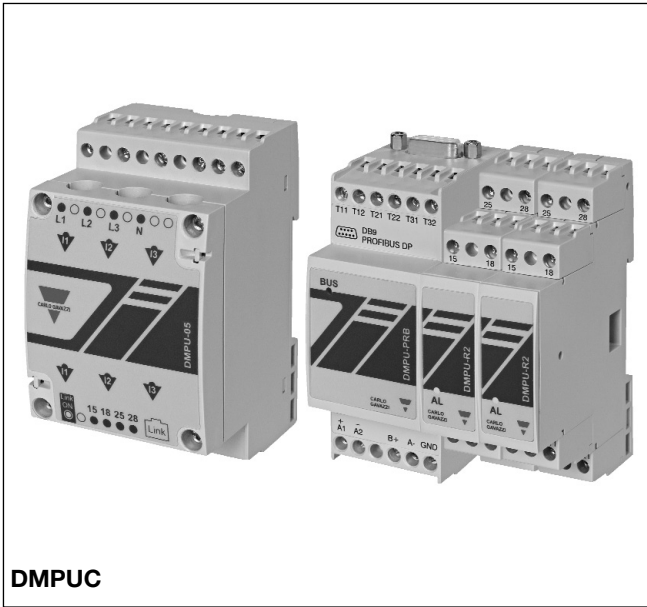


Motor Controllers DMPUC, DIN-Rail Motor Protection Unit



- Controlling motor operation
- Motor thermal protection
- Phase sequence, phase loss, unbalance, locked rotor, stall, earth fault and earth leakage protection
- Alarm set-points adjustable by the user
- TRMS measurements of distorted sine waves (voltages/currents)
- 3-phase current range up to 2000A with external current transformers or pass-through 5A
- 3-phase voltage range up to 690V
- Electrical variables monitoring
- Monitoring of operating hours, down time, number of starts
- Communication port, included in the main module
- Modular motor management system
- DIN-rail mounting (expansion module mounted side by side from main module)
- Additional I/O expansion modules
- Easy connections management and installation
- Power Supply: 24 VDC
- Event datastamping
- Variable datalogging

Ordering Key

DMPUC-MBT

Model _____
Type _____

Product Description

DMPUC is a modular electronic motor protection relay that provides protection, monitoring and metering functions for 3-phase, constant or dual speed, AC induction motors. The modular housing is for DIN-rail mounting with IP20 protection degree. The device, in its basic configuration, is able to measure the electrical motor variables (current, voltage, harmonic distortion, etc), to

control the thermal image of the motor, and also its load, operational status (start-stop, star-delta starting, 2 speeds, alarm set-point and other functions adjustable by the user), motor temperature and includes an event datalogger. The current measurement is carried out by means of 3 external current transformers, or by pass-through holes up to 5 A. Being provided with a serial

communication module, it is possible to gather all the relevant instantaneous values and transmit them to a host control system for data collection and process control. Profibus and Modbus TCP protocols are available for a high connectivity to the most used fieldbus systems. Through the optional remote display (for panel mounting) it is possible to see the instantaneous values and

status and also to modify the set-points and the values of other parameters. The whole programming of the unit is to be performed via configuration software. Additional optional modules allow the collection of additional PTC and PT100 values for coils and bearing temperature control, and additional input/outputs are used for some local on-board logic functions.

Type Selection

DMPUC-PRB	Main module + Profibus.	DMPUC-65	Currents and voltages module.
DMPUC-MBT	Main module + Modbus TCP/IP.	DMPUC-R2	I/O module.
DMPUC-05	Currents and voltages module (pass-through holes).	DMPUC-EL	Earth leakage current module

DMPUC-MBT and DMPUC-PRB



- Main module for DMPUC
- Communication port for Profibus (DMPUC-PRB) or Modbus TCP (DMPUC-MBT)
- Auxiliary dual RS485 communication port (Modbus) to display or PC
- RJ 11 connection to measurement module
- Internal bus connecting additional modules
- 3 PTC or PT100 or digital inputs
- Data logging and event data stamping
- 24 VDC $\pm 20\%$ power supply input
- Dimensions: 2-DIN module
- Protection degree: IP20

LED Specification DMPUC-MBT and DMPUC-PRB

LED Type	Status and color	Color	Meaning
Green flashing	Green fixed	Dual color	Power supply ok, configuration error.
Red fixed	Green fixed	Communication and power supply ok.	Communication error, internal bus.

Input Specification DMPUC-MBT and DMPUC-PRB

Parameter	Specification	Parameter	Specification
Digital inputs		Temperature	
Number of input	Max 3, (no common reference), including the already used thermal inputs.	Number of input	Max 3, including the already used thermal inputs.
Working modes	Each input can be configured as a switch or as a toggle.	Temperature probe	PT100 or PTC (programmable via DMPUC-PS software).
Switch	When the input is activated the value is ON; when the input is deactivated the value is OFF.	Number of wires	2-wire connection
Toggle	Each time the input goes from de-activate to activate the value changes state.	PT100	Detecting short-circuit ($<15\Omega$) and wire braking ($>10k\Omega$).
Activation mode	Each input is programmable to be considered active when the contact is closed or when it is open when used as a switch, while only at pressure when used as a button.	Range	-50° to $+850^\circ$
Type	Contact resistance or NPN.	Resolution	$1^\circ\text{C}/^\circ\text{F}$
Contact reading voltage	3.3VDC	Accuracy	$\pm(0.5\% \text{ FS})$
Contact reading current	Max. 0.45mA	PTC (3 in series)	According to EN 60947-7-8
Contact resistance	$\leq 1k\Omega$, closed contact; $\geq 20k\Omega$, open contact.	PTC	Setpoint $3.1 k\Omega$, release $1.65 k\Omega$, Detecting short-circuits ($<0.02 k\Omega$) and wire braking ($>10k\Omega$).
NPN	$V_{ON} < 1V, V_{OFF} > 2V$.	Temperature drift	$<150 \text{ ppm}/^\circ\text{C}$ at 850°C FS
Acquisition time	$\leq 200\text{ms}$.	Engineering unit	Selectable $^\circ\text{C}$ or $^\circ\text{F}$ by software (the same in all the temperature inputs).
Insulation	See the table "Insulation between inputs and outputs".	Insulation	See the table "insulation between inputs and outputs".

Communication Specification

RS485 port			
Type	Bidirectional (static and dynamic variables and parameters).	Connection	1 x RJ45 socket on the top side.
Functions	Configuring the device, modifying set-point parameter, digital virtual input and monitoring the measured variables by DMPU-PS software.	IP configuration	Fixed IP address (no DHCP), subnet mask, default gateway, port (selectable by DMPU-PS software).
Connection	1 x RJ11 socket on the bottom side (on the right) or 2-wires (to reduce the noise use a shielded cable and connect the shield to GND terminal and to the ground, in only one point).	Protocol	Modbus TCP/IP.
Address	1, selectable by DMPU-PS software.	Factory-defined values	IP address "192.168.1.2", subnet mask "255.255.255.0", default gateway "192.168.1.1", port "502".
Protocol	Modbus RTU.	Insulation	See the table "Insulation between inputs and outputs".
Factory-defined data format	Data bits "8", parity "none", stop bit "1".	Profibus port (DMPUC-PRB)	
Baud-rate	Default: 9.6k. Selectable by software: 9.6k, 19.2k, 38.4k, 115.2k.	Function	Digital virtual input and monitoring the measured variables by supervision system.
Insulation	See the table "insulation between inputs and outputs".	Connections	1 x DB-9 socket on the top side.
Note	During the connection by software (through RJ11 connector) the DMPU-HMI display must be disabled (see the display instruction to enable this mode).	Address	2-126, selectable by DMPU-PS.
Ethernet port (DMPUC-MBT)		Protocol	Profibus DP-V1.
Type	Bidirectional (static and dynamic variables and parameters).	Factory-defined address	126
Functions	Configuring the device, modifying set-point parameter, digital virtual input and monitoring the measured variables by DMPU-PS software or supervision system.	Baud-rate	9.6k, 19.2k, 45.45k, 93.75k, 187.5k, 500k, 1.5M, 3M, 6M, 12M. Auto baud rate identification.
		Telegram	Max. 255 characters.
		Physical layer	RS485
		Insulation	See the table "insulation between inputs and outputs".

