

#### **Features**

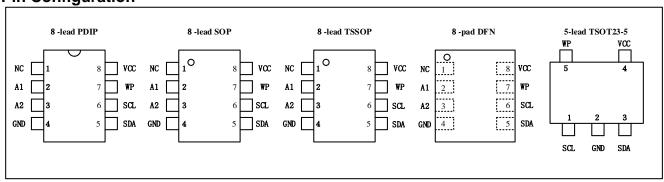
- Compatible with all I<sup>2</sup>C bidirectional data transfer protocol
- Memory array:
  - 4 Kbits (512bytes) of EEPROM
  - Page size: 16 bytes
- Single supply voltage and high speed:
  - 1MHZ
- Random and sequential Read modes
- Write:
  - Byte Write within 3 ms
  - Page Write within 3 ms

### **Description**

• The BL24C04F provides 2048 bits of serial • The device is optimized for use in many industrial electrically erasable and programmable read-only memory (EEPROM), organized as 256 words of 8 bits each.

- Partial Page Writes Allowed
- Write Protect Pin for Hardware Data Protection
- Schmitt Trigger, Filtered Inputs for Noise Suppression
- High-reliability
  - Endurance: 1 Million Write Cycles
  - Data Retention: 100 Years
- Enhanced ESD/Latch-up protection
  - HBM 6000V
- 8-lead PDIP/SOP/TSSOP/ UDFN and TSOT23-5packages
- and commercial applications where low-power and low-voltage operation are essential.

## **Pin Configuration**





#### **Pin Descriptions**

Pin Name	Type	Functions
A1-A2	Ι	Address Inputs
SDA	I/0	Serial Data
SCL	I	Serial Clock Input
WP	I	Write Protect
GND	Р	Ground
Vcc	Р	Power Supply

## Block Diagram

Table 1

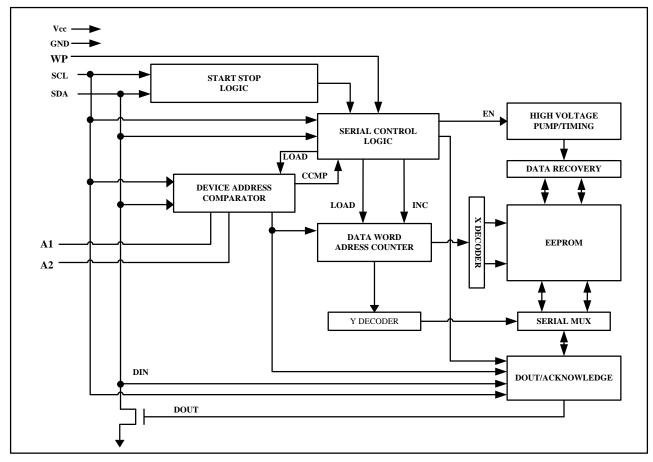


Figure 1

DEVICE/PAGE ADDRESSES (A2, A1 and A0): The A2 and A1 pins are device address inputs that are hard wire for the BL24C04F. Four 2K devices may be addressed on a single bus system (device addressing is discussed in detail under the Device Addressing section).

SERIAL DATA (SDA): The SDA pin is bi-directional for serial data transfer. This pin is open-drain driven and may be wire-ORed with any number of other open-drain or open- collector devices.

SERIAL CLOCK (SCL): The SCL input is used to positive edge clock data into each EEPROM device and negative edge clock data out of each device.

WRITE PROTECT (WP): The BL24C04F has a Write Protect pin that provides hardware data protection. The Write Protect pin allows normal read/write operations when connected to ground (GND). When the Write Protection pin is connected to Vcc, the write protection feature is enabled and operates as shown in the following **Table 2**.



WP Pin Status	BL24C04F				
At VCC	Full(4K)Array				
At GND	Normal Read/Write Operations				

Table 2

## **Functional Description**

## 1. Memory Organization

BL24C04F, 4K SERIAL EEPROM: Internally organized with 32 pages of 16 bytes each, the 4K requires a 9-bit data word address for random word addressing.

#### 2. Device Operation

CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see **Figure 2**). Data changes during SCL high periods will indicate a start or stop condition as defined below.

