

Description

The **Arduino® Nicla Voice** packs machine-learning capabilities on the edge into a tiny fingerprint.

Implement always-on speech recognition with the Nicla Voice. The board integrates a dedicated Neural Decision Processor **Syntiant® NDP 120** able to run multiple AI algorithms at the same time. Leverage the built-in microphone, nRF52832 microcontroller, Bluetooth® Low Energy module, 6-axis IMU and 3-axis magnetometer to create your own wireless sensor network for machine learning applications with low power consumption capabilities.

Target areas:

noise and vibration detection, low-power speech recognition, contactless operations, gesture recognition

Features

- **ANNA-B112** Bluetooth® Module with integrated microprocessor
 - **nRF52832** System-on-chip
 - 64 MHz ARM® Cortex-M4F microcontroller
 - 64 KB SRAM
 - 512 KB Flash
 - RAM mapped FIFOs using EasyDMA
 - 2x SPI (one is accessible via pin header)
 - 2x I2C (one is accessible via pin header)
 - 12-bit/200 ksps ADC
 - 2.400 - 2.4835 GHz Bluetooth® (5.0 via cordio stack, 4.2 via ArduinoBLE)
 - Internal antenna
 - Internal 32 MHz oscillator
 - 1.8 V Operating Voltage
- **Syntiant® NDP120** Neural Decision Processor™ (Microprocessor)
 - 1x Syntiant® Core 2™ ultra-low power deep neural network inference engine
 - 1x HiFi 3 Audio DSP
 - 1x Arm® Cortex® M0 core up to 48 MHz
 - Dedicated Low I_Q High PSRR Low-Dropout regulator (TPS7A05)
 - 1µA of typical very-low quiescent current consumption (3µA maximum)
 - Dedicated 48KB SRAM

▪ Sensors

- IMU 6-axis (BMI270)
 - 16-bit 3-axis accelerometer $\pm 2/4/8/16$ g range
 - Output data rates (ODR): 0.78Hz-1.6 kHz
 - 16-bit 3-axis gyroscope $\pm 125/250/500/1000/2000$ dps range
 - Output data rates (ODR): 25Hz-6.4 kHz
 - Fast offset error compensation for accelerometer and gyroscope
 - Rapid startup time:
 - 2ms for Gyroscope with fast start mode
 - 2ms for Accelerometer
 - $<1\mu\text{s}$ of HW synchronization
 - Wide voltage supply range
 - Low Power
 - Current consumption: typ. 685 μA (full ODR and aliasing-free operation)
 - Built-in PMU
- Magnetometer 3-axis (BMM150)
 - Low voltage operation
 - Ultra-low power, current consumption 170 μA @ 10 Hz in low power preset
 - Interrupt signal generation for magnetic Low-/High-Threshold detection
 - Magnetic field range typical of $\pm 1300\mu\text{T}$ (x, y-axis), $\pm 2500\mu\text{T}$ (z-axis)
 - Magnetic field resolution of $\sim 0.3\mu\text{T}$
 - Maximum magnetic field rating at any direction $>7\text{T}$
- High-Performance Microphone (IM69D130)
 - Frequency range 20 Hz ~ 20 kHz
 - MEMS (silicon) type
 - Dynamic range of 105dB
 - $<1\%$ total harmonic distortions up to 128 dB SPL
 - Sensitivity ($\pm 1\text{dB}$) and phase ($\pm 2^\circ$ @1kHz) matched
 - Flat frequency response with low-frequency roll-off at 28Hz
 - Power-optimized modes determined by PDM clock frequency
 - PDM output
 - Omnidirectional pickup pattern

- I/O

- Castellated pads (J1, J2, J3)
 - 1x I²C bus, also available on the ESLOV connector
 - 1x Serial Port (UART)
 - 1x SPI
 - 2x ADC
 - GPIOs configurable voltage 1.8 V/3.3 V
 - 1x Battery Input
 - Integrated battery charger and fuel gauge (BQ25120AYFPR) for 3.7V Li-Po battery
 - Power Input and Output (3.3 V, GND and VIN)
- External PDM microphone connector (Via 4-pin 0.5 mm pitch FFC cable compatible with FH33J-4S ZIF connector)

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1 The Board

1.1 Application Examples

The Arduino® Nicla Voice is your cutting edge development and deployment solution taking advantage of Syntiant® NDP120, a neural decision processor that will let you run multiple AI algorithms. Deploy predictive maintenance, gesture and speech recognition, and contactless applications in a miniaturized form factor. A 6-axis motion sensor, a magnetometer, and always-on speech recognition on the edge are at your disposal for unrestricted research and development. On-board Bluetooth® Low Energy connectivity grants interoperability with compatible Nicla, Portenta, and MKR devices for scalability. Ultra-low power consumption enables long lasting device life-time and wide range of deployment possibilities.

- **Automated Intruder Detection System:** Nicla Voice's edge capabilities enable faster identification of critical and time-sensitive events, including glass-breaking or motion sensing. Multiple voices, sound and sensor applications can run simultaneously with low power consumption, all in a tiny battery-powered size, allowing long periods of usage without intervention.
- **Predictive Maintenance:** Nicla Voice can be used to predict the wear of industrial equipment, machinery and automation devices. It can detect vibrations, noises coming from motors or coils and gather the information needed for the Neural Decision Network to align maintenance with the operational characteristics.
- **Add low-power speech recognition:** With the built-in microphone and its tiny form factor, you can easily equip an existing setup with the Nicla Voice to improve the workflow by adding speech recognition like voice commands. Moreover, an always-on speech recognition application can be developed thanks to the ultra low-power Syntiant® NDP120 Neural Decision Processor™.