Power Supply Specification

DMPUC-MBT and DMPUC-PRB	
Power supply	24VDC \pm 20% from screw terminals.
Power consumption	2W; startup peak current <1.8A.
Suggested power supply	SPM3241

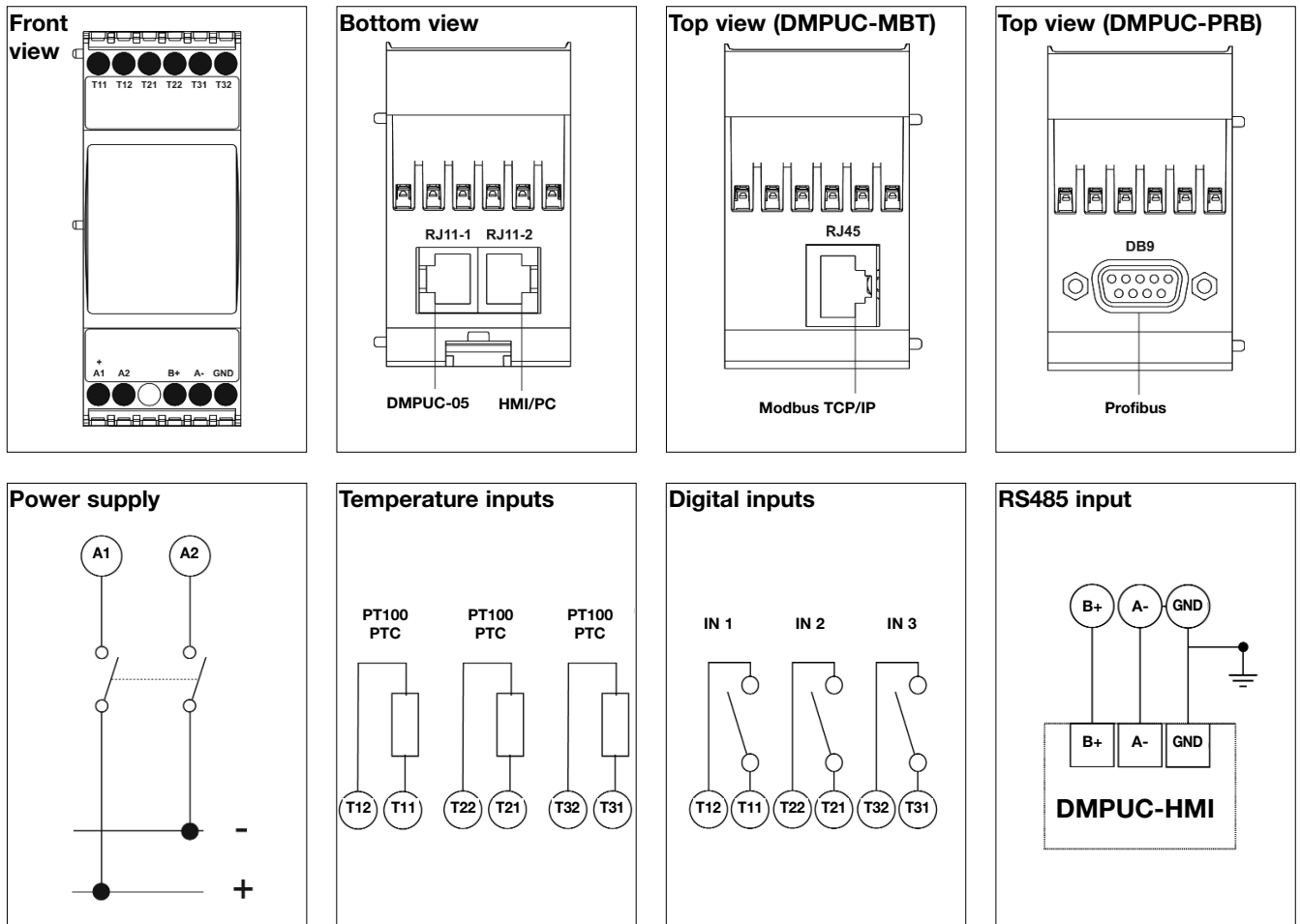
Modules Configuration

Minimal configuration	1 main module (DMPUC-MBT or DMPUC-PRB). 1 measurement module (DMPUC-05 or DMPUC-65).
Maximum configuration With DMPUC-EL	1 main module (DMPUC-MBT or DMPUC-PRB). 1 measurement module (DMPUC-05 or DMPUC-65). 9 I/O modules (DMPUC-R2). 1 earth leakage current module (DMPUC-EL).
Without DMPUC-EL	1 main module (DMPUC-MBT or DMPUC-PRB). 1 measurement module (DMPUC-05 or DMPUC-65). 10 I/O modules (DMPUC-R2).

Connections

DMPUC-MBT and DMPUC-PRB Power supply connections	Screw-type, 2 x 1.5 mm ² terminal blocks.
Input connection	Screw-type, 6 x 1.5 mm ² terminal blocks for 3 x P100/PTC (2 wires) or 3 digital inputs.
Communication connection RS485	One port with two twins terminals: 1 x RJ11 (on the right of the bottom side) for PC connection and screw type 3x1.5 mm ² Terminal box for DMPUC-HMI display connection.
Modbus TCP/IP	1 x RJ45 (DMPUC-MBT)
Profibus	1 x DB-9 (DMPUC-PRB)
Measurement module connection	1 x RJ11
Screw tightening torque	0.4 Nm / 0.8 Nm (min./max.).

Wiring Diagrams DMPUC-MBT and DMPUC-PRB



DMPUC-05 and DMPUC-65



- Measures 3-phase current, 3-phase voltage with neutral
- RJ 11 connection to main module
- Pass-through version up to 5A or 65A
- 2 relay outputs
- Split core housing for 5A version
- Dimensions: 3-DIN module
- Protection degree: IP20

Input Specification DMPUC-05 and DMPUC-65

Measurement system	3-phases (with or without neutral). Aron connection: only with DMPUC-05 and proper wiring.	Power factor	$\pm[0.002+1.5\%(1.000 - \text{"PF RDG"})]$
Working frequency	45 to 65 Hz	Reactive power	$\pm(2\% \text{ FS})$
Current inputs	TRMS measurement of distorted waves. The sampling frequency is automatically calculated.	Reactive power resolution	1% FS
Connection type (DMPUC-05)	3-phase split-core pass-through.	Harmonic distortion	$\pm 1\% \text{ FS (FS=100\%)}$
(DMPUC-65)	3-phase pass-through	Active Energy	Class1
Current range (DMPUC-05)	100mA - 6A	Reactive Energy	Class2
(DMPUC-65)	600mA - 65A	Leakage current	$\pm(1\% \text{ FS})$
Hole size (DMPUC-05)	9 mm	Leakage current resolution	1mA
(DMPUC-65)	12 mm	Temperature drift	$\leq 200\text{ppm}/^\circ\text{C}$
Max selectable primary current	CT programmable from 1 to 9999.	Sampling rate	3200 samples/s @ 50Hz; 3840 samples/s @ 60Hz.
Harmonic distortion	THD, up to 32 nd harmonic.	Measurements refresh time	100ms
Voltage inputs		Measurements Method	TRMS
Voltage range	3-phase, 100 to 690 VLL ($\pm 15\%$).	Digital filter	
Max selectable voltage ratio	VT programmable from 1 to 9999.	Filter operating range	0 to 99.9% of the input electrical scale
Neutral connection	Available	Filtering coefficient	Filtering coefficient 1 to 255
Harmonic distortion	THD, up to 32 nd harmonic.	Filter action	Display, alarm, analogue and serial outputs (all the variables).
Accuracy	Relevant to control function, serial communication data (@25°C $\pm 5^\circ\text{C}$, R.H. @60%, 48 to 62 Hz).	Crest factor	≤ 3
Current	$\pm(0.5\% \text{ FS})$	Current overload	
Current resolution	0.2% FS	Continuos	DMPUC-05 6A DMPUC-65 65A
Phase-neutral voltage	$\pm(0.5\% \text{ FS})$	For 20s	DMPUC-05 40A (accuracy 5%) DMPUC-65 400A (accuracy 5%)
Phase-phase voltage	1% FS	For 500ms (DMPUC-05)	200A Max @50Hz
Voltage resolution	0.1% FS	For 10ms (DMPUC-65)	1950A Max @50Hz
Frequency	$\pm 0.1\text{Hz}$ (45 to 65Hz)	Voltage overload	
Active power	$\pm(1\% \text{ FS})$	Continuos	1.2 Un
Active power resolution	0.5% FS	For 500ms	2 Un
		Input impedance	
		Voltage input	$> 1\text{M}\Omega$

Output Specification DMPUC-05 and DPMUC-65

Digital output

Number of outputs

Type

AC1

DC12

AC15

DC13

2

SPST NO relay (NE or ND programmable by software).

