

## 12V Input Single Channel Full Bridge Motor Driver

# CJDR9110T Motor Driver

### 1 Introduction

CJDR9110T is a 12V DC motor driver. The device is internally integrated with a full bridge composed of four MOS, which can support a power supply voltage range of 3.8V to 12V, and can provide a continuous output current of up to 1.5A or a peak output current of 2.5A. CJDR9110T has an input interface IN / IN compatible with industry standard devices, which can support pulse width modulation (PWM) mode control. When the input interfaces are all low level, the device will enter sleep mode, and the power consumption current in sleep mode is less than 1 $\mu$ A. Since the device has built-in LDO, it can be compatible with common input voltage (such as 3.3V or 5.0V) without logic power supply.

CJDR9110T is an upgraded version of CJDR9110, with functions such as thermal shutdown, undervoltage protection, short circuit protection, overcurrent protection, automatic fault recovery, etc. One CJDR9110T can be used to drive a DC motor or two CJDR9110Ts can be used to drive a stepping motor. Therefore, CJDR9110T is very suitable for applications, providing an integrated motor drive solution for consumer products such as cameras, toys, or other battery powered motion control applications.

## 2 Applications

- Video Camera
- Digital Single Lens Reflective (DSLR)
- Lens
- Toys
- Robotics
- Shared Bicycle Lock
- Water Meter Switch
- Medical Equipment

#### 3 Features

- Power supply input voltage: 3.8V~12V
  - Output current: 1.5A for continuous operation 2.5A for peak current
- Low R<sub>DS ON</sub>: 350mΩ (HS + LS)
- Pulse width modulation (PWM) input, compatible with common logic input levels of 3.3V and 5.0V
- Sleep mode low current consumption: nA level
- Comprehensive protection:
  - Thermal shutdown
  - Undervoltage protection
  - Built-in current limit
  - Short circuit protection
  - Automatic fault recovery

## 4 Available Package

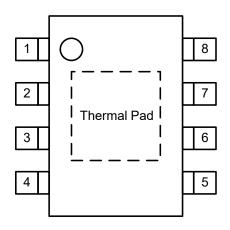
PART NUMBER	PACKAGE
CJDR9110T	ESOP8

**Note:** For more detailed packaging information, see the part *Pin Configuration and Function* and the part *Mechanical Information*.



Figure 4-1. ESP8 Package

## 5 Pin Configuration and Function





PIN	CJDR9110T	I/O	DESCRIPTION
NAME	ESOP8		
VM	2 & 3	Power	Logic power supply.
OUT 1	1	0	H-bridge output 1.
OUT 2	4	0	H-bridge output 2.
GND	5 & 8	-	Device ground. Connect to system ground.
IN 2	6	I	H-bridge control input 2.
IN 1	7	Ι	H-bridge control input 1.
-	Thermal Pad	-	Connect to system ground.

## 6 Specifications

#### 6.1 Absolute Maximum Ratings

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CHARACTERISTIC	SYMBOL	VALUE	UNIT
Power supply input voltage range <sup>(2)</sup>	Vм	0 ~ 17	
Logic input voltage range <sup>(2)</sup>	V <sub>IN x</sub>	-0.5 ~ 7.0	V
Continuous output current	Ιουτ	±1.5	Α
Peak output current	IOUT Max	±2.5	A
Maximum junction temperature	TJ	150	°C
Storage temperature	T <sub>stg</sub>	-60 ~ 150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum rated conditions for extended periods may affect device reliability.

(2) All voltages are with respect to network ground terminal.

#### 6.2 Recommended Operating Conditions

PARAMETER <sup>(3)</sup>	SYMBOL	MIN.	NOM.	MAX.	UNIT
Load power input voltage range	VM	3.8	-	12	V
Logic input voltage (IN x)	Vin x	0	-	5.0	V
Continuous output current	Ιουτ	0	-	1.5	А
PWM frequency	fрwм	0	-	250	kHz
Operating junction temperature	TJ	-40	-	150	°C
Operating ambient temperature	TA	-40	-	100 <sup>(4)</sup>	°C

(3) JSCJ recommends that users should not exceed the rated value in the *Recommended Operating Conditions* for the application conditions of the device, so as to ensure the stability of normal operation and reliability of long-term operation. Operation beyond the recommended rated conditions does not mean that the product will fail. The consumers need to evaluate the risks that may be caused by the operation of the product beyond the recommended rated conditions.

(4) It is necessary to ensure that the operating junction temperature of the device does not exceed the rated value of the recommended operating conditions when using the device for design.