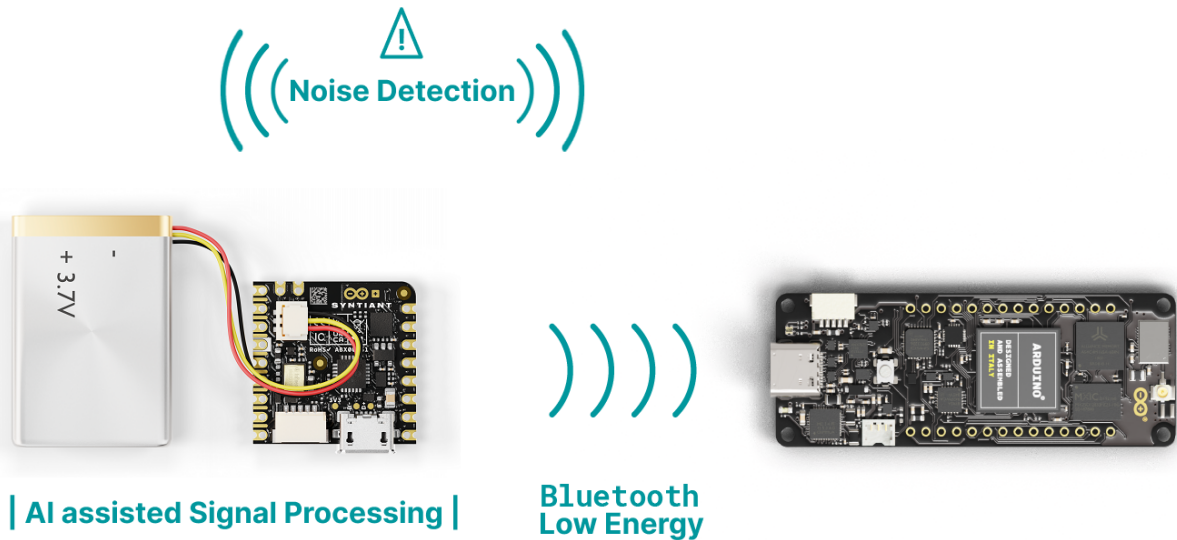
1.2 Accessories (Not Included)

- Single-cell Li-ion/Li-Po battery

1.3 Related Products

- ESLOV connector
- Arduino® Portenta H7 (SKU: ABX00042)
- Arduino® Portenta H7 Lite (SKU: ABX00045)
- Arduino® Portenta H7 Lite Connected (SKU: ABX00046)
- Arduino® Nicla Sense ME (SKU: ABX00050)

1.4 Assembly Overview



Example: Example of a typical solution for remote environmental sensing including an Arduino® Nicla Voice, Arduino® Portenta H7 and battery. Notice the orientation of the battery's cable in the board's connector.

Note: The NTC pin on the battery connector is optional. This is a feature that allows safer use and thermal shutoff of the PMIC.

2 Ratings

| Symbol | Description | Min | Typ | Max | Unit |
|-----------------------|----------------------------------|---------------------------------------|-----|---------------------------------------|------|
| V _{IN} | Input voltage from VIN pad | 3.5 | 5.0 | 5.5 | V |
| V _{USB} | Input voltage from USB connector | 4.8 | 5.0 | 5.5 | V |
| V _{DDIO_EXT} | Level Translator Voltage | 1.8 | 3.3 | 3.3 | V |
| V _{IH} | Input high-level voltage | 0.7V _{DDIO_EXT} ¹ | | V _{DDIO_EXT} | V |
| V _{IL} | Input low-level voltage | 0 | | 0.3V _{DDIO_EXT} ² | V |
| T _{OP} | Operating Temperature | 0 | 25 | 70 | °C |

Note : V_{DDIO_EXT} is software programmable. While the ADC inputs can accept up to 3.3 V, the maximum value is at the ANNA-B112 operating voltage.

All I/O pins operate at V_{DDIO_EXT} apart from the following:

- ADC1 and ADC2 - 1.8 V
- JTAG_SAMD11 - 3.3 V
- JTAG_ANNA - 1.8 V
- JTAG_BMI - 1.8 V

- VDDOTP - 1.8 V

²: If the internal V_{DDIO_EXT} is disabled by software, it is possible to supply it externally.

