

# Pulse Width Modulation Amplifiers

## FEATURES

- LOW COST
- HIGH VOLTAGE - 100 VOLTS
- HIGH OUTPUT CURRENT - 20 AMPS
- 2kW OUTPUT CAPABILITY
- VARIABLE SWITCHING FREQUENCY

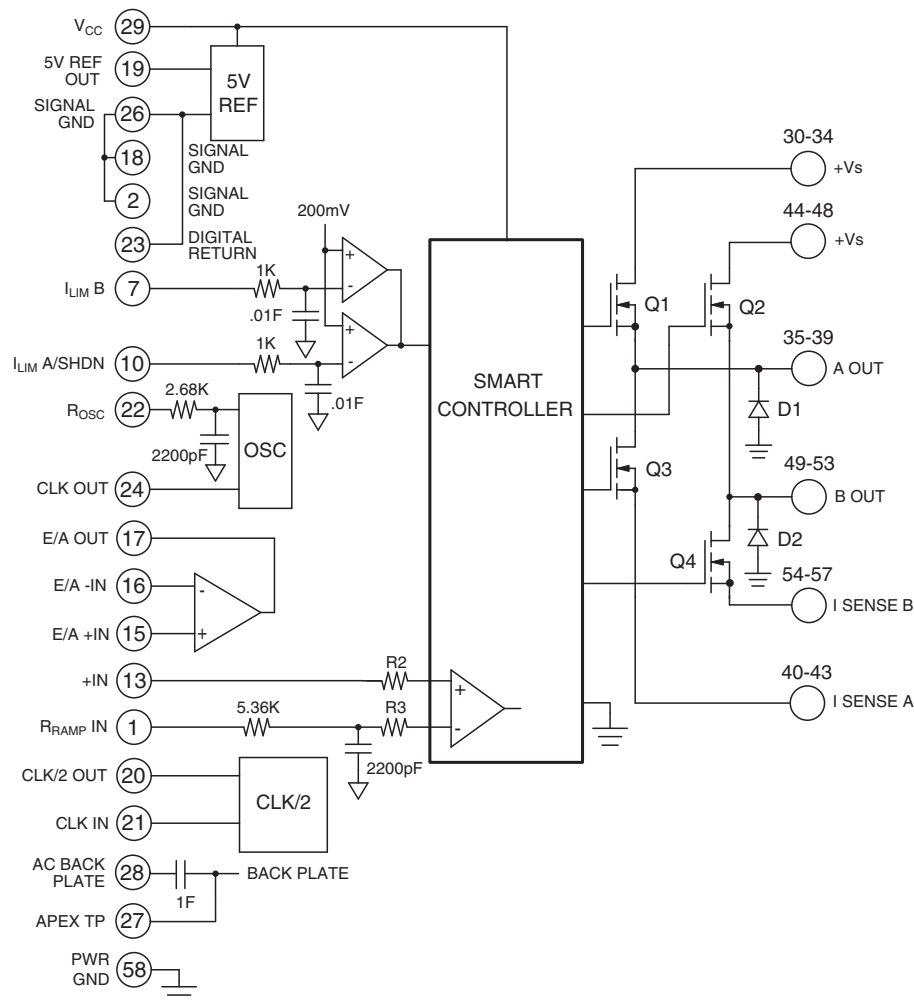
## APPLICATIONS

- BRUSH MOTOR CONTROL
- MRI
- MAGNETIC BEARINGS
- CLASS D SWITCHMODE AMPLIFIER

## DESCRIPTION

The MSA240 is a surface mount constructed PWM amplifier that provides a cost effective solution in many industrial applications. The MSA240 offers outstanding performance that rivals many much more expensive hybrid components. The MSA240 is a complete PWM amplifier including an oscillator, comparator, error amplifier, current limit comparators, 5V reference, a smart controller and a full bridge output circuit. The switching frequency is user programmable up to 50 kHz. The MSA240 is built on a thermally conductive but electrically insulating substrate that can be mounted to a heatsink.

