## FEATURES

2.5 kV rms signal and power isolated CAN transceiver isoPower integrated isolated dc-to-dc converter 5 V operation on $\mathrm{V}_{\mathrm{cc}}$
5 V or 3.3 V operation on $\mathrm{V}_{10}$
Complies with ISO 11898 standard
High speed data rates of up to 1 Mbps
Unpowered nodes do not disturb the bus
Connect $\mathbf{1 1 0}$ or more nodes on the bus
Slope control for reduced EMI
Thermal shutdown protection
High common-mode transient immunity: >25 kV/ $\mu \mathrm{s}$
Safety and regulatory approvals
UL recognition
2500 V rms for 1 minute per UL 1577
CSA Component Acceptance Notice 5A
VDE Certificate of Conformity
DIN EN 60747-5-2 (VDE 0884 Part 2): 2003-01

$$
\mathrm{V}_{\text {IORM }}=560 \mathrm{~V} \text { peak }
$$

Industrial operating temperature range $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$
Available in wide-body, 20-lead SOIC package

## APPLICATIONS

CAN data buses
Industrial field networks

## GENERAL DESCRIPTION

The ADM3053 is an isolated controller area network (CAN) physical layer transceiver with an integrated isolated dc-to-dc converter. The ADM3053 complies with the ISO 11898 standard.
The device employs Analog Devices, Inc., iCoupler ${ }^{\ominus}$ technology to combine a 2-channel isolator, a CAN transceiver, and Analog Devices isoPower ${ }^{\oplus}$ dc-to-dc converter into a single SOIC surface mount package. An on-chip oscillator outputs a pair of square waveforms that drive an internal transformer to provide isolated power. The device is powered by a single 5 V supply realizing a fully isolated CAN solution.
The ADM3053 creates a fully isolated interface between the CAN protocol controller and the physical layer bus. It is capable of running at data rates of up to 1 Mbps .
The device has current limiting and thermal shutdown features to protect against output short circuits. The part is fully specified over the industrial temperature range and is available in a 20-lead, wide-body SOIC package.
The ADM3053 contains isoPower technology that uses high frequency switching elements to transfer power through the transformer. Special care must be taken during printed circuit board (PCB) layout to meet emissions standards. Refer to the AN-0971 Application Note, Recommendations for Control of Radiated Emissions with isoPower Devices, for details on board layout considerations.

FUNCTIONAL BLOCK DIAGRAM


Figure 1.

## ADM3053

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## SPECIFICATIONS

All voltages are relative to their respective grounds; $4.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CC}} \leq 5.5 \mathrm{~V} ; 3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IO}} \leq 5.5 \mathrm{~V}$. All minimum/maximum specifications apply over the entire recommended operation range, unless otherwise noted. All typical specifications are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}$, and $\mathrm{V}_{\mathrm{IO}}=5 \mathrm{~V}$ unless otherwise noted.

Table 1.