## 6 Specifications

#### 6.3 ESD Ratings

ESD RATI	SYMBOL	VALUE	UNIT	
Electrostatic discharge <sup>(5)</sup>	Human body model	Vesd-hbm	4000	V

(5) ESD testing is conducted in accordance with the relevant specifications formulated by the Joint Electronic Equipment Engineering Commission (JEDEC). The human body mode (HBM) electrostatic discharge test is based on the JESD22-114D test standard, using a 100pF capacitor and discharging to each pin of the device through a resistance of  $1.5k\Omega$ .

#### 6.4 Thermal Information

THERMAL METRIC <sup>(6)</sup>	SYMBOL	CJDR9110T	UNIT	
	STWIDOL	ESOP8	UNIT	
Junction-to-ambient thermal resistance	Roja	104.0	°C/W	
Maximum heat dissipation power for continuous operation	$P_{D Ref}$	1.20	W	

(6)  $T_A = 25^{\circ}$ C, all numbers are typical, and apply for packages soldered directly onto a PCB board in still air.

## 6 Specifications

#### 6.5 Electrical Characteristics

CJDR9110T (V<sub>cc</sub> = 5.0V,  $T_A$  = 25°C, unless otherwise specified)

CHARACTERISTIC	SYMBOL	TEST CONDITIONS	MIN.	TYP. <sup>(7)</sup>	MAX.	UNIT	
Power Supply				•		•	
$V_{M}$ working current	І∨м	No PWM input	-	0.8	1.2	mA	
V <sub>M</sub> standby current	Ivm q	nSleep = 0	-	0.01	1	μA	
Output H-bridge		·					
High side + low side bridge	D	I <sub>OUT</sub> = 500mA, T <sub>J</sub> = 25°C	-	350	450		
conduction resistance	Rds on	I <sub>OUT</sub> = 500mA, T <sub>J</sub> = 125°C	-	530	700	mΩ	
Off-state leakage current	IOFF	V <sub>OUT</sub> = 0V	-10	-	10	μA	
Logic Input Pin (IN 1, IN 2, n	Sleep)						
Logic input low voltage	VIL	High level to low level	-	-	1.20	V	
Logic input high voltage	Vін	Low level to high level	1.60	-	-	V	
Logic input hysteresis	VIHY	V <sub>IN</sub> = 3.3V	-	0.3	-	V	
Logic input low current	lı∟	V <sub>IN</sub> = 0V	-5	-	5	μA	
Logic input high current	Ін	V <sub>IN</sub> = 3.3V	-	50	70	μA	
Pull down resistance	R <sub>PD</sub>	IN x pins and nSleep pin	-	100	-	kΩ	
Protection Circuits						•	
Thermal shutdown temperature	T <sub>SD</sub>	-	155	170	180	°C	
Thermal shutdown hysteresis	ΔTsd	-	-	20	-	°C	
Undervoltage protection voltage	Vuvlo	V <sub>CC</sub> power supply	-	3.00	-	V	
Undervoltage protection hysteresis	ΔΫυνιο	V <sub>CC</sub> power supply	-	0.20	-	V	
		High side	-	3.0	-		
Output current limit	IOUT Limit	Low side - 3.0		3.0	-	A	
OCP delay time	t⊳	-	-	2.3	-	μs	
OCP retry time	t <sub>R</sub>	-	-	1.5		ms	

#### Note:

(7) Typical numbers are at 25°C and represent the most likely norm.

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## 6 Specifications

## 6.6 Time Series Parameters

CJDR9110T (	$(V_{CC} = 5.0V, T_{A})$	$= 25^{\circ}C, R_{L} = 20\Omega,$	, unless otherwise spec	;ified)
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CHARACTERISTIC	SYMBOL	TEST CONDITIONS	MIN.	<b>TYP.</b> <sup>(7)</sup>	MAX.	UNIT
Start-up time	T1	-	-	-	10	μs
Shutdown time	T2	-	-	180	220	ns
Input high to output high delay	Т3	-	-	160	200	ns
Input low to output low delay	T4	-	-	160	200	ns
Output rising edge time	T5	-	-	40	200	ns
Output drop edge time	Т6	-	-	2	3	ms

#### Note:

(7) Typical numbers are at 25°C and represent the most likely norm.

