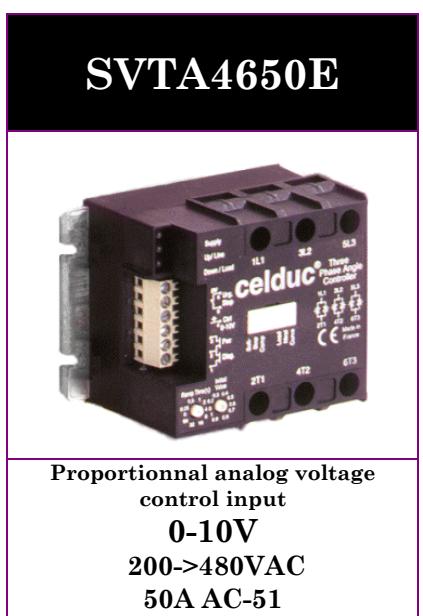


## DIGITAL THREE PHASE ANGLE CONTROLLER

- ▶ Allows to set the voltage applied to different sort of loads with 3 wires, 4 wires or inside the delta wiring:
  - ▶ Resistive (Bulbs, UV and IR lamps, ovens, ...),
  - ▶ Inductive (inductors, transformers, ...),
  - ▶ Motor (motorfan speed control (60 to 100% from the nominal speed),
  - ▶ Rectified (power supplies, ...).
- ▶ Small housing, easy and ready to use.
- ▶ Large mains frequency and voltage range.
- ▶ Fully optoisolated full cycle three phase phase angle controller (balanced currents, less harmonics, ...)
- ▶ Dynamic control voltage range according to the power factor of the load.
- ▶ Softstart and softstop functions (increase lifetime expectancy of the load).
- ▶ Adjustable filter regarding fast input voltage changes (ramps).
- ▶ Motor softstarting functions to control its speed within the stable area.
- ▶ Input-output transfert characteristic linearization function (resistive load).
- ▶ Diagnostic features : Status given on LED and AC/DC switches.



Mains Voltage	Mains Frequency	Max AC-51 Current	Max AC-53a Current	Control Input	Status Outputs	In / Out Insulation	Wire Size	Dimensions (WxHxD)	Weight
200 to 480VAC	40 to 65Hz	50A (with heatsink)	12A (with heatsink)	0-10VDC	0 to 24VDC 1A AC/DC	4kV	In=2.5mm <sup>2</sup> Out=10mm <sup>2</sup>	100x78x56,5 (mm)	500g

