Motor Controllers 3-Phase Analog Power Controller Types RSC-AAM60/RSO





- Control and output modules for analogue control of 3-phase induction motors or heaters
- Rated operational current: 3 x 10, 25, 50, 90, 110 AACrms
- Rated operational voltage: Up to 600 VACrms
- Supply voltage range: 10 to 32 VDC
- Control current range: 0 to 20 mA/4 to 20 mA
- LED-indication for line ON and load ON
- Varistor protection
- Approvals: CE, CCC, UL, CSA

Product Description

The micro processor based control module RSC-AAM60 is used with output modules RSO... to achieve a voltage controlled soft start/soft stop of 3-phase motors and a possibility for energy reduction when e.g. a fan is running with a variable capacity. This function is achieved by controlling the control module with a current between 4 and 20 mA (0 and 20 mA). The output mod-

ule can be selected according to the rated operational voltage and the size of the load.

This phase angle controlled soft-start unit can be used for pumps, fans, heaters, lights and many other applications.

LED indications for line ON and load ON gives a clear status indication.

Solid State Relay Soft starting/stopping Control module Output module Control input type Multivoltage Rated operational voltage Rated operational current RSO 4050

Type Selection, Control Module

Control current	Mains	Max. operational voltage	Type Number	
0-20 mA/4-20 mA	Multivoltage	600 VAC	RSC-AA M 60	

Type Selection, Output Module

Rated operational voltage	Rated opera	ational currer	nt					
	10 A	25 A	50 A	90 A	110 A			
3 x 220 VAC	RSO 2210	RSO 2225	RSO 2250	RSO 2290	RSO 22110			
3 x 400 VAC	RSO 4010	RSO 4025	RSO 4050	RSO 4090	RSO 40110			
3 x 480 VAC	RSO 4810	RSO 4825	RSO 4850	RSO 4890	RSO 48110			
3 x 600 VAC			RSO 6050	RSO 6090	RSO 60110			

General Spec., Control Module

Operational voltage range Line to line	150 to 660 VACrms
Operational frequency range	45 to 65 Hz
Supply current @ no output current @ max. output current	< 30 mA < 180 mA
Supply voltage range	10 to 32 VDC
CE-marking	Yes
Approvals	UL, CSA, CCC

Control Specifications

Minimum output voltage	Power supply minus 8 VDC
Output current short-circuit protected	≤ 150 mA DC

Thermal Specifications

Operating temperature	-20° to +70°C (-4° to +158°F)
Storage temperature	-40° to +100°C (-40° to +212°F)



Control Input Specifications

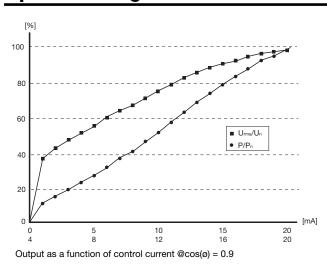
Control current A-input B-input	0 to 20 mA 4 to 20 mA
Input impedance	250 Ω
Power supply reset time	≤ 300 ms
Response time (input to trigger outputs)	≤ 1 cycle

Isolation Control Module

Rated isolation voltage Input to trigger outputs

≥ 4000 VACrms

Operation Diagram



Mode of Operation

The control module RSC-AAM60 is used with the output module RSO..... to achieve analog control of 3-phase induction motors.

Soft starting is achieved by increasing the motor voltage in accordance with the input current. Soft stopping is achieved by decreasing the motor voltage in accordance with the input current.

When the motor is running in the motor voltage can

When the motor is running idle, the motor voltage can be reduced by lowering the input current, whereby energy is saved.

Heating elements can also be controlled with the RSC/RSO with the use of appropriate filters.

General Specifications, Output Module

	RSO 22	RSO 40	RSO 48	RSO 60
Operational voltage range				
Line to line	150 to 250 VACrms	220 to 420 VACrms	400 to 510 VACrms	400 to 625 VACrms
Blocking voltage	1200 V _p	1200 V _p	1200 V _p	1600 V _p
Varistor voltage	275 VAC	420 VAC	510 VAC	625 VAC
CE-marking	Yes	Yes	Yes	Yes

