## Dual, Low Power, 8-10-/12-/14-Bit TxDAC Digital-to-Analog Converters

## Data Sheet

## FEATURES

Power dissipation @ $3.3 \mathrm{~V}, 2 \mathrm{~mA}$ output
37 mW @ 10 MSPS
86 mW @ 125 MSPS
Sleep mode: <3 mW @ 3.3 V
Supply voltage: 1.8 V to 3.3 V
SFDR to Nyquist
84 dBc @ 1 MHz output
75 dBc @ 10 MHz output
AD9717 NSD @ 1 MHz output, 125 MSPS, 2 mA: - 151 dBc/Hz
Differential current outputs: 1 mA to 4 mA
2 on-chip auxiliary DACs
CMOS inputs with single-port operation
Output common mode: adjustable 0 V to 1.2 V
Small footprint 40-lead LFCSP RoHS-compliant package

## APPLICATIONS

Wireless infrastructures
Picocell, femtocell base stations

## Medical instrumentation

Ultrasound transducer excitation
Portable instrumentation
Signal generators, arbitrary waveform generators

## GENERAL DESCRIPTION

The AD9714/AD9715/AD9716/AD9717 are pin-compatible, dual, $8-/ 10-/ 12-/ 14$-bit, low power digital-to-analog converters (DACs) that provide a sample rate of 125 MSPS. These TxDAC ${ }^{\circ}$ converters are optimized for the transmit signal path of communication systems. All the devices share the same interface, package, and pinout, providing an upward or downward component selection path based on performance, resolution, and cost.

The AD9714/AD9715/AD9716/AD9717 offer exceptional ac and dc performance and support update rates up to 125 MSPS.

The flexible power supply operating range of 1.8 V to 3.3 V and low power dissipation of the AD9714/AD9715/AD9716/AD9717 make them well-suited for portable and low power applications.

## PRODUCT HIGHLIGHTS

1. Low Power.

DACs operate on a single 1.8 V to 3.3 V supply; total power consumption reduces to 35 mW at 125 MSPS with a 1.8 V supply. Sleep and power-down modes are provided for low power idle periods.
2. CMOS Clock Input.

High speed, single-ended CMOS clock input supports a 125 MSPS conversion rate.
3. Easy Interfacing to Other Components.

Adjustable output common mode from 0 V to 1.2 V allows easy interfacing to other components that accept commonmode levels greater than 0 V .

## AD9714/AD9715/AD9716/AD9717

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## REVISION HISTORY

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3/2009—Rev. 0 to Rev. A
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8/2008-Revision 0: Initial Version

## FUNCTIONAL BLOCK DIAGRAM



Figure 1.

## SPECIFICATIONS

## DC SPECIFICATIONS

$\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{AVDD}=3.3 \mathrm{~V}, \mathrm{DVDD}=1.8 \mathrm{~V}, \mathrm{DVDDIO}=3.3 \mathrm{~V}, \mathrm{CVDD}=3.3 \mathrm{~V}, \mathrm{I}_{\mathrm{xOUTFS}}=2 \mathrm{~mA}$, maximum sample rate, unless otherwise noted.

Table 1.

| Parameter | AD9714 |  |  | AD9715 |  |  | AD9716 |  |  | AD9717 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |  |
| RESOLUTION | 8 |  |  | 10 |  |  | 12 |  |  | 14 |  |  | Bits |
| $\begin{aligned} & \text { ACCURACY, AVDD }=\text { DVDDIO }= \\ & \text { CVDD }=3.3 \mathrm{~V} \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Differential Nonlinearity (DNL) |  |  |  |  |  |  |  |  |  |  |  |  | LSB |
| Precalibration | $\pm 0.02$$\pm 0.003$ |  |  | $\pm 0.08$$\pm 0.01$ |  |  |  | $\pm 0.4$ |  |  | $\pm 1.7$ |  |  |
| Postcalibration |  |  |  | $\pm 0.2$ | $\pm 1.0$ |  |  | LSB |  |
| Integral Nonlinearity (INL) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | LSB |
| Precalibration |  | $\pm 0.025$ |  |  | $\pm 0.13$ |  |  | $\pm 0.4$ |  |  | $\pm 1.8$ |  |  |  |
| Postcalibration | $\pm 0.01$ |  |  | $\pm 0.05$ |  |  | $\pm 0.3$ |  |  | $\pm 1.3$ |  |  | LSB |  |
| $\begin{aligned} & \text { ACCURACY, AVDD }=\text { DVDDIO }= \\ & \text { CVDD }=1.8 \mathrm{~V} \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Differential Nonlinearity (DNL) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Precalibration | $\pm 0.02$ |  |  | $\pm 0.08$ |  |  | $\pm 0.4$ |  |  | $\pm 1.2$ |  |  | LSB |  |
| Postcalibration | $\pm 0.005$ |  |  | $\pm 0.01$ |  |  | $\pm 0.2$ |  |  | $\pm 1.0$ |  |  | LSB |  |
| Integral Nonlinearity (INL) | $\pm 0.025$ |  |  | $\pm 0.12$ |  |  | $\pm 0.4$ |  |  | +1.5 |  |  |  |  |
| Precalibration |  |  |  | LSB |  |  |  |  |  |  |  |  |
| Postcalibration | $\pm 0.02$ |  |  |  |  |  | $\pm 0.05$ |  |  | $\pm 0.25$ |  |  | $\pm 1.1$ |  |  | LSB |
| MAIN DAC OUTPUTS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Offset Error | -1 | 0 | +1 | -1 | 0 | +1 | -1 | 0 | +1 | -1 | 0 | +1 | mV |  |
| Gain Error | -2 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Internal Reference |  |  | +2 | -2 |  | +2 | -2 |  | +2 | -2 |  | +2 | \% of FSR |  |
| Full-Scale Output Current ${ }^{1}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| AVDD $=3.3 \mathrm{~V}$ | 1 | 2 | 4 | 1 | 2 | 4 | 1 | 2 | 4 | 1 | 2 | 4 | mA |  |
| AVDD $=1.8 \mathrm{~V}$ | 1 | 2 | 2.5 | 1 | 2 | 2.5 | 1 | 2 | 2.5 | 1 | 2 | 2.5 | mA |  |
| Output Compliance Range | -0.5 | 0 | +1.2 | -0.5 | 0 | +1.2 | -0.5 | 0 | +1.2 | -0.5 | 0 | +1.2 | V |  |
| Output Resistance | 200 |  |  | 200 |  |  | 200 |  |  | 200 |  |  | $\mathrm{M} \Omega$ |  |
| Crosstalk, Q DAC to IDAC | 97 |  |  | 97 |  |  | 97 |  |  | 97 |  |  | dB |  |
| fout $=30 \mathrm{MHz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| fout $=60 \mathrm{MHz}$ | 78 |  |  | 78 |  |  | 78 |  |  | 78 |  |  | dB |  |
| MAIN DAC TEMPERATURE DRIFT |  |  |  |  |  |  | 0 |  |  | 0 |  |  | $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |  |
| Offset | $\pm 40$ |  |  | $\pm 40$ |  |  |  |  |  |  |  |  |  |  |
| Gain |  |  |  | $\pm 40$ | $\pm 40$ |  |  |  |  |  |  |  |
| Reference Voltage | $\pm 25$ |  |  |  |  |  | $\pm 25$ |  |  | $\pm 25$ |  |  |  | $\pm 25$ |  |  |
| AUXDAC OUTPUTS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Resolution | 10 |  |  | 10 |  |  | 10 |  |  | 10 |  |  | Bits $\mu \mathrm{A}$ |  |
| Full-Scale Output Current (Current Sourcing Mode) | 125 |  |  | 125 |  |  | 125 |  |  | 125 |  |  |  |  |
| Voltage Output Mode | $\mathrm{V}_{\text {ss }}$ |  | $V_{\text {DD }}$ | $\mathrm{V}_{\text {ss }}$ |  | $V_{\text {DD }}$ | $\mathrm{V}_{\text {ss }}$ |  | $V_{D D}$ | $\mathrm{V}_{\text {ss }}$ |  | $V_{\text {DD }}$ | v |  |
| Output Compliance Range (Sourcing 1 mA ) | $\mathrm{V}_{\text {ss }}$ |  | $\begin{aligned} & V_{D D}- \\ & 0.25 \end{aligned}$ | Vss |  | $\begin{aligned} & \mathrm{V}_{\mathrm{DD}}- \\ & 0.25 \end{aligned}$ | $\mathrm{V}_{\text {ss }}$ |  | $\begin{aligned} & V_{\mathrm{DD}}- \\ & 0.25 \end{aligned}$ | $\mathrm{v}_{\mathrm{ss}}$ |  | $\begin{aligned} & V_{\mathrm{DD}}- \\ & 0.25 \end{aligned}$ | V |  |
| Output Compliance Range (Sinking 1 mA ) | $\begin{aligned} & V_{s s}+ \\ & 0.25 \end{aligned}$ |  | $V_{D D}$ | $\begin{aligned} & V_{s s}+ \\ & 0.25 \end{aligned}$ |  | $V_{D D}$ | $\begin{aligned} & V_{s s}+ \\ & 0.25 \end{aligned}$ |  | $V_{D D}$ | $\begin{aligned} & \mathrm{V}_{s s}+ \\ & 0.25 \end{aligned}$ |  | $V_{\text {D }}$ | v |  |
| Output Resistance in Current Output Mode, $\mathrm{AV}_{\text {ss }}$ to 1 V | 1 |  |  | 1 |  |  | 1 |  |  | 1 |  |  | $\mathrm{M} \Omega$ |  |
| AUX DAC Monotonicity Guaranteed | 10 |  |  | 10 |  |  | 10 |  |  | 10 |  |  | Bits |  |
| REFERENCE OUTPUT |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Internal Reference Voltage | 0.98 |  | 1.08 | 0.98 | 1.025 | 1.08 | 0.98 | 1.025 | 1.08 | 0.98 | 1.025 | 1.08 | $\mathrm{k} \Omega$ |  |
| Output Resistance |  |  |  |  | 10 |  |  | 10 |  |  | 10 |  |  |  |

## AD9714/AD9715/AD9716/AD9717

| Parameter | AD9714 |  |  | AD9715 |  |  | AD9716 |  |  | AD9717 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |  |
| REFERENCE INPUT |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Voltage Compliance |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{AVDD}=3.3 \mathrm{~V}$ | 0.1 |  | 1.25 | 0.1 |  | 1.25 | 0.1 |  | 1.25 | 0.1 |  | 1.25 | V |
| AVDD $=1.8 \mathrm{~V}$ | 0.1 |  | 1.0 | 0.1 |  | 1.0 | 0.1 |  | 1.0 | 0.1 |  | 1.0 | V |
| Input Resistance External Reference Mode |  | 1 |  |  | 1 |  |  | 1 |  |  | 1 |  | $\mathrm{M} \Omega$ |
| DAC MATCHING |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Gain Matching | -1 |  | +1 | -1 |  | +1 | -1 |  | +1 | -1 |  | +1 | \% FSR |
| ANALOG SUPPLY VOLTAGES |  |  |  |  |  |  |  |  |  |  |  |  |  |
| AVDD | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | V |
| CVDD | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | V |
| DIGITAL SUPPLY VOLTAGES |  |  |  |  |  |  |  |  |  |  |  |  |  |
| DVDD | 1.7 |  | 1.9 | 1.7 |  | 1.9 | 1.7 |  | 1.9 | 1.7 |  | 1.9 | V |
| DVDDIO | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | 1.7 |  | 3.5 | V |
| $\begin{aligned} & \text { POWER CONSUMPTION, AVDD = } \\ & \text { DVDDIO = CVDD }=3.3 \mathrm{~V} \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{fDAC}=125 \mathrm{MSPS}, \mathrm{IF}=12.5 \mathrm{MHz}$ |  | 86 |  |  | 86 |  |  | 86 |  |  | 86 |  | mW |
| $\mathrm{l}_{\text {AVdD }}$ |  | 10 |  |  | 10 |  |  | 10 |  |  | 10 |  | mA |
| IDVDD + IDVDDIO |  | 11 |  |  | 11 |  |  | 11 |  |  | 11 |  | mA |
| I cvid |  | 3 |  |  | 3 |  |  | 3 |  |  | 3 |  | mA |
| Power-Down Mode with Clock |  | 50 |  |  | 50 |  |  | 50 |  |  | 50 |  | mW |
| Power-Down Mode, No Clock |  | 1.5 |  |  | 1.5 |  |  | 1.5 |  |  | 1.5 |  | mW |
| Power Supply Rejection Ratio |  | -0.04 |  |  | -0.04 |  |  | -0.04 |  |  | -0.04 |  | \% FSR/V |
| POWER CONSUMPTION, AVDD = DVDDIO $=$ CVDD $=1.8 \mathrm{~V}$. |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{f}_{\mathrm{DAC}}=125 \mathrm{MSPS}, \mathrm{IF}=12.5 \mathrm{MHz}$ |  | 35 |  |  | 35 |  |  | 35 |  |  | 35 |  | mW |
| $\mathrm{l}_{\text {AVdD }}$ |  | 10 |  |  | 10 |  |  | 10 |  |  | 10 |  | mA |
| $\mathrm{I}_{\text {DVDD }}+\mathrm{I}_{\text {DVDDIO }}$ |  | 8 |  |  | 8 |  |  | 8 |  |  | 8 |  | $m A$ |
| Icvod |  | 1.5 |  |  | 1.5 |  |  | 1.5 |  |  | 1.5 |  | mA |
| Power-Down Mode with Clock |  | 12 |  |  | 12 |  |  | 12 |  |  | 12 |  | mW |
| Power-Down Mode, No Clock |  | 850 |  |  | 850 |  |  | 850 |  |  | 850 |  | $\mu \mathrm{W}$ |
| Power Supply Rejection Ratio |  | -0.001 |  |  | -0.001 |  |  | -0.001 |  |  | -0.001 |  | \% FSR/V |
| OPERATING RANGE | -40 | +25 | +85 | -40 | +25 | +85 | -40 | +25 | +85 | -40 | +25 | +85 | ${ }^{\circ} \mathrm{C}$ |

${ }^{1}$ Based on a $10 \mathrm{k} \Omega$ external resistor.

## DIGITAL SPECIFICATIONS

$\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{AVDD}=3.3 \mathrm{~V}, \mathrm{DVDD}=1.8 \mathrm{~V}, \mathrm{DVDDIO}=3.3 \mathrm{~V}, \mathrm{CVDD}=3.3 \mathrm{~V}, \mathrm{I}_{\mathrm{xOUTFS}}=2 \mathrm{~mA}$, maximum sample rate, unless otherwise noted.

Table 2.

| Parameter | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: |
| DAC CLOCK INPUT (CLKIN) |  |  |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | 2.1 | 3 |  | V |
| VIL |  | 0 | 0.9 | V |
| Maximum Clock Rate |  |  | 125 | MSPS |
| SERIAL PERIPHERAL INTERFACE |  |  |  |  |
| Maximum Clock Rate (SCLK) |  | 25 |  | MHz |
| Minimum Pulse Width High |  | 20 |  | ns |
| Minimum Pulse Width Low |  | 20 |  | ns |
| INPUT DATA |  |  |  |  |
| 1.8 V Q Channel or DCLKIO Falling Edge |  |  |  |  |
| Setup |  | 0.25 |  | ns |
| Hold |  | 1.2 |  | ns |
| 1.8 V I Channel or DCLKIO Rising Edge |  |  |  |  |
| Setup |  | 0.13 |  | ns |
| Hold |  | 1.1 |  | ns |
| 3.3 V Q Channel or DCLKIO Falling Edge |  |  |  |  |
| Setup |  | -0.2 |  | ns |
| Hold |  | 1.5 |  | ns |
| 3.3 V I Channel or DCLKIO Rising Edge |  |  |  |  |
| Setup |  | -0.2 |  | ns |
| Hold |  | 1.6 |  | ns |
| $\mathrm{V}_{\mathrm{H}}$ | 2.1 | 3 |  | V |
| $\mathrm{V}_{\text {IL }}$ |  | 0 | 0.9 | V |

## AD9714/AD9715/AD9716/AD9717

## AC SPECIFICATIONS

$\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{AVDD}=3.3 \mathrm{~V}, \mathrm{DVDD}=1.8 \mathrm{~V}, \mathrm{DVDDIO}=3.3 \mathrm{~V}, \mathrm{CVDD}=3.3 \mathrm{~V}, \mathrm{I}_{\mathrm{xOUTFS}}=2 \mathrm{~mA}$, maximum sample rate, unless otherwise noted.

Table 3.

$\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{AVDD}=1.8 \mathrm{~V}, \mathrm{DVDD}=1.8 \mathrm{~V}, \mathrm{DVDDIO}=1.8 \mathrm{~V}, \mathrm{CVDD}=1.8 \mathrm{~V}, \mathrm{I}_{\mathrm{xOUTf}}=2 \mathrm{~mA}$, maximum sample rate, unless otherwise noted.