Fig. 1

### TYPICAL APPLICATIONS

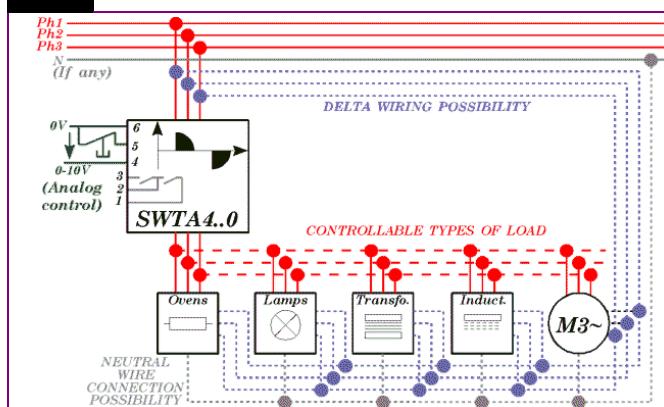


Fig. 2

### WIRING DIAGRAM

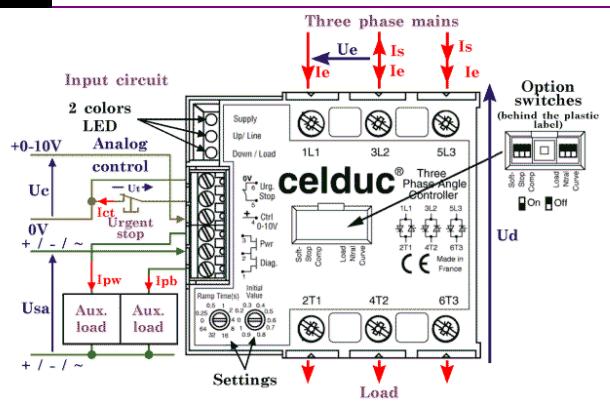


Fig. 3

### PHASE ANGLE CONTROL DESCRIPTION

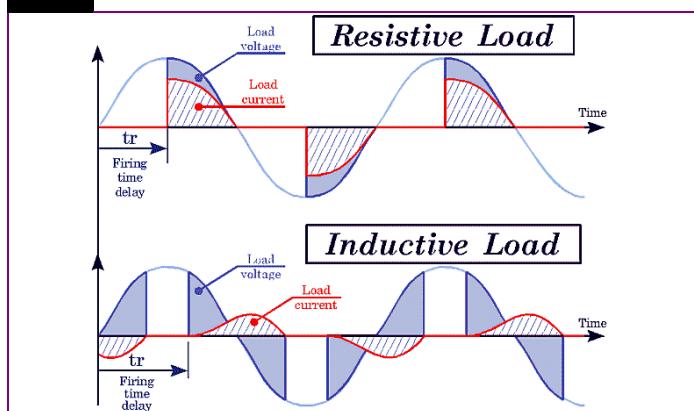
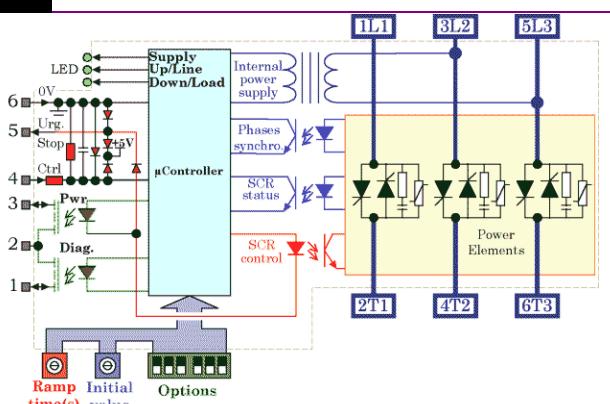


Fig. 4

### INTERNAL DIAGRAM



Proud to serve you

Data given at Tambient=40°C and subject to modification without previous notice

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## SETTINGS

Label	“Ramp Time (s)”	“Initial Value”	“Soft Stop”	“Comp”	“Load”	“Ntrl”	“Curve”	
Description	Ramp Time(s) 0.5 1 2 0.25 0.4 0.5 0 0.6 0.7 64 32 16 8	Initial Value 0.3 0.4 0.5 0.2 0.6 0.7 0.9 0.8						
Function	Ramp up time (Softstart and smooth transients)	Initial load voltage (footstep)	Ramp down time	Allows to adapt the control signal range whatever the power factor of the load	Ask the unit to make a softstart up to the max. before analog control.	Tells the unit the load star point is connected to the mains neutral	Tells the unit what kind of in-out response to use (angle or RMS voltage linearity)	
Setting possibilities	White squares = buttons Example :  = all switches down (OFF) (factory setting)	Ts= 0 to 64s	Vi=0 to 100 %	<b>0 x ts =</b>  <b>0.5 x ts =</b>  <b>ts =</b>  <b>2 x ts =</b> 	<b>On (Up)</b>  <b>Inductive load</b>	<b>On (Up)</b>  Motor	<b>On (Up)</b>  Star wiring with neutral (4 wires)	<b>On (Up)</b>  RMS voltage control
				<b>Off (Down)</b>  Resistive load	<b>Off (Down)</b>  Other loads than motors	<b>Off (Down)</b>  Delta or star without neutral	<b>Off (Down)</b>  Phase angle control	

## INPUT CHARACTERISTICS

CHARACTERISTIC	LABEL	VALUE		INFO.
Labels		“0-10V”		“Urg. Stop”
Function		Analog control input		Stop the thyristor controls
Control type		DC control voltage		Opening the connection between 5 & 6
Terminals		4 & 6		5 & 6
Control voltage range	Uc	0-10VDC		-
Release and control threshold voltage	Ucsmin	0.3VDC		-
Full power threshold control voltage	Ucsmax	9.7VDC		-
Max. input voltage	Ucmax	30VDC		6VDC
Max. reverse voltage	-Ucmax	30VDC		6VDC
Release voltage	Ut	>1,5V		
Input impedance	Re	100kΩ		-
Current to switch	Ict	- 20mAADC		Ict=f(Ut)

