

# BSY2-IOV2-L

# **Current Sensors**

# Description

For the electronic measurement of currents : DC, AC, pulsed, mixed, with a galvanic isolation between the primary circuit and the secondary circuit.

### Features

- Hall effect measuring principle
- Galvanic isolation between primary and secondary circuit
- Compact design for PCB mounting
- Low power consumption
- Extended measuring range  $(3 * I_{PN})$
- Insulated plastic case recognized according to UL 94-V0

### Advantages

- Easy installation
- Excellent accuracy
- ♦ No insertion losses
- Excellent performance and price
- Only one design for wide current ratings range
- High immunity against external Interference



 $I_{PN} = 50...600A$ 

 $V_{OUT} = \pm 4 V$ 

# **Industrial applications**

- AC variable speed drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Power supplies for welding applications
- Static converters for DC motor drives
- Switched-Mode Power Supplies (SMPS)

<b>TYPES OF PRODUCTS</b>				
Туре	Primary nominal current r. m. s I <sub>PN</sub> (A)	Primary current measuring range I <sub>PM</sub> (A)		
BSY2 -50IOV2-L	50	±150		
BSY2 -75IOV2-L	75	±225		
BSY2-100IOV2-L	100	±300		
BSY2-150IOV2-L	150	±450		
BSY2-200IOV2-L	200	±600		
BSY2-300IOV2-L	300	±900		
BSY2-400IOV2-L	400	±900		
BSY2-500IOV2-L	500	±900		
BSY2-600IOV2-L	600	±900		



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#### **Parameters Table**

PARAMETERS	SYMBOL	UNIT	VALUE	CONDITIONS
Electrical data				
Supply voltage(±5%) <sup>(1)</sup>	V <sub>C</sub>	V	±15	
Current consumption	I <sub>C</sub>	mA	±15	
Output voltage(Analog)	V <sub>OUT</sub>	mV	±4V±40	$@ \pm I_{PN}, R_L = 10 \text{ k}\Omega, T_A = 25^{\circ}\text{C}$
Overload capability(1ms)	I <sub>PC</sub>	At	50* I <sub>PN</sub>	
Isolation resistance	R <sub>IS</sub>	MΩ	>1000	@ 500 VDC
Output internal resistance	R <sub>OUT</sub>	Ω	100	approx
Load resistance <sup>(2)</sup>	R <sub>L</sub>	KΩ	>10	
R. m. s voltage for AC isolation test	V <sub>d</sub>	KV	3	@50Hz, 1 min
R. m. s rated voltage, safe separation	V <sub>b</sub>	V	500	
Accuracy - Dynamic perform	nance data			
Linearity <sup>(3)</sup> $(0\pm I_{PN})$	ε <sub>L</sub>	%of I <sub>PN</sub>	<±1	
Accuracy	Х	%	<±1	(a) $I_{PN}$ , $T_A = 25^{\circ}C$ (without offset)
Electrical offset voltage	V <sub>OE</sub>	mV	<±20	$@T_A = 25^{\circ}C$
Hysteresis offset voltage	V <sub>OH</sub>	mV	<±20	(a) $I_P = 0$ ; after an excursion of 1* $I_{PN}$
Temperature coefficient of $V_{\mbox{\scriptsize OE}}$	TCV <sub>OE</sub>	mV/K	<±2	@BSY2 5075IOV2-L
			<±1	@BSY2 100600IOV2-L
Temperature coefficient of $V_{\text{OUT}}$	TCV <sub>OUT</sub>	%/K	<±0.1	@% of reading
Response time	t <sub>r</sub>	μS	<3	@ 90% of I <sub>PN</sub> step
d <sub>i</sub> /d <sub>t</sub> accurately followed	$d_i/d_t$	A/µS	>50	
Frequency bandwidth (4)	BW	kHz	DC~50	@-3dB
General data				
Ambient operating temperature	T <sub>A</sub>	°C	-20+85	
Ambient storage temperature	Ts	°C	-40+105	
Mass	m	g	approx 60	

#### Notes:

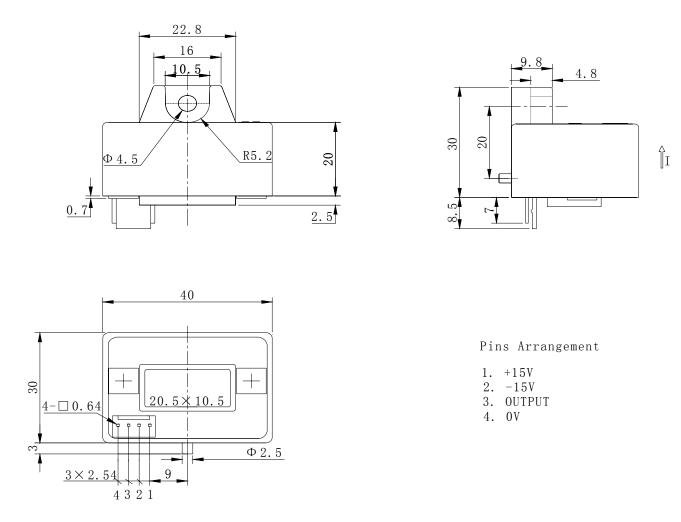
- (1) Operating at  $\pm 12V \leq V_C \leq \pm 15V$  will reduce the measuring range.
- (2) If the customer uses 1 K $\Omega$  of the load resistor, the primary current has to be limited as the nominal. To measure the full defined measuring range, the load resistor should be at minimum 10 K $\Omega$ .
- (3) Linearity data exclude the electrical offset.
- (4) Please refer to derating curves in the technical file to avoid excessive core heating at high frequency.



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#### **Current Sensors**

### **Dimensions BSY2-IOV2-L** (in mm. 1 mm = 0.0394 inch)



### ♦Instructions of use

- 1. When the test current passes through the sensors you can get the size of the output voltage. (Warning: wrong connection may lead to sensors damage.)
- 2. Based on user needs, the sensors output range can be appropriately regulated.
- 3. According to user needs, different rated input currents and output voltages of the sensors can be customized.



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