

### **Data Sheet**

### FEATURES

Low output skew <30 ps (typical)

- Distributes one differential clock input to 10 LVDS clock outputs
- Programmable—one of two differential clock inputs can be selected (CLK0, CLK1) and individual differential clock outputs enabled/disabled
- Signaling rate up to 1.1 GHz (typical)
- 2.375 V to 2.625 V power supply range
- ±100 mV differential input threshold
- Input common-mode range from rail-to-rail
- I/O pins fail-safe during power-down:  $V_{DD} = 0 V$
- Available in 32-lead LFCSP and LQFP packages
- Industrial operating temperature range: -40°C to +85°C

#### APPLICATIONS

**Clock distribution networks** 

# Programmable Low Voltage 1:10 LVDS Clock Driver

# ADN4670

#### FUNCTIONAL BLOCK DIAGRAM



#### **GENERAL DESCRIPTION**

The ADN4670 is a low voltage differential signaling (LVDS) clock driver that expands a differential clock input signal to 10 differential clock outputs. The device is programmable using a simple serial interface, so that one of two clock inputs can be selected (CLK0/ $\overline{\text{CLK0}}$  or CLK1/ $\overline{\text{CLK1}}$ ) and any of the differential outputs (Q0/ $\overline{\text{Q0}}$  to Q9/ $\overline{\text{Q9}}$ ) can be enabled or disabled (tristated). The ADN4670 is designed for use in 50  $\Omega$  transmission line environments.

When the enable input EN is high, the device may be programmed by clocking 11 data bits into the shift register. The first 10 bits determine which outputs are enabled (0 = disabled, 1 = enabled), while the  $11^{\text{th}}$  bit selects the clock input (0 = CLK0, 1 = CLK1). A  $12^{\text{th}}$  clock pulse transfers data from the shift register to the control register.

The ADN4670 is fully specified over the industrial temperature range and is available in a 32-lead LFCSP and LQFP packages.

Rev. A

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### **REVISION HISTORY**

#### 1/12—Rev. 0 to Rev. A

Added LQFP Package	. Throughout
Updated Outline Dimensions	
Changes to Ordering Guide	9
4/10—Revision 0: Initial Version	

# **SPECIFICATIONS**

 $V_{\rm DD}$  = 2.375 V to 2.625 V; all specifications  $T_{\rm MIN}$  to  $T_{\rm MAX}$  , unless otherwise noted.

### Table 1.

Parameter	Symbol	Min	Тур	Max	Unit	<b>Conditions/Comments</b>
RECEIVER						
Input High Threshold at CLK0/CLK0 or CLK1/CLK1	V <sub>TH</sub>			100	mV	
Input Low Threshold at CLK0/CLK0 or CLK1/CLK1	V <sub>TL</sub>	-100			mV	
Differential Input Voltage	VID	200			mV	
Input Common-Mode Voltage	VIC	0.5 VID		$V_{\text{DD}} - 0.5  V_{\text{ID}} $		
Input Current at CLK0, CLK0, CLK1, or CLK1	lıн, lı∟	-5		+5	μΑ	$V_I = V_{DD} \text{ or } V_I = 0 V$
Input Capacitance	Cı		3		рF	$V_I = V_{DD}$ or GND
DRIVER						
Differential Output Voltage	Vod	250	450	600	mV	$R_L = 100 \Omega$
Vod Magnitude Change	$\Delta V_{\text{OD}}$			50	mV	
Offset Voltage	Vos	0.95	1.2	1.45	V	–40°C to +85°C
Vos Magnitude Change	ΔVos			350	mV	
Output Short Circuit Current	los			-20	mA	$V_{\rm O} = 0 V$
				20	mA	$ V_{OD}  = 0 V$
Reference Output Voltage	V <sub>BB</sub>	1.15	1.25	1.35	V	$V_{\text{DD}}=2.5~V,I=-100~\mu\text{A}$
Output Capacitance	Co		3		рF	$V_{O} = V_{DD}$ or GND
SUPPLY CURRENT						
Supply Current	I <sub>DD</sub>			35	mA	All outputs tristated, $f = 0$ Hz
			100	110	mA	All outputs enabled and loaded, $R_L = 100  \Omega, f = 100  \text{MHz}$
			150	160	mA	All outputs enabled and loaded, $R_L = 100 \Omega$ , $f = 800 \text{ MHz}$