Labels		“Diag. “	“Pwr“	
Terminals		1 & 2	2 & 3	
Function		Indicates a problem detected in the circuit configuration	Indicates the load is supplied	
Nominal operating voltage	Usan	24VAC/DC		
Operating voltage range	Usa	0->28VAC/DC		
Max. peak voltage	Usap	60V		
Overvoltage protection		Built-in 25V size7 varistors		
Minimum load current	Ipw/Ipb	0A		
Maximum load current	Ipw/Ipb	1A AC/DC		See fig. 6
Maximum overload current	Ipw/Ipb	2.4A AC/DC		@100ms 10% of the cycle
On and off state switch resistance	Ron / Roff	500mΩ / 100MΩ		See fig. 6
On and off time delay	Ton / Toff	0.5ms / 2ms		

**OUTPUT CHARACTERISTICS**

<b>POWER CIRCUIT</b>	<b>CHARACTERISTIC</b>	<b>LABEL</b>	<b>VALUE</b>			<b>INFO.</b>
	Mains voltage range	Ue	200 -> 480VAC			
	Non-repetitive peak voltage	Uep	1200V			
	Overvoltage protection	VDR	Built-in 510V size 14 varistors			
<b>Maximum nominal currents</b>	Ie	Resistive Ithmax AC51	Motor Iemax AC53a	Motor Ie AC53a		See fig. 7 for limits
		50A	12A	8.5A		Values with heatsink
	Maximum line currents in delta wiring	ILine	87A	21A	14A	Delta wiring : See installation manual
	Max motor power	Pe	5.5kW @400VAC star connection			
	Non-repetitive peak overload current (1 cycle of 10ms)	ITSM	550A			See fig. 8
	Melting limit for choosing the protective fuses	I <sup>2</sup> t	1500A <sup>2</sup> s			@10ms
	Minimum load current	Iemin	100mA			
	Maximum leakage current	Ielk	7mA			@400VAC 50Hz
	Power factor	Pf	0->1			
	Mains frequency range	F	40->65Hz			
	Max. off-state voltage rise	dv/dt	500V/μs			
	Protection against fast voltage transients		Buit-in RC network			
	Max. current rise	di/dt	50A/μs			
	On-state voltage drop	Ud	1.4V			@Ith
	Resistive part of the voltage drop	rt	12mΩ			@125°C
	Potential part of the voltage drop	Vto	0.9V			@125°C
	Maximum junction temperature	Tjmax	125°C			
	Junction/case thermal resistance per power element	Rthjc	0.45K/W			Total = 3 power elements
	Case heatsink thermal resistance	Rthcs	-			
	Built-in heatsink thermal resistance vertically mounted	Rthra	4K/W			@ΔTra=60°C
	Heatsink thermal time constant	Tthra	15min			@ΔTra=60°C
	Inputs/power ouputs insulation voltage	Uimp	4kV			
	Input/status outputs insulation voltage	Uied	2.5kV			
	Inputs/case insulation voltage	Uimp	4kV			
	Status outputs/case insulation voltage	Uimp	4kV			
	Isolation resistance	Rio	1GΩ			
	Isolation capacitance	Cio	<8pF			
	Storage ambient temperature	Tstg	-40->+100°C			
	Operating ambient temperature	Tamb	-40->+90°C			See fig. 7
	Max. heatsink temperature	Tc	100°C			

**INTERNAL POWER SUPPLY**

<b>INTERNAL POWER SUPPLY</b>	<b>CHARACTERISTIC</b>	<b>LABEL</b>	<b>VALUE</b>	<b>INFO.</b>
Terminals			3L2 & 5L3	
Mains voltage range	<b>Ue</b>		200->480VAC	
Consumption	<b>I<sub>s</sub></b>		1mA typical	
Mains frequency range	<b>F</b>		40-65Hz	
Turn-on time	<b>t<sub>m</sub></b>		100ms	

