

CS470xx Data Sheet

Features

- Cost-effective, High-performance 32-bit DSP
 - 300,000,000 MAC/S (multiply accumulates per second)
 - Dual MAC cycles per clock
 - 72-bit accumulators are the highest precision in the industry
 - 32K x 32-bit SRAM with three 2K blocks assignable to either Y data or program memory
- Integrated DAC and ADC Functionality
 - 8† Channels of 24-bit DAC output: 108dB DR, –98 dB THD+N
 - 4[†] Channels of 24-bit ADC input: 105dB DR, –98 dB THD+N
 - Integrated 5:1 analog mux feeds one stereo ADC
- Configurable Serial Audio Inputs and Outputs
 - Integrated 192 kHz S/PDIF Rx
 - Integrated 192 kHz S/PDIF Tx
 - Supports 32-bit serial data @ 192 kHz
 - Supports 32-bit audio sample I/O between DSP chips
 - TDM I/O modes
- Supports Different Sample Rates (Fs)
 - Three integrated hardware SRC blocks
 - Output can be master or slave
 - Supports dual-domain Fs on S/PDIF vs. I²S inputs
- DSP Tool Set with Private Keys Protect Customer IP
- Integrated Clock Manager/PLL
 - Flexibility to operate from internal PLL, external crystal, external oscillator
- Input Fs Auto Detection w/ µC Acknowledgement
- Host Control and Boot via l²C[™] or SPI[™] Serial Interface
- Configurable GPIOs and External Interrupt Input
- 1.8V Core and a 3.3V I/O that is tolerant to 5V input
- Low-power Mode

"†" features differ on CS47024, CS47028, or CS47048. See Table 3-1.

The CS470xx family is a new generation of audio system-on-a-chip (ASOC) processors targeted at high fidelity, cost sensitive designs. Derived from the highly successful CS48500 32-bit fixed-point audio enhancement processor family, the CS470xx further simplifies system design and reduces total system cost by integrating the S/PDIF Rx, S/PDIF Tx, analog inputs, analog outputs, and SRCs. For example, a hardware SRC can down-sample a 192 kHz S/PDIF stream to a lower Fs to reduce memory and MIPS requirements for processing. This integration effectively reduces the chip count from 3 to 1, which allows smaller, less expensive board designs.

Target applications include:

- Automotive head units and outboard amplifiers
- Automotive processors and automotive integration hubs
- Digital TV
- MP3 docking stations
- AVR and DVD RX
- DSP controlled speakers (subwoofers, sound bars)

The CS470xx is programmed using the simple yet powerful Cirrus proprietary DSP Composer™ GUI development and pre-production tuning tool. Processing chains can be designed using a drag-and-drop interface to place/utilize functional macro audio DSP primitives and custom audio filtering blocks. The end result is a software image that is downloaded to the DSP via serial control port.

The Cirrus Framework™ programming environment offers Assembly and C language compilers and other software development tools for porting existing code to the CS470xx family platform.

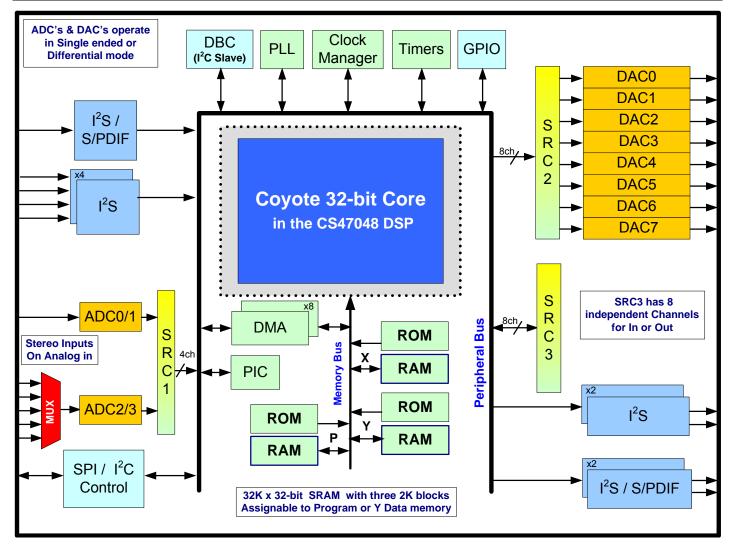
The CS470xx is available in a 100-pin LQFP package with exposed pad for better thermal characteristics. Both Commercial (0°C to +70°C) and Automotive (–40°C to +85°C) temperature grades.

Ordering Information:

See Section 6 for ordering information.







CS47048 Block Diagram



Contacting Cirrus Logic Support

For all product questions and inquiries, contact a Cirrus Logic Sales Representative.

To find the one nearest you, go to www.cirrus.com.

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1 Documentation Strategy

The CS470xx Data Sheet describes the CS47048, CS47028, and CS47024 audio processors. This document should be used in conjunction with the following documents when evaluating or designing a system around the CS470xx processors.

Table 1-1. CS470xx Related Documentation

| Document Name | Description |
|--------------------------------------|---|
| CS470xx Data Sheet | This document |
| CS470xx Hardware User's Manual Guide | Includes detailed system design information such as typical connection diagrams, boot-procedures, and pin descriptions |
| | Includes a list of firmware modules available on the CS470xx family platform and detailed firmware design information including signal processing flow diagrams and control API information |
| DSP Composer User's Manual | Includes detailed configuration and usage information for the GUI development tool |
| CDB470xx User's Manual | Includes detailed instructions on the use of the CDB470xx development board |

The scope of the CS470xx Data Sheet is primarily the hardware specifications of the CS470xx family of devices. This includes hardware functionality, characteristic data, pinout, and packaging information.

The intended audience for the CS470xx Data Sheet is the system PCB designer, MCU programmer, and the quality control engineer.

2 Overview

The CS470xx DSP is designed to provide high-performance post-processing and mixing of analog and digital audio. Dual clock domains are supported when the DAI and SPDIF RX inputs are used together. Integrated sample rate converters (SRCs) allow audio streams with different sample rates to be mixed. The low-power standby preserves battery life for applications that are always on, but not necessarily processing audio, such as automotive audio systems.

The CS470xx uses voltage-out DACs and is capable of supporting dual input clock domains through the use of the internal SRCs. The CS470xx is available in a 100-pin LQFP package. Refer to Table 3-1 and Table 3-2 for the input, output, and firmware configurations for the CS470xx DSP.

2.1 Licensing

Licenses are required for any third-party audio processing algorithms provided for the CS470xx. Contact your local Cirrus Logic Sales representative for more information.



3 Code Overlays

The suite of software available for the CS470xx family consists of an operating system (OS) and a library of overlays. The software components for the CS470xx family include:

- 1. OS/Kernel—Encompasses all non-audio processing tasks, including loading data from external serial memory, processing host messages, calling audio-processing subroutines, error concealment, etc.
- 2. Decoder—Any module that performs a compressed audio decode on IEC61937-packed data delivered via S/PDIF Rx or I²S input, such as Dolby Digital (AC3).
- 3. *Matrix-processor*—Any Module that performs a matrix decode on PCM data to produce more output channels than input channels (2Æn channels). Examples are Dolby® Pro Logic® IIx and SRS Circle Surround II®. Generally speaking, these modules increase the number of valid channels in the audio I/O buffer.
- 4. Virtualizer-processor—Any module that encodes PCM data into fewer output channels than input channels (nÆ2 channels) with the effect of providing "phantom" speakers to represent the physical audio channels that were eliminated. Examples are Dolby Headphone® 2 and Dolby® Virtual Speaker® 2. Generally speaking, these modules reduce the number of valid channels in the audio I/O buffer.
- 5. *Post-processors*—Any module that processes audio I/O buffer PCM data. Examples are bass management, audio manager, tone control, EQ, delay, customer-specific effects, and any post-processing algorithms available for the CS470xx DSP.

The bulk of standard overlays are stored in ROM within the CS470xx, but a small image is required to configure the overlays and boot the DSP. This small image can either be stored in an external serial flash/EEPROM, or downloaded via a host controller through the SPI/I²C serial port.

The overlay structure reduces the time required to reconfigure the DSP when a processing change is requested. Each overlay can be reloaded independently without disturbing the other overlays. For example, when a different post-processor is selected, the OS, does not need to be reloaded—only the new post-processor.

Table 3-1 lists the different configuration options available. Refer to the CS470xx Firmware User's Manual for the latest listing of application codes and Cirrus Framework™ modules available. See Table 3-2, which provides a summary of the available channels for each type of input and output communication mode for members of the CS470xx family of DSPs.