Table 4.

| Parameter | AD9714 |  |  | AD9715 |  |  | AD9716 |  |  | AD9717 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |  |
| SPURIOUS-FREE DYNAMIC RANGE (SFDR) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}, \mathrm{fout}=10 \mathrm{MHz}$ |  | 75 |  |  | 78 |  |  | 79 |  |  | 80 |  | dBc |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}, \mathrm{fout}=50 \mathrm{MHz}$ |  | 55 |  |  | 56 |  |  | 57 |  |  | 58 |  | dBc |
| TWO TONE INTERMODULATION |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}, \mathrm{fout}=10 \mathrm{MHz}$ |  | 79 |  |  | 80 |  |  | 84 |  |  | 85 |  | dBc |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}, \mathrm{fout}=50 \mathrm{MHz}$ |  | 53 |  |  | 53 |  |  | 53 |  |  | 53 |  | dBc |
| NOISE SPECTRAL DENSITY (NSD) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}, \mathrm{f}_{\text {OUT }}=10 \mathrm{MHz}$ |  | -132 |  |  | -141 |  |  | -146 |  |  | -148 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| $\mathrm{f}_{\text {DAC }}=125 \mathrm{MSPS}$, fout $=50 \mathrm{MHz}$ |  | -126 |  |  | -131 |  |  | -131 |  |  | -132 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| W-CDMA ADJACENT CHANNEL LEAKAGE RATIO (ACLR), SINGLE CARRIER |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\mathrm{ffac}^{\text {a }}$ 61.44 MSPS, fout $=20 \mathrm{MHz}$ |  | -68 |  |  | -68 |  |  | -68 |  |  | -68 |  | dBc |
| $\mathrm{f}_{\text {DAC }}=122.88 \mathrm{MSPS}, \mathrm{fout}=30 \mathrm{MHz}$ |  | -68 |  |  | -68 |  |  | -68 |  |  | -68 |  | dBc |

## ABSOLUTE MAXIMUM RATINGS

Table 5.

| Parameter | Rating |
| :--- | :--- |
| AVDD, DVDDIO, CVDD to AVSS, DVSS, CVSS | -0.3 V to +3.9 V |
| DVDD to DVSS | -0.3 V to +2.1 V |
| AVSS to DVSS, CVSS | -0.3 V to +0.3 V |
| DVSS to AVSS, CVSS | -0.3 V to +0.3 V |
| CVSS to AVSS, DVSS | -0.3 V to +0.3 V |
| REFIO, FSADJQ, FSADJ, CMLQ, CMLI to AVSS | -0.3 V to AVDD + 0.3 V |
| QOUTP, QOUTN, IOUTP, IOUTN, RLQP, RLQN, | -1.0 V to AVDD + 0.3 V |
| RLIP, RLIN to AVSS |  |
| DBn ${ }^{1}$ (MSB) to DBO (LSB), $\overline{C S}$, SCLK, SDIO, | -0.3 V to DVDDIO + 0.3 V |
| $\quad$ RESET to DVSS |  |
| CLKIN to CVSS | -0.3 V to CVDD +0.3 V |
| Junction Temperature | $125^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |

${ }^{1} \mathrm{n}$ stands for 7 for the AD9714, 9 for the AD9715, 11 for the AD9716, and 13 for the AD9717.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

Table 6.

| Package Type | $\boldsymbol{\theta}_{\mathrm{JA}}$ | $\boldsymbol{\theta}_{\mathrm{JB}}{ }^{\mathbf{1}}$ | $\boldsymbol{\theta}_{\mathrm{Jc}}{ }^{\mathbf{1}}$ | Unit |
| :--- | :--- | :--- | :--- | :--- |
| 40-Lead LFCSP (with No Airflow <br> Movement) | 29.8 | 19.0 | 3.4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

${ }^{1}$ These calculations are intended to represent the thermal performance of the indicated packages using a JEDEC multilayer test board. Do not assume the same level of thermal performance in actual applications without a careful inspection of the conditions in the application to determine that they are similar to those assumed in these calculations.

## ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## AD9714/AD9715/AD9716/AD9717

## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



Figure 2. AD9714 Pin Configuration
Table 7. AD9714 Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 to 4 | DB[5:2] | Digital Inputs. |
| 5 | DVDDIO | Digital I/O Supply Voltage (1.8 V to 3.3 V Nominal). |
| 6 | DVSS | Digital Common. |
| 7 | DVDD | Digital Core Supply Voltage ( 1.8 V ). Strap DVDD to DVDDIO at 1.8 V . If DVDDIO $>1.8 \mathrm{~V}$, bypass DVDD with a $1.0 \mu \mathrm{~F}$ capacitor; however, do not otherwise connect it. The LDO should not drive external loads. |
| 8 | DB1 | Digital Inputs. |
| 9 | DB0 (LSB) | Digital Input (LSB). |
| 10 to 15 | NC | No Connect. These pins are not connected to the chip. |
| 16 | DCLKIO | Data Input/Output Clock. Clock used to qualify input data. |
| 17 | CVDD | Sampling Clock Supply Voltage ( 1.8 V to 3.3 V ). CVDD must be $\geq$ DVDD. |
| 18 | CLKIN | LVCMOS Sampling Clock Input. |
| 19 | CVSS | Sampling Clock Supply Voltage Common. |
| 20 | CMLQ | Q DAC Output Common-Mode Level. When the internal on chip (QRcmL) is enabled, this pin is connected to the on-chip QRcml resistor. It is recommended to leave this pin unconnected. When the internal on chip ( $\mathrm{QR} \mathrm{RcmL}^{\prime}$ ) is disabled, this pin is the common-mode load for Q DAC and must be connected to AVSS through a resistor (see the Using the Internal Termination Resistors section). The recommended value for this external resistor is $0 \Omega$. |
| 21 | RLQN | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTN externally. |
| 22 | QOUTN | Complementary Q DAC Current Output. Full-scale current is sourced when all data bits are Os. |
| 23 | QOUTP | Q DAC Current Output. Full-scale current is sourced when all data bits are 1s. |
| 24 | RLQP | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTP externally. |
| 25 | AVSS | Analog Common. |
| 26 | AVDD | Analog Supply Voltage ( 1.8 V to 3.3 V ). |
| 27 | RLIP | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTP externally. |
| 28 | IOUTP | I DAC Current Output. Full-scale current is sourced when all data bits are 1s. |
| 29 | IOUTN | Complementary I DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 30 | RLIN | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTN externally. |

## AD9714/AD9715/AD9716/AD9717

| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 31 | CMLI | I DAC Output Common-Mode Level. When the internal on chip (IRcmL) is enabled, this pin is connected to the <br> on-chip IRcmL resistor. It is recommended to leave this pin unconnected. When the internal on chip (IRcmL) is <br> disabled, this pin is the common-mode load for I DAC and must be connected to AVSS through a resistor <br> (see the Using the Internal Termination Resistors section). The recommended value for this external resistor <br> is 0 ת. |
| 32 |  |  |

## AD9714/AD9715/AD9716/AD9717



Figure 3. AD9715 Pin Configuration
Table 8. AD9715 Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 to 4 | DB[7:4] | Digital Inputs. |
| 5 | DVDDIO | Digital I/O Supply Voltage ( 1.8 V to 3.3 V Nominal). |
| 6 | DVSS | Digital Common. |
| 7 | DVDD | Digital Core Supply Voltage ( 1.8 V ). Strap DVDD to DVDDIO at 1.8 V . If DVDDIO $>1.8 \mathrm{~V}$, bypass DVDD with a $1.0 \mu \mathrm{~F}$ capacitor; however, do not otherwise connect it. The LDO should not drive external loads. |
| 8 to 10 | DB[3:1] | Digital Inputs. |
| 11 | DB0 (LSB) | Digital Input (LSB). |
| 12 to 15 | NC | No Connect. These pins are not connected to the chip. |
| 16 | DCLKIO | Data Input/Output Clock. Clock used to qualify input data. |
| 17 | CVDD | Sampling Clock Supply Voltage ( 1.8 V to 3.3 V). CVDD must be $\geq$ DVDD. |
| 18 | CLKIN | LVCMOS Sampling Clock Input. |
| 19 | CVSS | Sampling Clock Supply Voltage Common. |
| 20 | CMLQ | Q DAC Output Common-Mode Level. When the internal on chip ( $Q R_{c m L}$ ) is enabled, this pin is connected to the on-chip QRcmı resistor. It is recommended to leave this pin unconnected. When the internal on chip ( $\mathrm{QR}_{\mathrm{cmL}}$ ) is disabled, this pin is the common-mode load for Q DAC and must be connected to AVSS through a resistor (see the Using the Internal Termination Resistors section). The recommended value for this external resistor is $0 \Omega$. |
| 21 | RLQN | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTN externally. |
| 22 | QOUTN | Complementary Q DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 23 | QOUTP | Q DAC Current Output. Full-scale current is sourced when all data bits are 1s. |
| 24 | RLQP | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTP externally. |
| 25 | AVSS | Analog Common. |
| 26 | AVDD | Analog Supply Voltage (1.8 V to 3.3 V ). |
| 27 | RLIP | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTP externally. |
| 28 | IOUTP | I DAC Current Output. Full-scale current is sourced when all data bits are 1s. |
| 29 | IOUTN | Complementary I DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 30 | RLIN | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTN externally. |

## AD9714/AD9715/AD9716/AD9717

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 31 | CMLI | I DAC Output Common-Mode Level. When the internal on chip (IRсмц) is enabled, this pin is connected to the on-chip IRcmı resistor. It is recommended to leave this pin unconnected. When the internal on chip (IRcml) is disabled, this pin is the common-mode load for I DAC and must be connected to AVSS through a resistor (see the Using the Internal Termination Resistors section). The recommended value for this external resistor is $0 \Omega$. |
| 32 | FSADJQ/AUXQ | Full-Scale Current Output Adjust (FSADJQ). When the internal on chip (QRSET) is disabled, this pin is the fullscale current output adjust for Q DAC and must be connected to AVSS through a resistor (see the Theory of Operation section). The nominal value for this external resistor is $16 \mathrm{k} \Omega$ for a 2 mA output current. <br> Auxiliary Q DAC Output (AUXQ). When the internal on chip (QRSET) is enabled, this pin is the auxiliary Q DAC output. |
| 33 | FSADJI/AUXI | Full-Scale Current Output Adjust (FSADJI). When the internal on chip (IRSET) is disabled, this pin is the fullscale current output adjust for I DAC and must be connected to AVSS through a resistor (see the Theory of Operation section). The nominal value for this external resistor is $16 \mathrm{k} \Omega$ for a 2 mA output current. Auxiliary I DAC Output (AUXI). When the internal on chip (IRSET) is enabled, this pin is the auxiliary I DAC output. |
| 34 | REFIO | Reference Input/Output. Serves as a reference input when the internal reference is disabled. Provides a 1.0 V reference output when in internal reference mode (a $0.1 \mu \mathrm{~F}$ capacitor to AVSS is required). |
| 35 | RESET/PINMD | This pin defines the operation mode of the part. A logic low (pull-down to DVSS) sets the part in SPI mode. Pulse RESET high to reset the SPI registers to their default values. <br> A logic high (pull-up to DVDDIO) puts the device into pin mode (PINMD). |
| 36 | SCLK/CLKMD | Clock Input for Serial Port (SCLK). In SPI mode, this pin is the clock input for the serial port. Clock Mode (CLKMD). In pin mode, CLKMD determines the phase of the internal retiming clock. When DCLKIO $=$ CLKIN, tie it to 0 . When DCLKIO $\neq$ CLKIN, pulse 0 to 1 to edge trigger the internal retimer (see the Retimer section). |
| 37 | SDIO/FORMAT | Serial Port Input/Output (SDIO). In SPI mode, this pin is the bidirectional data line for the serial port. Format Pin (FORMAT). In pin mode, FORMAT determines the data format of digital data. A logic low (pull-down to DVSS) selects the binary input data format. A logic high (pull-up to DVDDIO) selects the twos complement input data format. |
| 38 | $\overline{\mathrm{CS}} / \mathrm{PWRDN}$ | Active Low Chip Select ( $\overline{(\mathrm{CS})}$. In SPI mode, this pin serves as the active low chip select. <br> Power-Down (PWRDN). In pin mode, a logic high (pull-up to DVDDIO) powers down the device, except for the SPI port. |
| 39 | DB9 (MSB) | Digital Input (MSB). |
| 40 | DB8 | Digital Input. |
| 41 (EPAD) | Exposed Pad (EPAD) | The exposed pad is connected to AVSS and should be soldered to the ground plane. Exposed metal at the package corners is connected to this pad. |

## AD9714/AD9715/AD9716/AD9717



Figure 4. AD9716 Pin Configuration
Table 9. AD9716 Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 to 4 | DB[9:6] | Digital Inputs. |
| 5 | DVDDIO | Digital I/O Supply Voltage (1.8V to 3.3 V Nominal). |
| 6 | DVSS | Digital Common. |
| 7 | DVDD | Digital Core Supply Voltage ( 1.8 V ). Strap DVDD to DVDDIO at 1.8 V . If DVDDIO $>1.8 \mathrm{~V}$, bypass DVDD with a $1.0 \mu \mathrm{~F}$ capacitor; however, do not otherwise connect it. The LDO should not drive external loads. |
| 8 to 12 | DB[5:1] | Digital Inputs. |
| 13 | DB0 (LSB) | Digital Input (LSB). |
| 14, 15 | NC | No Connect. These pins are not connected to the chip. |
| 16 | DCLKIO | Data Input/Output Clock. Clock used to qualify input data. |
| 17 | CVDD | Sampling Clock Supply Voltage (1.8V to 3.3 V). CVDD must be $\geq$ DVDD. |
| 18 | CLKIN | LVCMOS Sampling Clock Input. |
| 19 | CVSS | Sampling Clock Supply Voltage Common. |
| 20 | CMLQ | Q DAC Output Common-Mode Level. When the internal on chip ( $\mathrm{QR} \mathrm{c}_{с м}$ ) is enabled, this pin is connected to the on-chip $Q_{\text {смц }}$ resistor. It is recommended to leave this pin unconnected. When the internal on chip ( $\mathrm{QR} \mathrm{cmL}_{\mathrm{L}}$ ) is disabled, this pin is the common-mode load for Q DAC and must be connected to AVSS through a resistor (see the Using the Internal Termination Resistors section). The recommended value for this external resistor is $0 \Omega$. |
| 21 | RLQN | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTN externally. |
| 22 | QOUTN | Complementary Q DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 23 | QOUTP | Q DAC Current Output. Full-scale current is sourced when all data bits are 1 s . |
| 24 | RLQP | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTP externally. |
| 25 | AVSS | Analog Common. |
| 26 | AVDD | Analog Supply Voltage (1.8 V to 3.3 V). |
| 27 | RLIP | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTP externally. |
| 28 | IOUTP | I DAC Current Output. Full-scale current is sourced when all data bits are 1 s . |
| 29 | IOUTN | Complementary I DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 30 | RLIN | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTN externally. |

## AD9714/AD9715/AD9716/AD9717

| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 31 | CMLI | I DAC Output Common-Mode Level. When the internal on chip (IRcmL) is enabled, this pin is connected to the <br> on-chip IRcmL resistor. It is recommended to leave this pin unconnected. When the internal on chip (IRcmL) is <br> disabled, this pin is the common-mode load for I DAC and must be connected to AVSS through a resistor <br> (see the Using the Internal Termination Resistors section). The recommended value for this external resistor <br> is 0 ת. |
| 32 |  |  |

## AD9714/AD9715/AD9716/AD9717



Figure 5. AD9717 Pin Configuration
Table 10. AD9717 Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 to 4 | DB[11:8] | Digital Inputs. |
| 5 | DVDDIO | Digital I/O Supply Voltage (1.8 V to 3.3 V Nominal). |
| 6 | DVSS | Digital Common. |
| 7 | DVDD | Digital Core Supply Voltage ( 1.8 V ). Strap DVDD to DVDDIO at 1.8 V . If DVDDIO $>1.8 \mathrm{~V}$, bypass DVDD with a $1.0 \mu \mathrm{~F}$ capacitor; however, do not otherwise connect it. The LDO should not drive external loads. |
| 8 to 14 | DB[7:1] | Digital Inputs. |
| 15 | DB0 (LSB) | Digital Input (LSB). |
| 16 | DCLKIO | Data Input/Output Clock. Clock used to qualify input data. |
| 17 | CVDD | Sampling Clock Supply Voltage (1.8V to 3.3 V). CVDD must be $\geq$ DVDD. |
| 18 | CLKIN | LVCMOS Sampling Clock Input. |
| 19 | CVSS | Sampling Clock Supply Voltage Common. |
| 20 | CMLQ | Q DAC Output Common-Mode Level. When the internal on chip (QRсмц) is enabled, this pin is connected to the on-chip QRcml resistor. It is recommended to leave this pin unconnected. When the internal on chip ( $\mathrm{QR} \mathrm{R}_{\mathrm{cmL}}$ ) is disabled, this pin is the common-mode load for Q DAC and must be connected to AVSS through a resistor (see the Using the Internal Termination Resistors section). The recommended value for this external resistor is $0 \Omega$. |
| 21 | RLQN | Load Resistor ( $500 \Omega$ ) to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTN externally. |
| 22 | QOUTN | Complementary Q DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 23 | QOUTP | Q DAC Current Output. Full-scale current is sourced when all data bits are 1 s . |
| 24 | RLQP | Load Resistor $(500 \Omega)$ to the CMLQ Pin. For the internal load resistor to be used, this pin should be tied to QOUTP externally. |
| 25 | AVSS | Analog Common. |
| 26 | AVDD | Analog Supply Voltage (1.8 V to 3.3 V). |
| 27 | RLIP | Load Resistor ( $500 \Omega$ ) to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTP externally. |
| 28 | IOUTP | I DAC Current Output. Full-scale current is sourced when all data bits are 1 s . |
| 29 | IOUTN | Complementary I DAC Current Output. Full-scale current is sourced when all data bits are 0s. |
| 30 | RLIN | Load Resistor $(500 \Omega)$ to the CMLI Pin. For the internal load resistor to be used, this pin should be tied to IOUTN externally. |

## AD9714/AD9715/AD9716/AD9717

| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 31 | CMLI | I DAC Output Common-Mode Level. When the internal on chip (IRcmL) is enabled, this pin is connected to the <br> on-chip IRcmL resistor. It is recommended to leave this pin unconnected. When the internal on chip (IRcmL) is <br> disabled, this pin is the common-mode load for I DAC and must be connected to AVSS through a resistor <br> (see the Using the Internal Termination Resistors section). The recommended value for this external resistor <br> is 0 ת. |
| 32 |  |  |

## TYPICAL PERFORMANCE CHARACTERISTICS

$\mathrm{I}_{\mathrm{x} \text { OUTFS }}=2 \mathrm{~mA}$, maximum sample rate, unless otherwise noted. DVDD is always at 1.8 V .


