ANALOG DEVICES

## FEATURES

Meets and exceeds EIA RS-485 and EIA RS-422 standards<br>30 Mbps data rate<br>Recommended for PROFIBUS applications<br>2.1 V minimum differential output with $\mathbf{5 4} \Omega$ termination<br>Low power 0.8 mA Icc<br>Thermal shutdown and short-circuit protection<br>0.5 ns skew driver and receiver<br>Driver propagation delay: 11 ns<br>Receiver propagation delay: 12 ns

High impedance outputs with drivers disabled or power off
Superior upgrade for SN65ALS1176
Available in standard 8-lead SOIC package

## APPLICATIONS

## Industrial field equipment

## GENERAL DESCRIPTION

The ADM1486 is a differential line transceiver suitable for high speed bidirectional data communication on multipoint bus transmission lines. It is designed for balanced data transmission, complies with EIA Standards RS-485 and RS-422, and is recommended for PROFIBUS applications. The part contains a differential line driver and a differential line receiver. Both the driver and the receiver may be enabled independently. When disabled or powered down, the driver outputs are high impedance.

The ADM1486 operates from a single 5 V power supply. Excessive power dissipation caused by bus contention or output shorting is prevented by short-circuit protection and thermal circuitry. Short-circuit protection circuits limit the maximum output current to $\pm 200 \mathrm{~mA}$ during fault conditions. A thermal shutdown circuit senses if the die temperature rises above $150^{\circ} \mathrm{C}$ and forces the driver outputs into a high impedance state under this condition.

Up to 50 transceivers may be connected simultaneously on a bus, but only one driver should be enabled at a time. Therefore, it is important that the remaining disabled drivers do not load the bus.


## Rev. A

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## FUNCTIONAL BLOCK DIAGRAM



Figure 1.

To ensure this, the ADM1486 driver features high output impedance when disabled and when powered down. This minimizes the loading effect when the transceiver is not being used. The high impedance driver output is maintained over the entire common-mode voltage range from -7 V to +12 V .

The receiver contains a fail-safe feature that results in a logic high output state if the inputs are unconnected (floating).

The ADM1486 is fabricated on BiCMOS, an advanced mixed technology process combining low power CMOS with fast switching bipolar technology. All inputs and outputs contain protection against ESD; all driver outputs feature high source and sink current capability. An epitaxial layer is used to guard against latch-up.

The ADM1486 features extremely fast and closely matched switching, enable, and disable times. Minimal driver propagation delays permit transmission at data rates up to 30 Mbps while low skew minimizes EMI interference.

The part is fully specified over the commercial and industrial temperature range and is available in an 8-lead SOIC package.

[^0]
## ADM1486

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## SPECIFICATIONS

$\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} \pm 5 \%$. All specifications $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 1.

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |
| Differential Output Voltage, Vod |  |  | 5.0 | V | $\mathrm{R}=$ Infinity, see Figure 3 |
|  | 2.1 |  | 5.0 | V | $V_{C C}=5 \mathrm{~V}, \mathrm{R}=50 \Omega$ (RS-422), see Figure 3 |
|  | 2.1 |  | 5.0 | V | $\mathrm{R}=27 \Omega$ (RS-485), see Figure 3 |
| $V_{\text {OD3 }}$ | 2.1 |  | 5.0 | V | $\mathrm{V}_{\text {TST }}=-7 \mathrm{~V}$ to +12 V , see Figure 4 |
| $\Delta \mid$ Vod \| for Complementary Output States |  |  | 0.2 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$, see Figure 3 |
| Common-Mode Output Voltage Voc |  |  | 3.0 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$, see Figure 3 |
| $\Delta \mid$ Voc \| for Complementary Output States |  |  | 0.2 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$ |
| Output Short-Circuit Current (Vout = High) | 60 |  | 200 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{0} \leq+12 \mathrm{~V}$ |
| Output Short-Circuit Current ( V OUt $^{\text {= Low }}$ ) | 60 |  | 200 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{0} \leq+12 \mathrm{~V}$ |
| CMOS Input Logic Threshold Low, $\mathrm{V}_{\text {INL }}$ |  |  | 0.8 | V |  |
| CMOS Input Logic Threshold High, Vinh | 2.0 |  |  | V |  |
| Logic Input Current (DE, DI) |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |  |
| RECEIVER |  |  |  |  |  |
| Differential Input Threshold Voltage, $\mathrm{V}_{\text {TH }}$ | -0.2 |  | +0.2 | V | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {СM }} \leq+12 \mathrm{~V}$ |
| Input Voltage Hysteresis, $\Delta \mathrm{V}_{\text {TH }}$ |  | 70 |  | mV | $\mathrm{V}_{\text {cm }}=0 \mathrm{~V}$ |
| Input Resistance | 20 | 30 |  | $k \Omega$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {cm }} \leq+12 \mathrm{~V}$ |
| Input Current (A, B) |  |  | 0.6 | mA | $\mathrm{V}_{\mathrm{IN}}=+12 \mathrm{~V}$ |
|  |  |  | -0.35 | mA | $\mathrm{V}_{\mathrm{IN}}=-7 \mathrm{~V}$ |
| Logic Enable Input Current ( $\overline{\mathrm{RE}})$ |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |  |
| CMOS Output Voltage Low, Vol |  |  | 0.4 | V | lout $=+4.0 \mathrm{~mA}$ |
| CMOS Output Voltage High, V о | 4.0 |  |  | V | lout $=-4.0 \mathrm{~mA}$ |
| Short-Circuit Output Current | 7 |  | 85 | mA | $\mathrm{V}_{\text {out }}=\mathrm{GND}$ or $\mathrm{V}_{\text {cc }}$ |
| Three-State Output Leakage Current |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ | $0.4 \mathrm{~V} \leq \mathrm{V}_{\text {out }} \leq 2.4 \mathrm{~V}$ |
| POWER SUPPLY CURRENT |  |  |  |  |  |
| Icc (Outputs Enabled) |  | 1.2 | 2.0 | mA | Outputs unloaded, digital inputs $=$ GND or $\mathrm{V}_{\text {cc }}$ |
| Icc (Outputs Disabled) |  | 0.8 | 1.5 | mA | Outputs unloaded, digital inputs = GND or Vcc |