Table 3-1. CS470xx Device Selection Guide

| Features | CS47048-CQZ CS47048-DQZ | CS47028-CQZ CS47028-DQZ | CS47024-CQZ CS47024-DQZ |
|---|---|--|--|
| Primary Applications | 4-In/8-Out Car Audio High-end Digital TV Dual Source/Dual Zone | 2-In/8-Out Car Audio Sound Bar DVD Receiver | 2-In/4-Out Car Audio Digital TV Portable Audio Docking Station Portable DVD DVD Mini / Receiver Multimedia PC Speakers |
| Package | 100-pin LQFP with Exposed Pad | | |
| DSP Core | Cirrus Logic 32-bit Core | | |
| SRAM | 32K x 32-bit SRAM with three 2K bloc | ks x 32-bit SRAM, assignable to either | r Y data or program memory |
| Integrated DAC and ADC | 2 Channels of ADC input: with integrated 5:1 analog mux 2 additional channels of ADC input: without mux 8 channels of DAC output | 2 channels of ADC input: with integrated 5:1 analog mux 8 channels of DAC output | 2 channels of ADC input: with integrated 5:1 analog mux 4 channels of DAC output |
| Configurable Serial Audio Inputs/Outputs | Integrated 192 kHz S/PDIF Rx, 2 Ir I2S support for 32-bit Samples @ 7 TDM Input modes (Up to 8 channe TDM Output modes (Up to 8 channe | 192 kHz ls) | |
| Supports Different Fs Sample Rates | Integrated hardware SRC blocks for Additional 8-channel hardware SRI Dual-domain Fs on inputs (I2S and Output can be master or slave | C block | |
| Other Features | Integrated Clock Manager/PLL with Host Control and Boot via SPI/I ² C s DSP Tool Set w/ Private Keys Prote Configurable GPIOs and External I Hardware Watchdog Timer | ect Customer IP | ., external crystal, external oscillator |

Table 3-2. CS470xx Channel Count

| Product | PCM/TDM In ¹ | TDM Out ¹ | PCM Out | ADC with 5:1 Input Mux | ADC with- out Mux | DAC Out | S/PDIF In (Stereo Pairs) | S/PDIF Out (Ste- reo Pairs) |
|---------|---|-----------------------|------------|---------------------------|----------------------|------------|--------------------------------|-----------------------------------|
| CS47048 | Up to 5 I2S lines, 2 channels per line or 1 TDM line, up to 8 channels per line. | Up to 8 chan- nels | 8 | 2 | 2 | 8 | 1 | 2 |
| CS47028 | Up to 5 I2S lines, 2 channels per line or 1 TDM line, up to 8 channels per line. | Up to 8 chan- nels | 8 | 2 | 0 | 8 | 1 | 2 |
| CS47024 | Up to 5 I2S lines, 2 channels per line or 1 TDM line, up to 8 channels per line. | Up to 8 chan- nels | 8 | 2 | 0 | 4 | 1 | 2 |

^{1.} Contact your Cirrus Logic representative to determine the TDM modes that are supported. The CS470xx can support up to 8 channels per line, but the DSP software provided for the IC can restrict this capability.



4 Hardware Functional Description

The CS470xx family, which includes the CS47048, CS47028, and CS47024 DSPs, is a true system-on-a-chip that combines a powerful 32-bit DSP engine with analog/digital audio inputs and analog/digital audio outputs. It can be integrated into a complex multi-DSP processing system, or stand alone in an audio product that requires analog-in and analog-out. A top level block diagram for the CS47048, CS47028, and CS47024 products are shown in Fig. 4-1, Fig. 4-2, and Fig. 4-3 respectively.

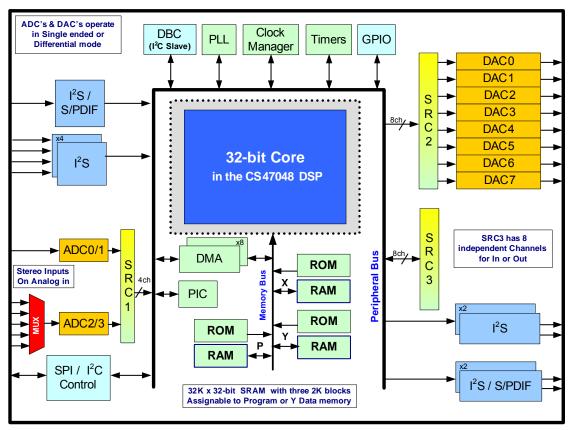


Figure 4-1. CS47048 Top-level Block Diagram



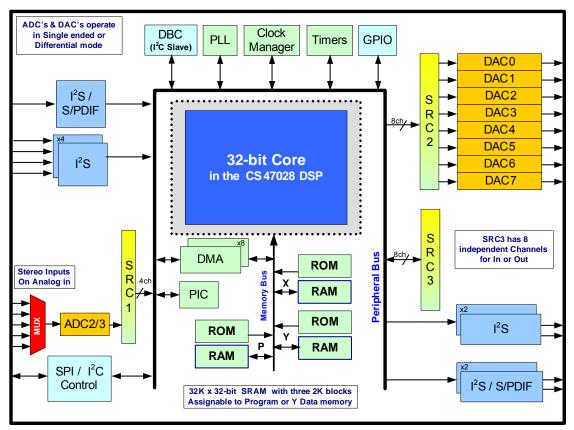


Figure 4-2. CS47028 Top-level Block Diagram

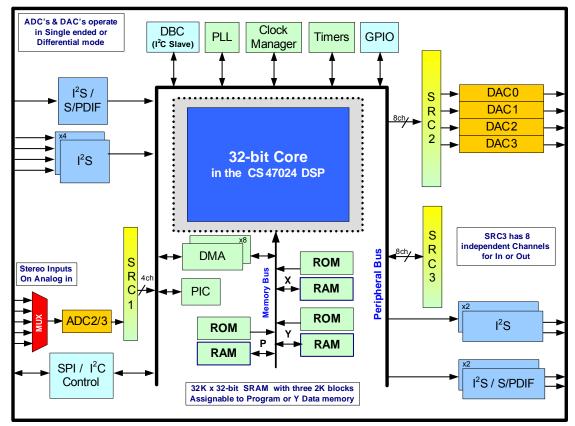


Figure 4-3. CS47024 Top-level Block Diagram



4.1 Cirrus Logic 32-bit DSP Core

The CS470xx comes with a Cirrus Logic 32-bit core with separate X and Y data and P code memory spaces. The DSP core is a high-performance, 32-bit, user-programmable, fixed-point DSP that is capable of performing two multiply-and-accumulate (MAC) operations per clock cycle. The DSP core has eight 72-bit accumulators, four X-data and four Y-data registers, and 12 index registers.

The DSP core is coupled to a flexible 8-channel DMA engine. The DMA engine can move data between peripherals such as the serial control port (SCP), digital audio input (DAI) and digital audio output (DAO), sample rate converters (SRC), analog-to-digital converters (ADC), digital-to-analog converters (DAC), or any DSP core memory, all without the intervention of the DSP. The DMA engine off-loads data move instructions from the DSP core, leaving more MIPS available for signal processing instructions.

CS470xx functionality is controlled by application codes that are stored in on-chip ROM or downloaded to the CS470xx from a host controller or external serial flash/EEPROM.

Users can develop applications using the DSP Composer™ tool to create the processing chain and then compile the image into a series of commands that are sent to the CS470xx through the SCP. The processing application can either load modules (post-processors) from the DSPs on-chip ROM, or custom firmware can be downloaded through the SCP.

The CS470xx is suitable for a variety of audio post-processing applications where sound quality via sound enhancement and speaker/cabinet tuning is required to achieve the sound quality consumers expect. Examples of such applications include automotive head-ends, automotive amplifiers, docking stations, sound bars, subwoofers, and boom boxes.

4.2 DSP Memory

The DSP core has its own on-chip data and program RAM and ROM and does not require external memory for post-processing applications.

The Y-RAM and P-RAM share a single block of memory that includes three 2K word blocks (32 bits/word) that are assignable to either Y-RAM or P-RAM as shown in Table 4.

| P-RAM | X-RAM | Y-RAM |
|-----------|-----------|-----------|
| 14K words | 10K words | 8K words |
| 12K words | 10K words | 10K words |
| 10K words | 10K words | 12K words |
| 8K words | 10K words | 14K words |

Table 4-1. Memory Configurations for the C470xx

4.2.1 DMA Controller

The powerful 8-channel DMA controller can move data between 8 on-chip resources. Each resource has its own arbiter: X, Y, and P RAMs/ROMs and the peripheral bus. Modulo and linear addressing modes are supported, with flexible start address and increment controls. The service intervals for each DMA channel, as well as up to 6 interrupt events, are programmable.

4.3 On-chip DSP Peripherals

4.3.1 Analog to Digital Converter Port (ADC)

The ADCs in the CS470xx devices feature dynamic range performance in excess of 100 dB. See Section 5.16 for more details on CS470xx ADC performance. The CS47024 and CS47028 devices support up to 2 simultaneous channels of analog-to-digital conversion with the input source selectable using an integrated 5:1 stereo analog mux (analog inputs AIN_2A/B through AIN_6A/B). The CS47048 device adds a second pair of ADCs that are directly connected to input pins AIN_1A/B providing a total of 4 simultaneous channels of analog-to-digital conversion. This feature gives the CS47048 the ability to select from a total of six stereo pairs of analog input. A single programmable bit selects single-ended or differential mode signals for all inputs. The conversions are performed with Fs=96 kHz.



4.3.2 Digital to Analog Converter Port (DAC)

The DACs in the CS470xx devices feature dynamic range performance in excess of 100 dB. See Section 5.17 for more details on CS470xx DAC performance. The CS47024 device supports four simultaneous channels of digital-to-analog conversion. The CS47028 and CS47048 devices provide eight simultaneous channels of digital-to-analog conversion. The DACs have voltage mode outputs that can be connected either as single-ended or differential signals. The conversions are performed with Fs=96 kHz.

4.3.3 Digital Audio Input Port (DAI)

The input capabilities for each version of the CS470xx are summarized in Table 3-1 and Table 3-2.

Up to five DAI ports are available. Two of the DAI ports can be programmed to implement other functions. If the SPI mode is used, the DAI_DATA4 pin becomes the SCP_CS input. The integrated S/PDIF receiver can be used to take over the DAI_DATA3 pin.

The DAI port PCM inputs have a single slave-only clock domain. The S/PDIF receiver, if used, is a separate clock domain. The output of the S/PDIF Rx can then be converted through one of the internal SRC blocks to synchronize with the PCM input. The sample rate of the input clock domains can be determined automatically by the DSP, off-loading the task of monitoring the S/PDIF Rx from the host. A time-stamping feature provides the ability to also sample-rate convert the input data via software. The DAI port supports PCM format with word lengths up to 32 bits and sample rates as high as 192 kHz.