5AAC @ 250VAC

5ADC @ 24VDC

1.5AAC @ 250VDC

1.5ADC @ 24VDC

Function

Activation delay

Insulation

Programmable by software

≤100ms

See the table "insulation between inputs and outputs".

Power Supply Specification

DMPUC-05 and DMPUC-65

Power supply

Power consumption

Self-power supplied through the communication bus.
2W

Connections

DMPUC-05 and DMPUC-65

Connection to main module

Output connection

Screw tightening torque

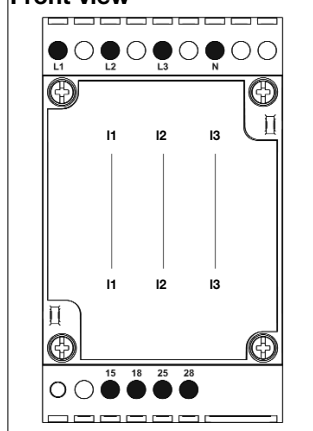
Supplied cable (60 cm), 1 x RJ11 for power supply and communication of measured data.

Screw-type, 4 x 1.5 mm² terminal blocks.

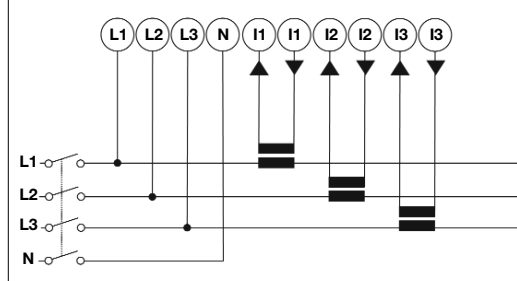
0.4 Nm / 0.8 Nm (min./max.)

Wiring Diagrams DMPUC-05 and DMPUC-65

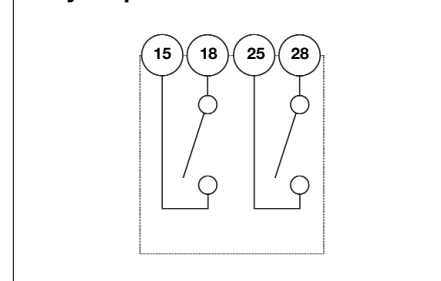
Front view



Measurement connection



Relay outputs



DMPUC-R2



- 2 PTC or PT100 or digital inputs
- 2 relay outputs
- Dimensions: 1-DIN module
- Protection degree: IP20
- Internal bus connecting main and additional modules
- 24 VDC $\pm 20\%$ power supply input via internal bus

LED Specification DMPUC-R2

LED Type	Dual color	Status and color	Communication and power supply OK.
		Green fixed	
		Red fixed	Communication error.

Input Specification DMPUC-R2

Digital inputs		Temperature	
Number of inputs	Max 2 (no common reference), including the already used thermal inputs.	Input	Max 2, including the already used thermal inputs.
Working modes	Each input can be configured as a switch or as a toggle.	Temperature probe	PT100 or PTC (programmable via DMPUC-PS software).
Switch	When the input is activated the value is ON; when the input is deactivated the value is OFF.	Number of wires	2 or 3-wire connection.
Toggle	Each time the input goes from de-activate to activate the value changes state.	PT100	Detecting short-circuits ($< 15\Omega$) and wire breaking ($> 10k\Omega$).
Activation mode	Each input is programmable to be considered active when the contact is closed or when it is open when used as a switch, while only at pressure when used as a button.	Range	-50° to $+850^{\circ}\text{C}$
Type	Voltage free contact or PNP.	Resolution	$1^{\circ}\text{C}/^{\circ}\text{F}$
Contact reading voltage	3.3VDC	Accuracy	$\pm(0.5\%)\text{FS}$
Contact reading current	Max. 0.45mA	PTC (3 in series)	According to EN 60847-7-8
Contact resistance	$\leq 1k\Omega$ closed contact $\geq 20k\Omega$ open contact	PTC	Setpoint $3.1k\Omega$, release $1.65k\Omega$. Detecting short-circuits ($< 0.02k\Omega$) and wire breaking ($> 10k\Omega$).
NPN	$V_{\text{ON}} < 1\text{V}$, $V_{\text{OFF}} > 2\text{V}$	Temperature drift	$< 150 \text{ ppm}/^{\circ}\text{C}$ at 850°C FS.
Acquisition time	$\leq 200\text{ms}$	Engineering unit	Selectable $^{\circ}\text{C}$ or $^{\circ}\text{F}$ by software (the same in all the temperature inputs).
Insulation	See the table "insulation between inputs and outputs".	Insulation	See table "insulation between inputs and outputs".

Output Specification DMPUC-R2

Digital output

Number of output

Type

AC1

AC15

DC12

2

SPST NO relay (NE or ND programmable by software).

5 AAC@250VAC

1 AAC@250VAC

5 ADC@30VDC

Function

Activation delay

Insulation

Programmable by software

<500ms

See the table "insulation between inputs and outputs".

