# LTC3607EUD Dual 600mA 15V Monolithic Synchronous Step-Down Regulator 

## DESCRIPTION

Demonstration circuit DC1596 is a dual output regulator consisting of two constant-frequency step-down converters, based on the LTC ${ }^{\circledR} 3607$ monolithic dual channel synchronous buck regulator. The DC1596 has an input voltage range of 4.5 V to 15 V , with each regulator capable of delivering up to 600 mA of output current. The DC1596 can operate in either Burst Mode ${ }^{\circledR}$ operation or pulse-skipping mode. In shutdown, the DC1596 quiescent current is less than $1 \mu \mathrm{~A}$. The DC1596 is a very efficient circuit attaining up to $90 \%$. The DC1596 uses the LTC3607's16-lead QFN
package, which has an exposed pad on the bottom side of the IC for better thermal performance. These features, plus a set operating frequency range of 2.25 MHz , make the DC1596 demo board an ideal circuit for industrial or distributed power applications.
Design files for this circuit board are available at http://www.linear.com/demo
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## PERFORMANCE SUMMARY <br> Specifications are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$

| PARAMETER | CONDITIONS | VALUE |
| :---: | :---: | :---: |
| Minimum Input Voltage |  | 4.5V |
| Maximum Input Voltage |  | 15V |
| Run | $\begin{aligned} & \text { RUN Pin }=\text { GND } \\ & \text { RUN Pin }=V_{I N} \end{aligned}$ | Shutdown Operating |
| Output Voltage V ${ }_{\text {OUT1 }}$ Regulation | $\mathrm{V}_{\text {IN1 }}=4.5 \mathrm{~V}$ to $15 \mathrm{~V}, \mathrm{I}_{\text {OUT } 1}=0 \mathrm{~A}$ to 600 mA | $\begin{aligned} & 1.2 \mathrm{~V} \pm 4 \%(1.152 \mathrm{~V}-1.148 \mathrm{~V}) \\ & 1.5 \mathrm{~V} \pm 4 \%(1.44 \mathrm{~V}-1.56 \mathrm{~V}) \\ & 1.8 \mathrm{~V} \pm 4 \%(1.728 \mathrm{~V}-1.872 \mathrm{~V}) \end{aligned}$ |
| Typical Output Ripple V ${ }_{\text {Out1 }}$ | $\mathrm{V}_{\text {IN } 1}=12 \mathrm{~V}, \mathrm{I}_{\text {OUT } 1}=600 \mathrm{~mA}(20 \mathrm{MHz} \mathrm{BW})$ | $<20 \mathrm{mV} \mathrm{P}_{\text {P- }}$ |
| Output Voltage V ${ }_{\text {OUT2 }}$ Regulation | $\mathrm{V}_{\text {IN2 } 2}=4.5 \mathrm{~V}$ to $15 \mathrm{~V}, \mathrm{I}_{\text {OUT2 }}=0 \mathrm{~A}$ to 600 mA | $\begin{aligned} & 2.5 \mathrm{~V} \pm 4 \%(2.425 \mathrm{~V}-2.6 \mathrm{~V}) \\ & 3.3 \mathrm{~V} \pm 4 \%(3.168 \mathrm{~V}-3.432 \mathrm{~V}) \\ & 5 \mathrm{~V} \pm 4 \%(4.8 \mathrm{~V}-5.2 \mathrm{~V}) \end{aligned}$ |
| Typical Output Ripple V 0 UT2 | $\mathrm{V}_{\text {IN2 }}=12 \mathrm{~V}, \mathrm{I}_{\text {OUT2 }}=600 \mathrm{~mA}(20 \mathrm{MHz} \mathrm{BW})$ | <20mVP-p |
| Mode Setting | Mode Pin Floating Mode Pin Grounded | Burst Mode Operation Pulse-Skipping |
| Burst Mode Operation Output Current Thresholds | Channel 1: PV ${ }_{\text {IN } 1}=12 \mathrm{~V}, \mathrm{~V}_{\text {out } 1}=1.8 \mathrm{~V}$ <br> Channel 2: PVIN2 $=12 \mathrm{~V}, \mathrm{~V}_{\text {OUT2 }}=3.3 \mathrm{~V}$ | $\begin{aligned} & I_{\text {OUT1 }}<480 \mathrm{~mA} \\ & I_{\text {OUT2 }}<360 \mathrm{~mA} \end{aligned}$ |
| Pulse-Skipping Operation Output Current Thresholds | Channel 1: $\mathrm{PV}_{\operatorname{IN} 1}=12 \mathrm{~V}, \mathrm{~V}_{\text {out } 1}=1.8 \mathrm{~V}$ <br> Channel 2: $\mathrm{PV}_{\text {IN2 }}=12 \mathrm{~V}, \mathrm{~V}_{\text {OUT2 }}=3.3 \mathrm{~V}$ | $\begin{aligned} & I_{\text {OUT } 1}<330 \mathrm{~mA} \\ & \mathrm{I}_{\text {OUT2 }}<240 \mathrm{~mA} \end{aligned}$ |
| Switching Frequency |  | $2.25 \mathrm{MHz} \pm 20 \%$ |