The DAI also supports a time division multiplexed (TDM) mode that packs up to 10 PCM audio channels on a single data line.

4.3.4 S/PDIF RX Input Port (DAI)

One of the PCM pins of the DAI can also be used as a DC-coupled, TTL-level S/PDIF Rx input capable of receiving and demodulating bi-phase encoded S/PDIF signals with Fs ≤ 192 kHz.

4.3.5 Digital Audio Output Port (DAO)

DAO port supports PCM resolutions of up to 32-bits. The port supports sample rates (Fs) as high as 192 kHz. The port can be configured as an independent clock domain mastered by the DSP, or as a clock slave if an external MCLK or SCLK/LRCLK source is available.

The DAO also supports a time division multiplexed (TDM) mode, that packs up to 8 channels of PCM audio on a single data line.

4.3.6 S/PDIF TX Output Port (DAO)

Two of the serial audio pins can be re-configured as S/PDIF TX pins that drive a bi-phase encoded S/PDIF signal (data with embedded clock on a single line).

4.3.7 Sample Rate Converters (SRC)

All CS470xx devices have at least two internal hardware SRC modules. One is directly associated with the ADCs and normally serves to convert data from the 96 kHz sampling rate of the ADCs to another Fs appropriate for mixing with other audio in the system.

The other SRC module is directly associated with the DACs and normally serves to convert data from the DSP into the 96 kHz sample rate needed by the DACs.

The CS47024, CS47028, and CS47048 devices have an additional stand-alone 8-channel SRC module. This SRC module can be used to make independent input clock domains synchronous (different Fs on PCM input and S/PDIF Rx).



4.3.8 Serial Control Port (I²C or SPI)

The on-chip serial control port is capable of operating as master or slave in either SPI or I2C modes. Master/Slave operation is chosen by mode select pins when the CS470xx comes out of reset. The serial clock pin can support frequencies as high as 25 MHz in SPI mode (SPI clock speed must always be ≤ (DSP Core Frequency/2)). The CS470xx serial control port also includes a pin for flow control of the communications interface (SCP_BSY) and a pin to indicate when the DSP has a message for the host (SCP_IRQ).

4.3.9 **GPIO**

Many of the CS470xx peripheral pins are multiplexed with GPIO. Each GPIO can be configured as an output, an input, or an input with interrupt. Each input-pin interrupt can be configured as rising edge, falling edge, active-low, or active-high.

4.3.10 PLL-based Clock Generator

The low-jitter PLL generates integer or fractional multiples of a reference frequency, which is used to clock the DSP core and peripherals. Through a second PLL divider chain, a dependent clock domain can be output on the DAO port for driving audio converters. The CS470xx defaults to running from the external reference frequency and is switched to use the PLL output after overlays have been loaded and configured, either through master boot from an external flash or through host control. A built-in crystal oscillator circuit with a buffered output is provided. The buffered output frequency ratio is selectable between 1:1 (default) or 2:1.

4.3.11 Hardware Watchdog Timer

The CS470xx has an integrated watchdog timer that acts as a "health" monitor for the DSP. The watchdog timer must be reset by the DSP before the counter expires, or the entire chip is reset. This peripheral ensures that the CS470xx resets itself in the event of a temporary system failure. In stand-alone mode (where there is no host MCU), the DSP reboots from external flash. In slave mode (where the host MCU is present), a GPIO is used to signal the host that the watchdog has expired and the DSP should be rebooted and re-configured.

4.4 DSP I/O Description

4.4.1 Multiplexed Pins

Many of the CS470xx pins are multifunctional. For details on pin functionality, see Section 10.5, "Pin Assignments", in the CS470xx Hardware User's Manual.

4.4.2 Termination Requirements

Open-drain pins on the CS470xx must be pulled high for proper operation. See the CS470xx Hardware User's Manual to identify which pins are open-drain and what value of pull-up resistor is required for proper operation.

Mode select pins on CS470xx are used to select the boot mode on the rising edge from reset. A detailed explanation of termination requirements for each communication mode select pin can be found in the CS470xx Hardware User's Manual.

4.4.3 Pads

The CS470xx Digital I/Os operate from the 3.3 V supply and are 5 V tolerant.

4.5 Application Code Security

The external program code can be encrypted by the programmer to protect any intellectual property it contains. A secret, customer-specific key is used to encrypt the program code that is to be stored external to the device. Contact your local Cirrus representative for details.



5 Characteristics and Specifications

Note: All data sheet minimum and maximum timing parameters are guaranteed over the rated voltage and temperature. All data sheet typical parameters are measured under the following conditions: T = 25°C, VDD = 1.8 V, VDDIO = VDDA = 3.3 V, GND = GNDIO = GNDA = 0 V.

5.1 Absolute Maximum Ratings

(GND = GNDIO = GNDA = 0V; all voltages with respect to 0V)

| Parameter | Symbol | Min | Max | Unit |
|---|----------------------|----------------------|--------------------------|-------|
| DC power supplies: Core supply Analog supply I/O supply VDDA-VDDIO | VDD VDDA VDDIO | -0.3 -0.3 -0.3 | 2.0 3.6 3.6 0.3 | V V V |
| Input pin current, any pin except supplies | l _{in} | _ | ±10 | mA |
| Input voltage on PLL_REF_RES | V_{filt} | -0.3 | 3.6 | V |
| Input voltage on digital I/O pins | V _{inio} | -0.3 | 5.0 | V |
| Analog Input Voltage | V _{in} | AGND-0.7 | VA+0.7 | V |
| Storage temperature | T _{stg} | -65 | 150 | °C |

WARNING: Operation at or beyond these limits can result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

5.2 Recommended Operating Conditions

(GND = GNDIO = GNDA = 0V; all voltages with respect to 0V)

| Parameter | Symbol | Min | Тур | Max | Unit |
|---|----------------------|----------------------|-----|----------------------|-------------|
| DC power supplies: Core supply Analog supply I/O supply VDDA – VDDIO | VDD VDDA VDDIO | 1.71 3.13 3.13 | | 1.89 3.46 3.46 | V V V |
| Ambient operating temperature Commercial—CQZ (147 MHz) Automotive—DQZ (131 MHz) Automotive—DQZ (113 MHz) | T _A | 0 -40 -40 | _ | +70 +85 +105 | °C |

Note: It is recommended that the 3.3 V IO supply come up ahead of or simultaneously with the 1.8 V core supply.

5.3 Digital DC Characteristics

(Measurements performed under static conditions.)

| Parameter | Symbol | Min | Тур | Max | Unit |
|--|---------------------|-----------|-----|-----------|------|
| High-level input voltage | V _{IH} | 2.0 | _ | _ | V |
| Low-level input voltage, except XTI | V _{IL} | _ | _ | 0.8 | V |
| Low-level input voltage, XTI | V _{ILKXTI} | _ | _ | 0.6 | V |
| Input Hysteresis | V _{hys} | _ | 0.4 | _ | V |
| High-level output voltage (I _O = -2mA), except XTO | V _{OH} | VDDIO*0.9 | _ | _ | V |
| Low-level output voltage (I _O = 2mA), except XTO | V _{OL} | _ | _ | VDDIO*0.1 | V |
| Input leakage XTI | I _{LXTI} | _ | _ | 5 | μΑ |
| Input leakage current (all digital pins with internal pull-up resistors enabled) | I _{LEAK} | _ | _ | 70 | μΑ |



5.4 Power Supply Characteristics

Note: Measurements performed under operating conditions

| Parameter | Min | Тур | Max | Unit |
|---|----------|------|----------|------|
| Operational Power Supply Current: | | | | |
| VDD: Core and I/O operating1 | _ | 325 | | mΑ |
| VDDA: PLL operating current | _ | 16 | | mΑ |
| VDDA: DAC operating current (all 8 channels enabled) | _ | 56 | — | mΑ |
| VDDA: ADC operating current (all 4 channels enabled) | — | 34 | _ | mΑ |
| VDDIO: With most ports operating | — | 27 | _ | mΑ |
| Total Operational Power Dissipation: | | 1025 | | mW |
| Standby Power Supply Current: | | | | |
| VDD: Core and I/O not clocked | _ | 410 | _ | μΑ |
| VDDA: PLLs halted | _ | 26 | _ | μĄ |
| VDDA: DAC disabled | — | 40 | — | μĄ |
| VDDA: ADC disabled | _ | 24 | _ | μΑ |
| VDDIO: All connected I/O pins 3-stated by other ICs in system | — | 215 | _ | μΑ |
| Total Standby Power Dissipation: | | 1745 | | μW |

^{1.} Dependent on application firmware and DSP clock speed.

5.5 Thermal Data (100-pin LQFP with Exposed Pad)

| Parameter | Symbol | Min | Тур | Max | Unit |
|--|-----------------|-----|-------------|-----|---------|
| Thermal Resistance (Junction to Ambient) Two-layer Board ¹ Four-layer Board ² | θ_{ja} | | 34 18 | | °C/Watt |
| Thermal Resistance (Junction to Top of Package) Two-layer Board ¹ Four-layer Board ² | Ψ _{jt} | | 0.54 .28 | | °C/Watt |

1. To calculate the die temperature for a given power dissipation:

 T_i = Ambient temperature + [(Power Dissipation in Watts) * θ_{ia}]

2. To calculate the case temperature for a given power dissipation:

$$T_c = T_i$$
 - [(Power Dissipation in Watts) * ψ_{it}]

Note: Two-layer board is specified as a 76 mm X 114 mm, 1.6 mm thick FR-4 material with 1-oz. copper covering 20% of the top and bottom layers.