Power Supply Specification

DMPUC-R2

Power supply

Power consumption

Self-power supplied through the communication bus.
0.8W

Connections

DMPU-R2

Connection to main module

Input-output connection

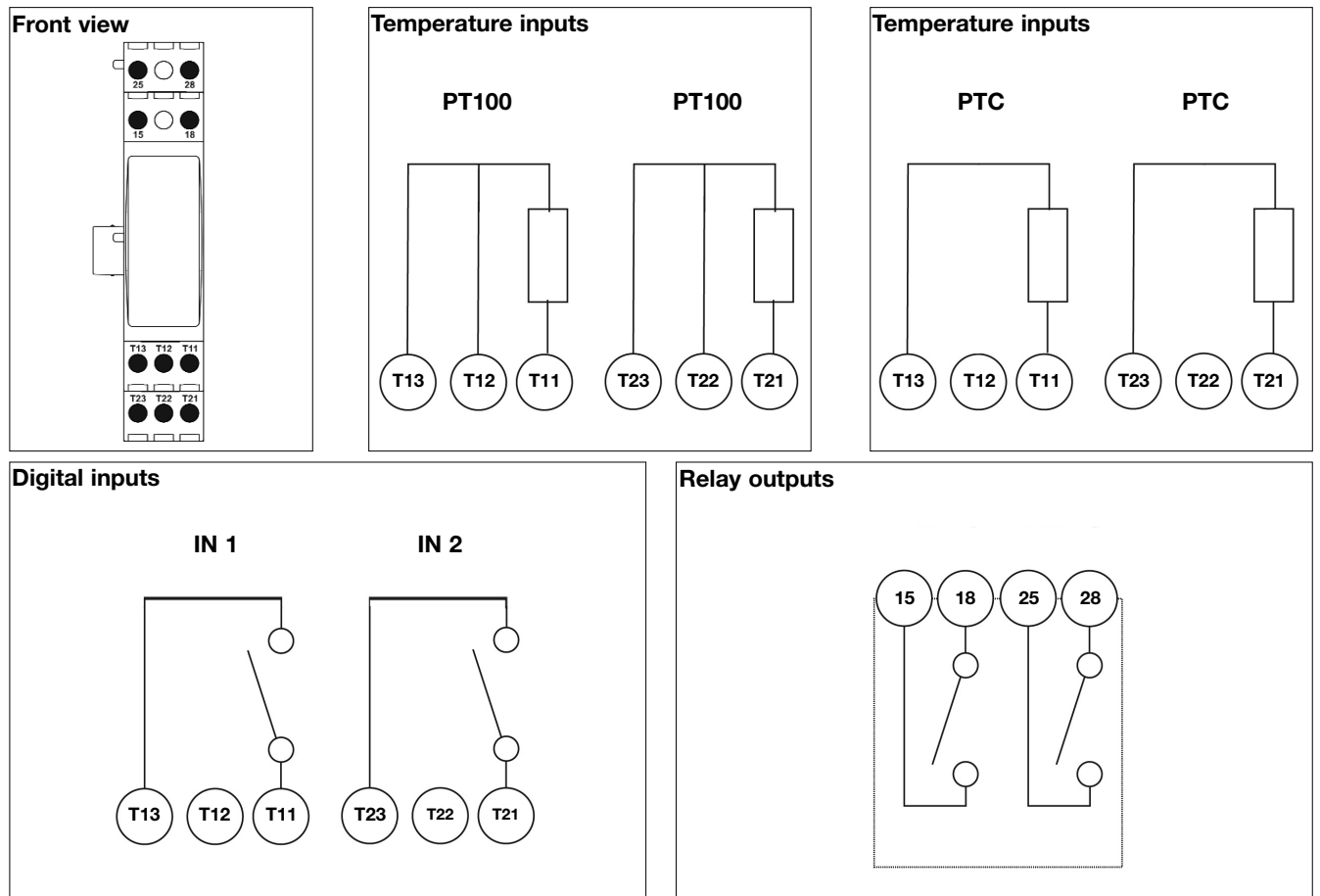
Screw tightening torque

By internal bus.

Screw-type, 4 x 1.5 mm² terminal blocks.

All outputs 0.4 Nm / 0.8 Nm (min./max.).

Wiring Diagrams DMPUC-R2



DMPUC-EL



- Core balance transformer input 1/250 to 1/1000 ratio
- 1 relay output dedicated to earth leakage alarm
- 3 digital inputs
- 0.03A to 30A set-point
- AC and A type protection (50/60Hz)
- Dimensions: 1-DIN module
- 24 VDC $\pm 20\%$ power supply input via internal bus

LED Specification DMPUC-EL

LED Type	Dual color	Status and color	
		Green fixed	Communication and power supply OK.
		Red fixed	Communication error.

Input Specification DMPUC-EL

Digital inputs		Earth current input	
Number of inputs	Max 3 (no common reference).	Earth current set points	30mA, 50mA, 100mA, 300mA, 500mA, 1A, 3A, 5A, 10A, 30A.
Working modes	Each input can be configured as a switch or as a toggle.	External toroid CT ratio	From 250 to 1000
Switch	When the input is activated the value is ON; when the input is deactivated the value is OFF.	Input impedance	51 Ω (with C-C1 terminals); 1 Ω (with C-C2 terminals).
Toggle	Each time the input goes from de-activate to activate the value changes state.	System frequency	50Hz or 60Hz; measured by measurement module. If voltage measurement is not available it must be set via programming software.
Activation mode	Each input is programmable to be considered active when the contact is closed or when it is open when used as a switch, while only at pressure when used as a button.	Time of non-intervention	60 ms
Type	Voltage free contact or NPN.	Current overload	On terminals C-C1: 50mA On terminals C-C2: 430mA On terminals C-C1: 150mA On terminals C-C2: 1A
Contact reading voltage	3.3VDC	Continuous	
Contact reading current	Max. 2mA	For 1 s	
Contact resistance	$\leq 300k\Omega$ closed contact $\geq 10k\Omega$ open contact	Accuracy	Relevant to control function, serial communication data (@25°C $\pm 5^\circ$ C R.H. $\leq 60\%$, 48 to 62 Hz).
NPN	$V_{ON} < 1V$, $V_{OFF} > 2V$	Earth leakage current	$\pm 2.5\%$ of the set-point
Acquisition time	$\leq 200ms$	Current resolution	0.1 μA with C-C1 terminals, 0.01mA with C-C2 terminals.
Activation delay	$\leq 1s$		

Output Specification DMPUC-EL

Digital output

Number of output
 Type

AC1
 AC15
 DC12

1
 SPST NO relay (NE or ND programmable by software).
 5 AAC@250VAC
 1 AAC@250VAC
 5 ADC@30VDC

Function
 Activation delay
 Insulation

Programmable by software
 <0.150ms
 4kV against inputs and internal bus.

Power Supply Specification

DMPUC-EL

Power supply
 Power consumption

Self-power supplied through the communication bus.
 0.8W

Connections

DMPUC-EL

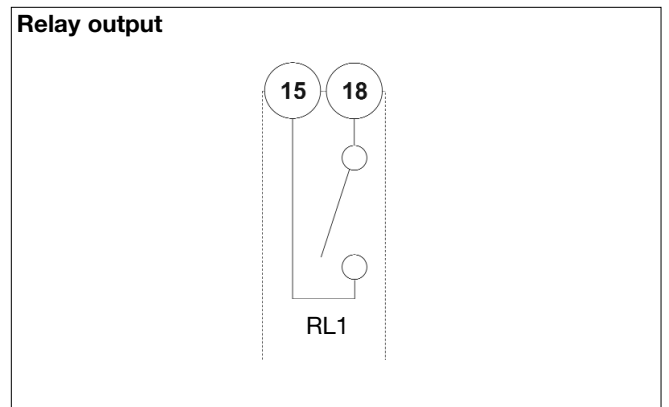
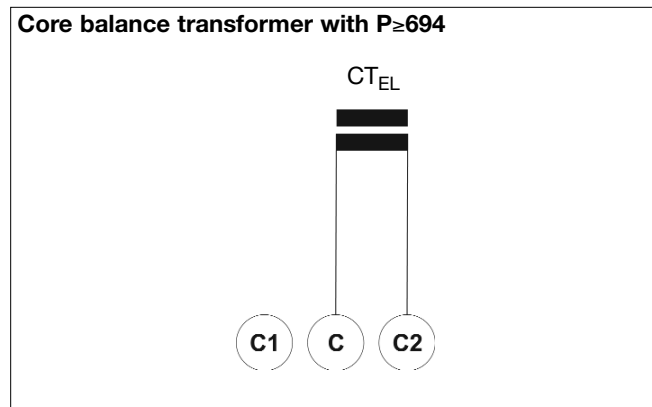
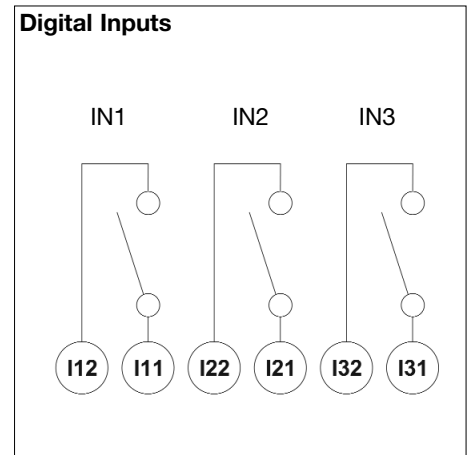
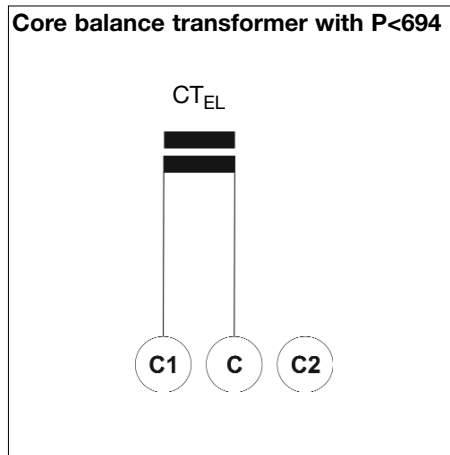
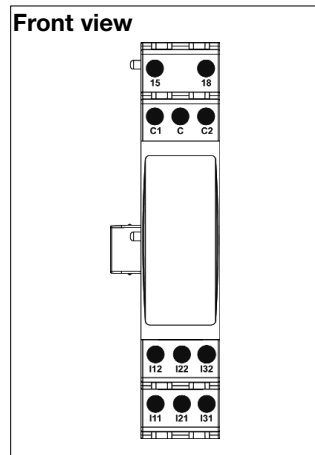
Connection to main module
 Input-output connection
 Screw tightening torque

By internal bus.
 Screw-type, 8 x 1.5 mm² terminal blocks.
 All outputs 0.4 Nm / 0.8 Nm (min./max.).

