

# CA-IS1300x 5-kV<sub>RMS</sub> Isolated Amplifier for Current Sensing

## 1 Key Features

- Differential Input Voltage Range:  $\pm 50$  mV or  $\pm 250$  mV
- Fixed Initial Gain: 8.2 or 41
- Low Input Offset and Drift:
  - CA-IS1300G05:  $\pm 0.1$  mV (max) at 25°C,  $\pm 1$   $\mu$ V/°C (max)
  - CA-IS1300G25:  $\pm 1$  mV (max) at 25°C,  $\pm 4$   $\mu$ V/°C (max)
  - CA-IS1300B25:  $\pm 0.2$  mV (max) at 25°C,  $\pm 4$   $\mu$ V/°C (max)
- Low Gain Error and Drift:
  - CA-IS1300G05:  $\pm 0.3\%$  (max) at 25°C,  $\pm 50$  ppm/°C (max)
  - CA-IS1300G25:  $\pm 0.5\%$  (max) at 25°C,  $\pm 50$  ppm/°C (max)
  - CA-IS1300B25:  $\pm 0.3\%$  (max) at 25°C,  $\pm 50$  ppm/°C (max)
- Low Nonlinearity and Drift: 0.01% (typ) for Full Scale,  $\pm 1$  ppm/°C (typ)
- 3.3-V or 5-V Operation for Both High- and Low-Side
- High CMTI:  $\pm 150$  kV/ $\mu$ s (typ)
- Wide Operating Temperature Range:  $-40^\circ\text{C}$  to  $125^\circ\text{C}$
- Safety-Related Certifications (Pending)
  - 7070-V<sub>PK</sub> Isolation per DIN V VDE V 0884-11 (VDE V 0884-11): 2017-01
  - 5-kV<sub>RMS</sub> Isolation for 1 Minute per UL 1577
  - CQC and TUV Certification Approvals
- >40-year Life at Rated Working Voltage

## 2 Applications

- Industrial Motor Controls and Drives
- Isolated Switch Mode Supplies
- Uninterruptible Power Supplies

## 3 Description

The CA-IS1300x devices are high-precision isolated amplifiers and optimized for shunt-resistor-based current sensing. Low offset and gain error and drift guarantee that measuring accuracy is maintained over the entire operating temperature range.

The CA-IS1300x devices utilize silicon oxide (SiO<sub>2</sub>) isolation barriers and support up to 5-kV<sub>RMS</sub> galvanic isolation per UL

1577. This technology separates high- and low-voltage domain to protect lower-voltage parts from damage and provides low emissions as well as strong anti-interference capability from magnetic changes. The high common-mode transient immunity (CMTI) means that the CA-IS1300x devices transmit correct signals through isolation barriers and are suitable for industrial motor controls and drives which require high-voltage and high-power switching. The internal input common-mode overvoltage and missing high-side supply voltage detection functions contribute to fault diagnostics and system safety.

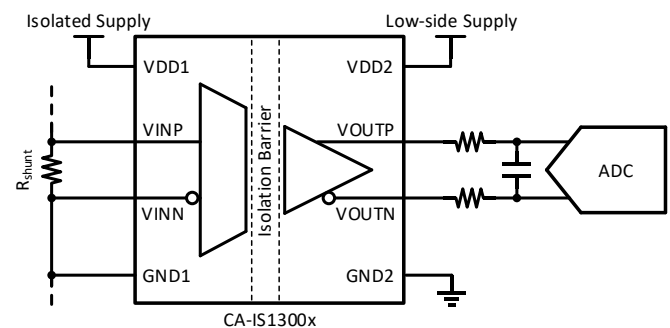
The CA-IS1300x series provide two input voltage range options and the smaller rank ( $\pm 50$  mV) allows significant reduction of the power dissipation through the shunt resistor.

The CA-IS1300x devices are packaged in wide body, 8-pin SOIC packages and specified over the extended industrial temperature range of  $-40^\circ\text{C}$  to  $125^\circ\text{C}$ .

### Device Information

| PART NUMBER | PACKAGE      | BODY SIZE (NOM)   |
|-------------|--------------|-------------------|
| CA-IS1300x  | SOIC8-WB (G) | 5.85 mm × 7.50 mm |

### Simplified Schematic



#### 4 Ordering Guide

Table 4-1 Ordering Guide for Valid Ordering Part Number

| Ordering Part Number | Specified Input Range | Gain | Gain Error  | Input $V_{OS}$ | Isolation Rating    | Package  |
|----------------------|-----------------------|------|-------------|----------------|---------------------|----------|
| CA-IS1300G05G        | $\pm 50$ mV           | 41   | $\pm 0.3\%$ | $\pm 0.1$ mV   | 5 kV <sub>RMS</sub> | SOIC8-WB |
| CA-IS1300G25G        | $\pm 250$ mV          | 8.2  | $\pm 0.5\%$ | $\pm 1$ mV     | 5 kV <sub>RMS</sub> | SOIC8-WB |
| CA-IS1300B25G        | $\pm 250$ mV          | 8.2  | $\pm 0.3\%$ | $\pm 0.2$ mV   | 5 kV <sub>RMS</sub> | SOIC8-WB |

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### 5 Revision History

| Revision     | Description  | Page        |
|--------------|--|-------------|
| Version 1.00 | Updated data of CA-IS1300G25G  | NA          |
| Version 1.01 | Updated data of CA-IS1300B25G<br>Added CA-IS1300B25G character curve | 10~11<br>16 |
| Version 1.02 | Change POD and tape information                                      | 23,25       |
| Version 1.03 | Updated UL certification information                                 | 7           |

## 6 Pin Descriptions and Functions

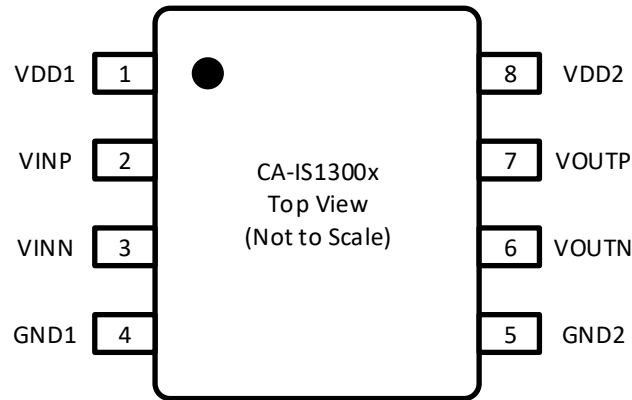


Figure 6-1 CA-IS1300x Top View

Table 6-1 CA-IS1300x Pin Description and Functions

| NAME  | PIN NUMBER | TYPE   | DESCRIPTION                          |
|-------|------------|--------|--------------------------------------|
| VDD1  | 1          | Power  | High-side power supply, 3 V to 5.5 V |
| VINP  | 2          | Input  | Noninverting analog input            |
| VINN  | 3          | Input  | Inverting analog input               |
| GND1  | 4          | Ground | High-side ground                     |
| GND2  | 5          | Ground | Low-side ground                      |
| VOUTN | 6          | Output | Inverting analog output              |
| VOUTP | 7          | Output | Noninverting analog output           |
| VDD2  | 8          | Power  | Low-side power supply, 3 V to 5.5 V  |

## 7 Specifications

### 7.1 Absolute Maximum Ratings<sup>1</sup>

| PARAMETER        |   | MIN        | MAX                     | UNIT |
|------------------|---|------------|-------------------------|------|
| VDD1, VDD2       | Supply voltage <sup>2</sup>                 | -0.5       | 6.5                     | V    |
| VINP, VINN       | Analog input voltage                        | GND1 - 6   | 6.5                     | V    |
| VOU TP, VOU TN   | Analog output voltage                       | GND2 - 0.5 | VDD2 + 0.5 <sup>3</sup> | V    |
| I <sub>IN</sub>  | Input current to any pin except supply pins | -10        | 10                      | mA   |
| T <sub>J</sub>   | Junction Temperature                        |            | 150                     | °C   |
| T <sub>STG</sub> | Storage Temperature                         | -65        | 150                     | °C   |

**NOTE:**

- Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- All voltage values are with respect to the local ground terminal (GND1 or GND2) and are peak voltage values.
- Maximum voltage must not exceed 6.5 V.

### 7.2 ESD Ratings

|  |   | VALUE | UNIT |
|--|---|-------|------|
| V <sub>ESD</sub> Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins              | ±4000 | V    |
|  | Charged device model (CDM), per JEDEC specification JESD22-C101, all pins | ±2000 |      |

### 7.3 Recommended Operating Conditions

| PARAMETER      |  | MIN | NOM | MAX | UNIT |
|----------------|--|-----|-----|-----|------|
| VDD1           | High-side supply voltage, with respect to GND1 | 3.0 | 5.0 | 5.5 | V    |
| VDD2           | Low-side supply voltage, with respect to GND2  | 3.0 | 3.3 | 5.5 | V    |
| T <sub>A</sub> | Ambient Temperature                            | -40 |     | 125 | °C   |

### 7.4 Thermal Information

| THERMAL METRIC           |  | VALUE | UNIT |
|--------------------------|--|-------|------|
| R <sub>θJA</sub>         | Junction-to-ambient thermal resistance       | 110.1 | °C/W |
| R <sub>θJC(top)</sub>    | Junction-to-case (top) thermal resistance    | 51.7  | °C/W |
| R <sub>θJB</sub>         | Junction-to-board thermal resistance         | 66.4  | °C/W |
| ψ <sub>JT</sub>          | Junction-to-top characterization parameter   | 16.0  | °C/W |
| ψ <sub>JB</sub>          | Junction-to-board characterization parameter | 64.5  | °C/W |
| R <sub>θJC(bottom)</sub> | Junction-to-case (bottom) thermal resistance | NA    | °C/W |

### 7.5 Power Ratings

| PARAMETER       |  | TEST CONDITIONS                   | VALUE  | UNIT |
|-----------------|--|-----------------------------------|--------|------|
| P <sub>D</sub>  | Maximum power dissipation for both sides | CA-IS1300G05, VDD1 = VDD2 = 5.5 V | 134.75 | mW   |
|                 |  | CA-IS1300G25, VDD1 = VDD2 = 5.5 V | 129.25 |      |
|                 |  | CA-IS1300B25, VDD1 = VDD2 = 5.5 V | 134.75 |      |
| P <sub>D1</sub> | Maximum power dissipation for high-side  | CA-IS1300G05, VDD1 = 5.5 V        | 90.75  | mW   |
|                 |  | CA-IS1300G25, VDD1 = 5.5 V        | 85.25  |      |
|                 |  | CA-IS1300B25, VDD1 = 5.5 V        | 90.75  |      |
| P <sub>D2</sub> | Maximum power dissipation for low-side   | VDD2 = 5.5 V                      | 44.00  | mW   |

**7.6 Insulation Specifications**

| PARAMETR   |   | TEST CONDITIONS   | VALUE              | UNIT             |
|--|---|---|--------------------|------------------|
| CLR  | External clearance <sup>1</sup>                   | Shortest terminal-to-terminal distance through air  | 8                  | mm               |
| CPG  | External creepage <sup>1</sup>                    | Shortest terminal-to-terminal distance across the package surface   | 8                  | mm               |
| DTI  | Distance through the insulation                   | Minimum internal gap (internal clearance)   | 28                 | μm               |
| CTI  | Comparative tracking index                        | DIN EN 60112 (VDE 0303-11); IEC 60112   | > 600              | V                |
|  | Material group                                    | According to IEC 60664-1  | I                  |                  |
|  | Overvoltage category per IEC 60664-1              | Rated mains voltage ≤ 300 V <sub>RMS</sub>  | I-IV               |                  |
|  |   | Rated mains voltage ≤ 400 V <sub>RMS</sub>  | I-IV               |                  |
|  |   | Rated mains voltage ≤ 600 V <sub>RMS</sub>  | I-III              |                  |
| <b>DIN V VDE V 0884-11:2017-01<sup>2</sup></b>   |   |   |                    |                  |
| V <sub>IORM</sub>  | Maximum repetitive peak isolation voltage         | AC voltage (bipolar)  | 1414               | V <sub>PK</sub>  |
| V <sub>IOWM</sub>  | Maximum working isolation voltage                 | AC voltage; Time dependent dielectric breakdown (TDDB) Test   | 1000               | V <sub>RMS</sub> |
|  |   | DC voltage  | 1414               | V <sub>DC</sub>  |
| V <sub>IOTM</sub>  | Maximum transient isolation voltage               | V <sub>TEST</sub> = V <sub>IOTM</sub> ,<br>t = 60 s (qualification);<br>V <sub>TEST</sub> = 1.2 × V <sub>IOTM</sub> ,<br>t = 1 s (100% production)  | 7070               | V <sub>PK</sub>  |
| V <sub>IOSM</sub>  | Maximum surge isolation voltage <sup>3</sup>      | Test method per IEC 60065, 1.2/50 μs waveform,<br>V <sub>TEST</sub> = 1.6 × V <sub>IOSM</sub> (qualification)   | 6250               | V <sub>PK</sub>  |
| q <sub>pd</sub>  | Apparent charge <sup>4</sup>                      | Method b1, At routine test (100% production) and preconditioning (type test)<br>V <sub>ini</sub> = 1.2 × V <sub>IOTM</sub> , t <sub>ini</sub> = 1 s;<br>V <sub>pd(m)</sub> = 1.875 × V <sub>IORM</sub> , t <sub>m</sub> = 1 s | ≤ 5                | pC               |
| C <sub>IO</sub>  | Barrier capacitance, input to output <sup>5</sup> | V <sub>IO</sub> = 0.4 × sin(2πft), f = 1 MHz  | ~ 1                | pF               |
| R <sub>IO</sub>  | Isolation resistance <sup>5</sup>                 | V <sub>IO</sub> = 500 V, T <sub>A</sub> = 25°C  | > 10 <sup>12</sup> | Ω                |
|  |   | V <sub>IO</sub> = 500 V, 100°C ≤ T <sub>A</sub> ≤ 125°C   | > 10 <sup>11</sup> |                  |
|  |   | V <sub>IO</sub> = 500 V at T <sub>S</sub> = 150°C   | > 10 <sup>9</sup>  |                  |
|  | Pollution degree                                  |   | 2                  |                  |
| <b>UL 1577</b>   |   |   |                    |                  |
| V <sub>ISO</sub>   | Maximum withstanding isolation voltage            | V <sub>TEST</sub> = V <sub>ISO</sub> , t = 60 s (qualification),<br>V <sub>TEST</sub> = 1.2 × V <sub>ISO</sub> , t = 1 s (100% production)  | 5000               | V <sub>RMS</sub> |
| <b>NOTE:</b>   |   |   |                    |                  |
| 1. Creepage and clearance requirements should be applied according to the specific equipment isolation standards of an application. Care should be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed-circuit board do not reduce this distance. Creepage and clearance on a printed-circuit board become equal in certain cases. Techniques such as inserting grooves and/or ribs on a printed circuit board are used to help increase these specifications. |   |   |                    |                  |
| 2. This coupler is suitable for safe electrical insulation only within the safety ratings. Compliance with the safety ratings shall be ensured by means of suitable protective circuits.   |   |   |                    |                  |
| 3. Testing is carried out in air or oil to determine the intrinsic surge immunity of the isolation barrier.  |   |   |                    |                  |
| 4. Apparent charge is electrical discharge caused by a partial discharge (pd).   |   |   |                    |                  |
| 5. All pins on each side of the barrier tied together creating a two-terminal device.  |   |   |                    |                  |