Four-layer board is specified as a 76 mm X 114 mm, 1.6 mm thick FR-4 material with 1-oz. copper covering 20% of the top and bottom layers and 0.5-oz. copper covering 90% of the internal power plane and ground plane layers.

5.6 Digital Switching Characteristics-RESET

| Parameter | Symbol | Min | Max | Unit |
|---|---------------------|-----|-----|------|
| RESET minimum pulse width low1 | T _{rstl} | 1 | _ | μs |
| All bidirectional pins high-Z after RESET low | T _{rst2z} | _ | 200 | ns |
| Configuration pins setup before RESET high | T _{rstsu} | 50 | _ | ns |
| Configuration pins hold after RESET high | T _{rsthld} | 20 | _ | ns |

^{1.} The rising edge of RESET must not occur before the power supplies are stable at the recommended operating values as described in Section 5.2. In addition, for the configuration pins to be read correctly, the RESET Tristl requirement must be met.

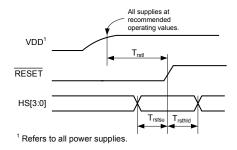


Figure 5-1. RESET Timing at Power-on

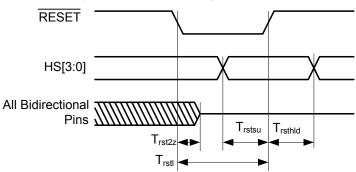


Figure 5-2. RESET Timing after Power is Stable

5.7 Digital Switching Characteristics-XTI

| Parameter | Symbol | Min | Max | Unit |
|--|--------------------|--------|--------|------|
| External Crystal operating frequency ¹ | F _{xtal} | 12.288 | 24.576 | MHz |
| XTI period | T _{clki} | 41 | 81 | ns |
| XTI high time | T _{clkih} | 13.3 | _ | ns |
| XTI low time | T _{clkil} | 13.3 | _ | ns |
| External Crystal Load Capacitance (parallel resonant)2 | C _L | 10 | 18 | pF |
| External Crystal Equivalent Series Resistance | ESR | _ | 50 | Ω |

- 1. Part characterized with the following crystal frequency values: 12.288 and 24.576 MHz.
- 2. C_L refers to the total load capacitance as specified by the crystal manufacturer. Crystals that require a C_L outside this range should be avoided. The crystal oscillator circuit design should follow the crystal manufacturer's recommendation for load capacitor selection.

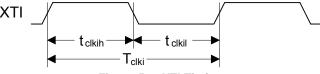


Figure 5-3. XTI Timing



5.8 Digital Switching Characteristics-Internal Clock

| Parameter | Symbol | Min (2- layer Boards) | Min (4- layer Boards) | Max (2- layer Boards) | Max (4- layer Boards) | Unit |
|--|-------------------|--|--|--|---|------|
| Internal DSP_CLK frequency¹ CS47048-CQZ CS47048-DQZ CS47028-CQZ CS47028-DQZ CS47024-CQZ CS47024-DQZ | F _{dclk} | (See Footnote 2) Fxtal | | 147 131 147 131 147 131 | 147 147 147 147 147 147 | MHz |
| Internal DSP_CLK period ¹ CS47048-CQZ CS47048-DQZ CS47028-CQZ CS47028-DQZ CS47024-CQZ CS47024-DQZ | DCLKP | 6.8 7.6 6.8 7.6 6.8 7.6 | 6.8 6.8 6.8 6.8 6.8 6.8 | 1/F 1/F 1/F 1/F | xtal xtal xtal xtal xtal xtal xtal xtal | ns |

^{1.} After initial power-on reset, F_{dclk} = F_{xtal}. After initial kick-start commands, the PLL is locked to max F_{dclk} and remains locked until the next power-on reset

5.9 Digital Switching Characteristics-Serial Control Port-SPI Slave Mode

| Parameter | Symbol | Min | Typical | Max | Unit |
|---|-----------------------|-----|------------|-----|------|
| SCP_CLK frequency1 | f _{spisck} | _ | _ | 25 | MHz |
| SCP_CS falling to SCP_CLK rising | t _{spicss} | 24 | _ | _ | ns |
| SCP_CLK low time | t _{spickl} | 20 | _ | _ | ns |
| SCP_CLK high time | t _{spickh} | 20 | _ | _ | ns |
| Setup time SCP_MOSI input | t _{spidsu} | 5 | _ | _ | ns |
| Hold time SCP_MOSI input | t _{spidh} | 5 | _ | _ | ns |
| SCP_CLK low to SCP_MISO output valid | t _{spidov} | _ | _ | 11 | ns |
| SCP_CLK falling to SCP_IRQ rising | t _{spiirqh} | _ | _ | 27 | ns |
| SCP_CS rising to SCP_IRQ falling | t _{spiirql} | 0 | _ | _ | ns |
| SCP_CLK low to SCP_CS rising | t _{spicsh} | 24 | _ | _ | ns |
| SCP_CS rising to SCP_MISO output high-Z | t _{spicsdz} | _ | 20 | _ | ns |
| SCP_CLK rising to SCP_BSY falling | t _{spicbsyl} | _ | 3*DCLKP+20 | _ | ns |

^{1.} f_{spisck} indicates the maximum speed of the hardware. The system designer should be aware that the actual maximum speed of the communication port can be limited by the firmware application. Flow control using the SCP_BSY pin should be implemented to prevent overflow of the input data buffer. At boot the maximum speed is F_{xtal}/3.

^{2.} See Section 5.7. for all references to F_{xtal}.

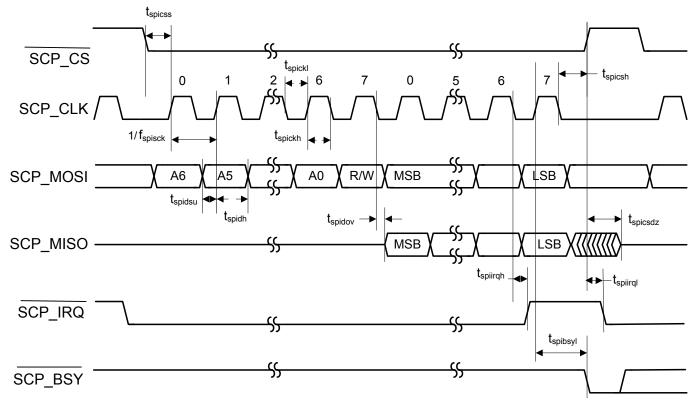


Figure 5-4. Serial Control Port-SPI Slave Mode Timing

5.10 Digital Switching Characteristics-Serial Control Port-SPI Master Mode

| Parameter | Symbol | Min | Typical | Max | Units |
|--|---------------------|-----|-----------------------------|----------------------|-------|
| SCP_CLK frequency ^{1,2} | f _{spisck} | _ | _ | F _{xtal} /2 | MHz |
| EE_CS falling to SCP_CLK rising ³ | t _{spicss} | | 11*DCLKP+(SCP_CLK PERIOD)/2 | _ | ns |
| SCP_CLK low time | t _{spickl} | 18 | ı | _ | ns |
| SCP_CLK high time | t _{spickh} | 18 | _ | _ | ns |
| Setup time SCP_MISO input | t _{spidsu} | 9 | _ | _ | ns |
| Hold time SCP_MISO input | t _{spidh} | 5 | _ | _ | ns |
| SCP_CLK low to SCP_MOSI output valid | t _{spidov} | | _ | 8 | ns |
| SCP_CLK low to EE_CS falling | t _{spicsl} | 7 | _ | _ | ns |
| SCP_CLK low to EE_CS rising | t _{spicsh} | | 11*DCLKP+(SCP_CLK PERIOD)/2 | _ | ns |
| Bus free time between active EE_CS | t _{spicsx} | _ | 3*DCLKP | _ | ns |
| SCP_CLK falling to SCP_MOSI output high-Z | t _{spidz} | _ | | 20 | ns |

^{1.} f_{spisck} indicates the maximum speed of the hardware. The system designer should be aware that the actual maximum speed of the communication port can be limited by the firmware application.

^{2.} See Section 5.7.

^{3.} SCP_CLK PERIOD refers to the period of SCP_CLK as being used in a given application. It does not refer to a tested parameter.

