



# System-on-Module datasheet

Version 1.11

## Features

- NXP iMX 8M SoC
  - Quad-core ARM Cortex-A53, plus Cortex-M4F
  - 2D/3D Vivante GC7000 Lite GPU and VPU
- Google Edge TPU ML accelerator
- Cryptographic coprocessor
- Wi-Fi 2x2 MIMO (802.11b/g/n/ac 2.4/5 GHz)
- Bluetooth 4.2
- 8 or 16 GB eMMC
- 1, 2, or 4 GB LPDDR4
- USB 3.0
- Gigabit Ethernet
- HDMI and MIPI-DSI
- MIPI-CSI-2
- Up to 95x GPIO (including SPI, I2C, PWM, UART, SAI, and SDIO)

## Description

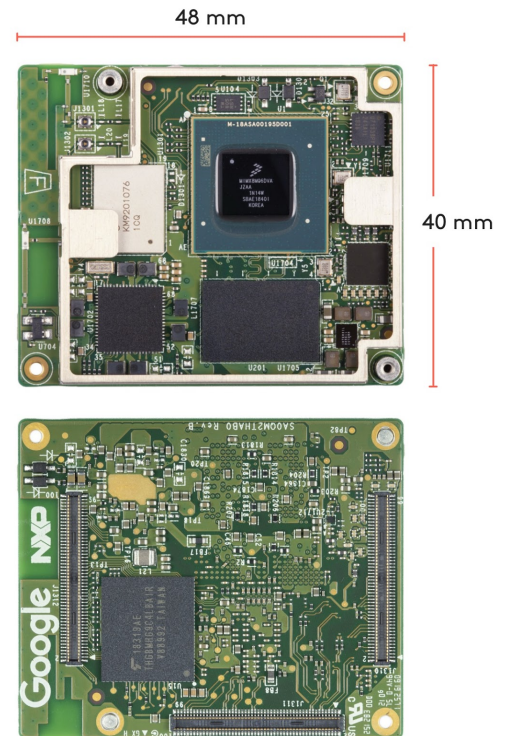
The Coral System-on-Module (SoM) is a fully-integrated system that helps you build embedded systems that demand fast machine learning (ML) inferencing. It contains NXP's iMX 8M system-on-chip (SoC), eMMC memory, LPDDR4 RAM, Wi-Fi, and Bluetooth, but its unique power comes from Google's Edge TPU coprocessor.

The Edge TPU is a small ASIC designed by Google that accelerates TensorFlow Lite models in a power efficient manner: it's capable of performing 4 trillion operations per second (4 TOPS), using 2 watts of power—that's 2 TOPS per watt. For example, the Edge TPU can execute state-of-the-art mobile vision models such as MobileNet v2 at almost 400 frames per second. This on-device ML processing reduces latency, increases data privacy, and removes the need for a constant internet connection.

Key benefits of the SoM:

- High-speed and low-power ML inferencing (4 TOPS @2 W)
- A complete Linux system (running Mendel, a Debian derivative)
- Small footprint (40 x 48 mm)

The SoM is also included in the [Coral Dev Board](#), which is a single-board computer that enables fast prototyping and evaluation of the standalone SoM.



## Ordering information

Part number	Description
G650-04474-01	Coral System-on-Module with 1 GB RAM (8 GB eMMC)
G650-05369-01	Coral System-on-Module with 2 GB RAM (8 GB eMMC)
G650-05370-01	Coral System-on-Module with 4 GB RAM (16 GB eMMC)

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# 1 System components

**Table 1.** Available SoM components and features

Feature	Details
Main system-on-chip (iMX 8M)	
Arm Cortex-A53 MPCore platform	Quad symmetric Cortex-A53 processors: <ul style="list-style-type: none"> <li>● 32 KB L1 Instruction Cache</li> <li>● 32 KB L1 Data Cache</li> <li>● Support L1 cache RAMs protection with parity/ECC</li> </ul> Support of 64-bit Armv8-A architecture: <ul style="list-style-type: none"> <li>● 1 MB unified L2 cache</li> <li>● Support L2 cache RAMs protection with ECC</li> <li>● Frequency of 1.5 GHz</li> </ul>
Arm Cortex-M4 core platform	<ul style="list-style-type: none"> <li>● 16 KB L1 Instruction Cache</li> <li>● 16 KB L1 Data Cache</li> <li>● 256 KB tightly coupled memory (TCM)</li> </ul>
Graphic Processing Unit (GPU)	<ul style="list-style-type: none"> <li>● Vivante GC7000Lite</li> <li>● 4 shaders</li> <li>● 267 million triangles/sec</li> <li>● 1.6 Gigapixel/sec</li> <li>● 32 GFLOPs 32-bit or 64 GFLOPs 16-bit</li> <li>● Supports OpenGL ES 1.1, 2.0, 3.0, 3.1, Open CL 1.2, and Vulkan</li> </ul>
Video Processing Unit (VPU)	<ul style="list-style-type: none"> <li>● 4Kp60 HEVC/H.265 main, and main 10 decoder</li> <li>● 4Kp60 VP9 and 4Kp30 AVC/H.264 decoder (requires full system resources)</li> <li>● 1080p60 MPEG-2, MPEG-4p2, VC-1, VP8, RV9, AVS, MJPEG, H.263 decoder</li> </ul>
I/O connectivity	<ul style="list-style-type: none"> <li>● 2x USB 3.0/2.0 controllers with integrated PHY interfaces</li> <li>● 1x Ultra Secure Digital Host Controller (uSDHC) interfaces</li> <li>● 1x Gigabit Ethernet controller with support for IEEE, Ethernet AVB, and IEEE 1588</li> <li>● 2x UART modules</li> <li>● 2x I2C modules</li> <li>● 2x SPI modules</li> <li>● 16x GPIO lines with interrupt capability</li> <li>● 4x PWM lines</li> <li>● Input/output multiplexing controller (IOMUXC) to provide centralized pad control</li> </ul> <p>Note: The list above is the number of signals available to the baseboard (after considering SoC signals used by the SoM).</p>
On-chip memory	<ul style="list-style-type: none"> <li>● Boot ROM (128 KB)</li> <li>● On-chip RAM (128 KB + 32 KB)</li> </ul>

<p>Display</p>	<p>HDMI Display Interface:</p> <ul style="list-style-type: none"> <li>• HDMI 2.0a supporting one display up to 1080p</li> <li>• Upscale and downscale between 4K and HD video (requires full system resources)</li> <li>• 20+ Audio interfaces 32-bit @ 384 kHz fs, with Time Division Multiplexing (TDM) support</li> <li>• SPDIF input and output</li> <li>• Audio Return Channel (ARC) on HDMI</li> </ul> <p>MIPI-DSI Display Interface:</p> <ul style="list-style-type: none"> <li>• MIPI-DSI 4 channels supporting one display, resolution up to 1920 x 1080 at 60 Hz</li> <li>• LCDIF display controller</li> <li>• Output can be LCDIF output or DC display controller output</li> </ul>
<p>Audio</p>	<ul style="list-style-type: none"> <li>• 1x SPDIF input and output</li> <li>• 2x synchronous audio interface (SAI) modules supporting I2S, AC97, TDM, and codec/DSP interfaces</li> <li>• 1x SAI for 8 Tx channels for HDMI output audio</li> <li>• 1x SPDIF input for HDMI ARC input</li> </ul>
<p>Camera</p>	<ul style="list-style-type: none"> <li>• 2x MIPI-CSI2 camera inputs (4-lane each)</li> </ul>
<p>Security</p>	<ul style="list-style-type: none"> <li>• Resource Domain Controller (RDC) supports four domains and up to eight regions</li> <li>• Arm TrustZone (TZ) architecture</li> <li>• On-chip RAM (OCRAM) secure region protection using OCRAM controller</li> <li>• High Assurance Boot (HAB)</li> <li>• Cryptographic acceleration and assurance (CAAM) module</li> <li>• Secure non-volatile storage (SNVS): Secure real-time clock (RTC)</li> <li>• Secure JTAG controller (SJC)</li> </ul>
<p>ML accelerator</p>	
<p>Edge TPU coprocessor</p>	<ul style="list-style-type: none"> <li>• ASIC designed by Google that provides high performance ML inferencing for TensorFlow Lite models</li> <li>• Uses PCIe Gen2 x1 and I2C/GPIO to interface with the iMX 8M SoC</li> <li>• 4 trillion operations per second (TOPS)</li> <li>• 2 TOPS per watt</li> </ul>
<p>Memory and storage</p>	
<p>Random access memory (SDRAM)</p>	<ul style="list-style-type: none"> <li>• 1, 2, or 4 GB LPDDR4 SDRAM (4-channel, 32-bit bus width)</li> <li>• 1600 MHz maximum DDR clock</li> <li>• Interfaces directly to the iMX 8M build-in DDR controller</li> </ul>
<p>Flash memory (eMMC)</p>	<ul style="list-style-type: none"> <li>• 8 GB eMMC (KLMBG4GEND-B031) for the 1 and 2 GB RAM models or 16 GB eMMC (EMMC16G-TB29-PZ90) for the 4 GB RAM model</li> <li>• 8-bits MMC mode</li> <li>• Conforms to JEDEC version 5.0 and 5.1</li> </ul>
<p>Expandable flash support</p>	<ul style="list-style-type: none"> <li>• Meets SD/SDIO 3.0 standard</li> <li>• Runs at 4-bits SDIO mode</li> <li>• Supports system boot from SD card</li> </ul>