| Parameter | Symbol | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SUPPLY CURRENT <br> Logic Side isoPower Current <br> Recessive State <br> Dominant State <br> TxD/RxD Data Rate 1 Mbps <br> Logic Side iCoupler Current <br> TxD/RxD Data Rate 1 Mbps | Icc Icc Icc Io |  | $\begin{aligned} & 29 \\ & 195 \\ & 139 \\ & 1.6 \end{aligned}$ | $\begin{aligned} & 36 \\ & 260 \\ & 200 \\ & 2.5 \end{aligned}$ | mA <br> mA <br> mA <br> mA | $R_{L}=60 \Omega, R_{s}=$ low, see Figure 25 <br> $R_{L}=60 \Omega, R_{s}=$ low, see Figure 25 <br> $R_{L}=60 \Omega, R_{S}=$ low, see Figure 25 |
| DRIVER <br> Logic Inputs Input Voltage High Input Voltage Low CMOS Logic Input Currents Differential Outputs Recessive Bus Voltage CANH Output Voltage CANL Output Voltage Differential Output Voltage <br> Short-Circuit Current, CANH <br> Short-Circuit Current, CANL | $\mathrm{V}_{\mathrm{IH}}$ <br> VIL <br> $\mathrm{I}_{\mathrm{H}, \mathrm{I}} \mathrm{IL}$ <br> $\mathrm{V}_{\text {Canl, }} \mathrm{V}_{\text {Canh }}$ <br> $V_{\text {Canh }}$ <br> $V_{\text {canl }}$ <br> Vod <br> Vod <br> Isccanh <br> Isccanl | $\begin{aligned} & 0.7 \mathrm{~V}_{10} \\ & \\ & \\ & 2.0 \\ & 2.75 \\ & 0.5 \\ & 1.5 \\ & -500 \end{aligned}$ | $-100$ | 0.25 V 10 500 3.0 4.5 2.0 3.0 +50 -200 200 | V <br> V <br> $\mu \mathrm{A}$ <br> V <br> V <br> V <br> V <br> mV <br> mA <br> mA <br> mA | Output recessive <br> Output dominant <br> TxD $\begin{aligned} & \mathrm{TxD}=\text { high, } \mathrm{R}_{\mathrm{L}}=\infty, \text { see Figure } 22 \\ & \mathrm{TxD}=\text { low, see Figure } 22 \\ & \mathrm{TxD}=\text { low, see Figure } 22 \\ & \mathrm{TxD}=\text { low, } \mathrm{R}_{\mathrm{L}}=45 \Omega \text {, see Figure } 22 \\ & \mathrm{TxD}=\text { high, } \mathrm{R}_{\mathrm{L}}=\infty \text {, see Figure } 22 \\ & \mathrm{~V}_{\text {CANH }}=-5 \mathrm{~V} \\ & \mathrm{~V}_{\text {CANH }}=-36 \mathrm{~V} \\ & \mathrm{~V}_{\text {CANL }}=36 \mathrm{~V} \end{aligned}$ |
| RECEIVER <br> Differential Inputs <br> Differential Input Voltage Recessive <br> Differential Input Voltage Dominant <br> Input Voltage Hysteresis <br> CANH, CANL Input Resistance <br> Differential Input Resistance <br> Logic Outputs <br> Output Low Voltage <br> Output High Voltage <br> Short Circuit Current | $V_{\text {IDR }}$ <br> $V_{\text {IDD }}$ <br> $V_{\text {HYS }}$ <br> Rin <br> Roiff <br> Vol <br> Voн <br> los | $-1.0$ <br> 0.9 <br> 5 <br> 20 <br> $V_{10}-0.3$ <br> 7 | $150$ <br> 0.2 $V_{10}-0.2$ | $+0.5$ <br> 5.0 <br> 25 <br> 100 <br> 0.4 <br> 85 | V <br> V <br> mV <br> k $\Omega$ <br> k $\Omega$ <br> V <br> V <br> mA | $\begin{aligned} & -7 \mathrm{~V}<\mathrm{V}_{\text {CANL }}, \mathrm{V}_{\text {CANH }}<+12 \mathrm{~V} \text {, see Figure 23, } \\ & \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF} \\ & -7 \mathrm{~V}<\mathrm{V}_{\text {CANL, }} \mathrm{V}_{\text {CANH }}<+12 \mathrm{~V} \text {, see Figure 23, } \\ & \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF} \end{aligned}$ $\text { See Figure } 3$ $\begin{aligned} & \text { lout }=1.5 \mathrm{~mA} \\ & \text { lout }=-1.5 \mathrm{~mA} \\ & \text { V }_{\text {OUT }}=\mathrm{GND} 1 \text { or } \mathrm{V}_{\text {IO }} \end{aligned}$ |
| VOLTAGE REFERENCE <br> Reference Output Voltage | $V_{\text {ReF }}$ | 2.025 |  | 3.025 | V | $\left.\|l\| l\right\|_{\text {REF }}=50 \mu \mathrm{~A} \mid$ |
| COMMON-MODE TRANSIENT IMMUNITY ${ }^{1}$ |  | 25 |  |  | kV/ $\mu \mathrm{s}$ | $\mathrm{V}_{\text {CM }}=1 \mathrm{kV}$, transient magnitude $=800 \mathrm{~V}$ |
| SLOPE CONTROL <br> Current for Slope Control Mode Slope Control Mode Voltage | Islope $V_{\text {SLOPE }}$ | $\begin{gathered} -10 \\ 1.8 \end{gathered}$ |  | $\begin{aligned} & -200 \\ & 3.3 \end{aligned}$ | $\begin{aligned} & \mu \mathrm{A} \\ & \mathrm{~V} \end{aligned}$ |  |

## ADM3053

## TIMING SPECIFICATIONS

All voltages are relative to their respective ground; $3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IO}} \leq 5.5 \mathrm{~V} ; 4.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CC}} \leq 5.5 \mathrm{~V} . \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted.
Table 2.

| Parameter | Symbol | Min | Typ | Max | Unit | Test Conditions/Comments |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| DRIVER <br> Maximum Data Rate <br> Propagation Delay from TxD On to Bus Active |  | tonTxD |  |  |  | Mbps |

${ }^{1}$ Guaranteed by design and characterization.