## DEMO MANUAL DC1596A

## DUICK START PROCEDURE

The DC1596 is easy to set up to evaluate the performance of the LTC3607. For a proper measurement equipment configuration, set up the circuit according to the diagram in Figure 1.

Note: When measuring the input or output voltage ripple, care must be taken to avoid a long ground lead on the oscilloscope probe. Measure the input or output voltage ripple by touching the probe tip directly across the $\mathrm{V}_{\text {IN }}$ or $V_{\text {OUt }}$ and GND terminals. See the proper scope probe technique in Figure 2.
Please follow the procedure outlined below for proper operation.

1. Connect the input power supply to the PVIN1/PVIN2 and GND terminals ( $\mathrm{V}_{\text {IN1 }}$ and $\mathrm{V}_{\text {IN2 }}$ are separate nodes but are connected). Connect the loads between the VOUT and GND terminals. Refer to Figure 1 for the proper measurement equipment setup.

Before proceeding to operation, insert jumper shunts XJP1 and XJP2 into the OFF positions of headers JP1 and JP2, shunt XJP3 into the pulse-skip position of MODE header JP3, and shunt XJP4 into the VOUT1 voltage options of choice of header JP4: 1.2V, 1.5V, or 1.8 V , and shunt XJP5 into the VOUT2 voltage options of choice of header JP5: 2.5V, 3.3V, or 5V.
2. Apply 5.5 V at PVINs 1 , 2. Measure both VOUTs; they should read OV. If desired, one can measure the shutdown supply current at this point. The supply current will be less than $1 \mu \mathrm{~A}$ in shutdown.
3. Turn on VOUT1 and VOUT2 by shifting shunts XJP1 and XJP2 from the OFF positions to the ON positions. Both output voltages should be within a tolerance of $\pm 2 \%$.
4. Vary the input voltages from 5.8 V (the minimum $\mathrm{V}_{\text {IN }}$ is dependent on $\mathrm{V}_{\text {OUT }}$ ) to 15 V , and the load currents from OA to 600 mA . Both output voltages should be within $\pm 4 \%$ tolerance.
5. Set the load current of both outputs to 600 mA and the input voltages to 12 V , and then measure each output ripple voltage (refer to Figure 2 for proper measurement technique); they should each measure less than 20 mVAC . Also, observe the voltage waveform at either switch node (Pin 5 for reg. 1 and Pin 8 for reg.2) of each regulator. The switching frequencies should be about $2.25 \mathrm{MHz} \pm 20 \%$ ( $\mathrm{T}=555 \mathrm{~ns}$ and 370 ns ). Both switch node waveforms should be rectangular in shape, and $180^{\circ}$ out-of-phase with each other.
6. To operate the ckt.s in Burst Mode operation, change the shunt position of header JP3 to BURST MODE.
7. Regulators 1 (PVIN1) and 2 (PVIN2) are completely separated from each other; thus, they can be powered from different individual input supplies (if R11 is removed), as can the signal input supply, SVIN. However, SVIN must powered for either regulator to function (SVIN is connected to PVIN1 through a filter on the demo board.).
8. When finished, insert shunts XJP1 and XJP2 to the OFF position(s) and disconnect the power.