### JITTER CHARACTERISTICS

Table 2.						
Parameter	Symbol	Min	Тур	Max	Unit	<b>Conditions/Comments</b>
Additive Phase Jitter from Input to LVDS Outputs, Q3 and $\overline{Q3}$	t <sub>JITTER LVDS</sub>		281		f <sub>s</sub> rms	12 kHz to 5 MHz, $f_{OUT} = 30.72$ MHz
			111		fs rms	12 kHz to 20 MHz, fouт = 125 MHz

### LVDS SWITCHING CHARACTERISTICS

 $V_{DD}$  = 2.375 V to 2.625 V; all specifications  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

#### Table 3.

Parameter	Symbol	Min	Тур	Max <sup>1</sup>	Unit	Conditions/Comments
Propagation Delay Low to High	<b>t</b> <sub>PLHx</sub>		2	3	ns	From CLK0/CLK0 or CLK1/ CLK1 to any Qx/Qx
Propagation Delay High to Low	<b>t</b> PHLx		2	3	ns	From CLK0/CLK0 or CLK1/ CLK1 to any Qx/Qx
Duty Cycle	<b>t</b> duty	45		55	%	From CLK0/ $\overline{\text{CLK0}}$ or CLK1/ $\overline{\text{CLK1}}$ to any Qx/ $\overline{\text{Qx}}$
Output Skew <sup>2</sup>	t <sub>sk(O)</sub>		30		ps	Any Qx/Qx
Pulse Skew <sup>3</sup>	t <sub>SK(P)</sub>			50	ps	Any Qx/Qx
Part-to-Part Output Skew <sup>4</sup>	t <sub>SK(PP)</sub>			600	ps	Any Qx/Qx
Output Rise Time	t <sub>r</sub>			350	ps	Any Qx/ $\overline{Qx}$ , 20% to 80%, R <sub>L</sub> = 100 $\Omega$ C <sub>L</sub> = 5 pF
Output Fall Time	t <sub>f</sub>			350		Any $Qx/\overline{Qx}$ , 80% to 20%, $R_L = 100 \Omega C_L = 5 pF$
Maximum Input Frequency	fclk	900	1100		MHz	From CLK0/CLK0 or CLK1/ CLK1 to any Qx/Qx

<sup>1</sup> Guaranteed by design and characterization.

<sup>2</sup> Output skew is defined as the difference between the largest and smallest values of T<sub>PLHx</sub> within a device or the difference between the largest and smallest values of T<sub>PHLx</sub> within a device, whichever of the two is greater.

<sup>3</sup> Pulse skew is defined as the magnitude of the maximum difference between  $t_{PLH}$  and  $t_{PHL}$  for any channel of a device, that is,  $|t_{PHLx} - t_{HLPx}|$ . <sup>4</sup> Part-to-part output skew is defined as the difference between the largest and smallest values of  $T_{PLHx}$  across multiple devices or the difference between the largest and smallest values of T<sub>PHLx</sub> across multiple devices, whichever of the two is greater.



Figure 2. Waveforms for Calculation of t<sub>SK(O)</sub> and t<sub>SK(PP)</sub>



### **PROGRAMMING LOGIC AC CHARACTERISTICS**

 $V_{\rm DD}$  = 2.375 V to 2.625 V; all specifications  $T_{\rm MIN}$  to  $T_{\rm MAX}$  , unless otherwise noted.