## SWITCHING CHARACTERISTICS



Figure 2. Driver Propagation Delay, Rise/Fall Timing


ADM3053

## REGULATORY INFORMATION

Table 3. ADM3053 Approvals

| Organization | Approval Type | Notes |
| :---: | :---: | :---: |
| UL | Recognized under the Component Recognition Program of Underwriters Laboratories, Inc. | In accordance with UL 1577, each ADM3053 is proof tested by applying an insulation test voltage $\geq 2500 \mathrm{~V}$ rms for 1 second. File E214100. |
| VDE | Certified according to DIN EN 60747-5-2 (VDE 0884 Part 2): 2003-01. | In accordance with VDE 0884-2. File 2471900-4880-0001. |
| CSA | Approved under CSA Component Acceptance Notice 5A. Testing was conducted per CSA 60950-1-07 and IEC 60950-1, 2nd Edition at 2.5 kV rated voltage. <br> Testing was conducted per CSA 61010-1-04 and IEC 61010-1 2nd Edition at 2.5 kV rated voltage. | Basic insulation at 760 V rms ( 1074 V peak) working voltage. Reinforced insulation at 380 V rms ( 537 V peak) working voltage. <br> Basic insulation at 424 V rms ( 600 V peak) working voltage. Reinforced insulation at 300 V rms ( 424 V peak) working voltage. <br> File 205078. |

## INSULATION AND SAFETY-RELATED SPECIFICATIONS

Table 4.

| Parameter | Symbol | Value | Unit | Test Conditions/Comments |
| :--- | :--- | :--- | :--- | :--- |
| Rated Dielectric Insulation Voltage | L(I01) | 2500 | V rms | 1-minute duration <br> Minimum External Air Gap (Clearance) |
| Measured from input terminals to output terminals, <br> shortest distance through air |  |  |  |  |
| Minimum External Tracking (Creepage) | L(IO2) | 7.6 | mm | Measured from input terminals to output terminals, <br> shortest distance along body |
| Minimum Internal Gap (Internal <br> $\quad$ Clearance) |  | 0.017 min | mm | Insulation distance through insulation |
| Tracking Resistance (Comparative <br> $\quad$ Tracking Index) | CTI | $>400$ | V | DIN IEC 112/VDE 0303-1 |
| Isolation Group | II |  | Material group (DIN VDE 0110: 1989-01, Table 1) |  |

## ADM3053

## VDE 0884 INSULATION CHARACTERISTICS

This isolator is suitable for basic electrical isolation only within the safety limit data. Maintenance of the safety data must be ensured by means of protective circuits.

Table 5.

| Description | Test Conditions/Comments | Symbol | Characteristic | Unit |
| :---: | :---: | :---: | :---: | :---: |
| CLASSIFICATIONS <br> Installation Classification per DIN VDE 0110 for Rated <br> Mains Voltage <br> $\leq 150$ V rms <br> $\leq 300$ V rms <br> $\leq 400 \mathrm{~V}$ rms <br> Climatic Classification <br> Pollution Degree | DIN VDE 0110, see Table 3 |  | I to IV <br> I to III <br> I to \|| <br> 40/85/21 <br> 2 |  |
| VOLTAGE <br> Maximum Working Insulation Voltage Input-to-Output Test Voltage Method b1 <br> Highest Allowable Overvoltage | $V_{\text {IORM }} \times 1.875=V_{\text {PR, }} 100 \%$ production tested, $\mathrm{t}_{\mathrm{m}}=1 \mathrm{sec}$, partial discharge $<5 \mathrm{pC}$ <br> (Transient overvoltage, $\mathrm{t}_{\text {TR }}=10 \mathrm{sec}$ ) | Viorm $V_{\text {PR }}$ $V_{T R}$ | $\begin{aligned} & 560 \\ & 1050 \\ & 4000 \end{aligned}$ | $V_{\text {Peak }}$ <br> $V_{\text {Peak }}$ <br> $V_{\text {PEAK }}$ |
| SAFETY-LIMITING VALUES <br> Case Temperature Input Current Output Current Insulation Resistance at $\mathrm{T}_{\mathrm{s}}$ | Maximum value allowed in the event of a failure $V_{10}=500 \mathrm{~V}$ | $\mathrm{T}_{\mathrm{s}}$ <br> Is, Input <br> Is, output <br> Rs | $\begin{aligned} & 150 \\ & 265 \\ & 335 \\ & >10^{9} \end{aligned}$ | ${ }^{\circ} \mathrm{C}$ <br> mA <br> mA <br> $\Omega$ |

## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted. All voltages are relative to their respective ground.