Network & wireless	
Ethernet	<ul style="list-style-type: none"><li>• 10/100/1000 Mbps Ethernet/IEEE 802.3 networks</li><li>• Reduced gigabit media-independent interface (RGMI)</li></ul>
Wi-Fi	Murata LBEE5U91CQ module: <ul style="list-style-type: none"><li>• Wi-Fi 2x2 MIMO (802.11a/b/g/n/ac 2.4/5 GHz)</li><li>• Supports PCIe host interface for W-LAN</li></ul>
Bluetooth	Murata LBEE5U91CQ module: <ul style="list-style-type: none"><li>• Bluetooth 4.2 (supports Bluetooth low-energy)</li><li>• Supports UART interface</li></ul>
Security	
Cryptographic coprocessor	Microchip ATECC608A cryptographic coprocessor: <ul style="list-style-type: none"><li>• Asymmetric (public/private) key cryptographic signature solution based on Elliptic Curve Cryptography and ECDSA signature protocols</li></ul>
Hardware interface	
Baseboard connectors	3x 100-pin connectors (Hirose DF40C-100DP-0.4V)

## 1.1 Block diagrams

Figures 1 and 2 illustrate the core components on the SoM and SoC.

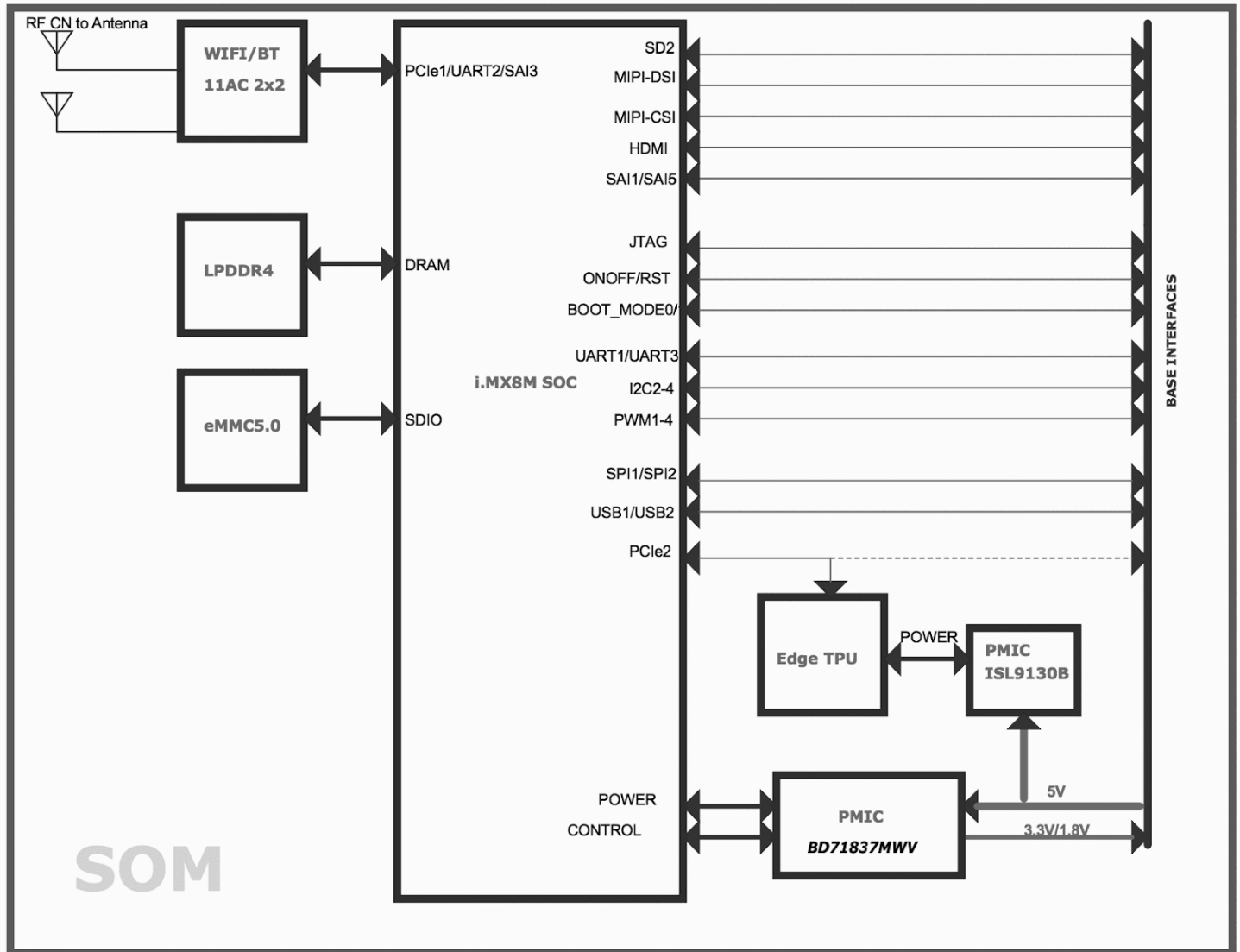
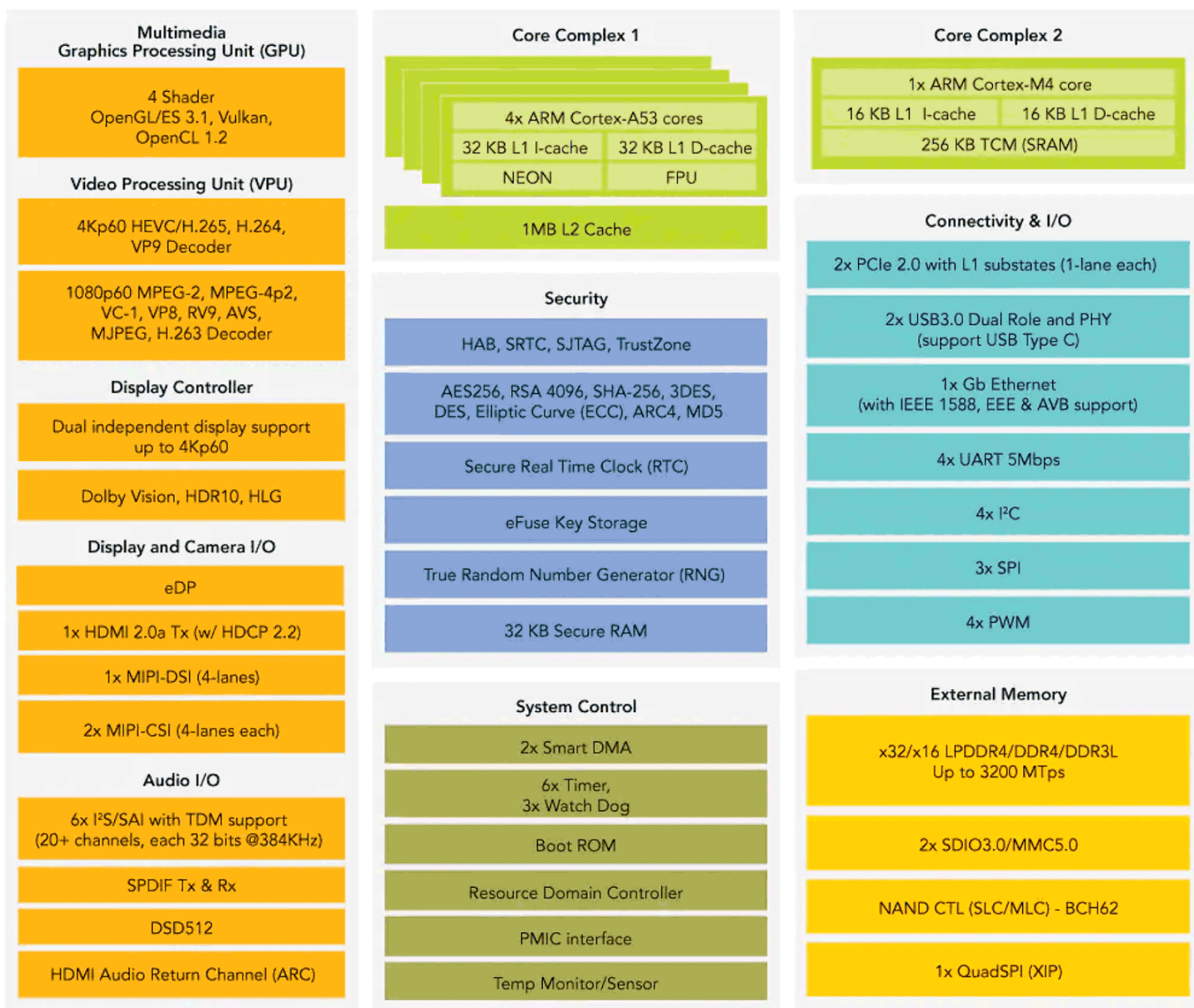