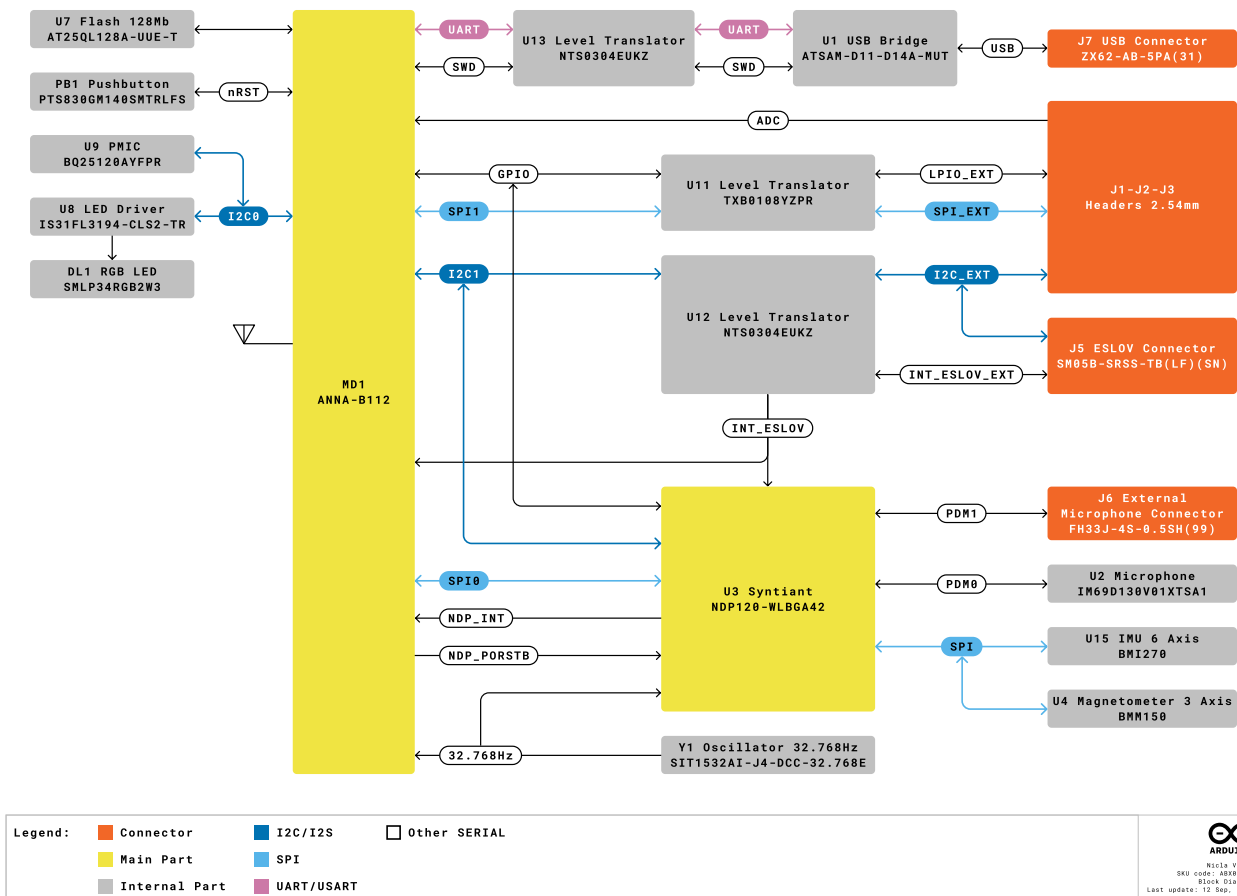
3 Power Consumption

| Description | Min | Typ | Max | Unit |
|---|-----|------|-----|------|
| Standby | - | 0.46 | - | mA |
| Alexa demo ON with BLE off | - | 0.80 | - | mA |
| Alexa demo ON with BLE advertising and sensor polling at 1 Hz | - | 2.4 | - | mA |

The measurements have been performed with $V_{BAT} = 3.7 V$. Alexa demo corresponds to the factory firmware flashed by default on the Nicla Voice.