Table 4.	Γable 4.										
Parameter	Symbol	Min	Тур	Max	Unit	Conditions/Comments					
Maximum Frequency at CK Input	f <sub>MAX</sub>	100	150		MHz						
Setup Time, SI to CK	ts∪			2	ns	Time for which SI must not change before the CK 0-to-1 transition					
Hold Time, CK to SI	tн			1.5	ns	Time for which SI must not change after the CK 0-to-1 transition					
EN to CK Removal Time	tremoval			1.5	ns	Removal time, EN to CK					
Start-Up Time	tstartup			1	μs	Start-up time after disable through SI					
Minimum Clock Pulse Width	tw	3			ns						
Logic Input High Level	VIH	2			V	$V_{DD} = 2.5 V$					
Logic Input Low Level	VIL			0.8	V	$V_{DD} = 2.5 V$					
High Level Logic Input Current, CK	Ін	-5		+5	μΑ	$V_I = V_{DD}$					
High Level Logic Input Current, SI and EN		+10		-30	μΑ	$V_I = V_{DD}$					
Low Level Logic Input Current, CK	l <sub>IL</sub>	-10		+30	μΑ	$V_1 = GND$					
Low Level Logic Input Current, SI and EN		-5		+5	μA	V <sub>I</sub> = GND					

### **ABSOLUTE MAXIMUM RATINGS**

 $T_A = 25^{\circ}C$ , unless otherwise noted.

#### Table 3.

Parameter	Rating
V <sub>cc</sub> to GND	–0.3 V to +2.8 V
Input Voltage to GND	-0.2 V to (V <sub>DD</sub> + 0.2) V
Output Voltage to GND	-0.2 V to (V <sub>DD</sub> + 0.2) V
Operating Temperature Range	
Industrial	-40°C to +85°C
Storage Temperature Range	–65°C to +150°C
Junction Temperature (TJ max)	150°C
Power Dissipation	$(T_J max - T_A)/\theta_{JA}$
LFCSP Package	
$\theta_{JA}$ Thermal Impedance	32.5°C/W
LQFP Package	
$\theta_{JA}$ Thermal Impedance	59°C/W
Reflow Soldering Peak Temperature	
Pb-Free	260°C ± 5°C
ESD (Human Body Model, 1.5 kΩ 100 pF)	4000 V

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**



Figure 4. Pin Configuration

#### **Table 4. Pin Function Descriptions**

Pin No.	Mnemonic	Description
1	СК	Programming Clock. Programming data is clocked in on a low-to-high transition at this input. If left open-circuit, it is pulled high by a 120 k $\Omega$ resistor.
2	SI	Serial Data Input. This is the input for programming data. If left open-circuit, it is pulled low by a 120 k $\Omega$ resistor.
3	CLK0	Noninverting Differential Clock Input 0.
4	CLK0	Inverting Differential Clock Input 0.
5	V <sub>BB</sub>	Reference Voltage Output.
6	CLK1	Noninverting Differential Clock Input 1.
7	CLK1	Inverting Differential Clock Input 1.
8	EN	Active-High Enable Input. When this input is high, programming is enabled. If left open-circuit, it is pulled low by a 120 k $\Omega$ resistor.
9, 25	Vss	Device Ground.
10, 12, 14, 17, 19, 21, 23, 26, 28, 30	$\overline{Q9}$ to $\overline{Q0}$	Inverted Clock Output. When the differential input voltage is between CLKx and $\overline{\text{CLKx}}$ > 100 mV, this output sinks current. When the differential input voltage is between CLKx and $\overline{\text{CLKx}}$ < -100 mV, this output sources current.
11, 13, 15, 18, 20, 22, 24, 27, 29, 31	Q9 to Q0	Noninverted Clock Output. When the differential input voltage is between CLKx and $\overline{\text{CLKx}}$ > 100 mV, this output sources current. When the differential input voltage is between CLKx and $\overline{\text{CLKx}}$ < -100 mV, this output sinks current.
16, 32	V <sub>DD</sub>	Power Supply Input. This part can be operated from 2.375 V to 2.625 V.

### THEORY OF OPERATION

The ADN4670 is a clock driver/expander for low voltage differential signaling (LVDS). It takes a differential clock signal of typically 350 mV and expands it to 10 differential clock outputs with very low skew (typically < 30 ps). The device receives a differential current signal from a source such as a twisted pair cable, which develops a voltage of typically  $\pm$ 350 mV across a 100  $\Omega$  terminating resistor. This signal passes via a differential current signal.