## EQUIVALENT CIRCUIT DIAGRAM



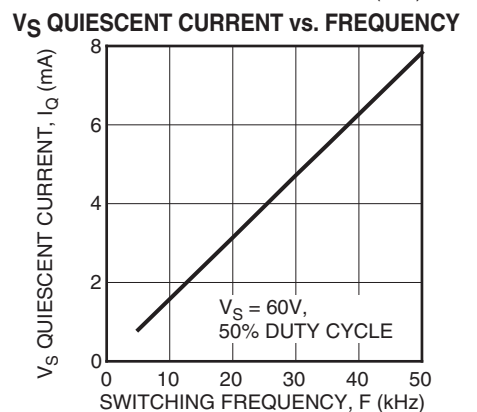
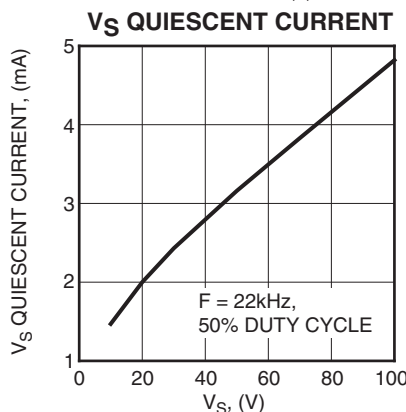
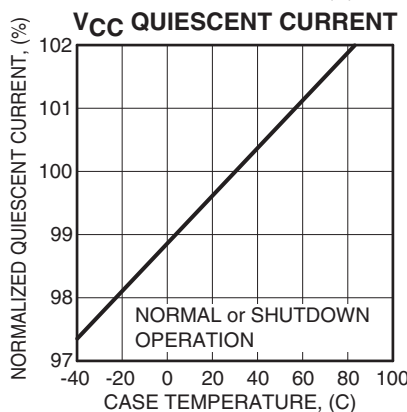
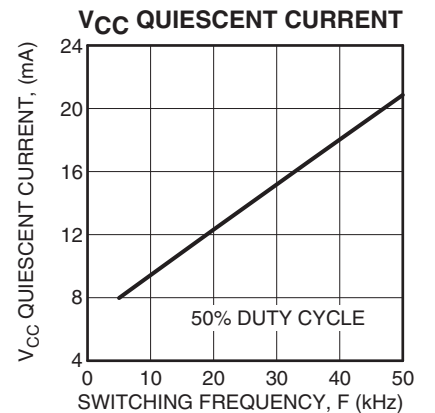
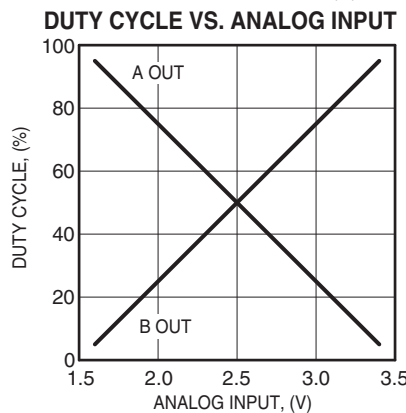
