





## EL6022 | 2-channel serial interface RS422/RS485, D-sub connection

The EL6022 serial interface enables the connection of devices with two RS422/RS485 interfaces. The devices connected to the EL6022 EtherCAT Terminal communicate with the automation device via the Coupler. The active communication channel operates independently of the higher-level EtherCAT system in full duplex mode with 300 baud up to 115.2 kbaud. The RS422/RS485 interfaces guarantee high interference immunity through electrically isolated signals. The EL6022 can provide 2 x 5 V/20 mA out of the E-bus supply (electrically isolated, short-circuit-proof) for the supply of external devices.

In conjunction with the TwinCAT Virtual Serial COM Driver, the EL6022 can be used as a normal Windows COM interface.

Technical data	EL6022
Technology	D-sub, 9-pin
Data transfer channels	2
Data transfer rates	300115,200 baud; default: 9600 baud, 8 data bits, no parity and one stop bit
Interfaces	2 x RS422/RS485
Line impedance	120 Ω
Cable length	approx. 1000 m twisted pair
Providing external supply	2 x max. 5 V/20 mA, out of E-Bus supply, short-circuit-proof
Power supply	via the E-bus
Distributed clocks	-
Electrical isolation	500 V (E-bus/signal voltage)
Data buffer	864 bytes receive buffer, 128 bytes transmit buffer
Bit width in the process image	22 x 8 bit input, 22 x 8 bit output, 16 bit control, 16 bit status
Configuration	no address setting, configuration via the controller
Current consumption power contacts	-
Current consumption E-bus	typ. 270 mA
Special features	2 x 5 V/20 mA for external supply
Weight	approx. 55 g
Operating/storage temperature	-25+60 °C/-40+85 °C
Relative humidity	95 %, no condensation
Vibration/shock resistance	conforms to EN 60068-2-6/EN 60068-2-27
EMC immunity/emission	conforms to EN 61000-6-2/EN 61000-6-4
Protect. class/installation pos.	IP 20/variable
Approvals	CE, UL, Ex

Accessories	
TS6360	license for using the TwinCAT Virtual Serial COM Driver for Windows and Windows CE platforms

System

RS485

For further RS485 products please see the system overview.

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