Autonics

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

• Δ symbol indicates caution due to special circumstances in which hazards may occur.

Marning Failure to follow instructions may result in serious injury or death

Safety Considerations

Independent Single Display PID Temperature Controllers



TR1D Series

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- · Compact, space-saving design with 22.5 mm width size
- 50 ms high-speed sampling and \pm 0.3% display accuracy
- Simultaneous heating/cooling and automatic/manual control function
- · Switch between current output and SSR drive output
- Easy mount on DIN rails (patent)*1
- RS485 communication output model available
- Protocol: Modbus RTU or ASCII
- Communication speed: up to 115,200 bps
- Parameter setting via PC (USB or RS485 communication)
- Comprehensive device management software (DAQMaster) provided
- · Heater disconnect alarm function (CT input)
- Current transformer (CT) sold separately: CSTC-E80LN, CSTC-E200LN, CSTS-E80PP Screen protection function
- *1 Korea Patent Registration 10-2019-0158569, Korea Design Registration 30-1065663, China Design Registration 202030164351.2

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install the unit on DIN rail to use.** Failure to follow this instruction may result in electric shock.
- Failure to follow this instruction may result in electric shock.
 Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. **05. Check 'Connections' before wiring.**
- Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.**
 - Failure to follow this instruction may result in fire or electric shock.

Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m. When connecting the sensor input and communication cable without

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m. Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage **03. Use a dry cloth to clean the unit, and do not use water or organic solvent.** Failure to follow this instruction may result in fire or electric shock.
- Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.

- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of
- external noise. • Make a required space around the unit for radiation of heat. For accurate temperature
- measurement, warm up the unit over 20 min after turning on the power.Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

Model	Control output1	Control output2	Option output	Additional function
TR1D-14RN ⁰¹⁾	Relay	-	-	-
TR1D-14RR	Relay	Relay ↔ Alarm	-	CT input, Dual alarm output ⁰²⁾
TR1D-R4RR	D-R4RR Relay Relay ↔ Alarm		Transmission	CT input, Dual alarm output ⁰²⁾
TR1D-T4RR	- T4RR Relay Relay ↔ Alarm		Communication	CT input, Dual alarm output ⁰²⁾
TR1D-14CN 01)	Current/SSR	-	-	-
TR1D-14CC Current/SSR		Current/SSR↔ Transmission	-	CT input
TR1D-R4CC	Current/SSR Current/SSR↔ Current/SSR		Transmission	CT input, Dual transmission output
TR1D-T4CC	ID-T4CC Current/SSR Current/SSR ↔ Transmission		Communication	CT input

01) The model does not support terminal for the control output 2 is not available to use heating&cooling control and alarm outputs at the same time.

02) It is not possible to use dual alarm output and heating&cooling control at the same time.

Product Components

• Product

Instruction manual

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Unit Descriptions

Top terminal block 5 to 8 1 to 4 6 6 6 7 5 to 8 01 02 0 9 03 0 9 03 0 9 04 05 04 05

01.	PV / SV dis	play part (Red)				
	RUN mode:	Displays PV (Present value) and SV (Setting value).				
	Parameter:	Displays name and setting value of parameters.				
02.	Indicator					
	Indicator	ON contition				
	SV	SV display				
	OUT	Control output□ ON				
	AL1	AL1 alarm output ON				
	•	The difference between PV and SV is less than 2°C				
	▲/▼	The difference between PV and SV is greater than 2°C				
	°C or °F	'2-2 Temperature unit' parameter setting				
03.	Control ke	у				
	[M]: MODE	(ey				
~ •		▼]: Setting value control key				
04.	. PC loader port					

Use to mount and detach the DIN rail.