Figure 6. AD9717 Precalibration INL at 1.8 V (DVDD = 1.8 V)


Figure 7. $A D 9717$ Precalibration $D N L$ at $1.8 \mathrm{~V}(\mathrm{DVDD}=1.8 \mathrm{~V})$


Figure 8. AD9717 Precalibration INL at 3.3 V (DVDD = 1.8 V)


Figure 9. AD9717 Postcalibration INL at $1.8 \mathrm{~V}(\mathrm{DVDD}=1.8 \mathrm{~V})$


Figure 10. AD9717 Postcalibration DNL at 1.8 V (DVDD $=1.8 \mathrm{~V})$


Figure 11. AD9717 Postcalibration INL at 3.3 V (DVDD = 1.8 V)


Figure 12. AD9717 Precalibration DNL at 3.3 V


Figure 13. AD9716 Precalibration INL at 1.8 V


Figure 14. AD9716 Precalibration DNL at 1.8 V


Figure 15. AD9717 Postcalibration DNL at 3.3 V


Figure 16. AD9716 Postcalibration INL at 1.8 V


Figure 17. AD9716 Postcalibration DNL at 1.8 V


Figure 18. AD9716 Precalibration INL at 3.3 V


Figure 19. AD9716 Precalibration DNL at 3.3 V


Figure 20. AD9715 Precalibration INL at 1.8 V


Figure 21. AD9716 Postcalibration INL at 3.3 V


Figure 22. AD9716 Postcalibration DNL at 3.3 V


Figure 23. AD9715 Postcalibration INL at 1.8 V


Figure 24. AD9715 Precalibration DNL at 1.8 V


Figure 25. AD9715 Precalibration INL at 3.3 V


Figure 26. AD9715 Precalibration DNL at 3.3 V


Figure 27. AD9715 Postcalibration DNL at 1.8 V


Figure 28. AD9715 Postcalibration INL at 3.3 V


Figure 29. AD9715 Postcalibration DNL at 3.3 V


Figure 30. AD9714 Precalibration INL at 1.8 V


Figure 31. AD9714 Precalibration DNL at 1.8 V


Figure 32. AD9714 Precalibration INL at 3.3 V


Figure 33. AD9714 Postcalibration INL at 1.8V


Figure 34. AD9714 Postcalibration DNL at 1.8 V


Figure 35. AD9714 Postcalibration INL at 3.3 V


Figure 36. AD9714 Precalibration DNL at 3.3 V


Figure 37. AD9714/AD9715/AD9716/AD9717 Noise Spectral Density at 1.8 V


Figure 38. AD9717 Noise Spectral Density at Three Temperatures, 1.8 V


Figure 39. AD9714 Postcalibration DNL at 3.3 V


Figure 40. AD9714/AD9715/AD9716/AD9717 Noise Spectral Density at 3.3 V


Figure 41. AD9717 Noise Spectral Density at Three Temperatures, 3.3 V


Figure 42. AD9717 Noise Spectral Density at Two Output Currents, 1.8 V


Figure 43. AD9717 Two Tone Spectrum, 1.8 V


Figure 44. AD9714/AD9715/AD9716/AD9717 IMD at 1.8 V


Figure 45. AD9717 Noise Spectral Density at Three Output Currents, 3.3 V


Figure 46. AD9717 Two Tone Spectrum, 3.3 V


Figure 47. AD9714/AD9715/AD9716/AD9717 IMD at 3.3 V


Figure 48. AD9717 IMD at Three Temperatures, 1.8 V


Figure 49. AD9717 IMD at Three Digital Input Levels, 1.8 V


Figure 50. AD9717 IMD at Two Output Currents, 1.8 V


Figure 51. AD9717 IMD at Three Temperatures, 3.3 V


Figure 52. AD9717 IMD at Three Digital Input Levels, 3.3 V


Figure 53. AD9717 IMD at Three Output Currents, 3.3 V


Figure 54. AD9717 Single-Tone Spectrum, 1.8 V


Figure 55. AD9714/AD9715/AD9716/AD9717 SFDR at 1.8 V


Figure 56. AD9717 SFDR at Three Temperatures, 1.8 V


Figure 57. AD9717 Single-Tone Spectrum, 3.3 V


Figure 58. AD9714/AD9715/AD9716/AD9717 SFDR at 3.3 V


Figure 59. AD9717 SFDR at Three Temperatures, 3.3 V


Figure 60. SFDR at Three Digital Input Levels vs. fiN, 1.8 V


Figure 61. SFDR at Two Output Currents, 1.8 V

> CENTER 22.90 MHz
> RES BW 30kHz
> SPAN 38.84 MHz SWEEP 126ms (601pts)
> TOTAL CARRIER POWER $-19.81 \mathrm{dBm} / 7.87420 \mathrm{MHz}$
> REF CARRIER POWER $-19.81 \mathrm{dBm} / 4.03420 \mathrm{MHz}$
> RCC FILTER: OFF FILTER ALPHA 0.22


Figure 63. SFDR at Three Digital Input Levels vs. fis, 3.3 V


Figure 64. SFDR at Three Output Currents, 3.3 V


Figure 65. AD9717 One-Carrier ACLR, 3.3 V


Figure 66. AD9717 One-Carrier W-CDMA First ACLR, 1.8 V


Figure 67. AD9717 One-Carrier W-CDMA Second ACLR, 1.8 V


Figure 68. AD9717 One-Carrier W-CDMA Third ACLR, 1.8 V


Figure 69. AD9717 One-Carrier W-CDMA First ACLR, 3.3 V


Figure 70. AD9717 One-Carrier W-CDMA Second ACLR, 3.3 V


Figure 71. AD9717 One-Carrier W-CDMA Third ACLR, 3.3 V


TOTAL CARRIER POWER - $23.08 \mathrm{dBm} / 7.87420 \mathrm{MHz}$
REF CARRIER POWER $-25.84 \mathrm{dBm} / 4.03420 \mathrm{MHz}$
RCC FILTER: OFF FILTER ALPHA 0.22
OFFSET INTEG LOWER UPPER


Figure 72. AD9717 Two-Carrier ACLR, 1.8 V


Figure 73. AD9717 Two-Carrier W-CDMA First ACLR, 1.8 V


Figure 74. AD9717 Two-Carrier W-CDMA Second ACLR, 1.8 V


Figure 75. AD9717 Two-Carrier ACLR, 3.3 V


Figure 76. AD9717 Two-Carrier W-CDMA First ACLR, 3.3 V


Figure 77. AD9717 Two-Carrier W-CDMA Second ACLR, 3.3 V


Figure 78. AD9717 Two-Carrier W-CDMA Third ACLR, 1.8 V


Figure 79. AUXDAC DNL


Figure 80. Supply Current vs. Clock Frequency at 1.8 V


Figure 81. AD9717 Two-Carrier W-CDMA Third ACLR, 3.3 V


Figure 82. AUXDAC INL


Figure 83. Supply Current vs. Clock Frequency at 3.3 V

## TERMINOLOGY

## Linearity Error or Integral Nonlinearity (INL)

Linearity error is defined as the maximum deviation of the actual analog output from the ideal output, determined by a straight line drawn from zero scale to full scale.

## Differential Nonlinearity (DNL)

DNL is the measure of the variation in analog value, normalized to full scale, associated with a 1 LSB change in digital input code.

## Monotonicity

A DAC is monotonic if the output either increases or remains constant as the digital input increases.

## Offset Error

Offset error is the deviation of the output current from the ideal of zero. For Ioutp, 0 mA output is expected when the inputs are all 0 . For Ioutn, 0 mA output is expected when all inputs are set to 1 .

## Gain Error

Gain error is the difference between the actual and the ideal output span. The actual span is determined by the difference between the output when all inputs are set to 1 and the output when all inputs are set to 0 .

## Output Compliance Range

Output compliance range is the range of allowable voltage at the output of a current-output DAC. Operation beyond the maximum compliance limits can cause either output stage saturation or breakdown, resulting in nonlinear performance.

## Temperature Drift

Temperature drift is specified as the maximum change from the ambient value $\left(25^{\circ} \mathrm{C}\right)$ to the value at either $\mathrm{T}_{\text {MIN }}$ or $\mathrm{T}_{\text {MAX }}$. For offset and gain drift, the drift is reported in ppm of fullscale range per degree Celsius (ppm FSR $/{ }^{\circ} \mathrm{C}$ ). For reference drift, the drift is reported in parts per million per degree Celsius (ppm/ ${ }^{\circ} \mathrm{C}$ ).

## Power Supply Rejection

Power supply rejection is the maximum change in the full-scale output as the supplies are varied from minimum to maximum specified voltages.

## Settling Time

Settling time is the time required for the output to reach and remain within a specified error band around its final value, measured from the start of the output transition.

Spurious Free Dynamic Range (SFDR)
SFDR is the difference, in decibels (dB), between the peak amplitude of the output signal and the peak spurious signal between dc and the frequency equal to half the input data rate.
Total Harmonic Distortion (THD)
THD is the ratio of the rms sum of the first six harmonic components to the rms value of the measured fundamental. It is expressed as a percentage or in decibels.

Signal-to-Noise Ratio (SNR)
SNR is the ratio of the rms value of the measured output signal to the rms sum of all other spectral components below the Nyquist frequency, excluding the first six harmonics and dc. The value for SNR is expressed in decibels (dB).

Adjacent Channel Leakage Ratio (ACLR)
ACLR is the ratio in decibels relative to the carrier ( dBc ) between the measured power within a channel relative to its adjacent channel.

## Complex Image Rejection

In a traditional two-part upconversion, two images are created around the second IF frequency. These images have the effect of wasting transmitter power and system bandwidth. By placing the real part of a second complex modulator in series with the first complex modulator, either the upper or lower frequency image near the second IF can be rejected.

## THEORY OF OPERATION



Figure 84 shows a simplified block diagram of the AD9714/ AD9715/AD9716/AD9717 that consists of two DACs, digital control logic, and a full-scale output current control. Each DAC contains a PMOS current source array capable of providing a nominal full-scale current ( $\mathrm{I}_{\mathrm{xOUtFs}}$ ) of 2 mA and a maximum of 4 mA . The arrays are divided into 31 equal currents that make up the five most significant bits (MSBs). The next four bits, or middle bits, consist of 15 equal current sources whose value is $1 / 16$ of an MSB current source. The remaining LSBs are binary weighted fractions of the current sources of the middle bits. Implementing the middle and lower bits with current sources, instead of an R-2R ladder, enhances its dynamic performance for multitone or low amplitude signals and helps maintain the high output impedance of the DACs (that is, $>200 \mathrm{M} \Omega$ ).

All of these current sources are switched to one or the other of the two output nodes (Ioutp or Ioutv) via PMOS differential current switches. The switches are based on the architecture that was pioneered in the AD976x family, with further refinements to reduce distortion contributed by the switching transient. This switch architecture also reduces various timing errors and provides matching complementary drive signals to the inputs of the differential current switches.
The analog and digital I/O sections of the AD9714/AD9715/ AD9716/AD9717 have separate power supply inputs (AVDD and DVDDIO) that can operate independently over a 1.8 V to 3.3 V range. The core digital section requires 1.8 V . An optional on-chip

LDO is provided for DVDDIO supplies greater than 1.8 V , or the 1.8 V can be supplied directly through DVDD. A $1.0 \mu \mathrm{~F}$ bypass capacitor at DVDD (Pin 7) is required when using the LDO.
The core is capable of operating at a rate of up to 125 MSPS. It consists of edge-triggered latches and the segment decoding logic circuitry. The analog section includes PMOS current sources, associated differential switches, a 1.0 V band gap voltage reference, and a reference control amplifier.

Each DAC full-scale output current is regulated by the reference control amplifier and can be set from 1 mA to 4 mA via an external resistor, $\mathrm{xR}_{\text {SET }}$, connected to its full-scale adjust pin (FSADJx).
The external resistor, in combination with both the reference control amplifier and voltage reference, $\mathrm{V}_{\text {ReFIO }}$, sets the reference current, $\mathrm{I}_{\text {xREF }}$, which is replicated to the segmented current sources with the proper scaling factor. The full-scale current, $\mathrm{I}_{\mathrm{xOUtF}}$, is $32 \times \mathrm{I}_{\mathrm{xREF}}$.

Optional on-chip xRSET resistors are provided that can be programmed between a nominal value of $8 \mathrm{k} \Omega$ to $32 \mathrm{k} \Omega(4 \mathrm{~mA}$ to $1 \mathrm{~mA} \mathrm{I}_{\mathrm{xO} \text { utfs, }}$ respectively).
The AD9714/AD9715/AD9716/AD9717 provide the option of setting the output common mode to a value other than AVSS via the output common-mode pins (CMLI and CMLQ). This facilitates directly interfacing the output of the AD9714/AD9715/ AD9716/AD9717 to components that require common-mode levels greater than 0 V .

## SERIAL PERIPHERAL INTERFACE (SPI)

The serial port of the AD9714/AD9715/AD9716/AD9717 is a flexible, synchronous serial communications port that allows easy interfacing to many industry-standard microcontrollers and microprocessors. The serial I/O is compatible with most synchronous transfer formats, including both the Motorola SPI and Intel ${ }^{\circ}$ SSR protocols. The interface allows read/write access to all registers that configure the AD9714/AD9715/AD9716/AD9717. Single or multiple byte transfers are supported, as well as MSB first or LSB first transfer formats. The serial interface port of the AD9714/ AD9715/AD9716/AD9717 is configured as a single I/O pin on the SDIO pin.

## GENERAL OPERATION OF THE SERIAL INTERFACE

There are two phases to a communications cycle on the AD9714/ AD9715/AD9716/AD9717. Phase 1 is the instruction cycle, which is the writing of an instruction byte into the AD9714/AD9715/ AD9716/AD9717, coinciding with the first eight SCLK rising edges. In Phase 2, the instruction byte provides the serial port controller of the AD9714/AD9715/AD9716/AD9717 with information regarding the data transfer cycle. The Phase 1 instruction byte defines whether the upcoming data transfer is a read or write, the number of bytes in the data transfer, and the starting register address for the first byte of the data transfer. The first eight SCLK rising edges of each communication cycle are used to write the instruction byte into the AD9714/AD9715/AD9716/AD9717.
A Logic 1 on Pin 35 (RESET/PINMD), followed by a Logic 0 , resets the SPI port timing to the initial state of the instruction cycle. This is true regardless of the present state of the internal registers or the other signal levels present at the inputs to the SPI port. If the SPI port is in the midst of an instruction cycle or a data transfer cycle, none of the present data is written.
The remaining SCLK edges are for Phase 2 of the communication cycle. Phase 2 is the actual data transfer between the AD9714/ AD9715/AD9716/AD9717 and the system controller. Phase 2 of the communication cycle is a transfer of one, two, three, or four data bytes, as determined by the instruction byte. Using one multibyte transfer is the preferred method. Single-byte data transfers are useful to reduce CPU overhead when register access requires one byte only. Registers change immediately upon writing to the last bit of each transfer byte.

## INSTRUCTION BYTE

The instruction byte contains the information shown in Table 11.
Table 11.
MSB

| DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| R/W | N1 | N0 | A4 | A3 | A2 | A1 | A0 |

$\mathrm{R} / \overline{\mathrm{W}}$ (Bit 7 of the instruction byte) determines whether a read or a write data transfer occurs after the instruction byte write. Logic 1 indicates a read operation. Logic 0 indicates a write operation. N1 and N0 (Bit 6 and Bit 5 of the instruction byte) determine the number of bytes to be transferred during the data transfer cycle. The bit decodes are shown in Table 12.

