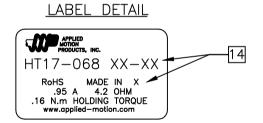
SPECIFICATIONS:					
STEPS PER REVOLUTION: 200	ROTOR INERTIA: 35.0 G-CM <sup>2</sup> (0.19 OZ-IN <sup>2</sup> ) REF				
STEP ANGLE: 1.8°	HOLDING TORQUE: 1.6KG-CM (22.2 OZ-IN)MIN 1				
STEP TO STEP ACCURACY: ±5 % 1,2	DETENT TORQUE: 36 G-CM (0.5 OZ-IN) MIN				
POSITIONAL ACCURACY: ±5 % 1,3					
HYSTERESIS: - %	INSULATION CLASS: B				
WINDING RESISTANCE: 4.2 OHM ±10% AT 25° 7	BEARINGS: ABEC 3 , DOUBLE SHIELDED				
WINDING INDUCTANCE: 2.8 mH ± 20% 8	WIEGHT: 200 G (7.0 OZ) APPROXIMATE				
PHASE VOLTAGE: 4.0 VDC	TEMP. RISE: 80°C MAX.				
PHASE CURRENT: .95 AMP (RATED)	OPERATING TEMP. RANGE: -10 TO 40 °C				
	STORAGE TEMP. RANGE: -40 TO 70 °C				
SHAFT RUNOUT: 0.013 T.I.R.	RELATIVE HUMIDITY RANGE: 5 TO 95 %				
RADIAL PLAY: 0.025 MAX WITH .5KG RADIAL LOAD.					
END PLAY: 0.075 MAX WITH 1.0KG AXIAL LOAD.	END PLAY: 0.075 MAX WITH 1.0KG AXIAL LOAD.				

NOTES, UNLESS OTHERWISE SPECIFIED:

- 1 MEASURMENTS MADE AT RATED CURRENT IN EACH PHASE.
- 2 BETWEEN ANY TWO ADJACENT STEP POSITIONS.
- 3 MAXIMUM ERROR IN 360°.
- 4. HIPOT 500 VAC FOR ONE MINUTE.
- 5. LEADS: 8 ,AWG 26,7 STRAND MIN., UL AND CSA APPROVED, UL 3265.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED ACROSS ANY WINDING.
- 8 AS MEASURED ACROSS ANY WINDING USING AN A.C. INDUCTANCE BRIDGE (1 KHz).
- 9 AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED VOLTAGE APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- 10. HIGH TORQUE MOTOR DESIGN.
- 11. ROTOR & STATOR LAMINATION MATERIAL: 0.5mm thk, SEE AMP STD SPEC #1500-062.
- 12 IF DOUBLE SHAFT IS REQUIRED, ADD "D" TO END OF PART NUMBER.
- 13. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU ROHS DIRECTIVE.
- 14 MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.

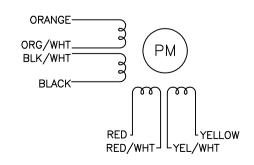
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	REVISIONS								
ECO NO.	REV	DESCRIPTION	DATE	APPROVED					
3847	Α	INITIAL RELEASE	2-16-94	X. Kordik					
3930	В	ADD HT17-068P NOTE	5-25-95	X. Xordik					
5000	С	ADD "17HT33D" NOTATION							
5235	D	ADD EU COMPLIANCE NOTES	8/25/05	R. Hazelwood					
5251	Е	Chg HT17-068P to 17HT33P	22/11/05	R. Hazelwood					
6018	F	ADD MECH DATA	10/29/09	J. Kordik					
6042	G	REVISE ENCODER HOLES	12/23/09	J Kordik					
6082	Η	ADD ENCODER HOLES	3/3/10	J Kordik					
7446	J	REVISE NOTE 13	6/6/16	J. Kordik					
	·								



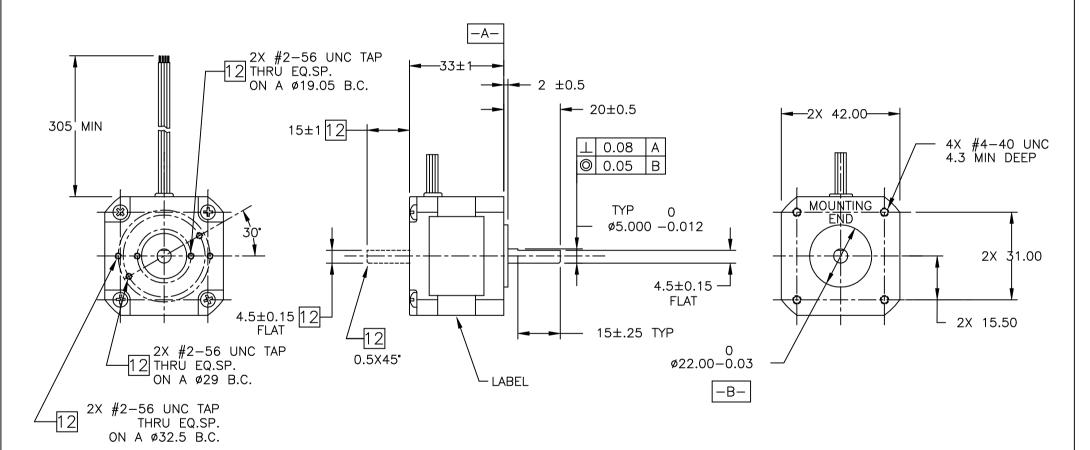
## SWITCHING SEQUENCE FOR CW ROTATION FACING MOUNTING END

STEP	ORANGE	BLACK	RED	YELLOW
0	+	_	+	_
1	_	+	+	_
2	1	+	-	+
3	+	_	_	+
4	+	-	+	_



CONTRACT NO. CAT					APPLIED MOTION PRODUCTS,	INC.	
APPROVALS	DATE						_
DRAWN R. BARRICK	1/10/94	STEP MOTOR OUTLINE					
CHECKED B. Corser	2/16/94		001101	TED DATA	DWG NO.		REV
	2/16/94			ITER DATA DRAWING	DWG NO	HT17-068	J. J
APPROVED		SCALE:	FULL			SHEET 1 OF 2	

## MOTOR DRAWING



TOLERANCES	THIRD ANGLE PI					
DECIMALS: MM (INCH) X.XXX= ± (.005)			APPLIED MOTION PRODUCTS, INC.			
$X.XX = \pm 0.13 (.010)$	$\Psi$	7	CIT.	IDD MAMA		
$X.X = \pm 0.25 (.020)$ ANGLES:	APPROVALS	DATE	」 STEP MOTOR OUTLI			NE
MACH. = $\pm .5^{\circ}$	DRAWN R.JONEZ	10/22/09	D DWG NO.		REV	
CHAM. = $\pm 5^{\circ}$	CHECKED		В	HT1	7–068	J
COMPUTER DATA BASE DRAWING	APPROVED		SCALE:	NONE	SHEET 2 OF 2	•

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