4 Functional Overview

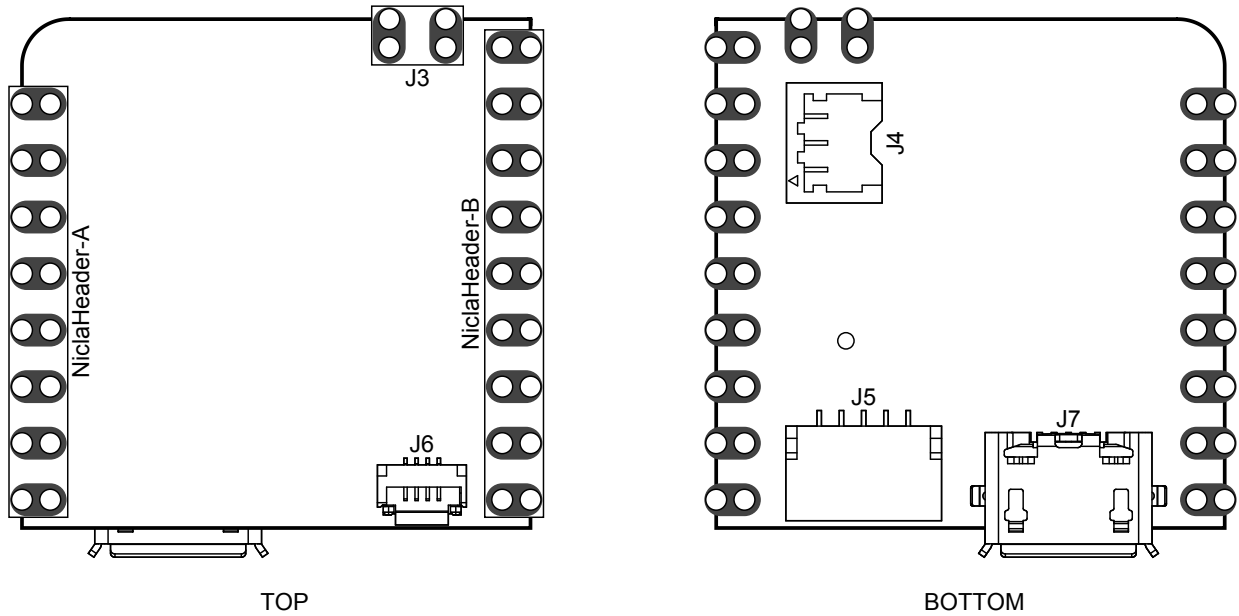
4.1 Block Diagram



Nicla Voice Block Diagram

4.2 Board Topology

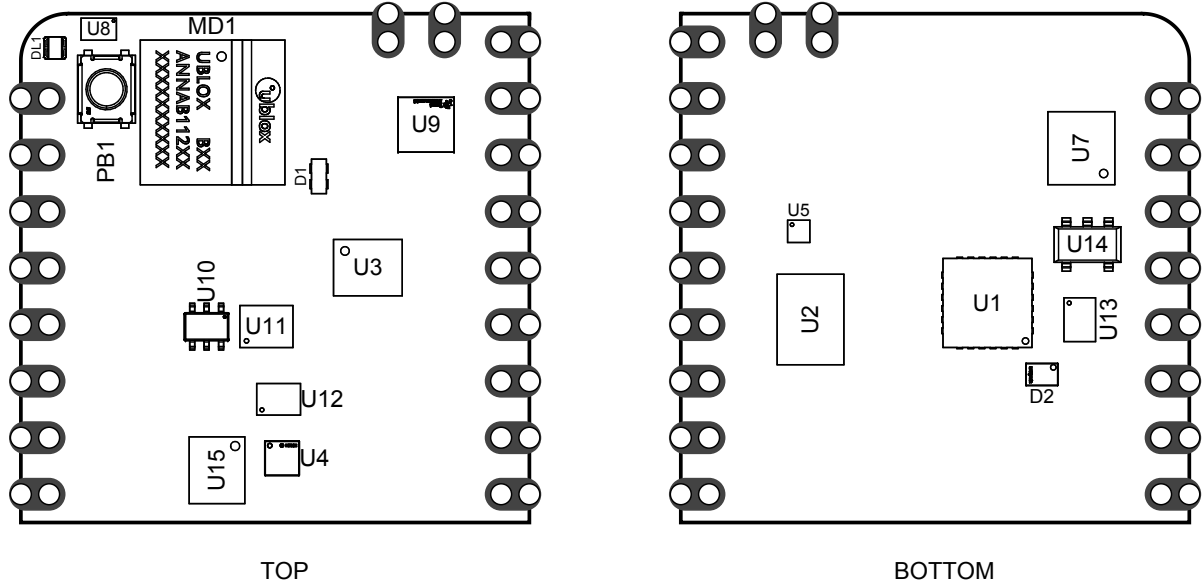
4.2.1 Connectors Topology



Nicla Voice Topology- Components

| Ref. | Description | Ref. | Description |
|------|------------------------------|------|---------------------------------|
| J1 | Nicla Header A | J2 | Nicla Header B |
| J3 | Battery Pads | J4 | Battery Connector (BM03B-ACHSS) |
| J5 | ESLOV Connector (SM05B-SRSS) | J6 | External Microphone (FH33J-4S) |
| J7 | Micro USB-AB (ZX62-AB) | | |

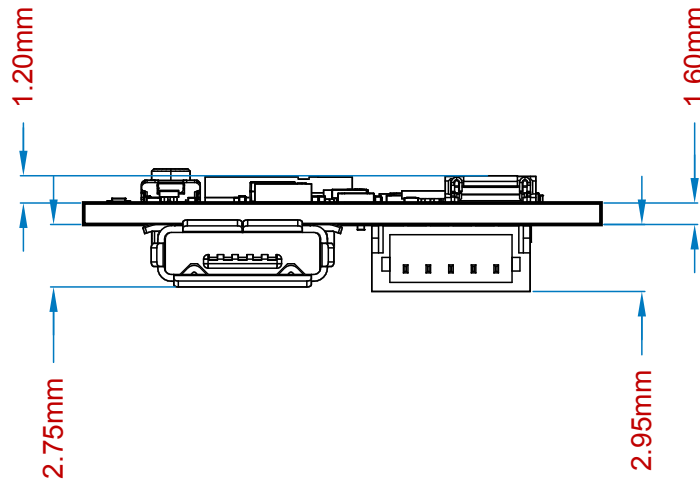
4.2.2 Components Topology



Nicla Voice Topology - components

| Ref. | Description | Ref. | Description |
|------|----------------------------------|------|--|
| DL1 | RGB LED | MD1 | u-blox ANNA-B112 |
| PB1 | Push Button | D1 | Schottky Diode, PMEG4005EPK |
| D2 | Resistor array PRTR5V0U0F | U1 | Arm® Cortex M0 ATSAM-D11 |
| U2 | Microphone IM69D130V01 | U3 | Syntiant® Neural Decision Processor NDP120 |
| U4 | Magnetic Sensor BMM150 | U5 | LDO TPS7A0511PDQNR |
| U7 | Flash, 128MX1. AT25QL128A | U8 | RGB LED Driver IS31FL3194 |
| U9 | Battery Charger LDO Buck BQ25120 | U10 | Bus Transceiver 74LVC1T45DW |
| U11 | Level Shifter TXB0108Y | U12 | Level Shifter NTS0304 |
| U13 | Level Shifter NTS0304 | U14 | LDO regulator, 3.3 V AP2112K |
| U15 | IMU 6 Axis Low Power BMI270 | | |

4.2.3 Front



Nicla Voice Front View

4.3 Microcontroller

The Arduino® Nicla Voice is powered by a nRF52832 SoC within the ANNA-B112 module (MD1). The nRF52832 SoC is built around an ARM® Cortex-M4 microcontroller with floating point unit running at 64 MHz. Sketches are stored inside the nRF52832 internal 512 KB FLASH which is shared with the bootloader. 64 KB SRAM is available to the user. The ANNA-B112 acts as the SPI host for the data logging 16MB flash (U7). While the module itself runs at 1.8 V, a level shifter can adjust the logic level between 1.8 V and 3.3 V depending on the LDO set in BQ25120 (U9). An external oscillator (Y1) provides a 32 KHz signal. The ANNA-B112 acts as the SPI host for the data logging 16MB flash (U7) and the Syntiant® NDP120 IC (U3).

4.4 Neural Decision Processor

The Arduino® Nicla Voice integrates a Neural Decision Processor™ NDP120 from Syntiant® (U3). The NDP120 leverages Syntiant Core 2™ ultra-low-power deep neural network inference engine to move larger neural networks into always-on domains with the capacity to run multiple applications simultaneously with minimal power consumption, including keyword spotting and event detection. The Syntiant® NDP120 IC (U3) also acts as the SPI host for the BMM150 3-axis magnetometer (U4) and the BMI270 6-axis IMU (U15).