Table 12. Byte Transfer Count

| N1 | N0 | Description |
| :--- | :--- | :--- |
| 0 | 0 | Transfer 1 byte |
| 0 | 1 | Transfer 2 bytes |
| 1 | 0 | Transfer 3 bytes |
| 1 | 1 | Transfer 4 bytes |

A4, A3, A2, A1, and A0 (Bit 4, Bit 3, Bit 2, Bit 1, and Bit 0 of the instruction byte) determine which register is accessed during the data transfer portion of the communications cycle. For multibyte transfers, this address is the starting byte address. The following register addresses are generated internally by the AD9714/AD9715/AD9716/AD9717, based on the LSBFIRST bit (Register 0x00, Bit 6).

## SERIAL INTERFACE PORT PIN DESCRIPTIONS SCLK—Serial Clock

The serial clock pin is used to synchronize data to and from the AD9714/AD9715/AD9716/AD9717 and to run the internal state machines. The SCLK maximum frequency is 20 MHz . All data input to the AD9714/AD9715/AD9716/AD9717 is registered on the rising edge of SCLK. All data is driven out of the AD9714/ AD9715/AD9716/AD9717 on the falling edge of SCLK.

## $\overline{\text { CS—Chip Select }}$

An active low input starts and gates a communications cycle. It allows more than one device to be used on the same serial communications lines. The SDIO/FORMAT pin reaches a high impedance state when this input is high. Chip select should stay low during the entire communications cycle.

## SDIO—Serial Data I/O

The SDIO pin is used as a bidirectional data line to transmit and receive data.

## MSB/LSB TRANSFERS

The serial port of the AD9714/AD9715/AD9716/AD9717 can support both most significant bit (MSB) first or least significant bit (LSB) first data formats. This functionality is controlled by the LSBFIRST bit (Register 0x00, Bit 6). The default is MSB first (LSBFIRST $=0$ ).

When LSBFIRST $=0$ (MSB first), the instruction and data bytes must be written from the most significant bit to the least significant bit. Multibyte data transfers in MSB first format start with an instruction byte that includes the register address of the most significant data byte. Subsequent data bytes should follow in order from a high address to a low address. In MSB first mode, the serial port internal byte address generator decrements for each data byte of the multibyte communications cycle.
When LSBFIRST = 1 (LSB first), the instruction and data bytes must be written from the least significant bit to the most significant bit. Multibyte data transfers in LSB first format start with an instruction byte that includes the register address of the least significant data byte followed by multiple data bytes. The serial port internal byte address generator increments for each byte of the multibyte communication cycle.
The serial port controller data address of the AD9714/AD9715/ AD9716/AD9717 decrements from the data address written toward $0 \times 00$ for multibyte I/O operations if the MSB first mode is active. The serial port controller address increments from the data address written toward $0 \times 1 \mathrm{~F}$ for multibyte I/O operations if the LSB first mode is active.

## SERIAL PORT OPERATION

The serial port configuration of the AD9714/AD9715/AD9716/ AD9717 is controlled by Register 0x00. It is important to note that the configuration changes immediately upon writing to the last bit of the register. For multibyte transfers, writing to this register can occur during the middle of the communications cycle. Care must be taken to compensate for this new configuration for the remaining bytes of the current communications cycle.
The same considerations apply to setting the software reset bit (Register 0x00, Bit 5). All registers are set to their default values except Register 0x00, which remains unchanged.

Use of single-byte transfers or initiating a software reset is recommended when changing serial port configurations to prevent unexpected device behavior.


Figure 85. Serial Register Interface Timing, MSB First Write


Figure 86. Serial Register Interface Timing, MSB First Read


Figure 87. Serial Register Interface Timing, LSB First Write


Figure 88. Serial Register Interface Timing, LSB First Read

## PIN MODE

The AD9714/AD9715/AD9716/AD9717 can also be operated without ever writing to the serial port. With the RESET/PINMD pin tied high, the SCLK pin becomes CLKMD to provide for clock mode control (see the Retimer section), the SDIO pin becomes FORMAT and selects the input data format, and the $\overline{\mathrm{CS}} / \mathrm{PWRDN}$ pin serves to power down the device.

Operation is otherwise exactly as defined by the default register values in Table 13; therefore, external resistors at FSADJI and FSADJQ are needed to set the DAC currents, and both DACs are active. This is also a convenient quick checkout mode.
DAC currents can be externally adjusted in pin mode by sourcing or sinking currents at the FSADJI/AUXI and FSADJQ/AUXQ pins as desired with the fixed resistors installed. An op amp output with appropriate series resistance is one of many possibilities. This has the same effect as changing the resistor value. Place at least $10 \mathrm{k} \Omega$ resistors in series right at the DAC to guard against accidental short circuits and noise modulation. The REFIO pin can be adjusted $\pm 25 \%$ in a similar manner, if desired.

## AD9714/AD9715/AD9716/AD9717

## SPI REGISTER MAP

Table 13.

| Name | Addr | Default | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SPI Control | 0x00 | 0x00 | Reserved | LSBFIRST | Reset | LNGINS |  |  |  |  |
| Power-Down | 0x01 | 0x40 | LDOOFF | LDOSTAT | PWRDN | Q DACOFF | I DACOFF | QCLKOFF | ICLKOFF | EXTREF |
| Data Control | $0 \times 02$ | 0x34 | TWOS | Reserved | IFIRST | IRISING | SIMULBIT | DCI_EN | DCOSGL | DCODBL |
| I DAC Gain | 0x03 | 0x00 | Reserved |  | I DACGAIN[5:0] |  |  |  |  |  |
| IRSET | 0x04 | 0x00 | IRSETEN | Reserved | IRSET[5:0] |  |  |  |  |  |
| IRCML | 0x05 | 0x00 | IRCMLEN | Reserved | IRCML[5:0] |  |  |  |  |  |
| Q DAC Gain | 0x06 | 0x00 | Reserved |  | Q DACGAIN[5:0] |  |  |  |  |  |
| QRSET | 0x07 | 0x00 | QRSETEN | Reserved | QRSET[5:0] |  |  |  |  |  |
| QRCML | 0x08 | 0x00 | QRCMLEN | Reserved | QRCML[5:0] |  |  |  |  |  |
| AUXDAC Q | 0x09 | 0x00 | QAUXDAC[7:0] |  |  |  |  |  |  |  |
| AUX CTLQ | 0x0A | 0x00 | QAUXEN | QAUXRNG[1:0] |  | QAUXOFS[2:0] |  |  | QAUXDAC[9:8] |  |
| AUXDAC I | 0x0B | 0x00 | IAUXDAC[7:0] |  |  |  |  |  |  |  |
| AUX CTLI | 0x0C | 0x00 | IAUXEN | IAUXRNG[1:0] |  | IAUXOFS[2:0] |  |  | IAUXDAC[9:8] |  |
| Reference Resistor | 0x0D | 0x00 | Reserved |  | RREF[5:0] |  |  |  |  |  |
| Cal Control | 0x0E | 0x00 | PRELDQ | PRELDI | CALSELQ | CALSELI | CALCLK | DIVSEL[2:0] |  |  |
| Cal Memory | 0x0F | 0x00 | CALSTATQ | CALSTATI |  |  | CALMEMQ[1:0] |  | CALMEMI[1:0] |  |
| Memory Address | 0x10 | 0x00 | Reserved |  | MEMADDR[5:0] |  |  |  |  |  |
| Memory Data | 0x11 | 0x34 | Reserved |  | MEMDATA[5:0] |  |  |  |  |  |
| Memory R/W | 0x12 | 0x00 | CALRSTQ | CALRSTI |  | CALEN | SMEMWR | SMEMRD | UNCALQ | UNCALI |
| CLKMODE | 0x14 | 0x00 | CLKMODEQ[1:0] |  |  | Searching | Reacquire | CLKMODEN | CLKMODEI[1:0] |  |
| Version | 0x1F | 0x03 | Version[7:0] |  |  |  |  |  |  |  |

## SPI REGISTER DESCRIPTIONS

Reading these registers returns previously written values for all defined register bits, unless otherwise noted.
Table 14.

| Register | Address | Bit | Name | Description |
| :---: | :---: | :---: | :---: | :---: |
| SPI Control | 0x00 | 6 5 4 | LSBFIRST <br> Reset <br> LNGINS | 0 (default): MSB first, per SPI standard. <br> 1: LSB first, per SPI standard. <br> Note that the user must always change the LSB/MSB order in single-byte instructions to avoid erratic behavior due to bit order errors. <br> Execute software reset of SPI and controllers, reload default register values except Register 0x00. <br> 1: sets software reset; write 0 on the next (or any following) cycle to release reset. <br> 0 (default): the SPI instruction word uses a 5-bit address. <br> 1: the SPI instruction word uses a 13-bit address. |
| Power-Down | $0 \times 01$ | 7 6 5 4 4 3 2 1 0 | LDOOFF <br> LDOSTAT <br> PWRDN <br> Q DACOFF <br> I DACOFF <br> QCLKOFF <br> ICLKOFF <br> EXTREF | 0 (default): LDO voltage regulator on. <br> 1: turns core LDO voltage regulator off. <br> 0 : indicates that the core LDO voltage regulator is off. <br> 1 (default): indicates that the core LDO voltage regulator is on. <br> 0 (default): all analog and digital circuitry and SPI logic are powered on. <br> 1: powers down all analog and digital circuitry except for SPI logic. <br> 0 (default): turns on Q DAC output current. <br> 1: turns off Q DAC output current. <br> 0 (default): turns on I DAC output current. <br> 1: turns off I DAC output current. <br> 0 (default): turns on Q DAC clock. <br> 1: turns off Q DAC clock. <br> 0 (default): turns on I DAC clock. <br> 1: turns off I DAC clock. <br> 0 (default): turns on internal voltage reference. <br> 1: powers down internal voltage reference (external reference required). |
| Data Control | 0x02 | 7 5 4 3 2 2 1 0 | TWOS <br> IFIRST <br> IRISING <br> SIMULBIT <br> DCI_EN <br> DCOSGL <br> DCODBL | 0 (default): unsigned binary input data format. <br> 1: twos complement input data format. <br> 0 : pairing of data-Q first of pair on data input pads. <br> 1 (default): pairing of data-I first of pair on data input pads. <br> 0 : Q data latched on DCLKIO rising edge. <br> 1 (default): I data latched on DCLKIO rising edge. <br> 0 (default): allows simultaneous input and output enable on DCLKIO. <br> 1: disallows simultaneous input and output enable on DCLKIO. <br> Controls the use of the DCLKIO pad for data clock input. <br> 0 : data clock input disabled. <br> 1 (default): data clock input enabled. <br> Controls the use of the DCLKIO pad for data clock output. <br> 0 (default): data clock output disabled. <br> 1: data clock output enabled; regular strength driver. <br> Controls the use of the DCLKIO pad for data clock output. <br> 0 (default): DCODBL data clock output disabled. <br> 1: DCODBL data clock output enabled; paralleled with DCOSGL for $2 \times$ drive current. |
| I DAC Gain | $0 \times 03$ | 5:0 | I DACGAIN[5:0] | DAC I fine gain adjustment; alters the full-scale current as shown in Figure 100. Default IDACGAIN $=0 \times 00$. |

## AD9714/AD9715/AD9716/AD9717

\begin{tabular}{|c|c|c|c|c|}
\hline Register \& Address \& Bit \& Name \& Description \\
\hline IRSET \& 0x04 \& 7
5:0 \& IRSETEN
IRSET[5:0] \& \begin{tabular}{l}
0 (default): IRSET resistor value for I channel is set by an external resistor connected to the FADJ//AUXI pin. Nominal value for this external resistor is \(16 \mathrm{k} \Omega\). \\
1: enables the on-chip IRSET value to be changed for I channel. \\
Changes the value of the on-chip IRSET resistor for I channel; this scales the full-scale current of the DAC in \(\sim 0.25 \mathrm{~dB}\) steps twos complement (nonlinear); see Figure 99. 000000 (default): \(\operatorname{IR}\) SEt \(=16 \mathrm{k} \Omega\). \\
011111: IRSET \(=32 \mathrm{k} \Omega\). \\
\(100000: \mathrm{I}_{\text {SET }}=8 \mathrm{k} \Omega\). \\
111111: \(\mathrm{IR}_{\text {SET }}=16 \mathrm{k} \Omega\).
\end{tabular} \\
\hline IRCML \& 0x05 \& 7
5:0 \& \begin{tabular}{l}
IRCMLEN \\
IRCML[5:0]
\end{tabular} \& \begin{tabular}{l}
0 (default): \(\mathrm{R}_{\text {СмL }}\) resistor value for the I channel is set by an external resistor connected to the CMLI pin. Recommended value for this external resistor is \(0 \Omega\). 1: enables on-chip IRсмц adjustment for I channel. \\
Changes the value of the on-chip IRcmı resistor for I channel; this adjusts the common-mode level of the DAC output stage.
\[
\begin{aligned}
\& 000000 \text { (default): } \mathrm{IR} \text { CML }=250 \Omega . \\
\& 100000: \text { IRCML }^{2} 25 \Omega . \\
\& 111111: \mathrm{I}_{\text {CML }}=1 \mathrm{k} \Omega .
\end{aligned}
\]
\end{tabular} \\
\hline Q DAC Gain \& 0x06 \& 5:0 \& Q DACGAIN[5:0] \& DAC Q fine gain adjustment; alters the full-scale current as shown in Figure 100. Default QDACGAIN \(=0 \times 00\). \\
\hline QRSET \& 0x07 \& 7
5:0 \& \begin{tabular}{l}
QRSETEN \\
QRSET[5:0]
\end{tabular} \& \begin{tabular}{l}
0 (default): QR \({ }_{\text {SEt }}\) resistor value for Q channel is set by an external resistor connected to the FADJQ/AUXQ pin. Recommended value for this external resistor is \(16 \mathrm{k} \Omega\). 1: enables on-chip \(Q_{\text {set }}\) adjustment for \(Q\) channel. \\
Changes the value of the on-chip QRset \(_{\text {res }}\) restor for \(Q\) channel; this scales the fullscale current of the DAC in \(\sim 0.25 \mathrm{~dB}\) steps twos complement (nonlinear); see Figure 99.
\end{tabular} \\
\hline QRCML \& 0x08 \& 7
5:0 \& \begin{tabular}{l}
QRCMLEN \\
QRCML[5:0]
\end{tabular} \& \begin{tabular}{l}
0 (default): QRcmı resistor value for the Q channel is set by an external resistor connected to CMLQ pin. Recommended value for this external resistor is \(0 \Omega\). 1: enables on-chip QRcmL adjustment for Q channel. \\
Changes the value of the on-chip QRсмц resistor for Q channel; this adjusts the common-mode level of the DAC output stage.
\[
\begin{aligned}
\& 000000 \text { (default): QRcML }=250 \Omega . \\
\& \text { 100000: QRCML }=625 \Omega . \\
\& \text { 111111: QRCML }=1 \mathrm{k} \Omega .
\end{aligned}
\]
\end{tabular} \\
\hline AUXDAC Q \& 0x09 \& 7:0 \& QAUXDAC[7:0] \& \begin{tabular}{l}
AUXDAC Q output voltage adjustment word LSBs. \\
\(0 \times 3 F F\) : sets AUXDAC Q output to full scale. \\
\(0 \times 200\) : sets AUXDAC Q output to midscale. \\
\(0 \times 000\) (default): sets AUXDAC Q output to bottom of scale.
\end{tabular} \\
\hline AUX CTLQ \& 0x0A \& 7
7:5

$4: 2$

1:0 \& \begin{tabular}{l}
QAUXEN <br>
QAUXRNG[1:0] <br>
QAUXOFS[2:0] <br>
QAUXDAC[9:8]

 \& 

0 (default): AUXDAC Q output disabled. <br>
1: enables AUXDAC Q output. <br>
00 (default): sets AUXDAC Q output voltage range to 2 V . <br>
01: sets AUXDAC Q output voltage range to 1.5 V . <br>
10: sets AUXDAC Q output voltage range to 1.0 V . <br>
11: sets AUXDAC Q output voltage range to 0.5 V . <br>
000 (default): sets AUXDAC Q top of range to 1.0 V . <br>
001: sets AUXDAC Q top of range to 1.5 V . <br>
010: sets AUXDAC Q top of range to 2.0 V . <br>
011: sets AUXDAC Q top of range to 2.5 V . <br>
100 : sets AUXDAC Q top of range to 2.9 V . <br>
AUXDAC Q output voltage adjustment word MSBs (default $=00$ ).
\end{tabular} <br>