separately) connection 05. Bracket handle

Series		TR1D Series				
Power supply		100 - 240 VAC~ 50/60 Hz				
Allowabl	e voltage range	90 to 110% of rated voltage				
Power co	onsumption	≤8 VA				
Samplin	g period	50, 100, 250 ms				
Input spe	ecification	Refer to 'Input Type and Using Range'.				
Option input CT input		 0.0-50.0 A (primary current measurement range) CT ratio: 1/1,000, Measurement accuracy: ±5% F.S. ±1digit 				
Control	relay	250 VAC~ 3 A 1a				
output	SSR	$12 \text{ VDC} = \pm 3 \text{ V}, \le 20 \text{ mA}$				
output	Current	DC 4-20 mA or DC 0-20 mA (parameter), Load: \leq 500 Ω				
	Alarm	AL1, AL2: 250 VAC~ 3 A 1a				
Option output	Transmission	DC4-20 mA (Load resistance: \leq 500 $\Omega,$ Output accuracy: $\pm 0.3\%$ F.S.)				
	RS485 comm.	Modbus RTU / ASCII				
Disularit		7				
Display t	ype	/ segment (red), 4-digit				
Controlt	уре	ON/OFF, P, PI, PD, PID CONTROL				
Hysteres	is	Alarm output: 1 to 100 °C/°F (0.1 to 50.0 °C/°F)				
Proporti	onal band (P)	0.1 to 999.9 °C				
Integral	time (I)	0 to 9,999 sec				
Derivativ	ve time (D)	0 to 9,999 sec				
Control	cycle (T)	Relay output: 0.5 to 120.0 sec, SSR drive output: 0.5 to 120.0 sec				
Manualr	eset	0.0 to 100.0%				
Dielectri	c strength	Between the power part and the case: 3,000 VAC \sim 50/60 Hz for 1 min				
Vibratior	ı	0.75 mm amplitude at frequency of 5 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				
Polay life	Mechanical	OUT1/2, AL1/2: ≥ 5,000,000 operations				
cycle	Electrical	OUT1/2, AL1/2: \geq 100,000 operations (resistance load: 250 VAC \sim 5 A)				
Insulation resistance		\geq 100 M Ω (500 VDC= megger)				
Insulation type		Double insulation or reinforced insulation (dielectric strength between the power part and the case: 3 kV)				
Noise im	munity	Square shaped noise (pulse width: 1 $\mu s)$ by noise simulator ± 2 kV R-phase, S-phase				
Memory	retention	pprox 10 years (non-volatile semiconductor memory type)				
Ambient	temperature	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)				
Ambient	humidity	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)				
Approva	l	CE				
Unit wei	ght (nackaged)	$\approx 1235 \sigma (\approx 1945 \sigma)$				

Communication Interface

RS485

Specifications

Communication protocol	Modbus RTU / ASCII			
Application standard	EIA RS485 compliance with			
Maximum connection	31 units (address: 01 to 127)			
Synchronous method	Asynchronous			
Communication method	Two-wire half duplex			
Communication effective range	\leq 800 m			
Communication speed	4,800 - 9,600 (default) - 19,200 - 38,400 - 57,600 - 115,200 bps (parameter)			
Response time	5 to 99 ms (default: 20 ms)			
Start bit	1 bit (fixed)			
Data bit	8 bit (fixed)			
Parity bit	None (default), Odd, Even			
Stop bit	1 bit, 2 bit (default)			

 It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.

Input Type and Using Range

• The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display Method	Using range(°C)	Using range(°F)		
	K (CA)	1	E C A'H	-50 to 1,200	-58 to 2,192		
	R (CA)	0.1	E C A.L	-50.0 to 999.9	-58.0 to 999.9		
	1/10)	1	JI [.H	-30 to 800	-22 to 1,472		
	J (IC)	0.1	J I E.L	-30.0 to 800.0	-22.0 to 999.9		
Thermo	1 (10)	1	LIE.H	-40 to 800	-40 to 1,472		
-couple	0.1	LIE.L	-40.0 to 800.0	-40.0 to 999.9			
	T (CC)	1	Е С С.Н	-50 to 400	-58 to 752		
		0.1	E C C.L	-50.0 to 400.0	-58.0 to 752.0		
	R (PR)	1	r P r	0 to 1,700	32 to 3,092		
	S (PR)	1	SPr	0 to 1,700	32 to 3,092		
	DD+100 0	1	d P E.H	-100 to 400	-148 to 752		
RTD	DPLIOUT	0.1	d P E.L	-100.0 to 400.0	-148.0 to 752.0		
	CLIERO	1	C U 5.H	-50 to 200	-58 to 392		
	000012	0.1	C U 5.L	-50.0 to 200.0	-58.0 to 392.0		
	Nickel120 Ω	1	n1 12	-80 to 260	-112 to 500		

Display accuracy

• The setting range of some parameters is limited when using the decimal point display.

