

# Octal 8-Bit TrimDAC with Power Shutdown

# AD8801/AD8803

### FEATURES

Low Cost Replaces Eight Potentiometers Eight Individually Programmable Outputs Three-Wire Serial Input Power Shutdown  $\leq 25 \ \mu$ W Including I<sub>DD</sub> and I<sub>REF</sub> Midscale Preset, AD8801 Separate V<sub>REFL</sub> Range Setting, AD8803 +3 V to +5 V Single Supply Operation

### **APPLICATIONS**

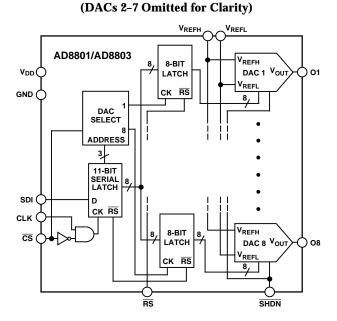
Automatic Adjustment Trimmer Potentiometer Replacement Video and Audio Equipment Gain and Offset Adjustment Portable and Battery Operated Equipment

### **GENERAL DESCRIPTION**

The AD8801/AD8803 provides eight digitally controlled dc voltage outputs. This potentiometer divider TrimDAC<sup>®</sup> allows replacement of the mechanical trimmer function in new designs. The AD8801/AD8803 is ideal for dc voltage adjustment applications.

Easily programmed by serial interfaced microcontroller ports, the AD8801 with its midscale preset is ideal for potentiometer replacement where adjustments start at a nominal value. Applications such as gain control of video amplifiers, voltage controlled frequencies and bandwidths in video equipment, geometric correction and automatic adjustment in CRT computer graphic displays are a few of the many applications ideally suited for these parts. The AD8803 provides independent control of both the top and bottom end of the potentiometer divider allowing a separate zero-scale voltage setting determined by the  $V_{REFL}$  pin. This is helpful for maximizing the resolution of devices with a limited allowable voltage control range.

### FUNCTIONAL BLOCK DIAGRAM



Internally the AD8801/AD8803 contain eight voltage output digital-to-analog converters, sharing a common reference voltage input.

Each DAC has its own DAC register that holds its output state. These DAC registers are updated from an internal serial-to-parallel shift register that is loaded from a standard three-wire serial input digital interface. Eleven data bits make up the data word clocked into the serial input register. This data word is decoded where the first 3 bits determine the address of the DAC register to be loaded with the last 8 bits of data. The AD8801/AD8803 consumes only 5  $\mu$ A from 5 V power supplies. In addition, in shutdown mode reference input current consumption is also reduced to 5  $\mu$ A while saving the DAC latch settings for use after return to normal operation.

The AD8801/AD8803 is available in 16-pin plastic DIP and the 1.5 mm height SO-16 surface mount packages.

See the AD8802/AD8804 for a twelve channel version of this product.

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### REV. A

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Parameter	Symbol	Conditions	Min	Typ <sup>1</sup>	Max	Units
STATIC ACCURACY Specifications Apply to All DACs Resolution Integral Nonlinearity Error Differential Nonlinearity Full-Scale Error Zero-Code Error DAC Output Resistance Output Resistance Match	$\begin{array}{c} N\\ INL\\ DNL\\ G_{FSE}\\ V_{ZSE}\\ R_{OUT}\\ \Delta R/R_{O} \end{array}$	Guaranteed Monotonic	8 -1.5 -1 -4 -0.5 3	$\pm 1/2$ $\pm 1/4$ -2.8 $\pm 0.1$ 5 1	+1.5 +1 +0.5 +0.5 8	Bits LSB LSB LSB LSB kΩ %
REFERENCE INPUT Voltage Range <sup>2</sup> Input Resistance Reference Input Capacitance <sup>3</sup>	$V_{ m REFH}$ $V_{ m REFL}$ $R_{ m REFH}$ $C_{ m REF0}$ $C_{ m REF1}$	Pin Available on AD8803 Only Digital Inputs = $55_{\rm H}$ , V <sub>REFH</sub> = V <sub>DD</sub> Digital Inputs All Zeros Digital Inputs All Ones	0 0	2 25 25	$V_{DD}$ $V_{DD}$	V V kΩ pF pF
DIGITAL INPUTS Logic High Logic Low Logic High Logic Low Input Current Input Capacitance <sup>3</sup>	V <sub>IH</sub> V <sub>IL</sub> V <sub>IH</sub> V <sub>IL</sub> I <sub>L</sub> C <sub>IL</sub>	$\begin{split} V_{\rm DD} &= +5 \ V \\ V_{\rm DD} &= +5 \ V \\ V_{\rm DD} &= +3 \ V \\ V_{\rm DD} &= +3 \ V \\ V_{\rm DD} &= +3 \ V \\ V_{\rm IN} &= 0 \ V \ or \ +5 \ V \end{split}$	2.4 2.1	5	0.8 0.6 ±1	V V V V μA pF
POWER SUPPLIES <sup>4</sup> Power Supply Range Supply Current (CMOS) Supply Current (TTL) Shutdown Current Power Dissipation Power Supply Sensitivity Power Supply Sensitivity	V <sub>DD</sub> Range I <sub>DD</sub> I <sub>DD</sub> I <sub>REFH</sub> P <sub>DISS</sub> PSRR PSRR	$\begin{split} V_{IH} &= V_{DD} \text{ or } V_{IL} = 0 \text{ V} \\ V_{IH} &= 2.4 \text{ V or } V_{IL} = 0.8 \text{ V},  V_{DD} \text{= } +5.5 \text{ V} \\ \hline \text{SHDN} &= 0 \\ V_{IH} &= V_{DD} \text{ or } V_{IL} = 0 \text{ V},  V_{DD} \text{= } +5.5 \text{ V} \\ V_{DD} &= 5 \text{ V} \pm 10\%,  V_{REFH} \text{= } +4.5 \text{ V} \\ V_{DD} &= 3 \text{ V} \pm 10\%,  V_{REFH} \text{= } +2.7 \text{ V} \end{split}$	2.7	0.01 1 0.01 0.001 0.01	5.5 5 4 5 27.5 0.002	V μA μA μW %/% %/%
DYNAMIC PERFORMANCE <sup>3</sup> V <sub>OUT</sub> Settling Time (Positive or Negative) Crosstalk	t <sub>s</sub> CT	±1/2 LSB Error Band See Note 5, f = 100 kHz		0.6 50		μs dB
SWITCHING CHARACTERISTICS <sup>3, 6</sup> Input Clock Pulse Width         Data Setup Time         Data Hold Time         CS         Setup Time         CS         High Pulse Width         Reset Pulse Width         CLK Rise to CS Rise Hold Time         CS         Rise to Next Rising Clock	$\begin{array}{c} t_{CH}, \ t_{CL} \\ t_{DS} \\ t_{DH} \\ t_{CSS} \\ t_{CSW} \\ t_{RS} \\ t_{CSH} \\ t_{CS1} \end{array}$	Clock Level High or Low	15 5 5 10 10 60 15 10			ns ns ns ns ns ns ns ns ns