Output Specifications, Output Module

	RSO10	RSO25	RSO50	RSO90	RSO110
IEC and CCC					
Rated Operational Current	40.4	05.4	50 A	00.4	440.4
AC 51	16 Arms	25 Arms	50 Arms	90 Arms	110 Arms
IEC and CCC rated operational current					
AC 53a	3 Arms	5 Arms	15 Arms	30 Arms	40 Arms
Number of starts/hr @40°C	7*	7*	7*	50*	50*
Overload cycle according to					
EN/ IEC 60947-4-2 @ 40°C	3A: AC53a:	3A: AC53a:	3A: AC53a:	3A: AC53a:	3A: AC53a:
	4 - 4:100 - 7*	4 - 4:100 - 7*	4 - 4: 100 - 7*	4 - 4:100 - 50*	4 - 4: 100 - 50*
Off-state leakage current	≤ 10 mArms	≤ 10 mArms	≤ 10 mArms	≤ 25 mArms	≤ 25 mArms
On-state voltage drop	≤ 1.6 Vrms	≤ 1.6 Vrms	≤ 1.6 Vrms	≤ 1.8 Vrms	≤ 1.8 Vrms
I ² t for fusing t=10 ms	≤ 130 A ² s	≤ 525 A ² s	≤ 1800 A ² s	≤ 6600 A ² s	≤ 18000 A ² s
Non-rep. surge current					
t=10 ms	160 A _p	325 A _p	600 A _p	1150 A _p	1900 A _p

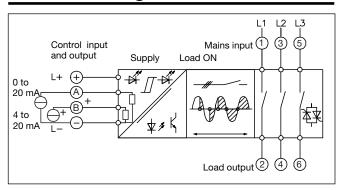
^{*} Mounted on RHS 301



Thermal Specifications Output Module

	RSO10	RSO25	RSO50	RSO90	RSO110
Operating temperature	-20° to +70°C (-4° to +158°F)				
Storage temperature	-40° to +100°C (-40° to +212°F)				
Junction temperature	≤ 125°C	≤ 125°C	≤ 125°C	≤ 125°C	≤ 125 °C
R _{th} junction to case	≤ 0.7 K/W	≤ 0.5 K/W	≤ 0.25 K/W	≤ 0.1 K/W	≤ 0.09 K/W

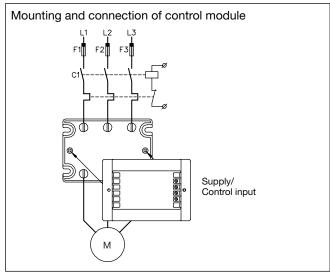
Functional Diagram



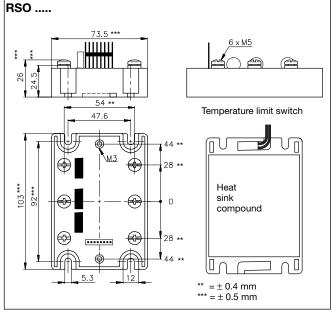
Accessories

Heatsinks Fuses Temperature limit switch Power supply For further information refer to "General Accessories".

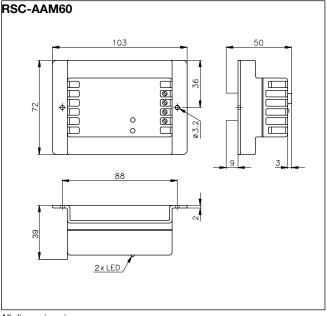
Wiring Diagram



Dimensions



All dimensions in mm



All dimensions in mm



Heatsink Dimensions (load current versus ambient temperature)

RSO ..10

Load current [A] Thermal resistance [K/W] Power dissipation [W] 0.97 0.81 0.65 0.48 0.32 62 16 15 1.1 0.88 0.71 0.53 0.35 57 0.58 14 0.97 52 1.2 0.77 0.39 13 0.85 47 1.3 1.1 0.64 0.43 12 1.4 1.2 0.95 0.71 0.47 42 0.53 1.6 1.3 0.80 38 11 1.1 80°C 10 33 1.8 1.5 1.2 0.90 0.60 9 2.1 1.7 1.4 1 0.69 29 7 2.8 2.3 1.9 1.4 0.93 21 5 3.5 2.8 2.1 14 4.2 1.4 3 4.9 2.5 8 7.4 6.2 3.7 23.8 19.8 15.9 11.9 7.9 3 20 30 40 50 60 Ambient temp. [°C]