Figure 1. Block diagram of the SoM components



**Figure 2.** Block diagram of iMX 8M SoC components, provided by NXP (some I/O signals on the SoC are consumed on the SoM, so refer to table 1 for availability)

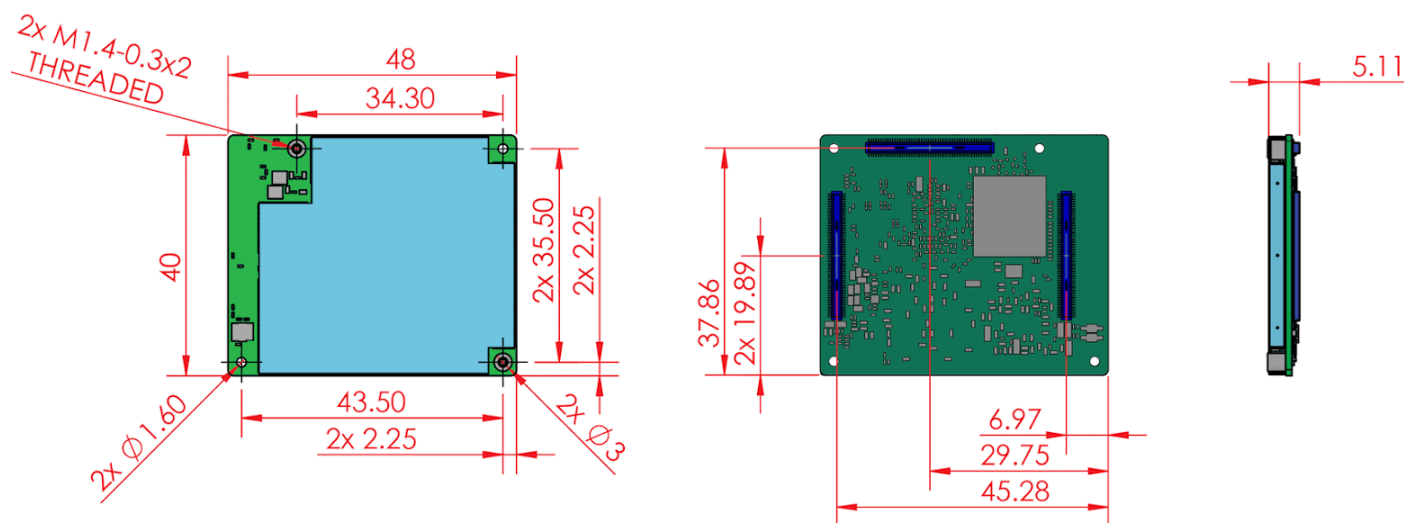


## 2 Mechanical dimensions

**Table 2.** SoM mechanical dimensions

Measurement	Value
Size	48 x 40 x 5.11 mm
Weight	13 g

Figure 3 illustrates all of the SoM's dimensions. For a top-down view of the baseboard connector locations and component height restrictions, see the [Baseboard developer guide](#).



**Figure 3.** SoM dimensions (in millimeters)

## 3 System power

The SoM requires 5 V as power input (at VSYS\_5V). The SoM then generates the local voltage rails for all SoM components through on-board PMICs.

**Table 3.** SoM power requirements

Power input	Voltage
Main power supply (VSYS_5V)	5 V $\pm$ 5%

**Caution:** Do not connect the 1.8/3.3 V power output pins to any high current devices or you might brownout the system. These power lines are shared with internal SoM circuits, so there is no safe limit for a high current device, but you can safely use them for low current tasks such as for a level shifter or pull-up/down.

**Caution:** Do not connect any of the 3.3 V I/O pins to a device that draws more than  $\sim$ 82 mA of power or you will brownout the system.

### 3.1 Power signals

Even though there are multiple power signals defined in the board-to-board connectors, only the VSYS\_5V and ground connections are required. All others are optional.

**Note:** Make sure to route all the VSYS\_5V and GND pins, and add decoupling (bypass) capacitors between VSYS\_5V and GND near the mating connector pins.

**Table 4.** Power and reset pin signals

Name	Type	Connector	Pins	Voltage	Description
VSYS_5V	Power	J1312	93, 94, 95, 96, 97, 98, 99, 100	5 V	Main 5 V power input to SoM. Must be connected.
GND	Power	J1312	9, 10, 65, 66, 71, 72, 77, 78, 83, 84		Common ground. Must be connected.
GND	Power	J1311	1, 2, 7, 8, 13, 14, 19, 20, 25, 26, 31, 32, 37, 38, 43, 44, 49, 50, 55, 56, 61, 62, 67, 68, 73, 74, 79, 80, 86, 89, 90, 94, 99, 100		Common ground. Must be connected.
GND	Power	J1310	1, 2, 7, 25, 39, 40, 42, 44, 45, 46, 50, 51, 56, 57, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 80		Common ground. Must be connected.
DCDC_3V3	Power	J1310	84, 86, 88, 90	3.3 V	3.3 V output from SoM. Can be left floating if not used. Not for high-current usage; can be used to pull-up GPIO.
VDD_3V3	Power	J1310	94, 96, 98 100	3.3 V	3.3 V output from SoM. Can be left floating if not used. Not for high-current usage; can be used to pull-up GPIO.
VDDA_1V8	Power	J1310	91, 93, 95, 97, 99	1.8 V	1.8 V output from SoM. Can be left floating if not used. Not for high-current usage; can be used to pull-up GPIO.
POR_B	Output	J1310	79	3.3 V	"Power_On_Reset" signal from iMX 8M PMIC to reset the SoC (active-low open-drain output). Available to enable sequencing.
PWRON_B	Input	J1312	86	3.3 V	"Power_On" (active-low input). Triggers a reset of the iMX 8M PMIC power cycle. Pull-up in SoM.
SYS_nRST	Input	J1312	63	3.3 V	System reset (active-low input). Recommended for reset button on baseboard. Pull-up in SoM.

### 3.2 Power consumption

**Caution:** You must provide a cooling solution to ensure the SoM surface maintains an operational temperature as specified in the [Environmental reliability](#) section. Unlike the Coral Dev Board, the standalone SoM does not include a cooling solution (the SoM components are covered only with an EMI shield).