NOTES

<sup>1</sup>Typical values represent average readings measured at +25 °C.

 $^{2}V_{REFH}^{2}$  can be any value between GND and  $V_{DD}$ , for the AD8803  $V_{REFL}$  can be any value between GND and  $V_{DD}$ .

<sup>3</sup>Guaranteed by design and not subject to production test.

<sup>4</sup>Digital Input voltages  $V_{IN} = 0$  V or  $V_{DD}$  for CMOS condition. DAC outputs unloaded.  $P_{DISS}$  is calculated from  $(I_{DD} \times V_{DD})$ .

 $^5\text{Measured}$  at a  $V_{\text{OUT}}$  pin where an adjacent  $V_{\text{OUT}}$  pin is making a full-scale voltage change.

<sup>6</sup>See timing diagram for location of measured values. All input control voltages are specified with  $t_R = t_F = 2$  ns (10% to 90% of  $V_{DD}$ ) and timed from a voltage level of 1.6 V.

Specifications subject to change without notice.

### ABSOLUTE MAXIMUM RATINGS

$(T_A = +25^{\circ}C, \text{ unless otherwise noted})$
V <sub>DD</sub> to GND
$V_{REFX}$ to GND 0 V, $V_{DD}$
Outputs (Ox) to GND 0 V, V <sub>DD</sub>
Digital Input Voltage to GND 0 V, V <sub>DD</sub>
Operating Temperature Range40°C to +85°C
Maximum Junction Temperature (T <sub>J</sub> MAX)+150°C
Storage Temperature65°C to +150°C
Lead Temperature (Soldering, 10 sec) +300°C
Package Power Dissipation $\dots \dots \dots$
Thermal Resistance $\hat{\theta}_{JA}$
SOIC (SO-16)
P-DIP (N-16) 57°C/W

#### **AD8801 PIN DESCRIPTIONS**

Pin	Name	Description
1	V <sub>REFH</sub>	Common DAC Reference Input
2	01	DAC Output #1, Addr = $000_2$
3	O2	DAC Output #2, Addr = $001_2$
4	O3	DAC Output #3, Addr = $010_2$
5	O4	DAC Output #4, Addr = $011_2$
6	SHDN	Reference input open circuit, active low, all DAC outputs open circuit. DAC latch settings maintained.
7	CS	Chip Select Input, active low. When $\overline{CS}$ returns high, data in the serial input register is decoded based on the address bits and loaded into the target DAC register.
8	GND	Ground
9	CLK	Serial Clock Input, Positive Edge Triggered
10	SDI	Serial Data Input
11	O5	DAC Output #5, Addr = $100_2$
12	O6	DAC Output #6, Addr = $101_2$
13	07	DAC Output #7, Addr = $110_2$
14	08	DAC Output #8, Addr = $111_2$
15	RS	Asynchronous preset to midscale output setting, active low. Loads all DAC latches with $80_{\rm H}$ .
16	V <sub>DD</sub>	Positive power supply, specified for operation at both $+3$ V and $+5$ V.

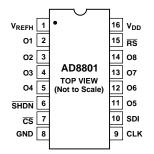
### **ORDERING GUIDE**

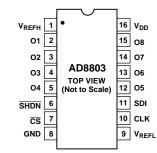
Model	FTN	Temperature	Package Description	Package Option
AD8801AN	RS	-40°C to +85°C	SO-16	N-16
AD8801AR	RS	-40°C to +85°C		R-16A
AD8803AN	REFL	-40°C to +85°C		N-16
AD8803AR	REFL	-40°C to +85°C		R-16A

### **AD8803 PIN DESCRIPTIONS**

Pin	Name	Description
1	V <sub>REFH</sub>	Common High-Side DAC Reference Input
2	01	DAC Output #1, Addr = $000_2$
3	O2	DAC Output #2, Addr = $001_2$
4	O3	DAC Output #3, Addr = $010_2$
5	O4	DAC Output #4, Addr = $011_2$
6	SHDN	Reference inputs open circuit, active low, all
		DAC outputs open circuit. DAC latch settings maintained.
7	CS	Chip Select Input, active low. When $\overline{CS}$ returns high, data in the serial input register is decoded based on the address bits and loaded into the target DAC register.
8	GND	Ground
9	V <sub>REFL</sub>	Common Low-Side DAC Reference Input
10	CLK	Serial Clock Input, Positive Edge Triggered
11	SDI	Serial Data Input
12	O5	DAC Output #5, Addr = $100_2$
13	O6	DAC Output #6, Addr = $101_2$
14	07	DAC Output #7, Addr = $110_2$
15	O8	DAC Output #8, Addr = $111_2$
16	V <sub>DD</sub>	Positive power supply, specified for operation at both $+3$ V and $+5$ V.