4.5 IMU

The Nicla Voice provides 9-axis IMU capabilities, by the combination of the 3-axis BMM150 (U4) and 6-axis BMI270 (U15) ICs. The BMI270 includes both a three-axis gyroscope as well as a three-axis accelerometer, while the BMM150 is capable of sensing magnetic field variations in all three dimensions. The information obtained can be used for measuring raw movement parameters as well as for machine learning. Both are connected via an SPI connection to the Syntiant® NDP120 IC (U3).

4.6 RGB LED

An I2C LED driver (U8) drives the common anode RGB LED (DL1) and is capable of a maximum output of 40 mA. It is driven by the ANNA-B112 (U5) microcontroller.

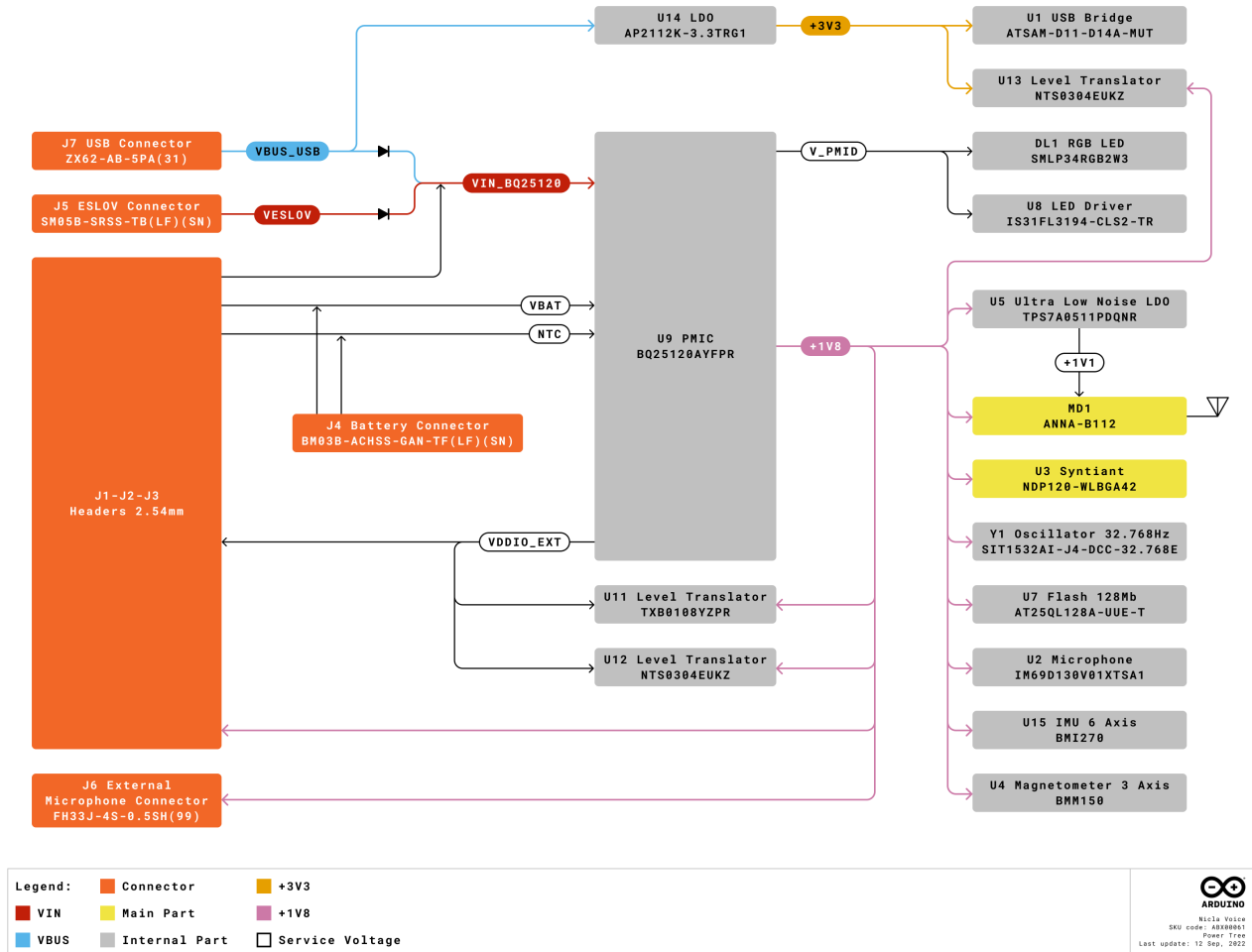
4.7 Microphone

The IM69D130V01XTSA1 microphone IC (U2) includes two near identical MEMS microphones with a common membrane. The audio signal is transported over a PDM channel to the NDP120 (U3). An external microphone can be added using the J6 connector, which is also connected to the NDP120 (U3) over a separate PDM channel. Internal microphone (U2) and optional external microphone (J6) are on PDM 0 and PDM 1 channels respectively.

4.8 USB Bridge

The SAMD11 microcontroller (U1) is dedicated to act as both the USB bridge as well as the JTAG controller for the ANNA-B112. A logic level translator (U13) acts as an in between to translate 3.3 V logic to 1.8 V for the ANNA-B112. The 3.3 V voltage is generated from the USB voltage by a LDO (U14).

4.9 Power Tree



Nicla Voice Power Tree

The **Arduino® Nicla Voice** can be powered via micro USB (J7), ESLOV (J5) or VIN pin. The input power is converted into the relevant voltages via the BQ2512BAYFPR IC (U9). A Schottky diode provides reverse polarity protection to the USB and ESLOV voltages. When voltage is supplied via the micro USB, a linear 3.3 V regulator also provides power to the SAMD11 microcontroller used for programming the board as well as for JTAG and SWD. The LED driver (U8) and RGB Leds (DL1) are driven by a boost voltage of 5V. All other components operate off the 1.8 V rail regulated by a buck converter. PMID acts as an OR switch between VIN and BATT and operates the LED driver. All I/O broken out to the pins are fed through a bi-direction voltage translator running at V_{DDIO_EXT}.