Table 6.

| Parameter | Rating |
| :---: | :---: |
| Vcc | -0.5 V to +6 V |
| $V_{10}$ | -0.5 V to +6 V |
| Digital Input Voltage, TxD | -0.5 V to $\mathrm{V}_{10}+0.5 \mathrm{~V}$ |
| Digital Output Voltage, RxD | -0.5 V to $\mathrm{V}_{10}+0.5 \mathrm{~V}$ |
| CANH, CANL | -36 V to +36 V |
| $\mathrm{V}_{\text {ReF }}$ | -0.5 V to +6 V |
| Rs | -0.5 V to +6 V |
| Operating Temperature Range | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| ESD (Human Body Model) | 3 kV |
| Lead Temperature |  |
| Soldering (10 sec) | $300^{\circ} \mathrm{C}$ |
| Vapor Phase (60 sec) | $215^{\circ} \mathrm{C}$ |
| Infrared (15 sec) | $220^{\circ} \mathrm{C}$ |
| $\theta_{\mathrm{JA}}$ Thermal Impedance | $53^{\circ} \mathrm{C} / \mathrm{W}$ |
| T, Junction Temperature | $150^{\circ} \mathrm{C}$ |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

Table 7. Maximum Continuous Working Voltage ${ }^{1}$

| Parameter | Max | Unit | Reference Standard |
| :---: | :---: | :---: | :---: |
| AC Voltage |  |  |  |
| Bipolar Waveform | 424 | $\checkmark$ peak | 50 year minimum lifetime |
| Unipolar Waveform |  |  |  |
| Basic Insulation | 1074 | $\checkmark$ peak | Maximum approved working voltage per IEC60950-1 |
| Reinforced Insulation | 537 | $\checkmark$ peak | Maximum approved working voltage per IEC60950-1 |
| DC Voltage |  |  |  |
| Basic Insulation | 1074 | $\checkmark$ peak | Maximum approved working voltage per IEC60950-1 |
| Reinforced Insulation | 537 | $\checkmark$ peak | Maximum approved working voltage per IEC60950-1 |

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

| GND1 1 | ADM3053 TOP VIEW (Not to Scale) | 20 GND2 |
| :---: | :---: | :---: |
| NC ${ }^{2}$ |  | 19 V ISOIN |
| GND1 3 |  | $18 \mathrm{R}_{\mathrm{S}}$ |
| RxD 4 |  | 17 CANH |
| TxD 5 |  | 16 GND2 |
| $\mathrm{v}_{10} 6$ |  | 15 CANL |
| GND1 7 |  | 14 V VEF |
| $\mathrm{v}_{\mathrm{cc}} 8$ |  | 13 GND2 |
| GND1 9 |  | 12 V ISOOUT |
| GND1 10 |  | 11 GND 2 |

NOTES

1. NC = NO CONNECT. DO NOT CONNECT TO THIS PIN.
2. PIN 12 AND PIN 19 MUST BE CONNECTED EXTERNALLY.

Figure 4. Pin Configuration
Table 8. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1,3, 7, 9, 10 | GND1 | Ground, Logic Side. |
| 2 | NC | No Connect. Do not connect to this pin. |
| 4 | RxD | Receiver Output Data. |
| 5 | TxD | Driver Input Data. |
| 6 | $V_{10}$ | $i$ Coupler Power Supply. It is recommended that a $0.1 \mu \mathrm{~F}$ and a $0.01 \mu \mathrm{~F}$ decoupling capacitor be fitted between Pin 6 and GND1. See Figure 28 for layout recommendations. |
| 8 | $\mathrm{V}_{\text {cc }}$ | isoPower Power Supply. It is recommended that a $0.1 \mu \mathrm{~F}$ and a $10 \mu \mathrm{~F}$ decoupling capacitor be fitted between Pin 8 and Pin 9. |
| 11,13 | GND2 | Ground for Isolated DC-to-DC Converter. It is recommended to connect Pin 11 and Pin 13 together through one ferrite bead to the PCB ground. |
| 12 | $V_{\text {Isoout }}$ | Isolated Power Supply Output. This pin must be connected externally to $\mathrm{V}_{\text {Isoin. }}$. It is recommended that a ferrite bead reservoir capacitor of $10 \mu \mathrm{~F}$ and a decoupling capacitor of $0.1 \mu \mathrm{~F}$ be fitted between Pin 12 and Pin 11. |
| 14 | $V_{\text {ReF }}$ | Reference Voltage Output. It is recommended not to connect to this pin. |
| 15 | CANL | Low-Level CAN Voltage Input/Output. |
| 16, 20 | GND2 | Ground, Bus Side. |
| 17 | CANH | High-Level CAN Voltage Input/Output. |
| 18 | Rs | Slope Control Pin. Short this pin to GND2 (Pin 16 or Pin 20) for full speed operation. Use a weak pull-down for slope control. An input high places the transceiver in standby. This pin must not be left floating. |
| 19 | Visoin | Isolated Power Supply Input. This pin must be connected externally to $\mathrm{V}_{\text {Isoout. It }}$ is recommended this pin have a $0.1 \mu \mathrm{~F}$ capacitor to GND2 (Pin13 or Pin 11). Connect this pin through a ferrite bead and short trace length to $\mathrm{V}_{\text {Isoin }}$ for operation. |