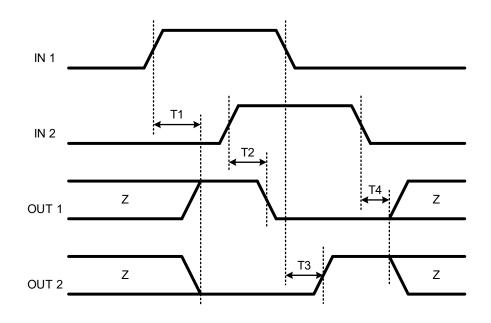


Figure 6-1. Input and Output Time Parameter 1

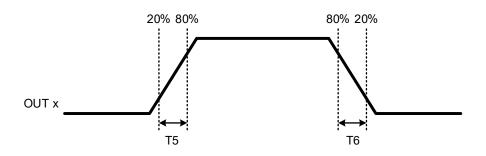


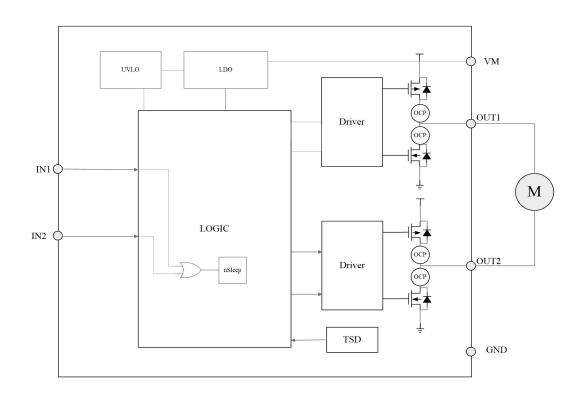
Figure 6-2. Input and Output Time Parameter 2

## 7 Detailed Description

## 7.1 Description

CJDR9110T is a 12V, single channel, full bridge motor drive integrated circuit. It supports 12V power input supply voltage and can provide up to 1.5A continuous output current. CJDR9110T has a PWM (IN / IN) input interface and is compatible with industry standard devices.

## 7.2 Functional Block Diagram



## 7 Detailed Description

#### 7.3 Feature Description

#### **PWM Control Mode**

CJDR9110T is controlled by PWM input interface, also known as IN / IN input mode, the PWM interface (IN 1 / IN 2) controls the OUT x pins according to the logic table in Table 7-1.

IN 1	IN 2	OUT 1	OUT 2	DESCRIPTION
0	0	Hi-Z	Hi-Z	Coast (H-bridge Hi-Z) / low-power automatic sleep mode
0	1	L	Н	Reverse (OUT 2 $\rightarrow$ OUT 1)
1	0	н	L	Forward (OUT 1 $\rightarrow$ OUT 2)
1	1	L	L	Brake (low-side slow decay)

Table 7-1. PWM Control Mode with Automatic Sleep

#### Sleep Mode

When IN 1 and IN 2 are at low level, the device will enter sleep mode. At this time, the internal circuit of the device will stop working, and the current power consumption will be less than  $1\mu$ A.

When one of IN 1 and IN 2 is at high level and the other is at low level, the device will resume normal operation.

The recovery time from sleep mode to normal operation shall not exceed 10 $\ensuremath{\mu s}.$ 

If the control logic of IN 1= IN 2= 0 needs to be used when using the control mode of pulse width modulation for adjustment, ensure that keep the input low level within the range of  $0.9V \sim 1.2V$ .

#### Input Pin

IN 1 and IN 2 input pins have  $100k\Omega$  resistance pull-down, and the default is low level.

#### Thermal Shutdown

When the junction temperature  $T_J$  exceeds 170°C (Typ.), the thermal shutdown circuit is activated and all outputs of the device will be turned off. When the  $T_J$  decreases by a hysteresis temperature of 20°C (Typ.), the device will return to normal operation.

Although the internal protection circuit of the device is designed to prevent overall thermal conditions, it is not intended to replace appropriate power consumption. Continuous operation of the equipment until thermal shutdown or higher than the recommended  $T_J$  will reduce long-term reliability.

#### **Undervoltage Locking**

When the power supply voltage is lower than  $V_{UVLO}$ , the device will enter the undervoltage protection mode, and the internal detection circuit will turn off the H-bridge output. At this time, if the power supply voltage rises within a certain range of  $\Delta V_{UVLO}$ , the device will release the undervoltage protection mode and resume normal operation.

## 7 Detailed Description

## 7.3 Feature Description (continued)

#### **Built-in Current Limit**

Each drive MOS of the H-bridge in CJDR9110T has a built-in current limiting mechanism. When it is detected that the current of any drive MOS exceeds the output current limit  $I_{OUT \ Limit}$  in the data sheet and the duration exceeds the delay time  $T_D$ , all drive MOS will be turned off. After the retry time  $T_R$ , the drive tube will automatically attempt to resume normal operation. At this time, if the output current still exceeds the rated range, the device will enter the current limit state again and turn off the output. Therefore, when the device enters the output current limit state because the output current exceeds the rated range, the device will continue the process of "Detection - Shutdown - Release - Detection" until the output current no longer exceeds its rated range. Typical values of output current limit  $I_{OUT \ Limit}$ , delay time  $T_D$  and retry time  $T_R$  can be found in *Electrical Characteristics*.