The power consumption numbers listed in this section are based on a high performance test that includes the following:

- GPU: 3D rendering
- CPU: 2 of 4 cores 100% loaded
- Active Wi-Fi download
- 7" HDMI display on
- DDR: 800 MHz
- Edge TPU running MobileNet V1 at 500 MHz
- Fan intermittently on

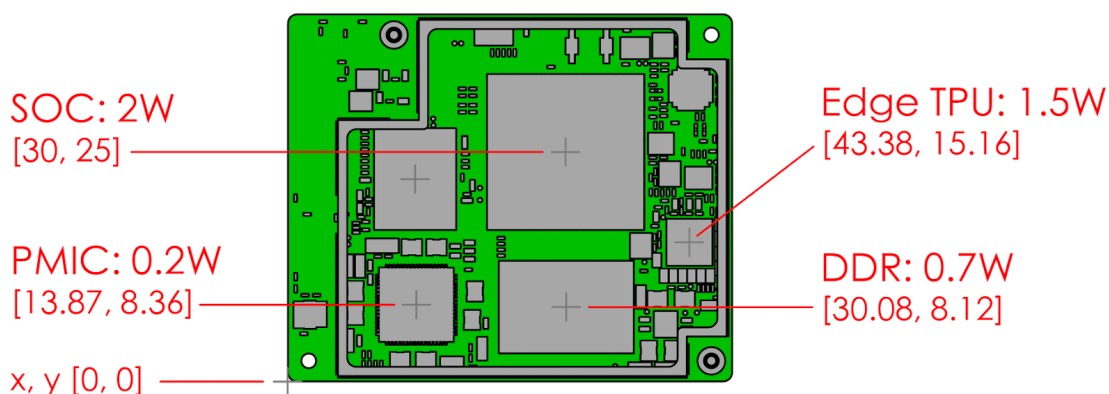
Table 5 lists the power draw measurements during different operational tests both for both the SoM, and for the Dev Board baseboard and SoM working together.

**Table 5.** SoM power draw measurements

Operational test	SoM power	System power (SoM + Dev Board baseboard)*
Idle	2.6 W	4.0 W
Idle with HDMI display on	3.0 W	4.3 W
High performance	6.2 W	8.5 W

\* Tested with [Coral Dev Board](#)—performance on your custom baseboard may vary.

During the high performance test, the top power-consuming components (top heat sources) are as indicated in figure 4.



**Figure 4.** Power draw and ordinate locations (in millimeters) of top power components during high performance test

### 3.3 Edge TPU power characteristics

The current drawn by the Edge TPU is highly variable and depends on the model being executed. Although the average current drawn by the Edge TPU may be less than 500 mA, it can repeatedly and rapidly spike up to 3 A, depending on the model you're running. These spikes also occur suddenly: even a simple model can generate current transients in excess of 1 A/ $\mu$ s, which can last several tens of microseconds.

The Edge TPU dissipates power roughly proportional to its computational load. The resulting heat in the Edge TPU die must be safely and reliably conducted away to avoid excessive die temperatures that can affect performance and reliability.

The Edge TPU's junction temperature  $T_j$  must stay below the maximum operating specification:

- Maximum Edge TPU junction temperature  $T_j$ : 115 °C

**Warning:** Exceeding the maximum temperature can result in permanent damage to the Edge TPU and surrounding components, and can possibly cause fire and serious damage, injury, or death.

For information about thermal management strategies for the Edge TPU, see [section 7.6](#).

## 4 Boot mode

Use the BOOT\_MODE[1:0] pins to configure the SoM boot mode setting as indicated in the following tables.

**Table 6.** Boot mode pin signals

Name	Type	Connector	Pins	Voltage	Description
BOOT_MODE0	Input	J1312	64	3.3 V	SoC BOOT_MODE0 signal (can be set by switch or pin-strap on baseboard)
BOOT_MODE1	Input	J1312	62	3.3 V	SoC BOOT_MODE1 signal (can be set by switch or pin-strap on baseboard)

**Table 7.** Boot mode pin settings

BOOT_MODE[1:0] bits	Boot type
00	Boot from fuses (default behavior)
01	Serial downloader
10	Internal boot
11	Reserved

The boot configuration is specified by the iMX 8M SoC, so for more details, refer to the [iMX 8M SoC documentation](#).

**Note:** If BOOT\_MODE[1:0] is "10" (internal boot), then GPIO pins SAI1\_RX[7:0] and SAI1\_TX[7:0] are used to enable boot configuration overrides (such as whether to boot from eMMC or SD card) by latching them to the BOOT\_CFG[15:0] bits in the SoC. For further details, such as information about GPIO boot overrides and boot fuses, see the [iMX 8M SoC documentation](#).

## 5 Peripheral interfaces

The following interfaces are available from the SoM, through the three 100-pin board-to-board connectors.

This section is organized based on the default pin functions when running the Mendel operating system. For information about alternative pin functions you may enable with your own device tree overlay, see the [iMX 8M SoC documentation](#).

**Note:** All I/O pins have a 90 k pull-down resistor in the SoC that are used by default during bootup, which you can reconfigure with a device tree overlay after bootup. However, some pins (such as I2C, some SAI, and some SD2 pins) also have pull-up resistors inside the SoM, as noted in the following tables, which you cannot reconfigure with a device tree overlay.

**Caution:** Do not connect any of the 3.3 V I/O pins to a device that draws more than ~82 mA of power or you will brownout the system.

## 5.1 MIPI camera (CSI)

There are two channels for MIPI camera serial interface (CSI-2), each with four lanes and a maximum bit rate of 1.5 Gbps.

**Table 8.** CSI channel 1 pins

Name	Type	Connector	Pins	Voltage	Description
MIPI_CSI1_CLK_P/N	Input	J1311	18/16	0.2-1.2 V	MIPI CSI1 clock (positive/negative)
MIPI_CSI1_D0_P/N	Input	J1311	12/10	0.2-1.2 V	MIPI CSI1 data (positive/negative)
MIPI_CSI1_D1_P/N	Input	J1311	23/21	0.2-1.2 V	MIPI CSI1 data (positive/negative)
MIPI_CSI1_D2_P/N	Input	J1311	6/4	0.2-1.2 V	MIPI CSI1 data (positive/negative)
MIPI_CSI1_D3_P/N	Input	J1311	29/27	0.2-1.2 V	MIPI CSI1 data (positive/negative)

**Table 9.** CSI channel 2 pins

Name	Type	Connector	Pins	Voltage	Description
MIPI_CSI2_CLK_P/N	Input	J1311	36/34	0.2-1.2 V	MIPI CSI2 clock (positive/negative)
MIPI_CSI2_D0_P/N	Input	J1311	35/33	0.2-1.2 V	MIPI CSI2 data (positive/negative)
MIPI_CSI2_D1_P/N	Input	J1311	30/28	0.2-1.2 V	MIPI CSI2 data (positive/negative)
MIPI_CSI2_D2_P/N	Input	J1311	24/22	0.2-1.2 V	MIPI CSI2 data (positive/negative)
MIPI_CSI2_D3_P/N	Input	J1311	41/39	0.2-1.2 V	MIPI CSI2 data (positive/negative)

## 5.2 MIPI display (DSI)

The four-lane MIPI display serial interface (DSI) offers the following features:

- Resolution up to 1920 x 1080 at 60 Hz
- LCDIF display controller
- Maximum bit rate of 1.5 Gbps

**Table 10.** DSI pins

Name	Type	Connector	Pins	Voltage	Description
MIPI_DSI1_CLK_P/N	Output	J1311	59/57	0.2-1.2 V	MIPI DSI clock (positive/negative)
MIPI_DSI1_D0_P/N	Output	J1311	47/45	0.2-1.2 V	MIPI DSI data (positive/negative)
MIPI_DSI1_D1_P/N	Output	J1311	54/52	0.2-1.2 V	MIPI DSI data (positive/negative)
MIPI_DSI1_D2_P/N	Output	J1311	42/40	0.2-1.2 V	MIPI DSI data (positive/negative)
MIPI_DSI1_D3_P/N	Output	J1311	48/46	0.2-1.2 V	MIPI DSI data (positive/negative)