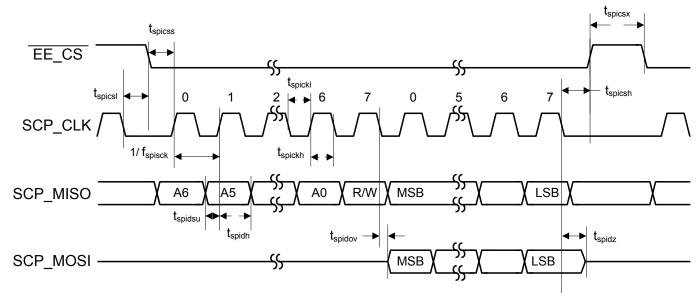


Figure 5-5. Serial Control Port-SPI Master Mode Timing

5.11 Digital Switching Characteristics-Serial Control Port I²C Slave Mode

| Parameter | Symbol | Min | Typical | Max | Units |
|---|----------------------|------|------------|------------|-------|
| SCP_CLK frequency ¹ | f _{iicck} | _ | _ | 400 | kHz |
| SCP_CLK rise time | t _{iicr} | _ | _ | 150 | ns |
| SCP_CLK fall time | t _{iicf} | _ | _ | 150 | ns |
| SCP_CLK low time | t _{iicckl} | 1.25 | _ | _ | μs |
| SCP_CLK high time | t _{iicckh} | 1.25 | _ | _ | μs |
| SCP_CLK rising to SCP_SDA rising or falling for START or STOP condition | tiicckcmd | 1.25 | _ | _ | μs |
| START condition to SCP_CLK falling | tiicstscl | 1.25 | _ | _ | μs |
| SCP_CLK falling to STOP condition | t _{iicstp} | 2.5 | _ | _ | μs |
| Bus free time between STOP and START conditions | tiicbft | 3 | _ | _ | μs |
| Setup time SCP_SDA input valid to SCP_CLK rising | t _{iicsu} | 110 | _ | _ | ns |
| Hold time SCP_SDA input after SCP_CLK falling | t _{iich} | 100 | _ | _ | ns |
| SCP_CLK low to SCP_SDA out valid | tiicdov | _ | _ | 18 | ns |
| SCP_CLK falling to SCP_IRQ rising | tiicirqh | _ | _ | 3*DCLKP+40 | ns |
| NAK condition to SCP_IRQ low | t _{iicirql} | _ | 3*DCLKP+20 | _ | ns |
| SCP_CLK rising to SCB_BSY low | t _{iicbsyl} | _ | 3*DCLKP+20 | _ | ns |

^{1.} f_{licck} indicates the maximum speed of the hardware. The system designer should be aware that the actual maximum speed of the communication port can be limited by the firmware application. Flow control using the SCP_BSY pin should be implemented to prevent overflow of the input data buffer.

I²C Slave Address = 0x82

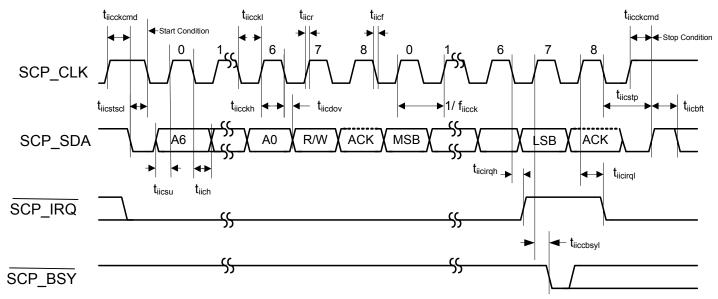


Figure 5-6. Serial Control Port-I²C Slave Mode Timing

5.12 Digital Switching Characteristics-Serial Control Port-I²C Master Mode

| Parameter | Symbol | Min | Max | Units |
|---|-----------------------|------|-----|-------|
| SCP_CLK frequency ¹ | f _{iicck} | _ | 400 | kHz |
| SCP_CLK rise time | t _{iicr} | _ | 150 | ns |
| SCP_CLK fall time | t _{iicf} | _ | 150 | ns |
| SCP_CLK low time | t _{iicckl} | 1.25 | _ | μs |
| SCP_CLK high time | t _{iicckh} | 1.25 | _ | μs |
| SCP_CLK rising to SCP_SDA rising or falling for START or STOP condition | tiicckcmd | 1.25 | | μs |
| START condition to SCP_CLK falling | t _{iicstscl} | 1.25 | | μs |
| SCP_CLK falling to STOP condition | t _{iicstp} | 2.5 | | μs |
| Bus free time between STOP and START conditions | t _{iicbft} | 3 | | μs |
| Setup time SCP_SDA input valid to SCP_CLK rising | t _{iicsu} | 110 | | ns |
| Hold time SCP_SDA input after SCP_CLK falling | t _{iich} | 100 | _ | ns |
| SCP_CLK low to SCP_SDA out valid | t _{iicdov} | _ | 36 | ns |

^{1.} f_{licck} indicates the maximum speed of the hardware. The system designer should be aware that the actual maximum speed of the communication port can be limited by the firmware application.

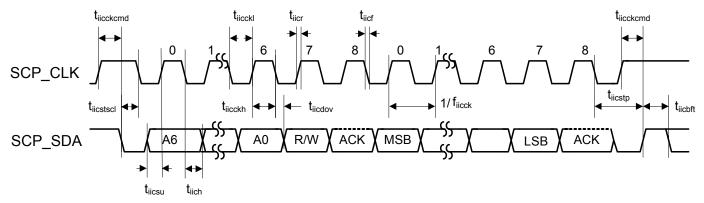


Figure 5-7. Serial Control Port-I²C Master Mode Timing



5.13 Digital Switching Characteristics-Digital Audio Slave Input Port

| Parameter | Symbol | Min | Max | Unit |
|----------------------|----------------------|-----|-----|------|
| DAI_SCLK period | T _{daiclkp} | 20 | _ | ns |
| DAI_SCLK duty cycle | _ | 45 | 55 | % |
| Setup time DAI_DATAn | t _{daidsu} | 8 | _ | ns |
| Hold time DAI_DATAn | t _{daidh} | 5 | | ns |

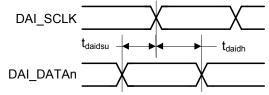


Figure 5-8. Digital Audio Input (DAI) Port Timing Diagram

5.14 Digital Switching Characteristics-Digital Audio Output Port

| Parameter | Symbol | Min | Max | Unit |
|--|-----------------------|-----|-----|------|
| DAO_MCLK period | T _{daomclk} | 20 | _ | ns |
| DAO_MCLK duty cycle | _ | 45 | 55 | % |
| DAO_SCLK period for Master or Slave mode1 | T _{daosclk} | 20 | _ | ns |
| DAO_SCLK duty cycle for Master or Slave mode1 | _ | 40 | 60 | % |
| Master Mode (Output A1 Mode) ^{1,2} | • | • | | |
| DAO_SCLK delay from DAO_MCLK rising edge, DAO MCLK as an input | t _{daomsck} | _ | 19 | ns |
| DAO_LRCLK to DAO_SCLK inactive edge ³ . See Fig. 5-9. | t _{daomirts} | _ | 8 | ns |
| DAO_SCLK inactive edge ³ to DAO_LRCLK. See Fig. 5-10. | t _{daomstlr} | _ | 8 | ns |
| DAO_DATA[3:0] delay from DAO_SCLK inactive edge ³ | t _{daomdy} | _ | 8 | ns |
| Slave Mode (Output A0 Mode) ⁴ | | | | |
| DAO_SCLK active edge to DAO_LRCLK transition. See Fig. 5-11. | t _{daosstlr} | 10 | _ | ns |
| DAO_LRCLK transition to DAO_SCLK active edge. See Fig. 5-12. | t _{daosIrts} | 10 | _ | ns |
| DAO_Dx delay from DAO_SCLK inactive edge | t _{daosdv} | _ | 11 | ns |

- 1. Master mode timing specifications are characterized, not production tested.
- 2. Master mode is defined as the CS47048 driving both DAO_SCLK, DAO_LRCLK. When MCLK is an input, it is divided to produce DAO_SCLK, DAO_LRCLK.
- 3. The DAO_LRCLK transition can occur on either side of the edge of DAO_SCLK. The active edge of DAO_SCLK is the point at which the data is valid.
- 4. Slave mode is defined as DAO_SCLK, DAO_LRCLK driven by an external source.

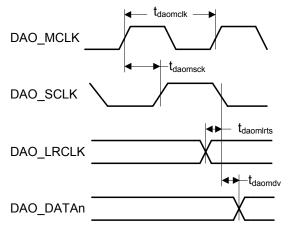


Figure 5-9. DAO_LRCLK Transition before DAO_SCLK Inactive Edge

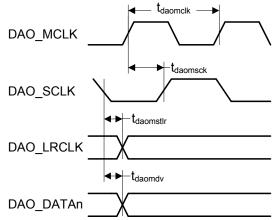


Figure 5-10. DAO_LRCLK Transition after DAO_SCLK Inactive Edge

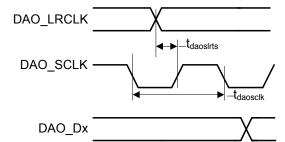


Figure 5-11. DAO_LRCLK Transition before DAO_SCLK Inactive Edge

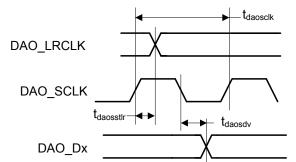


Figure 5-12. DAO_LRCLK Transition after DAO_SCLK Inactive Edge



5.15 Digital Switching Characteristics-S/PDIF RX Port

(Inputs: Logic $0 = V_{IL}$, Logic $1 = V_{IH}$, $C_L = 20 pF$)

| Parameter | Symbol | Min | Тур | Max | Units |
|--------------------------------------|--------|-----|-----|-----|-------|
| PLL Clock Recovery Sample Rate Range | _ | 30 | _ | 200 | kHz |

5.16 ADC Characteristics

5.16.1 Analog Input Characteristics (Commercial)

Test Conditions (unless otherwise specified): $T_A = 0-+70^{\circ}C$; VDD = 1.8V±5%, VDDA (VA) = 3.3V±5%, 1kHz sine wave driven through the passive input filter ($R_i = 10 \text{ k}\Omega$) in Fig. 5-13 or Fig. 5-14; DSP running test application; Measurement Bandwidth is 10–20kHz.