**7.7 Safety-Related Certifications**

| VDE (Pending)                                      | UL   | CQC (Pending)                        |
|--|--|--------------------------------------|
| Certified according to DIN V VDE V 0884-11:2017-01 | Recognized under UL 1577 Component Recognition Program | Certified according to GB4943.1-2011 |
| Certification number:                              | Certification number: E511334-20200520                 | Certification number:                |

**7.8 Electrical Characteristics: CA-IS1300G05**

All minimum and maximum specifications apply from  $T_A = -40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $V_{DD1} = V_{DD2} = 3\text{ V}$  to  $5.5\text{ V}$ ,  $V_{INP} = -50\text{ mV}$  to  $50\text{ mV}$ , and  $V_{INN} = \text{GND1} = 0\text{ V}$  (unless otherwise noted). All typical specifications are at  $T_A = 25^{\circ}\text{C}$ ,  $V_{DD1} = 5\text{ V}$ , and  $V_{DD2} = 3.3\text{ V}$  (unless otherwise noted).

| PARAMETER                 |   | TEST CONDITIONS  | MIN                  | TYP          | MAX                    | UNIT                           |
|---------------------------|---|--|----------------------|--------------|------------------------|--------------------------------|
| <b>ANALOG INPUT</b>       |   |  |                      |              |                        |                                |
| $V_{\text{Clipping}}$     | Maximum input voltage before clipping output    | $V_{\text{INP}} - V_{\text{INN}}$  |                      | $\pm 64$     |                        | mV                             |
| $V_{\text{FSR}}$          | Specified linear full-scale input range         | $V_{\text{INP}} - V_{\text{INN}}$  | -50                  |              | 50                     | mV                             |
| $V_{\text{CM}}$           | Operating common-mode input voltage             | $(V_{\text{INP}} + V_{\text{INN}}) / 2$ to GND1  | -0.032               |              | $V_{\text{DD1}} - 2.1$ | V                              |
| $V_{\text{CMOV}}$         | Common-mode overvoltage threshold               | $(V_{\text{INP}} + V_{\text{INN}}) / 2$ to GND1  | $V_{\text{DD1}} - 2$ |              |                        | V                              |
| $V_{\text{CMOV\_HYS}}$    | Hysteresis of common-mode overvoltage threshold |  |                      | 100          |                        | mV                             |
| $V_{\text{OS}}$           | Input offset voltage                            | Initial, at $T_A = 25^{\circ}\text{C}$ ,<br>$V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$                  | -100                 | $\pm 10$     | 100                    | $\mu\text{V}$                  |
| $\text{TCV}_{\text{OS}}$  | Input offset voltage drift                      |  | -1                   | $\pm 0.15$   | 1                      | $\mu\text{V}/^{\circ}\text{C}$ |
| $\text{CMRR}_{\text{IN}}$ | Input common-mode rejection ratio               | DC, $V_{\text{INP}} = V_{\text{INN}}$  |                      | -100         |                        | dB                             |
|                           |   | $f_{\text{IN}} = 10\text{ kHz}$ , $V_{\text{INP}} = V_{\text{INN}}$  |                      | -98          |                        |                                |
| $C_{\text{IN}}$           | Single-ended input capacitance                  | $f_{\text{IN}} = 300\text{ kHz}$ , $V_{\text{INN}} = \text{GND1}$  |                      | 4            |                        | pF                             |
| $C_{\text{IND}}$          | Differential input capacitance                  | $f_{\text{IN}} = 300\text{ kHz}$   |                      | 2            |                        | pF                             |
| $R_{\text{IN}}$           | Single-ended input resistance                   | $V_{\text{INN}} = \text{GND1}$   |                      | 4.75         |                        | k $\Omega$                     |
| $R_{\text{IND}}$          | Differential input resistance                   |  |                      | 4.9          |                        | k $\Omega$                     |
| $I_{\text{IN}}$           | Input current                                   | $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$ ,<br>$I_{\text{IN}} = (I_{\text{INP}} + I_{\text{INN}}) / 2$ | -48.5                | -36          | -28.5                  | $\mu\text{A}$                  |
| $\text{TCI}_{\text{IN}}$  | Input current drift                             |  |                      | $\pm 1.5$    |                        | nA/ $^{\circ}\text{C}$         |
| $I_{\text{INOS}}$         | Input offset current                            |  |                      | $\pm 10$     |                        | nA                             |
| $\text{BW}_{\text{IN}}$   | Input bandwidth                                 |  |                      | 1000         |                        | kHz                            |
| <b>ANALOG OUTPUT</b>      |   |  |                      |              |                        |                                |
|                           | Gain <sup>1</sup>                               | Initial  |                      | 41           |                        | V/V                            |
| $E_{\text{G}}$            | Gain error                                      | Initial, at $T_A = 25^{\circ}\text{C}$   | -0.3%                | $\pm 0.05\%$ | 0.3%                   |                                |
| $\text{TCE}_{\text{G}}$   | Gain error drift                                |  | -50                  | $\pm 15$     | 50                     | ppm/ $^{\circ}\text{C}$        |
| NL                        | Nonlinearity <sup>2</sup>                       |  | -0.03%               | $\pm 0.01\%$ | 0.03%                  |                                |
| $\text{TCNL}$             | Nonlinearity drift                              |  |                      | $\pm 1$      |                        | ppm/ $^{\circ}\text{C}$        |
|                           | Output noise                                    | $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$ , $\text{BW} = 100\text{ kHz}$                               |                      | 260          |                        | $\mu\text{V}_{\text{RMS}}$     |
| THD                       | Total harmonic distortion                       | $V_{\text{IN}} = 100\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 10\text{ kHz}$ , $\text{BW} = 100\text{ kHz}$ |                      | -85          |                        | dB                             |
| SNR                       | Signal-to-noise ratio                           | $V_{\text{IN}} = 100\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 1\text{ kHz}$ , $\text{BW} = 10\text{ kHz}$   |                      | 84           |                        | dB                             |
|                           |   | $V_{\text{IN}} = 100\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 10\text{ kHz}$ , $\text{BW} = 100\text{ kHz}$ |                      | 70           |                        |                                |
| PSRR                      | Power supply rejection ratio <sup>3</sup>       | At $V_{\text{DD1}}$ , DC   |                      | -113         |                        | dB                             |
|                           |   | At $V_{\text{DD1}}$ , 100-mV and 10-kHz ripple   |                      | -108         |                        |                                |
|                           |   | At $V_{\text{DD2}}$ , DC   |                      | -116         |                        |                                |
|                           |   | At $V_{\text{DD2}}$ , 100-mV and 10-kHz ripple   |                      | -87          |                        |                                |
| $V_{\text{CMOUT}}$        | Common-mode output voltage                      |  | 1.39                 | 1.44         | 1.49                   | V                              |
| $V_{\text{FAILSAFE}}$     | Fail-safe differential output voltage           | $V_{\text{CMOV}} \leq V_{\text{CM}}$ or $V_{\text{DD1}}$ missing   |                      | -2.6         | -2.5                   | V                              |
| $I_{\text{OSC}}$          | Output short-circuit current                    | $\text{VOUTP}$ or $\text{VOUTN}$ shorts to $V_{\text{DD2}}$ or $\text{GND2}$                                 |                      | $\pm 13$     |                        | mA                             |
| $R_{\text{OUT}}$          | Output resistance                               | On $\text{VOUTP}$ or $\text{VOUTN}$  |                      | < 0.2        |                        | $\Omega$                       |
| $\text{BW}_{\text{OUT}}$  | Output bandwidth (-3 dB)                        |  | 250                  | 310          |                        | kHz                            |
| CMTI                      | Common-mode transient immunity                  | $ \text{GND1} - \text{GND2}  = 1.5\text{ kV}$ ; <i>See Figure 8-1</i>  | 100                  | 150          |                        | kV/ $\mu\text{s}$              |
| <b>POWER SUPPLY</b>       |   |  |                      |              |                        |                                |
| $V_{\text{DDUv}}$         | VDD undervoltage threshold                      | $V_{\text{DD1}}$ or $V_{\text{DD2}}$ rising  |                      | 2.5          | 2.7                    | V                              |



|  |                                      |  |      |      |               |
|--|--------------------------------------|--|------|------|---------------|
| IDD1   | High-side supply current             | $3.0\text{ V} \leq \text{VDD1} \leq 3.6\text{ V}$  | 10.5 | 15.0 | mA            |
|  |                                      | $4.5\text{ V} \leq \text{VDD1} \leq 5.5\text{ V}$  | 11.5 | 16.5 |               |
| IDD2   | Low-side supply current              | $3.0\text{ V} \leq \text{VDD2} \leq 3.6\text{ V}$  | 5.2  | 7.2  | mA            |
|  |                                      | $4.5\text{ V} \leq \text{VDD2} \leq 5.5\text{ V}$  | 5.7  | 8.0  |               |
| <b>TIMING</b>  |                                      |  |      |      |               |
| $t_r$  | Rise time of VOUT (10% – 90%)        | VINP = 0 to 0.1 V step; <i>See Figure 8-2</i>  | 1.2  |      | $\mu\text{s}$ |
| $t_f$  | Fall time of VOUT (90% – 10%)        | VINP = 0.1 V to 0 step; <i>See Figure 8-2</i>  | 1.2  |      | $\mu\text{s}$ |
| $t_{PD}$   | VIN to VOUT signal delay (50% – 50%) | Output unfiltered; <i>See Figure 8-3</i>   | 1.5  | 2.1  | $\mu\text{s}$ |
| $t_{AS}$   | Analog settling time                 | VDD1 = 0 to 3 V step and $3.0\text{ V} \leq \text{VDD2}$ , to VOUT valid (0.1% settling) | 500  |      | $\mu\text{s}$ |
| <b>NOTE:</b>   |                                      |  |      |      |               |
| <ol style="list-style-type: none"> <li>The gain is defined as the slope of the optimum line derived by the method of least squares between differential input voltage (VINP – VINN) and differential output voltage (VOUTP – VOUTN) over the specified input range.</li> <li>Nonlinearity is defined as a fraction of the half of the peak-to-peak value of differential output voltage deviation divided by the full-scale differential output voltage.</li> <li>This parameter is input referred.</li> </ol> |                                      |  |      |      |               |

**7.9 Electrical Characteristics: CA-IS1300x25**

All minimum and maximum specifications apply from  $T_A = -40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $V_{DD1} = V_{DD2} = 3\text{ V}$  to  $5.5\text{ V}$ ,  $V_{INP} = -250\text{ mV}$  to  $250\text{ mV}$ , and  $V_{INN} = \text{GND1} = 0\text{ V}$  (unless otherwise noted). All typical specifications are at  $T_A = 25^{\circ}\text{C}$ ,  $V_{DD1} = 5\text{ V}$ , and  $V_{DD2} = 3.3\text{ V}$  (unless otherwise noted).