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 5. Supply Current, Icc vs. Data Rate


Figure 6. Driver Slew Rate vs. Resistance, Rs


Figure 7. Supply Current, $I_{10}$ vs. Data Rate


Figure 8. Receiver Input Hysteresis vs. Temperature


Figure 9. Propagation Delay from TxD On to Bus Active vs. Temperature


Figure 10. Propagation Delay from TxD Off to Bus Inactive vs. Temperature


Figure 11. Propagation Delay from TxD On to Receiver Active vs. Temperature


Figure 12. Propagation Delay from TxD On to Receiver Active vs. Temperature


Figure 13. Propagation Delay from TxD Off to Receiver Inactive vs. Temperature


Figure 14. Propagation Delay from TxD Off to Receiver Inactive vs. Temperature


Figure 15. Differential Output Voltage Dominant vs. Temperature


Figure 16. Differential Output Voltage Dominant vs. Supply Voltage, Vcc


Figure 17. Reference Voltage vs. Temperature


Figure 18. Supply Current Icc vs. Temperature


Figure 19. Supply Current, I Icc vs. Supply Voltage Vcc


Figure 20. Receiver Output High Voltage vs. Temperature


Figure 21. Receiver Output Low Voltage vs. Temperature

## TEST CIRCUITS



Figure 22. Driver Voltage Measurement


Figure 23. Receiver Voltage Measurements


Figure 25. Supply Current Measurement Test Circuit

## CIRCUIT DESCRIPTION

## CAN TRANSCEIVER OPERATION

A CAN bus has two states called dominant and recessive. A dominant state is present on the bus when the differential voltage between CANH and CANL is greater than 0.9 V . A recessive state is present on the bus when the differential voltage between CANH and CANL is less than 0.5 V . During a dominant bus state, the CANH pin is high, and the CANL pin is low. During a recessive bus state, both the CANH and CANL pins are in the high impedance state.

Pin 18 ( $\mathrm{R}_{\mathrm{S}}$ ) allows two different modes of operation to be selected: high-speed and slope control. For high-speed operation, the transmitter output transistors are simply switched on and off as fast as possible. In this mode, no measures are taken to limit the rise and fall slopes. A shielded cable is recommended to avoid electromagnetic interference (EMI) problems. High-speed mode is selected by connecting Pin 18 to ground.
Slope control mode allows the use of an unshielded twisted pair or a parallel pair of wires as bus lines. To reduce EMI, the rise and fall slopes must be limited. The rise and fall slopes can be programmed with a resistor connected from Pin 18 to ground. The slope is proportional to the current output at Pin 18.

## SIGNAL ISOLATION

The ADM3053 signal isolation is implemented on the logic side of the interface. The part achieves signal isolation by having a digital isolation section and a transceiver section (see Figure 1). Data applied to the TxD pin referenced to logic ground (GND1) are coupled across an isolation barrier to appear at the transceiver section referenced to isolated ground (GND2). Similarly, the singleended receiver output signal, referenced to isolated ground in the transceiver section, is coupled across the isolation barrier to appear at the RxD pin referenced to logic ground (GND1). The signal isolation is powered by the $\mathrm{V}_{\text {Io }}$ pin and allows the digital interface to 3.3 V or 5 V logic.

## POWER ISOLATION

The ADM3053 power isolation is implemented using an isoPower integrated isolated dc-to-dc converter. The dc-to-dc converter section of the ADM3053 works on principles that are common to most modern power supplies. It is a secondary side controller architecture with isolated pulse-width modulation (PWM) feedback. V ${ }_{\text {CC }}$ power is supplied to an oscillating circuit that switches current into a chip-scale air core transformer. Power transferred to the secondary side is rectified and regulated to 5 V . The secondary ( $\mathrm{V}_{\text {ISO }}$ ) side controller regulates the output by creating a PWM control signal that is sent to the primary $\left(\mathrm{V}_{\mathrm{CC}}\right)$ side by a dedicated $i$ Coupler data channel. The PWM modulates the oscillator circuit to control the power being sent to the secondary side. Feedback allows for significantly higher power and efficiency.