## ADM1486

## TIMING SPECIFICATIONS

$\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} \pm 5 \%$. All specifications $\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 2.

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |
| Propagation Delay Input to Output tplh, $\mathrm{t}_{\text {PHL }}$ | 4 | 11 | 17 | ns | RLDIFF $=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$, see Figure 5 |
|  |  | 11 | 13 | ns | $R_{\text {LDIFF }}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF} @ \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |
| Driver O/P to $\overline{\mathrm{O} / \mathrm{P}} \mathrm{t}_{\text {skew }}$ |  | 0.5 | 2 | ns | $\mathrm{R}_{\text {LDIFF }}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$, see Figure $5^{1}$ |
| Driver Rise/Fall Time $\mathrm{t}_{\mathrm{R}}, \mathrm{t}_{\mathrm{F}}$ |  | 8 | 15 | ns | $\mathrm{R}_{\text {LDIFF }}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$, see Figure 5 |
| Driver Enable to Output Valid $\mathrm{tzr}^{\text {, }}$, zzL |  | 9 | 15 | ns | $R_{L}=110 \Omega, C_{L}=50 \mathrm{pF}$, see Figure 6 |
| Driver Disable Timing thz, tız |  | 9 | 15 | ns | $\mathrm{RL}_{\mathrm{L}}=110 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, see Figure 6 |
| Matched Enable Switching $\left\|\mathrm{t}_{\mathrm{AzH}}-\mathrm{t}_{\mathrm{BZL}}\right\|,\left\|\mathrm{t}_{\mathrm{BZH}}-\mathrm{t}_{\mathrm{AZL}}\right\|$ |  | 1 | 3 | ns | $\mathrm{R}_{\mathrm{L}}=110 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, see Figure 6 |
| Matched Disable Switching <br> $\mid \mathrm{t}_{\text {AHz }}$ - $\mathrm{t}_{\mathrm{BLZ}}\left\|,\left\|\mathrm{t}_{\mathrm{BHz}}-\mathrm{t}_{\mathrm{ALZ}}\right\|\right.$ |  | 2 | 5 | ns | $\mathrm{RL}=110 \Omega, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, see Figure 6 |
| RECEIVER |  |  |  |  |  |
| Propagation Delay Input to Output $\mathrm{t}_{\text {PLH, }} \mathrm{t}_{\text {PHL }}$ | 6 | 12 | 20 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, see Figure 7 |
|  |  | 0.4 | 2 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}^{1}$, see Figure 7 |
| Receiver Enable tzh, tzl |  | 7 | 13 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k}$, see Figure 8 |
| Receiver Disable thz, $\mathrm{t}_{\mathrm{z}}$ |  | 7 | 13 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$, see Figure 8 |

[^1]
## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted.