| | D | Differential Single-ended | | | ed | | |
|---|------------------|---------------------------|-------------|------------------|--------------------------|--------------------|----------------------|
| Parameter | Min | Тур | Max | Min | Тур | Max | Unit |
| Fs = 96 kHz | | | | | | | |
| Dynamic Range ^{1,6,7} A-weighted Unweighted 40 kHz bandwidth unweighted | 99 96 — | 105 102 99 | | 96 93 — | 102 99 96 | 111 | dB dB dB |
| Total Harmonic Distortion + Noise ^{6,7} –1 dB –20 dB –60 dB 40 kHz bandwidth –1 dB | _ _ _ _ | -98 -82 -42 -90 | -92 | _ _ _ _ | -95 -79 -39 -90 | -89 - - - | dB dB dB dB |
| AIN_1A/B Interchannel Isolation ¹⁰ | _ | 95 | _ | _ | 95 | _ | dB |
| AID_[2.6]A/B MUX Interchannel Isolation | _ | 95 | _ | _ | 95 | _ | dB |
| DC Accuracy | | | | | | | |
| Interchannel Gain Mismatch | _ | 0.1 | _ | _ | 0.1 | _ | dB |
| Gain Drift | _ | ±120 | _ | _ | ±120 | _ | ppm/°C |
| Analog Input | | | | | • | | |
| Full-scale Input Voltage ^{2,3} | 3.3 | 3.7•VA | 3.9 | 1.65 | 1.85•VA | 1.95 | V_{PP} |
| Differential Input Impedance ⁴ | _ | 400 | _ | _ | _ | _ | Ω |
| Single-ended Input Impedance ⁵ | _ | _ | _ | _ | 200 | _ | Ω |
| Common Mode Rejection Ratio (CMRR)8 | _ | 60 | _ | _ | _ | _ | dB |
| Parasitic Load Capacitance (C _L) ⁹ | _ | _ | 20 | _ | _ | 20 | pF |

- 1. dB units referred to the typical full-scale voltage.
- 2. These full-scale values were measured with Ri=10k for both the single-ended and differential mode input circuits.
- The full-scale voltage can be changed by scaling R_i.
 Differential Full-Scale (Vpp) = 3.7*VDDA*(Ri+200)/(10k+200)
 Single-Ended Full-Scale (Vpp) = 1.85*VDDA*(Ri+200)/(10k+200)
- 4. Measured between AIN_xx+ and AN_xx-.
- 5. Measured between AIN_xx+ and AGND.
- 6. Decreasing full-scale voltage by reducing R_i causes the noise floor to increase.
- 7. Common mode input current should be kept to less than ± 160 uA to avoid performance degradation: $|(l_{ip}+l_{in})/2| < 160$ uA. This corresponds to ± 1.6 V for $R_i=10$ k Ω in the differential case.
- 8. This number was measured using perfectly matched external resistors (R_i). Mismatch in the external resistors typically reduces CMRR by 20 log ($|\Delta R_i|/R_i + 0.001$).
- 9. C_L represents the parasitic load capacitance between R_i on the input circuit and the input pin of the CS47048 package.
- 10. This measurement is not applicable to the CS47028 and CS47024 devices.



5.16.2 Analog Input Characteristics (Automotive)

Test Conditions (unless otherwise specified): TA = $-40-85^{\circ}$ C; VDD = $1.8V\pm5\%$, VDDA (VA) = $3.3V\pm5\%$; kHz sine wave driven through the passive input filter (R_i = $10 \text{ k}\Omega$) in Fig. 5-13 or Fig. 5-14; DSP running test application; Measurement Bandwidth is 10 Hz-20 kHz.

| | D | ifferent | erential Single-ended | | | ed | |
|---|------------------|--------------------------|-----------------------|------------------|--------------------------|--------------------|----------------------|
| Parameter | Min | Тур | Max | Min | Тур | Max | Unit |
| Fs = 96 kHz | | | | | | | |
| Dynamic Range ^{1,6,7} A-weighted Unweighted 40 kHz bandwidth unweighted | 97 94 — | 105 102 99 | _ | 94 91 — | 102 99 96 | _ | dB dB dB |
| Total Harmonic Distortion + Noise ^{6,7} –1 dB –20 dB –60 dB 40 kHz bandwidth –1 dB | _ _ _ _ | -98 -82 -42 -90 | _90 _ _ _ | _ _ _ _ | -95 -79 -39 -90 | -87 - - - | dB dB dB dB |
| AIN_1A/B Interchannel Isolation ¹⁰ | _ | 95 | _ | _ | 95 | _ | dB |
| AID_[2.6]A/B MUX Interchannel Isolation | _ | 95 | _ | _ | 95 | _ | dB |
| DC Accuracy | | • | | | | | |
| Interchannel Gain Mismatch | _ | 0.1 | _ | _ | 0.1 | _ | dB |
| Gain Drift | _ | ±120 | _ | _ | ±120 | _ | ppm/°C |
| Analog Input | | • | | | | | |
| Full-scale Input Voltage ^{2,3} | 3.3 | 3.7•VA | 3.9 | 1.65 | 1.85•VA | 1.95 | V_{PP} |
| Differential Input Impedance ⁴ | _ | 400 | _ | _ | _ | _ | Ω |
| Single-ended Input Impedance ⁵ | _ | _ | _ | _ | 200 | _ | Ω |
| Common Mode Rejection Ratio (CMRR)8 | _ | 60 | _ | _ | _ | _ | dB |
| Parasitic Load Capacitance (C _L) ⁹ | _ | _ | 20 | _ | _ | 20 | pF |

- 1. dB units referred to the typical full-scale voltage.
- 2. These full-scale values were measured with Ri=10k for both the single-ended and differential mode input circuits.
- The full-scale voltage can be changed by scaling R_i.
 Differential Full-Scale (Vpp) = 3.7*VDDA*(Ri+200)/(10k+200)
 Single-Ended Full-Scale (Vpp) = 1.85*VDDA*(Ri+200)/(10k+200)
- 4. Measured between AIN xx+ and AN xx-.
- Measured between AIN_xx+ and AGND.
- 6. Decreasing full-scale voltage by reducing $R_{\rm i}$ causes the noise floor to increase.
- 7. Common mode input current should be kept to less than ± 160 uA to avoid performance degradation: $|(I_{ip}+I_{in})/2| < 160$ uA. This corresponds to ± 1.6 V for $R_i=10$ k Ω in the differential case.
- 8. This number was measured using perfectly matched external resistors (R_i). Mismatch in the external resistors typically reduces CMRR by 20 log ($|\Delta R_i|/R_i + 0.001$).
- 9. CL represents the parasitic load capacitance between Ri on the input circuit and the input pin of the CS47048 package.
- 10. This measurement is not applicable to the CS47028 and CS47024 devices.

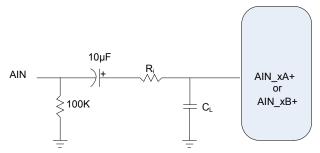


Figure 5-13. ADC Single-ended Input Test Circuit



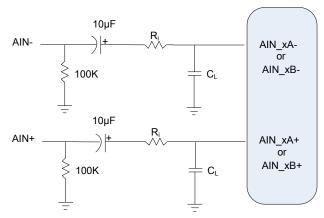


Figure 5-14. ADC Differential Input Test Circuit

5.16.3 ADC Digital Filter Characteristics

| Parameter1,2 | Min | Тур | Max | Unit |
|---|--------|---------------------|--------|----------|
| Fs = 96 kHz | | | • | |
| Passband (Frequency Response) to -0.1 dB corner | 0 | _ | 0.4896 | Fs |
| Passband Ripple | _ | _ | 0.08 | dB |
| Stopband | 0.5688 | _ | _ | Fs |
| Stopband Attenuation | 70 | _ | _ | dB |
| Total Group Delay | _ | 12/Fs | _ | S |
| High-pass Filter Characteristics | | | | |
| Frequency Response: -3.0 dB -0.13 dB | _ | 1 20 | _ | Hz Hz |
| Phase Deviation @ 20 Hz | _ | 10 | _ | Deg |
| Passband Ripple | _ | _ | 0 | dB |
| Filter Settling Time | _ | 10 ⁵ /Fs | 0 | S |

^{1.} Filter response is guaranteed by design.

5.17 DAC Characteristics

5.17.1 Analog Output Characteristics (Commercial)

Test Conditions (unless otherwise specified): $TA = 0-+70^{\circ}C$; $VDD = 1.8V\pm5\%$, $VDDA(VA) = 3.3V\pm5\%$; 1 kHz sine wave driven through a filter shown in Fig. 5-15 or Fig. 5-16; DSP running test application; Measurement Bandwidth is 20 Hz–20 kHz.

| | D | Differential Single-ended | | | | | |
|---|--------------|---------------------------|---------|----------|-------------------|---------|----------------|
| Parameter | Min | Тур | Max | Min | Тур | Max | Unit |
| Fs = 96 kHz | | | | | | | |
| Dynamic Range A-weighted Unweighted | 102 99 | 108 105 | _ | 99 96 | 105 102 | _ | dB dB |
| Total Harmonic Distortion + Noise 0 dB -20 dB -60 dB | - - | -98 -88 -48 | -90 | | -95 -85 -45 | -87 | dB dB dB |
| Interchannel Isolation (1 kHz) | — | 95 | _ | _ | 95 | _ | dB |

^{2.} Response is clock-dependent and scales with Fs.



| | Differential | | | Sii | | | |
|---|--------------|---------|------|------|---------|------|-----------------|
| Parameter | Min | Тур | Max | Min | Тур | Max | Unit |
| Analog Input | | | | | | | |
| Full-scale Output | 1.20 | 1.40•VA | 1.60 | 0.60 | 0.70•VA | 0.80 | V _{PP} |
| Interchannel Gain Mismatch | _ | 0.1 | _ | _ | 0.1 | _ | dB |
| Gain Drift | _ | ±120 | _ | _ | ±120 | _ | ppm/°C |
| Output Impedance | _ | 100 | _ | _ | 100 | _ | Ω |
| DC Current Draw from an AOUT Pin1 | _ | _ | 10 | _ | _ | 10 | μΑ |
| AC-load Resistance (R _L) ² | 3 | _ | _ | 3 | _ | _ | kΩ |
| Load Capacitance (C _L) ² | | _ | 100 | | _ | 100 | pF |

