Shaft Type/Hollow Shaft Type/Blind Hollow Shaft Type Ø40mm

Incremental Rotary Encoder

Features

- Easy installation at narrow space
- Low moment of inertia
- Power supply: 5VDC, 12-24VDC ±5%
- Various output types



Please read "Caution for your safety" in operation manual before using.

Ordering Information

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E40 H		3	- 5000 -	- 3 -	- N -	- 24	
Series	Shaft type	Hollow type	Pulses/revolution	Output phase	Control output	Power supply	Cable
Ø40mm	External	Inner			T: Totem pole output		
I TVDE	6: Ø6mm 8: Ø8mm	6: Ø6mm 8: Ø8mm 10: Ø10mm 12: Ø12mm	Refer to resolution	2: A, B 3: A, B, Z 4: A, Ā, B, B̄ 6: A, Ā, B, B̄, Z, Z̄	N: NPN open collector output	15 . 5//1/(. +5%	

Specifications

Item			Shaft Type/Hollow Shaft Type/Blind Hollow Shaft Type Ø40mm Incremental Rotary Encoder			
Resolution (PPR) ^{×1})*1	*1, *2, *5, 10, *12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000			
Output phase			A, B, Z phase (line driver A, \overline{A} , B, \overline{B} , Z, \overline{Z} phase)			
Phase difference of output		rence of output	Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)			
		Totem pole output	 [Low] - Load current: Max. 30mA, Residual voltage: Max. 0.4VDC [High] - Load current: Max. 10mA, Output voltage (power voltage 5VDC): Min. (power voltage-2.0)VDC, Output voltage (power voltage 12-24VDC): Min. (power voltage-3.0)VDC 			
	COLLEGE	NPN open collector output	Load current: Max. 30mA, Residual voltage: Max. 0.4VDC			
l oi		Voltage output	Load current: Max. 10mA, Residual voltage: Max. 0.4VDC			
Electrical specification		Line driver output	[Low] - Load current: Max. 20mA, Residual voltage: Max. 0.5VDC [High] - Load current: Max20mA, Output voltage (power voltage 5VDC): Min. 2.5VDC, Output voltage (power voltage 12-24VDC): Min. (power voltage-3.0)VDC			
S		Totem pole output				
ig	Response time	NPN open collector output	Max. 1μs (cable length: 2m, I sink = 20mA)			
ecti	(rise/fall)	Voltage output				
Ĭ		Line driver output	Max. 0.5μs (cable length: 2m, I sink = 20mA)			
	Max. respo	nse frequency	300kHz			
	Power supply		• 5VDC ±5% (ripple P-P: Max. 5%) • 12-24VDC ±5% (ripple P-P: Max. 5%)			
	Current cor	nsumption	Max. 80mA (disconnection of the load), Line driver output: Max. 50mA (disconnection of the load)			
	Insulation resistance Dielectric strength		Over 100MΩ (at 500VDC megger between all terminals and case)			
			750VAC 50/60Hz for 1 minute (between all terminals and case)			
	Connection		Radial cable type, Radial cable connector type			
ᇢᇊ	Starting tor	que	S type: max. 40gf·cm (0.004N·m), H/HB type: max. 50gf·cm (0.005N·m)			
anic	Moment of inertia		Max. 40g·cm² (4×10 ⁻⁶ kg·m²)			
ecifi	Starting torque Moment of inertia Shaft loading Max. allowable revolution *2		Radial: max. 2kgf, Thrust: max. 1kgf			
≥ 🖔 Max. allowable revolution *2		able revolution *2	5,000rpm			
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock			Approx. max. 50G			
I nvironment		Ambient temperature	-10 to 70°C, storage: -25 to 85°C			
		Ambient humidity	35 to 85%RH, storage: 35 to 90%RH			
Protection structure			IP50 (IEC standard)			
Cable			Ø5mm, 5-wire (line driver output: 8-wire), 2m, Shield cable (AWG24, core diameter: Ø1mm)			
Accessory			• S: Ø6mm coupling standard, Ø8mm coupling (sold separately) • H/HB type: Bracket			
Approval			C € (except line driver output)			
Unit	weight		Approx. 120g			
V/ 4 . I . I	X4. '- Juliea is only for A. B. phase /line driver output is for A. A. B. B. phase). Not indicated resolutions are customizable					

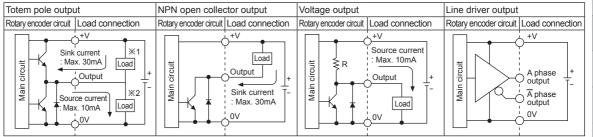
 $[\]times$ 1: '*' pulse is only for A, B phase (line driver output is for A, \overline{A} , B, \overline{B} phase). Not indicated resolutions are customizable.