### 5.3 HDMI

The High-Definition Multimedia Interface (HDMI) connection provides the following features:

- HDMI 2.0a supporting one display up to 1080p
- Upscale and downscale between 4K and HD video (requires full system resources)
- 20+ Audio interfaces 32-bit @ 384 kHz fs, with Time Division Multiplexing (TDM) support
- SPDIF input and output
- Audio Return Channel (ARC) on HDMI

**Table 11.** HDMI pins

Name	Type	Connector	Pins	Voltage	Description
HDMI_REFCLKP/N	Output	J1310	58/60	3.3 V	HDMI reference clock (27 MHz) (positive/negative). <b>Required for bootup</b> , even if you don't use HDMI. For detail, see the <a href="#">reference design schematic</a> .
HDMI_CLKP/N	Output	J1312	68/70	3.3 V	HDMI clock (positive/negative)
HDMI_TX0_P/N	Output	J1312	75/73	3.3 V	HDMI transmit (positive/negative)
HDMI_TX1_P/N	Output	J1312	79/81	3.3 V	HDMI transmit (positive/negative)
HDMI_TX2_P/N	Output	J1312	76/74	3.3 V	HDMI transmit (positive/negative)
HDMI_AUX_P/N	Output	J1312	82/80	3.3 V	HDMI AUX (positive/negative)
HDMI_HPD	Output	J1312	89	3.3 V	HDMI Hot Plug Detect
HDMI_DDC_SDA	Output	J1312	85	3.3 V	HDMI Display Data Channel data
HDMI_DDC_SCL	Output	J1312	87	3.3 V	HDMI Display Data Channel clock
HDMI_CEC	Output	J1312	91	3.3 V	HDMI Consumer Electronic Control

### 5.4 Ethernet

The Ethernet Media Access Controller (MAC) supports 10/100/1000 Mbps Ethernet/IEEE 802.3 networks with reduced gigabit media-independent interface (RGMI). Requires an Ethernet PHY on the baseboard.

**Table 12.** Ethernet pins

Name	Type	Connector	Pins	Voltage	Description
ENET_RD0	Input	J1310	33	1.8 V	RGMI receive from PHY
ENET_RD1	Input	J1310	35	1.8 V	RGMI receive from PHY
ENET_RD2	Input	J1310	31	1.8 V	RGMI receive from PHY
ENET_RD3	Input	J1310	37	1.8 V	RGMI receive from PHY
ENET_RX_CTL	Input	J1310	29	1.8 V	RGMI receive from PHY
ENET_RXC	Input	J1310	27	1.8 V	RGMI receive from PHY

ENET_TD0	Output	J1310	19	1.8 V	RGMIIT transmit to PHY
ENET_TD1	Output	J1310	21	1.8 V	RGMIIT transmit to PHY
ENET_TD2	Output	J1310	17	1.8 V	RGMIIT transmit to PHY
ENET_TD3	Output	J1310	15	1.8 V	RGMIIT transmit to PHY
ENET_TX_CTL	Output	J1310	13	1.8 V	RGMIIT transmit to PHY
ENET_TXC	Output	J1310	23	1.8 V	RGMIIT transmit to PHY
ENET_MDC	Output	J1310	11	1.8 V	RGMIIT clock for PHY
ENET_MDIO	Output	J1310	9	1.8 V	RGMIIT MDIO data for PHY
ENET_nRST (GPIO1_IO09)	Output	J1312	43	3.3 V	PHY reset
ENET_nINT (GPIO1_IO11)	Input	J1312	39	3.3 V	PHY interrupt
ENET_WoL (GPIO1_IO10)	Input	J1312	41	3.3 V	PHY Wake-on-Lan
CLKO_25M (GPIO1_IO15)	Output	J1310	54	3.3 V	Optional 25 Mhz clock to PHY

## 5.5 PCIe

The SoC includes PCIe1 and PCIe2 lines that are routed to the baseboard connectors, but you should not need to connect these and **you should not remap these with your own device tree** because both are used on the SoM for Wi-Fi (PCIe1) and the Edge TPU (PCIe2).

## 5.6 USB

There are two USB controllers and corresponding PHYs on the SoM. Each USB instance contains USB 3.0 (USB 3.1 Gen 1) core, which can operate in both USB 3.0 and 2.0 mode.

**Table 13.** USB channel 1 pins

Name	Type	Connector	Pins	Voltage	Description
USB1_DP/N	I/O	J1311	51/53	3.3 V	USB 2.0 (positive/negative)
USB1_TXP/N	Output	J1311	58/60	1.8 V	USB 3.0 transmit (positive/negative)
USB1_RXP/N	Input	J1311	64/66	1.8 V	USB 3.0 receive (positive/negative)
USB1_VBUS	Input	J1311	82/84	5 V	VBUS detect (same at both pins)
USB1_ID	Input	J1311	76	3.3 V	USB ID



**Table 14.** USB channel 2 pins

Name	Type	Connector	Pins	Voltage	Description
USB2_DP/N	I/O	J1311	63/65	3.3 V	USB 2.0 (positive/negative)
USB2_TXP/N	Output	J1311	69/71	1.8 V	USB 3.0 transmit (positive/negative)
USB2_RXP/N	Input	J1311	70/72	1.8 V	USB 3.0 receive (positive/negative)
USB2_VBUS	Input	J1311	75/77	5 V	VBUS detect (same at both pins)
USB2_ID	Input	J1311	88	3.3 V	USB ID

## 5.7 Digital audio (SAI)

The SAI module provides a synchronous audio interface (SAI) that supports full duplex serial interfaces with frame synchronization, such as I2S, AC97, TDM, and codec/DSP interfaces.

**Note:** If booting the SoM in eFUSE mode (default behavior), all SAI pins are available during boot. However, when using the other boot modes, pins SAI1\_RX[7:0] and SAI1\_TX[7:0] are used to enable boot configuration overrides by latching them to the BOOT\_CFG[15:0] bits in the SoC—that is, only until boot completes. The SoM uses internal pin strap (pull-up and pull-down) resistors to select the different boot configuration, so you should be careful if you add any pull-up/down resistors for these pins on your baseboard. For details, see the [iMX 8M SoC documentation](#).

**Table 15.** SAI 1 signals

Name	Type	Connector	Pins	Voltage	Description
SAI1_MCLK	I/O	J1312	26	3.3 V	Audio master clock
SAI1_RXC	Input	J1312	17	3.3 V	Receive bit clock
SAI1_RXFS	Input	J1312	19	3.3 V	Receive frame sync
SAI1_RXD0	Input	J1312	33	3.3 V	Receive channel. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD1	Input	J1312	35	3.3 V	Receive channel. Pull-up in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD2	Input	J1312	27	3.3 V	Receive channel. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD3	Input	J1312	31	3.3 V	Receive channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD4	Input	J1312	29	3.3 V	Receive channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.

SAI1_RXD5	Input	J1312	21	3.3 V	Receive channel. Pull-up in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD6	Input	J1312	25	3.3 V	Receive channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_RXD7	Input	J1312	23	3.3 V	Receive channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXC	Output	J1312	40	3.3 V	Transmit bit clock.
SAI1_TXFS	Output	J1312	46	3.3 V	Transmit frame sync.
SAI1_TXD0	Output	J1312	44	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD1	Output	J1312	42	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD2	Output	J1312	30	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD3	Output	J1312	36	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD4	Output	J1312	38	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD5	Output	J1312	34	3.3 V	Transmit channel. Pull-up in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD6	Output	J1312	28	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.
SAI1_TXD7	Output	J1312	32	3.3 V	Transmit channel. Pull-down in SoM: 10k Ohm. Reserved during boot, except in eFUSE mode. See note above.

**Table 16.** SAI 2 signals

Name	Type	Connector	Pins	Voltage	Description
SAI2_TXD	Output	J1312	14	3.3 V	Transmit channel
SAI2_RXD	Input	J1312	20	3.3 V	Receive channel
SAI2_TXC	Output	J1312	18	3.3 V	Transmit bit clock
SAI2_TXFS	Output	J1312	16	3.3 V	Transmit frame sync
SAI2_MCLK	I/O	J1312	12	3.3 V	Audio master clock
SAI2_RXFS	Input	J1312	24	3.3 V	Receive frame sync
SAI2_RXC	Input	J1312	23	3.3 V	Receive bit clock

**Note:** The SoC includes SAI3 lines, but most of these are used by the SoM for Wi-Fi, so you should not remap these with your device tree. Only SAI3\_RXC and SAI3\_RXFS are provided by the SoM baseboard connectors and available for use as [GPIO](#).