### **PIN CONFIGURATIONS**

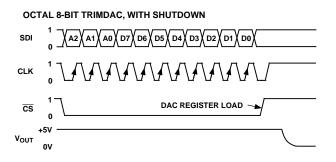


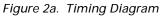


### CAUTION

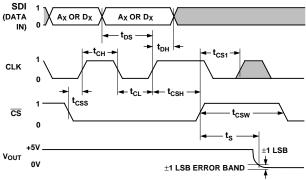
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although these devices feature proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.







DETAIL SERIAL DATA INPUT TIMING (RS = "1")





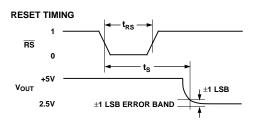


Figure 2c. Reset Timing Diagram

Table I. Serial-Data Word Format

ADD										
<b>B10</b>	<b>B9</b>	<b>B8</b>	<b>B</b> 7	<b>B6</b>	<b>B5</b>	<b>B4</b>	<b>B3</b>	<b>B2</b>	<b>B1</b>	<b>B0</b>
		A0 LSB			D5	D4	D3	D2	D1	D0 LSB
$2^{10}$	$2^9$	2 <sup>8</sup>	$2^{7}$	2 <sup>6</sup>	$2^5$	$2^4$	<b>2</b> <sup>3</sup>	$2^2$	$2^1$	

### **OPERATION**

The AD8801/AD8803 provides eight channels of programmable voltage output adjustment capability. Changing the programmed output voltage of each TrimDAC is accomplished by clocking in an 11-bit serial data word into the SDI (Serial Data Input) pin. The format of this data word is three address bits, MSB first, followed by eight data bits, MSB first. Table I provides the serial register data word format. The AD8801/AD8803 has the

following address assignments for the ADDR decode which determines the location of DAC register receiving the serial register data in bits B7 through B0:

$$DAC # = A2 \times 4 + A1 \times 2 + A0 + 1$$

DAC outputs can be changed one at a time in random sequence. The fast serial-data loading of 33 MHz makes it possible to load all eight DACs in as little time as  $3 \mu s$  ( $12 \times 8 \times 30$  ns). The exact timing requirements are shown in Figure 2.

The AD8801 offers a midscale preset activated by the  $\overline{\text{RS}}$  pin simplifying initial setting conditions at first power up. The AD8803 has both a  $V_{\text{REFH}}$  and a  $V_{\text{REFL}}$  pin to establish independent positive full-scale and zero-scale settings to optimize resolution. Both parts offer a power shutdown SHDN that places the DAC structure in a zero power consumption state resulting in only leakage currents being consumed from the power supply,  $V_{\text{REF}}$  inputs, and all 8 outputs. In shutdown mode the DACx latch settings are maintained. When returning to operational mode from power shutdown the DAC outputs return to their previous voltage settings.

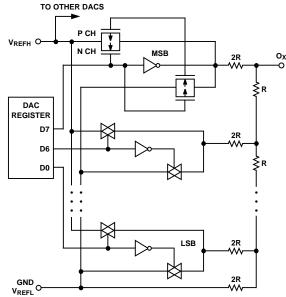


Figure 3. AD8801/AD8803 Equivalent TrimDAC Circuit

### **PROGRAMMING THE OUTPUT VOLTAGE**

The output voltage range is determined by the external reference connected to  $V_{REFH}$  and  $V_{REFL}$  pins. See Figure 3 for a simplified diagram of the equivalent DAC circuit. In the case of the AD8801, its  $V_{REFL}$  is internally connected to GND and therefore cannot be offset.  $V_{REFH}$  can be tied to  $V_{DD}$  and  $V_{REFL}$  can be tied to GND establishing a basic rail-to-rail voltage output programming range. Other output ranges are established by the use of different external voltage references. The general transfer equation that determines the programmed output voltage is:

$$V_O(Dx) = (Dx)/256 \times (V_{REFH} - V_{REFL}) + V_{REFL}$$
(1)

where Dx is the data contained in the 8-bit DACx latch.

For example, when  $V_{REFH} = +5$  V and  $V_{REFL} = 0$  V the following output voltages will be generated for the following codes:

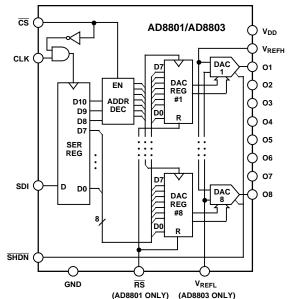
D	V <sub>OX</sub>	Output State ( $V_{REFH} = +5 V$ , $V_{REFL} = 0 V$ )
255	4.98 V	Full-Scale
128	2.50 V	Half-Scale (Midscale Reset Value)
1	0.02 V	1 LSB
0	0.00 V	Zero-Scale