The ADM3053 integrated dc-to-dc converter is designed as a self contained solution and must not drive an external load. To meet additional isolated power needs, isoPower isolated dc-todc converters are available in a variety of power or power plus standard data channel options.

## TRUTH TABLES

The truth tables in this section use the abbreviations found in Table 9.

Table 9. Truth Table Abbreviations

| Letter | Description |
| :--- | :--- |
| H | High level |
| L | Low level |
| X | Don't care |
| Z | High impedance (off) |
| I | Indeterminate |
| NC | Not connected |

Table 10. Transmitting

| Supply Status |  | Input | Outputs |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{V}_{\mathbf{o}}$ | $\mathbf{V}_{\mathrm{cc}}$ | TxD | Bus State | CANH | CANL |
| On | On | L | Dominant | H | L |
| On | On | H | Recessive | Z | Z |
| On | On | Floating | Recessive | Z | Z |
| Off | On | X | Recessive | Z | Z |
| On | Off | L | Indeterminate | I | I |

Table 11. Receiving

| Supply Status |  | Inputs |  | Output |
| :--- | :--- | :--- | :--- | :--- |
| $\mathbf{V}_{\mathbf{I O}}$ | $\mathbf{V}_{\mathbf{C C}}$ | $\mathbf{V}_{\mathbf{I D}}=$ CANH - CANL | Bus State | RxD |
| On | On | $\geq 0.9 \mathrm{~V}$ | Dominant | L |
| On | On | $\leq 0.5 \mathrm{~V}$ | Recessive | H |
| On | On | $0.5 \mathrm{~V}<\mathrm{V}_{\mathrm{ID}}<0.9 \mathrm{~V}$ | $\mathrm{X}^{1}$ | I |
| On | On | Inputs open | Recessive | H |
| Off | On | $\mathrm{X}^{1}$ | $\mathrm{X}^{1}$ | I |
| On | Off | $\mathrm{X}^{1}$ | $\mathrm{X}^{1}$ | H |

${ }^{1} \mathrm{X}$ means don't care.

## THERMAL SHUTDOWN

The ADM3053 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. The thermal sensing circuitry detects the increase in die temperature under this condition and disables the driver outputs. This circuitry is designed to disable the driver outputs when a die temperature of $150^{\circ} \mathrm{C}$ is reached. As the device cools, the drivers are reenabled at a temperature of $140^{\circ} \mathrm{C}$.

## DC CORRECTNESS AND MAGNETIC FIELD IMMUNITY

The digital signals transmit across the isolation barrier using $i$ Coupler technology. This technique uses chip-scale transformer windings to couple the digital signals magnetically from one side of the barrier to the other.

Digital inputs are encoded into waveforms that are capable of exciting the primary transformer winding. At the secondary winding, the induced waveforms are decoded into the binary value that was originally transmitted.
Positive and negative logic transitions at the isolator input cause narrow ( $\sim 1 \mathrm{~ns}$ ) pulses to be sent to the decoder via the transformer. The decoder is bistable and is, therefore, either set or reset by the pulses, indicating input logic transitions. In the absence of logic transitions at the input for more than $1 \mu \mathrm{~s}$, periodic sets of refresh pulses indicative of the correct input state are sent to ensure dc correctness at the output. If the decoder receives no internal pulses of more than approximately $5 \mu \mathrm{~s}$, the input side is assumed to be unpowered or nonfunctional, in which case, the isolator output is forced to a default state by the watchdog timer circuit.
This situation must occur in the ADM3053 devices only during power-up and power-down operations. The limitation on the ADM3053 magnetic field immunity is set by the condition in which induced voltage in the transformer receiving coil is sufficiently large to either falsely set or reset the decoder. The following analysis defines the conditions under which this can occur.
The 3.3 V operating condition of the ADM3053 is examined because it represents the most susceptible mode of operation. The pulses at the transformer output have an amplitude of $>1.0 \mathrm{~V}$. The decoder has a sensing threshold of about 0.5 V , thus establishing a 0.5 V margin in which induced voltages can be tolerated. The voltage induced across the receiving coil is given by

$$
V=(-d \beta / d t) \sum \pi r_{n} 2 ; n=1,2, \ldots, N
$$

where:
$\beta$ is magnetic flux density (gauss).
$N$ is the number of turns in the receiving coil. $r_{n}$ is the radius of the $\mathrm{n}^{\text {th }}$ turn in the receiving coil ( cm ).
Given the geometry of the receiving coil in the ADM3053 and an imposed requirement that the induced voltage be, at most, $50 \%$ of the 0.5 V margin at the decoder, a maximum allowable magnetic field is calculated as shown in Figure 26.