**GENERAL INFORMATION**

<b>CONNEX- TIONS</b>	Connections		<b>Power</b>	<b>Input terminal block</b>
	Screwdriver advised		Posidriv 2 or 0.8 x 5.5mm	0.8 x 2mm
	Min and max tightening torque		1.8->3N.m	
	Number and cross section of the wires		2 x 1.5->6mm <sup>2</sup> (10mm <sup>2</sup> without ferrule)	1 x 2.5mm <sup>2</sup>
	Screwdriver for settings			0.8 x 2mm
<b>MISC.</b>	Housing		UL94V0	
	Mounting		Omega DIN rail (DIN50022) or screwed	
	Noise level		Low audible vibrations	
	Weight		500g	

**STANDARDS**

<b>GENERAL</b>	Standards		EN60947-4-2 & EN60947-4-3	
	Protection level		IP2L0	
	Protection against direct touch		Accordin to V.D.E. 160 part 100 : Back hand and finger safety	
	CE marking		Yes	
	UL, cULUS and VDE approvals		Pending	

<b>E.M.C. IMMUNITY</b>	<b>TYPE OF TEST</b>	<b>STANDARD</b>	<b>LEVEL</b>	<b>EFFECT</b>
	E.S.D. (Electrostatic discharges)	EN61000-4-2	8kV (air) 4kV (touch)	No effect
	Radiated electromagnetic fields	EN61000-4-3	10V/m	No effect
	Fast transients bursts	EN61000-4-4	2kV direct coupling on the power side 2kV coupling by clamp on the input side	No effect
	Electric chocks	EN61000-4-5	1kV direct coupling differential mode (input and output) 2kV direct coupling common mode (input and output)	No effect
	Voltage drop	EN61000-4-11	-	

<b>E.M.C. EMISSION</b>	Radiated and conducted disturbances	NFEN55011	The conducted or radiated disturbances generated by solid state relays depend on the wiring and load configuration. The test method recommended by the European standards and concerning electromagnetic compatibility leading to results far from reality, we decided to advise our customer in order to adapt their filtering scheme to their application. Please refer to the SVTA - SWTA installation manual.
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## CHARACTERISTIC CURVES