Wiring Diagrams DMPUC-EL

The wiring diagram for core balance transformer depends on the earth leakage current setpoint (I_{SEL}) and the transformer ratio (R_{CTEL}); calculate the P value according of the following formula to define when to use the wiring diagram ($P < 694$) or ($P \geq 694$).

$$P = \frac{I_{SEL}}{R_{CTEL}} \times 5 \times 10^5$$



General Specifications

Operating temperature	-25° to +55°C (-13°F to 131°F) (R.H. < 90% non-condensing @ 40°C).	Standard compliance	IEC60664, IEC61010-1
Storage temperature	-30° to +70°C (-22° to 140°F) (R.H. <90% non-condensig @ 40°C).	Safety	IEC60664, EN61010-1
Installation category	Cat. III (IEC60664, EN60664)	Thermal protection	EN62052, EN61000-6-2
Insulation (for 1 minute)	See the table "Insulation between inputs and outputs".	Earth leakage	EN60255-26, EN5002
EMC	According to EN62052-11	Approvals	IEC947
Electrostatic discharges	15kV air discharge.		IEC60947-2 parts related to the tripping characteristic of DMPUC-EL output.
Immunity to irradiated	Test with current: 10V/m from 80 to 2000MHz.		
Elettromagnetic fields	Test without current: 30V/m from 80 to 2000MHz.	Housing	
Immunity to burst	On current and voltage measuring inputs circuit: 4kV.	Dimensions (WxHxD)	
Immunity to conducted disturbances	10V/m from 150kHz to 80MHz.	DMPUC-MBT	35.5 x 90 x 63.2 mm
Surge	On current and voltage measuring inputs circuit: 4kV.	DMPUC-PRB	35.5 x 90 x 63.2 mm
Radio frequency suppression	According to CISPR 22	DMPUC-05	53.5 x 90 x 63.2 mm
		DMPUC-65	53.5 x 90 x 92 mm
		DMPUC-R2	17.5 x 90 x 63.2 mm
		DMPUC-EL	17.5 x 90 x 63.2 mm
		Material	Noryl, self-extinguishing: UL 94 V-0
		Mounting	DIN-rail
		Protection degree	IP20
		Weight	(carton box included)
		DMPUC-MBT	Approx. 172g
		DMPUC-PRB	Approx. 176g
		DMPUC-05	Approx. 280g
		DMPUC-65	Approx. 350g
		DMPUC-R2	Approx. 119g
		DMPUC-EL	Approx. 120g

Insulation Between Inputs and Outputs

Module	Type of input/output	DMPUC-05 / 65			DMPUC-PRB/MBT					DMPUC-R2				
		Measuring Input	Internal bus	Relay	Power supply	RS485 port	Profibus	Ethernet	Digital Input/Temperature	Internal bus	Digital Input/Temperature	Relay	Internal bus	
DMPUC-05 / 65	Measuring input	-	2.7kV	4kV	2.7kV	2.7kV	2.7kV	2.7kV	2.7kV	2.7kV	2.7kV	4kV	2.7kV	
	Internal bus	2.7kV	-	4kV	0V	0.5kV	0.5kV	0.5kV	0V	0V	0V	4kV	0V	
	Static output	4kV	4kV	-	4kV	4kV	4kV	4kV	4kV	4kV	4kV	4kV	4kV	
DMPUC-PRB/MBT	Power supply	2.7kV	0V	4kV	-	0.5kV	0.5kV	0.5kV	0V	0V	0V	4kV	0V	
	RS485 port	2.7kV	0.5kV	4kV	0.5kV	-	0V	0.5kV	0.5kV	0.5kV	0.5kV	4kV	0.5kV	
	Conn	Profibus	2.7kV	0.5kV	4kV	0.5kV	0V	-	-	0.5kV	0.5kV	0.5kV	4kV	0.5kV
		Ethernet	2.7kV	0.5kV	4kV	0.5kV	0.5kV	-	-	0.5kV	0.5kV	0.5kV	4kV	0.5kV
	Digital Input/Temperature	2.7kV	0V	4kV	0V	0.5kV	0.5kV	0.5kV	-	0V	0V	4kV	0V	
	Internal bus	2.7kV	0V	4kV	0V	0.5kV	0.5kV	0.5kV	0V	-	0V	4kV	0V	
DMPUC-R2	Digital Input/Temperature	2.7kV	0V	4kV	0V	0.5kV	0.5kV	0.5kV	0V	0V	-	4kV	0V	
	Relay	4kV	4kV	4kV	4kV	4kV	4kV	4kV	4kV	4kV	4kV	-	4kV	
	Internal bus	2.7kV	0V	4kV	0V	0.5kV	0.5kV	0.5kV	0V	0V	0V	4kV	-	

Functions Description (cont.)

Block management		Each variable defined as "Block" in the table "Variable List" is associated with a monitoring variable function. This function defines the ON or OFF block status. Each block can be connected to each other if the function depends on other block status. The function parameters are set through the DPMU-PS software configuration. Up to 32 blocks defined as "Block status" are available.	ANSI64	Measures the vector sum of the three phase current (neutral isn't present). The sum is earth fault current.
			ANSI66 _{SH}	Monitors that the number of starts during the last set time period is lower than max starts set point.
			ANSI66 _{MTBS}	Monitors the time since previous start.
			ANSI66 _{MTFLS}	Monitors the time since previous stop.
			ANSI64EL	Monitors if the earth leakage current is above the set-point during a set-point time.
Monitoring functions				
Input				
	Digital input	Monitors the contact or PTC status. Each input is programmable to be considered active when the contact is closed or when it is open when used as a switch, while only at pressure when used as a button.	ANSI48	Prevents the locked rotor condition at motor start by monitoring the current.
			ANSI51LR	Prevents the locked rotor condition during motor running by monitoring the current.
	Temperature input	Monitors the PT100 temperature. It is based on two set-point. 4 different configuration with under /over level (with hysteresis) or in/out window (without hysteresis) are available.	ANSI37	Monitors if any of the phase currents measured is below the set-point current during a set point time.
			ANSI27S	Monitors if any of the phase - phase voltages is too low during the set time.
			ANSI59	Monitors if any of the phase - phase voltage is too high during a set-point time.
	Istantaneous variables	Monitors the selected instantaneous variable. It is based on two set-point. 4 different function configuration with under /over level (with hysteresis) or in/out window (without hysteresis) are available.	ANSI47	Monitors if the phase sequence is L1-L2-L3 or L1-L3-L2.
			ANSI27D	Monitors if at least one phase - phase voltage drops below the 70% of mains voltage.
	ANSI functions		Counters/timers	Based on one set-point (in seconds with the timer, in counts with the counter). This function depends on other blocks status. Connect two blocks to start/increase the timer/counter and reset it.
	ANSI49	Allows to protect the motor against damage due to thermal effects wich take place in overload conditions, starting from current measurement. The protection function trips when motor heating, i.e. the heat quantity in the motor, (represented by the TCU parameter - Thermal Capacity Used) reaches 100% of the maximum one for that specific motor.	Internal counter	It is based on one set- point. The block status is activated when the internal counter goes above the set-point.
	ANSI46	Monitors inverse current which is one of the main causes of motor heating.	Output	
	ANSI50	Monitors if any of the phase currents measured is too high.	Relay output	This function depends on other blocks status. Connect one or more blocks to open / close the relay (the output is activated when at least one of the selected block status is activated). NE or ND programmable.

Functions Description (cont.)