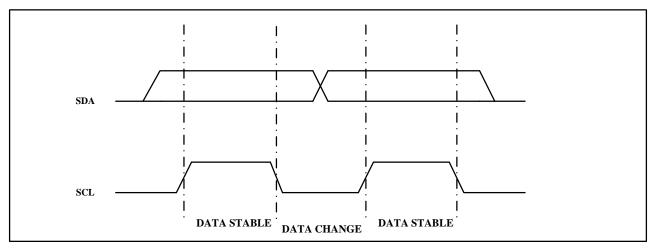


Figure 2. Data Validity

START CONDITION: A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see **Figure 3**).

STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see **Figure 3**).

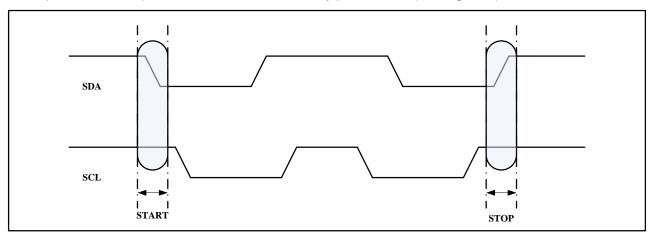


Figure 3. Start and Stop Definition



ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The EEPROM sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

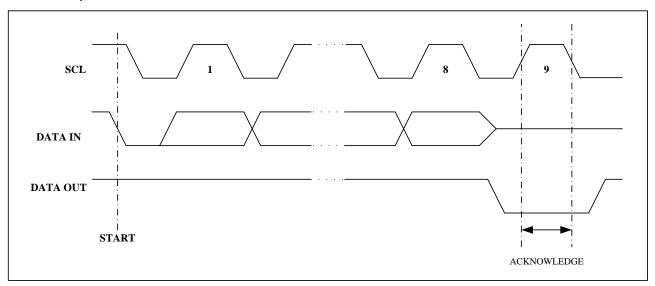


Figure 4. Output Acknowledge

STANDBY MODE: The BL24C04F features a low-power standby mode which is enabled: (a) upon power-up and (b) after the receipt of the STOP bit and the completion of any internal operations.

MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps:

- 1. Clock up to 9 cycles.
- 2. Lock SDA high in each cycle while SCL is high.
- 3. Create a start condition.



#### 3. Device Addressing

The 4K EEPROM devices all require an 8-bit device address word following a start condition to enable the chip for a read or write operation (see **Figure 5**)

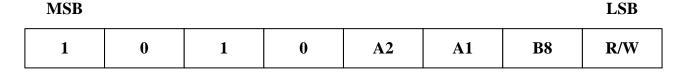


Figure 5. Device Address

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits as shown. This is common to all the Serial EEPROM devices.

The 4K EEPROM uses A2 and A1 device address bits to allow as much as for devices on the same bus. These 2 bits must be compared to their corresponding hardwired input pins. The A2 and A1 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are allowed to float.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low.

Upon a compare of the device address, the EEPROM will output a "0". If a compare is not made, the chip will return to a standby state.

DATA SECURITY: The BL24C04F has a hardware data protection scheme that allows the user to write protect the entire memory when the WP pin is at VCC.

#### 4. Write Operations

BYTE WRITE: A write operation requires an 9-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the EEPROM will again respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the EEPROM will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, tWR, to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see **Figure 7**).

MSB							LSB
1	0	1	0	A2	A1	B8	R/W
B7	В6	B5	B4	В3	B2	B1	В0

Figure 6. ADDRESS

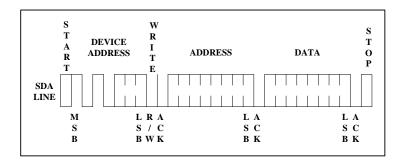


Figure 7. Byte Write



PAGE WRITE: The 4K EEPROM is capable of a 16-byte page write. A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit up to seven more data words. The EEPROM will respond with a "0" after each data word received. The microcontroller must terminate the page write sequence with a stop condition (see **Figure 8**).

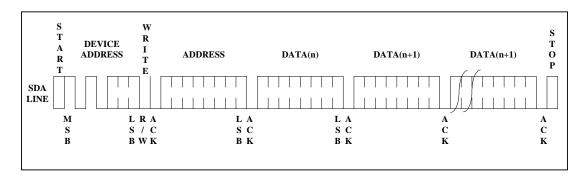


Figure 8. Page Write

The data word address lower three bits are internally incremented following the receipt of each data word. The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than eight data words are transmitted to the EEPROM, the data word address will "roll over" and previous data will be overwritten.

