

Features

- Hybrid technology
- Highly resistant to vibration/shock
- Highly resistant to fluid/dust ingress
- Robust design for industrial applications
- Highly repeatable
- RoHS compliant*

HES38U-RS485 Hybrid Position Sensor

Electrical Characteristics (@ 25 °C)

VDD Supply Voltage	10 to 30 V DC
Supply Current	44 mA max.
Output Signal (Single)	RS-485
Independent Linearity	±0.1 % max.
Hysteresis	0.3 % VDD max.
Effective Electrical Angle	
Output Resolution	163,840
Baud Rate	19 200

Environmental Characteristics

Storage Temperature......-40 °C to +125 °C Operating Temperature...... -40 °C to +85 °C Moisture Resistance

......MIL-STD-202, Method 106 Insulation Resistance @ 500 V AC

	500 MW min.
Vibration	15 G
Shock	
IP Rating	IP 65
ESD Rating	2 kV max.

Mechanical Characteristics

Mechanical Angle	
Shaft/RPM	
Torque	

Starting & Running2.12 N-cm (3.0 oz-in.)max. Mounting

0	
2.12	2 N-cm (3.0 oz-in.)max.
Shaft Material	Stainless steel
Bearing	2 ball bearings
Rotational Life (Shaft R	evolutions) 5 million





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Asia-Pacific: Tel: +886-2 2562-4117 • Email: asiacus@bourns.com EMEA: Tel: +36 88 885 877 · Email: eurocus@bourns.com The Americas: Tel: +1-951 781-5500 • Email: americus@bourns.com www.bourns.com

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Applications

- Patient platform positioning feedback
- 3D imaging position feedback
- Pneumatic control valve position feedback
- Draw wire position sensors
- Actuator motor position feedback

HES38U-RS485 Hybrid Position Sensor



- Automated manufacturing robotics
- Electric linear actuator position sensors

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Connect the GND of the power supply with the GND of the RS-485 reader.

Serial Protocol

Model HES38 RS-485 Protocol

Maximum resolution for the Model HES38U is 163,840 bits = 027FFF HEX Baud Rate 19,200 BPS

Start frame and data length



(Continued on Next Page)

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HES38U-RS485 Hybrid Position Sensor

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Serial Protocol (Continued)

Start	Frame		Data	Frame	Accumulat	End of Frame		
Неа	ader	Data Length	High Byte	Mid Byte	Low Byte	AND	OR	
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte8
Header 1	Header 2	[A]	[B]	[C]	[D]	[A]+[B]+[C]+[D]	[A]^[B]^[C]^[D]	END
0XAB	0XCD	0X04	0X00 to 0X02	0X00 to 0X7F	0X00 to 0XFF	AND DATA	OR DATA	0X3D

The position data is contained within bytes B, C, and D. Together, this data makes up a 24-bit packet referred to as DATA24 which could be a valid angle or an error condition. The meaning is distinguished by the MSB. DATA24: Position data P [17.0], Error data E[15:0].

DATA24 Position Data Structure

	Most Significant Byte						Middle Byte							Least Significant Byte									
MSB							LSB	MSB							LSB	MSB							LSB
0	0	0	0	0	0	P17	P16	P15	P14	P13	P12	P11	P10	P9	P8	P7	P6	P5	P4	P3	P2	P1	P0

DATA24 Error Data Structure

	Most Significant Byte							Middle Byte							Least SIgnificant Byte								
MSB							LSB	MSB							LSB	MSB							LSB
1	0	0	0	0	0	0	0	E15	E14	E13	E12	E11	E10	E9	E8	E7	E6	E5	E4	E3	E2	E1	E0

DATA24 Error Structure

Bit	Name	Description		Bit	Name		
E0	F_ERROR	Sensor error occurred		E12	F_ADCGN		
E1	F_INTSPIREAD	Internal SPI read failure		E13	F_ADCCO		
E2	F_ADCMONITOR	ADC failure		E14	F_DACMO		
E3	F_ADCSATURA	ADC saturation (electrical failure or field too strong		E15	F_INTCHK		
E4	F_RGTOOLOW	Analog gain below trimmed threshold (likely reason: field too strong)		E16	_		
E5	F_MAGTOOLOW	Magnetic field too weak		E17	_		
E6	F_MAGTOOHIGH	Magnetic field too strong		E18	_		
E7	F_RGTOOHIGH	Analog gain above trimmed threshold (likely reason: field too strong)		E19	-		
E8	F_FGCLAMP	Never occurring in serial protocol		E20	-		
E9	F_ROCLAMP	Analog chain rough offset compensation: clipping		E21	_		
E10	F_MT7V	AT7V Device supply Vdd greater than 7V					
E11	F_ADCVDD	Potentiometer ADC VDD disconnected		E23	F_SYSER		

Bit	Name	Description
E12	F_ADCGND	Potentiometer ADC GND disconnected
E13	F_ADCCON	Potentiometer ADC connection disconnected
E14	F_DACMONITOR	Never occurring in serial protocol
E15	F_INTCHKSUM	Internal checksum failure
E16	-	
E17	-	
E18	-	
E19	-	
E20	-	
E21	-	
E22	_	
E23	F_SYSERROR	Internal system error flag

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