### **REFERENCE INPUTS (V<sub>REFH</sub>, V<sub>REFL</sub>)**

The reference input pins set the output voltage range of all eight DACs. In the case of the AD8801 only the V<sub>REFH</sub> pin is available to establish a user designed full-scale output voltage. The external reference voltage can be any value between 0 and  $V_{DD}$ but must not exceed the V<sub>DD</sub> supply voltage. In the case of the AD8803, which has access to the  $V_{REFL}$  which establishes the zero-scale output voltage, any voltage can be applied between 0 V and  $V_{DD}$ .  $V_{REFL}$  can be smaller or larger in voltage than V<sub>REFH</sub> since the DAC design uses fully bidirectional switches as shown in Figure 3. The input resistance to the DAC has a code dependent variation that has a nominal worst case measured at  $55_{\rm H}$ , which is approximately 2 k $\Omega$ . When V<sub>REFH</sub> is greater than  $V_{REFL}$ , the REFL reference must be able to sink current out of the DAC ladder, while the REFH reference is sourcing current into the DAC ladder. The DAC design minimizes reference glitch current maintaining minimum interference between DAC channels during code changes.

### DAC OUTPUTS (O1-O8)

The eight DAC outputs present a constant output resistance of approximately 5 k $\Omega$  independent of code setting. The distribution of R<sub>OUT</sub> from DAC to DAC typically matches within ±1%. However, device to device matching is process lot dependent having a ±20% variation. The change in R<sub>OUT</sub> with temperature has a 500 ppm/°C temperature coefficient. During power shutdown all eight outputs are open circuited.



(AD0001 ONE1) (AD0003 ONE)

Figure 4. Block Diagram

### DIGITAL INTERFACING

The AD8801/AD8803 contains a standard three-wire serial input control interface. The three inputs are clock (CLK),  $\overline{CS}$  and serial data input (SDI). The positive-edge sensitive CLK input requires clean transitions to avoid clocking incorrect data into the serial input register. Standard logic families work well. If mechanical switches are used for product evaluation, they should be debounced by a flip-flop or other suitable means. Figure 4 block diagram shows more detail of the internal digital circuitry. When  $\overline{CS}$  is taken active low, the clock can load data into the serial register on each positive clock edge, see Table II.

Table II. Input Logic Control Truth Table

<b>CS</b>	CLK	Register Activity
1	X	No effect.
0	Р	Shifts Serial Register one bit loading the
		next bit in from the SDI pin.
Р	X	Data is transferred from the serial register
		to the decoded DAC register. See Figure 5.

NOTE: P = positive edge, X = don't care.

The data setup and data hold times in the specification table determine the data valid time requirements. The last 11 bits of the data word entered into the serial register are held when  $\overline{CS}$  returns high. At the same time  $\overline{CS}$  goes high it gates the address decoder which enables one of the eight positive edge triggered DAC registers, see Figure 5 detail.

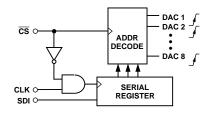
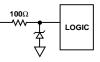


Figure 5. Equivalent Control Logic

The target DAC register is loaded with the last eight bits of the serial data word completing one DAC update. Eight separate 11-bit data words must be clocked in to change all eight output settings.

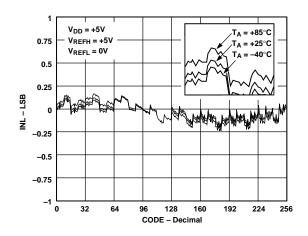
All digital inputs are protected with a series input resistor and parallel Zener ESD structure shown in Figure 6. This applies to digital input pins  $\overline{CS}$ , SDI,  $\overline{RS}$ ,  $\overline{SHDN}$ , CLK.



### Figure 6. Equivalent ESD Protection Circuit

Digital inputs can be driven by voltages exceeding the AD8801/ AD8803  $V_{\rm DD}$  value. This allows 5 V logic to interface directly to the part when it is operated at 3 V.