| PARAMETER                 |   | TEST CONDITIONS  | MIN                  | TYP          | MAX                    | UNIT                           |
|---------------------------|---|--|----------------------|--------------|------------------------|--------------------------------|
| <b>ANALOG INPUT</b>       |   |  |                      |              |                        |                                |
| $V_{\text{Clipping}}$     | Maximum input voltage before clipping output    | $V_{\text{INP}} - V_{\text{INN}}$  |                      | $\pm 320$    |                        | mV                             |
| $V_{\text{FSR}}$          | Specified linear full-scale input range         | $V_{\text{INP}} - V_{\text{INN}}$  | -250                 |              | 250                    | mV                             |
| $V_{\text{CM}}$           | Operating common-mode input voltage             | $(V_{\text{INP}} + V_{\text{INN}}) / 2$ to GND1  | -0.16                |              | $V_{\text{DD1}} - 2.1$ | V                              |
| $V_{\text{CMOV}}$         | Common-mode overvoltage threshold               | $(V_{\text{INP}} + V_{\text{INN}}) / 2$ to GND1  | $V_{\text{DD1}} - 2$ |              |                        | V                              |
| $V_{\text{CMOV\_HYS}}$    | Hysteresis of common-mode overvoltage threshold |  |                      | 100          |                        | mV                             |
| $V_{\text{OS}}$           | Input offset voltage                            | CA-IS1300G25, Initial, at $T_A = 25^{\circ}\text{C}$ , $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$       | -1                   | $\pm 0.05$   | 1                      | mV                             |
|                           |   | CA-IS1300B25, Initial, at $T_A = 25^{\circ}\text{C}$ , $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$       | -0.2                 | $\pm 0.05$   | 0.2                    |                                |
| $\text{TCV}_{\text{OS}}$  | Input offset voltage drift                      | CA-IS1300G25   | -4                   | $\pm 1$      | 4                      | $\mu\text{V}/^{\circ}\text{C}$ |
|                           |   | CA-IS1300B25   | -3                   | $\pm 1$      | 3                      |                                |
| $\text{CMRR}_{\text{IN}}$ | Input common-mode rejection ratio               | DC, $V_{\text{INP}} = V_{\text{INN}}$  |                      | -98          |                        | dB                             |
|                           |   | $f_{\text{IN}} = 10\text{ kHz}$ , $V_{\text{INP}} = V_{\text{INN}}$  |                      | -98          |                        |                                |
| $C_{\text{IN}}$           | Single-ended input capacitance                  | $f_{\text{IN}} = 275\text{ kHz}$ , $V_{\text{INN}} = \text{GND1}$  |                      | 2            |                        | pF                             |
| $C_{\text{IND}}$          | Differential input capacitance                  | $f_{\text{IN}} = 275\text{ kHz}$   |                      | 1            |                        | pF                             |
| $R_{\text{IN}}$           | Single-ended input resistance                   | $V_{\text{INN}} = \text{GND1}$   |                      | 19           |                        | k $\Omega$                     |
| $R_{\text{IND}}$          | Differential input resistance                   |  |                      | 22           |                        | k $\Omega$                     |
| $I_{\text{IN}}$           | Input current                                   | $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$ ,<br>$I_{\text{IN}} = (I_{\text{INP}} + I_{\text{INN}}) / 2$ | -41                  | -30          | -24                    | $\mu\text{A}$                  |
| $\text{TCI}_{\text{IN}}$  | Input current drift                             |  |                      | $\pm 1$      |                        | nA/ $^{\circ}\text{C}$         |
| $I_{\text{INOS}}$         | Input offset current                            |  |                      | $\pm 5$      |                        | nA                             |
| $\text{BW}_{\text{IN}}$   | Input bandwidth                                 |  |                      | 1000         |                        | kHz                            |
| <b>ANALOG OUTPUT</b>      |   |  |                      |              |                        |                                |
|                           | Gain <sup>1</sup>                               | Initial, at $T_A = 25^{\circ}\text{C}$   |                      | 8.2          |                        | V/V                            |
| $E_{\text{G}}$            | Gain error                                      | CA-IS1300G25, Initial, at $T_A = 25^{\circ}\text{C}$   | -0.5%                | $\pm 0.05\%$ | 0.5%                   |                                |
|                           |   | CA-IS1300B25, Initial, at $T_A = 25^{\circ}\text{C}$   | -0.3%                | $\pm 0.05\%$ | 0.3%                   |                                |
| $\text{TCE}_{\text{G}}$   | Gain error drift                                |  | -50                  | $\pm 15$     | 50                     | ppm/ $^{\circ}\text{C}$        |
| NL                        | Nonlinearity <sup>2</sup>                       |  | -0.03%               | $\pm 0.01\%$ | 0.03%                  |                                |
| $\text{TCNL}$             | Nonlinearity drift                              |  |                      | $\pm 1$      |                        | ppm/ $^{\circ}\text{C}$        |
|                           | Output noise                                    | $V_{\text{INP}} = V_{\text{INN}} = \text{GND1}$ , $\text{BW} = 100\text{ kHz}$                               |                      | 330          |                        | $\mu\text{V}_{\text{RMS}}$     |
| THD                       | Total harmonic distortion                       | $V_{\text{IN}} = 500\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 10\text{ kHz}$ , $\text{BW} = 100\text{ kHz}$ |                      | -85          |                        | dB                             |
| SNR                       | Signal-to-noise ratio                           | $V_{\text{IN}} = 500\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 1\text{ kHz}$ , $\text{BW} = 10\text{ kHz}$   |                      | 83           |                        | dB                             |
|                           |   | $V_{\text{IN}} = 500\text{ mV}_{\text{pp}}$ , $f_{\text{IN}} = 10\text{ kHz}$ , $\text{BW} = 100\text{ kHz}$ |                      | 68           |                        |                                |
| PSRR                      | Power supply rejection ratio <sup>3</sup>       | At $V_{\text{DD1}}$ , DC   |                      | -100         |                        | dB                             |
|                           |   | At $V_{\text{DD1}}$ , 100-mV and 10-kHz ripple   |                      | -96          |                        |                                |
|                           |   | At $V_{\text{DD2}}$ , DC   |                      | -100         |                        |                                |
|                           |   | At $V_{\text{DD2}}$ , 100-mV and 10-kHz ripple   |                      | -98          |                        |                                |
| $V_{\text{CMOUT}}$        | Common-mode output voltage                      |  | 1.39                 | 1.44         | 1.49                   | V                              |
| $V_{\text{FAILSAFE}}$     | Fail-safe differential output voltage           | $V_{\text{CMOV}} \leq V_{\text{CM}}$ or $V_{\text{DD1}}$ missing   |                      | -2.6         | -2.5                   | V                              |
| $I_{\text{OSC}}$          | Output short-circuit current                    | $V_{\text{OUTP}}$ or $V_{\text{OUTN}}$ shorts to $V_{\text{DD2}}$ or $\text{GND2}$                           |                      | $\pm 13$     |                        | mA                             |
| $R_{\text{OUT}}$          | Output resistance                               | On $V_{\text{OUTP}}$ or $V_{\text{OUTN}}$  |                      | < 0.2        |                        | $\Omega$                       |
| $\text{BW}_{\text{OUT}}$  | Output bandwidth (-3 dB)                        |  | 250                  | 310          |                        | kHz                            |

|  |                                      |  |      |      |                         |
|--|--------------------------------------|--|------|------|-------------------------|
| CMTI   | Common-mode transient immunity       | $ GND1 - GND2  = 1.5 \text{ kV}$ ; <i>See Figure 8-1</i>                           | 100  | 150  | $\text{kV}/\mu\text{s}$ |
| <b>POWER SUPPLY</b>  |                                      |  |      |      |                         |
| VDD <sub>UV</sub>  | VDD undervoltage threshold           | VDD1 or VDD2 rising  | 2.5  | 2.7  | V                       |
| IDD1   | High-side supply current             | CA-IS1300G25, $3.0 \text{ V} \leq VDD1 \leq 3.6 \text{ V}$                         | 9.3  | 14.0 | mA                      |
|  |                                      | CA-IS1300G25, $4.5 \text{ V} \leq VDD1 \leq 5.5 \text{ V}$                         | 10.7 | 15.5 |                         |
|  |                                      | CA-IS1300B25, $3.0 \text{ V} \leq VDD1 \leq 3.6 \text{ V}$                         | 10.5 | 15.0 |                         |
|  |                                      | CA-IS1300B25, $4.5 \text{ V} \leq VDD1 \leq 5.5 \text{ V}$                         | 11.5 | 16.5 |                         |
| IDD2   | Low-side supply current              | $3.0 \text{ V} \leq VDD2 \leq 3.6 \text{ V}$                                       | 5.2  | 7.2  | mA                      |
|  |                                      | $4.5 \text{ V} \leq VDD2 \leq 5.5 \text{ V}$                                       | 5.7  | 8.0  |                         |
| t <sub>r</sub>   | Rise time of VOUT (10% – 90%)        | VINP = 0 to 0.5 V step; <i>See Figure 8-2</i>                                      | 1.2  |      | $\mu\text{s}$           |
| t <sub>f</sub>   | Fall time of VOUT (90% – 10%)        | VINP = 0.5 V to 0 step; <i>See Figure 8-2</i>                                      | 1.2  |      | $\mu\text{s}$           |
| t <sub>PD</sub>  | VIN to VOUT signal delay (50% – 50%) | Output unfiltered; <i>See Figure 8-3</i>   | 1.5  | 2.1  | $\mu\text{s}$           |
| t <sub>AS</sub>  | Analog settling time                 | VDD1 = 0 to 3 V step and $3.0 \text{ V} \leq VDD2$ , to VOUT valid (0.1% settling) | 500  |      | $\mu\text{s}$           |
| <b>NOTE:</b>   |                                      |  |      |      |                         |
| <ol style="list-style-type: none"> <li>The gain is defined as the slope of the optimum line derived by the method of least squares between differential input voltage (VINP – VINN) and differential output voltage (VOUTP – VOUTN) over the specified input range.</li> <li>Nonlinearity is defined as a fraction of the half of the peak-to-peak value of differential output voltage deviation divided by the full-scale differential output voltage.</li> <li>This parameter is input referred.</li> </ol> |                                      |  |      |      |                         |

**7.10 Typical Characteristics: CA-IS1300G25**

All typical specifications are at  $V_{INP} = -250\text{ mV to }250\text{ mV}$ , and  $V_{INN} = GND1 = 0\text{ V}$ ,  $V_{DD1} = 5\text{ V}$ , and  $V_{DD2} = 3.3\text{ V}$  (unless otherwise noted).

