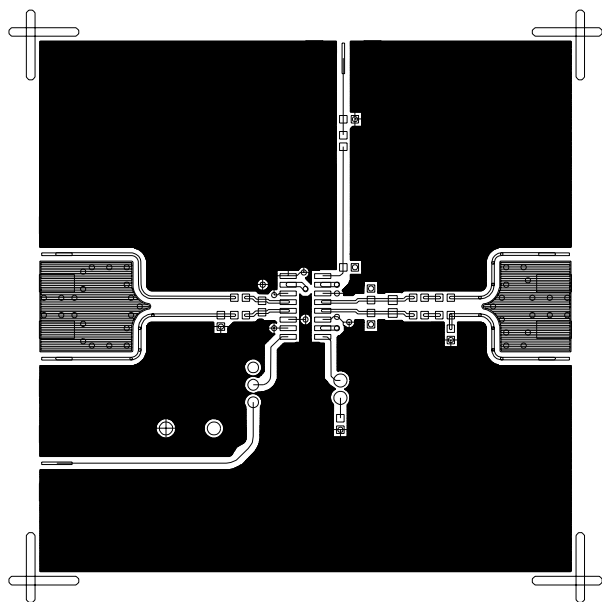


Figure 34. Layout of Signal Layer

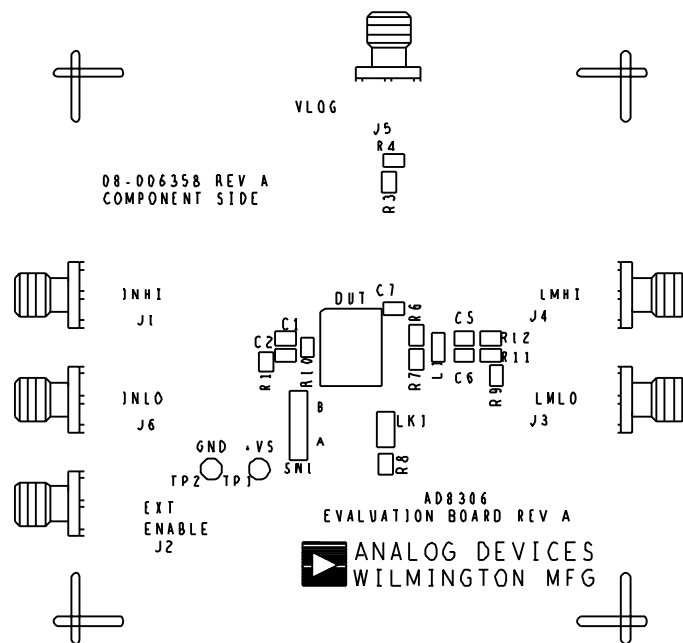


Figure 36. Signal Layer Silkscreen

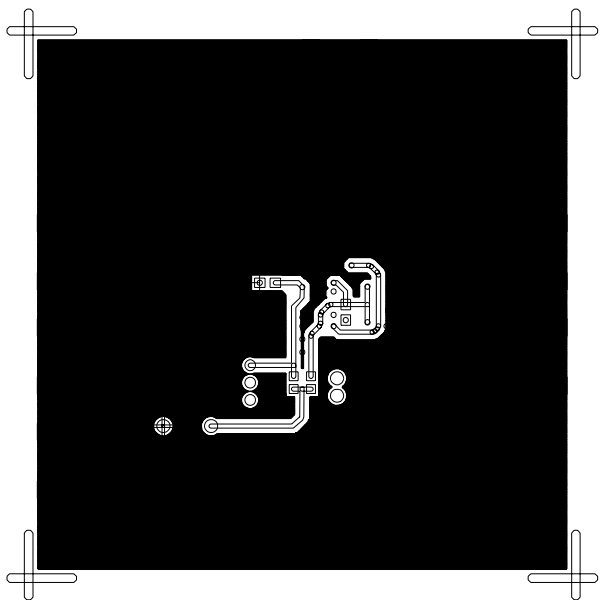


Figure 35. Layout of Power Layer

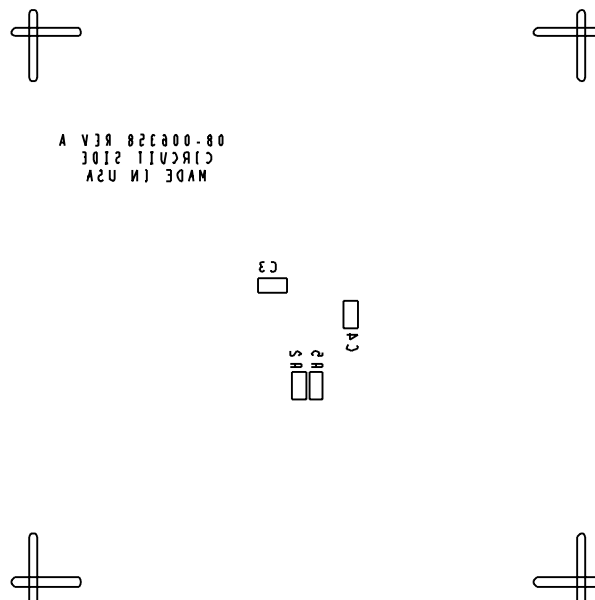
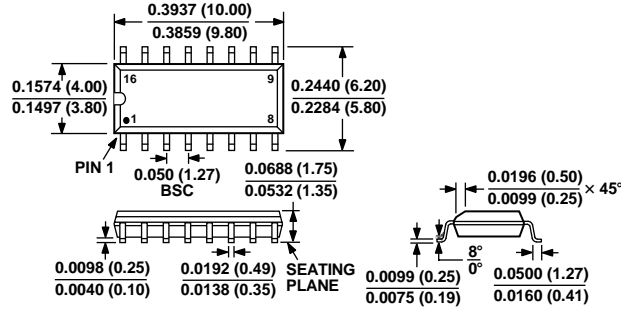


Figure 37. Power Layer Silkscreen

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

16-Lead Narrow Body SO  
(SO-16)





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