# AD8801/AD8803–Typical Performance Characteristics





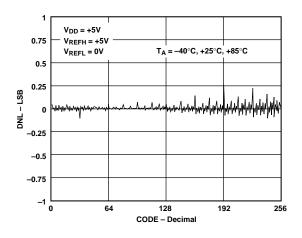


Figure 8. Differential Nonlinearity Error vs. Code

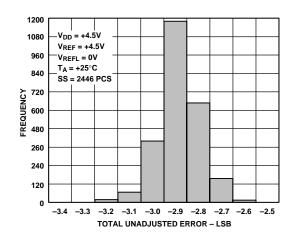


Figure 9. Total Unadjusted Error Histogram

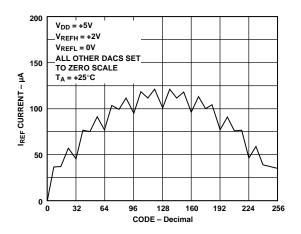


Figure 10. Input Reference Current vs. Code

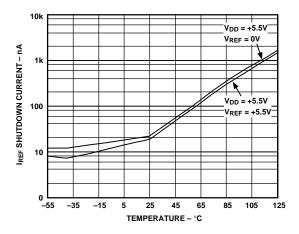


Figure 11. Shutdown Current vs. Temperature

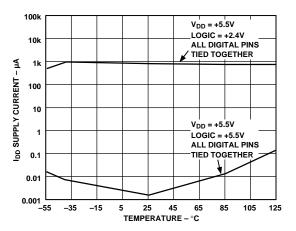


Figure 12. Supply Current vs. Temperature

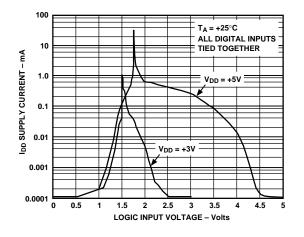


Figure 13. Supply Current vs. Logic Input Voltage

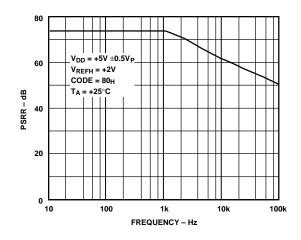


Figure 14. Power Supply Rejection vs. Frequency

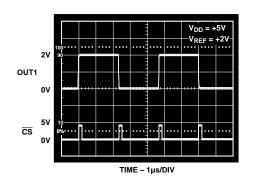


Figure 15. Large-Signal Settling Time

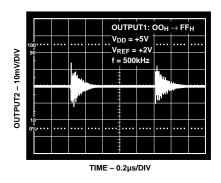


Figure 16. Adjacent Channel Clock Feedthrough

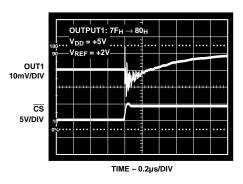


Figure 17. Midscale Transition

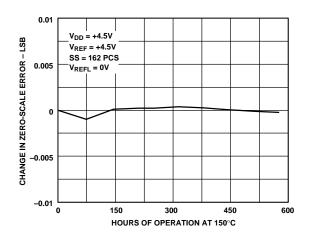


Figure 18. Zero-Scale Error Accelerated by Burn-In

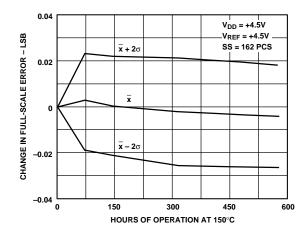


Figure 19. Full-Scale Error Accelerated by Burn-In

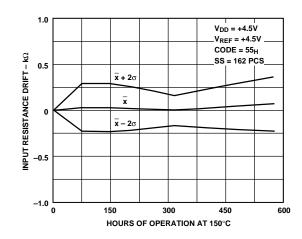


Figure 20. REF Input Resistance Accelerated by Burn-In

#### APPLICATIONS Supply Bypassing

Precision analog products, such as the AD8801/AD8803, require a well filtered power source. Since the AD8801/AD8803 operate from a single +3 V to +5 V supply, it seems convenient to simply tap into the digital logic power supply. Unfortunately, the logic supply is often a switch-mode design, which generates noise in the 20 kHz to 1 MHz range. In addition, fast logic gates can generate glitches hundred of millivolts in amplitude due to wiring resistances and inductances.

If possible, the AD8801/AD8803 should be powered directly from the system power supply. This arrangement, shown in Figure 21, will isolate the analog section from the logic switching transients. Even if a separate power supply trace is not available, however, generous supply bypassing will reduce supply-line induced errors. Local supply bypassing consisting of a 10  $\mu$ F tantalum electrolytic in parallel with a 0.1  $\mu$ F ceramic capacitor is recommended (Figure 22).

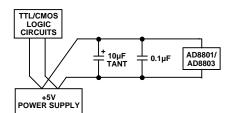


Figure 21. Use Separate Traces to Reduce Power Supply Noise

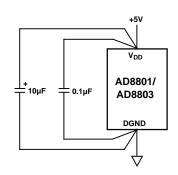


Figure 22. Recommended Supply Bypassing for the AD8801/AD8803

#### Buffering the AD8801/AD8803 Output

In many cases, the nominal 5 k $\Omega$  output impedance of the AD8801/AD8803 is sufficient to drive succeeding circuitry. If a lower output impedance is required, an external amplifier can be added. Several examples are shown in Figure 23. One amplifier of an OP291 is used as a simple buffer to reduce the output resistance of DAC A. The OP291 was chosen primarily for its rail-to-rail input and output operation, but it also offers operation to less than 3 V, low offset voltage, and low supply current.

The next two DACs, B and C, are configured in a summing arrangement where DAC C provides the coarse output voltage setting and DAC B can be used for fine adjustment. The insertion of R1 in series with DAC B attenuates its contribution to the voltage sum node at the DAC C output.

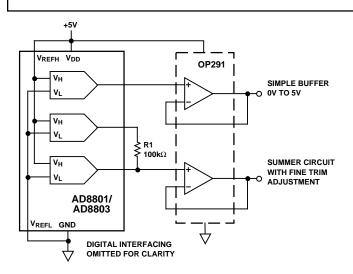


Figure 23. Buffering the AD8801/AD8803 Output

### **Increasing Output Voltage Swing**

An external amplifier can also be used to extend the output voltage swing beyond the power supply rails of the AD8801/AD8803. This technique permits an easy digital interface for the DAC, while expanding the output swing to take advantage of higher voltage external power supplies. For example, DAC A of Figure 24 is configured to swing from -5 V to +5 V. The actual output voltage is given by:

$$V_{OUT} = \left(1 + \frac{R_F}{R_S}\right) \times \left(\frac{D}{256} \times 5 V\right) - 5 V$$

Where D is the DAC input value (i.e., 0 to 255). This circuit can be combined with the "fine/coarse" circuit of Figure 23 if, for example, a very accurate adjustment around 0 V is desired.

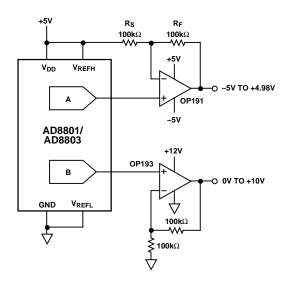


Figure 24. Increasing Output Voltage Swing

DAC B of Figure 24 is in a noninverting gain of two configuration, which increases the available output swing to +10 V. The feedback resistors can be adjusted to provide any scaling of the output voltage, within the limits of the external op amp power supplies.