5.17.2 Analog Output Characteristics (Automotive)

Test Conditions (unless otherwise specified): $T_A = -40$ to $+85^{\circ}$ C; VDD = 1.8V±5%, VDDA(VA) = 3.3V±5%; 1 kHz sine wave driven through a filter shown in Fig. 5-15 or Fig. 5-16; DSP running test application; Measurement Bandwidth is 20 Hz–20 kHz.

| | Differential | | Single-ended | | | | |
|---|--------------|-------------------|--------------|----------|-------------------|---------|-----------------|
| Parameter | Min | Тур | Max | Min | Тур | Max | Unit |
| Fs = 96 kHz | Fs = 96 kHz | | | | | | |
| Dynamic Range A-weighted Unweighted | 100 97 | 108 105 | _ | 97 94 | 105 102 | _ | dB dB |
| Total Harmonic Distortion + Noise 0 dB -20 dB -60 dB | _ _ _ | -98 -88 -48 | -90 | | -95 -85 -45 | -87 | dB dB dB |
| Interchannel Isolation (1 kHz) | _ | 95 | _ | | 95 | _ | dB |
| Analog Input | | | | | | | |
| Full-scale Output | 1.20 | 1.40•VA | 1.60 | 0.60 | 0.70•VA | 0.80 | V _{PP} |
| Interchannel Gain Mismatch | _ | 0.1 | _ | _ | 0.1 | _ | dB |
| Gain Drift | _ | ±120 | _ | _ | ±120 | _ | ppm/°C |
| Output Impedance | _ | 100 | _ | _ | 100 | _ | Ω |
| DC Current Draw from an AOUT Pin1 | _ | _ | 10 | | _ | 10 | μΑ |
| AC-load Resistance (R _L) ² | 3 | _ | _ | 3 | _ | _ | kΩ |
| Load Capacitance (C _L) ² | _ | _ | 100 | _ | _ | 100 | pF |

- 1. Guaranteed by design. The DC current draw represents the allowed current draw from the AOUT pin due to typical leakage through the electrolytic DC-blocking capacitors.
- 2. Guaranteed by design. R_L and C_L reflect the recommended minimum resistance and maximum capacitance required for the internal op-amp's stability and signal integrity. In this circuit topology, C_L represents any capacitive loading that appears *before* the 560 Ω series resistor (typically parasitic), and effectively moves the dominant pole of the two-pole amp in the output stage. Increasing this value beyond the recommended 100 pF can cause the internal op-amp to become unstable.

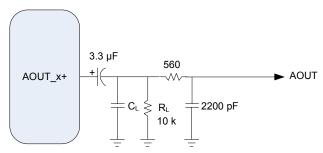
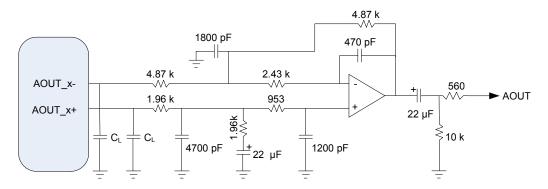


Figure 5-15. DAC Single-ended Output Test Circuit





P output: $R_L = 1.96k + ([2\pi F^*4700pF]^{-1}||(1.96k + [2\pi F^*22\mu F^{-}]^{-1})||(953 + [2\pi F^*1200pF]^{-1})|$ N output: $R_L = 4.87k + ([2\pi F^*1800pF]^{-1}||((2.43k + [2\pi F^*470pF]^{-1})||4.87k|))$

Figure 5-16. DAC Differential Output Test Circuit

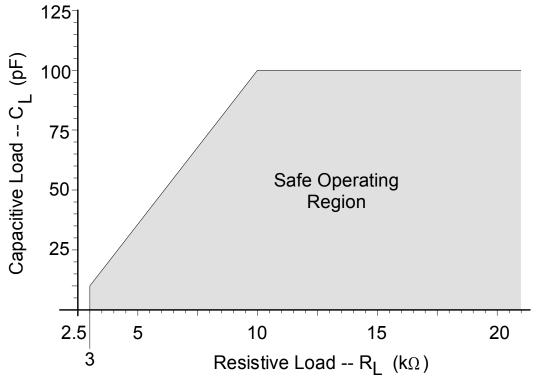


Figure 5-17. Maximum Loading

5.17.3 Combined DAC Interpolation and On-chip Analog Filter Response

| Parameter | Min | Тур | Max | Unit |
|---|--------|-------|------------------|------|
| Passband (Frequency Response) to 0.22 dB corner to –3 dB corner | 0 | | 0.4125 0.4979 | |
| Frequency Response 10 Hz-20 kHz | -0.02 | _ | +0.02 | dB |
| StopBand | 0.5465 | _ | _ | Fs |
| StopBand Attenuation | 100 | _ | _ | dB |
| Group Delay | _ | 10/Fs | _ | S |



6 Ordering Information

The CS470xx DSP part numbers are described as follows:

Example:

CS47048I-XYZR

where

I-ROM ID Letter

X-Product Grade

Y-Package Type

Z-Lead (Pb) Free

R-Tape and Reel Packaging

Table 6-1. Ordering Information

| Part No. | Grade | Temp. Range | Package |
|--------------|---------------------|-------------|--------------|
| CS47048C-CQZ | Commercial | 0-+70°C | 100-pin LQFP |
| CS47048C-DQZ | Automotive | -40-+85°C | |
| CS47048C-EQZ | Extended Automotive | -40-+105°C | |
| CS47028C-CQZ | Commercial | 0-+70°C | |
| CS47028C-DQZ | Automotive | -40-+85°C | |
| CS47028C-EQZ | Extended Automotive | -40-+105°C | |
| CS47024C-CQZ | Commercial | 0-+70°C | |
| CS47024C-DQZ | Automotive | -40-+85°C | |
| CS47024C-EQZ | Extended Automotive | -40-+105°C | |

Note: Contact the factory for availability of the –D (automotive grade) package.

7 Environmental, Manufacturing, and Handling Information

Table 7-1. Environmental, Manufacturing, and Handling Information

| Model Number | Peak Reflow Temp. | MSL ¹ Rating | Max Floor Life |
|--------------|-------------------|-------------------------|----------------|
| CS47048C-CQZ | 260° C | 3 | 7 days |
| CS47048C-DQZ | | | |
| CS47048C-EQZ | | | |
| CS47028C-CQZ | 260° C | 3 | 7 days |
| CS47028C-DQZ | | | |
| CS47028C-EQZ | | | |
| CS47024C-CQZ | 260° C | 3 | 7 days |
| CS47024C-DQZ | | | |
| CS47024C-EQZ | | | |