Warning: If the power for the demo board is carried in long leads, the input voltage at the part could "ring", which could affect the operation of the circuit or even exceed the maximum voltage rating of the IC. To eliminate the ringing, a small tantalum capacitor (for instance, AVX part \# TPSY226M035R0200) is inserted on the pads between the input power and return terminals on the bottom of the demo board. The (greater) ESR of the tantalum capacitor will dampen the (possible) ringing voltage caused by the long input leads. On a normal, typical PCB, with short traces, this capacitor is not needed.

## DEMO MANUAL DC1596A

## PUICK START PROCEDURE



Figure 1. Proper Measurement Equipment Setup


Figure 2. Measuring Input or Output Ripple

## DEMO MANUAL DC1596A

## PUICK START PROCEDURE



Figure 3. Switch Operation


Figure 5. Load Step Response

$V_{\text {IN }}=12 \mathrm{~V}$
$V_{\text {OUT1 }}=1.2 \mathrm{~V}$
400mA LOAD STEP ( 200 mA TO 600 mA )
PULSE-SKIPPING MODE, $\mathrm{f}_{\mathrm{SW}}=2.25 \mathrm{MHz}$
Figure 4. Load Step Response


Figure 6. Load Step Response

## PUICK START PROCEDURE


$\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}$
$V_{\text {OUT2 }}=2.5 \mathrm{~V}$
400 mA LOAD STEP ( 200 mA TO 600 mA )
PULSE-SKIPPING MODE, $\mathrm{f}_{\mathrm{SW}}=2.25 \mathrm{MHz}$
Figure 7. Load Step Response


Figure 9. Load Step Response

$V_{I N}=12 \mathrm{~V}$
$V_{\text {OUT2 }}=3.3 \mathrm{~V}$
400mA LOAD STEP ( 200 mA TO 600 mA )
PULSE-SKIPPING MODE, $\mathrm{f}_{\mathrm{SW}}=2.25 \mathrm{MHz}$
Figure 8. Load Step Response


Figure 10. Efficiency

## DEMO MANUAL DC1596A

## PARTS LIST

| ITEM | QTY | REFERENCE | PART DESCRIPTION | MANUFACTURER/PART NUMBER |
| :---: | :---: | :--- | :--- | :--- |
| Required Circuit Components |  | CAP., NPO, 22pF, 25V, 5\%, 0402 | AVX, 04025A220JAT2A |  |
| 1 | 2 | CFFW1, CFFW2 | CAP., X7R, $0.1 \mu F, 16 \mathrm{~V}, 10 \%, 0603$ | AVX, 0603YC104KAT2A |
| 2 | 2 | CIN1BYP, CIN2BYP | CAP., X5R, $10 \mu \mathrm{~F}, 6.3 \mathrm{~V}, 10 \%, 0805$ | AVX, 08056D106KAT2A |
| 3 | 2 | COUT1, COUT2 | CAP., X5R, 10 $\mathrm{FF}, 16 \mathrm{~V}, 10 \%, 1206$ | AVX, 1206YD106KAT2A |
| 4 | 2 | CIN1, CIN2 | Inductor, $2.2 \mu \mathrm{H}$ | VISHAY, IHLP1616BZER2R2M11 |
| 5 | 1 | L1 | Inductor, 4.7 $\mu \mathrm{H}$ | VISHAY, IHLP1616BZER4R7M11 |
| 6 | 1 | L2 | RES., CHIP, 210k, $1 \%, 0402$ | VISHAY, CRCW0402210KFKED |
| 7 | 1 | R1 | RES., CHIP, 887k, $1 \%, 0402$ | VISHAY, CRCW0402887KFKED |
| 8 | 1 | R2 | RES., CHIP, 196k, $1 \%, 0402$ | VISHAY, CRCW0402196KFKED |
| 9 | 1 | R6 | RES., CHIP, 105k, $1 \%, 0402$ | VISHAY, CRCW0402105KFKED |
| 10 | 1 | R7 | IC., LTC3607EUD, 16-PIN QFN 3X3 | LINEAR TECH., LTC3607EUD |
| 11 | 1 | U1 |  |  |