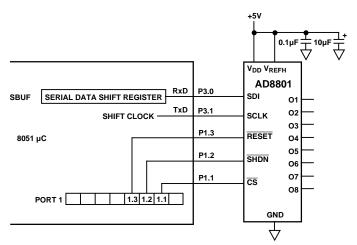
### **Microcomputer Interfaces**

The AD8801/AD8803 serial data input provides an easy interface to a variety of single-chip microcomputers ( $\mu$ Cs). Many  $\mu$ Cs have a built-in serial data capability that can be used for communicating with the DAC. In cases where no serial port is provided, or it is being used for some other purpose (such as an RS-232 communications interface), the AD8801/AD8803 can easily be addressed in software.

Eleven data bits are required to load a value into the AD8801/ AD8803 (3 bits for the DAC address and 8 bits for the DAC value). If more than 11 bits are transmitted before the Chip Select input goes high, the extra (i.e., the most-significant) bits are ignored. This feature is valuable because most  $\mu$ Cs only transmit data in 8-bit increments. Thus, the  $\mu$ C will send 16 bits to the DAC instead of 11 bits. The AD8801/AD8803 will only respond to the last 11 bits clocked into the SDI input, however, so the serial data interface is not affected.

### An 8051 $\mu C$ Interface

A typical interface between the AD8801/AD8803 and an 8051  $\mu$ C is shown in Figure 25. This interface uses the 8051's internal serial port. The serial port is programmed for Mode 0 operation, which functions as a simple 8-bit shift register. The 8051's Port3.0 pin functions as the serial data output, while Port3.1 serves as the serial clock.



# Figure 25. Interfacing the 8051 $\mu C$ to an AD8801/AD8803, Using the Serial Port

When data is written to the Serial Buffer Register (SBUF, at Special Function Register location  $99_{\rm H}$ ), the data is automatically converted to serial format and clocked out via Port3.0 and Port3.1. After 8 bits have been transmitted, the Transmit Interrupt flag (SCON.1) is set and the next 8 bits can be transmitted.

The AD8801 and AD8803 require the Chip Select to go low at the beginning of the serial data transfer. In addition, the SCLK input must be high when the Chip Select input goes high at the end of the transfer. The 8051's serial clock meets this requirement, since Port3.1 both begins and ends the serial data in the high state.

### Software for the 8051 Interface

A software routine for the AD8801/AD8803 to 8051 interface is shown in Listing 1. The routine transfers the 8-bit data stored at data memory location DAC\_VALUE to the AD8801/AD8803 DAC addressed by the contents of location DAC\_ADDR.

This subroutine loads an AD8801/AD8803 DAC from an 8051 microcomputer, using the 8051's serial port in MODE 0 (Shift Register Mode). The DAC value is stored at location DAC\_VAL The DAC address is stored at location DAC\_ADDR Variable declarations PORT1 DATA 90H ;SFR register for port 1 ;DAC Value DAC\_VALUE DATA 40H DAC\_ADDR DATA 41H ;DAC Address SHIFT1 DATA 042H ;high byte of 16-bit answer SHIFT2 043H ;low byte of answer DATA SHIFT\_COUNT DATA 44H ORG 100H ;arbitrary start DO\_8801: CLR SCON.7 ;set serial CLR SCON.6 ; data mode 0 CLR SCON.5 CLR SCON.1 ;clr transmit flag PORT1.1,#00001110B ;/RS, /SHDN, /CS high ORL CLR ;set the /CS low PORT1.1 ;put DAC value in shift register MOV SHIFT1, DAC\_ADDR ACALL BYTESWAP MOV SBUF, SHIFT2 ;send the address byte ADDR\_WAIT: JNB SCON.1, ADDR\_WAIT ;wait until 8 bits are sent CLR SCON.1 ;clear the serial transmit flag SHIFT1, DAC\_VALUE ;send the DAC value MOV ACALL BYTESWAP MOV SBUF, SHIFT2 VALU\_WAIT: ;wait again **JNB** SCON.1, VALU\_WAIT CLR SCON.1 ;clear serial flag SETB PORT1.1 ;/CS high, latch data ; into AD8801 RET **BYTESWAP:** MOV SHIFT\_COUNT,#8 ;Shift 8 bits SWAP\_LOOP: MOV A,SHIFT1 ;Get source byte RLC ;Rotate MSB to carry Α MOV SHIFT1,A ;Save new source byte MOV A,SHIFT2 ;Get destination byte RRC ;Move carry to MSB Α MOV SHIFT2,A ;Save DJNZ SHIFT\_COUNT,SWAP\_LOOP ;Done? RET END

Listing 1. Software for the 8051 to AD8801/AD8803 Serial Port Interface

high,

The subroutine begins by setting appropriate bits in the Serial Control register to configure the serial port for Mode 0 operation. Next the DAC's Chip Select input is set low to enable the AD8801/AD8803. The DAC address is obtained from memory location DAC\_ADDR, adjusted to compensate for the 8051's serial data format, and moved to the serial buffer register. At this point, serial data transmission begins automatically. When all 8 bits have been sent, the Transmit Interrupt bit is set, and the subroutine then proceeds to send the DAC value stored at location DAC\_VALUE. Finally the Chip Select input is re-turned high, causing the appropriate AD8801/AD8803 output voltage to change, and the subroutine ends.