\hline
\end{tabular}

\begin{tabular}{|c|c|c|c|c|}
\hline Register \& Address \& Bit \& Name \& Description \\
\hline AUXDACI \& 0x0B \& 7:0 \& IAUXDAC[7:0] \& \begin{tabular}{l}
AUXDAC I output voltage adjustment word LSBs. \\
\(0 \times 3 F F\) : sets AUXDAC I output to full scale. \\
\(0 \times 200\) : sets AUXDAC I output to midscale. \\
\(0 \times 000\) (default): sets AUXDAC I output to bottom of scale.
\end{tabular} \\
\hline AUX CTLI \& 0x0C \& \begin{tabular}{l}
7 \\
6:5 \\
4:2 \\
1:0
\end{tabular} \& \begin{tabular}{l}
IAUXEN \\
IAUXRNG[1:0] \\
IAUXOFS[2:0] \\
IAUXDAC[9:8]
\end{tabular} \& \begin{tabular}{l}
0 (default): AUXDAC I output disabled. \\
1: enables AUXDAC I output. \\
00 (default): sets AUXDAC I output voltage range to 2 V . \\
01: sets AUXDAC I output voltage range to 1.5 V . \\
10: sets AUXDAC I output voltage range to 1.0 V . \\
11: sets AUXDAC I output voltage range to 0.5 V . \\
000 (default): sets AUXDAC I top of range to 1.0 V . \\
001: sets AUXDAC I top of range to 1.5 V . \\
010: sets AUXDAC I top of range to 2.0 V . \\
011: sets AUXDAC I top of range to 2.5 V . \\
100: sets AUXDAC I top of range to 2.9 V . \\
AUXDAC I output voltage adjustment word MSBs (default = 00).
\end{tabular} \\
\hline Reference Resistor \& 0x0D \& 5:0 \& RREF[5:0] \& \begin{tabular}{l}
Permits an adjustment of the on-chip reference voltage and output at REFIO (see Figure 98) twos complement. \\
000000 (default): sets the value of \(R_{\text {REF }}\) to \(10 \mathrm{k} \Omega, \mathrm{V}_{\text {REF }}=1.0 \mathrm{~V}\). \\
011111: sets the value of \(R_{\text {REF }}\) to \(12 \mathrm{k} \Omega, \mathrm{V}_{\text {REF }}=1.2 \mathrm{~V}\). \\
100000: sets the value of \(R_{\text {REF }}\) to \(8 \mathrm{k} \Omega, \mathrm{V}_{\text {REF }}=0.8 \mathrm{~V}\). \\
111111: sets the value of \(R_{\text {REF }}\) to \(10 \mathrm{k} \Omega, \mathrm{V}_{\text {REF }}=1.0 \mathrm{~V}\).
\end{tabular} \\
\hline Cal Control \& 0x0E \& \begin{tabular}{l}
7 \\
6 \\
5 \\
4 \\
3 \\
2:0
\end{tabular} \& \begin{tabular}{l}
PRELDQ \\
PRELDI \\
CALSELQ \\
CALSELI \\
CALCLK \\
DIVSEL[2:0]
\end{tabular} \& \begin{tabular}{l}
0 (default): preload Q DAC calibration reference set to 32 . \\
1: preload Q DAC calibration reference set by user (Cal Address 1). \\
0 (default): preload I DAC calibration reference set to 32. \\
1: preload I DAC calibration reference set by user (Cal Address 1). \\
0 (default): Q DAC self-calibration done. \\
1: select Q DAC self-calibration. \\
0 (default): I DAC self-calibration done. \\
1: select I DAC self-calibration. \\
0 (default): calibration clock disabled. \\
1: calibration clock enabled. \\
Calibration clock divide ratio from DAC clock rate. \\
000 (default): divide by 256. \\
001: divide by 128. \\
... \\
110: divide by 4 . \\
111: divide by 2.
\end{tabular} \\
\hline Cal Memory \& 0x0F \& 7
6
\(3: 2\)

$1: 0$ \& | CALSTATQ |
| :--- |
| CALSTATI |
| CALMEMQ[1:0] |
| CALMEMI[1:0] | \& | 0 (default): Q DAC calibration in progress. |
| :--- |
| 1: calibration of Q DAC complete. |
| 0 (default): I DAC calibration in progress. |
| 1: calibration of I DAC complete. |
| Status of Q DAC calibration memory. |
| 00 (default): uncalibrated. |
| 01: self-calibrated. |
| 10: user calibrated. |
| Status of I DAC calibration memory. |
| 00 (default): uncalibrated. |
| 01: self-calibrated. |
| 10: user calibrated. | <br>

\hline Memory Address \& 0x10 \& 5:0 \& MEMADDR[5:0] \& Address of static memory to be accessed. <br>
\hline Memory Data \& 0x11 \& 5:0 \& MEMDATA[5:0] \& Data for static memory access. <br>
\hline
\end{tabular}

## AD9714/AD9715/AD9716/AD9717

| Register | Address | Bit | Name | Description |
| :---: | :---: | :---: | :---: | :---: |
| Memory R/W | 0x12 | 7 | CALRSTQ | 0 (default): no action. <br> 1: clear CALSTATQ. |
|  |  | 6 | CALRSTI | 0 (default): no action. <br> 1: clear CALSTATI. |
|  |  | 4 | CALEN | 0 (default): no action. <br> 1: initiate device self-calibration. |
|  |  | 3 | SMEMWR | 0 (default): no action. <br> 1: write to static memory (calibration coefficients). |
|  |  | 2 | SMEMRD | 0 (default): no action. <br> 1: read from static memory (calibration coefficients). |
|  |  | 1 | UNCALQ | 0 (default): no action. <br> 1: reset Q DAC calibration coefficients to default (uncalibrated). |
|  |  | 0 | UNCALI | 0 (default): no action. <br> 1: reset I DAC calibration coefficients to default (uncalibrated). |
| CLKMODE | 0x14 | 7:6 | CLKMODEQ[1:0] | Depending on the CLKMODEN bit setting, these two bits reflect the phase relationship between DCLKIO and CLKIN, as described in Table 16. <br> If CLKMODEN $=0$, read only; reports the clock phase chosen by the retimer. If CLKMODEN $=1$, read/write; value in this register sets Q clock phases; force if needed to better synchronize the DACs (see the Retimer section). |
|  |  | 4 | Searching | Data path retimer status bit. <br> 0 (default): clock relationship established. <br> 1: indicates that the internal data path retimer is searching for clock relationship (device output is not usable while this bit is high). |
|  |  | 3 | Reacquire | Edge triggered, 0 to 1 causes the retimer to reacquire the clock relationship. |
|  |  | 2 | CLKMODEN | 0 (default): CLKMODEI/CLKMODEQ values computed by the two retimers and read back in CLKMODEI[1:0] and CLKMODEQ[1:0]. <br> 1: CLKMODE values set in CLKMODEI[1:0] override both I and Q retimers. |
|  |  | 1:0 | CLKMODEI[1:0] | Depending on CLKMODEN bit setting, these two bits reflect the phase relationship between DCLKIO and CLKIN as described in Table 16. If CLKMODEN $=0$, read only; reports the clock phase chosen by the retimer. If CLKMODEN $=1$, read/write; value in this register sets I clock phases; force if needed to better synchronize the DACs (see the Retimer section). |
| Version | 0x1F | 7:0 | Version[7:0] | Hardware version of the device. This register is set to $0 \times 03$ for the latest version of the device. |

## DIGITAL INTERFACE OPERATION

Digital data for the I and Q DACs is supplied over a single parallel bus ( $\mathrm{DB}[\mathrm{n}: 0$ ), where n is 7 for the AD9714, 9 for the AD9715, 11 for the AD9716, and 13 for the AD9717) accompanied by a qualifying clock (DCLKIO). The I and Q data are provided to the chip in an interleaved double data rate (DDR) format. The maximum guaranteed data rate is 250 MSPS with a 125 MHz clock. The order of data pairing and the sampling edge selection is user programmable using the IFIRST and IRISING data control bits, resulting in four possible timing diagrams. These are shown in Figure 89, Figure 90, Figure 91, and Figure 92.

notes:

1. DB[n:0], WHERE $n$ IS 7 FOR THE AD9714, 9 FOR THE AD9715, 11 FOR THE AD9716, AND 13 FOR THE AD9717.

Figure 89. Timing Diagram with $I F I R S T=0, I R I S I N G=0$


NOTES:

1. DB[n:0], WHERE $n$ IS 7 FOR THE AD9714, 9 FOR THE AD9715, 11 FOR THE AD9716, AND 13 FOR THE AD9717.

Figure 90. Timing Diagram with IFIRST $=0, I$ IRISING $=1$


NOTES:

1. DB[n:0], WHERE n IS 7 FOR THE AD9714, 9 FOR THE AD9715, 11 FOR THE AD9716, AND 13 FOR THE AD9717.

Figure 91. Timing Diagram with $\operatorname{IFIRST}=1, I$ IISING $=0$


NOTES:

1. DB[n: 0 ], WHERE $n$ IS 7 FOR THE AD9714, 9 FOR THE AD9715, 11 FOR THE AD9716, AND 13 FOR THE AD9717.

Figure 92. Timing Diagram with $\operatorname{IFIRST}=1, I$ IRISING $=1$
Ideally, the rising and falling edges of the clock fall in the center of the keep-in-window formed by the setup and hold times, $\mathrm{t}_{\mathrm{s}}$ and $t_{H}$. Refer to Table 2 for setup and hold times. A detailed timing diagram is shown in Figure 93.


In addition to the different timing modes listed in Table 2, the input data can also be presented to the device in either unsigned binary or twos complement format. The format type is chosen via the TWOS data control bit.


## NOTES:

1. DB[n:0], WHERE n IS 7 FOR THE AD9714, 9 FOR THE AD9715, 11 FOR THE AD9716, AND 13 FOR THE AD9717.

Figure 94. Simplified Diagram of AD9714/AD9715/AD9716/AD9717 Timing

## DIGITAL DATA LATCHING AND RETIMER BLOCK

The AD9714/AD9715/AD9716/AD9717 have two clock inputs, DCLKIO and CLKIN. The CLKIN is the analog clock whose jitter affects DAC performance, and the DCLKIO is a digital clock from an FPGA that needs to have a fixed relationship with the input data to ensure that the data is picked up correctly by the flip-flops on the pads.
Figure 94 is a simplified diagram of the entire data capture system in the AD9714/AD9715/AD9716/AD9717. The double data rate input data ( $\mathrm{DB}[\mathrm{n}: 0$ ), where n is 7 for the AD9714, 9 for the AD9715, 11 for the AD9716, and 13 for the AD9717) is latched at the pads/pins either on the rising edge or the falling edge of the DCLKIO-INT clock, as determined by IRISING, Bit 4 of SPI Address 0x02. Bit 5 of SPI Address 0x02, IFIRST, determines which channel data is latched first (that is, I or Q). The captured data is then retimed to the internal clock (CLKIN-INT) in the retimer block before being sent to the final analog DAC core (D-FF 4), which controls the current steering output switches. All delay blocks depicted in Figure 94 are noninverting, and any wires without an explicit delay block can be assumed to have no delay.
Only one channel is shown in Figure 94 with the data pads ( $\mathrm{DB}[\mathrm{n}: 0)$, where n is 7 for the AD9714, 9 for the AD9715, 11 for the AD9716, and 13 for the AD9717) serving as double data rate pads for both channels.
The default PINMD and SPI settings are IE $=$ high (closed) and $\mathrm{OE}=$ low (open). These settings are enabled when RESET/ PINMD (Pin 35) is held high. In this mode, the user has to supply both DCLKIO and CLKIN. In PINMD, it is also recommended that the DCLKIO and the CLKIN be in phase for proper functioning of the DAC, which can easily be ensured by tying the pins together on the PCB. If the user can access the SPI, setting Bit 2 of SPI Address 0x02, DCI_EN, to logic low causes the CLKIN to be used as the DCLKIO also.

Setting Bit 1 or Bit 0 of SPI Address $0 \times 02$, DCOSGL or DCODBL, respectively, to logic high allows the user to obtain a DCLKIO output from the CLKIN input for use in the user's PCB system.

It is strongly recommended that DCI_EN = DCOSGL $=$ high or DCI_EN = DCODBL $=$ high not be used even though the device may appear to function correctly. Similarly, do not set DCOSGL and DCODBL to logic high simultaneously.

## Retimer

The AD9714/AD9715/AD9716/AD9717 have an internal data retimer circuit that compares the CLKIN-INT and DCLKIO-INT clocks and, depending on their phase relationship, selects a retimer clock (RETIMER-CLK) to safely transfer data from the DCLKIO used at the chip's input interface to the CLKIN used to clock the analog DAC cores (D-FF 4).
The retimer selects one of the three phases shown in Figure 95. The retimer is controlled by the CLKMODE SPI bits, as shown in Table 15.


Note that, in most cases, more than one retimer phase works and ,in such cases, the retimer arbitrarily picks one phase that works. The retimer cannot pick the best or safest phase. If the user has a working knowledge of the exact phase relationship between DCLKIO and CLKIN (and thus DCLKIO-INT and CLKIN-INT because the delay is approximately the same for both clocks and equal to DELAY1), then the retimer can be forced to this phase with CLKMODEN $=1$, as described in Table 15 and the following paragraphs.

Table 15. Timer Register List

| Bit Name | Description |
| :--- | :--- |
| CLKMODEQ[1:0] | Q data path retimer clock selected output. Valid after the searching bit goes low. <br> Sigh indicates that the internal data path retimer is searching for the clock relationship (DAC is not usable until it is low again). <br> Reacquire |
| CLKMODEN <br> Changing this bit from 0 to 1 causes the data path retimer circuit to reacquire the clock relationship. <br> 0: uses CLKMODEI/CLKMODEQ values (as computed by the two internal retimers) for I and Q clocking. |  |
| CLKMODEI[1:0] | 1: uses the CLKMODE value set in CLKMODEI[1:0] to override the bits for both I and Q retimers (that is, force the retimer). <br> I data path retimer clock selected output. Valid after searching goes low. <br> If CLKMODEN = 1, a value written to this register overrides both the I and Q automatic retimer values. |

Table 16. CLKMODEI/CLKMODEQ Details

| CLKMODEI[1:0]/CLKMODEQ[1:0] | DCLKIO-to-CLKIN Phase Relationship | RETIMER-CLK Selected |
| :--- | :--- | :--- |
| 00 | $0^{\circ}$ to $90^{\circ}$ | Phase 2 |
| 01 | $90^{\circ}$ to $180^{\circ}$ | Phase 3 |
| 10 | $180^{\circ}$ to $270^{\circ}$ | Phase 3 |
| 11 | $270^{\circ}$ to $360^{\circ}$ | Phase 1 |

When RESET is pulsed high and then returns low (the part is in SPI mode), the retimer runs and automatically selects a suitable clock phase for the RETIMER-CLK within 128 clock cycles. The SPI searching bit, Bit 4 of SPI Address 0x14, returns to low, indicating that the retimer has locked and the part is ready for use. The reacquire bit, Bit 3 of SPI Address 0x14, can be used to reinitiate phase detection in the I and Q retimers at any time. CLKMODEQ[1:0] and CLKMODEI[1:0] of SPI Address 0x14 provide readback for the values picked by the internal phase detectors in the retimer (see Table 16).

To force the two retimers (I and Q) to pick a particular phase for the retimer clock (they must both be forced to the same value), CLKMODEN, Bit 2 of SPI Address 0x14, should be set high and the required phase value is written into CLKMODEI[1:0] and CLKMODEQ[1:0]. For example, if the DCLKIO and the CLKIN are in phase to the first order, the user can safely force the retimers to pick Phase 2 for the RETIMER-CLK. This forcing function may be useful for synchronizing multiple devices.

In pin mode, it is expected that the user tie CLKIN and DCLKIO together. The device has a small amount of programmable functionality using the unused SPI pins (SCLK, SDIO, and $\overline{\mathrm{CS}}$ ). If the two chip clocks are tied together, the SCLK pin can be tied to ground, and the chip uses a clock for the retimer that is $180^{\circ}$ out of phase with the two input clocks (that is, Phase 2, which is the safest and best option). The chip has an additional option in pin mode when the redefined SCLK pin is high. Use this mode if using pin mode, but CLKIN and DCLKIO are not tied together (that is, not in phase). Holding SCLK high causes the internal clock detector to use the phase detector output to determine which clock to use in the retimer (that is, select a suitable RETIMER-CLK phase). The action of taking SCLK high causes the internal phase detector to reexamine the two clocks and determine the relative phase. Whenever the user wants to reevaluate the relative phase of the two clocks, the SCLK pin can be taken low and then high again.

## ESTIMATING THE OVERALL DAC PIPELINE DELAY

DAC pipeline latency is affected by the phase of the RETIMERCLK that is selected. If latency is critical to the system and must be constant, the retimer should be forced to a particular phase and not be allowed to automatically select a phase each time.