The SoC also includes SAI5 lines that are all provided by the SoM connectors, but three of them are pin-strapped inside the SoM (SAI5\_RXD1, SAI5\_RXD3, and SAI5\_RXFS), and their level is latched by the U-Boot bootloader to determine the SoM SKU (LPDDR4 memory size). **We recommend that you do not use these three pins for any other purpose and do not connect them.** The remaining SAI5 pins (SAI5\_MCLK, SAI5\_RXC, SAI5\_RXD0, and SAI5\_RXD2) are available for use as GPIO.

## 5.8 Sony/Philips audio (SPDIF)

Sony/Philips Digital Interface (SPDIF) is a standard audio file transfer format that supports Transmitter and Receiver functionality. Refer to [NXP iMX 8M documentation](#) for additional details.

**Table 17.** SPDIF pin signals

Name	Type	Connector	Pins	Voltage	Description
SPDIF_EXT_CLK	Output	J1311	92	3.3 V	External clock signal
SPDIF_TX	Output	J1311	96	3.3 V	Transmit data channel
SPDIF_RX	Input	J1311	98	3.3 V	Receive data channel

## 5.9 Micro-SD card

An Ultra Secure Digital Host Controller (uSDHC) module provides the interface between the host and SD/SDIO/MMC cards, with the following features:

- SD/SDIO standard, up to version 3.0
- MMC standard, up to version 5.0
- 3.3 V operation only
- 1- and 4-bit SD/SDIO/MMC modes

**Table 18.** SD/MMC pin signals

Name	Type	Connector	Pins	Voltage	Description
SD2_CLK	Output	J1310	48	3.3 V	Serial clock
SD2_CMD	Output	J1310	26	3.3 V	Command line Pull-up in SoM: 10k Ohm
SD2_nCD (SD2_CD_B)	Output	J1310	24	3.3 V	Card detect
SD2_DAT0	I/O	J1310	28	3.3 V	Data bit 0 Pull-up in SoM: 10k Ohm
SD2_DAT1	I/O	J1310	32	3.3 V	Data bit 1
SD2_DAT2	I/O	J1310	34	3.3 V	Data bit 2
SD2_DAT3	I/O	J1310	38	3.3 V	Data bit 3
SD2_nRST (SD2_RESET_B)	Output	J1310	36	3.3 V	Card reset
SDIO_WAKE (SD2_WP)	Output	J1310	30	3.3 V	Write protect or GPIO

## 5.10 JTAG debugging

5-pin JTAG debugging with a Secure JTAG Controller (SJC) for secure debugging.

**Table 19.** JTAG pin signals

Name	Type	Connector	Pins	Voltage	Description
JTAG_TMS	Output	J1312	59	3.3 V	Test mode select
JTAG_TDI	Input	J1312	61	3.3 V	Test data in
JTAG_TDO	Output	J1312	57	3.3 V	Test data out
JTAG_TCK	Output	J1312	53	3.3 V	Test clock
JTAG_nTRST	Input	J1312	55	3.3 V	Test reset

## 5.11 I2C

Two I2C bus interfaces are available.

**Table 20.** I2C pin signals

Name	Type	Connector	Pins	Voltage	Description
I2C2_SCL	Input	J1311	87	3.3 V	Serial clock Pull-up in SoM: 4.7k Ohm
I2C2_SDA	Output	J1311	85	3.3 V	Serial data Pull-up in SoM: 4.7k Ohm
I2C3_SCL	Input	J1311	83	3.3 V	Serial clock Pull-up in SoM: 4.7k Ohm
I2C3_SDA	Output	J1311	81	3.3 V	Serial data Pull-up in SoM: 4.7k Ohm

**Note:** The SoC also includes I2C1 and I2C4 lines, but these are used by the SoM for power management and wireless controls, so you should not remap these with your own device tree.

## 5.12 UART

Two UART v2 modules are available with the following features:

- 7- or 8-bit data words, 1 or 2 stop bits, programmable parity (even, odd, or none).
- Programmable baud rates up to 4 Mbps.
- 32-byte FIFO on Tx and 32 half-word FIFO on Rx supporting auto-baud.

**Note:** By default, the Mendel operating system configures UART1 for use with the the serial console.

The SoC also includes UART2 and UART4 lines, but these are used by the SoM for Bluetooth, so you should not remap these with your own device tree.

**Table 21.** UART pin signals

Name	Type	Connector	Pins	Voltage	Description
UART1_TXD	Output	J1311	93	3.3 V	Transmit channel
UART1_RXD	Input	J1311	95	3.3 V	Receive channel
UART3_TXD	Output	J1311	91	3.3 V	Transmit channel
UART3_RXD	Input	J1311	97	3.3 V	Receive channel

### 5.13 SPI

Two full-duplex eSPI interfaces are available, with data rates up to 52 Mbit/s and two chip select lines.

**Table 22.** SPI channel 1 pin signals

Name	Type	Connector	Pins	Voltage	Description
ECSPI1_MISO	Input	J1312	5	3.3 V	Master input
ECSPI1_MOSI	Output	J1312	7	3.3 V	Master output
ECSPI1_SCLK	Output	J1312	4	3.3 V	Serial clock
ECSPI1_SS0	Output	J1312	8	3.3 V	Chip select
ECSPI1_SS1	Output	J1310	6	3.3 V	Chip select

**Table 23.** SPI channel 2 pin signals

Name	Type	Connector	Pins	Voltage	Description
ECSPI2_MISO	Input	J1312	3	3.3 V	Master input
ECSPI2_MOSI	Output	J1312	6	3.3 V	Master output
ECSPI2_SCLK	Output	J1312	2	3.3 V	Serial clock
ECSPI2_SS0	Output	J1312	1	3.3 V	Chip select
ECSPI2_SS1	Output	J1310	4	3.3 V	Chip select

### 5.14 GPIO

The following pins are configured for general purpose input/output, by default. Additionally, you can reconfigure other pins (SAI, SPDIF, SDIO, I2C, UART, SPI, and PWM) to behave as GPIO, using a device tree overlay.

**Table 24.** GPIO pin signals

Name	Type	Connector	Pins	Voltage	Description
GPIO6	I/O	J1312	49	3.3 V	GPIO
GPIO7	I/O	J1312	45	3.3 V	GPIO
GPIO8	I/O	J1312	47	3.3 V	GPIO
GPIO12	I/O	J1312	51	3.3 V	GPIO
NAND_CLE	I/O	J1310	10	3.3 V	GPIO
NAND_DATA02	I/O	J1310	12	3.3 V	GPIO
NAND_ALE	I/O	J1310	16	3.3 V	GPIO
NAND_DATA07	I/O	J1310	18	3.3 V	GPIO

NAND_DATA06	I/O	J1310	20	3.3 V	GPIO
NAND_DATA03	I/O	J1310	22	3.3 V	GPIO
SAI3_RXC	I/O	J1312	13	3.3 V	GPIO
SAI3_RXFS	I/O	J1312	15	3.3 V	GPIO
SAI5_MCLK	I/O	J1312	50	3.3 V	GPIO
SAI5_RXC	I/O	J1312	56	3.3 V	GPIO
SAI5_RXD0	I/O	J1312	58	3.3 V	GPIO
SAI5_RXD2	I/O	J1312	54	3.3 V	GPIO
SAI5_RXD1	I/O	J1312	48	3.3 V	<b>Do not pin-strap.</b> Pin-strapped in SoM for latch from bootloader. We recommend you do not connect.
SAI5_RXD3	I/O	J1312	52	3.3 V	
SAI5_RXFS	I/O	J1312	60	3.3 V	

## 5.15 PWM

There are four PWM output pins available with 16-bit resolution and 4x16 data FIFO.