The 8051 sends data out of its shift register LSB first, while the AD8801/AD8803 require data MSB first. The subroutine therefore includes a BYTESWAP subroutine to reformat the data. This routine transfers the MSB-first byte at location SHIFT1 to an LSB-first byte at location SHIFT2. The routine rotates the MSB of the first byte into the carry with a Rotate Left Carry instruction, then rotates the carry into the MSB of the second byte with a Rotate Right Carry instruction. After 8 loops, SHIFT2 contains the data in the proper format.

1 00001

The BYTESWAP routine in Listing 1 is convenient because the DAC data can be calculated in normal LSB form. For example, producing a ramp voltage on a DAC is simply a matter of repeatedly incrementing the DAC\_VALUE location and calling the LD\_8801 subroutine.

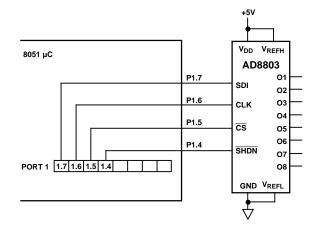
If the  $\mu$ C's hardware serial port is being used for other purposes, the AD8801/AD8803 can be loaded by using the parallel port. A typical parallel interface is shown in Figure 26. The serial data is transmitted to the DAC via the 8051's Port1.7 output, while Port1.6 acts as the serial clock.

Software for the interface of Figure 26 is contained in Listing 2. The subroutine will send the value stored at location DAC\_VALUE to the AD8801/AD8803 DAC addressed by location DAC\_ADDR. The program begins by setting the AD8801/AD8803's Serial Clock and Chip Select inputs high, then setting Chip Select low to start the serial interface process. The DAC address is loaded into the accumulator and three Rotate Right shifts are performed. This places the DAC address in the 3 MSBs of the accumulator. The address is then sent to the AD8801/AD8803 via the SEND\_SERIAL subroutine. Next, the DAC value is loaded into the accumulator and sent to the AD8801/AD8803. Finally, the Chip Select input is set high to complete the data transfer.

; This 8051 μC sub ; using the 8051's p		8801 or AD8803 DAC with an 8-bit value,	
; The DAC value is	stored at location D	AC_VALUE	
; The DAC address	is stored at location	DAC_ADDR	
;			
; Variable declaration	ns		
PORT1	DATA	90H	;SFR register for port 1
DAC_VALUE	DATA	40H	;DAC Value
DAC_ADDR	DATA	41H	;DAC Address (0 through 7)
LOOPCOUNT	DATA	43H	;COUNT LOOPS
	;		
	ORG	100H	;arbitrary start
LD_8803:	ORL	PORT1,#11110000B	set CLK, /CS and /SHDN hig
	CLR	PORT1.5	;Set Chip Select low
	MOV	LOOPCOUNT,#3	;Address is 3 bits
	MOV	A,DAC_ADDR	; Get DAC address
	RR	A	; Rotate the DAC
	RR	А	address to the Most
	RR	А	;Significant Bits (MSBs)
	ACALL	SEND_SERIAL	;Send the address
	MOV	LOOPCOUNT,#8	;Do 8 bits of data
	MOV	A,DAC_VALUE	
	ACALL	SEND_SERIAL	;Send the data
	SETB	PORT1.5	;Set /CS high
	RET		;DONE
SEND_SERIAL:	RLC	А	;Move next bit to carry
—	MOV	PORT1.7,C	Move data to SDI
	CLR	PORT1.6	;Pulse the
	SETB	PORT1.6	; CLK input
	DJNZ	LOOPCOUNT, SEND_SERIAL	;Loop if not done
	RET;	· _	· 1
	END		

0 1 1

Listing 2. Software for the 8051 to AD8801/AD8803 Parallel Port Interface

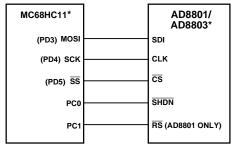


# Figure 26. An AD8801/AD8803-8051 $\mu C$ Interface Using Parallel Port 1

Unlike the serial port interface of Figure 25, the parallel port interface only transmits 11 bits to the AD8801/AD8803. Also, the BYTESWAP subroutine is not required for the parallel interface, because data can be shifted out MSB first. However, the results of the two interface methods are exactly identical. In most cases, the decision on which method to use will be determined by whether or not the serial data port is available for communication with the AD8801/AD8803.

### An MC68HC11-to-AD8801/AD8803 Interface

Like the 8051, the MC68HC11 includes a dedicated serial data port (labeled SPI). The SPI port provides an easy interface to the AD8801/AD8803 (Figure 27). The interface uses three lines of Port D for the serial data, and one or two lines from Port C to control the  $\overline{SHDN}$  and  $\overline{RS}$  (AD8801 only) inputs.



\*ADDITIONAL PINS OMITTED FOR CLARITY

### Figure 27. An AD8801/AD8803-to-MC68HC11 Interface

A software routine for loading the AD8801/AD8803 from a 68HC11 evaluation board is shown in Listing 3. First, the MC68HC11 is configured for SPI operation. Bits CPHA and CPOL define the SPI mode wherein the serial clock (SCK) is high at the beginning and end of transmission, and data is valid on the rising edge of SCK. This mode matches the requirements of the AD8801/AD8803. After the registers are saved on the stack, the DAC value and address are transferred to RAM and the AD8801/AD8803's  $\overline{CS}$  is driven low. Next, the DAC's address byte is transferred to the SPDR register, which automatically initiates the SPI data transfer. The program tests the SPIF bit and loops until the data transfer is complete. Then the DAC value is sent to the SPI. When transmission of the second byte is complete,  $\overline{CS}$  is driven high to load the new data and address into the AD8801/AD8803.