Fig. 5

INPUT CHARACTERISTIC

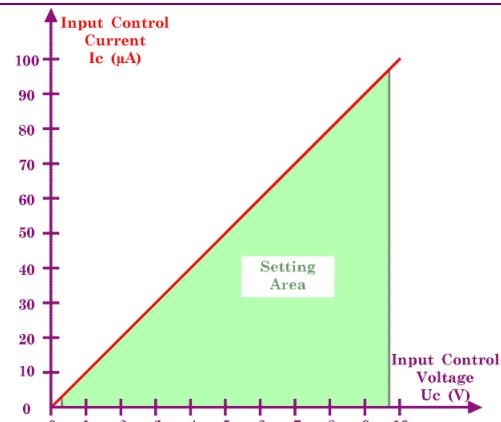


Fig. 6

CURRENT AND ON RESISTANCE VS TEMPERATURE

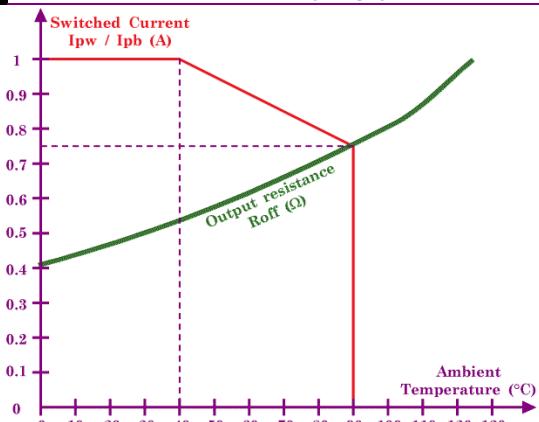


Fig. 7

POWER DISSIPATED AND LOAD CURRENT LIMIT VS TEMPERATURE

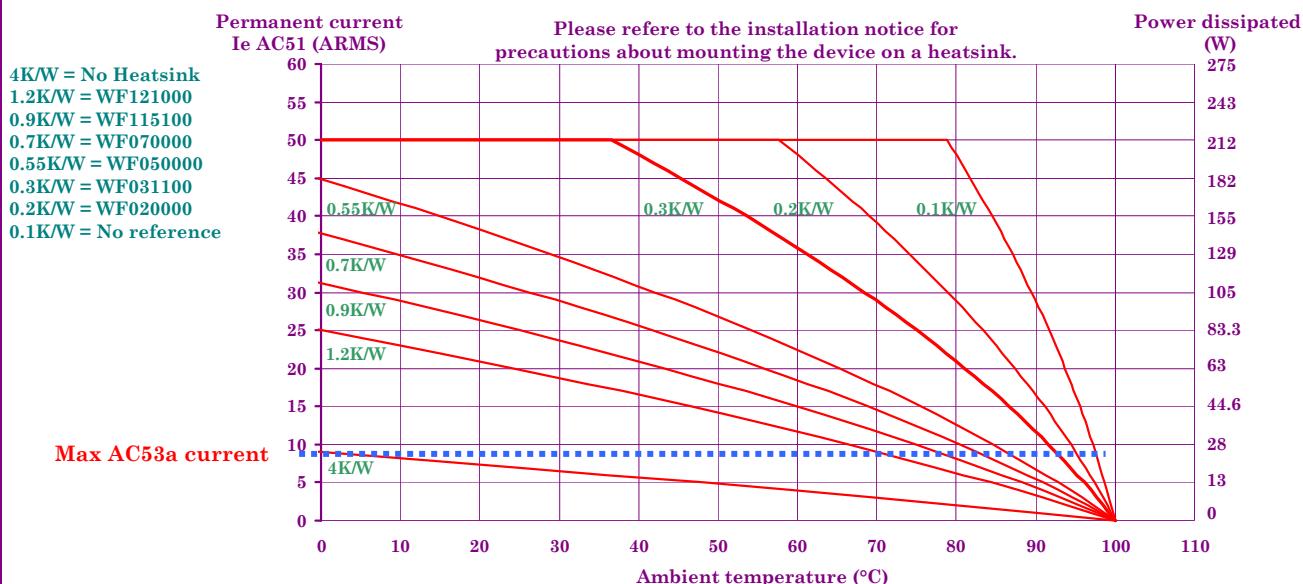
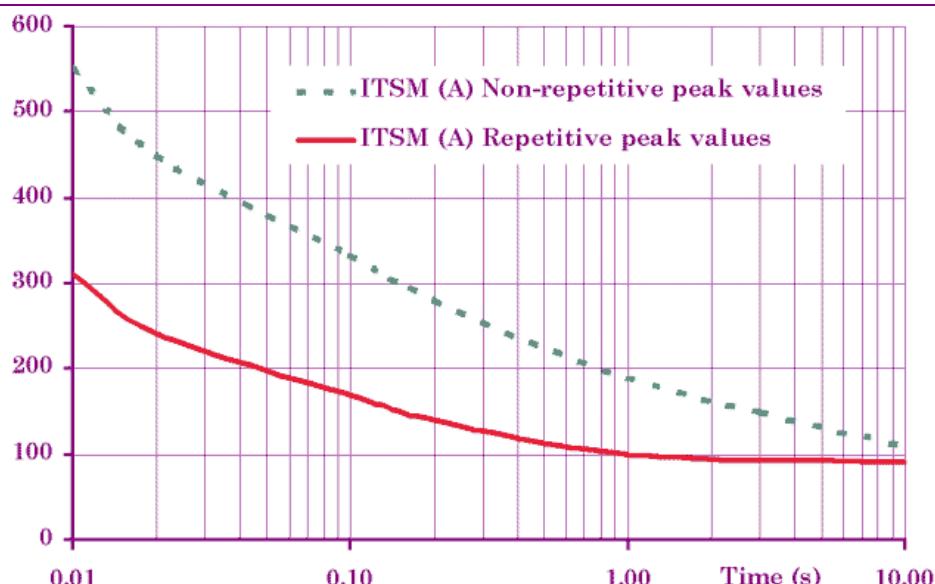