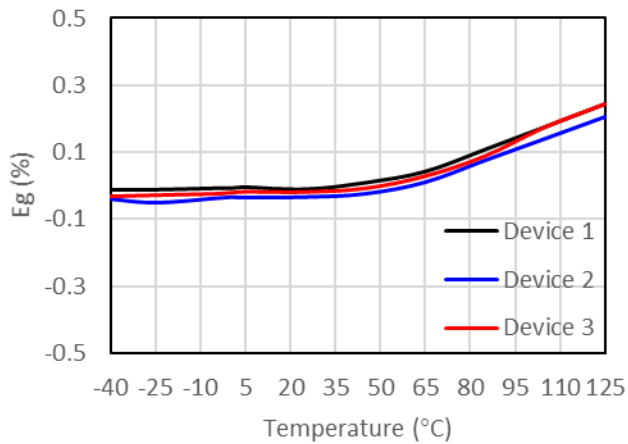


Figure 7-1 Gain Error vs Temperature

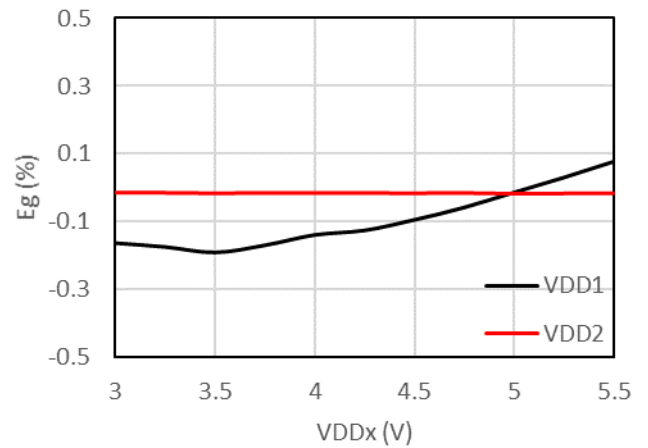


Figure 7-2 Gain Error vs Supply Voltage

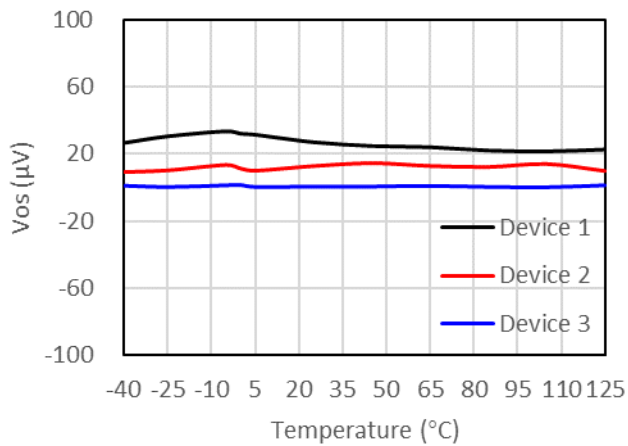


Figure 7-3 Input Offset vs Temperature

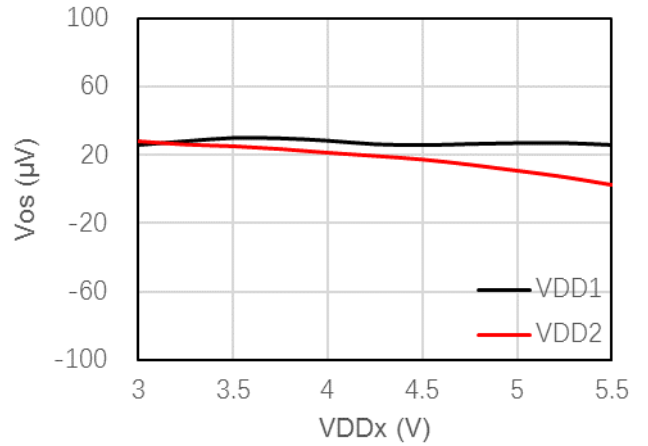


Figure 7-4 Input Offset vs Supply Voltage

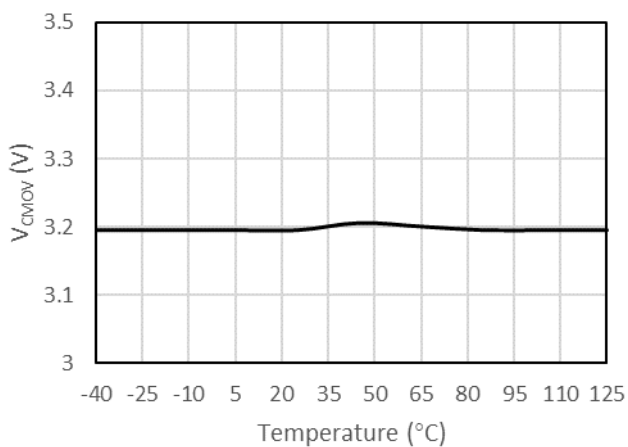


Figure 7-5 High-Side  $V_{CMOV}$  vs Temperature

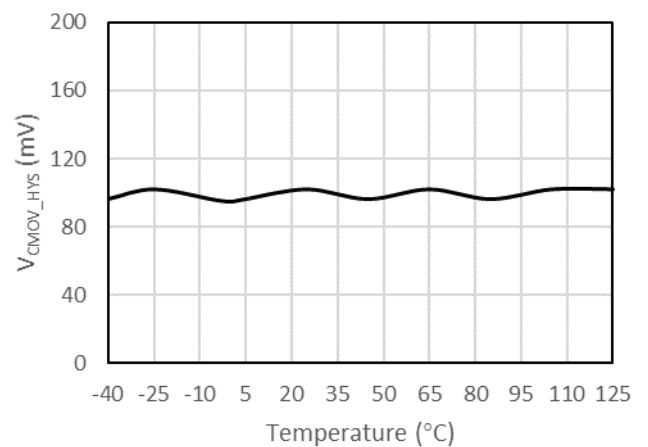


Figure 7-6 High-Side  $V_{CMOV\_HYS}$  vs Temperature

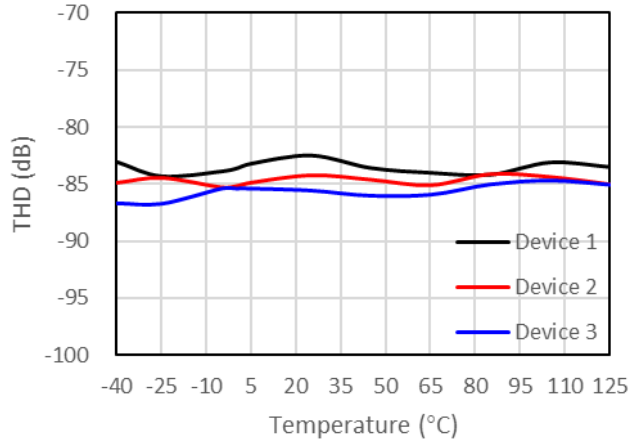


Figure 7-7 Total Harmonic Distortion vs Temperature @  $f_{IN} = 10 \text{ kHz}$

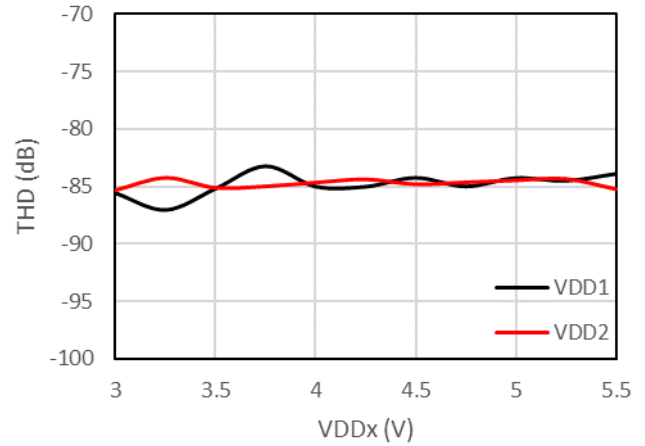


Figure 7-8 Total Harmonic Distortion vs Supply Voltage @  $f_{IN} = 10 \text{ kHz}$

