

Low Power, 10Mbps, RS-485/RS-422 Transceiver

Features

- Low Quiescent Current: Icc=330µA, Typ
- Low Shutdown Current: Icc<1µA, Max
- -7V to 12V Bus Common Mode Input Range
- ±7V Ground Difference Between Devices on the Bus
- Fail-safe Functions
- Bus Glitch-Free Power-Up and Power-Down
- Over Temperature Protection
- Driver Outputs High Impedance When Disabled or Power Off
- Allow Up to 256 Transceivers on the bus
- Data Rate Up to 10Mbps
- Half-duplex Transceiver
- Small Packaging: SOP8/MSOP8/DFN8

Applications

- Power Inverters
- Motor Control
- Industrial Automation
- Battery-Powered Applications



Pin Diagram

General Description

The COS485 is an ultra-low power differential bus/line transceiver designed for multipoint data transmission standard RS485 applications with extended common mode range: -7V to 12V. It also meets the requirements of RS422.

The driver and receiver feature three-state outputs, with the driver outputs maintaining high impedance over the entire common mode range. Excessive power dissipation caused by bus contention or faults is prevented by a thermal shutdown circuit which forces the driver outputs into a high impedance state.

The receiver has a fail-safe feature which guarantees a high output state when the inputs are left open or shorted. Power-on reset circuits keep the outputs in a high impedance state until the supply voltage has stabilized.

The COS485 offers significant power saving without sacrificing ruggedness against overload or ESD damage. It is available in 8-lead plastic SOP8, MSOP8, and DFN3x3-8, and is specified for operation from –40°C to +125°C ambient temperature.

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1. Pin Configuration and Functions



Pin Description

| Pin | Name | Description |
|-----|------|---|
| 1 | RO | Receiver output. If the receiver output is enabled (RE low), then if A > B by 200mV, RO will be high. If A < B by 200mV, then RO will be low. |
| 2 | RE | Receiver output enable. A low enables the receiver output, RO. A high input forces the receiver output into a high impedance state. |
| 3 | DE | Driver output enable. A high on DE enables the driver outputs, A and B, and the chip will function as a line driver. A low input will force the driver outputs into a high impedance state and the chip will function as a line receiver. |
| 4 | DI | Driver input. If the driver outputs are enabled (DE high), then a low on DI forces the outputs A low and B high. A high on DI with the driver outputs enabled will force A high and B low. |
| 5 | GND | Ground |
| 6 | А | Non-inverting receiver input and non-inverting driver output |
| 7 | В | Inverting receiver input and inverting driver output |
| 8 | Vcc | Power Supply |



Driver Truth Table

| Inp | uts | Outputs | | Eurotion | |
|------|------|---------|---|------------------------------------|--|
| DE | DI | Α | В | Function | |
| Н | Н | Н | L | Actively drive bus High | |
| Н | L | L | Н | Actively drive bus Low | |
| L | Х | Z | Z | Driver disabled | |
| OPEN | Х | Z | Z | Driver disabled by default | |
| Н | OPEN | Н | L | Actively drive bus high by default | |

Note: X = Don't care; Z = High impedance

Receiver Truth Table

| | Inputs | Outputs | Function | |
|------|-------------------|---------|------------------------------|--|
| RE | A-B | RO | | |
| L | ≥ +0.2V | Н | Receiver valid bus High | |
| L | ≤ -0.2V | L | Receiver valid bus Low | |
| L | ≥ -0.2V ≤+0.2V | ? | Indeterminate bus state | |
| Н | Х | Z | Receiver disabled | |
| OPEN | X | Z | Receiver disabled by default | |
| L | Open-circuit bus | Н | Fail-safe high output | |
| L | Short-circuit bus | Н | Fail-safe high output | |
| L | Idle bus | Н | Fail-safe high output | |

Note: DE = L or OPEN



2. Product Specification

2.1 Absolute Maximum Ratings⁽¹⁾

| Parameter | Min | Max | Unit |
|---------------------------------|------|-----------|------|
| DC supply voltage Vcc | | 7 | V |
| Control input voltages | -0.5 | Vcc + 0.5 | V |
| Driver input voltages | -0.5 | Vcc + 0.5 | V |
| Driver output voltage at A or B | | ±14 | V |
| Receiver input voltage | | ±14 | V |
| Receiver output voltage | -0.5 | Vcc + 0.5 | V |
| Operating junction temperature | -40 | +135 | °C |
| Storage temperature | -55 | +150 | °C |

(1) Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

2.2 Thermal Data

| Parameter | Rating | Unit |
|----------------------------|--|------|
| Package Thermal Resistance | 150 (SOP8) 206 (MSOP8) 57 (DFN8,3x3) | °C/W |

