SPECIFICATIONS:			
STEPS PER REVOLUTION: 200	ROTOR INERTIA: 38.0 G-CM 2 (0.200Z-IN2)REF		
STEP ANGLE: 1.8°	DETENT TORQUE: 122.3G-CM (1.69 OZ-IN) MIN		
STEP TO STEP ACCURACY: ±.09 DEGREES 1, 2	INSULATION CLASS: B		
POSITIONAL ACCURACY: ±.09 DEGREES 1,3	BEARINGS: ABEC 3, DOUBLE SHIELDED		
HYSTERESIS: - %	WEIGHT: 210 G (7.3 OZ) APPROXIMATE		
SHAFT RUNOUT: 0.03 T.I.R.	TEMP. RISE: 80 °C MAX.		
RADIAL PLAY: 0.02 MAX W/A .5KG RADIAL LOAD	OPERATING TEMP. RANGE: -20 TO +50 °C		
END PLAY: 0.08 MAX W/A 0.5KG AXIAL LOAD	STORAGE TEMP. RANGE: -30 TO +70 °C		
	RELATIVE HUMIDITY RANGE: 15 TO 85 %		

7		
JCTANCE	RATED	RATE
PHASE	CURRENT	I VOLTA

SPECIFICATION	NUMBER	RESISTANCE	INDUCTANCE	RATED	RATED	HOLDING	
CONNECTION	OF PHASE	PER PHASE OHM ±10%	PER PHASE mH ±20%	CURRENT	VOLTAGE	TORQUE N.m. Min	
BI-POLAR SERIES	PHASE 2	8.4	10.0	0.67	5.6	0.22	╨
BI-POLAR PARALLEL	2	2.1	2.5	1.34	2.8	0.22	1
UNI-POLAR	4	4.2	2.5	0.95	4.0	0.16]

NOTES, UNLESS OTHERWISE SPECIFIED:

- 1 MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.
- BETWEEN ANY TWO ADJACENT STEP POSITIONS.
- MAXIMUM ERROR IN 360°.
- 4. HIPOT 500 VAC, 60 Hz FOR ONE MINUTE.
- 5. LEADS: 8, 26 AWG, 7 STRAND MIN., UL AND CSA APPROVED, UL 1430 OR UL 3265.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED USING AN A.C. INDUCTANCE BRIDGE, AT 1KHz.
- AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED VOLTAGE APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- 9 SHAFT OPTION: IF DOUBLE SHAFT REQUIRED ADD "D" TO END OF PART NUMBER, DOUBLE SHAFT REQUIRES ADDED HOLES FOR ENCODER OPTION.
- 10. THIS MOTOR IS MANUFACTURED IN COMPLIANCE WITH THE CURRENT EU ROHS DIRECTIVE.
- 1 MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.

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REVISIONS				
ECO NO.	REV	DESCRIPTION	DATE	APPROVED
5976	Α	INITIAL RELEASE	8/28/09	J.KORDIK
5995	В	PERPENDICULARITY CORRECTED	9/28/09	J.KORDIK
6090	С	STANDARDIZE ENCODER HOLES	3/29/10	J.KORDIK
7247	D	ADD UL TO LABEL	1/26/16	J.KORDIK
7446	Е	REVISE NOTE 10	6/6/16	J.KORDIK
8209	F	CLEAN-UP	4/29/19	J.KORDIK
8277	G	REMOVE ENCODER HOLES	7/3/19	J.KORDIK

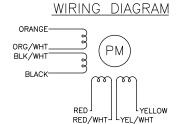
DRIVE SEQUENCE MODEL BI-POLAR FULL STEP

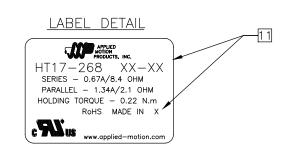
CCW

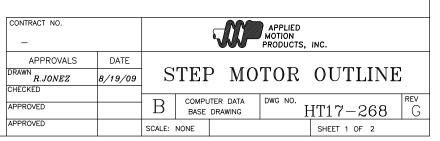


CW(CLOCKWISE) AND CCW(COUNTER-CLOCKWISE) ROTATION WHEN SEEN FROM THE FLANGE SIDE OF THE MOTOR

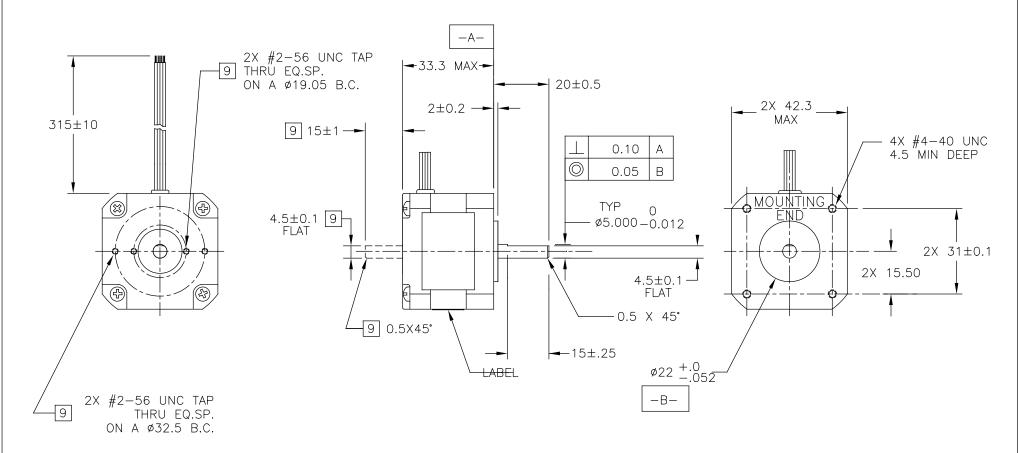
CW











	ROJECTION	THIRD ANGLE P	TOLERANCES	
			DECIMALS: MM (INCH) X.XXX= ±0.013(.005)	
		\Box	$X.XX = \pm 0.25 (.01)'$	
STEP	DATE	APPROVALS	$X.X = \pm 2.5$ (0.1) ANGLES:	
	0 (40 (00	DRAWN	MACH. = ±.5°	
B	8/19/09	R.JONEZ CHECKED	CHAM. = $\pm 5^{\circ}$	
		10000 (50	COMPUTER DATA	
SCALE: NONE		APPROVED	BASE DRAWING	



STEP MOTOR OUTLINE

REV G

В	DWG N	17-268
CALE:	NONE	SHEET 2 OF 2

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