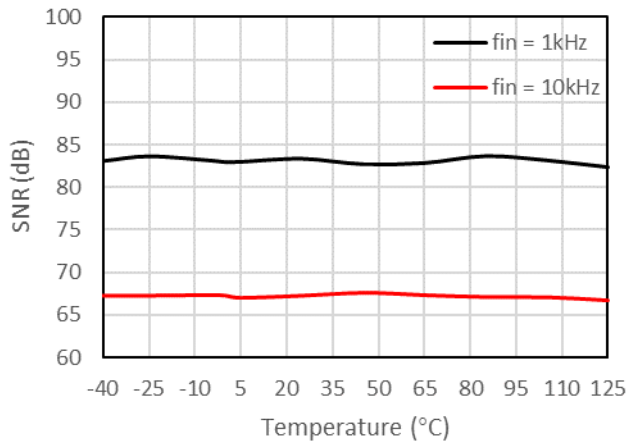


Figure 7-9 SNR vs Temperature

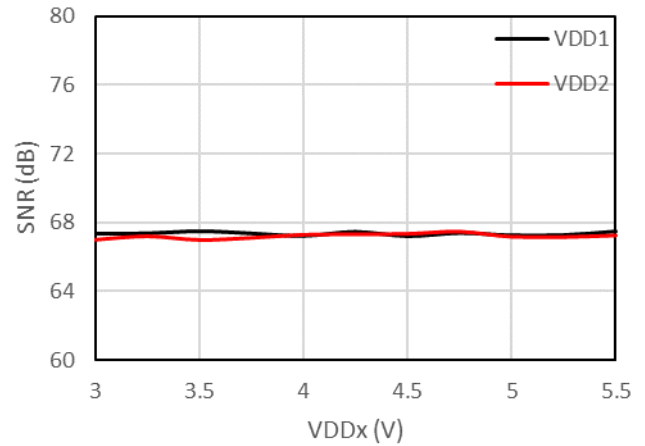


Figure 7-10 SNR vs Supply Voltage @  $f_{IN} = 10 \text{ kHz}$

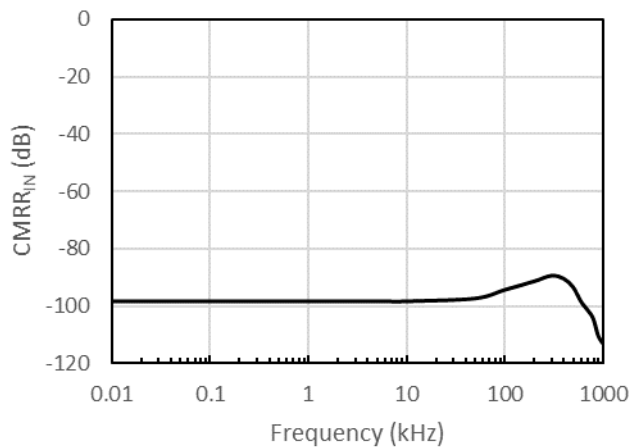


Figure 7-11 Input CMRR vs Frequency

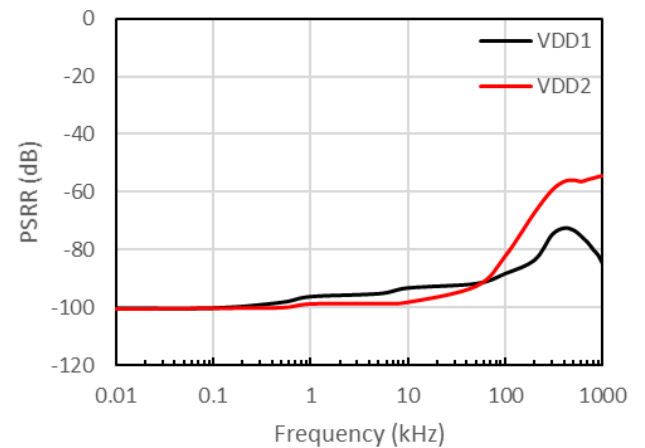


Figure 7-12 PSRR vs Frequency

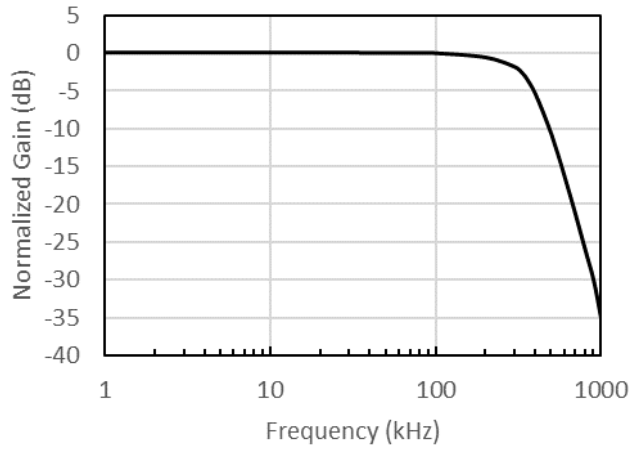


Figure 7-13 Normalized Gain vs Frequency

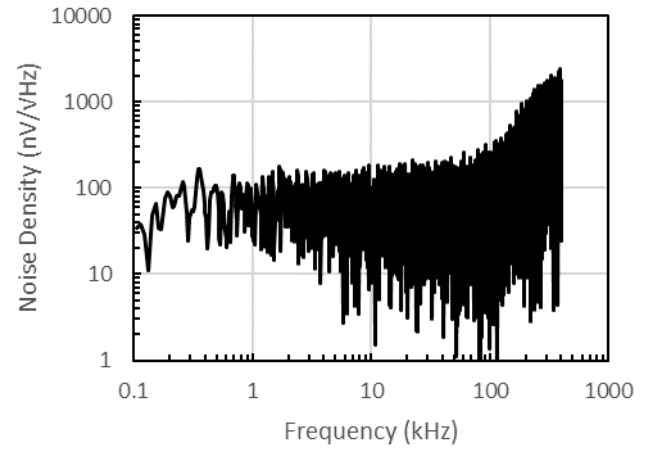


Figure 7-14 Input-Referred Noise Density vs Frequency

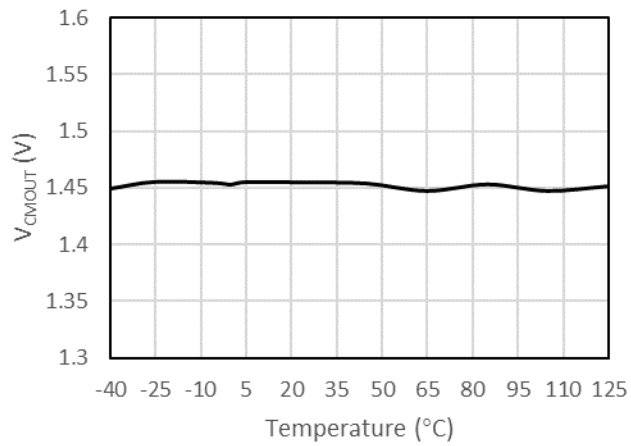


Figure 7-15 Low-Side  $V_{CMOUT}$  vs Temperature

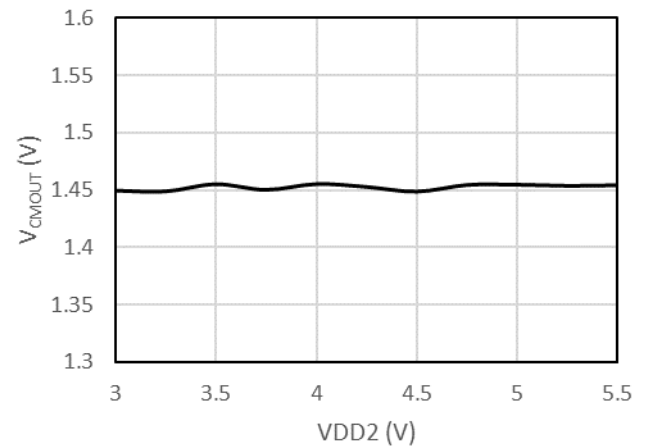


Figure 7-16 Low-Side  $V_{CMOUT}$  vs VDD2

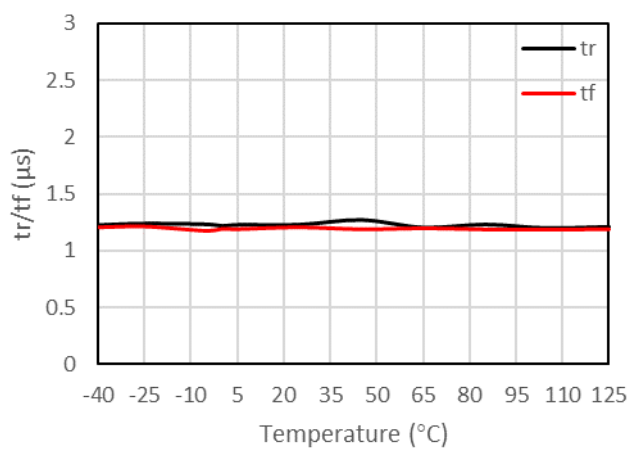


Figure 7-17 Output Rise and Fall Time vs Temperature

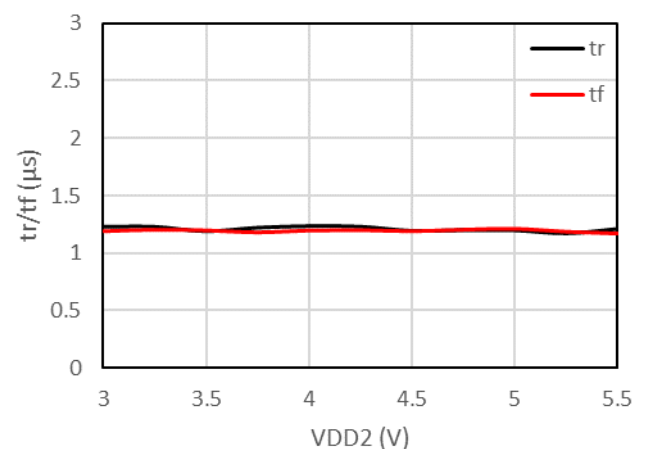
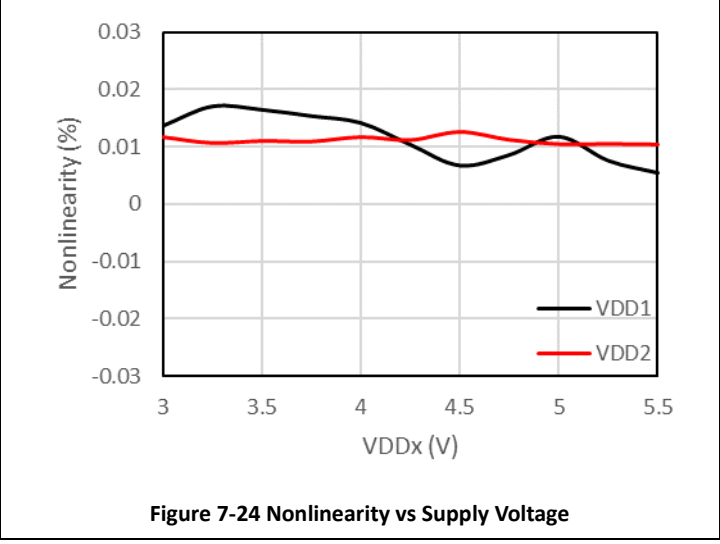
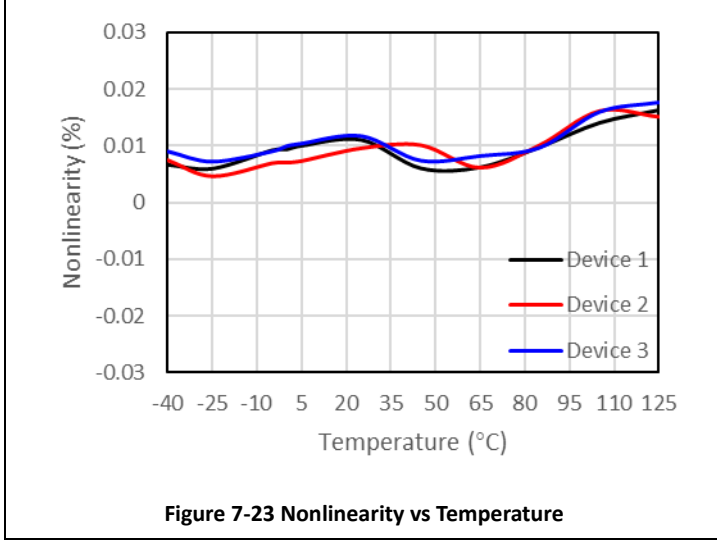
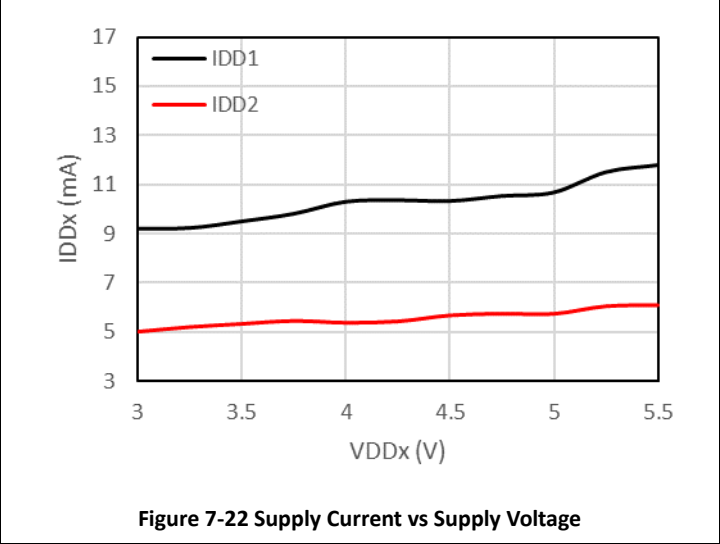
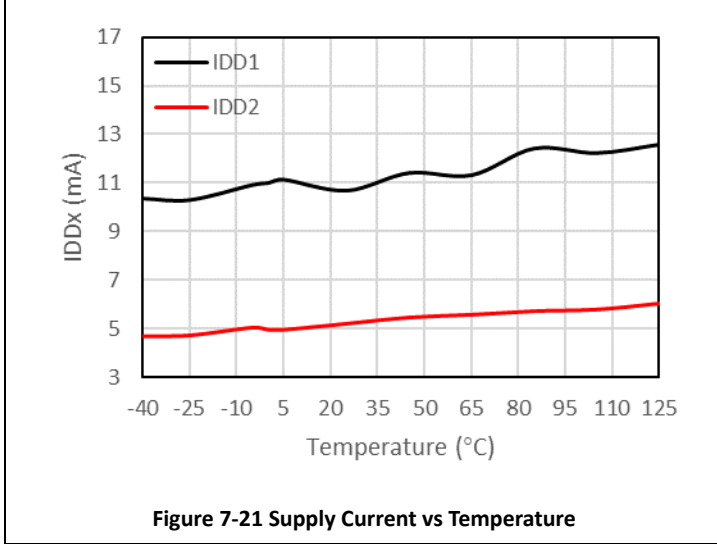
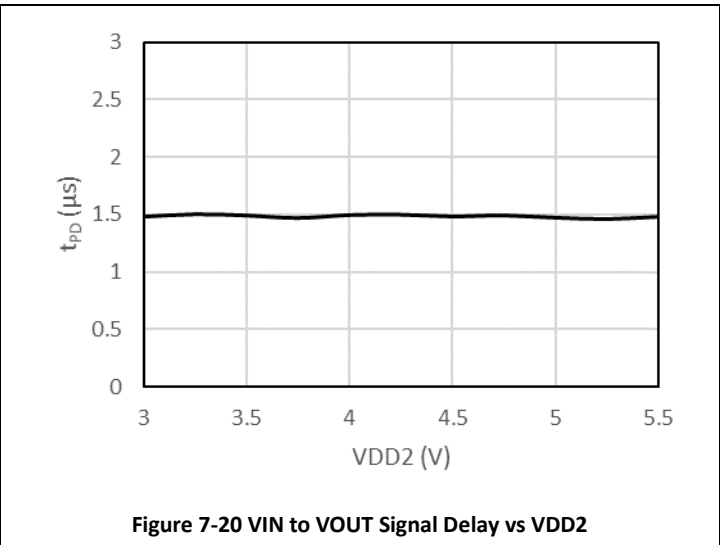
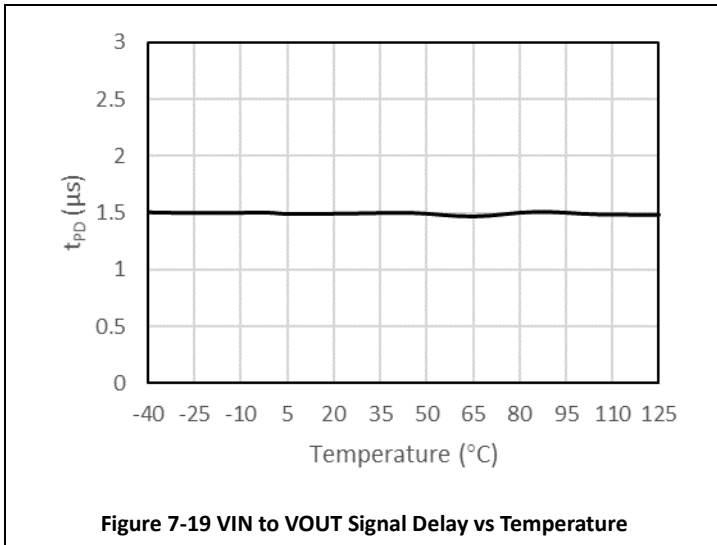


Figure 7-18 Output Rise and Fall Time vs VDD2



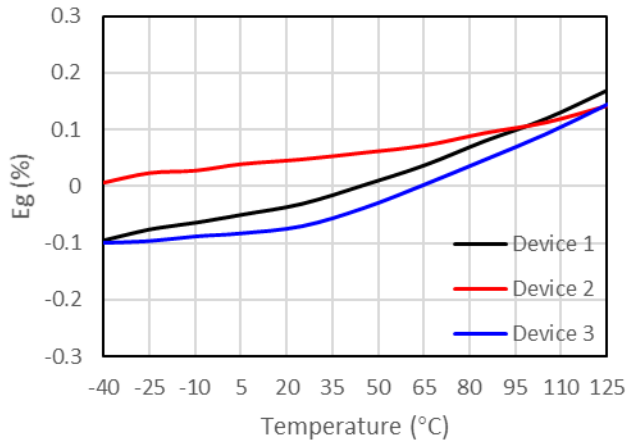


Figure 7-25 Gain Error vs Temperature (CA-IS1300B25)

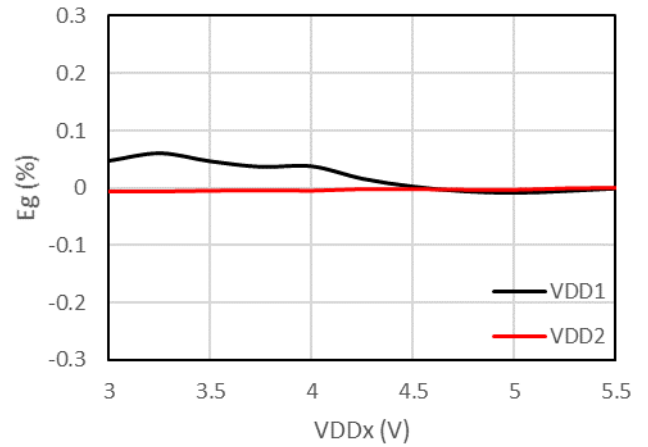


Figure 7-26 Gain Error vs VDDx (CA-IS1300B25)

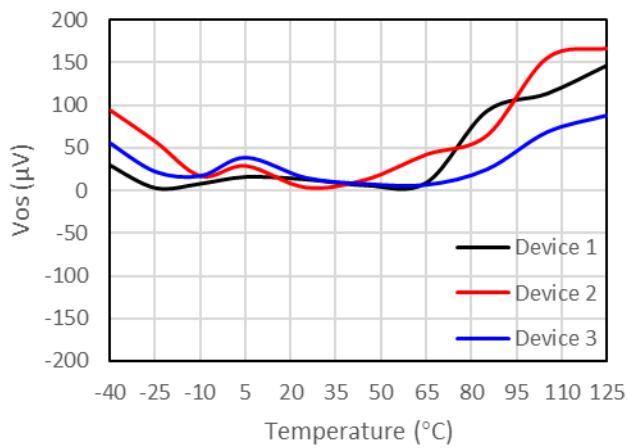


Figure 7-27 Vos vs Temperature (CA-IS1300B25)

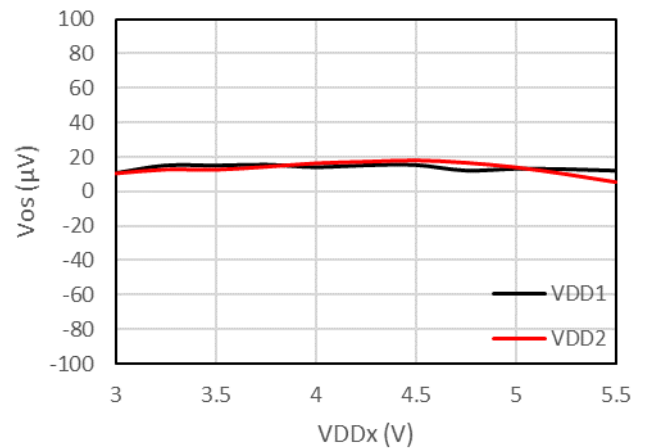


Figure 7-28 Vos vs VDDx (CA-IS1300B25)

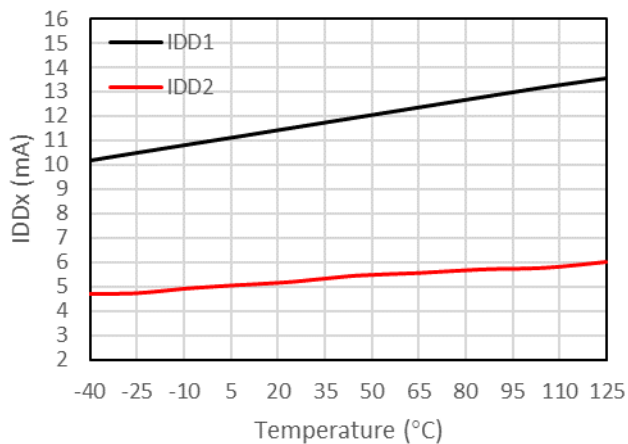


Figure 7-29 IDD<sub>x</sub> vs Temperature (CA-IS1300B25)