2.3 Recommended Operating Conditions

| Parameter | Min. | Тур. | Max. | Unit |
|-----------------------------------|------|------|------|------|
| DC Supply voltage | 4.5 | | 5.5 | V |
| Input voltage at any bus terminal | -7 | | 12 | V |
| Differential input voltage | -12 | | 12 | V |
| Differential load resistance | 54 | 60 | | Ω |
| Data rate | 0 | | 10 | Mbps |
| Operating ambient temperature | -40 | | +85 | °C |
| Operating junction temperature | -40 | | +125 | °C |



2.4 Electrical Characteristics

(Typical values are tested at T_A=25 °C, Vcc=5V)

| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Unit |
|--|------------------|---|------------|------------|-------------|------|
| Driver Electrical Character | stics | | | | | |
| Differential driver output (no load) | V _{OD1} | I _O = 0 | 3 | 3.5 | | V |
| Differential driver output (with load) | V _{OD2} | $R_L = 50 \Omega$ (RS422) $R_L = 27 \Omega$ (RS485), Figure 1 | 2.0 1.5 | 2.5 2.0 | | V |
| Change in magnitude of driver differential output voltage for complementary output states | ΔVod | $R_L = 27\Omega \text{ or } 50\Omega$ | -0.2 | 0 | 0.2 | V |
| Driver common-mode output voltage | Voc | $R_L = 27\Omega \text{ or } 50\Omega$ | 1 | 2.4 | 3 | V |
| Change in magnitude of driver common-mode output voltage for complementary output states | ΔVoc | $R_L = 27\Omega \text{ or } 50\Omega$ | | | 0.2 | V |
| Driver short-circuit current | los | Vo = -7V to 12V | -250 | | 250 | mA |
| Logic Input high voltage | VIH | RE, DE, DI | 2.0 | | | V |
| Logic Input low voltage | VIL | RE, DE, DI | | | 0.8 | V |
| Logic Input current | I _{IN1} | RE, DE, DI | | | ±5 | μA |
| Receiver Electrical Charact | teristics | | | | | |
| Receiver differential threshold voltage | V _{TH} | V _{CM} = -7V to 12V | -0.2 | | 0.2 | V |
| Receiver input hysteresis | ΔV _{TH} | V _{CM} = 0V | | 30 | | mV |
| Receiver input resistance | R _{IN} | V _{CM} = -7V to 12V | 100 | | | kΩ |
| Input current (A, B) | l _{in} | $V_{CC} = 0V \text{ or } 5V, V_{DE} = 0V$ $V_{IN} = 12V$ $V_{IN} = -7V$ | | | 0.3 -0.3 | mA |
| Receiver output high voltage | V _{OH} | I _O = -8mA, V _{ID} = 200mV | 4.0 | 4.6 | | V |



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| Receiver output low voltage | Vol | I _O = -8mA, V _{ID} = 200mV | | 0.2 | 0.4 | V |
|--|---------------------------------|---|----|--------------|------------|----------|
| Receiver short-circuit current | I _{OSR} | VO = 0V to Vcc | 7 | | 30 | mA |
| Tristate output leakage current | I _{OZR} | $V_0 = 0.4$ to 2.4V | -1 | | 1 | μA |
| Supply Current and Power I | Dissipati | on Characteristics | | | | |
| Supply current | Icc | No Load, $V_{RE} = 0V$ or V_{CC} Outputs Enabled, $V_{DE}=Vcc$ Outputs Disabled, $V_{DE}=0$ | | 0.52 0.33 | 0.8 0.5 | mA mA |
| Average power dissipation | P _{AVG} | Data rate=10Mbps, 50% duty cycle, RL = 27Ω | | | 220 | mW |
| Shutdown current | I _{SHDN} | | | | 1 | μA |
| Thermal shut-down junction temperature | T _{SD} | | | 150 | | °C |
| Driver Switching Characteristics | | | | | | |
| Propagation delay input to output | t _{PLH} | | 3 | 5 | 10 | ns |
| Propagation delay input to output | t _{PHL} | $R_{DIFF} = 54\Omega,$ $C_{L1} = C_{L2} = 100 pF$ | 3 | 5 | 10 | ns |
| Output to output skew | t _{sк} | (See Figure 4 and Figure 6) | | 2 | 5 | ns |
| Rise or fall time | t _r , t _f | | 3 | 6 | 10 | ns |
| Enable to output high | t _{PZH} | C_L = 100pF, S2 = Closed (See Figure 5 and Figure 7) | | 5 | 10 | ns |
| Enable to output low | t _{PZL} | C_L = 100pF, S1 = Closed (See Figure 5 and Figure 7) | | 5 | 10 | ns |
| Disable time from low | t _{PLZ} | C_L = 15pF, S1 = Closed (See Figure 5 and Figure 7) | | 8 | 15 | ns |
| Disable time from high | t _{PHZ} | C_L = 15pF, S2 = Closed (See Figure 5 and Figure 7) | | 8 | 15 | ns |
| Receiver Switching Characte | eristics | | | | | |
| Propagation delay input to output | t PLH | | 30 | 105 | 150 | ns |
| Propagation delay input to output | t _{PHL} | $R_{\text{DIFF}} = 54\Omega$, | 30 | 105 | 150 | ns |
| Output to output skew | t _{sк} | (See Figure 4 and Figure 8) | | | 10 | ns |
| Enable to output high | t _{PZH} | C _{RL} = 15pF, S1 = Closed (See Figure 2 and Figure 9) | | 50 | 70 | ns |
| Enable to output low | t _{PZL} | C _{RL} = 15pF, S2 = Closed (See Figure 2 and Figure 9) | | 50 | 70 | ns |
| Disable time from low | t _{PLZ} | C _{RL} = 15pF, S1 = Closed (See Figure 2 and Figure 9) | | 50 | 70 | ns |