Input type	Using temperature	Measurement accuracy	
Thermocouple RTD	At room temperature (23°C±5 °C)	 (PV ±0.3% or ±1 °C higher one) ±1-digit •Thermocouple R (PR), S (PR) below 200 °C: (PV ±0.5% or ±3 °C higher one) ±1-digit, Over 200 °C: (PV ±0.5% or ±2 °C higher one) ±1-digit, • Thermocouple L (IC), RTD Cu50 Ω: (PV ±0.5% or ±2 °C higher one) ±1-digit 	
	Out of room temperature range	$\begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm2\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit}\\ \bullet\text{Thermocouple R (PR), 5 (PR);}\\ (\pm1.0\% \text{ or }\pm5\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit}\\ \bullet\text{Thermocouple L ((C), RTD Cu50 }\Omega;\\ (\text{PV}\pm0.5\% \text{ or }\pm3\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit}\\ \end{array}$	

• When multiple products (or more) are mounted without separation, ±1°C is added to all accuracy.

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Connections



Terminal support by model

			·	-												
Terminal No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Function Model	Con out	itrol put 1	Con out	trol out 2	Ala out	rm put	Po	wer	-	Ten sen	npera sor i	ature nput	CT inp	ut	Opt out	ion out
TR1D-14RN	Rela	у	-		Rela	ay	0		-	TC RTC)	-	-	-	-	-
TR1D-14RR	Rela	y	Rela	Relay		ay	0		-	TC RTE)	-	0		-	-
TR1D-R4RR	Rela	вy	Relay		Rela	ay	0		-	TC RTD)	-	0		Tran -mis	s sion
TR1D-T4RR	Rela	ay	Rela	Relay		ay	0		-	TC RTD)	-	0		Com -catio	imuni on
TR1D-14CN	Curr SSR	rent	-	- Relay		ау	0		-	TC RTD)	-	-	-	-	-
TR1D-14CC	Curr SSR	rent	Curr SSR	ent	Relay		0		-	TC RTE)	-	0		-	-
TR1D-R4CC	Curr SSR	rent	Curr SSR	ent	Relay		0		-	TC RTC)	-	0		Tran -mis	s sion
TR1D-T4CC	Curr SSR	rent	Curr SSR	ent	Rela	Relay			-	TC RTC		-	0		Com -catio	imuni on

Initial Display When Power is ON

When power is supplied, after all display will flash for a while, series and model name are displayed sequentially. After input sensor type will flash twice, enter into RUN mode.



Errors

Display	Description	Troubleshooting	
oPEn	Flashes if input sensor is disconnected or sensor is not connected.	Check input sensor status.	
нннн	Flashes when PV is higher than input range.	When input is within the rated	
LLLL	Flashes when PV is lower than input range.	temperature range, this display disappears.	

Installation Method

Mounting on DIN rail

• Mount the metal part with a spanner so that a large force is not applied to the body.



Attaching and Dettaching a Terminal Unit

Detaching





Attaching

Lift the lower part of the terminal unit (a) upwards by using a tool (e.g. flat-head driver).

Press the terminal unit downwards to insert.

• When disconnecting terminal unit and wiring, refer to 'Connections' to attach to right position. Failure to follow this instruction may result in fire product damage or malfunction.