Additional Demo Board Circuit Components

| 1 | 3 | COUT3, COUT4, CF | CAP., X7R, $0.1 \mu \mathrm{~F}, 16 \mathrm{~V}, 10 \%, 0603$ | AVX, 0603YC104KAT2A |
| :---: | :--- | :--- | :--- | :--- |
| 2 | 2 | CIN3, CIN4 | CAP., TANT, $22 \mu F, 35 \mathrm{~V}, 20 \%$, CASE Y | AVX, TPSY226M035R0200 |
| 3 | 0 | COUT5, COUT6 (OPT.) | CAP., X5R, $47 \mu F, 6.3 \mathrm{~V}, 10 \%, 1210$ | AVX, 12106D476KAQ2A |
| 4 | 0 | CIN5, CIN6 (OPT.) | CAP., X5R, $47 \mu \mathrm{~F}, 20 \mathrm{~V}, 10 \%, 1812$ |  |
| 5 | 1 | RF | RES., CHIP, 100 $\Omega, 1 / 16 \mathrm{~W}, 5 \%, 0402$ | VISHAY, CRCW0402100RJNED |
| 6 | 1 | R3 | RES., CHIP, 210k, $1 \%, 0402$ | VISHAY, CRCW0402210KFKED |
| 7 | 1 | R4 | RES., CHIP, 280k, $1 \%, 0402$ | VISHAY, CRCW0402280KFKED |
| 8 | 1 | R5 | RES., CHIP, 140k, $1 \%, 0402$ | VISHAY, CRCW0402140KFKED |
| 9 | 1 | R8 | RES., CHIP, 121k, $1 \%, 0402$ | VISHAY, CRCW0402105KFKED |
| 10 | 0 | R9, R10 (OPT.) | RES., 0402 |  |
| 11 | 1 | R11 | RES., CHIP, 0 $2,1 \%, 0805$ | VISHAY, CRCW08050000Z0ED |
| 12 | 2 | RSD1, RSD2 | RES., CHIP, $5.1 M, 5 \%, 0402$ | VISHAY, CRCW04025M10JNED |
| 13 | 2 | RPG1, RPG2 | RES., CHIP, 100k, $1 \%, 0402$ | VISHAY, CRCW0402100KFKED |

Hardware

| 1 | 12 | E1-E12 | Testpoint, TURRET, 0.094" | MILL-MAX-2501-2-00-80-00-00-07-0 |
| :---: | :---: | :--- | :--- | :--- |
| 2 | 2 | JP1,JP2 | 0.079 SINGLE ROW HEADER, 3-PIN | SAMTEC, TMM103-02-L-S |
| 3 | 2 | JP4,JP5 | $0.079,2$ 2X4 HEADER | SAMTEC, TMM104-02-L-D |
| 4 | 1 | JP3 | $0.079,2 X 3$ HEADER | SAMTEC, TMM103-02-L-D |
| 5 | 5 | JP1-JP5 | SHUNT, FOR JP1-JP5 | SAMTEC, 2SN-BK-G |

## SCHEMATIC DIAGRAM



## DEMO MANUAL DC1596A

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Mailing Address:

Linear Technology<br>1630 McCarthy Blvd.<br>Milpitas, CA 95035

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