ACKNOWLEDGE POLLING: Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write sequence to continue.



#### 5. Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page. The address "roll over" during write is from the last byte of the current page to the first byte of the same page. Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 9).

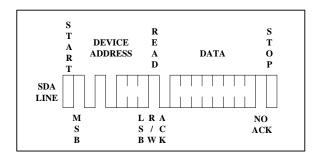


Figure 9. Current Address Read

RANDOM READ: A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a current address read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see **Figure 10**)

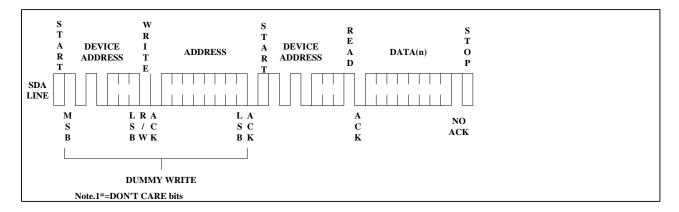


Figure 10. Random Read



SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see **Figure 11**).

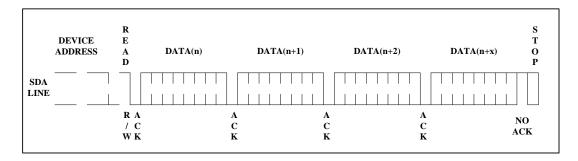


Figure 11. Sequential Read



#### **Electrical Characteristics**

Absolute Maximum Stress Ratings:

•	DC Supply Voltage	0.3V to +6.5V
•	Input / Output Voltage	0.3V to VCC+0.3V
•	Operating Ambient Temperature	40°C to +85°C
•	Storage Temperature	65℃ to +150℃
•	Electrostatic pulse (Human Body model)	6000V

#### Comments:

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

#### **DC Electrical Characteristics**

Applicable over recommended operating range from:  $TA = -40^{\circ}C$  to  $+85^{\circ}C$ , VCC = +1.7V to +5.5V (unless otherwise noted)

Parameter	Symbol	Min	Тур	Max	Unit	Condition
Supply Voltage	Vcc1	1.7	-	5.5	V	@400KHz
Supply Voltage	Vcc2	2.5	-	5.5	V	@1MHz
Supply Current VCC=5.0V	Icc1	-	0.14	0.3	mA	READ at 400KHZ
Supply Current VCC=5.0V	Icc2	-	0.28	0.5	mA	WRITE at 400KHZ
Supply Current VCC=5.0V	I <sub>SB1</sub>	-	0.03	0.5	μΑ	VIN=Vcc or Vss
Input Leakage Current	I <sub>L1</sub>	-	0.10	1.0	μΑ	Vin=Vcc or Vss
Output Leakage Current	Іьо	-	0.05	1.0	μΑ	Vout=Vcc or Vss
Input Low Level	VIL1	-0.3	-	Vcc <b>x</b> 0.3	V	Vcc=1.7V to 5.5V
Input High Level	VIH1	Vcc×0.7	-	Vcc+0.3	V	Vcc=1.7V to 5.5V
Output Low Level VCC=1.7V	V <sub>OL1</sub>	-	-	0.2	V	IoL=0.15mA
Output Low Level VCC=5.0V	V <sub>OL2</sub>	-	-	0.4	V	IoL=3.0mA

Table 3

## Pin Capacitance

Applicable over recommended operating range from TA = 25°C, f = 1.0 MHz, VCC = +1.7V

Parameter	Symbol	Min	Тур	Max	Unit	Condition
Input/Output Capacitance(SDA)	Cı⁄o	-	-	8	pF	Vio=0V
Input Capacitance(A0,A1,A2,SCL)	CIN	-	-	6	pF	V <sub>IN</sub> =0V

Table 4



#### **AC Electrical Characteristics**

Applicable over recommended operating range from  $TA = -40^{\circ}C$  to  $+85^{\circ}C$ , VCC = +1.8V to +5.5V, CL = 1 TTL Gate and 100 pF (unless otherwise noted)