Mode Setting

	[▲] key over 2 sec	\rightarrow	Display part switching	Auto	\rightarrow	
	No key input over screen protection time	÷	Screen protection	[MODE], [◀], [▲], [▼] key	÷	
RUN	[▼] + [▲] key over 3 sec	\rightarrow	Digital input key	Auto	\rightarrow	RUI
	[MODE], [◀], [▲] or [▼] key	\rightarrow	SV setting	[MODE] key or no key input over 3 sec	→	
	[MODE] key over 2 sec	\rightarrow	Parameter group	[MODE] key over 2 sec	\rightarrow	
	[◀] + [▲] + [▼] key over 3 sec	\rightarrow	Parameter reset	Auto	\rightarrow	

Parameter Setting

- · Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the descriptions of each item.
- Select group by $[\blacktriangle], [\blacktriangledown]$ key and press [MODE] key to parameter setting mode in parameter group setting mode.
- [MODE] key: Move to next item after saving / Return to upper level with save (\geq 2 sec) $[\blacktriangleleft]$ key: Move digits / Return to the upper level without saving (\geq 2 sec) / Return to RUN mode without saving (\geq 3 sec)
- $[\blacktriangle], [\blacktriangledown]$ key: Select parameter / Change setting value
- Return to the upper level without saving when there is no key input for more than 30 seconds.
- The range in parentheses '()' is the setting range when the set value of the 'input specification' parameter is used with one decimal point.
- Recommended parameter setting sequence: Parameter 2 group \rightarrow Parameter 1 group → SV setting mode