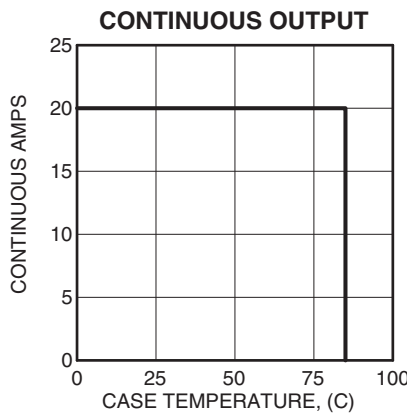
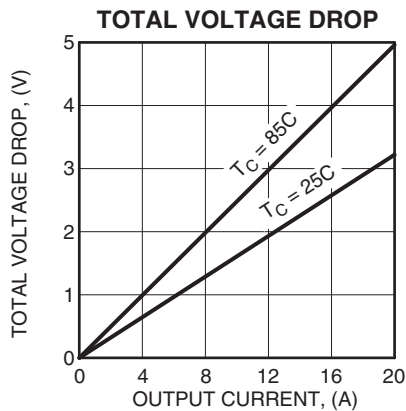
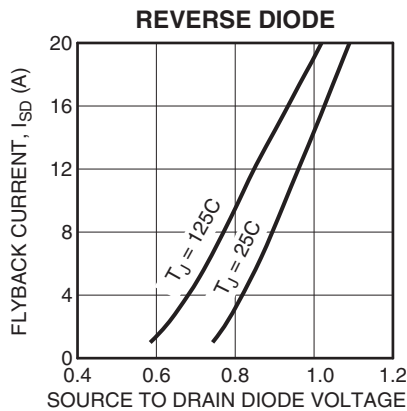
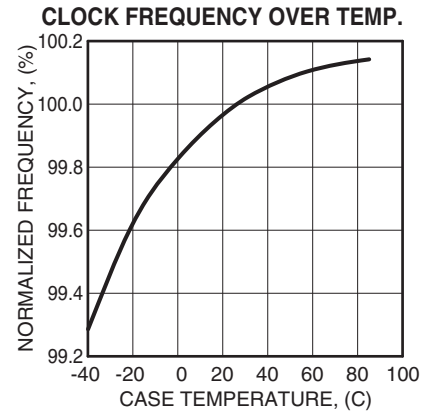
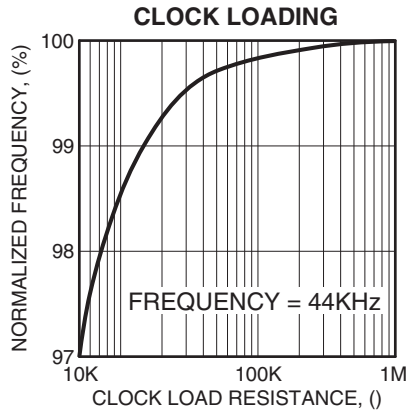
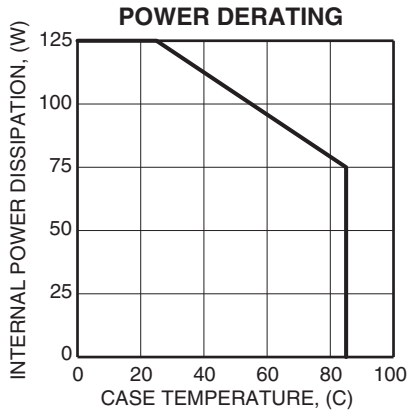
## ABSOLUTE MAXIMUM RATINGS