Doromotor	Symbol	1.7V	′≤Vcc <	2.5V	2.5V	′≤Vcc <	5.5V	Units
Parameter	Symbol	Min	Тур	Max	Min	Тур	Max	Units
Clock Frequency,SCL	fscL	-	-	400	-	-	1000	kHz
Clock Pulse Width Low	<b>t</b> LOW	1.3	-	-	0.5	-	-	μs
Clock Pulse Width High	<b>t</b> HIGH	0.6	-	-	0.26	-	-	μs
Noise Suppression Time	tı	-	-	50	-	-	50	ns
Clock Low to Data Out Valid	<b>t</b> AA	-	-	0.9	-	-	0.45	μs
Time the bus must be free before a new transmission can start	<b>t</b> buf	1.3	-	-	0.5	-	-	μs
Start Hold Time	thd:sta	0.6	-	-	0.25	-	-	μs
Start Setup Time	tsu:sta	0.6	-	-	0.25	-	-	μs
Data In Hold Time	thd:dat	0	-	-	0	-	-	μs
Data in Setup Time	tsu:dat	100	-	-	100	-	-	ns
Input Rise Time(1)	<b>t</b> R	-	-	0.3	-	-	0.12	μs
Input Fall Time(1)	t⊦	-	-	0.3	-	-	0.12	μs
Stop Setup Time	tsu:sto	0.6	-	-	0.25	-	-	μs
Data Out Hold Time	tон	50	-	-	50	-	-	ns
Write Cycle Time	<b>tw</b> R	-	1.9	3	-	1.9	3	ms
5.0V,25°C,Byte Mode(1)	Endurance	1M	-	-	1M	-	-	Write Cycle

#### Table 5

#### Notes:

1. This parameter is characterized and is not 100% tested.

2. AC measurement conditions: RL (connects to VCC): 1.3 k

Input pulse voltages: 0.3 VCC to 0.7 VCC

Input rise and fall time: 50 ns

Input and output timing reference voltages: 0.5 VCC

The value of RL should be concerned according to the actual loading on the user's system.