Parameter 1 group

ParameterDisplayDefaultSetting rangeCondition1-1LockLofE oFF $Order<$	_					
1-1LockLoE LoFFOFF LOC: Lock parameter 1, 2 group + SV setting lock + SV setting lock <th>Para</th> <th>ameter</th> <th>Display</th> <th>Default</th> <th>Setting range</th> <th>Condition</th>	Para	ameter	Display	Default	Setting range	Condition
Image: 1-2Heater current monitoring $\mathcal{L} \models - R$.[CT input model] (0 to 500 A2-10/11 	1-1	Lock	LoEY	o F F	OFF LOC1: Lock parameter 2 group LOC2: Lock parameter 1, 2 group LOC3: Lock parameter 1, 2 group + SV setting lock • It is possible to check the value only in lock mode.	-
1-3Auto tuning RE σFF OFF, ON: Execution2-9 Control type: PID1-4AL1 alarm temperature RL I $I \ge 5D$ Deviation alarm: -F.S. to F.S. "C/"F Absolute value alarm: Within input specification operation' and '2-17/20 AL1/2 alarm operation' and '2-17/20 AL1/2 alarm 	1-2	Heater current monitoring	С Е - А	-	[CT input model] 0.0 to 50.0 A	2-10/11 Control output 1/2: SSR
1-4AL1 alarm temperature RL I $I \ge 5D$ Deviation alarm: -F.S. to F.S. °C/°F Absolute value alarm: Within input specification operation' and '2-17/20AL1/2 alarm operation' and '2-17/20AL1/2 alarm 	1-3	Auto tuning	ЯĿ	oFF	OFF, ON: Execution	2-9 Control type: PID
1-5AL2 alarm temperature $RL2$ $I250$ operation' and '2-17/20 AL1/2 alarm option' will automatically reset the value to the maximum or minimum 	1-4	AL1 alarm temperature	AL I	1250	Deviation alarm: -F.S. to F.S. °C/°F Absolute value alarm: Within input specification • Changing the '2-16/19 AL1/2 alarm	2-16/19 AL1/2 alarm
$ \begin{array}{ c c c c c } \hline Heating & H-P & ID \\ \mbox{integral time} & H-I & 24D \\ \hline 1.7 & Heating & Hat & H-d & 49 \\ \hline 1.8 & derivative & H-d & 49 \\ \mbox{time} & H-d & 49 \\ \mbox{time} & H-d & 49 \\ \hline 1.8 & derivative & H-d & 49 \\ \hline 1.8 & derivative & H-d & 49 \\ \mbox{time} & 0 & (OFF) to 9999 sec & - \\ \hline 1.8 & derivative & H-d & 49 \\ \hline 1.9 & proportional & E-P & ID \\ \mbox{band} & E-P & ID \\ \mbox{online} & E-I & 24D & 0 & (OFF) to 9999 sec & - \\ \hline 1.10 & Cooling & E-I & 24D & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 49 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & time & E-d & 49 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 49 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 49 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 49 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 5D & 0 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & derivative & E-d & 5D & 0 & 0 & (OFF) to 9999 sec & - \\ \hline 1.11 & Manual reset & rE5E & 5D & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 1.12 & Heating & HH & 5 & 2 & 1 & to 100 & (0.1 to 100.0) \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	1-5	AL2 alarm temperature	AL 2	1250	operation' and '2-17/20 AL1/2 alarm option' will automatically reset the value to the maximum or minimum that will not be output.	AM1 to AM6, HBA
1-7 Heating integral time H - I 2 4 0 0 (OFF) to 9999 sec - 1-8 derivative time H - d 4 9 0 (OFF) to 9999 sec - 1-9 proportional band $E - P$ I 0 0.1 to 9999 °C/°F - 1-10 Cooling integral time $E - I$ 2 4 0 0 (OFF) to 9999 sec - 1-10 Cooling integral time $E - I$ 2 4 0 0 (OFF) to 9999 sec - 1-11 derivative time $E - d$ 4 9 0 (OFF) to 9999 sec - 1-12 Dead band ⁰¹⁰ $d b$ $Proportional band to +Proportionalband °C/°F 2-9 Controltype: P.P.PON, ON.P 1-12 Dead band010 d b Proportional band to +Proportionalband °C/°F 2-9 Controltype: ON.ON 1-13 Manual reset r E 5 E 5 0 0.0 to 100.0% Coolingintegral time:0 1-14 Heatinghysteresis HH 95 2 1 to 100 (0.1 to 100.0) °C/°F 2-9 Controltype: ONOF&2-9 Controltype: ONOF&2-9 Control 1-15 Heating OFF H.o 5 E 0 0 to 100 (0.0 to 100.0) °C/°F 2-9 Controltype: ONOF&2-9 Controltype: ONOF $	1-6	Heating proportional band	H - P	10	0.1 to 999.9 °C/°F	-