Latch reset	Internal output to reset all the active block status which have been set for latching. Each variable defined as "variable list" could be set for latching.	Variable monitoring	The software allows to monitor in real time the variables value or/and the used blocks status of the listed variables in the "Variable list" table (see the "Monitor" columns).
Logic functions	This function depends on other blocks status (up to 6). This block status depends on the state of up to 6 other blocks. This dependence is set through elementary logic functions (OR, AND and NOT).	Label	A label (defined by user) could be associated at each variable defined as "label" in the table "variable list".

Data Logger Functions

Data base logging	
Available variables	See table "Variable List".
Max number of variables	Up to 20.
Memory capacity	Max 9999 data with date/hour reference based on FIFO storage.
Variable type	Average values on time windows.
Time window	Programmable, from 60s to 3600s.
Fast data logger	
Available variables	See table "Variable List".
Max number of variables	Up to 20
Memory capacity	Max 9999 data with progressive number based on STACK storage.
Variable type	Instantaneous values from the start event.
Time window	Fixed, 100 ms.
Data event logging	
Available variables	See table "Dataevent variable list"; each listed variable can be enabled or disabled for data-event storing.
Memory capacity	Max 9999 data with date/hour reference based on FIFO storage.
Trigger	By event.
Event timing resolution	<1s (if more than one event take place in 1s they are registered but the correct sequence isn't guaranteed).

Data Event Variable List

Variables	Description
START	Start up Motor
RUN/STOP	Run/Stop Motor
ERR _{CONF}	Module configuration Error
RST _{DB}	Data base logging reset
RST _{FS}	Fast data logger reset
RST _{EV}	Data event logging reset
RST	Reset command (latch)
PW _{ON}	Power OFF
PW _{OFF}	Power ON
IN ₁ to IN ₂₃	Digital input (23 available)
OUT ₁ to OUT ₂₂	Relay outputs (22 available)
BLK ₁ to BLK ₃₂	Used blocks status (32 available)

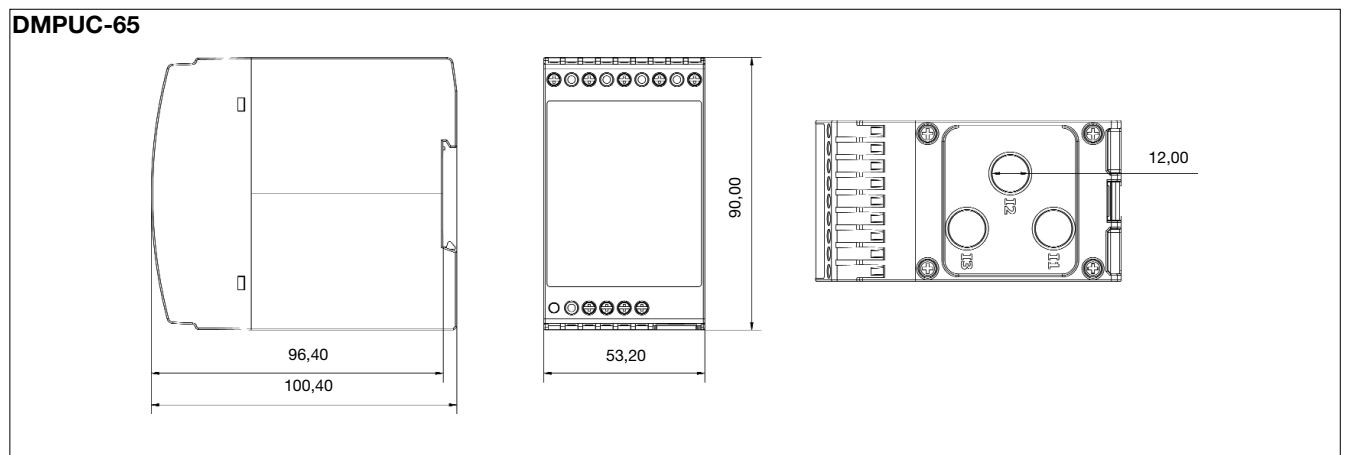
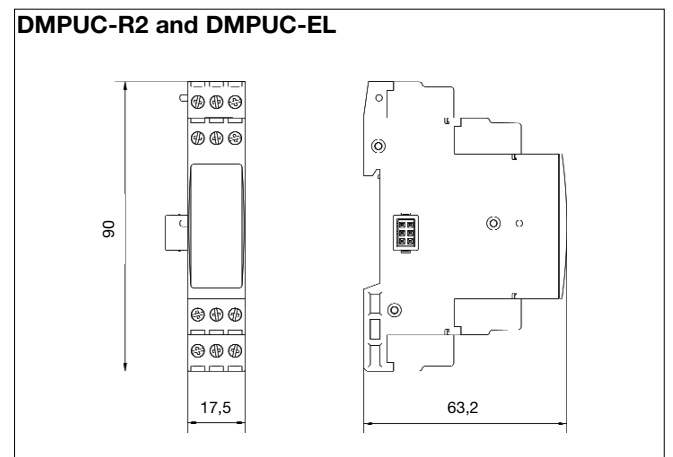
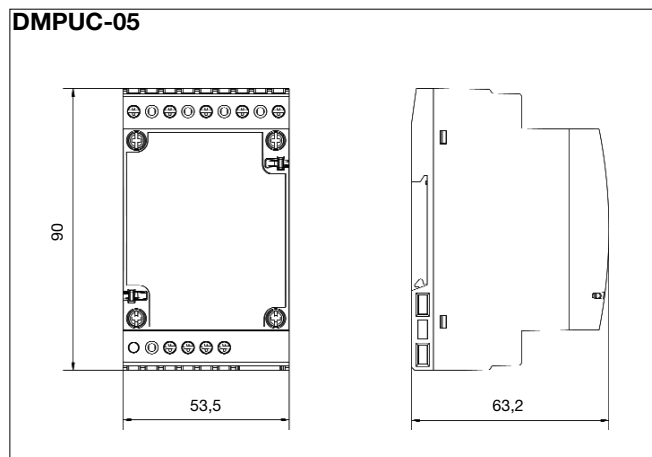
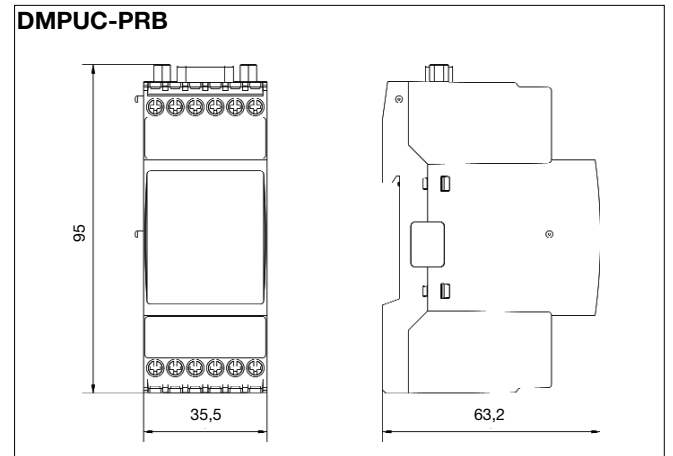
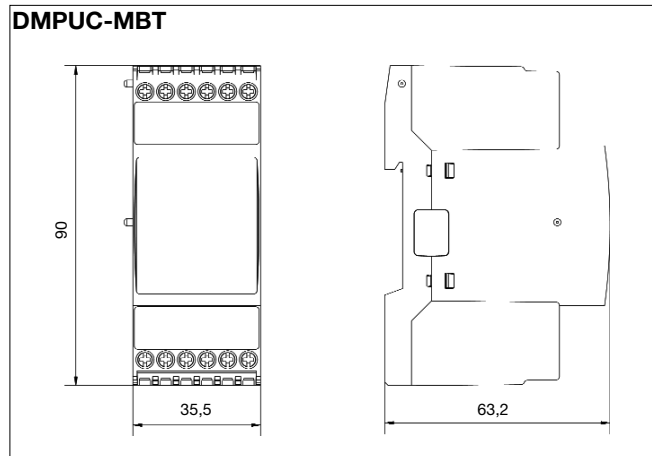
Variable List