#### **Bus Timing**

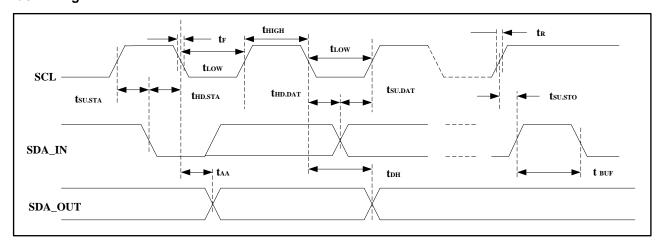


Figure 12. SCL: Serial Clock, SDA: Serial Data I/O

## **Write Cycle Timing**

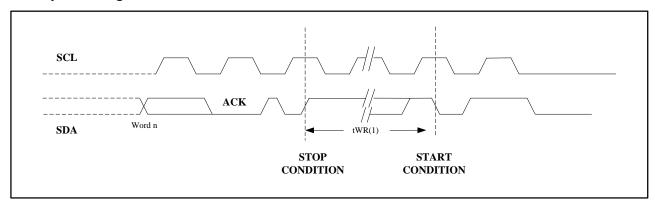


Figure 13. SCL: Serial Clock, SDA: Serial Data I/O



## **Package Information**

## **PDIP Outline Dimensions**

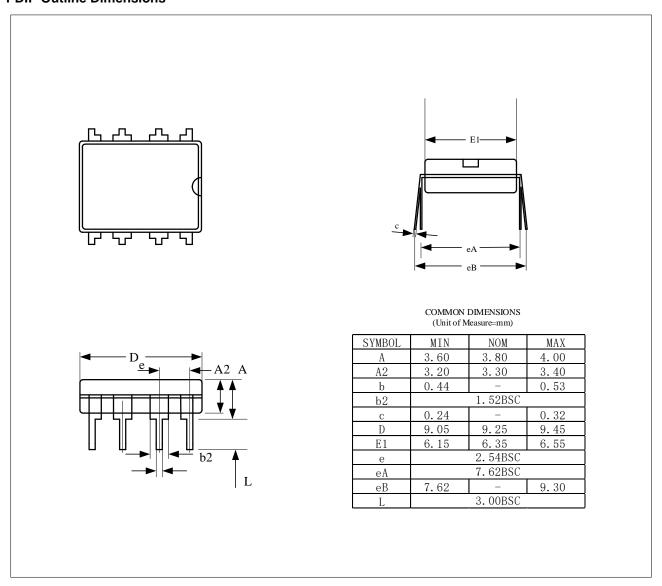


Figure 14

## SOP

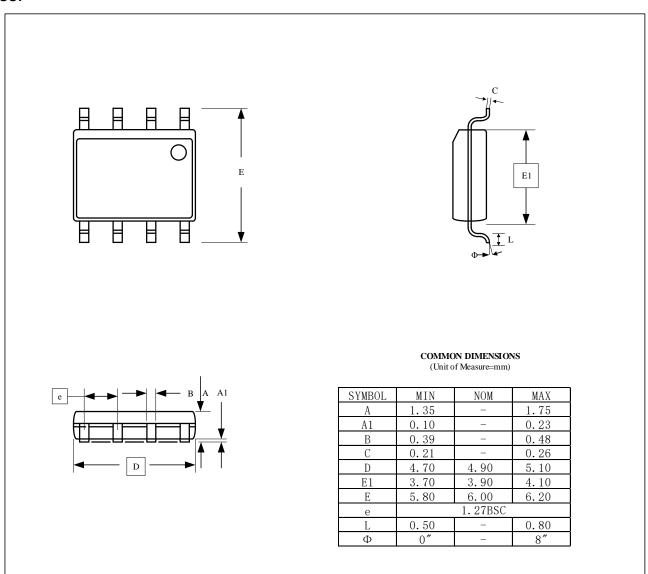


Figure 15



## TSSOP

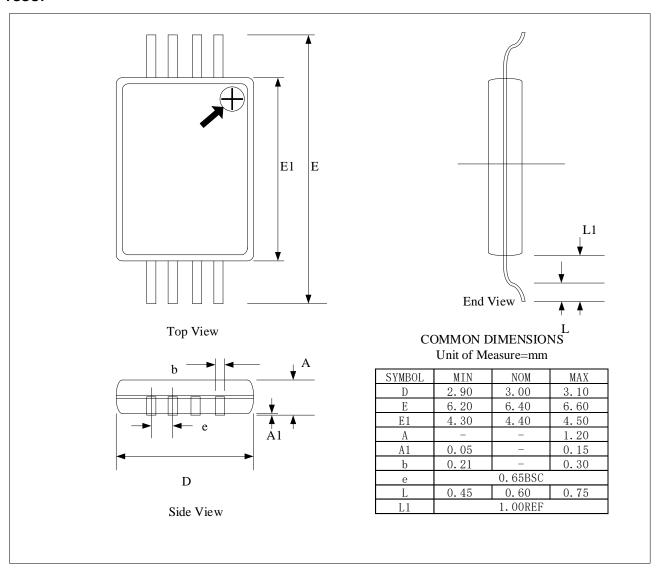


Figure 16

## UDFN

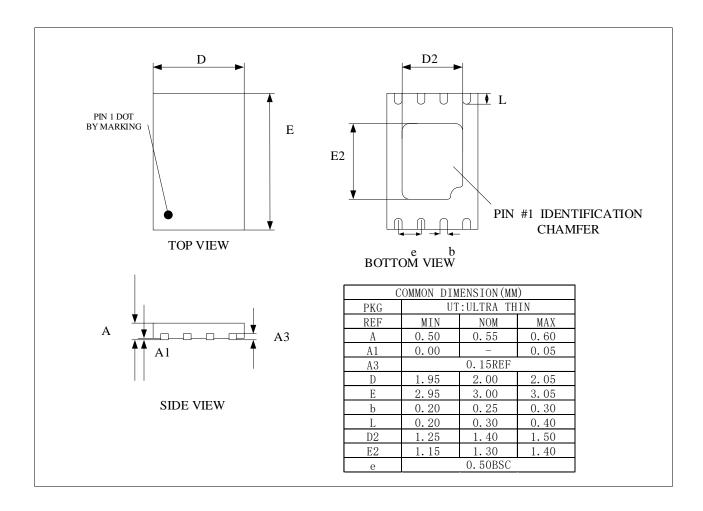


Figure 17



#### **TSOT23-5**

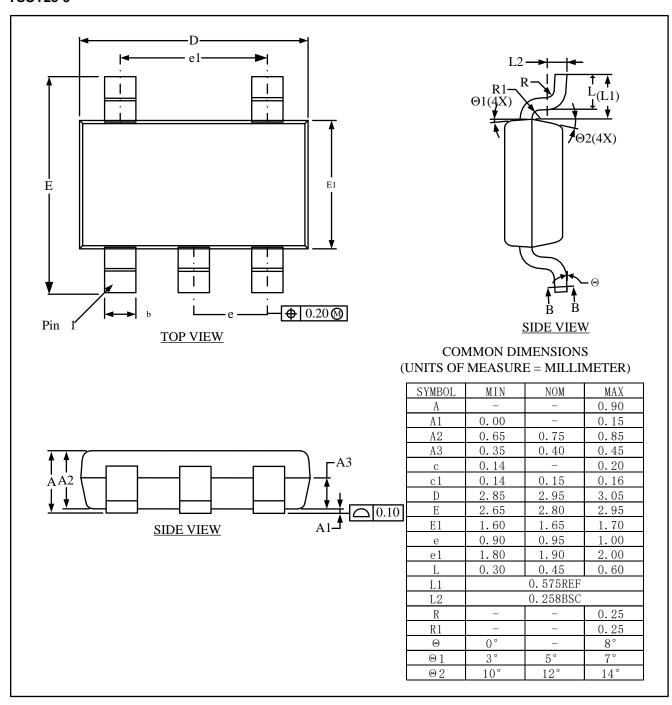


Figure 18



# Marking Diagram

PDIP

BL24C04F YYWW#ZZ SSSSSP

YY: year

WW:week

ZZ: assembly house

SSSSS: Lot ID

SOP

BL24C04F SSSSSP

SSSSS: Lot ID

**TSSOP** 

○ BL24C04F SSSSS

SSSSS: Lot ID

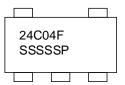
**UDFN** 



YY: year

WW:week