1-8Heating derivative timeH - dY90 (OFF) to 9999 sec-1-0Cooling band $\mathcal{L} - \mathcal{P}$ $\mathcal{I} \square$ 0.1 to 9999 °C/°F-1-10Cooling integral time $\mathcal{L} - \mathcal{I}$ $\mathcal{2} + \mathcal{Q}$ 0 (OFF) to 9999 sec-1-10Cooling integral time $\mathcal{L} - \mathcal{I}$ $\mathcal{2} + \mathcal{Q}$ 0 (OFF) to 9999 sec-1-11derivative time $\mathcal{L} - d$ $\mathcal{4} + \mathcal{4}$ $\mathcal{4} - \mathcal{4}$ $\mathcal{4} - \mathcal{4}$ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-12Dead band ⁰¹ $\mathcal{4} - \mathcal{4}$ 1-13Manual reset $\mathbf{r} \in 5 + 5$ $5 \square 0$ $\mathcal{4} - \mathcal{4}$ $\mathcal{4} - \mathcal{4}$	1-7	Heating integral time	H - I	240	0 (OFF) to 9999 sec	-
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1-8	Heating derivative time	Н- d	49	0 (OFF) to 9999 sec	-
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1-9	Cooling proportional band	C - P	10	0.1 to 9999 °C/°F	-
$\begin{array}{c c} \mbox{Cooling} \\ \mbox{Index} \\ Inde$	1-10	Cooling integral time	E - I	240	0 (OFF) to 9999 sec	-
1-12 Dead band ⁰¹⁾ db db $e^{-Proportional band to +Proportional band to the type: ONON 1-13 Manual reset r \in S \in S = 0$	1-11	Cooling derivative time	C - d	49	0 (OFF) to 9999 sec	-
	1-12	Dead band ⁰¹⁾	dЪ	٥	-Proportional band to +Proportional band °C/°F	2-9 Control type: P.P, P.ON, ON.P
1-13 Manual reset $r \in 5 \vdash$ 50 0.0 to 100.0% 1-7/10 Heating/Cooling integral time: 0 1-14 Heating hysteresis HH 95 2 1 to 100 (0.1 to 100.0) °C/°F 2-9 Control 1-15 Heating OFF offset Ho 5 t 0 0 to 100 (0.0 to 100.0) °C/°F 2-9 Control 1-16 Cooling hysteresis $\mathcal{L}H 95$ 2 1 to 100 (0.1 to 100.0) °C/°F 2-8 Control output mode 1-16 Cooling OFF hysteresis $\mathcal{L}H 95$ 2 1 to 100 (0.1 to 100.0) °C/°F 2-8 Control output mode 1-17 Cooling OFF offset $\mathcal{L} \circ 5 \vdash$ \mathcal{D} 0 to 100 (0.0 to 100.0) °C/°F 2-8 Control output mode					-999 to 999 (-199.9 to 999.9) °C/°F	2-9 Control type: ON.ON
1-14 Heating hysteresis HH ¥5 2 1 to 100 (0.1 to 100.0) °C/°F 2-9 Control type: ONOF 1-15 Heating OFF offset Ho 5 Ł D 0 to 100 (0.0 to 100.0) °C/°F 2-9 Control type: ONOF & 1-16 Cooling hysteresis E.H ¥5 Z 1 to 100 (0.1 to 100.0) °C/°F 2-8 Control output mode 1-17 Cooling OFF offset E.o 5 Ł D 0 to 100 (0.0 to 100.0) °C/°F 200	1-13	Manual reset	rESE	50	0.0 to 100.0%	1-7/10 Heating/ Cooling integral time: 0
1-15 Heating OFF offset H.o 5 Ł I 0 to 100 (0.0 to 100.0) °C/°F type: ONOF & 1-16 Cooling hysteresis C.H 95 Z 1 to 100 (0.1 to 100.0) °C/°F 2-8 Control output mode 1-17 Cooling OFF offset C.o 5 Ł I 0 to 100 (0.0 to 100.0) °C/°F 20	1-14	Heating hysteresis	н.н у 5	5	1 to 100 (0.1 to 100.0) °C/°F	2-9 Control
1-16 Cooling hysteresis E.H ¥ 5 Z 1 to 100 (0.1 to 100.0) °C/°F 2-8 Control output mode 1-17 Cooling OFF offset E.o 5 Ł D 0 to 100 (0.0 to 100.0) °C/°F 200	1-15	Heating OFF offset	H.o 5 E	٥	0 to 100 (0.0 to 100.0) °C/°F	type: ONOF
1-17 Cooling OFF C.o.5 L D 0 to 100 (0.0 to 100.0) °C/°F	1-16	Cooling hysteresis	С.Н У 5	5	1 to 100 (0.1 to 100.0) °C/°F	2-8 Control output mode
	1-17	Cooling OFF offset	E.o 5 E	٥	0 to 100 (0.0 to 100.0) °C/°F	