Table 3.

| Parameter | Rating |
| :---: | :---: |
| $\mathrm{V}_{\text {cc }}$ | 7 V |
| Inputs |  |
| Driver Input (DI) | -0.3 V to $\mathrm{V}_{\text {cc }}+0.3 \mathrm{~V}$ |
| Control Inputs ( $\mathrm{DE}, \overline{\mathrm{RE}}$ ) | -0.3 V to $\mathrm{V}_{\text {cc }}+0.3 \mathrm{~V}$ |
| Receiver Inputs (A, B) | -9 V to +14 V |
| Outputs |  |
| Driver Outputs | -9 V to +14 V |
| Receiver Outputs | -0.5 V to $\mathrm{V}_{\mathrm{cc}}+0.5 \mathrm{~V}$ |
| Power Dissipation 8-Lead SOIC | 450 mW |
| $\theta_{j A}$, Thermal Impedance | $170^{\circ} \mathrm{C} / \mathrm{W}$ |
| Operating Temperature Range |  |
| Industrial (A Version) | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering, 10 sec ) | $300^{\circ} \mathrm{C}$ |
| Vapor Phase (60 sec) | $215^{\circ} \mathrm{C}$ |
| Infrared (15 sec) | $220^{\circ} \mathrm{C}$ |

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect device reliability.

## ESD CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

## ADM1486

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Figure 2. Pin Configuration

Table 4. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 | RO | Receiver Output. When enabled, if $\mathrm{A}>\mathrm{B}$ by $200 \mathrm{mV}, \mathrm{RO}=$ high. If A < B by $200 \mathrm{mV}, \mathrm{RO}=$ low. |
| 2 | $\overline{\mathrm{RE}}$ | Receiver Output Enable. A low level enables the receiver output, RO. A high level places it in a high impedance state. |
| 3 | DE | Driver Output Enable. A high level enables the driver differential outputs, A and B. A low level places it in a high impedance state. |
| 4 | DI | Driver Input. When the driver is enabled, a logic low on DI forces A low and B high, while a logic high on DI forces $A$ high and $B$ low. |
| 5 | GND | Ground Connection, 0 V . |
| 6 | A | Noninverting Receiver Input A/Driver Output A. |
| 7 | B | Inverting Receiver Input B/Driver Output B. |
| 8 | V cc | Power Supply, $5 \mathrm{~V} \pm 5 \%$. |

Table 5. Transmitting

| DE Input | DI Input | B Output | A Output |
| :--- | :--- | :--- | :--- |
| 1 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 |
| 0 | X | Z | Z |

Table 6. Receiving

| $\overline{\mathbf{R E}}$ | A-B Input | RO Output |
| :--- | :--- | :--- |
| 0 | $\geq+0.2 \mathrm{~V}$ | 1 |
| 0 | $\leq-0.2 \mathrm{~V}$ | 0 |
| 0 | Inputs open | 1 |
| 1 | X | Z |

## TEST CIRCUITS



Figure 3. Driver Voltage Measurement


Figure 4. Driver Voltage Measurement


Figure 5. Driver Propagation Delay


Figure 6. Driver Enable/Disable


Figure 7. Receiver Propagation Delay


Figure 8. Receiver Enable/Disable

## ADM1486

## SWITCHING CHARACTERISTICS



Figure 9. Driver Propagation Delay, Rise/Fall Timing


Figure 10. Driver Enable/Disable Timing


Figure 11. Receiver Propagation Delay


Figure 12. Receiver Enable/Disable Timing

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 13. Output Current vs. Receiver Output Low Voltage


Figure 14. Output Current vs. Receiver Output High Voltage


Figure 15. Receiver Output High Voltage vs. Temperature $(I=8 \mathrm{~mA})$


Figure 16. Receiver Output Low Voltage vs. Temperature $(I=8 \mathrm{~mA})$


Figure 17. Output Current vs. Driver Differential Output Voltage


Figure 18. Driver Differential Output Voltage vs. Temperature $\left(R_{\text {LDIFF }}=53.6 \Omega\right)$


Figure 19. Output Current vs. Driver Output Low Voltage


Figure 20. Output Current vs. Driver Output High Voltage


Figure 21. Supply Current vs. Temperature


Figure 22. Receiver Skew vs. Temperature


Figure 23. Driver Skew vs. Temperature


Figure 24. Tx Pulse Width Distortion


Figure 25. Unloaded Driver Differential Outputs


Figure 26. Loaded Driver Differential Output
$\left(R_{L}\right.$ Diff $\left.=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}\right)$


Figure 27. Driver/Receiver Propagation Delays Low to High ( $R_{\text {LDIFF }}=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ )


Figure 28. Driver/Receiver Propagation Delays High to Low ( $R_{L}$ Diff $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$ )


Figure 29. Unloaded Driver Outputs at 15 Mbps


Figure 30. Unloaded Driver Outputs at 30 Mbps


Figure 31. Loaded Driver Outputs at 15 Mbps $\left(R_{\text {LDIFF }}=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}\right)$


Figure 32. Loaded Driver Outputs at 30 Mbps $\left(R_{L D I F F}=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}\right)$

## APPLICATIONS INFORMATION

## DIFFERENTIAL DATA TRANSMISSION

Differential data transmission is used to reliably transmit data at high rates over long distances and through noisy environments. Differential transmission nullifies the effects of ground shifts and noise signals that appear as common-mode voltages on the line. There are two main standards approved by the Electronics Industries Association (EIA) that specify the electrical characteristics of transceivers used in differential data transmission.