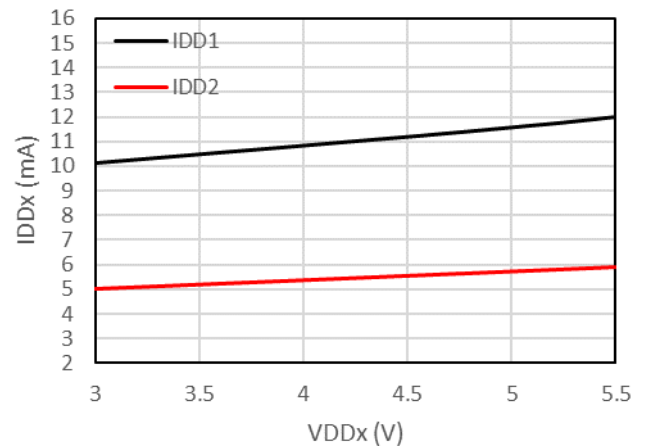
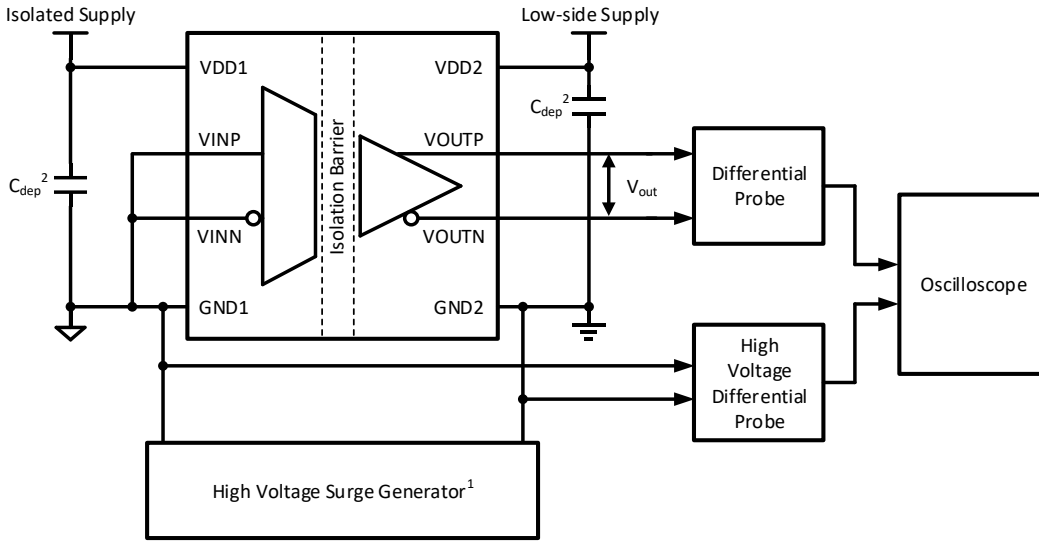


Figure 7-30 IDD<sub>x</sub> vs VDDx (CA-IS1300B25)



8 Parameter Measurement Information



- Note:**
1. The High Voltage Surge Generator generates repetitive high voltage surges with > 1 kV amplitude and < 10 ns rise time or fall time to generate common-mode transient noise with > 150 kV/μs slew rate.
  2. C<sub>dep</sub> is the 0.1~1 μF decoupling capacitor.

Figure 8-1 Common-Mode Transient Immunity Test Circuit

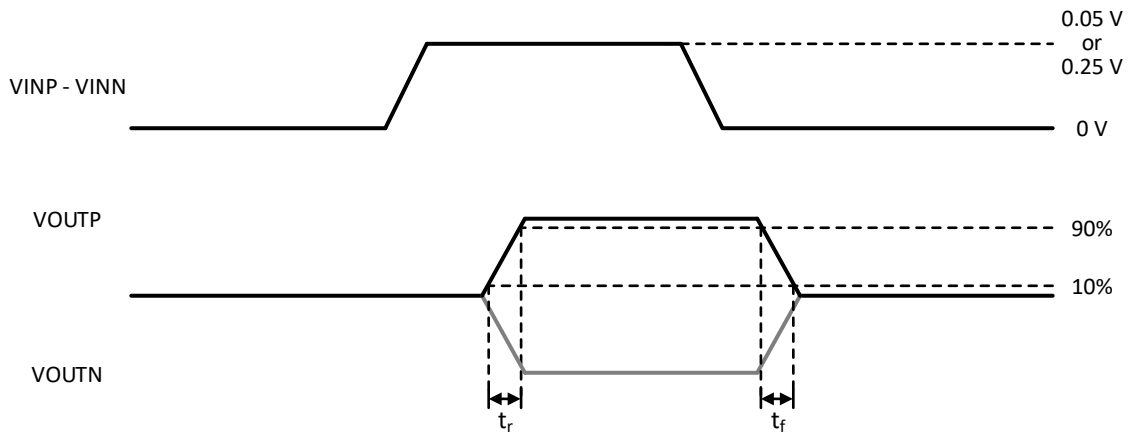


Figure 8-2 Rise and Fall Time Test Waveforms

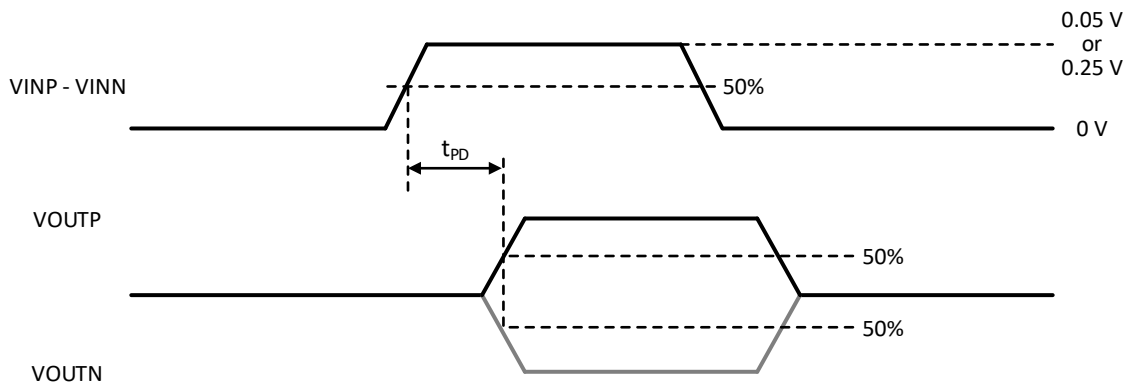
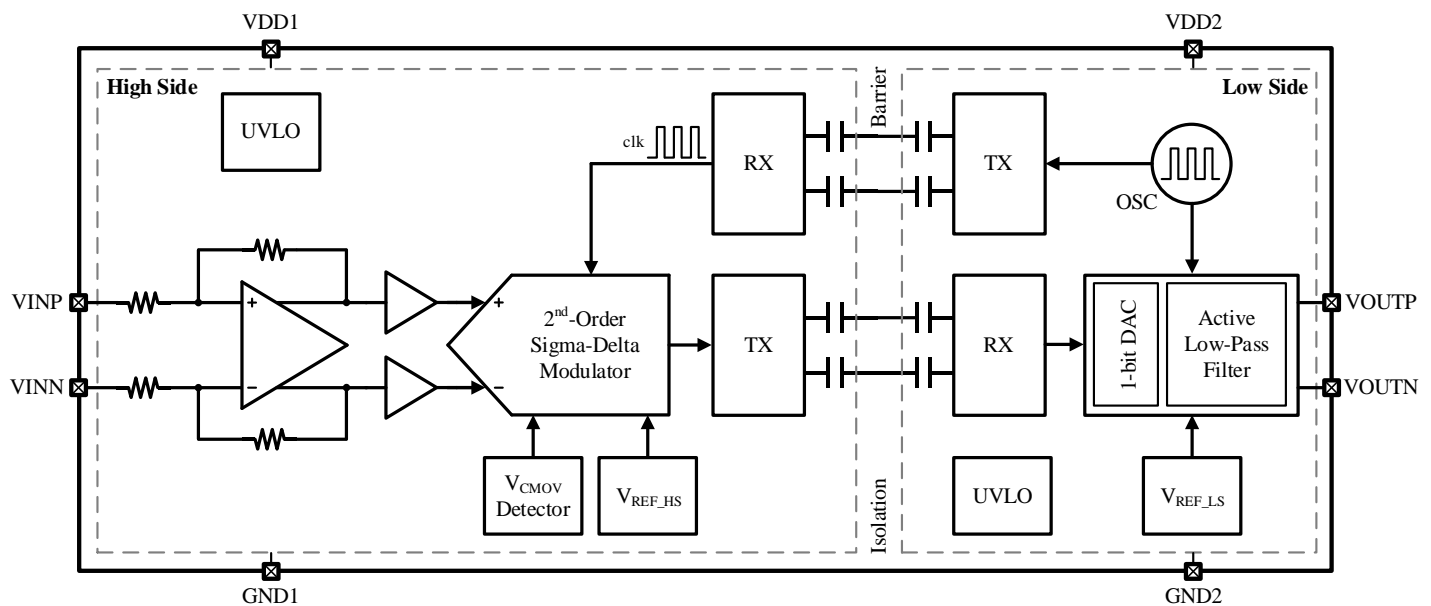


Figure 8-3 Delay Time Test Waveforms

## 9 Detailed Description

### 9.1 System Overview

The CA-IS1300x devices are high-precision isolated amplifiers designed for shunt-resistor-based current sensing. The functional block diagram of this device is shown in [Figure 9-1](#). At high side, the fully differential amplifier pre-amplifies the measuring voltage across a shunt resistor and then drives a 2<sup>nd</sup>-order Sigma-Delta ( $\Sigma\Delta$ ) modulator. This modulator converts the analog signal to a digital bitstream. For transmission across the SiO<sub>2</sub>-based isolation barrier, the digital stream is further modulated with a high-frequency carrier using a simple on-off keying (OOK) modulation scheme. The receiver (RX) recovers the modulated signal at low side. After processed by a 1-bit digital-to-analog converter (DAC), the digital bitstream is sent to an active low-pass filter to produce the analog output. For synchronization of the whole chip, the clock is generated at low side and sent back to high side ensuring that all clocks come from one source.



**Figure 9-1 Functional Block Diagram of CA-IS1300x**

### 9.2 Feature Description

#### 9.2.1 Analog Input

The CA-IS1300x device utilizes a fully differential amplifier stage to pre-amplify the measuring voltage across the shunt resistor. The nominal gain of the front-end differential amplifier is 20 for CA-IS1300G05 ( $\pm 50$ -mV input voltage range) and 4 for CA-IS1300x25 ( $\pm 250$ -mV input voltage range), contributing part of the total gain and ensuring that the 2<sup>nd</sup>-order Sigma-Delta modulator is not saturated when the analog input is within the specific input voltage range. This gain is set by the internal high-precision resistor network. The several- or tens-of-several-k $\Omega$  input resistance means it can bring in more gain error and offset if CA-IS1300x devices are applied in measurement where the input signal sources are high-impedance (refer to [Error Analysis in Voltage Sensing](#) for detailed information).

The ESD structure of CA-IS1300x supports the absolute maximum analog input voltage (with respect to GND1) to range from GND1 – 6 V to VDD1 + 0.5 V. To guarantee the long-term reliability and device performance, the differential analog input voltage and the input common-mode voltage of CA-IS1300x must be kept within the specific range.

#### 9.2.2 Signal Transmission Across Isolation Barrier

The CA-IS1300x devices utilize a simple on-off keying (OOK) modulation scheme to transmit the digital bitstream across the SiO<sub>2</sub>-based isolation barrier which supports up to 5-kV<sub>RMS</sub> galvanic isolation between high- and low-voltage domain. The block diagram of an isolation channel is shown in [Figure 9-2](#). As shown in [Figure 9-3](#), the transmitter (TX) modulates the digital bitstream with

a high-frequency carrier when the signal is HIGH while sends no signal when the signal is LOW. The receiver (RX) demodulates the signal across the isolation barrier and reproduces the digital bitstream faithfully. The isolation channel adopts fully differential capacitive-coupled structure which is insensitive to common-mode transient noises, thus the CMTI performance can be maximized. This structure and related circuitry also provide low emissions and strong anti-interference capability from magnetic changes.