Additionally, the BQ25120AYFPR (U9) also provides support for a single cell 3.7 V LiPo/Li-ion battery pack connected to J4, allowing the use of the board as a wireless sensor network.

5 Board Operation

5.1 Getting Started - IDE

If you want to program your Arduino® Nicla Voice while offline you need to install the Arduino® Desktop IDE **[1]**. To connect the Arduino® Nicla Voice to your computer, you'll need a micro USB cable.

5.2 Getting Started - Arduino Web Editor

All Arduino® boards, including this one, work out-of-the-box on the Arduino® Web Editor **[2]**, by just installing a simple plugin.

The Arduino® Web Editor is hosted online, therefore it will always be up-to-date with the latest features and support for all boards. Follow **[3]** to start coding on the browser and upload your sketches onto your board.

5.3 Getting Started - Arduino Cloud

All Arduino® IoT enabled products are supported on Arduino® Cloud which allows you to log, graph and analyze sensor data, trigger events, and automate your home or business.

5.4 Getting Started - ESLOV

The Nicla Voice board features an onboard ESLOV connector meant as an **extension** of the I2C communication bus; the board itself can act as a secondary ESLOV controller or peripheral. The ESLOV connector simplifies connecting various sensors, actuators, and other modules to the Nicla Voice without soldering or wiring.

The ESLOV connector is a small 5-pin connector with a 1.00 mm pitch; the mechanical details of the connector can be found in the connector's datasheet.

The pin layout of the Nicla Voice ESLOV connector is the following:

1. VCC_IN (5V input)
2. INT
3. SCL
4. SDA
5. GND

The manufacturer part number of the ESLOV connector is SM05B-SRSS and its matching receptacle manufacturer part number is SHR-05V-S-B.

Note: Pin 1 of the ESLOV connector of the Nicla Voice board is a **5V voltage input**, not a voltage output. This means that the Nicla Voice is intended to be used as a secondary or a peripheral board of a main board or controller with an ESLOV connector with a 5V output like, for example, the Portenta H7.

5.5 Sample Sketches

Sample sketches for the Arduino® Nicla Voice can be found either in the “Examples” menu in the Arduino® IDE or in the “Documentation” section of the Arduino® Pro website [4].

5.6 Online Resources

Now that you have gone through the basics of what you can do with the board you can explore the endless possibilities it provides by checking exciting projects on ProjectHub [5], the Arduino® Library Reference [6] and the online store [7] where you will be able to complement your board with sensors, actuators and more.

5.7 Board Recovery

All Arduino® boards have a built-in bootloader which allows flashing the board via USB. In case a sketch locks up the processor and the board is not reachable anymore via USB, it is possible to enter bootloader mode by double-tapping the reset button right after power up.

6 Connector Pinouts

All the pins on J1 and J2 (excluding fins) are referenced to the V_{DDIO_EXT} voltage which can be generated internally or supplied externally.

6.1 J1 Nicla Header A

| Pin | Function | Type | Description | MKR Compatibility |
|-----|-----------|---------|------------------------------------|-------------------|
| 1 | LPIIO_EXT | Digital | Low Power IO Pin 0 | A6 |
| 2 | NC | N/A | N/A | A5 |
| 3 | CS | Digital | SPI Cable Select | A4 |
| 4 | COPI | Digital | SPI Controller Out / Peripheral In | A3 |
| 5 | CIPO | Digital | SPI Controller In / Peripheral Out | A2 |
| 6 | SCLK | Digital | SPI Clock | A1 |
| 7 | ADC2 | Analog | Analog Input 2 | A0 |
| 8 | ADC1 | Analog | Analog Input 1 | AREF |

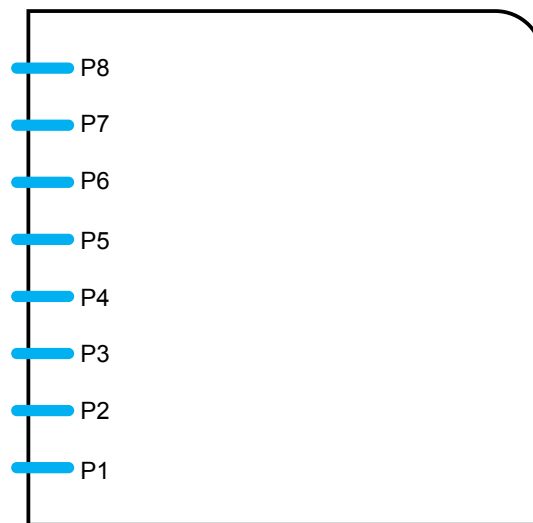
6.2 J2 Nicla Header B

| Pin | Function | Type | Description | MKR Compatibility |
|-----|-----------|---------|-----------------------|-------------------|
| 1 | SDA | Digital | I2C Data Line | SDA |
| 2 | SCL | Digital | I2C Clock | SCL |
| 3 | LPIO1_EXT | Digital | Low Power IO Pin 1 | RX |
| 4 | LPIO2_EXT | Digital | Low Power IO Pin 2 | TX |
| 5 | LPIO3_EXT | Digital | Low Power IO Pin 3 | RESET |
| 6 | GND | Power | Ground | GND |
| 7 | VDDIO_EXT | Digital | Logic Level Reference | 3.3 V |
| 8 | N/C | N/A | N/A | VIN |
| 9 | VIN | Digital | Input Voltage | 5V |

Note: For further information on how Low Power I/Os work, check Nicla Family Form Factor documentation.

6.3 J2 Fins

Between the main pins, there are smaller contacts (fins) that provide access to debugging capabilities. These test points can easily be accessed by inserting the board in a double row 1.27 mm/50 mil pitch male header.