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| Disable time from high | t _{PHZ} | C _{RL} = 15pF, S2 = Closed (See Figure 2 and Figure 9) | 50 | 70 | ns |
|------------------------|------------------|--|----|----|------|
| Maximum data rate | f _{MAX} | | | 10 | Mbps |

3. Test Circuits



Figure 2. Driver DC test load



Figure 3. Receiver timing test load





Figure 4. Driver/Receiver timing test circuit



Figure 5. Driver timing test load

4. Switching Time Waveforms



Figure 6. Driver Propagation Delays









Figure 8. Receiver Propagation Delays



Figure 9. Receiver Enable and Disable Times



5. Typical Application

The COS485 device is a half-duplex RS-485 transceiver suitable for data transmission at rates up to 10 Mbps over controlled-impedance transmission media (such as twisted-pair cabling). Up to 256 units of the COS485 device can share a common RS-485 bus due to the low bus-input currents of the device. A typical application showing a multi-point transmission network is illustrated in Figure 10. Only one driver can transmit at a particular time, but multiple receivers may be enabled simultaneously. As with any transmission line, it is important that reflections are minimized. This can be achieved by terminating the extreme ends of the line using resistors equal to the characteristic impedance of the line. Stub lengths off the main line must also be kept as short as possible. A properly terminated transmission line appears purely resistive to the driver.



Figure 10. Multi-point Transmission Networks

6. Ordering Information

| Model | Order Number | Package | Package Option | Marking Information |
|--------|--------------|----------|---------------------|------------------------|
| | COS485RS | SOP-8 | Tape and Reel, 4000 | COS4853RS |
| COS485 | COS485RM | MSOP-8 | Tape and Reel, 3000 | COS4853RM |
| | COS485RF | DFN3x3-8 | Tape and Reel, 4000 | COS4853RF |



7. Package Information

7.1 SOP8 (Package Outline Dimensions)



| Symbol | Dimer In Milli | nsions meters | Dimensions In Inches | | |
|--------|-------------------|------------------|-------------------------|-------|--|
| | Min | Max | Min | Max | |
| А | 1.350 | 1.750 | 0.053 | 0.069 | |
| A1 | 0.100 | 0.250 | 0.004 | 0.010 | |
| A2 | 1.350 | 1.550 | 0.053 | 0.061 | |
| В | 0.330 | 0.510 | 0.013 | 0.020 | |
| С | 0.190 | 0.250 | 0.007 | 0.010 | |
| D | 4.780 | 5.000 | 0.188 | 0.197 | |
| E | 3.800 | 4.000 | 0.150 | 0.157 | |
| E1 | 5.800 | 6.300 | 0.228 | 0.248 | |
| е | 1.270 | 1.270TYP | | OTYP | |
| L | 0.400 | 1.270 | 0.016 | 0.050 | |
| θ | 0 ° | 8° | 0° | 8° | |

7.2 MSOP8 (Package Outline Dimensions)



A2 A

| Symbol | Dimer In Milli | nsions meters | Dimensions In Inches | | |
|--------|-------------------|------------------|-------------------------|-------|--|
| - | Min | Max | Min | Max | |
| A | 0.800 | 1.200 | 0.031 | 0.047 | |
| A1 | 0.000 | 0.200 | 0.000 | 0.008 | |
| A2 | 0.760 | 0.970 | 0.030 | 0.038 | |
| b | 0.30 | TYP | 0.012 TYP | | |
| С | 0.15 | TYP | 0.006 | S TYP | |
| D | 2.900 | 3.100 | 0.114 | 0.122 | |
| е | 0.65 | TYP | 0.026 | TYP | |
| E | 2.900 | 3.100 | 0.114 | 0.122 | |
| E1 | 4.700 | 5.100 | 0.185 | 0.201 | |
| L | 0.410 | 0.650 | 0.016 | 0.026 | |
| θ | 0° | 6° | 0° | 6° | |

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