The RS-422 standard specifies data rates up to 10 MBaud and line lengths up to 4,000 feet. A single driver can drive a transmission line with up to 10 receivers.

In order to address true multipoint communications, the RS-485 standard was defined. This standard meets or exceeds all of the requirements of RS-422, and it allows up to 32 drivers and 32 receivers to connect to a single bus. An extended commonmode range of -7 V to +12 V is defined. The most significant difference between the RS-422 and the RS-485 is that the drivers with RS-485 can be disabled, allowing more than one driver to be connected to a single line; in fact, 32 drivers can be connected to a single line. Only one driver should be enabled at a time, but the RS-485 standard contains additional specifications to guarantee device safety in the event of line contention.

## CABLE AND DATA RATE

Twisted pair is the transmission line of choice for RS-485 communications. Twisted pair cable tends to cancel commonmode noise and causes cancellation of the magnetic fields generated by the current flowing through each wire, thereby reducing the effective inductance of the pair.

The ADM1486 is designed for bidirectional data communications on multipoint transmission lines. A typical application showing a multipoint transmission network is shown in Figure 33.

An RS-485 transmission line can have as many as 32 transceivers on the bus. Only one driver can transmit at a time, but multiple receivers may be enabled simultaneously.

As with any transmission line, it is important to minimize reflections. This can be achieved by terminating the extreme ends of the line using resistors equal to the characteristic impedance of the line. Stub lengths of the main line should also be kept as short as possible. A properly terminated transmission line appears purely resistive to the driver.

## THERMAL SHUTDOWN

The ADM1486 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. Thermal sensing circuitry detects the increase in die temperature and disables the driver outputs. Thermal sensing circuitry is designed to disable the driver outputs when a die temperature reaches $150^{\circ} \mathrm{C}$. As the device cools, the drivers are re-enabled at $140^{\circ} \mathrm{C}$.

## PROPAGATION DELAY

The ADM1486 features very low propagation delay, ensuring maximum baud rate operation. The well-balanced driver ensures distortion-free transmission.

Another important specification is a measure of the skew between the complementary outputs. Excessive skew impairs the noise immunity of the system and increases the amount of electromagnetic interference (EMI).

## RECEIVER OPEN-CIRCUIT FAIL-SAFE

The receiver input includes a fail-safe feature that guarantees a logic high on the receiver when the inputs are open circuit or floating.


Figure 33. Typical RS-485 Network

## ADM1486

Table 7. Comparison of RS-422, RS-485, and PROFIBUS Interface Standards

| Specification | RS-422 | RS-485 | PROFIBUS |
| :--- | :--- | :--- | :--- |
| Transmission Type | Differential | Differential | Differential |
| Maximum Cable Length | $4,000 \mathrm{ft}$. | $4,000 \mathrm{ft}$. |  |
| Minimum Driver Output Voltage | $\pm 2 \mathrm{~V}$ | $\pm 1.5 \mathrm{~V}$ | $\pm 2.1 \mathrm{~V}$ |
| Driver Load Impedance | $100 \Omega$ | $54 \Omega$ | $54 \Omega$ |
| Receiver Input Resistance | $4 \mathrm{k} \Omega \mathrm{min}$ | $12 \mathrm{k} \Omega \mathrm{min}$ | $20 \mathrm{k} \Omega \mathrm{min}$ |
| Receiver Input Sensitivity | $\pm 200 \mathrm{mV}$ | $\pm 200 \mathrm{mV}$ | $\pm 200 \mathrm{mV}$ |
| Receiver Input Voltage Range | -7 V to +7 V | -7 V to +12 V | -7 V to +12 V |
| No. of Drivers/Receivers per Line | $1 / 10$ | $32 / 32$ | $50 / 50$ |

## OUTLINE DIMENSIONS



Figure 34. 8-Lead Standard Small Outline Package [SOIC] Narrow Body
(R-8)
Dimensions shown in millimeters and (inches)

ORDERING GUIDE

| Model | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| ADM1486AR | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |
| ADM1486AR-REEL | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |
| ADM1486AR-REEL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |
| ADM1486ARZ $^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |
| ADM1486ARZ-REEL $^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |
| ADM1486ARZ-REEL7 $^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 8-Lead Narrow Body (SOIC) | R-8 |

[^2]
## ADM1486

## NOTES

## X-ON Electronics

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[^1]:    ${ }^{1}$ Guaranteed by characterization.

[^2]:    ${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.