**Table 25.** PWM pin signals

Name	Type	Connector	Pins	Voltage	Description
PWM1 (GPIO1_IO01)	Output	J1312	88	3.3 V	PWM or GPIO
PWM2 (GPIO1_IO013)	Output	J1312	90	3.3 V	PWM or GPIO
PWM3 (GPIO1_IO014)	Output	J1312	92	3.3 V	PWM or GPIO
PWM4 (SAI3_MCLK)	Output	J1312	11	3.3 V	PWM or GPIO

## 6 Wi-Fi and Bluetooth

The SoM includes the [Murata LBEE5U91CQ module](#), which provides Wi-Fi (IEEE 802.11 a/b/g/n/ac WLAN, 2.4/5 GHz) and Bluetooth 4.2 (with Bluetooth Low Energy support), using wireless antennas integrated into the board.

## 7 Baseboard developer guide

This section provides details to help you integrate the Coral SoM into your own baseboard (carrier board) hardware.

### 7.1 Reference design

If you'd like to see a reference baseboard design that uses the System-on-Module, download the following schematic and layout files for the Coral Dev Board.

**Table 26.** Dev Board schematics, layout, and 3D files

File	Description
<a href="#">Coral-Dev-Board-baseboard-schematic.pdf</a>	Baseboard schematic in PDF
<a href="#">Coral-Dev-Board-baseboard-schematic-Altium.zip</a>	Baseboard schematic files in Altium format
<a href="#">Coral-Dev-Board-baseboard-layout-Allegro.brd</a>	Baseboard CAD layout in BRD format
<a href="#">Coral-Dev-Board.STEP</a>	Dev Board (baseboard and SoM) 3D CAD file in STEP format
<a href="#">Coral-SoM.STEP</a>	SoM-only 3D CAD file in STEP format

### 7.2 Baseboard connectors

The SoM connects to the host baseboard with three 100-pin connectors.

**Table 27.** SoM and baseboard connectors

SoM	Baseboard
3x 100-position plug <a href="#">Hirose Electric DF40C-100DP-0.4V(51)</a>	3x 100-position receptacle <a href="#">Hirose Electric DF40HC(3.0)-100DS-0.4V(51)</a>

The location of each connector plug on the SoM is illustrated in [figure 3](#), and the corresponding position for each receptacle on your baseboard is illustrated in [figure 5](#).

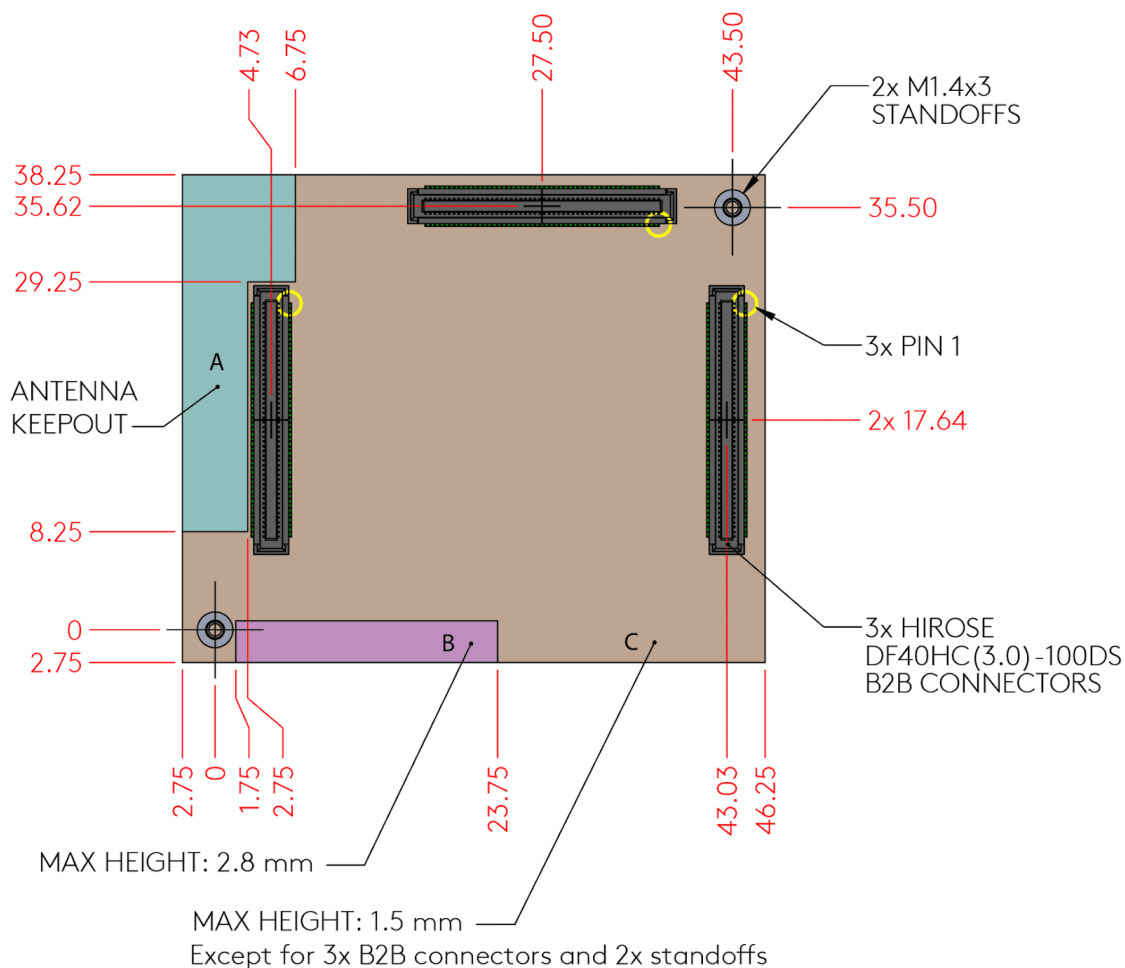
### 7.3 Connectors, keepouts, and component max heights

Figure 5 illustrates the area of your baseboard where the SoM connects. The measurements are relative to the standoff in the bottom-left corner, indicating the position for the three board-to-board (B2B) connectors (Hirose DF40C-100DP-0.4V), two standoffs, and the following component regions:

- A. Antenna keepout: Place no components and no copper in this region. This area of your baseboard is directly below the SoM's Wi-Fi and Bluetooth antennas, so it must be kept clear of any metals to ensure strong radio signals.
- B. Max height of baseboard components in this region is 2.8mm.
- C. Max height of baseboard components in this region is 1.5mm.

Additionally, figure 5 indicates the location of pin 1 on your baseboard connectors. To see all the pin assignments, refer to the [pinout schematic](#).





**Figure 5.** Top view of baseboard connectors and component restrictions (measured in millimeters)

## 7.4 Trace impedance recommendations

The following table lists the recommended impedance for high-speed signals on the baseboard.

**Table 28.** Trace impedance recommendation

Signal group	Impedance	PCB manufacture tolerance ( $\pm$ )
All single-ended signal, unless specified	50 Ohm single-ended	10%
PCIe TX/RX data pair	85 Ohm differential	10%
USB differential signals	90 Ohm differential	10%
Differential signals: including Ethernet, PCIe clocks, HDMI, MIPI (CSI and DSI)	100 Ohm differential	10%

## 7.5 MIPI trace length compensation

MIPI signals for the CSI/DSI interfaces are high-speed signals that require the total etched trace lengths for each line within a group (the paired clock lanes and four data lanes) be equal to each other. Due to space constraints on the SoM, the MIPI signal traces lengths currently are not equal (as indicated in the following tables). You must incorporate the length difference on your baseboard traces such that the trace lengths for each MIPI group match each other.