SUPPLY VOLTAGE, $V_S$	100V
SUPPLY VOLTAGE, $V_{CC}$	16V
OUTPUT CURRENT, peak	30A, within SOA
POWER DISSIPATION, internal, DC	250W <sup>3</sup>
SIGNAL INPUT VOLTAGES	5.4V
TEMPERATURE, pin solder, 10s	225°C.
TEMPERATURE, junction <sup>2</sup>	175°C.
TEMPERATURE RANGE, storage	-40° to 105°C.
OPERATING TEMPERATURE, case	-40° to 85°C.

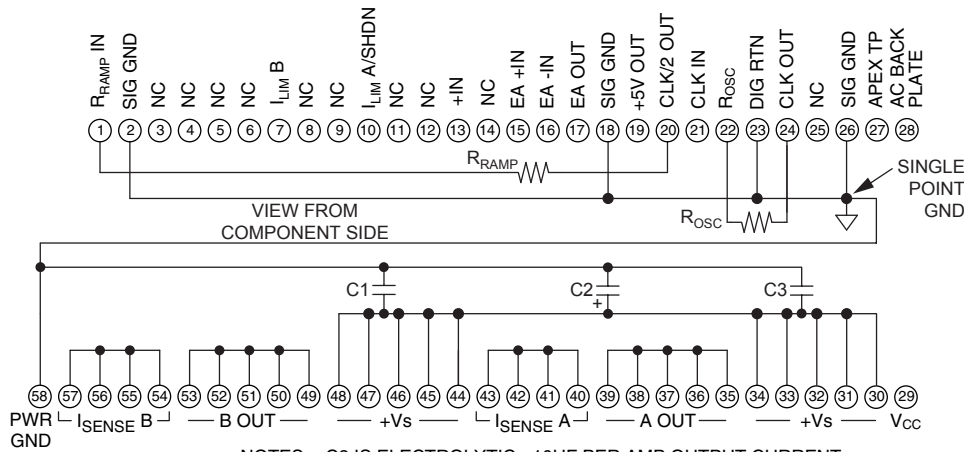
## SPECIFICATIONS

PARAMETER	TEST CONDITIONS <sup>1</sup>	MIN	TYP	MAX	UNITS
ERROR AMPLIFIER OFFSET VOLTAGE	Full temperature range			9	mV
BIAS CURRENT	Full temperature range			500	nA
OFFSET CURRENT	Full temperature range			150	nA
COMMON MODE VOLTAGE RANGE	Full temperature range	0		4	V
SLEW RATE	Full temperature range		1		V/ $\mu$ S
OPEN LOOP GAIN	$R_L = 2K\Omega$		96		dB
UNITY GAIN BANDWIDTH			1		MHz
CLOCK					
LOW LEVEL OUTPUT VOLTAGE	Full temperature range			.2	V
HIGH LEVEL OUTPUT VOLTAGE	Full temperature range	4.8			V
RISE TIME			7		nS
FALL TIME			7		nS
BIAS CURRENT, pin 22	Full temperature range			0.6	$\mu$ A
5V REFERENCE OUTPUT VOLTAGE		4.85		5.15	V
LOAD CURRENT				2	mA
<b>OUTPUT</b>					
TOTAL $R_{ON}$ , both MOSFETs <sup>4</sup>	$I_O = 20A, T_J = 85^\circ C$			155	m $\Omega$
CURRENT, continuous				20	A
CURRENT, peak	100mS			30	A
OUTPUT MOSFET BODY DIODE CONTINUOUS CURRENT				20	A
FORWARD VOLTAGE	$I = 16A$		1.3		V
REVERSE RECOVERY	$I_F = 16A$		250		nS
POWER SUPPLY					
VOLTAGE, $V_S$		3	60	100	V
VOLTAGE, $V_{CC}$		14	15	16	V
CURRENT, $V_S$ , quiescent	22kHz switching		4	28	mA
CURRENT, $V_{CC}$ , quiescent	22kHz switching			18	mA
CURRENT, $V_{CC}$ , shutdown				10	mA
<b>THERMAL</b>					
RESISTANCE, DC, junction to case	Full temperature range			1.2	$^\circ C/W$
RESISTANCE, junction to air	Full temperature range			14	$^\circ C/W$
TEMPERATURE RANGE, case		-40		85	$^\circ C/W$

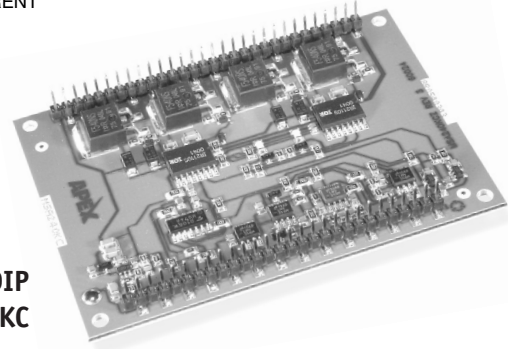
- NOTES: 1. Unless otherwise noted:  $T_C = 25^\circ C, V_{CC} = 15V, V_S = 60V$   
 2. Long term operation at the maximum junction temperature will result in reduced product life. Derate internal power dissipation to achieve high MTBF.  
 3. Each of the two output transistors on at any one time can dissipate 125W.  
 4. Maximum specification guaranteed but not tested.