BOTTOM FINS

Nicla Family Bottom Fins

| Pin | Function | Type | Description |
|-----|--------------|---------|-------------------------------------|
| P1 | BMI_SWDIO | Digital | BMI270 JTAG Serial Wire Debug Data |
| P2 | BMI_SWDCLK | Digital | BMI270 JTAG Serial Wire Debug Clock |
| P3 | ANNA_SWDIO | Digital | ANNA JTAG Serial Wire Debug Data |
| P4 | ANNA_SWDCLK | Digital | ANNA JTAG Serial Wire Debug Clock |
| P5 | RESET | Digital | Reset Pin |
| P6 | SAMD11_SWDIO | Digital | SAMD11 JTAG Serial Wire Debug Data |
| P7 | +1.8 V | Power | +1.8 V Voltage Rail |

| Pin | Function | Type | Description |
|-----|--------------|---------|-------------------------------------|
| P8 | SAMD11_SWCLK | Digital | SAMD11 JTAG Serial Wire Debug Clock |

Note: All JTAG logic levels operate at 1.8 V apart from the SAMD11 pins (P6 and P8) which are 3.3 V. All these JTAG pins are 1.8 V only and don't scale with VDDIO.

6.4 J3 Battery Pads

| Pin | Function | Type | Description |
|-----|----------|--------|----------------|
| 1 | VBAT | Power | Battery input |
| 2 | NTC | Analog | NTC Thermistor |

6.5 J4 Battery Connector

| Pin | Function | Type | Description |
|-----|----------|--------|----------------|
| 1 | VBAT | Power | Battery input |
| 2 | NTC | Analog | NTC Thermistor |
| 3 | GND | Power | Ground |

6.6 J5 ESLOV

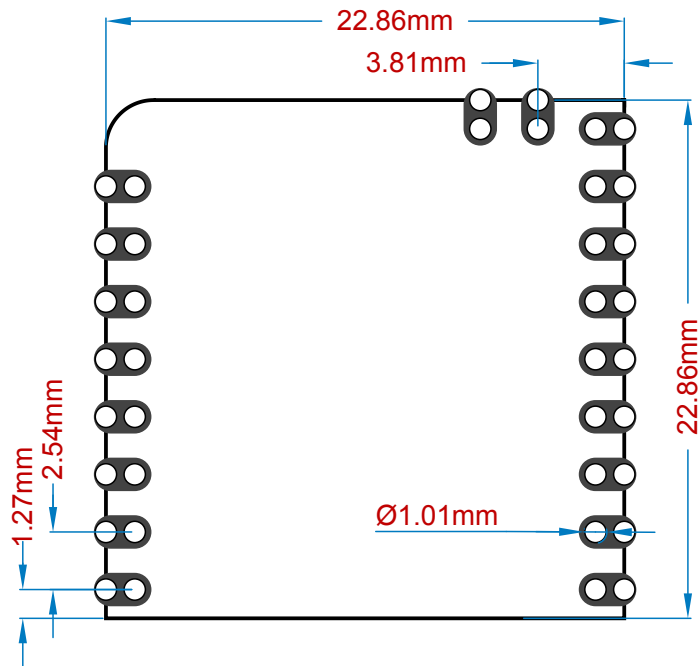
| Pin | Function | Type | Description |
|-----|----------|---------|----------------|
| 1 | 5V | Power | 5V Power Rail |
| 2 | INT | Digital | Digital IO |
| 3 | SCL | Digital | I2C Clock Line |
| 4 | SDA | Digital | I2C Data Line |
| 5 | GND | Power | Ground |

6.7 J6 External Microphone

| Pin | Function | Type | Description |
|-----|-----------|---------|------------------|
| 1 | 1.8 V_MIC | Power | 1.8 V Power Rail |
| 2 | GND | Power | Ground |
| 3 | PDMDIN1 | Digital | PDM 1 Data Line |
| 4 | PDMCLK1 | Digital | PDM 1 Clock Line |