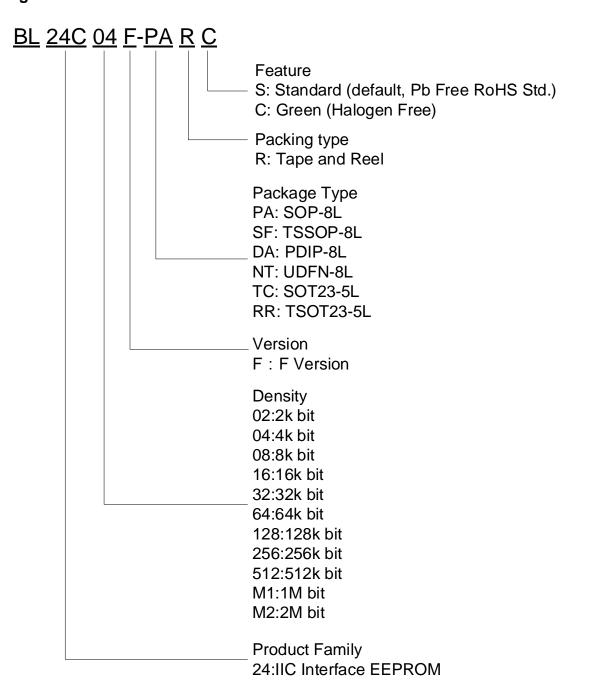
**TSOT23-5** 



SSSSS: Lot ID



## **Ordering Information**



Device	Package	Shipping (Qty/Packing)
BL24C04F	SOP8	2500/Tape &Reel
BL24C04F	TSSOP8L	3000/Tape &Reel
BL24C04F	UDFN	3000/Tape &Reel
BL24C04F	TSOT23-5	3000/Tape &Reel



## **Revision history**

3/7/2017
9/7/2018
5/23/2019
6/5/2019

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NV24M01MUW3VTBG S-93A66BD0A-K8T2U3 BR25H128NUX-5ACTR BR24G512FVT-5AE2 CAT24C512C8UTR GT24C04A-2ZLITR M24C64-DFCT6TPK M95080-RMC6TG AT24C01D-MAHM-T AT24C08D-MAHM-T BR24C21FJ-E2 BR24G02FVJ-3GTE2
BR24L16FJ-WE2 BR24L16FVJ-WE2 BR24S16FJ-WE2 BR24S256F-WE2 BR93L56RFV-WE2 BR93L66F-WE2 BR93L76RFV-WE2
CAT24C16C5ATR CAT24C64C4CTR 24LC024T-I/ST AT93C46DY6-YH-T 93LC66BT-I/ST BR24T02FVT-WSGE2 24CS08-SSHM-T
24LC08BT-I/ST 24LC512T-ESM BR24L16F-WE2 M93C66-RMC6TG 24AA16T-I/CS16K M35B32-WMN6TP M24M02-DRCS6TPK
M24C32-FDW6TP M24C64-FMC6TG