01) When set to the + value, the dead band is formed based on SV and does not control any control. When set to the - value, the overlap band is formed based on SV, perform the heating and cooling control at the same time.

02) Parameter display following to the setting value of '2-8 Control output mode' HEAT: '1-14 & 15 Heating hysteresis & OFF offset' COOL: '1-16 & 17 Cooling hysteresis & OFF offset' H-C: '1-14 & 15 Heating hysteresis & OFF offset', '1-16 & 17 Cooling hysteresis & OFF offset'

	Parameter 2	group)		
Para	meter	Display	Default	Setting range	Condition
2-1	Input specification	In-E	E C R.H	Refer to 'Input Type and Using Range'	-
2-2	Temperature unit	Unit] ہ	°C, °F	-
2-3	Sampling period	SPL.E	50	50, 100, 250 ms	-
2-4	Input correction	1 n-b	0	-999 to 999 (-199.9 to 999.9) °C/°F	-
2-5	Input digital filter	n Hu.F	<u>U.1</u>	U.1 to 120.0 sec	-
2-0	SV low limit value	1-50	-50	I -SV < H-SV - 1-digit °C /°F	-
2-7	SV high limit value	H-5u	1500	$H-SV \ge L-SV + 1-digit °C/°F$	-
2.0	Control output			HEAT: Heating, COOL: Cooling, H-C:	
2-8	mode	0-25	H-L	Heating&Cooling	-
				PID, ONOF: ON/OFF, P.P: PID-PID*, ON.ON:	* 2-8 Control
2-9	Control type	[-ād	P.P	ON/OFF-ON/OFF*, P.ON: PID-ON/OFF*,	output mode:
2.10	Control output 1	-115-1		UN.P: UN/UFF-PID"	H-C
2-10	Control output 2	00001	EUrr	ICUITERI/SSR Output modelj	-
2 11	Control output 1	00000			
2-12	range	01.08	4-20	4-20 0-20 mA	2-10/11 Control
2-13	Control output 2	0258	' ' ' '	-20, 0-20 mA	CURR
	range	0 2			
	Heating control		2 0.0	[Relay output model]	-
2-14	cvcle	H-F		[Current/SSR output model]	2-10/11 Control
	-)		2.0	0.5 to 120.0 sec	output 1/2: SSR
			200	[Relay output model]	_
2-15	Cooling control	Г-F	L 0.0	0.5 to 120.0 sec	-
2 10	cycle		D.5	[Current/SSR output model]	2-10/11 Control
				0.5 to 120.0 sec	output 1/2: 55K
				AMO: OFF	
				AM1: Deviation high limit alarm	
				AM2: Deviation low limit alarm	
	Al 1			AM3: Deviation high, low limit alarm	
2-16	ALI alarm			alarm	-
	operation			AM5: Absolute value high limit alarm	
			0-10	AM6: Absolute value low limit alarm	
		AL-1		SBA: Sensor break alarm	
				LBA: Loop break alarm	
				HBA. Heater break alarm	
				A: Standard alarm B: Alarm latch C:	
				Standby sequence 1, D: Alarm latch and	
2-17	AL1 alarm option			sequence 1, E: Standby sequence 2, F:	-
				Alarm latch and sequence 2	
				Enter to option setting: Press [4] key in	
				2-10 AE-1 alarm operation.	2-16/17
2 10	AL1 Hystorosis	0,00		1 to 100 (0.1 to 50.0) °C (°E	AL1/2 Alarm
2=10	ALT Hysteresis		'		operation: AM1
					to AM6 or HBA
2-19	AL2 alarm			[Dual alarm output model]	2-8 Control
	operation	RL-2	8 ñ l R	Same as '2-16/17 AL1 alarm operation/	output mode:
2-20	AL2 alarm option			loption'	HEAT OF COOL
					2-16/17
2-21	AL2 hvsteresis	яг.нч	1	[Dual alarm output model]	AL1/2 Alarm
	,			1 to 100 (0.1 to 50.0) °C/°F	operation: AM1
2-22	L BA time ⁰¹⁾	1.685	п	0 to 9999 sec or auto setting ⁰²⁾	2 16/17
	EDivenine			0 to 999 (0 0 to 999 9) °C/°E or Auto setting	Al 1/2 alarm
2-23	LBA band	L 6 A.6	2		operation: LBA
	Transmission			[Transmission output model]	
2-24	output1 mode	Ro.n I	Pu	PV, SV, H-MV: Heating MV), C-MV: Cooling	
				MV	
2-25	Iransmission	FSIL	- 50	(Tenerationical and the standard)	-
	Transmission			I I ransmission output modelj Refer to 'Input Type and Using Pange'	
2-26	outout1 high limit	FSLH	1500	Refer to input type and osing hange	
				[Dual transmission output model]	
2-27	Transmission	R o. ñ 2	Pu	PV, SV, H-MV: Heating MV, C-MV: Cooling	
	outputz mode			MV	2-8 Control
2-28	Transmission	ESU	-50		output mode:
	output2 low limit	1 2 12		[Dual transmission output model]	HEAT or COOL
2-29	output? high limit	FS I.H	1200	Refer to input Type and Using Range'	
			<u> </u>	STOP: Stop control output, ALRE: Alarm	
2-30	Digital input key	91-5	5202	reset, AT: Auto tuning execution, OFF	-
					2-8 Control
				0.0 (OFF) to 100.0 (ON)	output mode:
2-31	Sensor error, MV	Er.ñu	0		HEAT or COOL
				-100 (Cooling ON) to 0.0 (OFF) to 100	2-8 Control
				(Heating ON)	H-C.
2-32	Screen protection	dSP	oFF	OFF, 1, 30, 60 min	-
2-33	Comm. protocol	PrEL	rEU	RTU: Modbus RTU, ASCI: Modbus ASCII	-
2-34	Comm. address	Rdrs	1	1 to 99	-
2-35	Comm. speed	6P5	96	48, 96, 192, 384, 576, 1152 (×100) bps	-
2-36	Comm. parity bit	Pr 2 9	nonE	None, Even, Odd	-
2-31	Comm. stop bit	568	2	1, 2 DIC	-
2-30	Comm. write	5054	<u> </u>	EN A: Enable DIS A: Disable	-