Consider the case in which DCLKIO = CLKIN (that is, in phase), and the RETIMER-CLK is forced to Phase 2. Assume that IRISING is 1 (that is, I data is latched on the rising edge and Q data is latched on the falling edge). Then the latency to the output for the I channel is four clock cycles total; one clock cycle from the input interface (D-FF 1, not D-FF0, as it latches data on either edge and does not cause any delay); two clock cycles from the retimer (D-FF 2 and D-FF 4, but not D-FF 3, because it is latched on the half clock cycle or $180^{\circ}$ ); and one clock cycle going through the analog core (D-FF 5). The latency to the output for the Q channel from the time the falling edge latches it at the pads in D-FF 0 is 3.5 clock cycles (no delay due to D-FF0, 1 clock cycle due to D-FF $1,1 / 2$ clock cycle to D-FF 2,1 clock cycle to DFF 4, and 1 clock cycle to D-FF 5). This latency for the AD9714/ AD9715/AD9716/AD9717 is case specific and needs to be calculated based on the RETIMER-CLK phase that is automatically selected or manually forced.

## REFERENCE OPERATION

The AD9714/AD9715/AD9716/AD9717 contain an internal 1.0 V band gap reference. The internal reference can be disabled by setting Bit 0 (EXTREF) of the power-down register (Address $0 \times 01$ ) through the SPI interface. To use the internal reference, decouple the REFIO pin to AVSS with a $0.1 \mu \mathrm{~F}$ capacitor, enable the internal reference, and clear Bit 0 of the power-down register (Address 0x01) through the SPI interface. Note that this is the default configuration. The internal reference voltage is present at REFIO. If the voltage at REFIO is to be used anywhere else in the circuit, an external buffer amplifier with an input bias current of less than 100 nA must be used to avoid loading the reference. An example of the use of the internal reference is shown in Figure 96.


Figure 96. Internal Reference Configuration
REFIO serves as either an input or an output, depending on whether the internal or an external reference is used. Table 17 summarizes the reference operation.

Table 17. Reference Operation

| Reference Mode | REFIO Pin | Register Setting |
| :--- | :--- | :--- |
| Internal | Connect 0.1 $\mu \mathrm{F}$ <br> capacitor | Register 0x01, Bit 0=0 <br> (default) <br> Apply external <br> capacitor | | Register 0x01, Bit 0 = 1 |
| :--- |
| (for power saving) |

An external reference can be used in applications requiring tighter gain tolerances or lower temperature drift. Also, a variable external voltage reference can be used to implement a method for gain control of the DAC output.

## Recommendations When Using an External Reference

Apply the external reference to the REFIO pin. The internal reference can be directly overdriven by the external reference, or the internal reference can be powered down to save power consumption
The external $0.1 \mu \mathrm{~F}$ compensation capacitor on REFIO is not required unless specified by the external voltage reference manufacturer. The input impedance of REFIO is $10 \mathrm{k} \Omega$ when the internal reference is powered up and $1 \mathrm{M} \Omega$ when it is powered down.

## REFERENCE CONTROL AMPLIFIER

The AD9714/AD9715/AD9716/AD9717 contain a control amplifier that regulates the full-scale output current, $\mathrm{I}_{\mathrm{x} \text { OUtFs }}$. The control amplifier is configured as a V-I converter, as shown in Figure 96 . The output current, $\mathrm{I}_{\mathrm{xREF}}$, is determined by the ratio of the $\mathrm{V}_{\text {refio }}$ and an external resistor, $\mathrm{xR}_{\text {SET }}$, as stated in Equation 4 (see the DAC Transfer Function section). $\mathrm{I}_{\text {xREF }}$, is mirrored to the segmented current sources with the proper scale factor to set $\mathrm{I}_{\text {xoutrs }}$, as stated in Equation 3.
The control amplifier allows a $2.5: 1$ adjustment span of $I_{x O U T F S}$ from 1 mA to 4 mA by setting $\mathrm{I}_{\text {xReF }}$ between $125 \mu \mathrm{~A}$ and $31.25 \mu \mathrm{~A}$ (set $\mathrm{xR} \mathrm{R}_{\text {SET }}$ between $8 \mathrm{k} \Omega$ and $32 \mathrm{k} \Omega$ ). The wide adjustment span of $\mathrm{I}_{\mathrm{xO} \text { utfs }}$ provides several benefits. The first relates directly to the power dissipation of the AD9714/AD9715/AD9716/AD9717, which is proportional to $\mathrm{I}_{\mathrm{xO} \text { outrs }}$ (see the DAC Transfer Function section). The second benefit relates to the ability to adjust the output over a 8 dB range with 0.25 dB steps, which is useful for controlling the transmitted power. The small signal bandwidth of the reference control amplifier is approximately 500 kHz . This allows the device to be used for low frequency, small signal multiplying applications.
When an external resistor greater than $16 \mathrm{k} \Omega$ is used on the FSADJx pins, care must be taken to maintain the high frequency equivalent circuit to an impedance lower than $16 \mathrm{k} \Omega$ by splitting the resistor into two resistors in series with a 10 nF capacitor in parallel with the resistor to AVSS (see Figure 97).


Figure 97. $x R_{\text {SET }}$ Configuration for Values $>16 \mathrm{k} \Omega$

## DAC TRANSFER FUNCTION

The AD9714/AD9715/AD9716/AD9717 provide two differential current outputs, IOUTP/IOUTN and QOUTP/QOUTN. IOUTP and QOUTP provide a near full-scale current output, $\mathrm{I}_{\mathrm{xO}}$ trfs, when all bits are high (that is, $\mathrm{DAC} \operatorname{CODE}=2^{\mathrm{N}}-1$, where $\mathrm{N}=8,10,12$, or 14 for the AD9714, AD9715, AD9716, and AD9717, respectively), while IOUTN and QOUTN, the complementary outputs, provide no current. The current outputs appearing at the positive DAC outputs, IOUTP and QOUTP, and at the negative DAC outputs, IOUTN and QOUTN, are a function of both the input code and $\mathrm{I}_{\mathrm{xoutfs}}$ and can be expressed as follows:

$$
\begin{align*}
& \text { IOUTP }=\left(I D A C ~ C O D E / 2^{N}\right) \times I_{\text {IOUTFS }}  \tag{1}\\
& \text { QOUTP }=\left(Q D A C C O D E / 2^{N}\right) \times I_{\text {QOUTFS }} \\
& \text { IOUTN }=\left(\left(2^{N}-1\right)-I D A C C O D E\right) / 2^{N} \times I_{\text {IOUTFS }}  \tag{2}\\
& \text { QOUTN }=\left(\left(2^{N}-1\right)-Q D A C \text { CODE }\right) / 2^{N} \times I_{\text {QOUTFS }}
\end{align*}
$$

where:
$I D A C ~ C O D E$ and $Q D A C C O D E=0$ to $2^{\mathrm{N}}-1$ (that is, decimal representation).
$I_{\text {IOUTES }}$ and $I_{\text {QOUTFS }}$ are functions of the reference currents, $\mathrm{I}_{\text {IREF }}$ and $\mathrm{I}_{\mathrm{QREF}}$, respectively, which are nominally set by a reference voltage, $\mathrm{V}_{\text {REFIO }}$, and external resistors, $\mathrm{IR}_{\text {SET }}$ and $\mathrm{QR}_{\text {SET }}$, respectively. IIoutrs and $\mathrm{I}_{\text {Qoutrs }}$ can be expressed as follows:

$$
\begin{align*}
& I_{\text {IOUTFS }}=32 \times I_{\text {IREF }}  \tag{3}\\
& I_{\text {QOUTFS }}=32 \times I_{\text {QREF }}
\end{align*}
$$

where:

$$
\begin{equation*}
I_{I R E F}=V_{\text {REFIO }} / I R_{S E T} \tag{4}
\end{equation*}
$$

$I_{Q R E F}=V_{\text {REFIO }} / Q R_{\text {SET }}$
or

$$
\begin{align*}
& I_{\text {IOUTFS }}=32 \times V_{\text {REFII }} / R_{\text {SET }}  \tag{5}\\
& \mathrm{I}_{\mathrm{QOUTFS}}=32 \times \mathrm{V}_{\mathrm{REFIO}} / \mathrm{QR}_{\text {SET }}
\end{align*}
$$

A differential pair (IOUTP/IOUTN or QOUTP/QOUTN) typically drives a resistive load directly or via a transformer. If dc coupling is required, the differential pair (IOUTP/IOUTN or QOUTP/QOUTN) should be connected to matching resistive loads, $\mathrm{xR}_{\text {LOAD }}$, that are tied to analog common, AVSS. The single-ended voltage output appearing at the positive and negative nodes is

$$
\begin{align*}
& V_{I O U T P}=I O U T P \times I R_{\text {LOAD }}  \tag{6}\\
& V_{\text {QOUTP }}=Q O U T P \times Q R_{\text {LOAD }} \\
& V_{\text {IOUTN }}=I O U T N \times I R_{\text {LOAD }}  \tag{7}\\
& V_{\text {QOUTN }}=Q O U T N \times Q R_{\text {LOAD }}
\end{align*}
$$

To achieve the maximum output compliance of 1 V at the nominal 4 mA output current, $\mathrm{IR}_{\text {LOAD }}=\mathrm{QR}_{\text {LOAD }}$ must be set to $250 \Omega$.

Substituting the values of IOUTP, IOUTN, and $\mathrm{I}_{\text {xREF }}, \mathrm{V}_{\text {Idiff }}$ can be expressed as

$$
\begin{align*}
& V_{\text {IDIFF }}=\left\{\left(2 \times I D A C C O D E-\left(2^{N}-1\right)\right) / 2^{N}\right\} \times  \tag{8}\\
& \left(32 \times V_{\text {REFII }} / I R_{S E T}\right) \times I R_{\text {LOAD }}
\end{align*}
$$

Equation 8 highlights some of the advantages of operating the AD9714/AD9715/AD9716/AD9717 differentially. First, the differential operation helps cancel common-mode error sources associated with IOUTP and IOUTN, such as noise, distortion, and dc offsets. Second, the differential code-dependent current and subsequent voltage, $\mathrm{V}_{\text {IIIfF }}$, is twice the value of the single-ended voltage output (that is, $\mathrm{V}_{\text {Ioutp }}$ or $\mathrm{V}_{\text {IoutN }}$ ), thus providing twice the signal power to the load. Note that the gain drift temperature performance for a single-ended output ( $\mathrm{V}_{\text {IOUTP }}$ and $\mathrm{V}_{\text {IOUTN }}$ ) or differential output ( $\mathrm{V}_{\text {IDIFF }}$ ) of the AD9714/AD9715/AD9716/ AD9717 can be enhanced by selecting temperature-tracking resistors for $\mathrm{xR}_{\text {LOAD }}$ and $\mathrm{xR}_{\text {SET }}$ because of their ratiometric relationship, as shown in Equation 8.

## ANALOG OUTPUT

The complementary current outputs in each DAC, IOUTP/ IOUTN and QOUTP/QOUTN, can be configured for singleended or differential operation. IOUTP/IOUTN and QOUTP/ QOUTN can be converted into complementary single-ended voltage outputs, $\mathrm{V}_{\text {Ioutp }}$ and $\mathrm{V}_{\text {iouts, }}$ as well as $\mathrm{V}_{\text {qoutr }}$ and $\mathrm{V}_{\text {qoutn }}$ via a load resistor, $x R_{\text {LOAD }}$, as described in the DAC Transfer Function section by Equation 6 through Equation 8. The differential voltages, $\mathrm{V}_{\text {IDIFF }}$ and $V_{\text {QDiff }}$, existing between $V_{\text {IOUTP }}$ and $V_{\text {IOUTN }}$, and $V_{\text {Qoutr }}$ and $V_{\text {Qoutn, }}$, can also be converted to a single-ended voltage via a transformer or a differential amplifier configuration. The ac performance of the AD9714/AD9715/AD9716/AD9717 is optimum and is specified using a differential transformercoupled output in which the voltage swing at IOUTP and IOUTN is limited to $\pm 0.5 \mathrm{~V}$. The distortion and noise performance of the AD9714/AD9715/AD9716/AD9717 can be enhanced when it is configured for differential operation. The common-mode error sources of both IOUTP/IOUTN and QOUTP/QOUTN can be significantly reduced by the common-mode rejection of a transformer or differential amplifier. These common-mode error sources include even-order distortion products and noise. The enhancement in distortion performance becomes more significant as the frequency content of the reconstructed waveform increases and/or its amplitude increases. This is due to the first-order cancellation of various dynamic common-mode distortion mechanisms, digital feedthrough, and noise. Performing a differential-to-single-ended conversion via a transformer also provides the ability to deliver twice the reconstructed signal power to the load (assuming no source termination). Because the output currents of IOUTP/IOUTN and QOUTP/QOUTN are complementary, they become additive when processed differentially.

## SELF-CALIBRATION

The AD9714/AD9715/AD9716/AD9717 have a self-calibration feature that improves the DNL of the device. Performing a selfcalibration on the device improves device performance in low frequency applications. The device performance in applications where the analog output frequencies are above 5 MHz are generally influenced more by dynamic device behavior than by DNL and, in these cases, self-calibration is unlikely to provide much benefit. The calibration clock frequency is equal to the DAC clock divided by the division factor chosen by the DIVSEL value. Each calibration clock cycle is between 32 and 2048 DAC input clock cycles, depending on the value of DIVSEL[2:0] (Register 0x0E, Bits[2:0]). The frequency of the calibration clock should be between 0.5 MHz and 4 MHz for reliable calibrations. Best results are obtained by setting DIVSEL[2:0] (Register 0x0E, Bits[2:0]) to produce a calibration clock frequency between these values. Separate self-calibration hardware is included for each DAC. The DACs can be self-calibrated individually or simultaneously.
To perform a device self-calibration, the following procedure can be used:

1. Write $0 \times 00$ to Register $0 \times 12$. This ensures that the UNCALI and UNCALQ bits are reset.
2. Set up a calibration clock between 0.5 MHz and 4 MHz using DIVSEL[2:0], and then enable the calibration clock by setting the CALCLK bit (Register 0x0E, Bit 3).
3. Select the $\operatorname{DAC}(s)$ to self-calibrate by setting either Bit 4 (CALSELI) for the I DAC and/or Bit 5 (CALSELQ) for the Q DAC in Register 0x0E. Note that each DAC contains independent calibration hardware so that they can be calibrated simultaneously.
4. Start self-calibration by setting the CALEN bit (Register 0x12, Bit 4). Wait approximately 300 calibration clock cycles.
5. Check if the self-calibration has completed by reading the CALSTATI bit (Bit 6) and CALSTATQ bit (Bit 7) in Register 0x0F. Logic 1 indicates that the calibration has completed.
6. When the self-calibration has completed, write $0 \times 00$ to Register 0x12.
7. Disable the calibration clock by clearing the CALCLK bit (Register 0x0E, Bit 3).

The AD9714/AD9715/AD9716/AD9717 allow reading and writing of the calibration coefficients. There are 32 coefficients in total. The read/write feature of the coefficients can be useful for improving the results of the self-calibration routine by averaging the results of several self-calibration cycles and loading the averaged results back into the device.

To read the calibration coefficients, use the following steps:

1. Select which DAC core to read by setting either Bit 4 (CALSELI) for the I DAC or Bit 5 (CALSELQ) for the Q DAC in Register 0x0E. Write the address of the first coefficient ( $0 \times 01$ ) to Register 0x10.
2. Set the SMEMRD bit (Register 0x12, Bit 2) by writing 0x04 to Register 0x12.
3. Read the 6-bit value of the first coefficient by reading the contents of Register 0x11.
4. Clear the SMEMRD bit by writing $0 \times 00$ to Register $0 \times 12$.
5. Repeat Step 2 through Step 4 for each of the remaining 31 coefficients by incrementing the address by 1 for each read.
6. Deselect the DAC core by clearing either Bit 4 (CALSELI) for the I DAC or Bit 5 (CALSELQ) for the Q DAC in Register 0x0E.

To write the calibration coefficients to the device, use the following steps:

1. Select which DAC core to write to by setting either Bit 4 (CALSELI) for the I DAC or Bit 5 (CALSELQ) for the Q DAC in Register 0x0E.
2. Set the SMEMWR bit (Register 0x12, Bit 3) by writing $0 \times 08$ to Register 0x12.
3. Write the address of the first coefficient $(0 \times 01)$ to Register 0x10.
4. Write the value of the first coefficient to Register 0x11.
5. Repeat Step 2 through Step 4 for each of the remaining 31 coefficients by incrementing the address by one for each write.
6. Clear the SMEMWR bit by writing $0 \times 00$ to Register $0 \times 12$.
7. Deselect the DAC core by clearing either Bit 4 (CALSELI) for the I DAC or Bit 5 (CALSELQ) for the Q DAC in Register 0x0E.

## COARSE GAIN ADJUSTMENT

## Option 1

A coarse full-scale output current adjustment can be achieved using the lower six bits in Register 0x0D. This adds or subtracts up to $20 \%$ from the band gap voltage on Pin 34 (REFIO), and the voltage on the FSADJx resistors tracks this change. As a result, the DAC full-scale current varies by the same amount. A secondary effect to changing the REFIO voltage is that the full-scale voltage in the AUXDAC also changes by the same magnitude. The register uses twos complement format, in which 011111 maximizes the voltage on the REFIO node and 100000 minimizes the voltage.