RSO ..25

Load curren	Load current [A]		Thermal resistance [K/W]		Power dissipatior	i [W]	Temp. pro- tection [°C]	
25	0.66	0.55	0.44	0.33	0.22	91		
22.5	0.76	0.63	0.51	0.38	0.25	79		
20	0.88	0.74	0.59	0.44	0.29	68		
17.5	1.1	0.87	0.70	0.52	0.35	57		
15	1.3	1.1	0.85	0.63	0.42	47	80°C	
12.5	1.6	1.3	1.1	0.79	0.53	38	80 C	
10	2.1	1.7	1.4	1	0.69	29		
7.5	2.9	2.4	1.9	1.4	0.96	21		
5	4.5	3.8	3	2.3	1.5	13		
2.5	9.4	7.8	6.3	4.7	3.1	6		
	20	30	40	50	60	_	TA	
Ambient temp. [°C]								

RSO ..50

Load	nt [A]	Thermal resistance Power dissipation [N			[W]	Temp. pro- tection [°C]			
50	0.33	0.28	0.22	0.16	0.11	181			
45	0.38	0.32	0.25	0.19	0.13	158			
40	0.44	0.37	0.29	0.22	0.15	136			
35	0.52	0.43	0.35	0.26	0.17	116			
30	0.63	0.52	0.42	0.31	0.21	96	80°C		
25	0.78	0.65	0.52	0.39	0.26	77			
20	1	0.84	0.67	0.50	0.34	60			
15	1.4	1.2	0.93	0.69	0.46	43			
10	2.2	1.8	1.4	1.1	0.72	28			
5	4.5	3.8	3	2.3	1.5	13			
	20	30	40	50	60		T _A		
	Ambient temp. [°C]								

RSO ..90, RSO ..110

Load	nt [A]	Heatsink/Thermal Power resistance [K/W] dissipation			<u>[</u> [W]	Temp. pro- tection [°C]	
90	0.13	0.10	0.07	0.04	-	304	
80	0.19	0.15	0.12	80.0	0.04	260	
70	0.27	0.22	0.18	0.13	0.09	219	
60	0.33	0.28	0.22	0.17	0.11	181	
50	0.41	0.35	0.28	0.21	0.14	145	80°C
40	0.54	0.45	0.36	0.27	0.18	111	
30	0.75	0.63	0.50	0.38	0.25	80	
20	1.2	0.99	0.79	0.59	0.39	51	
10	2.5	2.1	1.7	1.2	0.83	24	
	20	30	40	50	60	T _A	
Ambient temp. [°C]							

Heatsink Selection

Carlo Gavazzi Heatsink (see Accessories)	Thermal resistance		
No heatsink required	R _{th s-a} > 8.0 K/W		
RHS 300 Assy or backplate	5.0 K/W		
RHS 301 Assy	0.8 K/W		
RHS 301 F Assy	0.25 K/W		
Consult your distributor	< 0.25 K/W		

Compare the value found in the load current versus temperature chart with the standard heatsink values and select the heatsink with the next lower value.

It is recommended to protect the solid state relay against overheating. Therefore the chart also states the maximum switching temperature (70, 80 or 90 $^{\circ}$ C) for the optional temperature limit switch.



Housing Specifications

Weight RSO10,25,50 RSO90,110	Approx. 275 g Approx. 385 g	Relay Mounting screws Mounting torque	M5 ≤ 1.5 Nm
Housing material Colour	Noryl, glass-reinforced Black	Control terminal Mounting screws	M3
Base plate		Mounting torque	≤ 0.5 Nm
@ ≤ 50 A	Aluminium, nickel-plated	Power terminal	
@ ≥ 90 A	Copper, nickel-plated	Mounting screws	M5 x 6
Potting compound	Polyurethane, black	Mounting torque	≤ 1.5 Nm

Applications

The output module RSO ..110 is recommended for motors up to 22 kW @ 400 V. The RSO ..110 is designed for use in applications with high surge current conditions. Care must be taken to ensure proper heat-sinking when the relays are to be used at high nominal currents. Adequate electrical connection between relay terminals and cable must be ensured.

Example 1: Power dissipation -RSO 40110:

 $I_{load} = 40 \text{ Arms} = 111 \text{ W}$ See previous page.

Example 2:

Motor: 3 kW, 4 HP 3 x 400 VAC, 4-pole T_A : 50°C Starting time: \leq 5 s

For this application RSC-AAM60 must be used. The output module RSO4025 is selected according to the Selection Guide.

