SPECIFICATIONS:					
STEPS PER REVOLUTION: 200	ROTOR INERTIA: 57.0 G-CM <sup>2</sup> ( .31 OZ-IN <sup>2</sup> ) REF				
STEP ANGLE: 1.8°	DETENT TORQUE: 152.9 G-CM (2.12 OZ-IN) MIN				
STEP TO STEP ACCURACY: ±5 % 1,2	INSULATION CLASS: B				
POSITIONAL ACCURACY: ±5 % 1,3	BEARINGS: ABEC 3, DOUBLE SHIELDED				
HYSTERESIS: - %	WEIGHT: 280 G (9.8 OZ) APPROXIMATE				
SHAFT RUNOUT: 0.03 T.I.R.	TEMP. RISE: 80 °C MAX.				
RADIAL PLAY: 0.02 MAX W/A .5KG RADIAL LOAD	OPERATING TEMP. RANGE: -20 TO +50 °C				
END PLAY: 0.08 MAX W/A .5KG AXIAL LOAD	STORAGE TEMP. RANGE: -30 TO +70 °C				
	RELATIVE HUMIDITY RANGE: 15 TO 85 %				

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SPECIFICATION	NUMBER	RESISTANCE	INDUCTANCE	RATED	RATED	HOLDING	
	OF	PER PHASE	PER PHASE	CURRENT	VOLTAGE	TORQUE	l
CONNECTION	PHASE	OHM ±10%	mH ±20%	Amp	V	N.m Min	1
BI-POLAR SERIES	2	7.0	12.0	0.85	6.0	0.37	1
BI-POLAR PARALLEL	2	1.7	3.0	1.70	2.9	0.37	
UNI-POLAR	4	3.5	3.0	1.20	4.2	0.29	]

### NOTES, UNLESS OTHERWISE SPECIFIED:

- 1 MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.
- 2 BETWEEN ANY TWO ADJACENT STEP POSITIONS.
- 3 MAXIMUM ERROR IN 360°.
- 4. HIPOT 500 VAC, 60 Hz FOR ONE MINUTE.
- 5. LEADS: 8, 26 AWG, 7 STRAND MIN., UL AND CSA APPROVED, UL 1430 OR UL 3265.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7 AS MEASURED USING AN A.C. INDUCTANCE BRIDGE, AT 1KHz.
- 8 AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED VOLTAGE APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- 9 SHAFT OPTION: IF DOUBLE SHAFT REQUIRED ADD "D" TO END OF PART NUMBER, DOUBLE SHAFT REQUIRES ADDED HOLES FOR ENCODER OPTIONS.
- 10. THIS MOTOR TO BE MANUFACTURED IN COMPLIANCE WITH EU DIRECTIVE "ROHS 2002/95/EC".
- 11 MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.

# HT17-271

REVISIONS								
ECO NO.	REV	DESCRIPTION	DATE	APPROVED				
5976	Α	INITIAL RELEASE	8/28/09	J KORDIK				
6090	В	STANDARDIZE ENCODER HOLES	3/29/10	J KORDIK				

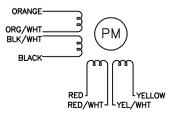
## DRIVE SEQUENCE MODEL BI-POLAR FULL STEP

CCW

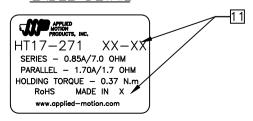
1	STEP	ORANGE & BLK/WHT	BLACK & ORG/WHT	RED & YEL/WHT	YELLOW & RED/WHT
	1	+	_	+	_
	2	-	+	+	_
Ų.	3	1	+	ı	+
cw	4	+	1	1	+

CW(CLOCKWISE) AND CCW(COUNTER-CLOCKWISE) ROTATION
WHEN SEEN FROM THE FLANGE SIDE OF THE MOTOR

### WIRING DIAGRAM

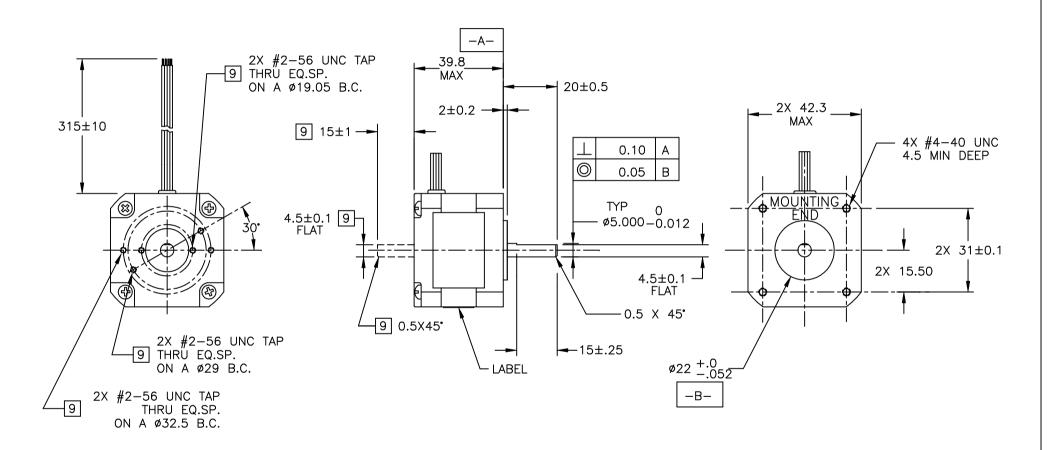


### LABEL DETAIL



CONTRACT NO.				APPLIED MOTION PRODUCTS,	INC.		
APPROVALS	DATE						
DRAWN R.JONEZ	8/19/09	STEP MOTOR OUTLINE					
CHECKED		<u> </u>					
			COMPL	JTER DATA	DWG NO.		REV
APPROVED		$\mid B \mid$ base drawing $\mid HT17-271$					В
APPROVED		SCALE:	NONE		•	SHEET 1 OF 2	

## MOTOR DRAWING



TOLERANCES	THIRD ANGLE P	ROJECTION				DDI IED	
DECIMALS: MM (INCH) X.XXX= ± (.005)	<del>-</del>	-[	APPLIED MOTION PRODUCTS, INC.				
$X.XX = \pm 0.13 (.010)$	$\Box$						
$X.X = \pm 0.25 (.020)$ ANGLES:	APPROVALS	DATE	ST	STEP MOTOR OUTLIN			
MACH. = ±.5°	DRAWN	8/18/09 D					
CHAM. = ±5°	R.JONEZ CHECKED			DWG NO.			REV
	CHECKED		D		HT1	.7-271	B
COMPUTER DATA BASE DRAWING	APPROVED		SCALE:	NONE		SHEET 2 OF 2	•

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