The device is programmable using a simple serial interface. One of two differential clock inputs (CLK0/CLK0 or CLK1/CLK1), can be selected and any of the differential outputs (Q0/ $\overline{Q0}$  to Q9/ $\overline{Q9}$ ) can be enabled or disabled.

### LVDS RECIEVER INPUT TERMINATION

Terminate the clock inputs with 100  $\Omega$  resistors from CLK0 to  $\overline{\text{CLK0}}$  and CLK1 to  $\overline{\text{CLK1}}$ , placed as close as possible to the input pins.

### **FAIL-SAFE OPERATION**

In power-down mode ( $V_{DD} = 0$  V), the ADN4670 has fail-safe input and output pins. In power-on mode, fail-safe biasing can be achieved by connecting 10 k $\Omega$  pull-up resistors from CLK0 and CLK1 to V<sub>DD</sub> and 10 k $\Omega$  pull-down resistors from CLK0 and CLK1 to GND.

#### Table 5. Control Logic Truth Table

### PROGRAMMING

Three control inputs are provided for programming the ADN4670. EN is the enable input, which allows programming when high, SI is the serial data input, and CK is the serial clock input, which clocks data into the device on a low-to-high clock transition. Each of these inputs has an internal pull-up or pull-down resistor of 120 k $\Omega$ . EN and SI are pulled low if left open-circuit while CK is pulled high.

The default condition if these inputs are left open-circuit is that all outputs are enabled, and the state of SI selects the inputs (0 = CLK0/CLK0, 1 = CLK1/CLK1). This is the standard operating mode for which no programming of the device is required.

Programming is enabled by taking EN high. The data on SI is then clocked into the device on each 0-to-1 transition of CK. Data on SI must be stable for the setup time  $(t_{SU})$  before the clock transition and remain stable for the hold time  $(t_{H})$  after the clock transition. To program the device, 11 bits of data are needed, starting with Bit 0, which enables or disables outputs Q9/Q9, through to Bit 10, which selects either CLK0/CLK0 or CLK1/CLK1 as the inputs. A 12<sup>th</sup> clock pulse is then required to transfer data from the shift register to the control register.

A low-to-high transition on EN resets the control register and the next 12 CK pulses are programmed.

	0							
СК	EN	SI	CLK0	CLK0	CLK1	CLK1	Q0 to Q9	Q0 to Q9
L	L	L	L	Н	Х	Х	L	Н
L	L	L	Н	L	Х	Х	Н	L
L	L	L	Open	Open	Х	Х	L	Н
L	L	Н	Х	Х	L	Н	L	Н
L	L	Н	Х	Х	Н	L	Н	L
L	L	Н	Х	Х	Open	Open	L	Н

#### Table 6. State Machine Inputs

EN	SI	СК	Output
L	L	Х	Default state with all outputs enabled, CLK0 selected, and the control register disabled
L	Н	Х	All outputs enabled, CLK1 selected, and the control register disabled
Н	L	<b>↑</b>	First stage stores low, other stage stores data of previous stage
Н	Н	<b>↑</b>	First stage stores high, other stage stores data of previous stage
L	Х	Х	Reset the state machine, control register, and shift register

#### Table 7. Serial Input Sequence

Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CLK_SEL	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7	Q8	Q9

#### Table 8. Control Register

Bit 10	Bit[9:0]	Qx[9:0]
L	Н	CLK0
Н	Н	CLK1
Х	L	Outputs disabled

# **OUTLINE DIMENSIONS**



COMPLIANT TO JEDEC STANDARDS MS-026-BBA

Figure 6. 32-Lead Low Profile Quad Flat Package [LQFP] (ST-32-2) Dimensions shown in millimeters

### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option
ADN4670BCPZ	-40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-7
ADN4670BCPZ-REEL7	-40°C to +85°C	32-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-32-7
ADN4670BSTZ	-40°C to +85°C	32-Lead Low Profile Quad Flat Package [LQFP]	ST-32-2
ADN4670BSTZ-REEL7	–40°C to +85°C	32-Lead Low Profile Quad Flat Package [LQFP]	ST-32-2

 $^{1}$  Z = RoHS Compliant Part.

# ADN4670

# NOTES

# NOTES

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# **Data Sheet**

# NOTES



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