2-40 Parameter reset Init no YES, NO

2:40 Parameter reset: PTME1 TUTES, RO [10] ITES, RO [10

10 21 input spectification is changed, the settings are initialized.
102) After auto tuning, the range is set as twice of the integral time automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.
103) After auto tuning, the range is set as 10% of the proportion band automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.

Function: Alarm

888.8 Alarm Alarm operation option

Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

			• H: Alarm output hysteres
Name	Alarm operation		Description
-	-		No alarm output
Deviation high limit	OFF H ON SV PV 100°C 110°C High deviation: Set as 10°C	OFF H ON PV SV 90°C 100°C High deviation: Set as -10°C	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.
Deviation low limit	ON H OFF A PV SV 90°C 100°C Low deviation: Set as 10°C	If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON.	
Deviation high, low limit	ON TH O A PV S 90°C 100 High, Low devia	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.	
Deviation high, low limit reverse	OFF H O PV 90°C 100 High, Low devia	If deviation between PV and SV as high/low-limit is lower than set value of deviation temperature, the alarm output will be OFF.	
Absolute value high limit	OFF HON PV SV 90°C 100°C Absolute value: Set as 90°C	OFF H ON SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is higher than the absolute value, the output will be ON.
Absolute value low limit	ON H OFF PV SV 90°C 100°C Absolute value: Set as 90°C	ON H OFF	If PV is lower than the absolute value, the output will be ON.
Sensor break	-	1	It will be ON when it detects sensor disconnection.
Heater break	-		It will be ON when it detects heater disconnection.
Loop break	-		It will be ON when it detects

Name	Description	Condition of re-apply	
Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-	
Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-	
Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Daviasi	
Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second lalarm condition, alarm latch operates.	Power UN	
Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm	
Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition alarm latch operates	/ operation or change STOP to RUN mode	

Segment Table

7 Segment			11 Segment			12 Segment				16 Segment					
0	0	1	1	٥	0	1	1	٥	0	1	1	٥	0	I	1
1	1	J	J	1	1	J	J	1	1	J	J	1	1	Ū.	J
2	2	Ľ	К	2	2	ĸ	к	2	2	К	к	2	2	к	К
Э	3	L	L	Э	3	L	L	Э	3	L	L	Э	3	L	L
ч	4	ñ	М	Ч	4	М	М	Ч	4	Μ	М	Ч	4	М	М
5	5	n	N	5	5	N	N	5	5	N	N	5	5	Ν	Ν
6	6	٥	0	Б	6	0	0	Б	6	ο	0	Б	6	۵	0
Л	7	Ρ	Р	7	7	Ρ	Р	Л	7	Ρ	Р	Л	7	Ρ	Р
8	8	9	Q	8	8	۵	Q	8	8	Q	Q	8	8	Q	Q
9	9	r	R	9	9	R	R	9	9	R	R	9	9	Ŗ	R
R	A	5	S	R	А	5	S	R	А	5	S	Я	А	5	S
Ь	В	F	Т	Ь	В	F	Т	Ь	В	Ł	Т	3	В	Ţ	Т
E	С	U	U	٢	С	U	U	٢	С	U	U	٢	С	U	U
Ь	D	U	V	d	D	V	V	d	D	V	V	IJ	D	V	V
Ε	E	U.	W	Ε	Е	М	W	Ε	E	М	W	Ε	Е	н	W
F	F	5	Х	F	F	×	Х	F	F	×	Х	F	F	X	Х
G	G	Ч	Y	G	G	Ч	Y	6	G	Ч	Y	6	G	ĭ	Y
Н	Н	Ξ	Ζ	н	Н	Z	Ζ	н	Н	ž	Ζ	н	Н	2	Ζ

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