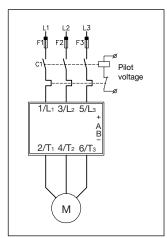
The smallest heatsink required is 1 K/W, and the power dissipation is 25 W.

This gives: Control module: RSC-AAM60 Output module: RSO 4025 Heatsink:1K/W

Connection to the mains

Since no motor protective circuitry is included in the RSC/RSO, the motor must be protected in the usual way, i.e. either by a thermal relay, a PTC-resistor or a Klixon bimetal temperature switch near the motor windings.

If short circuit protection is required, fuses F1 to F3 should be ultrafast and selected according to the load integral (I²t) of the RSO output module and the motor load.

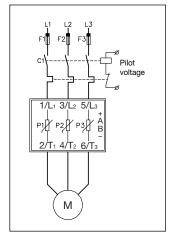


Overload protection by thermal relav

Transient voltage protection

With an unfiltered main supply, voltage transient may occur. Since these transients could have a high energy content, it is advisable to use varistors to protect the output module.

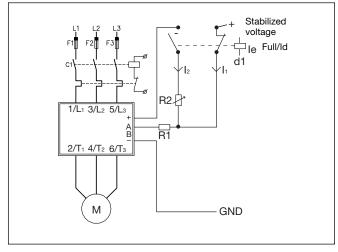
The varistors are already mounted in the RSO output module and they are selected according to the rated operational voltage.



Energy saving for motors in idle mode

When motors are running idle, it not necessary to maintain a full magnetic field, as is the case when the motor has to produce full torque. By lowering the motor voltage, power losses inside the motor are also reduced.

When the motor is idle, d1 will switch the control current from $I_1 > 20\,$ mA to I_2 , which is adjusted to a value at which the motor is still running at full speed, but at a lower voltage. Please remark that this type of phase-angle controlled voltage reduction, demands additional filtering to fulfill EMC regulations.





Applications (cont.)

In order to achieve a 4 to 20 mA signal from a 12 or 24 VDC source, a resistor and a potentiometer should be connected in series with the voltage source and the RSC controller.

We define the I_{max} to be e.g. 24 mA, which means that the series resistors must be:

 $R_1 (12 \text{ V}) = \text{U/I - Rint} = \\ 12 \text{ V/24 mA - } 250 \ \Omega = 250 \ \Omega$

 $R_1 (24 \text{ V}) = \text{U/I - Rint} = \\ 24 \text{ V/24 mA - } 250 \ \Omega = 750 \ \Omega$

If the minimum current is defined to be e.g. 2.4 mA and the 250 Ω Rint input resistance of the RSC is also calculated in:

 $R_2(12 \text{ V}) = \text{U/I} - R_1 - \text{Rint} = 12/2.4 - 250 - 250 = 4500 \ \Omega$

 $R_2(24 \text{ V}) = \text{U/I} - R_1 - \text{Rint} = 24/2.4 - 750 - 250 = 9000 \Omega$

Selection Guide

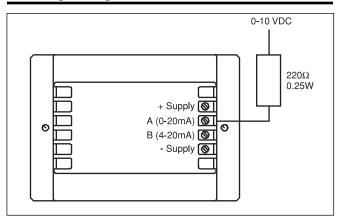
400 VACrms and 480 VACrms motors

Output module	RSO10	RSO25	RSO50	RSO90	RSO110
Max. motor size	3 HP/2.2 kW	5 HP/4 kW	15 HP/11 kW	20 HP/15 kW	30 HP/22 kW

600 VACrms motors

Output module		RSO 6050	RSO 6090	RSO 60110
Max. motor size		15 HP	30 HP	40 HP

Wiring Diagram (0-10 VDC control)



Short circuit Protection (according to EN/IEC 60947-4-2)

	RSO25 RSO10	RSO50	RSO90	RSO110
Type of coordination: 2				
Rated short circuit current	5kA when protected	5kA when protected	5kA when protected	5kA when protected
	by semiconductor fuses.	by semiconductor fuses.	by semiconductor fuses.	by semiconductor fuses.
	Ferraz Shawmut 25A,	Ferraz Shawmut 63A,	Ferraz Shawmut 80A,	Ferraz Shawmut 100A,
	Class URC Art. No. 6.9 CP	Class URQ Art. No. 6.921 CP	Class URQ Art. No. 6.921 CP	Class URQ Art. No. 6.921 CP
	gRC 14.51/25	URQ 27 x 60/63	URQ 27 x 60/80	URQ 27 x 60/100

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