## EXTERNAL CONNECTIONS



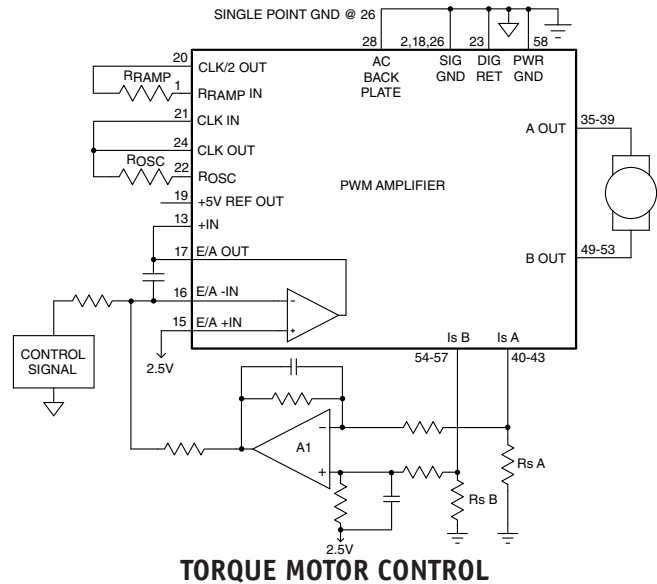
NOTES: C2 IS ELECTROLYTIC  $\geq 10\mu\text{F}$  PER AMP OUTPUT CURRENT  
 C1,3 HIGH QUALITY CERAMIC  $\geq 1.0\mu\text{F}$   
 ALL +Vs MUST BE TIED TOGETHER  
 ALL SIG GND PINS MUST BE TIED TOGETHER  
 SINGLE POINT GROUND @ PIN 26



**58-PIN DIP  
PACKAGE STYLE KC**

## TYPICAL APPLICATION

With the addition of a few external components the MSA240 becomes a motor torque controller. In the MSA240 the source terminal of each low side MOSFET driver is brought out for current sensing via  $R_{SA}$  and  $R_{SB}$ . A1 is a differential amplifier that amplifies the difference in currents of the two half bridges. This signal is fed into the internal error amplifier that mixes the current signal and the control signal. The result is an input signal to the MSA240 that controls the torque on the motor.



**TORQUE MOTOR CONTROL**

## GENERAL

Please read Application Note 30 “PWM Basics.” Refer also to Application Note 1 “General Operating Considerations” for helpful information regarding power supplies, heat sinking, mounting, SOA interpretation, and specification interpretation. Visit [www.apexanalog.com](http://www.apexanalog.com) for design tools that help automate tasks such as calculations for stability, internal power dissipation, current limit, heat sink selection, Apex Microtechnology's complete Application Notes library, Technical Seminar Workbook and Evaluation Kits.

## OSCILLATOR

The MSA240 includes a user frequency programmable oscillator. The oscillator determines the switching frequency of the amplifier. The switching frequency of the amplifier is 1/2 the oscillator frequency. Two resistor values must be chosen to properly program the switching frequency of the amplifier. One resistor,  $R_{OSC}$ , sets the oscillator frequency. The other resistor,  $R_{RAMP}$ , sets the internal ramp amplitude. In all cases the ramp voltage will oscillate between 1.5V and 3.5V. See Figure 1. If an external oscillator is applied use the equations to calculate  $R_{RAMP}$ .

To program the oscillator,  $R_{OSC}$  is given by:

$$R_{OSC} = (1.32 \times 10^8 / F) - 2680$$

where F is the desired **switching frequency** and:

$$R_{RAMP} = 2 \times R_{OSC}$$

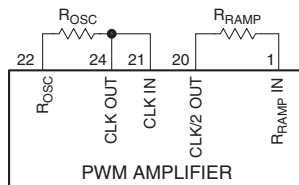
Use 1% resistors with 100ppm drift (RN55C type resistors, for example). Maximum **switching frequency** is 50kHz.