Figure 26. Maximum Allowable External Magnetic Flux Density
For example, at a magnetic field frequency of 1 MHz , the maximum allowable magnetic field of 0.2 kgauss induces a voltage of 0.25 V at the receiving coil. This is about $50 \%$ of the sensing threshold and does not cause a faulty output transition. Similarly, if such an event occurs during a transmitted pulse (and is of the worst-case polarity), it reduces the received pulse from $>1.0 \mathrm{~V}$ to 0.75 V , which is still well above the 0.5 V sensing threshold of the decoder.

The preceding magnetic flux density values correspond to specific current magnitudes at given distances from the ADM3053 transformers. Figure 27 expresses these allowable current magnitudes as a function of frequency for selected distances. As shown in Figure 27, the ADM3053 is extremely immune and can be affected only by extremely large currents operated at high frequency very close to the component. For the 1 MHz example, a 0.5 kA current must be placed 5 mm away from the ADM3053 to affect component operation.


Figure 27. Maximum Allowable Current for Various Current-to-ADM3053 Spacings
Note that in combinations of strong magnetic field and high frequency, any loops formed by the printed circuit board (PCB) traces can induce error voltages sufficiently large to trigger the thresholds of succeeding circuitry. Proceed with caution in the layout of such traces to prevent this from occurring.

## APPLICATIONS INFORMATION

## PCB LAYOUT

The ADM3053 signal and power isolated CAN transceiver contains an isoPower integrated dc-to-dc converter, requiring no external interface circuitry for the logic interfaces. Power supply bypassing is required at the input and output supply pins (see Figure 28). The power supply section of the ADM3053 uses a 180 MHz oscillator frequency to pass power efficiently through its chipscale transformers. In addition, the normal operation of the data section of the $i$ Coupler introduces switching transients on the power supply pins.

Bypass capacitors are required for several operating frequencies. Noise suppression requires a low inductance, high frequency capacitor, whereas ripple suppression and proper regulation require a large value capacitor. These capacitors are connected between GND1 and Pin $6\left(\mathrm{~V}_{\mathrm{IO}}\right)$ for $\mathrm{V}_{\mathrm{I}}$. It is recommended that a combination of 100 nF and 10 nF be placed as shown in Figure 28 (C6 and C4). It is recommended that a combination of two capacitors, with values of 100 nF and $10 \mu \mathrm{~F}$, are placed between Pin $8\left(\mathrm{~V}_{\mathrm{CC}}\right)$ and Pin 9 (GND1) for $\mathrm{V}_{\mathrm{CC}}$ as shown in Figure 28 (C2 and C 1 ). The $\mathrm{V}_{\text {Isoin }}$ and $\mathrm{V}_{\text {Isoout }}$ capacitors are connected between Pin 11 (GND2) and Pin 12 ( $\mathrm{V}_{\text {Isoout }}$ ) with recommended values of 100 nF and $10 \mu \mathrm{~F}$ as shown in Figure 28 (C5 and C8). Two capacitors are recommended to be fitted Pin 19 ( $\mathrm{V}_{\text {ISoin }}$ ) and Pin 20 (GND2) with values of 100 nF and 10 nF as shown in Figure 28 (C9 and C7). The best practice recommended is to use a very low inductance ceramic capacitor, or its equivalent, for the smaller value. The total lead length between both ends of the capacitor and the input power supply pin must not exceed 10 mm .
The ADM3053 features an internal split paddle, lead frame on the bus side. For the best noise suppression, filter both the GND2 pins (Pin 11 and Pin13) and $V_{\text {Isoout }}$ signals of the integrated dc-to-dc converter for high frequency currents. Use surface-mount ferrite beads in series with the signals before routing back to the device. See Figure 28 for the recommended PCB layout.

The impedance of the ferrite bead is chosen to be about $2 \mathrm{k} \Omega$ between the 100 MHz and 1 GHz frequency range, to reduce the emissions at the 180 MHz primary switching frequency and the 360 MHz secondary side rectifying frequency and harmonics.


Figure 28. Recommended PCB Layout
In applications involving high common-mode transients, ensure that board coupling across the isolation barrier is minimized. Furthermore, design the board layout such that any coupling that does occur equally affects all pins on a given component side.