Figure 98. Typical $V_{\text {REF }}$ Voltage vs. Code

## Option 2

While using the internal FSADJx resistors, each main DAC can achieve independently controlled coarse gain using the lower six bits of Register 0x04 (IRSET[5:0]) and Register 0x07 (QRSET[5:0]). Unlike Coarse Gain Option 1, this impacts only the main DAC full-scale output current. The register uses twos complement format and allows the output current to be changed in approximately 0.25 dB steps.


Figure 99. Effect of $x R_{\text {SET }}$ Code

## Option 3

Even when the device is in pin mode, full-scale values can be adjusted by sourcing or sinking current from the FSADJx pins. Any noise injected here appears as amplitude modulation of the output. Thus, a portion of the required series resistance (at least $20 \mathrm{k} \Omega$ ) must be installed right at the pin. A range of $\pm 10 \%$ is quite practical using this method.

## Option 4

As in Option 3, when the device is in pin mode, both full-scale values can be adjusted by sourcing or sinking current from the REFIO pin. Noise injected here appears as amplitude modulation of the output; therefore, a portion of the required series resistance (at least $10 \mathrm{k} \Omega$ ) must be installed at the pin. A range of $\pm 25 \%$ is quite practical when using this method.

## Fine Gain

Each main DAC has independent fine gain control using the lower six bits in Register 0x03 (I DAC gain) and Register 0x06 (Q DAC gain). Unlike Coarse Gain Option 1, this impacts only the main DAC full-scale output current. These registers use straight binary format. One application in which straight binary format is critical is for side-band suppression while using a quadrature modulator. This is described in more detail in the Applications Information section.


Figure 100. Typical DAC Gain Characteristics

## USING THE INTERNAL TERMINATION RESISTORS

The AD9717/AD9716/AD9715/AD9714 have four $500 \Omega$ termination internal resistors (two for each DAC output). To use these resistors to convert the DAC output current to a voltage, connect each DAC output pin to the adjacent load pin. For example, on the I DAC, IOUTP must be shorted to RLIP and IOUTN must be shorted to RLIN. In addition, the CMLI or CMLQ pin must be connected to ground directly or through a resistor. If the output current is at the nominal 2 mA and the CMLI or CMLQ pin is tied directly to ground, this produces a dc common-mode bias voltage on the DAC output equal to 0.5 V . If the DAC dc bias must be higher than 0.5 V , an external resistor can be connected between the CMLI or CMLQ pin and ground. This part also has an internal common-mode resistor that can be enabled. This is explained in the Using the Internal Common-Mode Resistor section.


Figure 101. Simplified Internal Load Options

## Using the Internal Common-Mode Resistor

These devices contain an adjustable internal common-mode resistor that can be used to increase the dc bias of the DAC outputs. By default, the common-mode resistor is not connected. When enabled, it can be adjusted from $\sim 250 \Omega$ to $\sim 1 \mathrm{k} \Omega$. Each main DAC has an independent adjustment using the lower six bits in Register 0x05 (IRCML[5:0]) and Register 0x08 (QRCML[5:0]).


Figure 102. Typical CML Resistor Value vs. Register Code

## Using the CMLx Pins for Optimal Performance

The CMLx pins also serve to change the DAC bias voltages in the parts allowing them to run at higher dc output bias voltages. When running the bias voltage below 0.9 V and an AVDD of 3.3 V , the parts perform optimally when the CMLx pins are tied to ground. When the dc bias increases above 0.9 V , set the CMLx pins at 0.5 V for optimal performance. The maximum dc bias on the DAC output should be kept at or below 1.2 V when the supply is 3.3 V . When the supply is 1.8 V , keep the dc bias close to 0 V and connect the CMLx pins directly to ground.

## APPLICATIONS INFORMATION

## OUTPUT CONFIGURATIONS

The following sections illustrate some typical output configurations for the AD9714/AD9715/AD9716/AD9717. Unless otherwise noted, it is assumed that $\mathrm{I}_{\mathrm{x} \text { outrs }}$ is set to a nominal 2 mA . For applications requiring the optimum dynamic performance, a differential output configuration is suggested. A differential output configuration can consist of either an RF transformer or a differential op amp configuration. The transformer configuration provides the optimum high frequency performance and is recommended for any application that allows ac coupling. The differential op amp configuration is suitable for applications requiring dc coupling, signal gain, and/or a low output impedance.

A single-ended output is suitable for applications in which low cost and low power consumption are primary concerns.

## DIFFERENTIAL COUPLING USING A TRANSFORMER

An RF transformer can be used to perform a differential-to-single-ended signal conversion, as shown in Figure 103. The distortion performance of a transformer typically exceeds that available from standard op amps, particularly at higher frequencies. Transformer coupling provides excellent rejection of common-mode distortion (that is, even-order harmonics) over a wide frequency range. It also provides electrical isolation and can deliver voltage gain without adding noise. Transformers with different impedance ratios can also be used for impedance matching purposes. The main disadvantages of transformer coupling are low frequency roll-off, lack-of-power gain, and high output impedance.


Figure 103. Differential Output Using a Transformer
The center tap on the primary side of the transformer must be connected to a voltage that keeps the voltages on IOUTP and IOUTN within the output common-mode voltage range of the device. Note that the dc component of the DAC output current is equal to $\mathrm{I}_{\mathrm{x} \text { outrs }}$ and flows out of both IOUTP and IOUTN. The center tap of the transformer should provide a path for this dc current. In most applications, AGND provides the most convenient voltage for the transformer center tap. The complementary voltages appearing at IOUTP and IOUTN (that is, VIoutr and $\mathrm{V}_{\text {Iouts }}$ ) swing symmetrically around AGND and should be maintained with the specified output compliance range of the AD9714/AD9715/AD9716/AD9717.

A differential resistor, R $\mathrm{R}_{\mathrm{DIFF}}$, can be inserted in applications where the output of the transformer is connected to the load, $R_{\text {LOAD }}$, via a passive reconstruction filter or cable. $R_{\text {DIFF }}$, as reflected by the transformer, is chosen to provide a source termination that results in a low voltage standing wave ratio (VSWR). Note that approximately half the signal power is dissipated across R Riff.

## SINGLE-ENDED BUFFERED OUTPUT USING AN OP AMP

An op amp such as the ADA4899-1 can be used to perform a single-ended current-to-voltage conversion, as shown in Figure 104. The AD9714/AD9715/AD9716/AD9717 are configured with a pair of series resistors, $\mathrm{R}_{\mathrm{s}}$, off each output. For best distortion performance, $\mathrm{R}_{\mathrm{S}}$ should be set to $0 \Omega$. The feedback resistor, $\mathrm{R}_{\mathrm{FB}}$, determines the peak-to-peak signal swing by the formula

$$
V_{O U T}=R_{F B} \times I_{F S}
$$

The common-mode voltage of the output is determined by the formula

$$
V_{C M}=V_{R E F} \times\left(1+\frac{R_{F B}}{R_{B}}\right)-\frac{R_{F B} \times I_{F S}}{2}
$$

The maximum and minimum voltages out of the amplifier are, respectively,

$$
\begin{aligned}
& V_{M A X}=V_{R E F} \times\left(1+\frac{R_{F B}}{R_{B}}\right) \\
& V_{M I N}=V_{M A X}-I_{F S} \times R_{F B}
\end{aligned}
$$



Figure 104. Single-Supply Single-Ended Buffer

## DIFFERENTIAL BUFFERED OUTPUT USING AN OP AMP

A dual op amp (see the circuit shown in Figure 105) can be used in a differential version of the single-ended buffer shown in Figure 104. The same RC network is used to form a one-pole differential, low-pass filter to isolate the op amp inputs from the high frequency images produced by the DAC outputs. The feedback resistors, $\mathrm{R}_{\mathrm{FB}}$, determine the differential peak-to-peak signal swing by the formula

$$
V_{\text {OUT }}=2 \times R_{F B} \times I_{F S}
$$

The maximum and minimum single-ended voltages out of the amplifier are, respectively,

$$
\begin{aligned}
& V_{M A X}=V_{R E F} \times\left(1+\frac{R_{F B}}{R_{B}}\right) \\
& V_{M I N}=V_{M A X}-R_{F B} \times I_{F S}
\end{aligned}
$$

The common-mode voltage of the differential output is determined by the formula

$$
V_{C M}=V_{M A X}-R_{F B} \times I_{F S}
$$



Figure 105. Single-Supply Differential Buffer

## AUXILIARY DACs

The DACs of the AD9714/AD9715/AD9716/AD9717 feature two versatile and independent 10-bit auxiliary DACs suitable for dc offset correction and similar tasks.
Because the AUXDACs are driven through the SPI port, they should never be used in timing-critical applications, such as inside analog feedback loops.

To keep the pin count reasonable, these auxiliary DACs each share a pin with the corresponding FSADJx resistor. They are, therefore, usable only when enabled and when that DAC is operated on its internal full-scale resistors. A simple I-to-V converter is implemented on chip with selectable shunt resistors ( $3.2 \mathrm{k} \Omega$ to $16 \mathrm{k} \Omega$ ) such that if REFIO is set to exactly 1 V , REFIO/2 equals 0.5 V and the following equation describes the no load output voltage:

$$
V_{\text {OUT }}=0.5 \mathrm{~V}-\left(I_{D A C}-\frac{1.5}{R_{S}}\right) 16 \mathrm{k} \Omega
$$

Figure 106 illustrates the function of all the SPI bits controlling these DACs with the exception of the QAUXEN (Register 0x0A, Bit 7) and IAUXEN (Register 0x0C, Bit 7) bits and gating to prohibit Rs $<3.2 \mathrm{k} \Omega$.


Figure 106. AUXDAC Simplified Circuit Diagram
The SPI speed limits the update rate of the auxiliary DACs. The data is inverted such that $\mathrm{I}_{\text {AUXDAC }}$ is full scale at 0 x 000 and zero at $0 \times 1$ FF, as shown in Figure 107.


Figure 107. AUXDAC Op Amp Output vs. Current, $A V D D=3.3 \mathrm{~V}$, No Load, AUXDAC 0x1FF to 0x000

Two registers are assigned to each DAC with 10 bits for the actual DAC current to be generated, a 3-bit offset (and gain) adjustment, a 2-bit current range adjustment, and an enable/disable bit. Setting the QAUXOFS (Register 0x0A, Bits[4:2]) and IAUXOFS (Register 0x0C, Bits[4:2]) bits to all 1s disables the respective op amp and routes the DAC current directly to the respective FSADJI/AUXI or FSADJQ/AUXQ pins. This is especially useful when the loads to be driven are beyond the limited capability of the on-chip amplifier.
When not enabled (QAUXEN or IAUXEN $=0$ ), the respective DAC output is in open circuit.

## DAC-TO-MODULATOR INTERFACING

The auxiliary DACs can be used for local oscillator (LO) cancellation when the DAC output is followed by a quadrature modulator. This LO feedthrough is caused by the input referred dc offset voltage of the quadrature modulator (and the DAC output offset voltage mismatch) and can degrade system performance. Typical DAC-to-quadrature modulator interfaces are shown in Figure 108 and Figure 109, with the series resistor value chosen to give an appropriate adjustment range. Figure 108 also shows external load resistors in use. Often, the input common-mode voltage for the modulator is much higher than the output compliance range of the DAC, so that ac coupling or a dc level shift is necessary. If the required common-mode input voltage on the quadrature modulator matches that of the DAC, the dc blocking capacitors in Figure 108 can be removed and the on-chip resistors can be connected.


Figure 108. Typical Use of Auxiliary DACs and External Components for Coupling to Quadrature Modulators

Figure 109 shows a greatly simplified circuit that takes full advantage of the internal components supplied in the DAC. A low-pass or band-pass passive filter is recommended when spurious signals from the DAC (distortion and DAC images) at the quadrature modulator inputs can affect the system performance. In the example shown in Figure 109, the filter must be able to pass dc to properly bias the modulator. Placing the filter at the location shown in Figure 108 and Figure 109 allows easy design of the filter because the source and load impedances can easily be designed close to $500 \Omega$ for a 2 mA full-scale output. Once the resistance at the modulator inputs is known, the user can easily look up the range of input offsets that may be encountered and compute a value for the series resistor on the AUXDAC output.


Figure 109. Simplified DC Coupling to Quadrature Modulator ADL537x Family or Equivalent Is Enabled By Using Internal Components
CORRECTING FOR NONIDEAL PERFORMANCE OF QUADRATURE MODULATORS ON THE IF-TO-RF CONVERSION
Analog quadrature modulators make it very easy to realize single sideband radios. However, there are several nonideal aspects of quadrature modulator performance. Among these analog degradations are gain mismatch and LO feedthrough.

## Gain Mismatch

The gain in the real and imaginary signal paths of the quadrature modulator may not be matched perfectly. This leads to less than optimal image rejection because the cancellation of the negative frequency image is less than perfect.

## LO Feedthrough

The quadrature modulator has a finite dc referred offset, as well as coupling from its LO port to the signal inputs. These can lead to a significant spectral spur at the frequency of the quadrature modulator LO.
The AD9714/AD9715/AD9716/AD9717 have the capability to correct for both of these analog degradations. However, understand that these degradations drift over temperature; therefore, if close to optimal single sideband performance is desired, a scheme for sensing these degradations over temperature and correcting them may be necessary.

## I/Q-CHANNEL GAIN MATCHING

Fine gain matching is achieved by adjusting the values in the DAC fine gain adjustment registers. For the I DAC, these values are in the I DAC gain register (Register 0x03). For the Q DAC, these values are in the Q DAC gain register (Register 0x06). These are 6 -bit values that cover $\pm 2 \%$ of full scale. To perform gain compensation starting from the default values of zero, raise the value of one of these registers a few steps until it can be determined if the amplitude of the unwanted image is increased or decreased. If the unwanted image increases in amplitude, remove the step and try the same adjustment on the other DAC control register. Iterate register changes until the rejection cannot be improved further. If the fine gain adjustment range is not sufficient to find a null (that is, the register goes full scale with no null apparent), adjust the course gain settings of the two DACs accordingly and try again. Variations on this simple method are possible.

Note that LO feedthrough compensation is independent of phase compensation. However, gain compensation can affect the LO compensation because the gain compensation may change the common-mode level of the signal. The dc offset of some modulators is common-mode level dependent. Therefore, it is recommended that the gain adjustment be performed prior to LO compensation.

## LO FEEDTHROUGH COMPENSATION

To achieve LO feedthrough compensation in a circuit, each output of the two AUXDACs must be connected through a $100 \mathrm{k} \Omega$ resistor to one side of the differential DAC output. See the Auxiliary DACS section for details of how to use AUXDACs. The purpose of these connections is to drive a very small amount of current into the nodes at the quadrature modulator inputs, thereby adding a slight dc bias to one or the other of the quadrature modulator signal inputs.
To achieve LO feedthrough compensation, the user should start with the default conditions of the AUXDAC registers, and then increment the magnitude of one or the other AUXDAC output voltages. While this is being done, the amplitude of the LO feedthrough at the quadrature modulator output should be sensed. If the LO feedthrough amplitude increases, try either decreasing the output voltage of the AUXDAC being adjusted, or try adjusting the output voltage of the other AUXDAC. It may take practice before an effective algorithm is achieved. The AD9714/AD9715/AD9716/AD9717 evaluation board can be used to adjust the LO feedthrough down to the noise floor, although this is not stable over temperature.

## RESULTS OF GAIN AND OFFSET CORRECTION

The results of gain and offset correction can be seen in Figure 110 and Figure 111. Figure 110 shows the output spectrum of the quadrature demodulator before gain and offset correction. Figure 111 shows the output spectrum after correction. The LO feedthrough spur at 450 MHz has been suppressed to the noise level. This result can be achieved by applying the correction, but the correction must be repeated after a large change in temperature.

Note that gain matching improves the negative frequency image rejection, but it is also related to the phase mismatch in the quadrature modulator. It can be improved by adjusting the relative phase between the two quadrature signals at the digital side or properly designing the low-pass filter between the DACs and quadrature modulators. Phase mismatch is frequency dependent; therefore, routines must be developed to adjust it if wideband signals are desired.


Figure 110. AD9714/AD9715/AD9716/AD9717 and ADL5370 with a SingleTone Signal at 450 MHz, No Gain or LO Compensation


Figure 111. AD9714/AD9715/AD9716/AD9717 and ADL5370 with a SingleTone Signal at 450 MHz, Gain and LO Compensation Optimized

## AD9714/AD9715/AD9716/AD9717

MODIFYING THE EVALUATION BOARD TO USE THE ADL5370 ON-BOARD QUADRATURE MODULATOR
The evaluation board contains an Analog Devices, Inc., ADL5370 quadrature modulator. The AD9714/AD9715/ AD9716/AD9717 and the ADL5370 provide an easy-tointerface DAC/modulator combination that can be easily characterized on the evaluation board. Solderable jumpers can be configured to evaluate the single-ended or differential outputs of the AD9714/AD9715/AD9716/AD9717. This setup is the default configuration from the factory and consists of the following population of the components:

- JP55, JP56, JP76, JP82-unsoldered
- R13, R14, R52, R53-unpopulated
- R50, R57, T1, T2-populated

To evaluate the ADL5370 on this board, the population of these same components should be reversed so that they are in the following positions:

- JP55, JP56, JP76, JP82-soldered
- R13, R14, R52, R53-populated
- R50, R57, T1, T2-unpopulated

The AUXDAC outputs can be connected to Test Point TP44 and Test Point TP45 if LO feedthrough compensation is necessary.