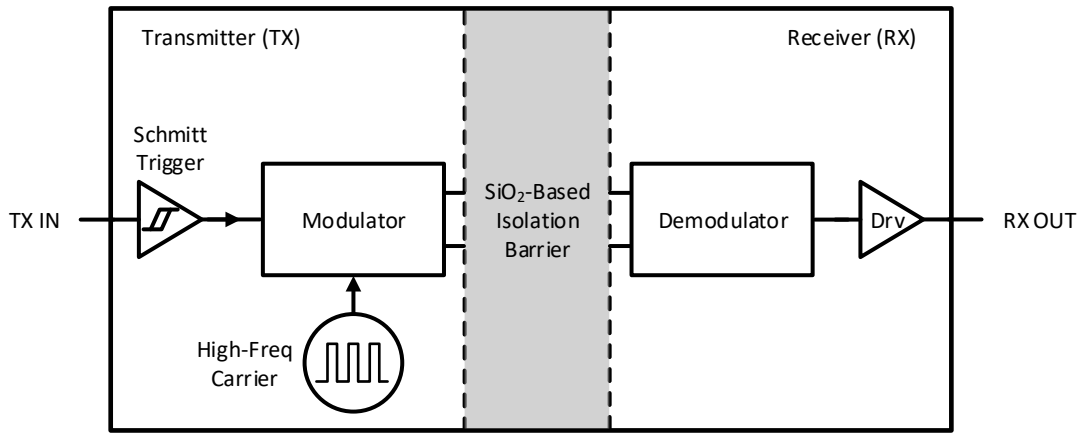


Figure 9-2 Block Diagram of an Isolation Channel

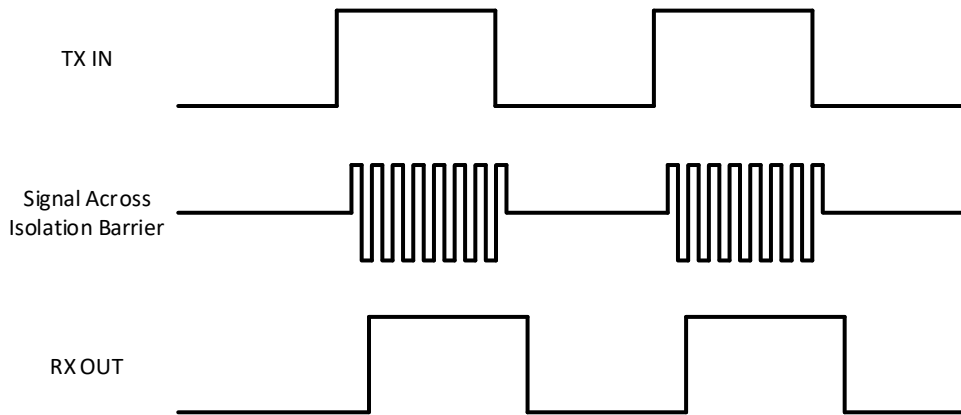


Figure 9-3 Conceptual Operation Waveforms of OOK Modulation Scheme

### 9.2.3 Fail-Safe Output

The CA-IS1300x devices have fail-safe output function which is activated in two conditions:

- The high-side power supply is missing;
- The common-mode input voltage  $V_{CM}$  exceeds the common-mode overvoltage threshold  $V_{CMOV}$ .

The fail-safe output is a more negative differential output voltage which can be distinguished from the negative clipping output voltage. This function contributes to fault diagnostics and system safety.

## 10 Application and Implementation

### 10.1.1 Typical Application for Current Sensing

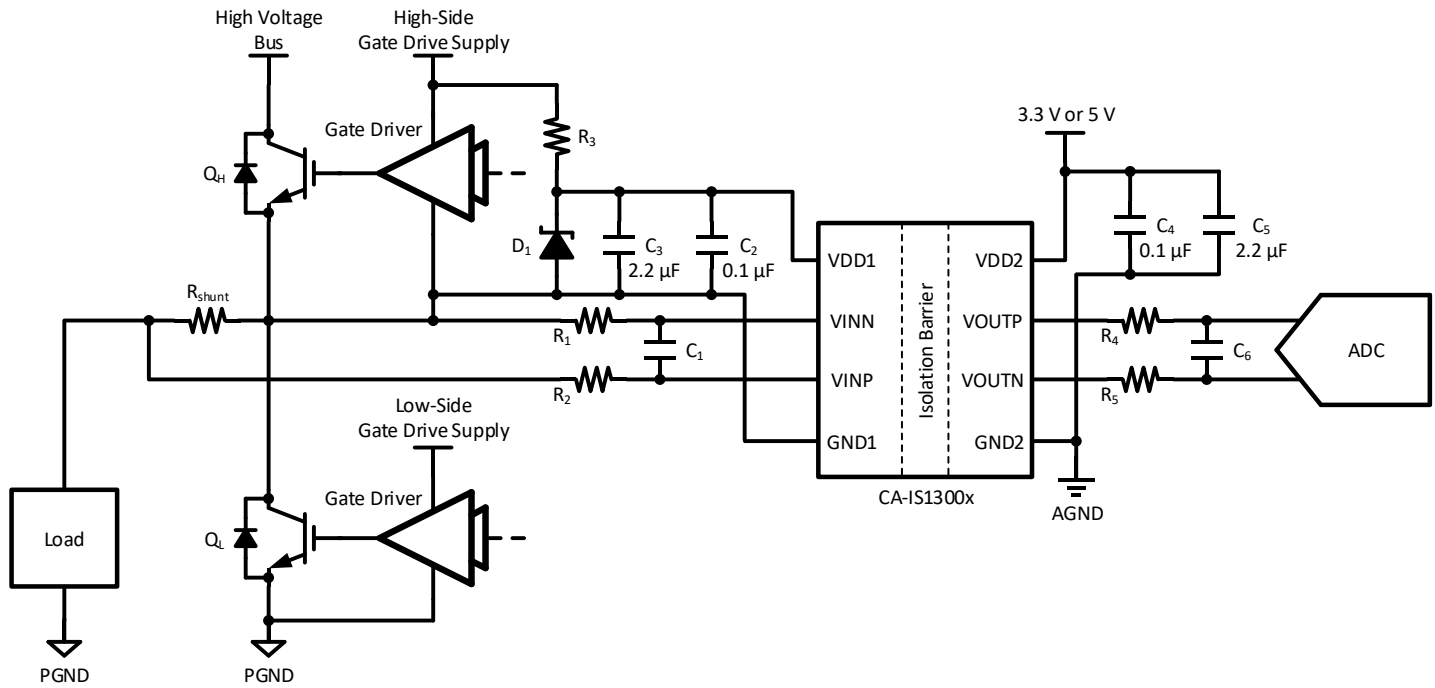


Figure 10-1 Typical Application for Current Sensing

The typical application for current sensing is shown in Figure 10-1. The CA-IS1300x device is used to amplify the voltage across the shunt resistor ( $R_{shunt}$ ) and transmit it to the low-voltage side for control circuit to process. The differential input and the high CMTI of CA-IS1300x ensure the reliable and accurate measurement in the high-noise and high-power switching applications such as industrial motor drives. The voltage of  $R_{shunt}$  with respect to PGND varies from 0 V to the high voltage bus when switching, thus isolation is required. The CA-IS1300x devices support up to 5-kV<sub>RMS</sub> galvanic isolation, making them suitable for these high-voltage industrial applications.

In a three-phase motor drive application, this circuit could be repeated three times and one for each phase in order to measure each phase current.

#### 10.1.2 Choose Proper $R_{shunt}$

The value chosen of shunt resistor is a trade off between power dissipation and measuring accuracy. Small value resistors minimize power dissipation, while large value resistors take advantage of the full performance input range of the Sigma-Delta modulator. The CA-IS1300x series provide two input voltage range options and the smaller range ( $\pm 50$  mV) allows significant reduction of the power dissipation through the shunt resistor.

Consider the following restrictions to choose proper value of the shunt resistor  $R_{shunt}$ :

- The voltage drop across  $R_{shunt}$  caused by the nominal measured current is within the linear differential input voltage range  $V_{FSR}$ ;
- The voltage drop across  $R_{shunt}$  caused by the maximum allowed current must not exceed the maximum input voltage before clipping output  $|V_{clipping}|$ .

For best performance, place the shunt resistor close to the inputs of CA-IS1300x and keep the layout of both connections symmetrical. This ensures that any noises occurring at high side are coupled equally to the inputs and would be rejected as a

common-mode signal. Kelvin connection is recommended between  $R_{shunt}$  and the inputs of CA-IS1300x to remove the impact from any voltage drops across the trace and leads.

**10.1.3 Input Filter**

The typical input bandwidth of CA-IS1300x is 1 MHz. A first-order passive RC low-pass filter could be placed between  $R_{shunt}$  and the inputs to narrow the input bandwidth. Choose  $R_1 = R_2 = 10 \Omega$  and  $C_1 = 20 \text{ nF}$  could provide a cutoff frequency of approximately 400 kHz.  $R_1$  and  $R_2$  should be low-value enough compared to the input impedance of CA-IS1300x to reduce gain error.

**10.1.4 Power Supply Recommendations**

The high-side power supply of CA-IS1300x could be generated directly derived from the high-side gate drive power supply by utilizing a Zener diode ( $D_1$ ) to produce a 3.3-V or 5-V ( $\pm 10\%$ ) voltage. And a low-ESR decoupling capacitor of 0.1  $\mu\text{F}$  ( $C_2$ ) is recommended to place as close as possible to the VDD1 pin of CA-IS1300x. Additional 2.2- $\mu\text{F}$  capacitor ( $C_3$ ) is recommended for better filtering to the high-side power-supply path.

Similarly, a 0.1- $\mu\text{F}$  decoupling capacitor ( $C_4$ ) followed by an additional capacitor ( $C_5$ ) from 2.2  $\mu\text{F}$  to 10  $\mu\text{F}$  should be placed as close as to the VDD2 pin of CA-IS1300x to filter the low-side power supply path.

**10.1.5 Output Filter**

Another first-order passive RC low-pass filter could be placed between the outputs of CA-IS1300x and the ADC to satisfy the potential requirement for anti-aliasing filtering. The characteristics of this filter depends on the structure and sampling frequency of the ADC. Choose  $R_4 = R_5 = 4.7 \text{ k}\Omega$  and  $C_6 = 180 \text{ pF}$  could provide a cutoff frequency of approximately 94 kHz.

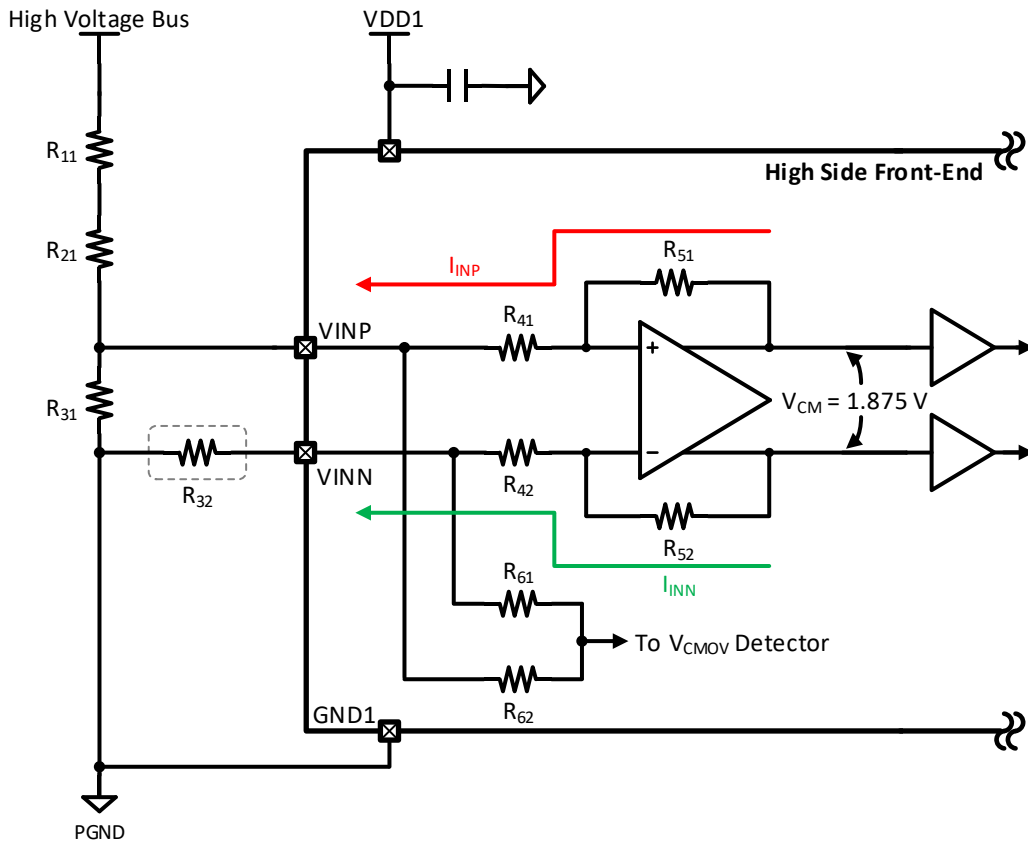


Figure 10-2 Typical Application for Voltage Sensing

### 10.1.6 Error Analysis in Voltage Sensing

The CA-IS1300x devices may also be used in the applications of voltage sensing as shown in [Figure 10-2](#). The resistors  $R_{11}$ ,  $R_{21}$  and  $R_{31}$  make up the resistor divider to scale down the high voltage from bus. Typically, the value of  $R_{11}$  and  $R_{21}$  is much larger than  $R_{31}$  to keep the input voltage of CA-IS1300x within the specific range.

In CA-IS1300x, resistors  $R_{41}$  and  $R_{51}$  (or  $R_{42}$  and  $R_{52}$ ) are used to set the gain of front-end amplifier. The typical values are  $R_{41} = R_{42} = 2.5 \text{ k}\Omega$  for CA-IS1300G05,  $R_{41} = R_{42} = 12.5 \text{ k}\Omega$  for CA-IS1300x25, and  $R_{51} = R_{52} = 50 \text{ k}\Omega$  for both. Resistors  $R_{61}$  and  $R_{62}$  are used to sense the common-mode voltage of the input in CA-IS1300x. The typical values are  $R_{61} = R_{62} = 100 \text{ k}\Omega$ .