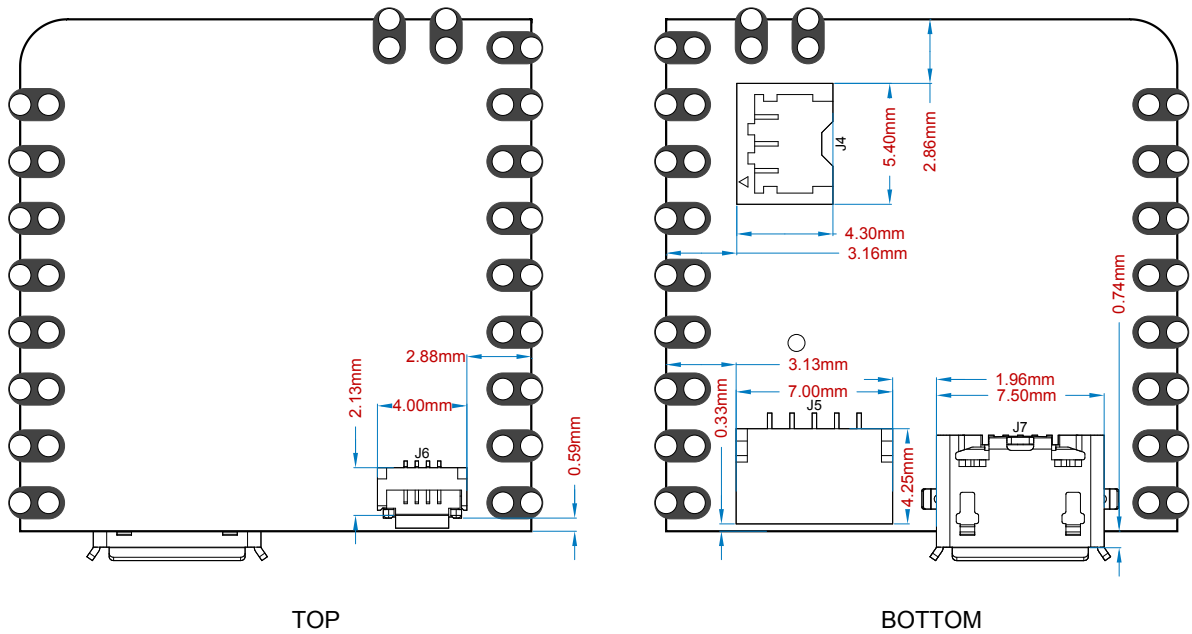
7 Mechanical Information

7.1 Outline Board Measures



Nicla Voice outline measures

7.2 Board's Connectors Measures



Nicla Voice connectors - mechanical measures

8 Certifications

8.1 Declaration of Conformity CE DoC (EU)

We declare under our sole responsibility that the products above are in conformity with the essential requirements of the following EU Directives and therefore qualify for free movement within markets comprising the European Union (EU) and European Economic Area (EEA).

8.2 Declaration of Conformity to EU RoHS & REACH 211 01/19/2021

Arduino boards are in compliance with RoHS 2 Directive 2011/65/EU of the European Parliament and RoHS 3 Directive 2015/863/EU of the Council of 4 June 2015 on the restriction of the use of certain hazardous substances in electrical and electronic equipment.

| Substance | Maximum Limit (ppm) |
|--|---------------------|
| Lead (Pb) | 1000 |
| Cadmium (Cd) | 100 |
| Mercury (Hg) | 1000 |
| Hexavalent Chromium (Cr6+) | 1000 |
| Poly Brominated Biphenyls (PBB) | 1000 |
| Poly Brominated Diphenyl ethers (PBDE) | 1000 |
| Bis(2-Ethylhexyl} phthalate (DEHP) | 1000 |
| Benzyl butyl phthalate (BBP) | 1000 |
| Dibutyl phthalate (DBP) | 1000 |
| Diisobutyl phthalate (DIBP) | 1000 |

Exemptions : No exemptions are claimed.

Arduino Boards are fully compliant with the related requirements of European Union Regulation (EC) 1907 /2006 concerning the Registration, Evaluation, Authorization and Restriction of Chemicals (REACH). We declare none of the SVHCs (<https://echa.europa.eu/web/guest/candidate-list-table>), the Candidate List of Substances of Very High Concern for authorization currently released by ECHA, is present in all products (and also package) in quantities totaling in a concentration equal or above 0.1%. To the best of our knowledge, we also declare that our products do not contain any of the substances listed on the "Authorization List" (Annex XIV of the REACH regulations) and Substances of Very High Concern (SVHC) in any significant amounts as specified by the Annex XVII of Candidate list published by ECHA (European Chemical Agency) 1907 /2006/EC.

8.3 Conflict Minerals Declaration

As a global supplier of electronic and electrical components, Arduino is aware of our obligations with regards to laws and regulations regarding Conflict Minerals, specifically the Dodd-Frank Wall Street Reform and Consumer Protection Act, Section 1502. Arduino does not directly source or process conflict minerals such as Tin, Tantalum, Tungsten, or Gold. Conflict minerals are contained in our products in the form of solder, or as a component in metal alloys. As part of our reasonable due diligence Arduino has contacted component suppliers within our supply chain to verify their continued compliance with the regulations. Based on the information received thus far we declare that our products contain Conflict Minerals sourced from conflict-free areas.

9 FCC Caution

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference
- (2) this device must accept any interference received, including interference that may cause undesired operation.

FCC RF Radiation Exposure Statement:

1. This Transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.
2. This equipment complies with RF radiation exposure limits set forth for an uncontrolled environment.
3. This equipment should be installed and operated with a minimum distance of 20cm between the radiator & your body.

English: User manuals for license-exempt radio apparatus shall contain the following or equivalent notice in a conspicuous location in the user manual or alternatively on the device or both. This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions:

- (1) this device may not cause interference
- (2) this device must accept any interference, including interference that may cause undesired operation of the device.

French: Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes:

- (1) l'appareil n' doit pas produire de brouillage
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

IC SAR Warning:

English This equipment should be installed and operated with a minimum distance of 20 cm between the radiator and your body.

French: Lors de l' installation et de l' exploitation de ce dispositif, la distance entre le radiateur et le corps est d' au moins 20 cm.

Important: The operating temperature of the EUT can't exceed 85°C and shouldn't be lower than -40°C.

Hereby, Arduino S.r.l. declares that this product is in compliance with essential requirements and other relevant provisions of Directive 201453/EU. This product is allowed to be used in all EU member states.

| Frequency bands | Typical Output Power |
|---------------------|----------------------|
| 2.4GHz, 40 channels | +4dBm |

10 Company Information

| Company name | Arduino SRL |
|-----------------|--|
| Company Address | Via Andrea Appiani, 25 - 20900 MONZA (Italy) |

11 Reference Documentation

| Ref | Link |
|------------------------------------|---|
| Arduino® IDE (Desktop) | https://www.arduino.cc/en/Main/Software |
| Arduino® IDE (Cloud) | https://create.arduino.cc/editor |
| Arduino® Cloud IDE Getting Started | https://create.arduino.cc/projecthub/Arduino_Genuino/getting-started-with-arduino-web-editor-4b3e4a |
| Arduino® Pro Website | https://www.arduino.cc/pro |
| Project Hub | https://create.arduino.cc/projecthub?by=part&part_id=11332&sort=trending |
| Online Store | https://store.arduino.cc/ |

12 Revision History

| Date | Revision | Changes |
|------------|----------|---------------------------|
| 17/05/2023 | 2 | ESLOV Information updated |
| 05/01/2023 | 1 | First release |

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