## EVALUATION BOARD SHEMATICS AND ARTWORK

## SCHEMATICS



Figure 112. Power Supplies and Filters


## Data Sheet



Figure 114. Clock Input and DUT


Figure 115. IOUT Network and FSADJ1


Figure 116. QOUT Network and FSADJ2



Figure 118. Modulated Output


## Data Sheet <br> AD9714/AD9715/AD9716/AD9717

SILKSCREENS


Figure 120. Layer 2, Ground Plane


Figure 121. Layer 3, Power Plane



Figure 123. Assembly—Secondary Side


Figure 124. Solder Mask_Primary Side with Socket


Figure 125. Solder Mask—Secondary Side

## Data Sheet



Figure 126. Hard Gold Plated with Bumps and Socket


Figure 127. Primary Side Paste

## Data Sheet




Figure 129. Silkscreen—Primary Side


Figure 130. Silkscreen-Secondary Side


Figure 131. Layer 1—Primary Side


Figure 132. Layer 4-Secondary Side


Figure 133. Immersion Gold, No Socket, No Bumps


Figure 134. Solder Mask—Primary Side, No Socket

## BILL OF MATERIALS

Table 18.

| Qty | Reference Designator | Device | Package | Description | Part No./ Manufacturer |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 6 | C1, C2, C4, C5, C32, C57 | CAPSMDA | ACASE | $10 \mu \mathrm{~F}, 6.3 \mathrm{~V}$ capacitor |  |
| 17 | C3, C6, C7, C8, C9, C10, C11, <br> C15, C16, C22, C24, C26, <br> C27, C48, C60, C61, C107 | CC0603 | CC0603 | $0.1 \mu \mathrm{~F}$ capacitor |  |
| 11 | $\begin{aligned} & \text { C12, C14, C17, C18, C20, } \\ & \text { C21, C31, C37, C39, C86, C88 } \end{aligned}$ | CC0603 | CC0603 | $1 \mu \mathrm{~F}$ capacitor |  |
| 5 | C13, C19, C30, C38, C89 | CC0603 | CC0603 | 100 pF capacitor |  |
| 3 | C23, C25, C28 | CC0603 | CC0603 | $0.01 \mu \mathrm{~F}$ capacitor |  |
| 6 | C29, C36, C47, C52, C72, C90 | CC0402 | CC0402 | $0.1 \mu \mathrm{~F}$ capacitor |  |
| 2 | C33, C49 | CC0603 | CC0603 | $10 \mathrm{pF}, 1 \%$ capacitor |  |
| 18 | $\begin{aligned} & \text { C34, C40, C42, C45, C46, } \\ & \text { C55, C58, C66, C67, C68, } \\ & \text { C69, C70, C71, C76, C77, } \\ & \text { C85, C101, C113 } \end{aligned}$ | CC0402 | CC0402 | $0.1 \mu \mathrm{~F}$ capacitor |  |
| 1 | C35 | CAPSMDA | ACASE | $22 \mu \mathrm{~F}, 16 \mathrm{~V}$ capacitor |  |
| 3 | C41, C43, C44 | CAPSMDB | ACASE | $10 \mu \mathrm{~F}, 10 \mathrm{~V}$ capacitor |  |
| 8 | $\begin{aligned} & \text { C50, C51, C53, C54, C63, } \\ & \text { C73, C83, C87 } \end{aligned}$ | CC0402 | CC0402 | 100 pF capacitor |  |
| 2 | C56, C62 | CC0402 | CC0402 | 1 nF capacitor |  |
| 1 | C59 | CAPSMDA | ACASE | $4.7 \mu \mathrm{~F}, 6.3 \mathrm{~V}$ capacitor |  |
| 4 | C64, C75, C79, C82 | CC0805 | CC0805 | 7.5 pF , 1\% capacitor |  |
| 4 | C65, C74, C80, C81 | CC0805 | CC0805 | 4.7 pF, 1\% capacitor |  |
| 1 | C78 | CC0402 | CC0402 | $0.01 \mu \mathrm{~F}$ capacitor |  |
| 11 | $\begin{aligned} & \text { C84, C97, C98, C99, C100, } \\ & \text { C106, C108, C109, C111, } \\ & \text { C112, C114 } \end{aligned}$ | CC0603 | CC0603 | $0.1 \mu \mathrm{~F}$ capacitor |  |
| 4 | C91, C92, C93, C94 | CC0805 | CC0805 | DNP |  |
| 2 | C95, C96 | CC0603 | CC0603 | DNP |  |
| 1 | C102 | CC0402 | CC0402 | 0.2 nF capacitor |  |
| 2 | C103, C104 | CAPSMDA | ACASE | $10 \mu \mathrm{~F}, 10 \mathrm{~V}$ capacitor |  |
| 1 | C105 | CC0805 | CC0805 | $1 \mu \mathrm{~F}$ ceramic capacitor |  |
| 1 | C110 | CC0603 | CC0603 | 470 nF capacitor |  |
| 1 | D1 | Panasonic LNJ312G8TRA | $1.6 \mathrm{~mm} \times 0.8 \mathrm{~mm}$ | LED-SMD-TSS-GRN | LNJ312G8TRA |
| 1 | D3 | HSMS-281C | SOT323-3 | HSMS-281C | HSMS-281C |
| 1 | J1 | Samtec SSW-120-02-SM-D-RA | 40-pin through hole | 40-pin right angle header female | SSW-120-02-SM-D-RA/ <br> Samtec |
| 6 | J2, J3, J4, J5, J8, J11 | SMAEDGE | SMAEDGE | DNP SMA connector edge right angle |  |
| 2 | J6, J7 | SMAEDGE | SMAEDGE | SMA connector edge right angle |  |
| 5 | J10, S3, S5, S6, S11 | SMAUPA04 | SMA200UP | SMA connector RF 5-pin upright |  |
| 5 | S4, S8, S9, S10, S12 | SMAUPA04 | SMA200UP | DNP |  |
| 11 | JP3, JP7, JP8, JP9, JP11, JP12, JP16, JP20, JP21, JP28, JP77 | JPRBLK02 | JPRBLK02 | 2-pin jumper header |  |
| 10 | JP6, JP10, JP15, JP22, JP26, JP29, JP54, JP78, JP88, JP89 | JPRBLK03 | JPRBLK03 | 3-pin jumper header |  |
| 10 | JP32, JP33, JP34, JP35, JP55, JP56, JP76, JP82, JP90, JP91 | JPRSLD02 | JPRSLD02 | Solder jumper |  |


| Qty | Reference Designator | Device | Package | Description | Part No./ Manufacturer |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 11 | $\begin{aligned} & \text { L1, L2, L3, L4, L5, L6, L7, } \\ & \text { L12, L13, L16, L19 } \end{aligned}$ | IND1812 | LC1812 | EXC-CL4532U1 | EXC-CL4532U1 |
| 4 | L8, L9, L10, L11 | IND1008 | LC1008 | $1.8 \mu \mathrm{H}, 10 \%$ |  |
| 4 | L14, L17, L18, L20 | IND1008 | LC1008 | DNP |  |
| 1 | L15 | IND1210 | LC1210 | EXC-CL3225U1 | EXC-CL3225U1 |
| 1 | P1 | USB-MINIB | USB-MINIB | USB mini 5-pin |  |
| 1 | P3 | Molex 0532610571 | Molex 0532610571 | $1.25 \mathrm{~mm}, 5$-pin wire-to-board connector | $\begin{aligned} & \text { 0532610571/ } \\ & \text { Molex } \end{aligned}$ |
| 2 | R1, R58 | RC0805 | RC0805 | $32 \mathrm{k} \Omega, 0.1 \%$ resistor | ERA6YEB323V, ERA6Y |
| 5 | R2, R23, R25, R31, R36 | RC0603 | RC0603 | $76.8 \mathrm{k} \Omega$ resistor |  |
| 5 | R3, R4, R5, R10, R29 | RC0603 | RC0603 | $78.7 \mathrm{k} \Omega$ resistor |  |
| 6 | R6, R33, R34, R64, R65, R67 | RC0402 | RC0402 | $0 \Omega$ resistor |  |
| 7 | R17, R66, R68, R69, R107, R110, R122 | RC0402 | RC0402 | DNP |  |
| 1 | R7 | RC0603 | RC0603 | $10 \mathrm{k} \Omega$ resistor |  |
| 5 | R8, R12, R30, R32, R92 | RC0603 | RC0603 | $64.9 \mathrm{k} \Omega$ resistor |  |
| 8 | R9, R37, R42, R56, R97, R98, R100, R101 | RC0603 | RC0603 | DNP |  |
| 4 | R11, R38, R79, R83 | RC0603 | RC0603 | $0 \Omega$ resistor |  |
| 4 | R13, R14, R52, R53 | RC0603 | RC0603 | DNP |  |
| 10 | R15, R16, R123, R124, R73 to R75, R78, R93, R94, R105, R106 | RC0603 | RC0603 | $0 \Omega$ resistor |  |
| 6 | R22, R54, R118, R119, R120, R121 | RC0603 | RC0603 | DNP |  |
| 1 | R18 | RC0402 | RC0402 | $49.9 \Omega$ resistor |  |
| 2 | R19, R21 | RC0402 | RC0402 | $0 \Omega$ resistor |  |
| 3 | R20, R26, R80 | RC0402 | RC0402 | DNP |  |
| 2 | R24, R61 | RC0603 | RC0603 | $1 \mathrm{k} \Omega$ resistor |  |
| 1 | R27 | RC0603 | RC0603 | $1 \mathrm{M} \Omega$ resistor |  |
| 7 | $\begin{aligned} & \text { R28, R39, R40, R41, R44, } \\ & \text { R45, R103 } \end{aligned}$ | RC0402 | RC0402 | $22 \Omega$ resistor |  |
| 4 | R35, R55, R99, R102 | RC0603 | RC0603 | $100 \mathrm{k} \Omega$ resistor |  |
| 1 | R43 | RC0402 | RC0402 | $0 \Omega$ resistor |  |
| 8 | $\begin{aligned} & \text { R46, R47, R48, R62, R82, } \\ & \text { R86, R116, R117 } \end{aligned}$ | RC0402 | RC0402 | $0 \Omega$ resistor |  |
| 2 | R49, R59 | RC0805 | RC0805 | $16 \mathrm{k} \Omega, 0.1 \%$ resistor | ERA6YEB323V, ERA6Y |
| 2 | R50, R57 | RC0603 | RC0603 | $453 \Omega$ resistor |  |
| 2 | R51, R60 | RC0805 | RC0805 | $8 \mathrm{k} \Omega, 0.1 \%$ resistor | ERA6YEB323V, ERA6Y |
| 3 | R63, R113, R115 | RC0402 | RC0402 | $499 \Omega$ resistor |  |
| 3 | R70, R71, R108 | RC0402 | RC0402 | $10 \mathrm{k} \Omega$ resistor |  |
| 1 | R72 | RC0402 | RC0402 | $25 \Omega$ resistor |  |
| 2 | R76, R77 | RC0402 | RC0402 | $1.8 \mathrm{k} \Omega$ resistor |  |
| 1 | R81 | RC0402 | RC0402 | $4.12 \mathrm{k} \Omega$ resistor |  |
| 1 | R87 | RC1206 | RC1206 | $0 \Omega$ resistor |  |
| 2 | R88, R89 | RC0402 | RC0402 | $0 \Omega$ resistor |  |
| 2 | R90, R109 | RC0402 | RC0402 | DNP |  |
| 1 | R91 | RC0805 | RC0805 | $49.9 \Omega$ resistor |  |
| 2 | R111, R112 | RC0603 | RC0603 | DNP |  |
| 1 | R114 | RC0402 | RC0402 | $15 \Omega$ resistor |  |
| 2 | RP1, RP5 | RNETCTS743-8 | RNETCTS743-8 | DNP |  |


| Qty | Reference Designator | Device | Package | Description | Part No./ Manufacturer |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | RP3, RP4 | RNETCTS743-8 | RNETCTS743-8 | $22 \Omega$ resistor |  |
| 2 | SW1, SW2 | KEYBDSWG | OMRONB3SG | B3S-1100 push-button |  |
| 4 | T1, T2, T3, T6 | ADTL1-12 | MINI_CD542 | DNP |  |
| 1 | T4 | ETC1-1-13 | SM-22 | M/A COM ETC1-1-13 | ETC1-1-13/ <br> M/A-COM |
| 2 | T5, 78 | ADT9-1T | MINI_CD542 | ADT9-1T | ADT9-1T/ <br> Mini-Circuits |
| 1 | T9 | JTX-4-10T | MINI_BH292 | JTX-4-10T+ | JTX-4-10T/ <br> Mini-Circuits |
| 16 | TP1, TP3, TP17, TP18, TP19, TP20, TP22, TP25, TP26, TP30, TP31, TP34, TP35, TP38, TP44, TP45 | LOOPMINI | LOOPMINI | White test point |  |
| 4 | TP32, TP33, TP36, TP37 | LOOPMINI | LOOPMINI | DNP |  |
| 8 | TP5, TP8, TP12, TP13, TP16, TP24, TP39, TP42 | LOOPMINI | LOOPMINI | Red test point |  |
| 1 | TP2 | LOOPMINI | LOOPMINI | DNP |  |
| 12 | TP4, TP6, TP7, TP9, TP10, TP11,TP14, TP15, TP21, TP23, TP41, TP43 | LOOPMINI | LOOPMINI | Black test point |  |
| 1 | TP40 | LOOPMINI | LOOPMINI | Orange test point |  |
| 1 | U1 | 40-lead LFCSP, AD9717 | LFCSP040-CP1 | 40-lead LFCSP, <br> AD9717 | AD9717/ <br> Analog Devices |
| 5 | U2, U4, U6, U7, U11 | ADP3334 | 8-lead SOIC | ADP3334 voltage regulator | ADP3334/ <br> Analog Devices |
| 1 | U3 | USB-PIC18F4550-//ML-ND | QFN044P65MM-EP1 | PIC18F4550, microchip USB port chip QFN44 8X8MM | PIC18F4550 |
| 2 | U5, U14 | ADG3304BRUZ | 14-lead TSSOP | $\begin{aligned} & \text { ADG3304, } \\ & \text { 14-lead TSSOP } \end{aligned}$ | ADG3304BRUZ/ Analog Devices |
| 1 | U8 | 74LVC1G34 | SC70-05 | SN74LVC1G34DCK, <br> TI buffer | $\begin{aligned} & \text { TI-DCK = } \\ & \text { SC70_05 PKG } \end{aligned}$ |
| 1 | U9 | ADL5370 | LFCSP024P5MM-EP1 | ADL5370ACPZ | ADL5370ACPZ/ Analog Devices |
| 1 | U10 | AD9512 | LFCSP048-CP1 | AD9512BCPZ | AD9512BCPZ/ Analog Devices |
| 1 | U12 | OSC-S1703 | OSC-S1703 | DNP |  |
| 1 | U13 | 8-lead SOIC, ADA4899-1 | SOIC8-N-EP | Op amp, ADA4899-1 | ADA4899-1/ Analog Devices |
| 1 | Y1 | ABM3B-20.000MHZ-10-1-U-T | SMD $3.2 \mathrm{~mm} \times 5.0 \mathrm{~mm}$ | 20 MHz | $\begin{aligned} & \text { 300-8214-1-ND/ } \\ & \text { Digi-Key } \\ & \hline \end{aligned}$ |

## OUTLINE DIMENSIONS



Figure 135. 40-Lead Lead Frame Chip Scale Package [LFCSP]
$6 \mathrm{~mm} \times 6 \mathrm{~mm}$ and 0.85 mm Package Height
(CP-40-1)
Dimensions shown in millimeters
ORDERING GUIDE

| Model $^{1}$ | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| AD9714BCPZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | CP-40-1 |
| AD9714BCPZRL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | CP-40-1 |
| AD9715BCPZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | $\mathrm{CP}-40-1$ |
| AD9715BCPZRL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | CP-40-1 |
| AD9716BCPZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | $\mathrm{CP}-40-1$ |
| AD9716BCPZRL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | CP-40-1 |
| AD9717BCPZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | $\mathrm{CP}-40-1$ |
| AD9717BCPZRL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 40 -Lead LFCSP | CP-40-1 |
| AD9714-DPG2-EBZ |  | Evaluation Board |  |
| AD9715-DPG2-EBZ |  | Evaluation Board |  |
| AD9716-DPG2-EBZ | Evaluation Board |  |  |
| AD9717-DPG2-EBZ |  | Evaluation Board |  |

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[^0]:    ${ }^{1} \mathrm{Z}=$ RoHS Compliant Part.