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X2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

Incremental Ø40mm Shaft/Hollow Shaft/Blind Hollow Shaft Type

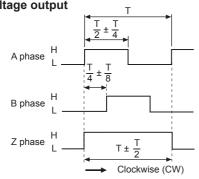
Control Output Diagram



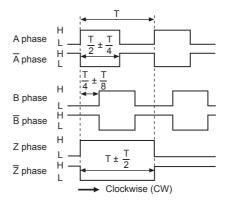
- Totem pole output type can be used for NPN open collector output type (X1) or Voltage output type (X2).
- All output circuits of A, B, Z phase are same. (line driver output is A, A, B, B, Z, Z)

Output Waveform

 Totem pole output / NPN open collector output / Voltage output



Line driver output



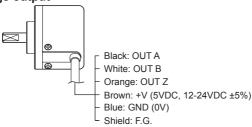


XZ reverse phase output is optional.

Connections

Radial cable type

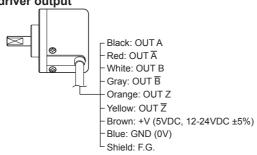
 Totem pole output / NPN open collector output / Voltage output



XUnused wires must be insulated.

**The metal case and shield wire of encoder should be grounded (F.G.).

• Line driver output



Radial cable connector type

Totem pole output /
 NPN open collector output /
 Voltage output





	oole output en collect output		Line driver output			
Pin No	Function	Cable color	Pin No	Function	Cable color	
1	OUTA	Black	1	OUT A	Black	
2	OUT B	White	2	OUTĀ	Red	
3	OUT Z	Orange	3	+V	Brown	
4	+V	Brown	4	GND	Blue	
⑤	GND	Blue	⑤	OUT B	White	
6	F.G.	Shield	6	OUT B	Gray	
			7	OUT Z	Orange	
_			8	OUT Z	Yellow	
			9	F.G.	Shield	

※F.G. (field ground): It should be grounded separately.

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Meters (M)

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(R) Graphic/ Logic Panels

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Dimensions (unit: mm) Radial cable type Shaft type 31 5 15 3-M3×0.5 DP: 5 P.C.D 30 10 ☻ 45 В Ø6-0.01 5 Ø8-0.01 Cable • Hollow shaft / Blind hollow shaft type Ø5mm, 5-wire (line driver output: 8-wire), 2000mm, Shield cable M3 Bolt mounting hole P.C.D 46 E40H 32 Cable Ø5mm, 5-wire (line driver output: 8-wire), 1 2000mm, Shield cable Ø8 Ø10 Ø12 Ø6 27 В Ø15 Ø17 E40HB Tolerance +0.015 Radial cable connector type • Coupling (E40S) • Bracket (E40H, E40HB) 3-M3×0.5 DP: 5 P.C.D 30 Ø6 Coupling Ø15 4-M3×0.5 M3 Bolt mounting hole Ø8 Coupling P.C.D 46 Ø19 Ø8+0 · Parallel misalignment: Max. 0.25mm • Angular misalignment: Max. 5° XConnector cable is sold separately and 4-M4×0.7 • End-play: Max. 0.5mm refer to page G-10 for specifications.

XDo not load overweight on the shaft.

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^{*}When mounting the coupling to the encoder shaft, if there is combined misalignment (parallel, angular misalignment) between rotating encoder shaft and mate shaft, it may cause encoder and coupling's life cycle to shorten.

^{**}For parallel misalignment, angular misalignment, end-play terms, refer to page F-87.

^{**}For flexible coupling (ERB Series) information, refer to page F-80.

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