*							
* AD8801/AD8803 to M68HC11 Interface Assembly Program *							
* M68HC11	* M68HC11 Register definitions *						
PORTC *	EQU	\$1003	Port C control register "0,0,0,0;0,0,RS/, SHDN/"				
DDRC	EQU	\$1007	Port C data direction				
PORTD *	EQU	\$1008	Port D data register				
DDRD	EQU	\$1009	"0,0,/CS,CLK;SDI,0,0,0" Port D data direction				
SPCR	EQU	\$1028	SPI control register				
*	DOLL	64.000	"SPIE,SPE,DWOM,MSTR;CPOL,CPHA,SPR1,SPR0"				
SPSR *	EQU	\$1029	SPI status register "SPIF,WCOL,0,MODF;0,0,0,0"				
SPDR *	EQU	\$102A	SPI data register; Read-Buffer; Write-Shifter				
* SDI RAM v	variables:		SDI1 is encoded from 0 (Hex) to 7 (Hex)				
*			SDI2 is encoded from 00 (Hex) to FF (Hex)				
*			AD8801/3 requires two 8-bit loads; upper 5 bits				
*			of SDI1 are ignored. AD8801/3 address bits in last three LSBs of SDI1.				
*							
SDI1	EQU	\$00	SDI packed byte 1 "0,0,0,0;0,A2,A1,A0"				
SDI2 *	EQU	\$01	SDI packed byte 2 "DB7,DB6,DB5,DB4;DB3,DB2,DB1,DB0"				
* Main Progra	am						
	ORG	\$C000	Start of user's RAM in EVB				
INIT *	LDS	#\$CFFF	Top of C page RAM				
* Initialize Po	rt C Outputs						
*	LDAA	#\$03	0,0,0,0;0,0,1,1 /RS-Hi, /SHDN-Hi				
	STAA	PORTC	Initialize Port C Outputs				
	LDAA	#\$03	0,0,0,0;0,0,1,1				
*	STAA	DDRC	/RS and /SHDN are now enabled as outputs				
* Initialize Po *	rt D Outputs						
	LDAA	#\$20	0,0,1,0;0,0,0,0				
*			/CS-Hi,/CLK-Lo,SDI-Lo				
	STAA LDAA	PORTD	Initialize Port D Outputs				
	STAA	#\$38 DDRD	0,0,1,1;1,0,0,0 /CS,CLK, and SDI are now enabled as outputs				
*			······································				
* Initialize SP *	* Initialize SPI Interface *						
	LDAA	#\$53					
*	STAA	SPCR	SPI is Master,CPHA=0,CPOL=0,Clk rate=E/32				
* Call update	subroutine						
	BSR	UPDATE	Xfer 2 8-bit words to AD8402				
	JMP	\$E000	Restart BUFFALO				
* * Subroutine	UPDATE						
* UPDATE	PSHX	Save registers X, Y,	and A				

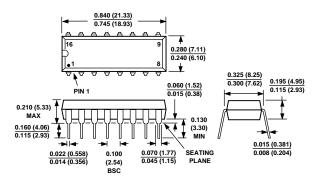
### PSHY PSHA

	PSHA		
* * Enter Cont	ents of SDI1 Data F	Register	
*		0	
	LDAA	\$0000	Hi-byte data loaded from memory
	STAA	SDI1	SDI1 = data in location 0000H
*			
* Enter Cont	ents of SDI2 Data F	Register	
·	LDAA	\$0001	Low-byte data loaded from memory
	STAA	SDI2	SDI2 = Data in location 0001H
*	JIAA	5012	
	LDX	#SDI1	Stack pointer at 1st byte to send via SDI
	LDY	#\$1000	Stack pointer at on-chip registers
*		# <b>Q</b> 1000	Stack pointer at on emp registers
* Reset AD88	301 to one-half scale	e (AD8803 does not ha	we a Reset input)
*			A court /DC
	BCLR BSET	PORTC,Y \$02 PORTC,Y \$02	Assert /RS De-assert /RS
*	DSEI	FURIC, 1 302	De-assert / KS
	1/03 ready for data	innut	
*	1705 Teauy 101 data	mput	
	BCLR	PORTD,Y \$20	Assert /CS
*			
TFRLP	LDAA	0,X	Get a byte to transfer via SPI
	STAA	SPDR	Write SDI data reg to start xfer
*			
WAIT	LDAA	SPSR	Loop to wait for SPIF
	BPL	WAIT	SPIF is the MSB of SPSR
*			(when SPIF is set, SPSR is negated)
	INX		Increment counter to next byte for xfer
	CPX	#SDI2+1	Are we done yet ?
	BNE	TFRLP	If not, xfer the second byte
*			
* Update AD	8801 output		
*			
	BSET	PORTD,Y \$20	Latch register & update AD8801
*			William dama markana marka NZ NZ 0. A
	PULA		When done, restore registers X, Y & A
	PULY		
	PULX		** Determente Maler Des stresses **
	RTS		** Return to Main Program **
	Listin	g 3. AD8801/AD8803	to MC68HC11 Interface Program Source Code

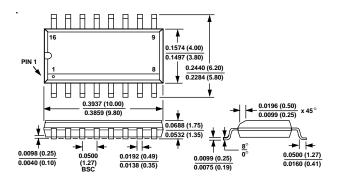
### **OUTLINE DIMENSIONS**

Dimensions shown in inches and (mm).

### 16-Pin Plastic DIP Package (N-16)



#### 16-Pin Narrow Body SOIC Package (R-16A)



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