First, consider the situation in which  $R_{32}$  is not used. Additional gain error and offset would arise in these applications for CA-IS1300x. On the one hand, the limited input impedance of CA-IS1300x is parallel with the external sensing resistor  $R_{31}$ , resulting in impedance change and thus additional gain error. On the other hand, the output common-mode voltage  $V_{CM}$  of the front-end differential amplifier in CA-IS1300x is biased to 1.875 V, which would generate bias current  $I_{INP}$  and  $I_{INN}$  flowing through the front-end resistor network. The bias current  $I_{INP}$  also flows through  $R_{31}$  while  $I_{INN}$  flows directly to PGND in the case of omitting  $R_{32}$ , which results in unbalance and thus additional offset.

To eliminate the effect of the bias current, resistor  $R_{32}$  equal to sensing resistor  $R_{31}$  is recommended to be added between VINN and PGND. The resistor  $R_{31}$  would bring in additional gain error  $E_{GA}$  and could be calculated as [Eq. 1](#) describes.

$$E_{GA} = R_{31} / (R_{31} + R_{41}) \quad \text{(Eq. 1)}$$

To reduce the effect of this gain error, the value of  $R_{31}$  should be chosen much smaller compared to  $R_{41}$ . And this gain error could also be minimized by the system-level gain calibration.

### 10.1.7 Caution

Do not leave the inputs of CA-IS1300x floating. If the VINP and VINN are left floating, the input common-mode voltage would be pulled to a high level by internal bias, which could activate the fail-safe mode under certain power supply and may lead to system-level abnormal reaction (refer to [Fail-Safe Output](#) for detailed information).

**11 Package Information**

**11.1 8-Pin Wide Body SOIC Package**

The figure below illustrates the package details and the recommended land pattern details for the CA-IS1300x isolated amplifier in an 8-pin wide-body SOIC package. The values for the dimensions are shown in millimeters.

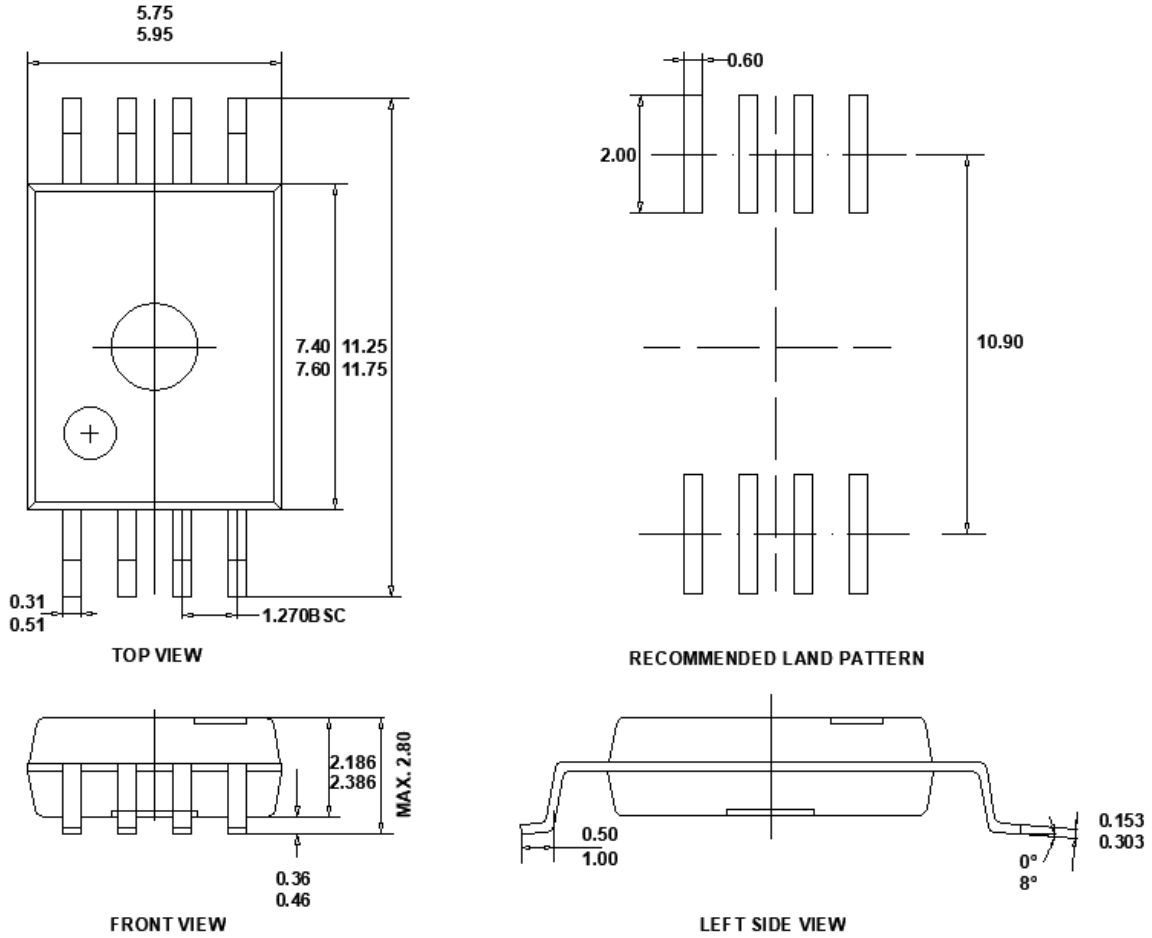


Figure 11-1 SOIC8 Wide-body Package

12 Soldering Information

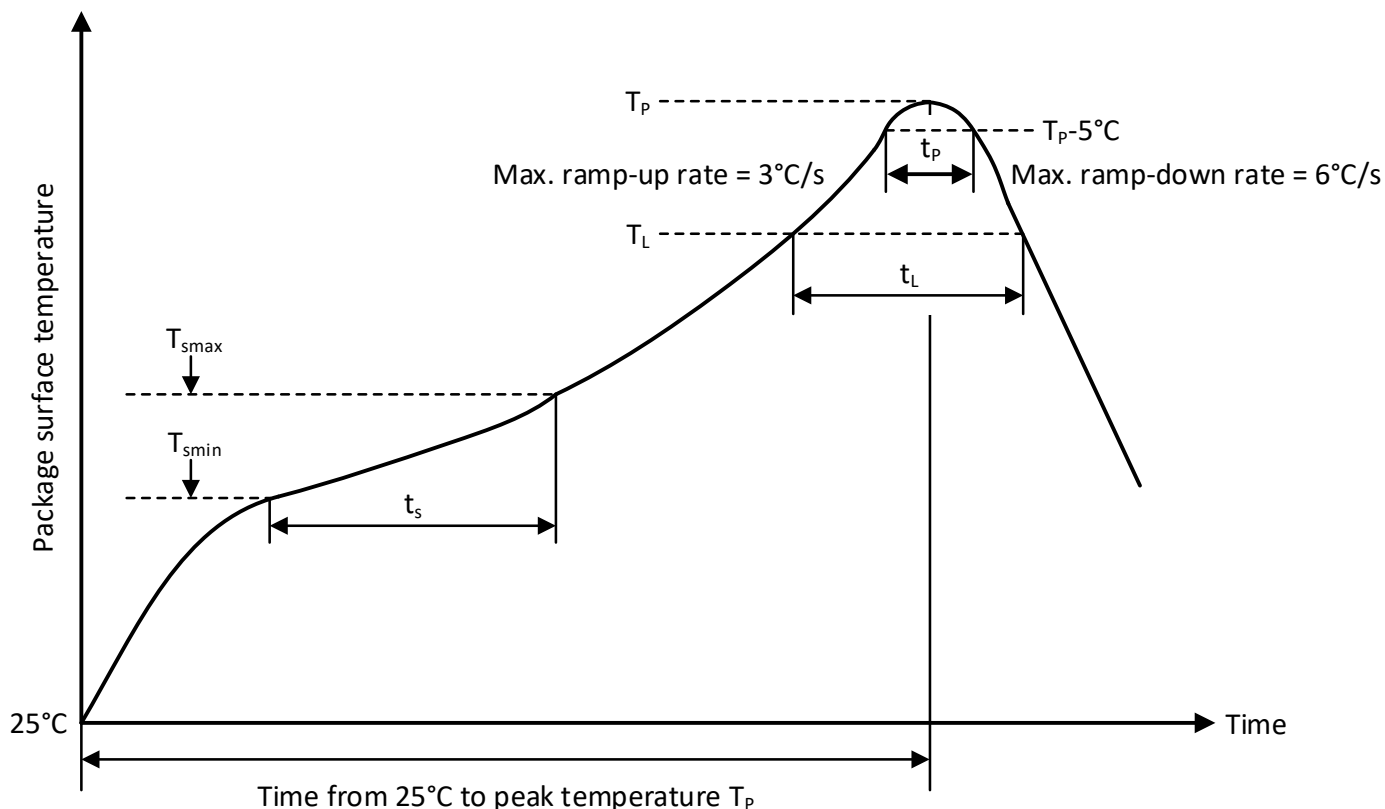


Figure 12-1 Soldering Temperature Curve

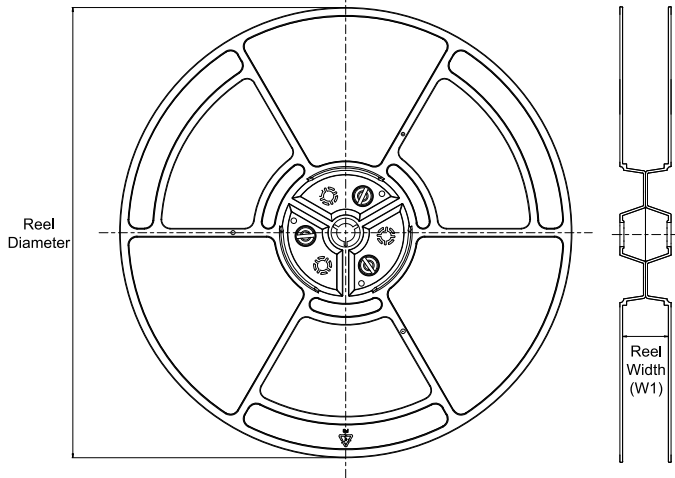
Table 12-1 Soldering Temperature Parameters

| Profile Feature   | Pb-Free Soldering |
|---|-------------------|
| Ramp-up rate ( $T_L = 217^\circ\text{C}$ to peak $T_p$ )  | 3°C/s max         |
| Time $t_s$ of preheat temp ( $T_{smin} = 150^\circ\text{C}$ to $T_{smax} = 200^\circ\text{C}$ ) | 60~120 seconds    |
| Time $t_L$ to be maintained above $217^\circ\text{C}$   | 60~150 seconds    |
| Peak temperature $T_p$  | 260°C             |
| Time $t_p$ within $5^\circ\text{C}$ of actual peak temp   | 30 seconds max    |
| Ramp-down rate (peak $T_p$ to $T_L = 217^\circ\text{C}$ )                                       | 6°C/s max         |
| Time from $25^\circ\text{C}$ to peak temperature $T_p$  | 8 minutes max     |

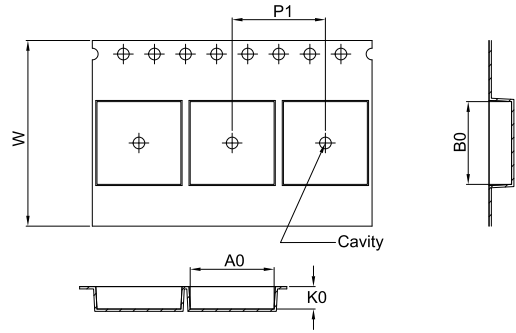


**13 Tape and Reel Information**

**REEL DIMENSIONS**

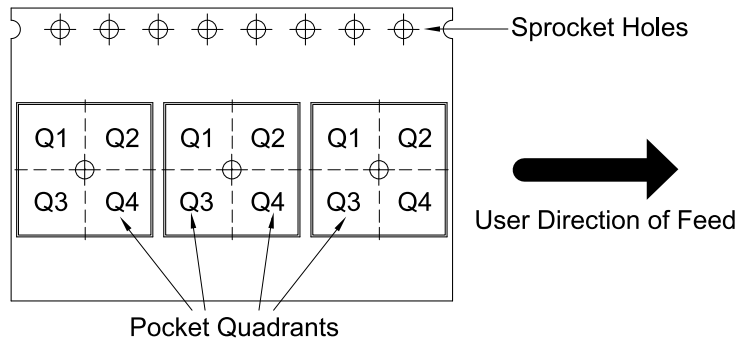


**TAPE DIMENSIONS**



|    |   |
|----|---|
| A0 | Dimension designed to accommodate the component width     |
| B0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**



\*All dimensions are nominal

| Device        | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|---------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| CA-IS1300G05G | SOIC         | G               | 8    | 1000 | 330                | 16.4               | 11.95   | 6.15    | 3.20    | 16.0    | 16.0   | Q1            |
| CA-IS1300G25G | SOIC         | G               | 8    | 1000 | 330                | 16.4               | 11.95   | 6.15    | 3.20    | 16.0    | 16.0   | Q1            |
| CA-IS1300B25G | SOIC         | G               | 8    | 1000 | 330                | 16.4               | 11.95   | 6.15    | 3.20    | 16.0    | 16.0   | Q1            |

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