#### **Short Circuit Protection**

CJDR9110T has short circuit protection mechanism. When OUT x is short circuited to GND (for example, when the high side of OUT 1 is conductive, OUT 1 is abnormally short circuited to GND), or when OUT x is short circuited to VM (for example, when the lower side of OUT 1 is conductive, OUT 1 is abnormally short circuited to VM), the device will turn off the output of all drive MOS to protect the device from being burnt due to large current. The action mechanism of short-circuit protection is the same as that of current limit. See *Build-in Current Limit* for more details.

#### **Operation Mode**

CJDR9110T enters the sleep mode when both IN 1 and IN 2 are low. In the sleep mode, all h-bridges are turned off and output high resistance state. Most circuits of chip circuits are turned off and enter the power saving mode. When IN 1 and IN 2 are not low at the same time, they will automatically resume normal operation. When the over temperature protection detects failure, it will also close the H-bridge.

		-
MODE CONDITION		H-BRIDGE
Work	0 when IN 1 is different from IN 2	Normal Operation
Sleep mode	IN 1 = IN 2 = 0	Shutdown
Failure detection	IN x = X	Shutdown

 Table 7-2. Operation Mode

## 8 Application and Implementation

## 8.1 Typical Application Circuit

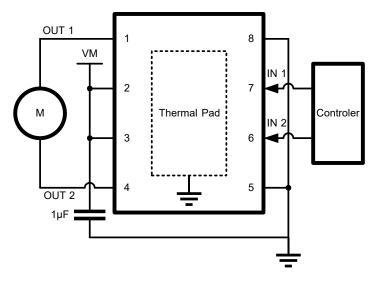


Figure 8-1. Typical Application Circuit

#### 8.2 Application Information

The absolute parameters of the device cannot be exceeded in any environment.

The bypass capacitor of  $V_{CC}$ , especially the connection of ceramic capacitor, should be as close to the  $V_{CC}$  pin of the device as possible.

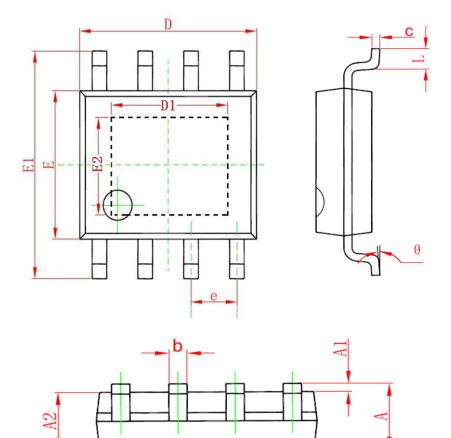
The ground wire connecting the motor needs to be isolated in layout design.

## NOTE

The application information in this section is not part of the data sheet component specification, and JSCJ makes no commitment or statement to guarantee its accuracy or completeness. Customers are responsible for determining the rationality of corresponding components in their circuit design and making tests and verifications to ensure the normal realization of their circuit design.

## 9 Mechanical Information

## **ESOP8 Outline Dimensions**



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min.	Max.	Min.	Max.
A	1.300	1.700	0.051	0.067
A1	0.000	0.100	0.000	0.004
A2	1.350	1.550	0.053	0.061
b	0.330	0.510	0.013	0.020
С	0.170	0. 250	0.006	0.010
D	4.700	5.100	0.185	0.200
D1	3.202	3.402	0.126	0.134
E	3.800	4.000	0.150	0.157
E1	5.800	6.200	0.228	0.244
E2	2.313	2.513	0.091	0.099
е	1.270(BSC)		0.050(BSC)	
L	0.400	1.270	0.016	0.050
θ	0°	8°	0°	8°

## 10 Notes and Revision History

#### **10.1 Associated Product Family and Others**

To view other products of the same type or IC products of other types, click the official website of JSCJ -- https: *www.jscj-elec.com* for more details.

#### 10.2 Notes

#### **Electrostatic Discharge Caution**



This IC may be damaged by ESD. Relevant personnel shall comply with correct installation and use specifications to avoid ESD damage to the IC. If appropriate measures are not taken to prevent ESD damage, the hazards caused by ESD include but are not limited to degradation of integrated circuit performance or complete damage of integrated circuit. For some precision integrated circuits, a very small parameter change may cause the whole device to be inconsistent with its published specifications.

#### 10.3 Revision History

August, 2022: released CJDR9110T rev - 1.0.

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