Variables	Block	Block status	Latch function	Label	Data logger functions	Monitor		Description
						Value	Block status	
Inputs								
IN ₁ to IN ₂₃	✓	✓	✓	✓	✓	✓	✓	Digital input (up to 23 available)
TIN ₁ to TIN ₂₃	✓	✓	✓	✓	✓	✓	✓	Temperature input (up to 23 available)
VIN ₁ to VIN ₉	✓	✓	✓	✓	✓	✓	✓	Virtual digital input (up to 9 available)
Istantaneous variable								
V _{1-N}	✓	✓	✓	✓	✓	✓	✓	L1-N voltage
V _{2-N}	✓	✓	✓	✓	✓	✓	✓	L2-N voltage
V _{3-N}	✓	✓	✓	✓	✓	✓	✓	L3-N voltage
V _{L-NΣ}	✓	✓	✓	✓	✓	✓	✓	Average value of phase-neutral voltages
V ₁₋₂	✓	✓	✓	✓	✓	✓	✓	L1-L2 voltage
V ₂₋₃	✓	✓	✓	✓	✓	✓	✓	L2-L3 voltage
V ₃₋₁	✓	✓	✓	✓	✓	✓	✓	L3-L1 voltage
V _{L-LΣ}	✓	✓	✓	✓	✓	✓	✓	Average value of phase-phase voltages
I ₁	✓	✓	✓	✓	✓	✓	✓	Phase 1 current
I ₂	✓	✓	✓	✓	✓	✓	✓	Phase 2 current
I ₃	✓	✓	✓	✓	✓	✓	✓	Phase 3 current
I _{Earth}	✓	✓	✓	✓	✓	✓	✓	Calculated neutral current
W ₁	✓	✓	✓	✓	✓	✓	✓	Phase 1 active power
W ₂	✓	✓	✓	✓	✓	✓	✓	Phase 2 active power
W ₃	✓	✓	✓	✓	✓	✓	✓	Phase 3 active power
W _{TOT}	✓	✓	✓	✓	✓	✓	✓	Total active power
VA ₁	✓	✓	✓	✓	✓	✓	✓	Phase 1 apparent power
VA ₂	✓	✓	✓	✓	✓	✓	✓	Phase 2 apparent power
VA ₃	✓	✓	✓	✓	✓	✓	✓	Phase 3 apparent power
VA _{TOT}	✓	✓	✓	✓	✓	✓	✓	Total apparent power
VAR ₁	✓	✓	✓	✓	✓	✓	✓	Phase 1 reactive power
VAR ₂	✓	✓	✓	✓	✓	✓	✓	Phase 2 reactive power
VAR ₃	✓	✓	✓	✓	✓	✓	✓	Phase 3 reactive power
VAR _{TOT}	✓	✓	✓	✓	✓	✓	✓	Total reactive power
PF ₁	✓	✓	✓	✓	✓	✓	✓	Phase 1 power factor
PF ₂	✓	✓	✓	✓	✓	✓	✓	Phase 2 power factor
PF ₃	✓	✓	✓	✓	✓	✓	✓	Phase 3 power factor
PF _{TOT}	✓	✓	✓	✓	✓	✓	✓	Total power factor
HZ	✓	✓	✓	✓	✓	✓	✓	Frequency
AsyV _{L-N}	✓	✓	✓	✓	✓	✓	✓	Asymmetry L-N%
AsyV _{L-L}	✓	✓	✓	✓	✓	✓	✓	Asymmetry L-L%
PSQ	✓	✓	✓	✓	✓	✓	✓	Phase sequence
I _{IMB}	✓	✓	✓	✓	✓	✓	✓	Current Imbalance
I ₊	✓	✓	✓	✓	✓	✓	✓	Positive Sequence Component of Motor Current
I ₋	✓	✓	✓	✓	✓	✓	✓	Negative Sequence Component of Motor Current
THD V _{1-N}	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V _{1-N}
THD V _{2-N}	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V _{2-N}
THD V _{3-N}	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V _{3-N}
THD V ₁₋₂	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V ₁₋₂
THD V ₂₋₃	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V ₂₋₃
THD V ₃₋₁	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of V ₃₋₁

Variable List

Variables	Block	Block status	Latch function	Label	Data logger functions	Monitor		Description
						Value	Block status	
THD I ₁	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of I ₁
THD I ₂	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of I ₂
THD I ₃	✓	✓	✓	✓	✓	✓	✓	Total harmonic distortion of I ₃
TCU	✓	✓	✓	✓	✓	✓	✓	Thermal Capacity Used [%]
ANSI functions								
ANSI 49	✓	✓	✓	✓	✓	●	✓	Thermal Image ANSI
ANSI 46	✓	✓	✓	✓	✓	●	✓	Max inverse sequence current ANSI
ANSI 50	✓	✓	✓	✓	✓	●	✓	Overcurrent ANSI
ANSI 64	✓	✓	✓	✓	✓	●	✓	Earth fault ANSI
ANSI 66 _{SH}	✓	✓	✓	✓	✓	●	✓	Starts per hours ANSI
ANSI 66 _{MTBS}	✓	✓	✓	✓	✓	●	✓	Minimum time between starts ANSI
ANSI 66 _{MTFLS}	✓	✓	✓	✓	✓	●	✓	Minimum time from last stop ANSI
ANSI 64EL	✓	✓	✓	✓	✓	●	✓	Leakage current ANSI
ANSI 48	✓	✓	✓	✓	✓	●	✓	Locked rotor at start-up ANSI
ANSI 51LR	✓	✓	✓	✓	✓	●	✓	Stalled rotor ANSI
ANSI 37	✓	✓	✓	✓	✓	●	✓	Undercurrent ANSI
ANSI 27S	✓	✓	✓	✓	✓	●	✓	Undervoltage ANSI
ANSI 59	✓	✓	✓	✓	✓	●	✓	Overvoltage ANSI
ANSI 47	✓	✓	✓	✓	✓	●	✓	Phase sequence ANSI
ANSI 27D	✓	✓	✓	✓	✓	●	✓	Phase loss ANSI
Counters/timers								
CT ₁	✓	✓	✓	✓	✓	✓	✓	Counter #1
CT ₂	✓	✓	✓	✓	✓	✓	✓	Counter #2
TM ₁	✓	✓	✓	✓	✓	✓	✓	Timer #1
TM ₂	✓	✓	✓	✓	✓	✓	✓	Timer #2
Internal counter								
kWh _{TOT}	●	●	●	●	●	✓	●	Active energy [kWh]
kVARh _{TOT}	●	●	●	●	●	✓	●	Reactive energy [kVARh]
N _S	●	●	●	●	✓	●	●	Number of Starts
N _{SH}	✓	✓	✓	✓	✓	✓	✓	Starts per hour (ANSI 66)
T _{RTOT}	●	●	●	●	✓	✓	●	Total running hours
T _{RPAR}	●	●	●	●	✓	✓	●	Partial running hours
T _{BT}	✓	✓	✓	✓	✓	✓	✓	Estimated time before trip (associated with ANSI 49)
T _{BR}	✓	✓	✓	✓	✓	✓	✓	Estimated time before restart (associated with ANSI 66)
Outputs								
OUT ₁ to OUT ₂₂	✓	●	●	✓	●	●	●	Relay outputs (up to 22 available)
TLC	✓	●	●	●	●	●	●	Latch reset
Logic functions								
TT ₁ to TT ₉	✓	✓	✓	✓	✓	●	✓	6IN/10OUT Truth table (up to 9 available)