1. Moisture Sensitivity Level as specified by IPC/JEDEC J-STD-020.



8 Device Pinout Diagrams

8.1 CS47048, 100-pin LQFP Pinout Diagram

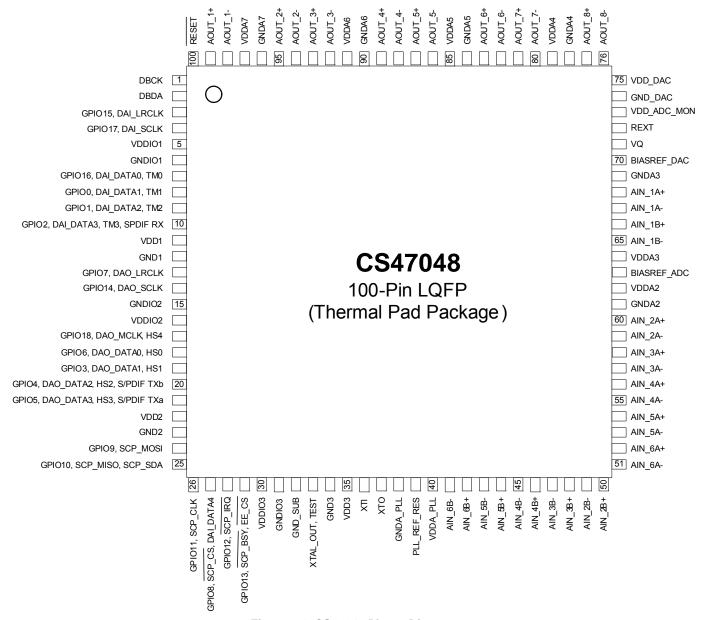


Figure 8-1. CS47048 Pinout Diagram



8.2 CS47028, 100-pin LQFP Pinout Diagram

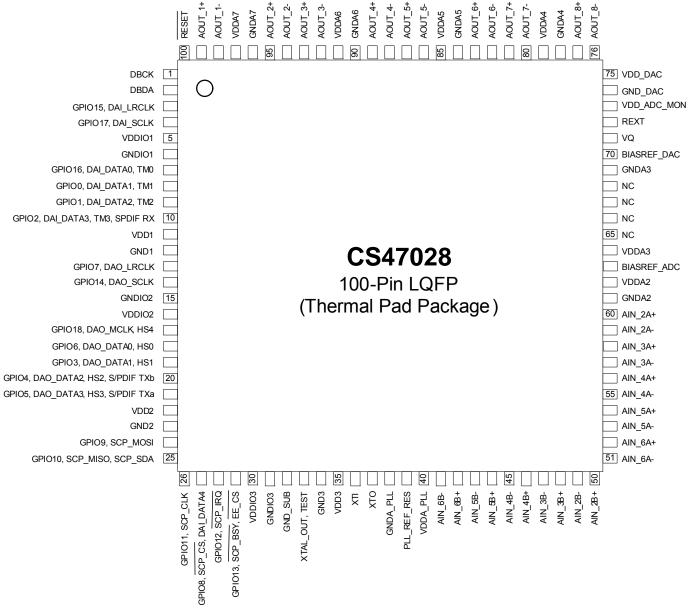


Figure 8-2. CS47028 Pinout Diagram



8.3 CS47024, 100-pin LQFP Pinout Diagram

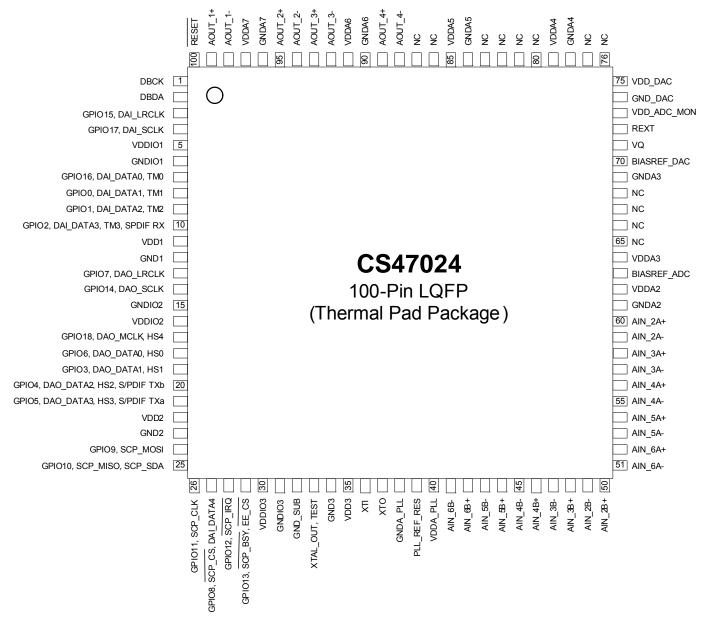
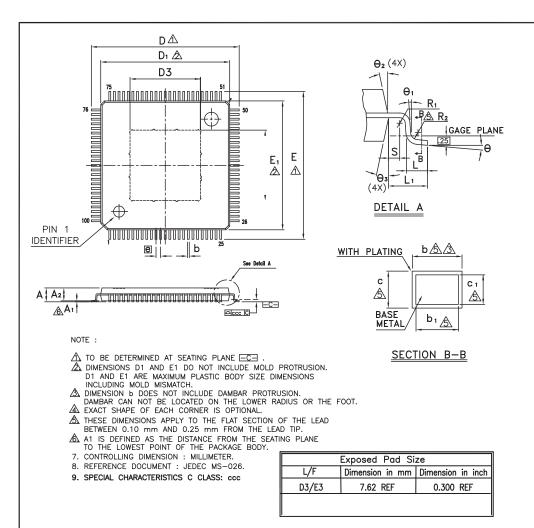


Figure 8-3. CS47024 Pinout Diagram

9 100-pin LQFP with Exposed Pad Package Drawing

Fig. 9-1 shows the 100-pin LQFP package with exposed pad for the CS47048, CS47028, and CS47024.



| Symbol | Din | nension | in mm | Dir |
|---------------------|----------|---------|-------|------|
| Syllibol | Min | Nom | Max | Min |
| Α | _ | _ | 1.60 | _ |
| A1 | 0.05 | _ | 0.15 | 0.0 |
| A ₂ | 1.35 | 1.40 | 1.45 | 0.0 |
| Ь | 0.17 | 0.22 | 0.27 | 0.0 |
| b ₁ | 0.17 | 0.20 | 0.23 | 0.0 |
| С | 0.09 | _ | 0.20 | 0.0 |
| C1 | 0.09 | _ | 0.16 | 0.0 |
| D | 15.85 | 16.00 | 16.15 | 0.6 |
| D ₁ | 13.90 | 14.00 | 14.10 | 0.5 |
| E E ₁ | 15.85 | 16.00 | 16.15 | 0.6 |
| E ₁ | 13.90 | 14.00 | 14.10 | 0.5 |
| е | 0.50 BSC | | | |
| L | 0.45 | 0.60 | 0.75 | 0.0 |
| L ₁ | 1.00 REF | | | |
| R ₁ | 0.08 | _ | _ | 0.00 |
| R₂ | 0.08 | _ | 0.20 | 0.00 |
| S | 0.20 | _ | _ | 0.00 |
| θ | 0, | 3.5° | 7° | 0. |
| θ1 | 0, | | | 0. |
| Θ₂ | 12°TYP | | | |
| Өз | | | | |
| ccc | 0.08 | | | |
| | | | | |

100LD E-PAD LQFP (14x14x1.4mm -Cu L/F,F00TPRINT 2.0mm

Figure 9-1. 100-pin LQFP Package Drawing



10 Parameter Definitions

10.1 Dynamic Range

The ratio of the RMS value of the signal to the RMS sum of all other spectral components over the specified bandwidth. Dynamic Range is a signal-to-noise ratio measurement over the specified bandwidth made with a -60 dBFS signal. 60 dB is added to resulting measurement to refer the measurement to full-scale. This technique ensures that the distortion components are below the noise level and do not affect the measurement. This measurement technique has been accepted by the Audio Engineering Society, AES17-1991, and the Electronic Industries Association of Japan, EIAJ CP-307. Expressed in decibels.

10.2 Total Harmonic Distortion + Noise

The ratio of the RMS value of the signal to the RMS sum of all other spectral components over the specified bandwidth (typically 10 Hz–20 kHz), including distortion components. Expressed in decibels. Measured at –1 and –20 dBFS as suggested in AES17-1991 Annex A.

10.3 Frequency Response

A measure of the amplitude response variation from 10 Hz–20 kHz relative to the amplitude response at 1 kHz. Units in decibels.

10.4 Interchannel Isolation

A measure of crosstalk between the left and right channels. Measured for each channel at the converter's output with no signal to the input under test and a full-scale signal applied to the other channel. Units in decibels.

10.5 Interchannel Gain Mismatch

The gain difference between left and right channels. Units in decibels.

10.6 Gain Error

The deviation from the nominal full-scale analog output for a full-scale digital input.

10.7 Gain Drift

The change in gain value with temperature. Units in ppm/°C.



11 Revision History

| Revision | Date | Changes |
|----------|----------------|--|
| PP1 | August, 2009 | Updated Characterization data in Section 5.4, Section 5.7, Section 5.9, Section 5.11, Section 5.12, Section 5.16.1, Section 5.16.2, Section 5.16.3, Section 5.17.1, and Section 5.17.2. Modified Footnote 3 in both Section 5.16.1 and Section 5.16.2. Added Footnote 5 to Section 5.14. Updated Section 2.1. Modified Section 4.3.6 and Section 4.3.8. Modified references to TDM in various sections of the data sheet. |
| PP2 | January, 2010 | Updated TDM Feature description on page 1. Modified note at the bottom of the feature list on page 1. Updated table in Section 5.8, specifying performance data for 2- and 4-layer boards. Updated Table 3-1 and Table 3-2 Updated block diagrams in Fig. 4-1, Fig. 4-2, and Fig. 4-3. |
| PP3 | June, 2010 | Table 3-1: Straddled all three columns in the "Supports Different Fs Sample Rates" row to indicate that CS47024 devices have the same features as the CS47048 and CS47028. Added "The CS47024 has the 8-channel SRC block" to Section 4.3.7. Added text in the following places to indicate that the CS47024 implements the S/PDIF Rx functionality: Removed dagger from the S/PDIF Rx bullet on p. 1. Updated bullet in "Configurable Serial Audio Inputs/Outputs" row in Table 2 Integrated 192 kHz S/PDIF Rx, 2 Integrated 192 kHz S/PDIF Tx. Changed entry in "S/PDIF In (Stereo Pairs)" column in Table 3-2. Updated I2S block in Table 3-2. Removed text "On the CS47048 and CS47028" from Section 4.3.4. Removed "(Not available on CS47024)" from the heading to Section 5.15. Described additional support for TDM 8-channel output mode on CS47024. Removed dagger from the TDM I/O bullet on p. 1. Straddled "Configurable Serial Audio Inputs/Outputs" row in Table 3-1. Changed cell in "TDM Out" column in Table 3-2. Removed text "On the CS47048 and CS47028" from Section 4.3.5. |
| PP4 | February, 2011 | Added "Decoder" information to Section 3. Changed the name of the core to "Cirrus Logic 32-bit core". |
| PP5 | February, 2011 | Added "SPDIF RX" to Fig. 5-17. |
| PP6 | June, 2011 | In Section 4.3.1 and Section 4.3.7, removed mention of 192 kHz sampling frequency. Updated temperature operating conditions in Section 5.2. Updated pin 33 to XTAL_OUT, TEST in Fig. 8-1, Fig. 8-2, and Fig. 8-3. |
| PP7 | April, 2012 | Corrected peak reflow temperature in Table 7-1. |
| PP8 | June, 2012 | Added number of bits to Integrated DAC and ADC Functionality on the cover page. |
| PP9 | July, 2012 | Updated frequencies in Section 5.2. Added extended automotive grade information to Section 6 and Section 7. |

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HMC288MS8ETR HMC240A STA323W13TR BU9408KS2 DSPB56725AF TAS3204PAGR ADAU1467WBCPZ300

ADAU1463WBCPZ300 BD37514FS-E2 ADAU1463WBCPZ150 ADAU1466WBCPZ300 NJM2294V-TE1 LC823450TA-2H NJM2537V-TE1 TWL1103TPBSQ1 LC823450XDTBG HMC-AUH312-SX ADAV4622BSTZ