Example:

If the desired switching frequency is 22kHz then  $R_{OSC} = 3.32K$  and  $R_{RAMP} = 6.64K$ . Choose the closest standard 1% values:

$$R_{OSC} = 3.32K \text{ and } R_{RAMP} = 6.65K$$

FIGURE 1. EXTERNAL OSCILLATOR CONNECTIONS



## SHUTDOWN

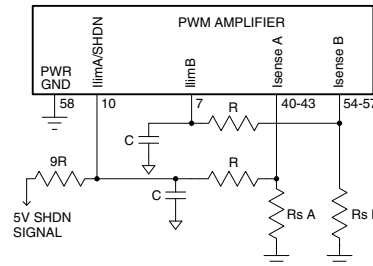
The MSA240 output stage can be turned off with a shutdown command voltage applied to Pin 10 as shown in Figure 2. The shutdown signal is OR'ed with the current limit signal and simply overrides it. As long as the shutdown signal remains high the output will be off.

## CURRENT SENSING

The low side drive transistors of the MSA240 are brought out for sensing the current in each half bridge. A resistor from each sense line to PWR GND (pin 58) develops the current sense voltage. Choose R and C such that the time constant is equal to 10 periods of the selected switching frequency. The internal current limit comparators trip at 200mV. Therefore, current limit occurs at  $I = 0.2/R_{SENSE}$  for each half bridge. See

Figure 2. Accurate milliohm power resistors are required and there are several sources for these listed in the Accessories Vendors section of the Databook.

FIGURE 2. CURRENT LIMIT WITH OPTIONAL SHUTDOWN



## POWER SUPPLY BYPASSING

Bypass capacitors to power supply terminals  $+V_S$  must be connected physically close to the pins to prevent local parasitic oscillation and overshoot. All  $+V_S$  pins must be connected together. Place an electrolytic capacitor of at least 10 $\mu$ F per output amp required midpoint between these sets of pins. In addition place a ceramic capacitor 1 $\mu$ F or greater directly at each set of pins for high frequency bypassing.  $V_{CC}$  is bypassed internally.

## GROUNDING AND PCB LAYOUT

Switching amplifiers combine millivolt level analog signals and large amplitude switching voltages and currents with fast rise times. As such grounding is crucial. Use a single ground at SIG GND (pin 26). Connect signal ground pins 2 and 18 directly to the single point ground on pin 26. Connect the digital return pin 23 directly to pin 26 as well. Connect PWR GND pin 58 also to pin 26. Connect AC BACKPLATE pin 28 also to the single point ground at pin 26. Connect the ground terminal of the  $V_{CC}$  supply directly to pin 26 as well. Make sure no current from the load return to PWR GND flows in the analog signal ground. Make sure that the power portion of the PCB layout does not pass over low-level analog signal traces on the opposite side of the PCB. Capacitive coupling through the PCB may inject switching voltages into the analog signal path. Further, make sure that the power side of the PCB layout does not come close to the analog signal side. Fast rising output signal can couple through the trace-to-trace capacitance on the same side of the PCB.

## DETERMINING THE OUTPUT STATE

The input signal is applied to +IN (Pin 13) and varies from 1.5 to 3.5 volts, zero to full scale. As +IN varies from 1.5 to 2.5 volts the A output "high" duty cycle (relative to ground) is greater than the B output "high" duty cycle. The reverse occurs as the input signal varies from 2.5 to 3.5 volts. When +IN = 2.5 volts the duty cycles of both A and B outputs are 50%. Consequently, when the input voltage is 1.5V the A output is close to 100% duty cycle and the B output is close to 0% duty cycle. The reverse occurs with an input voltage of 3.5V. The output duty cycle extremes vary somewhat with switching frequency and are internally limited to approximately 5% to 95% at 10kHz and 7% to 93% at 50kHz.

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