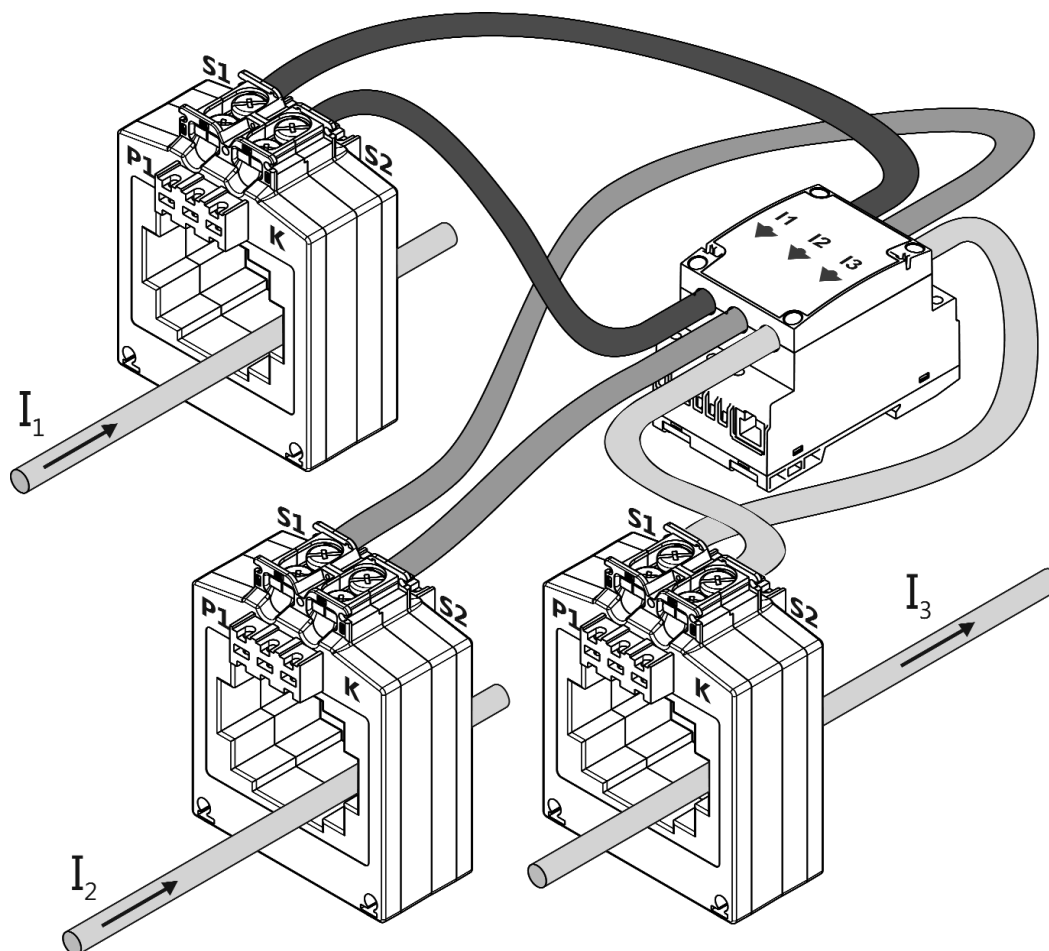
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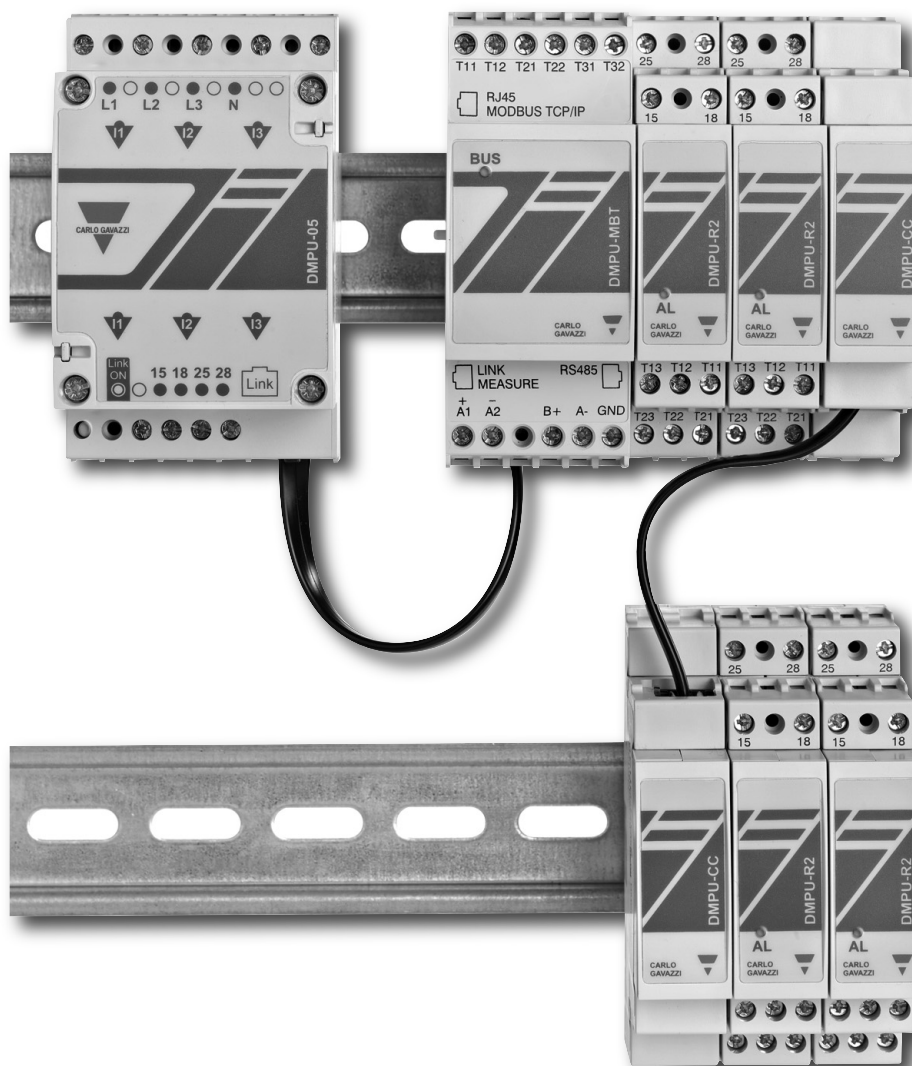
Current Transformer Selection

Motor power [kW]	Items			
	@230V	@400V	@480V	@600V
1.5	CTD3X1505A	-	-	-
2.2	CTD3X1505A	-	-	-
3.7	CTD3X1505A	CTD3X1505A	CTD3X1505A	-
5.5	CTD3X1505A	CTD3X1505A	CTD3X1505A	CTD3X1505A
7.5	CTD3X2005A	CTD3X1505A	CTD3X1505A	CTD3X1505A
11	CTD3X2005A	CTD3X1505A	CTD3X1505A	CTD3X1505A
15	CTD3X4005A	CTD3X2005A	CTD3X1505A	CTD3X1505A
18.5	CTD3X5005A	CTD3X2505A	CTD3X2005A	CTD3X1505A
22	CTD3X6005A	CTD3X3005A	CTD3X2505A	CTD3X2005A
30	CTD3X7005A	CTD3X4005A	CTD3X3005A	CTD3X2505A
37	CTD4X10005A	CTD3X5005A	CTD3X4005A	CTD3X3005A
45	CTD4X12005A	CTD3X6005A	CTD3X5005A	CTD3X4005A
55	CTD4X15005A	CTD3X7005A	CTD3X6005A	CTD3X5005A
75	CTD8V20005A	CTD4X10005A	CTD3X7505A	CTD3X6005A
90	CTD8V25005A	CTD4X15005A	CTD4X10005A	CTD3X7505A
110	CTD8V30005A	CTD4X16005A	CTD4X15005A	CTD4X10005A

These current transformers are suggested according to the nominal and locked rotor currents; for particular needs see the other current transformer types provided by Carlo Gavazzi (eg. current transformers with different mounting or housing).



Mounting and Positioning



Connect all module (except DMPUC-05) side by side according to the order defined while configuring the device. The first module must be DMPUC-MBT or DMPUC-PRB (main module). If it's used more than one DIN-rail use the internal bus adaptor DMPUC-CC to connect the different groups of modules.

Accessories

Code	Description
DMPUC-PS	DMPUC-MBT/DMPUC-PRB programming software (included with DMPUC-CPC cable or downloadable from the WEB)
DMPUC-HMI	DMPUC programmable display interface
DMPUC-PSHMI	DMPUC-HMI programming software (included with DMPUC-PS software)
DMPUC-CC	DMPUC Adaptor to internal bus-to-RJ connector
DMPUC-CPAN	DMPUC cable for panel connector
DMPUC-CPC	DMPUC cable for PC connection (included with the DMPUC-PS software)

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