Failure to ensure this can cause voltage differentials between pins exceeding the absolute maximum ratings for the device, thereby leading to latch-up and/or permanent damage.
The ADM3053 dissipates approximately 650 mW of power when fully loaded. Because it is not possible to apply a heat sink to an isolation device, the devices primarily depend on heat dissipation into the PCB through the GND pins. If the devices are used at high ambient temperatures, provide a thermal path from the GND pins to the PCB ground plane. The board layout in Figure 28 shows enlarged pads for Pin 1, Pin 3, Pin 9, Pin 10, Pin 11, Pin 14, Pin 16, and Pin 20. Implement multiple vias from the pad to the ground plane to reduce the temperature inside the chip significantly. The dimensions of the expanded pads are at the discretion of the designer and dependent on the available board space.

## EMI CONSIDERATIONS

The dc-to-dc converter section of the ADM3053 must, of necessity, operate at very high frequency to allow efficient power transfer through the small transformers. This creates high frequency currents that can propagate in circuit board ground and power planes, causing edge and dipole radiation. Grounded enclosures are recommended for applications that use these devices. If grounded enclosures are not possible, good RF design practices must be followed in the layout of the PCB. See the AN-0971 Application Note, Recommendations for Control of Radiated Emissions with isoPower Devices, for more information.

## Rs PIN

For high speed mode, the Rs pin is connected directly to GND2 (Pin 16 or Pin 20). The transition time of the CAN bus signals are short as possible, allowing higher speed signaling. A shielded cable is recommended to avoid EMI problems in high speed mode.

Slope control mode allows the use of unshielded twisted pair wires or parallel pair wires as bus lines. The signal rise and fall transition times are slowed to reduce EMI and ringing. The rise and fall slopes are adjusted with the resistor ( $\mathrm{R}_{\text {slope }}$ ) connected from Rs to GND2. See Figure 6 for details.
The Rs pin cannot be left floating.

## INSULATION LIFETIME

All insulation structures eventually break down when subjected to voltage stress over a sufficiently long period. The rate of insulation degradation is dependent on the characteristics of the voltage waveform applied across the insulation. Analog Devices conducts an extensive set of evaluations to determine the lifetime of the insulation structure within the ADM3053.

Accelerated life testing is performed using voltage levels higher than the rated continuous working voltage. Acceleration factors for several operating conditions are determined, allowing calculation of the time to failure at the working voltage of interest. The values shown in Table 5 summarize the peak voltages for 50 years of service life in several operating conditions. In many cases, the working voltage approved by agency testing is higher than the 50 year service life voltage. Operation at working voltages higher than the service life voltage listed leads to premature insulation failure.

The insulation lifetime of the ADM3053 depends on the voltage waveform type imposed across the isolation barrier. The $i$ Coupler insulation structure degrades at different rates, depending on whether the waveform is bipolar ac, unipolar ac, or dc. Figure 29, Figure 30, and Figure 31 illustrate these different isolation voltage waveforms.

Bipolar ac voltage is the most stringent environment. A 50 year operating lifetime under the bipolar ac condition determines the Analog Devices recommended maximum working voltage.
In the case of unipolar ac or dc voltage, the stress on the insulation is significantly lower. This allows operation at higher working voltages while still achieving a 50 year service life. The working voltages listed in Table 5 can be applied while maintaining the 50 year minimum lifetime, provided the voltage conforms to either the unipolar ac or dc voltage cases. Any cross insulation voltage waveform that does not conform to Figure 30 or Figure 31 must be treated as a bipolar ac waveform, and its peak voltage must be limited to the 50-year lifetime voltage value listed in Table 5.


Figure 31. Unipolar AC Waveform

## TYPICAL APPLICATIONS

Figure 32 is an example circuit diagram using the ADM3053.


Figure 32. Example Circuit Diagram Using the ADM3053

## ADM3053

## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-013-AC
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 33. 20-Lead Standard Small Outline Package [SOIC_W] Wide Body
(RW-20)
Dimensions shown in millimeters and (inches)

## ORDERING GUIDE

| Model $^{1}$ | Temperature Range | Package Description | Package <br> Option |
| :--- | :--- | :--- | :--- |
| ADM3053BRWZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 20-Lead Standard Small Outline Package [SOIC_W] | RW-20 |
| ADM3053BRWZ-REEL7 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 20-Lead Standard Small Outline Package [SOIC_W] | RW-20 |
| EVAL-ADM3053EBZ |  | Evaluation Board |  |
| EZLINX-IIIDE-EBZ |  | iCoupler Isolated Interface Development Environment Evaluation Board |  |

${ }^{1} Z=$ RoHS Compliant Part.

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