**Table 29.** CSI channel 1 signal trace length on SoM

Name	Etch length (mils)	Manhattan length (mils)
MIPI_CSI1_CLKN	306.1	287.89
MIPI_CSI1_CLKP	309.4	297.73
MIPI_CSI1_D0N	310.97	309.53
MIPI_CSI1_D0P	315.24	319.38
MIPI_CSI1_D1N	242.48	209.15
MIPI_CSI1_D1P	241.23	250.5
MIPI_CSI1_D2N	354.22	356.78
MIPI_CSI1_D2P	351.84	392.21
MIPI_CSI1_D3N	246.25	230.81
MIPI_CSI1_D3P	250.2	272.16

**Table 30.** CSI channel 2 signal trace length on SoM

Name	Etch length (mils)	Manhattan length (mils)
MIPI_CSI2_CLKN	299.51	282.39
MIPI_CSI2_CLKP	301.92	323.73
MIPI_CSI2_D0N	258.48	252.46
MIPI_CSI2_D0P	258.58	293.81
MIPI_CSI2_D1N	289.71	260.74
MIPI_CSI2_D1P	292.95	302.08
MIPI_CSI2_D2N	293.48	266.24
MIPI_CSI2_D2P	298.18	280.42
MIPI_CSI2_D3N	265.86	274.12
MIPI_CSI2_D3P	268.14	315.46

**Table 31.** DSI signal trace length on SoM

Name	Etch length (mils)	Manhattan length (mils)
MIPI_DSI_CLKN	296.45	339.08
MIPI_DSI_CLKP	297.41	380.43
MIPI_DSI_D0N	212.5	219
MIPI_DSI_D0P	211.9	260.34
MIPI_DSI_D1N	322.16	347.35
MIPI_DSI_D1P	326.95	388.69
MIPI_DSI_D2N	305.05	304.05
MIPI_DSI_D2P	309.08	345.38
MIPI_DSI_D3N	297.15	274.52
MIPI_DSI_D3P	298.16	315.86

## 7.6 Thermal management

**Caution:** You must provide a cooling solution to ensure the SoM surface maintains an operational temperature as specified in [section 9](#).

You can use the SoM's threaded standoffs (indicated in [figure 3](#)) to mount a passive or active cooling solution.

The Edge TPU includes an internal temperature sensor and the Coral PCIe driver provides a programmable interface to help you make power management decisions. Using the PCIe device interface, you can read the Edge TPU temperature and make your own thermal-management decisions such as when to activate a fan. Additionally, you can configure some Edge TPU parameters to specify the temperature at which the Edge TPU should shut down, and specify trip-points for dynamic frequency scaling (DFS). For more information, read the app note, [Manage the PCIe module temperature](#).

## 7.7 Other recommendations

- Make sure to route all the VSYS\_5V and GND pins, and add decoupling (bypass) capacitors between VSYS\_5V and GND near the mating connector pins.
- When placing a pull-up or pull-down resistor on some of the SoM signals, such as I/O pins (especially SAI1\_TXD[7:0] and SAI1\_RXD[7:0]), review the signal description for each [peripheral interface](#), because some of them already have pull-up/down resistor in the SoM for initialization purposes.
- Make sure to connect the HDMI reference clock (HDMI\_REFCLK) to a 27 MHz source. Even if you do not use HDMI, this is required during bootup for a DRM-related software check. For detail, see the [reference design schematic](#).

## 8 Pinout schematic

**Caution:** The signal directions in figure 6 are not all accurate. Instead refer to the "type" of each pin in the tables from the [Peripheral interfaces](#) section.

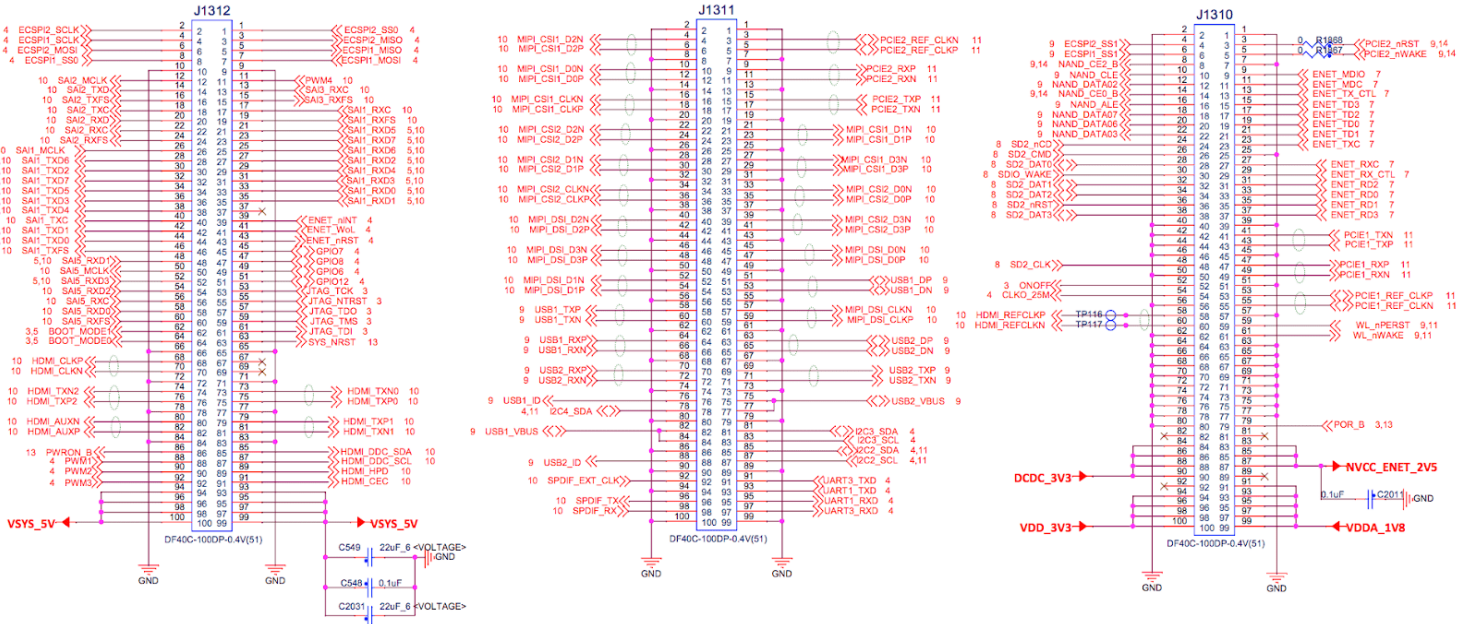


Figure 6. SoM connector schematic (see large image)

## 9 Environmental reliability

Table 32. SoM environmental and mechanical limits

Measurement	Limits
Shock	50 G / 20 ms
Vibration	20 G / 0-600 Hz
MTTF	>200,000 hours
Operating temperature	-20 to +85 °C <sup>1</sup>
Storage temperature	-40 to +85 °C
Relative humidity	10% to 90% (operation) 5% to 95% (storage)

<sup>1</sup> The operating temperature range is for the SoM's ambient environment, and assumes that the Edge TPU junction temperature (T<sub>j</sub>) does not exceed its absolute maximum rating, as specified in [section 3.3](#). It's your responsibility to provide thermal solution that maintains the maximum junction temperature for all SoM components.

## 10 Document revisions

**Table 33.** History of changes to this document

Version	Changes
1.11 (January 2021)	Changed the operating temperature to reflect the true SoM limits (previous limit of 0 to 50 °C was incorrectly based on performance with the heatsink and fan on the Dev Board). Added section 3.3 and section 7.6 to elaborate on the Edge TPU's power/thermal behaviors. Added detail about 16 GB eMMC included with the 4 GB RAM model, and eMMC PNs. Removed misleading "External memory" section about the SoC from table 1.
1.10 (October 2020)	Fixed MIPI_DSI1_D2_N pin position in table 10.
1.9 (August 2020)	Added detail about HDMI_REFCLK requirement. Removed list of certifications (instead <a href="#">see website</a> ). Updated document styles.
1.8 (July 2020)	Added part numbers for all SKU variants.
1.7 (June 2020)	Corrected J1311 list of grounds: changed pin 33 to 32.
1.6 (April 2020)	Added detail about SAI5 pins that are pin-strapped in the SoM.
1.5 (February 2020)	Clarified and enhanced documentation of SAI, power and reset pin signals. Added information about PWRON_B pin.
1.4 (January 2020)	Fixed USB2_RXP/N pin position.
1.3 (December 2019)	Fixed HDMI_TX1 pin positions.
1.2 (August 2019)	Added PDF download of this datasheet and the Dev Board baseboard schematic.
1.1 (July 2019)	Removed wireless antenna connector details.
1.0 (June 2019)	Initial release.

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