Fig. 8

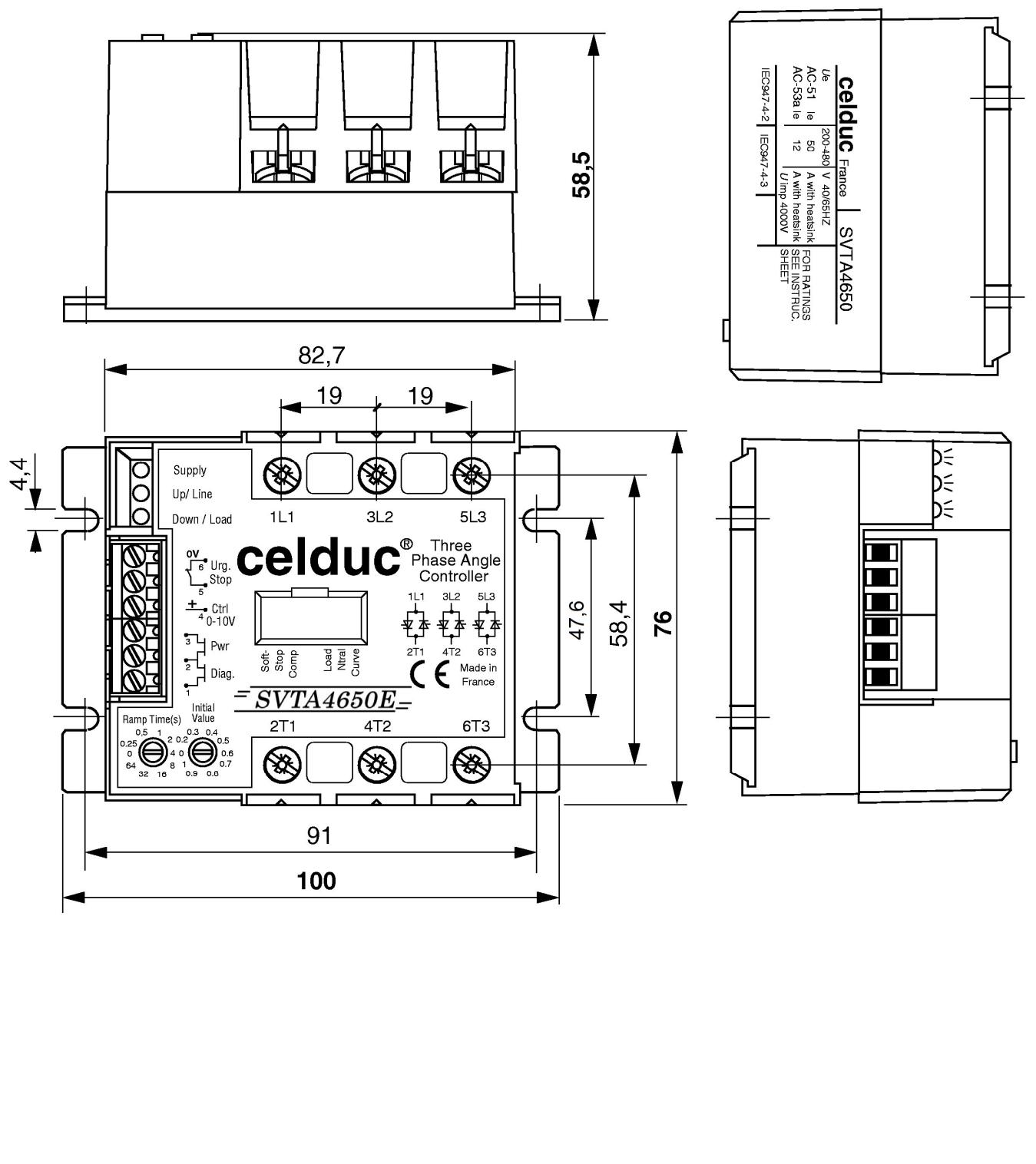
CURRENT OVERLOAD CHARACTERISTIC (ITSM PER POWER ELEMENT)



## DIMENSIONS AND ACCESSORIES

Fig. 9

### DIMENSIONS



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